R528

User Manual

Revision 1.8

May 11, 2023

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Revision History

Revision	Date	Author	Description
1.0	July 26, 2021	AWA0330	Initial release version.
1.1	August 13, 2021	XRA0041	Update section 10.5
1.2	September 30, 2021	AWA1896	Update some specifications
1.3	November 2, 2021	AWA1896	Update section 4
1.4	April 22, 2022	KPA0570	Update section 2.2.9.4, section 3.2.3.3, section 3.2.3.4, section 3.2.5, section 3.2.6, section 9.3, table 9-21, section 9.7.5, table 10.7.5.29, table 10-20, table 10-25, section 2.2.4, section 5.4.1
1.5	July 22, 2022	KPA0570	Update figure 3-5 and table 3-3
1.6	September 6, 2022	KPA0570	**Chapter 3** 1. Modify 3.1 Memory Mappping, Figure 3-3 System Bus Tree, Figure 3-4 Module Clock Generation, Figure 3-5 PLL Distribution, Table 3-3 PLL Typical Application 2. Delete 3.3.6.95 TCONTV Clock Register and TCONTV Bus Gating Reset Register **Chapter 4 DSP** Modify 4.2.1 DSP_CORE Interrupt Source, 4.2.2 DSP_INTC Interrupts, and 4.3.1 Overview. **Chapter 6 Video Output Interfaces** Delete 6.2 TCONTV
1.7	October 24, 2022	KPA0570	Added the frequency of CPU
1.8	May 11, 2023	KPA0570	Deleted the frequency of CPU **Chapter 3 System** Updated 3.11.6.1 0x0010 IOMMU Reset Register

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1 About This Document

1.1 Purpose and Scope

This document describes the features, logical structures, functions, operating modes, and related registers of each module about R528. For details about the interface timings and related parameters, the pins, pin usages, performance parameters, and package dimension, please refer to the *R528_Datasheet*.

CAUTION

The document defines two devices: R528-S2 and R528-S3. Unless other stated, their contents are consistent.

1.2 Intended Audience

The document is intended for:

- Design and maintenance personnel for electronics
- Programmers in writing code or modifying the Allwinner provided code

1.3 Symbol Conventions

1.3.1 Symbol Conventions

The symbols that may be found in this document are defined as follows.

Symbol	Description
WARNING	Indicates potential risk of injury or death exists if the instructions are not obeyed.
CAUTION	Indicates potential risk of equipment damage, data loss, performance degradation, or unexpected results exists if the instructions are not obeyed.
NOTE	Provides additional information to emphasize or supplement important points of the main text.

1.3.2 Table Content Conventions

The table content conventions that may be found in this document are defined as follows.

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Symbol	Description
/	The cell is blank.

1.3.3 Reset Value Conventions

In the register definition tables:

If other column value in a bit or multiple bits row is "/", that this bit or these multiple bits are unused.

If the default value of a bit or multiple bits is "UDF", that the default value is undefined.

1.3.4 Register Attributes

The register attributes that may be found in this document are defined as follows.

Symbol	Description
R	Read Only
R/W	Read/Write
R/WAC	Read/Write-Automatic-Clear, clear the bit automatically when the operation of complete. Writing 0 has no effect
R/WC	Read/Write-Clear
R/W0C	Read/Write 0 to Clear. Writing 1 has no effect
R/W1C	Read/Write 1 to Clear. Writing 0 has no effect
R/W1S	Read/Write 1 to Set. Writing 0 has no effect
W	Write Only

1.3.5 Numerical System

The expressions of data capacity, frequency, and data rate are described as follows.

Type	Symbol	Value
Data capacity	1 K	1024
	1 M	1,048,576
	1 G	1,073,741,824
Frequency, data rate	1 k	1000
	1 M	1,000,000
	1 G	1,000,000,000

The expressions of addresses and data are described as follows.

Symbol	Example	Description
0x	0x0200, 0x79	Address or data in hexadecimal
0b	0b010, 0b00 000 111	Data or sequence in binary (register description is excluded.)

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Symbol	Example	Description
X	00X, XX1	In data expression, X indicates 0 or 1. For example, 00X indicates 000 or 001 and XX1 indicates 001, 011, 101 or 111.

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2 Product Description

2.1 Overview

R528 is an advanced application processor designed for intelligent speaker application. It integrates the high-performance dual-core Cortex™-A7 and single-core HiFi4 DSP to provide the most-efficient computing power. R528 supports full format decoding such as H.265, H.264, MPEG-1/2/4, JPEG, VC1, and so on. And the independent encoder can encode in JPEG or MJPEG. Integrated multi ADCs/DACs and I2S/PCM/DMIC/OWA audio interfaces can work seamlessly with the CPU to accelerate multimedia algorithms and improve the user experience. R528 supports RGB/LVDS/MIPI DSI display output interfaces to meet the requirements of the screen display. To reduce the BOM cost, a DDR3 die is embedded for R528. R528 comes with extensive connectivity and interfaces, such as USB, SDIO, EMAC, TWI, UART, SPI, PWM, GPADC, LRADC, TPADC, IR TX&RX, and so on. Besides, R528 can connect with other different peripherals like WiFi and BT via SDIO and UART.

2.1.1 Device Difference

The R528 is configured with different sets of features in different devices. Table 2-1 shows the feature differences across different devices.

Table 2-1 Device Feature Differences

Contents	R528-S2	R528-S3
DDR	SIP 64 MB DDR2	SIP 128 MB DDR3
PCB Footprint	PCB pin-to-pin design	

2.2 Features

2.2.1 CPU Architecture

- Dual-core ARM Cortex™-A7
- 32 KB L1 I-cache + 32 KB L1 D-cache per core, 256 KB L2 cache

2.2.2 DSP Architecture

- HiFi4

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- 32 KB L1 I-cache and 32 KB L1 D-cache
- 64 KB I-ram and 64 KB D-ram

2.2.3 Memory SubSystem

2.2.3.1 Boot ROM (BROM)

- On-chip memory
- Supports system boot from the following devices:
  - SD card
  - eMMC
  - SPI NOR Flash
  - SPI NAND Flash
- Supports mandatory upgrade process through USB and SD card
- Supports GPIO pin and eFuse module to select the boot media type
- Supports normal booting and secure booting
- Secure BROM loads only certified firmware
- Secure BROM ensures that the secure boot is a trusted environment

2.2.3.2 SDRAM

- Embedded with 64 MB DDR2 (Only for R528-S2)
- Embedded with 128 MB DDR3 (Only for R528-S3)
- Supports clock frequency up to 533 MHz for DDR2
- Supports clock frequency up to 800 MHz for DDR3

2.2.3.3 SMHC

- Three SD/MMC host controller (SMHC) interfaces
- The SMHC0 controls the devices that comply with the protocol Secure Digital Memory (SD mem-version 3.0)

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- The SMHC1 controls the device that complies with the protocol Secure Digital I/O (SDIO-version 3.0)
- The SMHC2 controls the device that complies with the protocol Multimedia Card (eMMC-version 5.0)
- Maximum performance:
  - SDR mode 150 MHz@1.8 V IO pad
  - DDR mode 50 MHz@1.8 V IO pad
  - DDR mode 50 MHz@3.3 V IO pad
- Supports 1-bit or 4-bit data width
- Supports block size of 1 to 65535 bytes
- Internal 1024-Bytes RX FIFO and 1024-Bytes TX FIFO
- Supports card insertion and removal interrupt
- Supports hardware CRC generation and error detection
- Supports descriptor-based internal DMA controller

2.2.4 Video Engine

- Video decoding
  - H.265 MP@L4.1 up to 1080p@60fps
  - H.264 BP/MP/HP@L4.2 up to 1080p@60fps
  - H263 BP up to 1080p@60fps
  - MPEG-4 SP/ASP L5.0 up to 1080p@60fps
  - MPEG-2 MP/HL up to 1080p@60fps
  - MPEG-1 MP/HL up to 1080p@60fps
  - JPEG/Xvid/Sorenson Spark up to 1080p@60fps
  - MJPEG up to 1080p@30fps
- Video encoding
  - JPEG/MJPEG up to 1080p@60fps
  - Supports input picture scaler up/down

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2.2.5 Video and Graphics

2.2.5.1 Display Engine (DE)

- Output size up to 2048 x 2048
- Supports two alpha blending channels for main display and one channel for aux display
- Supports four overlay layers in each channel, and has an independent scaler
- Supports potter-duff compatible blending operation
- Supports LBC buffer decoder
- Supports dither output to TCON
- Supports input format Semi-planar YUV422/YUV420/YUV411 and Planar YUV422/YUV420/YUV411, ARGB8888/XRGB8888/RGB888/ARGB4444/ARGB1555/RGB565/palette
- Supports SmartColor2.0 for excellent display experience
  - Adaptive detail/edge enhancement
  - Adaptive color enhancement
  - Adaptive contrast enhancement and fresh tone rectify
- Supports write back for aux display

2.2.5.2 De-interlacer (DI)

- Supports YUV420 (Planar/NV12/NV21) and YUV422 (Planar/NV16/NV61) data format
- Supports video resolution from 32x32 to 2048x1280 pixel
- Supports Inter-field interpolation/motion adaptive de-interlace method
- Performance: module clock 600M for 1080p@60Hz YUV420

2.2.5.3 Graphic 2D (G2D)

- Supports layer size up to 2048 x 2048 pixels
- Supports pre-multiply alpha image data
- Supports color key
- Supports two pipes Porter-Duff alpha blending

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- Supports multiple video formats 4:2:0, 4:2:2, 4:1:1 and multiple pixel formats (8/16/24/32 bits graphics layer)
- Supports memory scan order option
- Supports any format convert function
- Supports 1/16× to 32× resize ratio
- Supports 32-phase 8-tap horizontal anti-alias filter and 32-phase 4-tap vertical anti-alias filter
- Supports window clip
- Supports FillRectangle, BitBlit, StretchBlit and MaskBlit
- Supports horizontal and vertical flip, clockwise 0/90/180/270 degree rotate for normal buffer
- Supports horizontal flip, clockwise 0/90/270 degree rotate for LBC buffer

2.2.6 Video Output

2.2.6.1 RGB and LVDS LCD

- Supports RGB interface with DE/SYNC mode, up to 1920 x 1080@60fps
- Supports serial RGB/dummy RGB interface, up to 800 x 480@60fps
- Supports LVDS interface with dual link, up to 1920 x 1080@60fps
- Supports LVDS interface with single link, up to 1366 x 768@60fps
- Supports i8080 interface, up to 800 x 480@60fps
- Supports BT656 interface for NTSC and PAL
- RGB666 and RGB565 with dither function
- Gamma correction with R/G/B channel independence

2.2.6.2 MIPI DSI

- Compliance with MIPI DSI v1.01
- Supports 4-lane MIPI DSI, up to 1280 x 720@60fps and 1920 x 1200@60fps resolution
- Supports non-burst mode with sync pulse/sync event and burst mode
- Supports pixel format: RGB888, RGB666, RGB666 loosely packed and RGB565
- Supports continuous and non-continuous lane clock modes

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- Supports bidirectional communication of all generic commands in LP through data lane 0
- Supports low power data transmission
- Supports ULPS and escape modes
- Hardware checksum capabilities

2.2.7 Video Input

2.2.7.1 Parallel CSI

- Supports 8-bit digital camera interface (RAW8/YUV422/YUV420)
- Supports BT656, BT601 interface (YUV422)
- Supports ITU-R BT.656 time-multiplexed format up to 2*1080p@30fps in DDR sample mode
- Maximum pixel clock of 148.5 MHz
- Supports de-interlacing for interlace video input
- Supports conversion from YUV422 to YUV420, YUV422 to YUV400, YUV420 to YUV400
- Supports horizontal and vertical flip

2.2.8 System Peripherals

2.2.8.1 Timer

- The timer module implements the timing and counting functions, which includes timer0, timer1, watchdog, and audio video synchronization (AVS)
- The timer0/timer1 is a 32-bit down counter. The timer0 and timer1 are completely consistent
- The watchdog is used to transmit a reset signal to reset the entire system when an exception occurs in the system
- The AVS is used to synchronize the audio and video. The AVS sub-block includes AVS0 and AVS1, which are completely consistent

2.2.8.2 High Speed Timer (HSTimer)

- The HSTimer module consists of HSTimer0 and HSTimer1. HSTimer0 and HSTimer1 are down counters that implement timing and counting functions. They are completely consistent.

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- Configurable 56-bit down timer
- Supports 5 prescale factors
- The clock source is synchronized with AHB0 clock, much more accurate than other timers
- Supports 2 working modes: periodic mode and single counting mode
- Generates an interrupt when the count is decreased to 0

2.2.8.3 GIC

- Supports 16 Software Generated Interrupts (SGIs), 16 Private Peripheral Interrupts (PPIs), and 192 Shared Peripheral Interrupts (SPIs)
- Software-configurable interrupts can be:
  - Enabled or disabled
  - Assigned to one of two groups: Group 0 or Group 1
  - Prioritized
  - Signaled to different processors in multiprocessor implementations
  - Either level-sensitive or edge-triggered
- GIC security extensions
  - Uses Group 0 interrupts as Secure interrupts, and Group 1 interrupts as Non-secure interrupts
  - Uses the FIQ interrupt request to signal Secure interrupts to a connected processor. The GIC-400 always signals Group 1 interrupts using the IRQ interrupt request

2.2.8.4 DMAC

- Up to 16-ch DMA
- Provides 32 peripheral DMA requests for data reading and 32 peripheral DMA requests for data writing
- Flexible data width of 8/16/32/64-bit
- Programmable DMA burst length
- Supports linear and IO address modes
- Supports data transfer types with memory-to-memory, memory-to-peripheral, peripheral-to-memory, peripheral-to-peripheral
- Supports transfer with linked list

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- DRQ response includes waiting mode and handshake mode
- DMA channel supports pause function
- Memory devices support non-aligned transform

2.2.8.5 Clock Controller Unit (CCU)

- 8 PLLs
- One on-chip RC oscillator
- Supports one external 24 MHz DCXO and one external 32.768 kHz oscillator
- Supports clock configuration and clock generation for corresponding modules
- Supports software-controlled clock gating and software-controlled reset for corresponding modules

2.2.8.6 Thermal Sensor Controller (THS)

- One thermal sensor located in CPU
- Temperature accuracy: ±3°C from 0°C to +100°C, ±5°C from -25°C to +125°C
- Averaging filter for thermal sensor reading
- Supports over-temperature protection interrupt and over-temperature alarm interrupt

2.2.8.7 LDO Power

- Integrated 2 LDOs (LDOA, LDOB)
- LDOA: 1.8 V power output, LDOB: 1.35 V/1.5 V/1.8 V power output
- LDOA for IO and analog module, LDOB for SDRAM
- Input voltage is 2.4 V to 3.6 V

2.2.8.8 RTC

- Implements time counter and timing wakeup
- Provides a 16-bit counter for counting day, 5-bit counter for counting hour, 6-bit counter for counting minute, 6-bit counter for counting second

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- External connect a 32.768 kHz low-frequency oscillator for count clock
- Timer frequency is 1 kHz
- Configurable initial value by software anytime
- Supports timing alarm, and generates interrupt and wakeup the external devices
- 8 general purpose registers for storing power-off information

2.2.8.9 I/O Memory Management Unit (IOMMU)

- Supports virtual address to physical address mapping by hardware implementation
- Supports VE, CSI, DE, G2D, DI parallel address mapping
- Supports VE, CSI, DE, G2D, DI bypass function independently
- Supports VE, CSI, DE, G2D, DI pre-fetch independently
- Supports VE, CSI, DE, G2D, DI interrupt handing mechanism independently
- Supports 2 levels TLB (level1 TLB for special using, and level2 TLB for sharing)
- Supports TLB Fully cleared and Partially disabled
- Supports trigger PTW behavior when TLB miss
- Supports checking the permission

2.2.8.10 Message Box (MSGBOX)

- Supports two CPU to transmit information through channels. Each CPU has a MSGBOX
  - CPU 0: ARM CPUX
  - CPU 1: DSP
- The channel between two CPU has 4 channels, and the FIFO depth of a channel is 8 x 32 bits

2.2.8.11 Spinlock

- Provides hardware synchronization mechanism in multi-core systems
- Supports 32 lock units
- Two kinds of lock status: locked and unlocked

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- Lock time of the processor is predictable (less than 200 cycles)

2.2.9 Audio Interfaces

2.2.9.1 Audio Codec

- Two audio digital-to-analog converter (DAC) channels
  - Supports 16-bit and 20-bit sample resolution
  - 8 kHz to 192 kHz DAC sample rate
  - 100 ± 2 dB SNR@A-weight, -85 ± 3 dB THD+N
- Two audio outputs:
  - One stereo headphone output: HPOUTL/R
  - One stereo differential lineout output: LINEOUTLP/N and LINEOUTRP/N
- Three audio analog-to-digital converter (ADC) channels
  - Supports 16-bit and 20-bit sample resolution
  - 8 kHz to 48 kHz ADC sample rate
  - 95 ± 3dB SNR@A-weight, -80 ± 3dB THD+N
- Five audio inputs:
  - Three differential microphone inputs: MICIN1P/1N, MICIN2P/2N, MICIN3P/3N, or three single-end microphone inputs: MICIN1P, MICIN2P, MICIN3P
  - One stereo LINEIN input: LINEINL/R
  - One stereo FMIN input: FMINL/R
- Supports Dynamic Range Controller adjusting the DAC playback and ADC recording
- One 128x20-bits FIFO for DAC data transmit, one 128x20-bits FIFO for ADC data receive
- Programmable FIFO thresholds
- Supports interrupts and DMA
- Internal HPLDO output for HPVCC
- Internal ALDO output for AVCC

2.2.9.2 I2S/PCM

- Three I2S/PCM external interfaces (I2S0, I2S1, I2S2) for connecting external power amplifier and MIC ADC

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- Compliant with standard Philips Inter-IC sound (I2S) bus specification
  - Left-justified, Right-justified, PCM mode, and Time Division Multiplexing (TDM) format
  - Programmable PCM frame width: 1 BCLK width (short frame) and 2 BCLKs width (long frame)
- Transmit and Receive data FIFOs
  - Programmable FIFO thresholds
  - 128 depth x 32-bit width TXFIFO and 64 depth x 32-bit width RXFIFO
- Supports multiple function clock
  - Clock up to 24.576 MHz Data Output of I2S/PCM in Master mode (Only if the IO PAD and Peripheral I2S/PCM satisfy Timing Parameters)
  - Clock up to 12.288 MHz Data Input of I2S/PCM in Master mode
- Supports TX/RX DMA slave interface
- Supports multiple application scenarios
  - Up to 16 channels (fs = 48 kHz) which has adjustable width from 8-bit to 32-bit
  - Sample rate from 8 kHz to 384 kHz (CHAN = 2)
  - 8-bit u-law and 8-bit A-law companded sample
- Supports master/slave mode

2.2.9.3 DMIC

- Supports maximum 8 digital PDM microphones
- Supports sample rate from 8 kHz to 48 kHz

2.2.9.4 One Wire Audio (OWA)

- One OWA TX
- Compliance with S/PDIF interface
- IEC-60958 transmitter functionality
- Supports 16-bit, 20-bit, and 24-bit data formats
- One 128×24bits TXFIFO for audio data transfer
- Programmable FIFO thresholds

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- Supports TX DMA slave interface
- Function clock includes 24.576 MHz and 22.579 MHz frequency
- Hardware parity generation on the transmitter
- Supports channel status insertion for the transmitter

  Supports interrupts and DMA

2.2.10 Security System

2.2.10.1 Crypto Engine (CE)

- Supports Symmetrical algorithm for encryption and decryption: AES, DES, TDES
  - Supports ECB, CBC, CTS, CTR, CFB, OFB mode for AES
  - Supports 128/192/256-bit key for AES
  - Supports ECB, CBC, CTR mode for DES/TDES
- Supports Hash algorithm for tamper proofing: MD5, SHA, HMAC
  - Supports SHA1, SHA224, SHA256, SHA384, SHA512 for SHA
  - Supports HMAC-SHA1, HMAC-SHA256 for HMAC
  - Supports multi-package mode for MD5/SHA1/SHA224/SHA256/SHA384/SHA512
- Supports Asymmetrical algorithm for signature verification: RSA
  - RSA supports 512/1024/2048-bit width
- Supports 160-bit hardware PRNG with 175-bit seed
- Supports 256-bit hardware TRNG
- Internal DMA controller for data transfer with memory
- Supports secure and non-secure interfaces respectively

2.2.10.2 Security ID (SID)

- Supports 2 Kbits eFuse for chip ID and security application
- The eFuse has secure zone and non-secure zone
- Backup eFuse information by using SID_SRAM
- Burning the key to the SID
- Reading the key use status in the SID

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- Loading the key to the CE

2.2.10.3 Secure Memory Control (SMC)

- The SMC is always secure, only secure CPU can access the SMC
- Sets secure area of DRAM
- Sets secure property that Master accesses to DRAM

2.2.10.4 Secure Peripherals Control (SPC)

- The SPC is always secure, only secure CPU can access the SPC
- Sets secure property of peripherals

2.2.11 External Peripherals

2.2.11.1 USB DRD

- One USB 2.0 DRD (USB0), with integrated USB 2.0 analog PHY
- Complies with USB2.0 Specification
- Supports USB Host function
  - Compatible with Enhanced Host Controller Interface (EHCI) Specification, Version 1.0
  - Compatible with Open Host Controller Interface (OHCI) Specification, Version 1.0a
  - Supports High-Speed (HS, 480 Mbit/s), Full-Speed (FS, 12 Mbit/s), and Low-Speed (LS, 1.5 Mbit/s)
  - Supports only 1 USB Root port shared between EHCI and OHCI
- Supports USB Device function
  - Supports High-Speed (HS, 480 Mbit/s), Full-Speed (FS, 12 Mbit/s)
  - Supports bi-directional endpoint0 (EP0) for Control transfer
  - Up to 10 user-configurable endpoints (EP1+, EP1-, EP2+, EP2-, EP3+, EP3-, EP4+, EP4-, EP5+, EP5-) for Bulk transfer, Isochronous transfer and Interrupt transfer
  - Up to (8 KB + 64 Bytes) FIFO for all EPs (including EP0)
  - Supports interface to an external Normal DMA controller for every EP

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- Supports an internal DMA controller for data transfer with memory
- Supports High-Bandwidth Isochronous & Interrupt transfers
- Automated splitting/combining of packets for Bulk transfers
- Supports point-to-point and point-to-multipoint transfer in both Host and Peripheral modes
- Includes automatic ping capabilities
- Soft connect/disconnect function
- Performs all transaction scheduling in hardware
- Power optimization and power management capabilities
- Device and host controller share a 8K SRAM and a physical PHY

2.2.11.2 USB HOST

- One USB 2.0 HOST (USB1), with integrated USB 2.0 analog PHY
- Complies with USB2.0 Specification
- Supports USB2.0 Host function
  - Compatible with Enhanced Host Controller Interface (EHCI) Specification, Version 1.0
  - Compatible with Open Host Controller Interface (OHCI) Specification, Version 1.0a
  - Supports High-Speed (HS, 480 Mbit/s), Full-Speed (FS, 12 Mbit/s) and Low-Speed (LS, 1.5 Mbit/s) Device
  - Supports only 1 USB Root port shared between EHCI and OHCI
- An internal DMA Controller for data transfer with memory

2.2.11.3 EMAC

- One EMAC interface for connecting external Ethernet PHY
- 10/100/1000 Mbit/s Ethernet port with RGMII and RMII interfaces
- Compliant with IEEE 802.3-2002 standard
- Supports both full-duplex and half-duplex operation
- Provides the management data input/output (MDIO) interface for PHY device configuration and management with configurable clock frequencies

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- Programmable frame length to support Standard or Jumbo Ethernet frames with sizes up to 16 KB
- Supports a variety of flexible address filtering modes
- Separate 32-bit status returned for transmission and reception packets
- Optimization for packet-oriented DMA transfers with frame delimiters
  - Supports linked-list descriptor list structure
  - Descriptor architecture, allowing large blocks of data transfer with minimum CPU intervention; each descriptor can transfer up to 4 KB of data
  - Comprehensive status reporting for normal operation and transfers with errors
- 4 KB TXFIFO for transmission packets and 16 KB RXFIFO for reception packets
- Programmable interrupt options for different operational conditions

2.2.11.4 UART

- Up to 6 UART controllers (UART0, UART1, UART2, UART3, UART4, UART5)
- UART0, UART4, UART5: 2-wire; UART1, UART2, UART3: 4-wire
- Compatible with industry-standard 16450/16550 UARTs
- Supports IrDA-compatible slow infrared (SIR) format
- Two separate FIFOs: one is RX FIFO, and the other is TX FIFO
  - Each of them is 64 bytes (For UART0)
  - Each of them is 256 bytes (For UART1, UART2, UART3, UART4, and UART5)
- The working reference clock is from the APB bus clock
  - Speed up to 4 Mbit/s with 64 MHz APB clock
  - Speed up to 1.5 Mbit/s with 24 MHz APB clock
- 5 to 8 data bits for RS-232 characters, or 9 bits RS-485 format
- 1, 1.5 or 2 stop bits
- Programmable parity (even, odd, or no parity)
- Supports TX/RX DMA slave controller interface
- Supports software/hardware flow control
- Supports RX DMA Master interface (Only for UART1)
- Supports auto-flow by using CTS & RTS (Only for UART1/2/3)

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2.2.11.5 Two Wire Interface (TWI)

- Up to 4 TWI controllers (TWI0, TWI1, TWI2, TWI3)
- Compliant with I2C bus standard
- Supports standard mode (up to 100 kbit/s) and fast mode (up to 400 kbit/s)
- Supports 7-bit and 10-bit device addressing modes
- Supports master mode or slave mode
- Master mode features:
  - Supports the bus arbitration in the case of multiple master devices
  - Supports clock synchronization and bit and byte waiting
  - Supports packet transmission and DMA
- Slave mode features:
  - Interrupt on address detection
- The TWI controller includes one TWI engine and one TWI driver. And the TWI driver supports packet transmission and DMA mode when TWI works in master mode

2.2.11.6 SPI and SPI_DBI

- Up to 2 SPI controllers (SPI0, SPI1)
- The SPI0 only supports SPI mode; The SPI1 supports SPI mode and display bus interface (DBI) mode
- SPI mode:
  - Full-duplex synchronous serial interface
  - Master/slave configurable
  - Mode0 to Mode3 are supported for both transmit and receive operations
  - 8-bit wide by 64-entry FIFO for both transmit and receive data
  - Polarity and phase of the Chip Select (SPI-CS) and SPI Clock (SPI-CLK) are configurable
  - Supports 3-wire/4-wire SPI
  - Supports programmable serial data frame length: 1-bit to 32-bit
  - Supports Standard SPI, Dual-Output/Dual-Input SPI, Dual IO SPI, Quad-Output/Quad-Input SPI

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- DBI mode:
  - Supports DBI Type C 3 Line/4 Line Interface Mode
  - Supports 2 Data Lane Interface Mode
  - Supports RGB111/444/565/666/888 video format
  - Maximum resolution of RGB666 240 x 320@30Hz with single data lane
  - Maximum resolution of RGB888 240 x 320@60Hz or 320 x 480@30Hz with dual data lane
  - Supports Tearing effect
  - Supports software flexible control video frame rate

2.2.11.7 CIR Receiver (CIR_RX)

- One CIR_RX interface (IR-RX)
- Full physical layer implementation
- Supports NEC format infra data
- Supports CIR for remote control or wireless keyboard
- 64x8 bits FIFO for data buffer
- Sample clock up to 1 MHz

2.2.11.8 CIR Transmitter (CIR_TX)

- One CIR_TX interface (IR-TX)
- Supports arbitrary wave generator
- Configurable carrier frequency
- Supports handshake mode and waiting mode of DMA
- 128 bytes FIFO for data buffer

2.2.11.9 PWM

- Supports 8 independent PWM channels (PWM0 to PWM7)
  - Supports PWM continuous mode output

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- Supports PWM pulse mode output, and the pulse number is configurable
- Output frequency range: 0 to 24 MHz or 100 MHz
- Various duty-cycle: 0% to 100%
- Minimum resolution: 1/65536

- Supports 4 complementary pairs output
  - PWM01 pair (PWM0 + PWM1), PWM23 pair (PWM2 + PWM3), PWM45 pair (PWM4 + PWM5), PWM67 pair (PWM6 + PWM7)
  - Supports dead-zone generator, and the dead-zone time is configurable
- Supports 4 group of PWM channel output for controlling stepping motors
  - Supports any plural channels to form a group, and output the same duty-cycle pulse
  - In group mode, the relative phase of the output waveform for each channel is configurable
- Supports 8 channels capture input
  - Supports rising edge detection and falling edge detection for input waveform pulse
  - Supports pulse-width measurement for input waveform pulse

2.2.11.10 General Purpose ADC (GPADC)

- 2-ch Successive approximation register (SAR) analog-to-digital converter (ADC)
- 12-bit sampling resolution and 8-bit precision
- 64 FIFO depth of data register
- Power reference voltage: AVCC, analog input voltage range: 0 to AVCC
- Maximum sampling frequency up to 1 MHz
- Supports three operation modes: single conversion mode, continuous conversion mode, burst conversion mode

2.2.11.11 Touch Panel ADC (TPADC)

- 12 bit SAR type A/D converter
- Configurable sample frequency up to 1 MHz
- One 32x12 FIFO for storing A/D conversion result

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- Supports DMA slave interface
- Supports 4-wire resistive touch panel input detection
  - Supports pen down detection with programmable sensitivity
  - Supports single touch coordinate measurement
  - Supports dual touch detection
  - Supports touch pressure measurement with programmable threshold
  - Supports median and averaging filter for noise reduction
  - Supports X and Y coordinate exchange function
- Supports Aux ADC with up to 4 channels

2.2.11.12 Low Rate ADC (LRADC)

- One LRADC input channel
- 6-bit sampling resolution and 5-bit precision
- Sample rate up to 2 kHz
- Supports hold Key and general Key
- Supports normal, continuous and single working mode
- Power supply voltage: AVCC, power reference voltage: 0.75*AVCC, analog input and detected voltage range: 0 to 1.266 V

2.2.11.13 LEDC

- LEDC is used to control the external intelligent control LED lamp
- Configurable LED output high/low level width
- Configurable LED reset time
- LEDC data supports DMA configuration mode and CPU configuration mode
- Maximum 1024 LEDs serial connect
- LED data transfer rate up to 800 kbit/s

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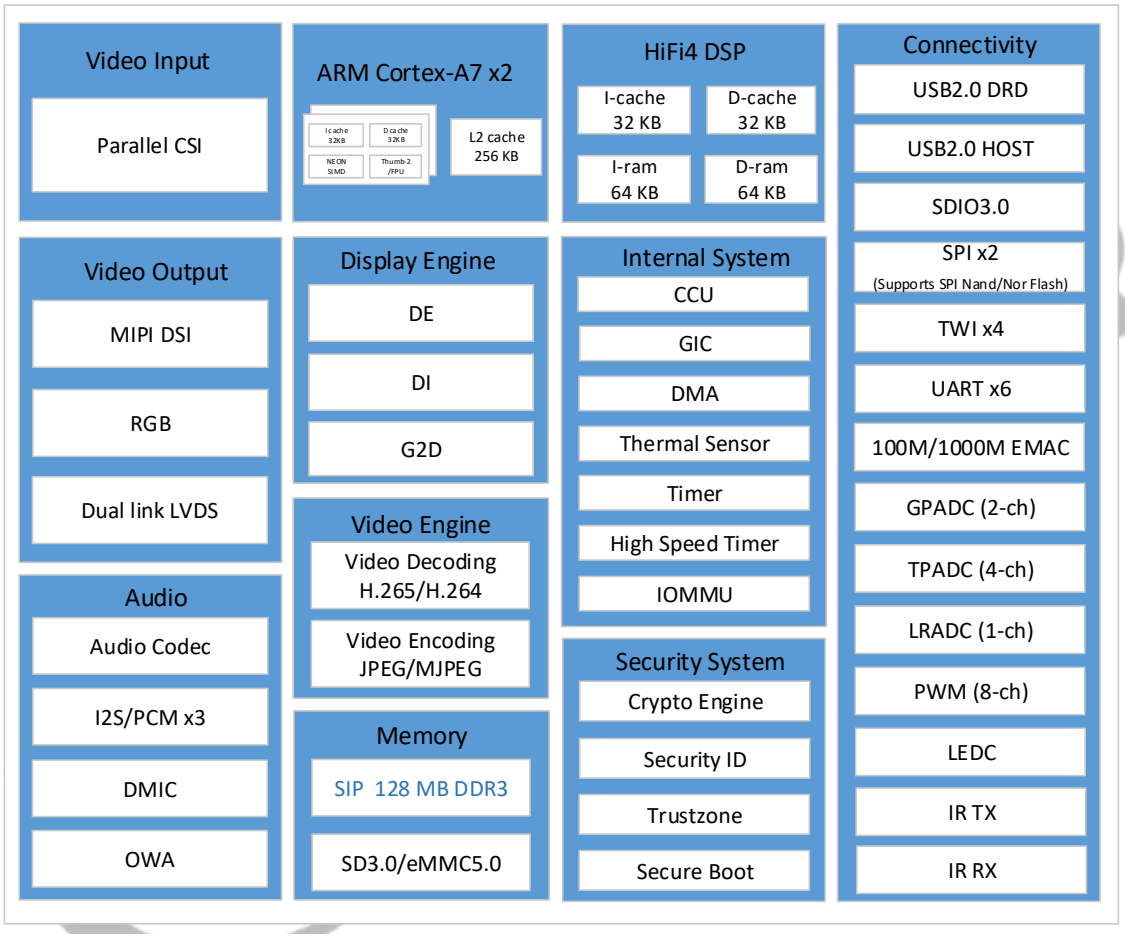
2.2.12 Package

- LFBGA 226 balls, 12 mm x 12 mm body size, 0.65 mm ball pitch, 0.35 mm ball size

2.3 Block Diagram

Figure 2-1 shows the system block diagram of the R528.

Figure 2-1 R528 System Block Diagram

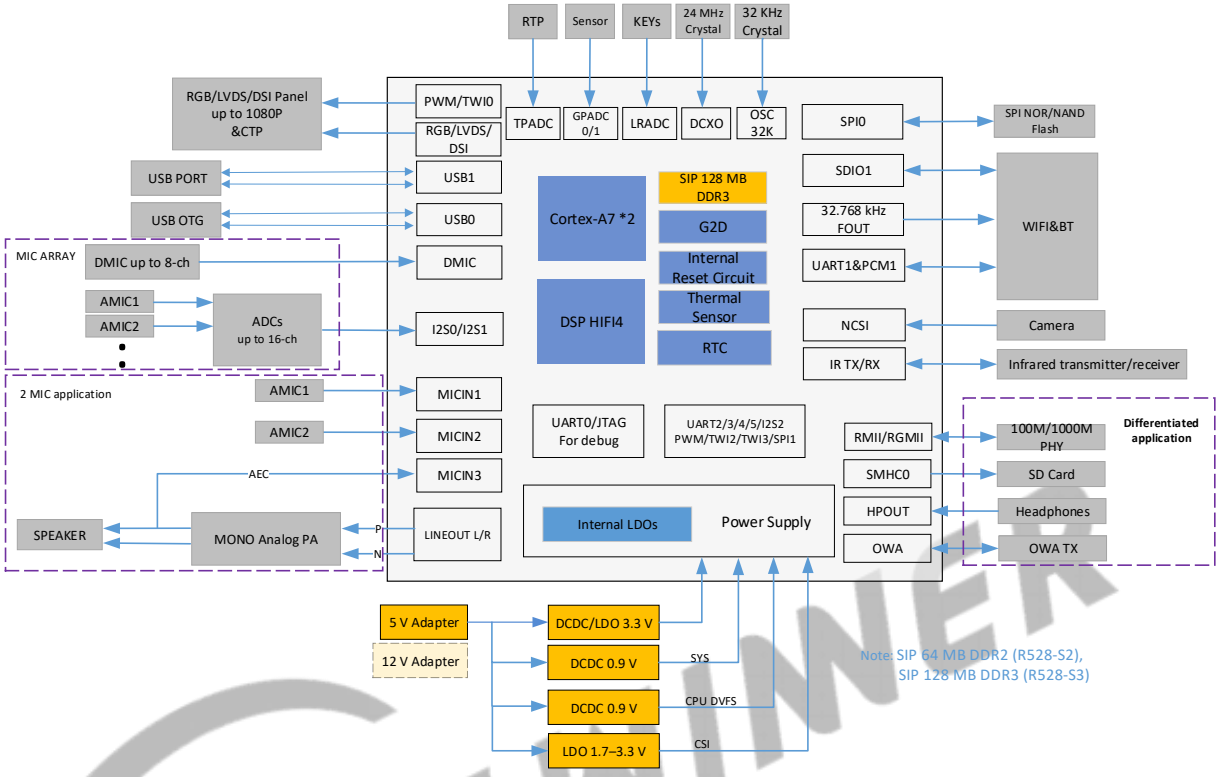


Note: SIP 64 MB DDR2 (R528-S2), SIP 128 MB DDR3 (R528-S3)

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Figure 2-2 shows the typical solution diagram of the R528.

Figure 2-2 Intelligent Speaker with Screen Solution of the R528



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3 System

3.1 Memory Mapping

Module	Address (It is for Cluster CPU)	Size
BROM & SRAM		
N-BROM	0x0000 0000—0x0000 BFFF	48 KB
S-BROM	0x0000 0000—0x0000 8FFF	36 KB
SRAM A1	0x0002 0000---0x0002 7FFF	32 KB
DSP0 IRAM	0x0002 8000---0x0003 7FFF	64 KB The local sram is switched to system boot.
DSP0 DRAM0	0x0003 8000---0x0003 FFFF	32 KB The local sram is switched to system boot.
DSP0 DRAM1	0x0004 0000---0x0004 7FFF	32 KB The local sram is switched to system boot.
DSP0 IRAM (local sram)	0x0040 0000---0x0040 FFFF	64 KB The local sram is switched to DSP.
DSP0 DRAM0 (local sram)	0x0042 0000---0x0042 7FFF	32 KB The local sram is switched to DSP.
DSP0 DRAM1 (local sram)	0x0044 0000---0x0044 7FFF	32 KB The local sram is switched to DSP.
DSP_SYS Related		
DSP_CFG	0x0170 0000---0x0170 03FF	1 KB
DSP_WDG	0x0170 0400---0x0170 07FF	1 KB
DSP_INTC	0x0170 0800---0x0170 0BFF	1 KB
DSP_TZMA	0x0170 0C00---0x0170 0FFF	1 KB
DSP_MSGBOX	0x0170 1000---0x0170 1FFF	4 KB
VE_SYS Related		
VE	0x01C0 E000---0x01C0 FFFF	8 KB
SP0 (SYS Domain)		
GPIO	0x0200 0000---0x0200 07FF	2 KB
SPC	0x0200 0800---0x0200 0BFF	1 KB

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Module	Address (It is for Cluster CPU)	Size
PWM	0x0200 0C00---0x0200 0FFF	1 KB
CCU	0x0200 1000---0x0200 1FFF	4 KB
IR_TX	0x0200 3000 – 0x0200 33FF	1 KB
TZMA	0x0200 4000---0x0200 43FF	1 KB
LEDC	0x0200 8000---0x0200 83FF	1 KB
GPADC	0x0200 9000---0x0200 93FF	1 KB
LRADC	0x0200 9800---0x0200 9BFF	1 KB
THS	0x0200 9400---0x0200 97FF	1 KB
TPADC	0x0200 9C00---0x0200 9FFF	1 KB
IOMMU	0x0201 0000---0x0201 FFFF	64 KB
Audio Codec	0x0203 0000---0x0203 0FFF	4 KB
DMIC	0x0203 1000---0x0203 13FF	1 KB
I2S0	0x0203 2000---0x0203 2FFF	4 KB
I2S1	0x0203 3000---0x0203 3FFF	4 KB
I2S2	0x0203 4000---0x0203 4FFF	4 KB
OWA	0x0203 6000---0x0203 63FF	1 KB
TIMER	0x0205 0000---0x0205 0FFF	4 KB
SP1 (SYS Domain)		
UART0	0x0250 0000---0x0250 03FF	1 KB
UART1	0x0250 0400---0x0250 07FF	1 KB
UART2	0x0250 0800---0x0250 0BFF	1 KB
UART3	0x0250 0C00---0x0250 0FFF	1 KB
UART4	0x0250 1000---0x0250 13FF	1 KB
UART5	0x0250 1400---0x0250 17FF	1 KB
TWI0	0x0250 2000---0x0250 23FF	1 KB
TWI1	0x0250 2400---0x0250 27FF	1 KB
TWI2	0x0250 2800---0x0250 2BFF	1 KB
TWI3	0x0250 2C00---0x0250 2FFF	1 KB
SH0 (SYS Domain)		
SYSCTRL	0x0300 0000---0x0300 0FFF	4 KB
DMAC	0x0300 2000---0x0300 2FFF	4 KB
CPUX_MSGBOX	0x0300 3000---0x0300 3FFF	4 KB
SPINLOCK	0x0300 5000---0x0300 5FFF	4 KB
SID	0x0300 6000---0x0300 6FFF	4 KB

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Module	Address (It is for Cluster CPU)	Size
SMC	0x0300 7000---0x0300 7FFF	4 KB
HSTIMER	0x0300 8000---0x0300 8FFF	4 KB
DCU	0x0301 0000---0x0301 FFFF	64 KB
CPU_GIC	0x0302 0000---0x0302 FFFF	64 KB
CE_NS	0x0304 0000---0x0304 07FF	2 KB
CE_S	0x0304 0800---0x0304 0FFF	2 KB
CE_KEY_SRAM	0x0304 1000---0x0304 1FFF	4 KB (only CE access)
MSI+MEMC	0x0310 2000---0x0330 1FFF	2 MB
SH2 (SYS Domain)		
SMHC0	0x0402 0000---0x0402 0FFF	4 KB
SMHC1	0x0402 1000---0x0402 1FFF	4 KB
SMHC2	0x0402 2000---0x0402 2FFF	4 KB
SPI0	0x0402 5000---0x0402 5FFF	4 KB
SPI1	0x0402 6000---0x0402 6FFF	4 KB
USB0	0x0410 0000---0x041F FFFF	1 MB
USB1	0x0420 0000---0x042F FFFF	1 MB
EMAC	0x0450 0000---0x0450 FFFF	64 KB
VIDEO_OUT_SYS Related (SYS Domain)		
DE	0x0500 0000---0x053F FFFF	4 MB
DI	0x0540 0000---0x0540 FFFF	64 KB
G2D	0x0541 0000---0x0544 FFFF	256 KB
DSI	0x0545 0000---0x0545 1FFF	8 KB
DISPLAY_TOP	0x0546 0000---0x0546 0FFF	4 KB
TCON_LCD0	0x0546 1000---0x0546 1FFF	4 KB
VIDEO_IN_SYS Related (SYS Domain)		
CSI	0x0580 0000---0x05BF FFFF	4 MB
APBS0 (CPUS Domain)		
R_CPUCFG	0x0700 0400---0x0700 0BFF	2 KB
R_PPU	0x0700 1000---0x0700 13FF	1 KB
R_SPC	0x0700 2000---0x0700 23FF	1 KB
R_PRCM	0x0701 0000---0x0701 FFFF	64 KB
R_TIMER	0x0702 0000 – 0x0702 03FF	1 KB
R_TWD	0x0702 0800 – 0x0702 0BFF	1 KB
IR_RX	0x0704 0000---0x0704 03FF	1 KB

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Module	Address (It is for Cluster CPU)	Size
AHBS (CPUS Domain)		
RTC	0x0709 0000---0x0709 03FF	1 KB
CPUX Related		
CPU_SYS_CFG	0x0810 0000---0x0810 03FF	1 KB
TimeStamp_STA	0x0811 0000---0x0811 0FFF	4 KB
TimeStamp_CTRL	0x0812 0000---0x0812 0FFF	4 KB
IDC	0x0813 0000---0x0813 0FFF	4 KB
C0_CPUX_CFG	0x0901 0000---0x0901 03FF	1 KB
C0_CPUX_MBIST	0x0902 0000---0x0902 0FFF	4 KB
DRAM Space (SYS Domain)		
DRAM SPACE	0x4000 0000---0xBFFF FFFF	2 GB

The following is the system memory mapping seen by the DSP0 host.

Module	Cacheable Property	Address	Size	Address Mapping Description
SRAM A1	Non-Cacheable (Total 512 MB)	0x0002 0000---0x0002 7FFF	32 KB	The start address of the default DSP.
DSP0 IRAM		0x0002 8000---0x0003 7FFF	64 KB	The DSP0 accesses the address through the external bus to operate the internal local SRAM.
DSP0 DRAM0		0x0003 8000---0x0003 FFFF	32 KB	
DSP0 DRAM1		0x0004 0000---0x0004 7FFF	32 KB	
DSP0 IRAM		0x0040 0000---0x0040 FFFF	64 KB	The DSP0 accesses the address through the internal bus to directly access the local SRAM, which is more efficient than the external bus.
DSP0 DRAM0		0x0042 0000---0x0042 7FFF	32 KB	
DSP0 DRAM1		0x0044 0000---0x0044 7FFF	32 KB	
L4_CONN_periph		0x0200 0000---0x09FF FFFF	128 MB	System Peripherals
DSP_SYS_CFG		0x0170 0000---0x0170 0FFF	4 KB	Peripherals
DRAM SPACE		0x1000 0000---0x1FFF FFFF	256 MB	The front 256 MB space of DDR (0x40000000–0x4FFFFFFF) It requires DSP output AHB for address remapping

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Module	Cacheable Property	Address	Size	Address Mapping Description
Cacheable Mapping Area				
SRAM	Cacheable (Total 512 MB)	0x2002 0000---0x2002 7FFF	32 KB	SRAM A1 has two addresses.
DSP0 IRAM		0x2002 8000---0x2003 7FFF	64 KB	The DSP0 accesses the address through the external bus to operate the internal local SRAM.
DSP0 DRAM0		0x2003 8000---0x2003 FFFF	32 KB	
DSP0 DRAM1		0x2004 0000---0x2004 7FFF	32 KB	
DRAM SPACE		0x3000 0000---0x3FFF FFFF	256 MB	The front 256 MB space of DDR (0x40000000–0x47FFFFFF) It requires DSP output AHB for address remapping
DRAM Special Mapping Area				
DRAM SPACE	Non-Cacheable	0x4000 0000---0x7FFF FFFF	1 GB	
DRAM SPACE	Cacheable Configurable	0x8000 0000---0xBFFF FFFF	1 GB	Reserved space
DRAM SPACE	Cacheable	0xC000 0000---0xFFFF FFFF	1 GB	The front 1 GB space of DDR (0x40000000–0x7FFFFFFF)

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3.2 CPUX Configuration

3.2.1 Overview

CPUX indicates the ARM CPU subsystem. You can configure the CPUX via the C0_CPUX_CFG and CPU_SUBSYS_CTRL modules.

The C0_CPUX_CFG module is used for configuring Cluster0. Cluster0 is the only cluster which consists of dual-core Cortex™-A7, 32 KB I-cache and 32 KB D-cache per core, and the shared 256 KB L2 cache. The C0_CPUX_CFG module includes the following features:

- CPU reset system: core reset, debug circuit reset, and other functional modules reset
- CPU related control: interface control, CP15 control, and power-on/off control
- CPU status check: idle status, SMP status, interrupt status, and so on
- CPU debug-related register for control and status

The CPU_SUBSYS_CTRL module is used for controlling CPU subsystem resources, such as GIC-400 and JTAG.

3.2.2 Functional Descriptions

3.2.2.1 Signal Description

For details of A7 CPUX signals, refer to the technical reference manual of *DDI0464F_cortex_A7_mpcore_r0p5_trm.pdf*.

3.2.2.2 L2 Idle Mode

Enter the L2 idle mode by configuring the L2 cache of Cluster to enter the wait for interrupt (WFI) mode.

Follow the steps below:

1. Make sure CPU[1:0] of Cluster has entered the WFI mode. You can check it through bit[17:16] of Cluster0 CPU Status Register.
2. Pull high the ACINACTM of Cluster by writing 1 to the bit0 of Cluster 0 Control Register1.
3. Check whether L2 enters idle status by checking whether the STANDBYWFIL2 is high.

To exit the L2 idle mode, set the ACINACTM to low.

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3.2.2.3 CPU Reset System

There are three levels of CPUX reset, with the scope size from small to large: core reset, power-on Reset, and H_Reset.

The following table describes all the reset signals in the CPUX reset system.

Table 3-1 Reset Signal Description

Reset Signal	Description
CORE_RST	This is the primary reset signal which resets the corresponding core logic, including NEON, VFP, Debug, ETM, breakpoint, and watchpoint logic. It maps to a warm reset that covers the reset of the processor logic.
PWRON_RST	This power-on reset signal resets all the processor logic, including the Debug, ETM trace unit, breakpoint, watchpoint logic, and performance monitors logic. It maps to a cold reset that covers the reset of the processor logic and the integrated debug functionality. It does not reset debug logic in the debug power domain. PWRON_RST includes CORE_RST, ETM_RST, and DBG_RST.
H_RST	H_RST includes PWRON_RST, L2_RST, MBIST_RST, SOC_DBG_RST, and C0_CPUX_CFG.
AXI2MBUS_RST	This reset signal resets the AXI2MBUS interface logic circuit.
L2_RST	This single, cluster-wide signal resets the L2 memory system and the logic in the SCU.
ETM_RST	This reset signal resets ETM debug logic circuit.
DBG_RST	In the processor power domain, this reset signal resets only the debug, breakpoint, and watchpoint logic. In the debug power domain, it resets the debug logic for each processor.
SOC_DBG_RST	This reset signal resets all the debug logic. It includes DBG_RST.
MBIST_RST	This reset signal resets all resettable registers in the cluster, for entry into and exit from MBIST mode.
CPU_SUBSYS_RST	CPU_SUBSYS_RST includes C0_H_RST, GIC-400, and CPU_SUBSYS_CTRL.

3.2.2.4 CPUX Power Block Diagram

The following table shows the power domain of the modules in the CPU subsystem.

Table 3-2 Power Domain of Modules in the CPU Subsystem

Power Domain	Modules	Description
Cluster0	Cluster0, C0_CPUX_CFG, and C0_MBIST	Cluster0 circuit, C0_CPUX_CFG module, and CPU reset/power/mbist
System	Timestamp, GIC, CPU_SUBSYS_CTRL, and Clock	Provides system source of CPU sub-system

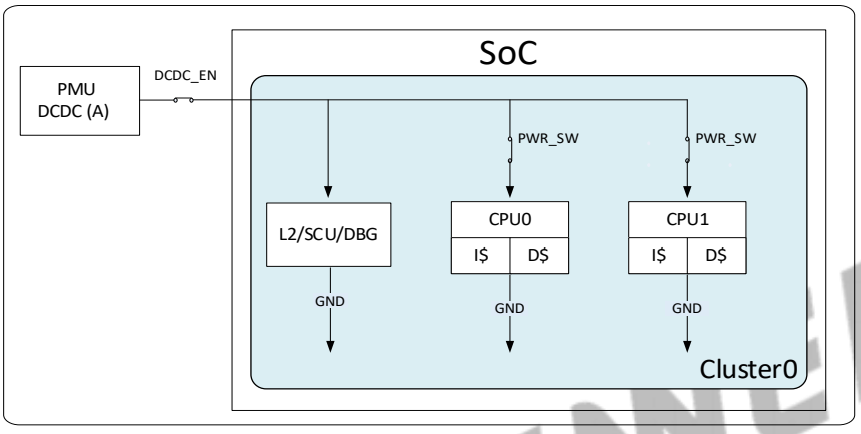
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As shown in the table, C0_CPUX_CFG belongs to Cluster0 power domain and CPU_SUBSYS_CTRL belongs to the system power domain.

Because C0_CPUX_CFG and Cluster0 belong to the same power domain, C0_CPUX_CFG holds in the default state when Cluster0 restarts. You need to initial C0_CPUX_CFG via software after C0_H_RST is de-asserted.

The following figure shows the default power domain of Cluster0.

Figure 3-1 Default Power Domain of Cluster0



For Cluster0, the power switch of all CPU cores are on, the PWRON_RST of all CPU cores are de-asserted, the CORE_RST of CPU0 is de-asserted, and the CORE_RST of CPU1 is asserted.

3.2.2.5 CPUX Power Block Diagram

The CPU-related operations, such as opening/closing cores, clustering switches, and querying status, require proper configurations of C0_CPUX_CFG module and the related system control resources like the bus and clock.

3.2.3 Cluster 0 Configuration Register List

Module Name	Base Address
C0_CPUX_CFG	0x09010000

Register Name	Offset	Description
C0_RST_CTRL	0x0000	Cluster 0 Reset Control Register
C0_CTRL_REG0	0x0010	Cluster 0 Control Register0
C0_CTRL_REG1	0x0014	Cluster 0 Control Register1
C0_CTRL_REG2	0x0018	Cluster 0 Control Register2
CACHE_CFG_REG	0x0024	Cache Configuration Register

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Register Name	Offset	Description
C0_CPU_STATUS	0x0080	Cluster 0 CPU Status Register
L2_STATUS_REG	0x0084	Cluster 0 L2 Status Register
DBG_REG0	0x00C0	Cluster 0 Debug Control Register0
DBG_REG1	0x00C4	Cluster 0 Debug Control Register1
AXI_MNT_CTRL_REG	0x00D0	AXI Monitor Control Register
AXI_MNT_PRD_REG	0x00D4	AXI Monitor Period Register
AXI_MNT_RLTCY_REG	0x00D8	AXI Monitor Read Total Latency Register
AXI_MNT_WLTCY_REG	0x00DC	AXI Monitor Write Total Latency Register
AXI_MNT_RREQ_REG	0x00E0	AXI Monitor Read Request Times Register
AXI_MNT_WREQ_REG	0x00E4	AXI Monitor Write Request Times Register
AXI_MNT_RBD_REG	0x00E8	AXI Monitor Read Bandwidth Register
AXI_MNT_WBD_REG	0x00EC	AXI Monitor Write Bandwidth Register

3.2.4 Cluster 0 Configuration Register Description

3.2.4.1 0x0000 Cluster 0 Reset Control Register (Default Value: 0x13FF_0101)

Offset: 0x0000			Register Name: C0_RST_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28	R/W	0x1	DDR_RST AXI2MBUS Logic Circuit Reset 0: Assert 1: De-assert
27:26	/	/	/
25	R/W	0x1	MBIST_RST CPUBIST Reset The reset signal is for test. 0: Assert 1: De-assert
24	R/W	0x1	SOC_DBG_RST Cluster SoC Debug Reset 0: Assert 1: De-assert

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Offset: 0x0000			Register Name: C0_RST_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	R/W	0xF	ETM_RST Cluster ETM Reset Assert 0: Assert 1: De-assert
19:16	R/W	0xF	DBG_RST Cluster Debug Reset Assert 0: Assert 1: De-assert
15:9	/	/	/
8	R/W	0x1	L2_RST Cluster L2 Cache Reset 0: Assert 1: De-assert
7:4	/	/	/
3:0	R/W	0x1	CORE_RESET Cluster CPU[1:0] Reset Assert (The bit[3:2] is not used) 0: Assert 1: De-assert

3.2.4.2 0x0010 Cluster 0 Control Register0 (Default Value: 0x8000_0000)

Offset: 0x0010			Register Name: C0_CTRL_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x1	SYSBAR_DISABLE Disable broadcasting barriers to the system bus. 0: Barriers are broadcasted to the system bus. This requires an AMBA4 interconnection. 1: Barriers are broadcasted to the system bus. This is compatible with an AXI3 interconnection.
30	R/W	0x0	BROADCAST_INNER Enable broadcasting inner shareable transactions. 0: Inner shareable transactions are not broadcasted externally. 1: Inner shareable transactions are broadcasted externally.

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Offset: 0x0010			Register Name: C0_CTRL_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
29	R/W	0x0	BROADCAST_OUTER Enable broadcasting outer shareable transactions. 0: Outer Shareable transactions are not broadcasted externally. 0: Outer Shareable transactions are broadcasted externally.
28	R/W	0x0	BROADCAST_CACHE_MAINT Enable broadcasting cache maintenance operations to downstream caches. 0: Cache maintenance operations are not broadcasted to downstream caches. 1: Cache maintenance operations are broadcasted to downstream caches.
27:12	/	/	/
11:8	R/W	0x0	CP15S_DISABLE Disable write access to some secure CP15 registers The meaning of each bit: 0: Enable write access to CP15 register 1: Disable write access to CP15 register
7:5	/	/	/
4	R/W	0x0	L2_RST_DISABLE Disable automatic L2 cache invalidation at reset. 0: L2 cache is reset by hardware. 1: L2 cache is not reset by hardware.
3:0	R/W	0x0	L1_RST_DISABLE Disable automatic Cluster CPU[1:0] L1 cache invalidation at reset. (The bit[3:2] is not used) 0: L1 cache is reset by hardware. 1: L1 cache is not reset by hardware.

3.2.4.3 0x0014 Cluster 0 Control Register1 (Default Value: 0x0000_0000)

Offset: 0x0014			Register Name: C0_CTRL_REG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/

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Offset: 0x0014			Register Name: C0_CTRL_REG1
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	CRM_LowFreq_AutoSelect Enable CRM to automatically select low frequency. 0: Disabled 1: Enabled
0	R/W	0x0	ACINACTM Deactivate snoop interface 0: Snoop interface is active 1: Snoop interface is inactive and no longer accepts requests

3.2.4.4 0x0018 Cluster 0 Control Register2 (Default Value: 0x0000_0010)

Offset: 0x0018			Register Name: C0_CTRL_REG2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	EVENTI Event input for processor to wake up from WFE state. This bit must remain high for at least one clock cycle to be visible by the cores.
23:20	R/W	0x0	EXM_CLR[1:0] Clear the status of the corresponding interface. (The bit[23:22] is not used) The meaning of each bit: 0: Not to clear 1: Clear
19:0	/	/	/

3.2.4.5 0x0024 Cache Configuration Register (Default Value: 0x0018_001A)

Offset: 0x0024			Register Name: CACHE_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21:19	R/W	0x3	EMA_L2D Indicates the port number of L2 Cache SRAM EMA control port.
18:17	R/W	0x0	EMAW_L2D Indicates the port number of L2 Cache SRAM EMAW control port.

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Offset: 0x0024			Register Name: CACHE_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
16	R/W	0x0	EMAS_L2D Indicates the port number of L2 Cache SRAM EMAS control port.
15:12	/	/	/
11:8	R/W	0x0	DVS FARADAY SRAM delay signal
7	R/W	0x0	DVSE FARADAY SRAM delay enable signal
6	R/W	0x0	STOV
5:3	R/W	0x3	EMA Indicates the port number of Cache SRAM EMA control port.
2:1	R/W	0x1	EMAW Indicates the port number of Cache SRAM EMAW control port.
0	R/W	0x0	EMAS Indicates the port number of Cache SRAM EMAS control port.

3.2.4.6 0x0080 Cluster0 CPU Status Register (Default Value: 0x000E_0000)

Offset: 0x0080			Register Name: C0_CPU_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/
27:24	R	0x0	SMP_AMP Configure the operating mode for CPU[1:0] as Symmetric Multiprocessing mode or Asymmetric Multiprocessing mode. (The bit[27:26] is not used) 0: AMP mode 1: SMP mode
23:20	/	/	/
19:16	R	0xE	STANDBYWFI Indicates if CPU[1:0] of Cluster0 is in WFI standby mode. (The bit[19:18] is not used) 0: The processor is not in WFI standby mode. 1: The processor is in WFI standby mode.
15:12	/	/	/

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Offset: 0x0080			Register Name: C0_CPU_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
11:8	R	0x0	STANDBYWFE Indicates if CPU[1:0] of Cluster0 is in the WFE standby mode. (The bit[11:10] is not used) 0: The processor is not in WFE standby mode. 1: The processor is in WFE standby mode.
7:1	/	/	/
0	R	0x0	STANDBYWFIL2 Indicates if the L2 memory system of Cluster0 is in WFI standby mode. 0: Cluster0 L2 is not in WFI standby mode. 1: Cluster0 L2 is in WFI standby mode.

3.2.4.7 0x0084 L2 Status Register (Default Value: 0x0000_0000)

Offset: 0x0084			Register Name: L2_STATUS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:10	/	/	/
9	R	0x0	EVENTO Event output. This bit is asserted high for 3 clock cycles when any core in the cluster executes an SEV instruction.
8:0	/	/	/

3.2.4.8 0x00C0 Cluster 0 Debug Control Register0 (Default Value: 0x0000_000F)

Offset: 0x00C0			Register Name: DBG_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:8	R/W	0x0	DBGRESTART[1:0] Indicates if there are external restart requests for CPU[1:0]. (The bit[11:10] is not used) The meaning of each bit: 0: There are no such requests. 1: There are such requests.
7:4	/	/	/

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Offset: 0x00C0			Register Name: DBG_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0xF	C_DBGPWRDUP Indicates if CPU[1:0] is powered-up. (The bit[3:2] is not used) The meaning of each bit: 0: The core is powered down. 1: The core is powered up.

3.2.4.9 0x00C4 Cluster 0 Debug Control Register1 (Default Value: 0x0000_0000)

Offset: 0x00C4			Register Name: DBG_REG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:12	R/W	0x0	DBGRESTARTED[1:0] (The bit[15:14] is not used) Handshake for DBGRESTART.
11:8	/	/	/
7:4	R	0x0	C_DBGNOPWRDWN Do Not Power Down Request. Indicates if the debugger requests CPU[1:0] not to power down. (The bit[7:6] is not used) The meaning of each bit: 0: There are no such requests. 1: There are such requests.
3:0	R	0x0	C_DBGPWRUPREQ Power Up Request. Indicates if the debugger requests CPU[1:0] to power up. (The bit[3:2] is not used) The meaning of each bit: 0: There are no such requests. 1: There are such requests.

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3.2.4.10 0x00D0 CPU AXI Monitor Control Register (Default Value: 0x0000_0000)

Offset: 0x00D0			Register Name: AXI_MNT_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R/W	0x0	AXI_MONITOR function clear 0: Not to clear 1: Clear the AXI_MONITOR related registers with the offset address from 0x00D8 to 0x00EC.
0	R/W	0x0	Enable AXI_MONITOR function 0: Disabled 1: Enabled

3.2.4.11 0x00D4 CPU AXI Monitor Period Register (Default Value: 0x0000_0000)

Offset: 0x00D4			Register Name: AXI_MNT_PRD_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	The monitoring period of AXI_MONITOR function (unit: cycles)

3.2.4.12 0x00D8 CPU AXI Monitor Read Latency Register (Default Value: 0x0000_0000)

Offset: 0x00D8			Register Name: AXI_MNT_RLTCY_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	The total latency of AXI_MONITOR function read channel (unit: cycles)

3.2.4.13 0x00DC CPU AXI Monitor Write Latency Register (Default Value: 0x0000_0000)

Offset: 0x00DC			Register Name: AXI_MNT_WLTCY_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	The total latency of AXI_MONITOR function write channel (unit: cycles)

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3.2.4.14 0x00E0 CPU AXI Monitor Read Request Register (Default Value: 0x0000_0000)

Offset: 0x00E0			Register Name: AXI_MNT_RREQ_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	The total times of AXI_MONITOR function read channel requests.

3.2.4.15 0x00E4 CPU AXI Monitor Write Request Register (Default Value: 0x0000_0000)

Offset: 0x00E4			Register Name: AXI_MNT_WREQ_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	The total times of AXI_MONITOR function write channel requests.

3.2.4.16 0x00E8 CPU AXI Monitor Read Bandwidth Register (Default Value: 0x0000_0000)

Offset: 0x00E8			Register Name: AXI_MNT_RBD_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	The bandwidth of AXI_MONITOR function read channel (Unit: KB)

3.2.4.17 0x00EC CPU AXI Monitor Write Bandwidth Register (Default Value: 0x0000_0000)

Offset: 0x00EC			Register Name: AXI_MNT_WBD_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	The bandwidth of AXI_MONITOR function write channel (Unit: KB)

3.2.5 CPU Subsystem Control Register List

Module Name	Base Address
CPU_SUBSYS_CTRL	0x08100000

Register Name	Offset	Description
GENER_CTRL_REG0	0x0000	General Control Register0
GIC_JTAG_RST_CTRL	0x000C	GIC and JTAG Reset Control Register
C0_INT_EN	0x0010	Cluster0 Interrupt Enable Control Register

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Register Name	Offset	Description
IRQ_FIQ_STATUS	0x0014	IRQ/FIQ Status Register
GENER_CTRL_REG2	0x0018	General Control Register2
DBG_STATE	0x001C	Debug State Register

3.2.6 CPU Subsystem Control Register Description

3.2.6.1 0x0000 General Control Register0 (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: GENER_CTRL_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/
2	R/W	0x0	Cluster 0 Corepll Select Register width state 0: CCU clock 1: Disp PLL clock
1	R/W	0x0	IDC Clock Enable 0: IDC clock is disabled 1: IDC clock is enabled
0	R/W	0x0	GIC_CFGSDISABLE Disable write access to some secure GIC registers. 0: The write access to some secure GIC registers is enabled. 1: The write access to some secure GIC registers is disabled.

3.2.6.2 0x000C GIC and JTAG Reset Control Register (Default Value: 0x0000_0F07)

Offset: 0x000C			Register Name: GIC_JTAG_RST_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:20	/	/	/
19:16	R/W	0x0	EXM_CLR[1:0] (The bit[19:18] is not used) Clear the status of interface for debug.
15:12	/	/	/

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Offset: 0x000C			Register Name: GIC_JTAG_RST_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
11	R/W	0x1	CS_RST CoreSight reset 0: Assert 1: De-assert
10	R/W	0x1	DAP_RST DAP reset 0: Assert 1: De-assert
9	R/W	0x1	PORTRST DAP reset signal control 0: Assert 1: De-assert
8	R/W	0x1	TRST JTAG RTST signal 0: Assert 1: De-assert
7:2	/	/	/
1	R/W	0x1	IDC_RST Interrupt delay controller reset 0: Assert 1: De-assert
0	R/W	0x1	GIC_RST GIC_reset_cpu_reg 0: Assert 1: De-assert

3.2.6.3 0x0010 Cluster 0 Interrupt Enable Register (Default Value: 0x0000_FFFF)

Offset: 0x0010			Register Name: C0_INT_EN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/

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Offset: 0x0010			Register Name: C0_INT_EN
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R/W	0xFFFF	C0_GIC_EN Mask the FIQ_OUT[15:0] and IRQ_OUT[15:0] signals to system domain. The meaning of each bit: 0: Mask the FIQ_OUT and IRQ_OUT signals to system domain. 1: Not to mask the FIQ_OUT and IRQ_OUT signals to system domain.

3.2.6.4 0x0014 GIC IRQ/FIQ Status Register (Default Value: 0x0000_0000)

Offset: 0x0014			Register Name: IRQ_FIQ_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0000	FIQ_OUT[15:0]
15:0	R/W	0x0000	IRQ_OUT[15:0]

3.2.6.5 0x0018 General Control Register2 (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: GENER_CTRL_REG2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	CDBGRSTACK Debug Reset ACK 0: There are no debug reset ACKs. 1: There are debug reset ACKs.
15:1	/	/	/
0	R/W	0x0	C0_TSCLKCHANGE Cluster 0 time stamp change. 0: There are no time stamp changes. 1: There are time stamp changes.

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3.2.6.6 0x001C Debug State Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: DBG_STATE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	R	0x0	CLU_PWRSW_STA
23:1	/	/	/
0	R	0x0	C0_DBG_STATE Indicates if Cluster0 is in debug mode or normal mode. 0: Normal mode 1: Debug mode

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3.3 Clock Controller Unit (CCU)

3.3.1 Overview

The clock controller unit (CCU) controls the PLL configurations and most of the clock generation, division, distribution, synchronization, and gating. The input signals of the CCU include the external clock for the reference frequency (24 MHz). The outputs from the CCU are mostly clocks to other blocks in the system.

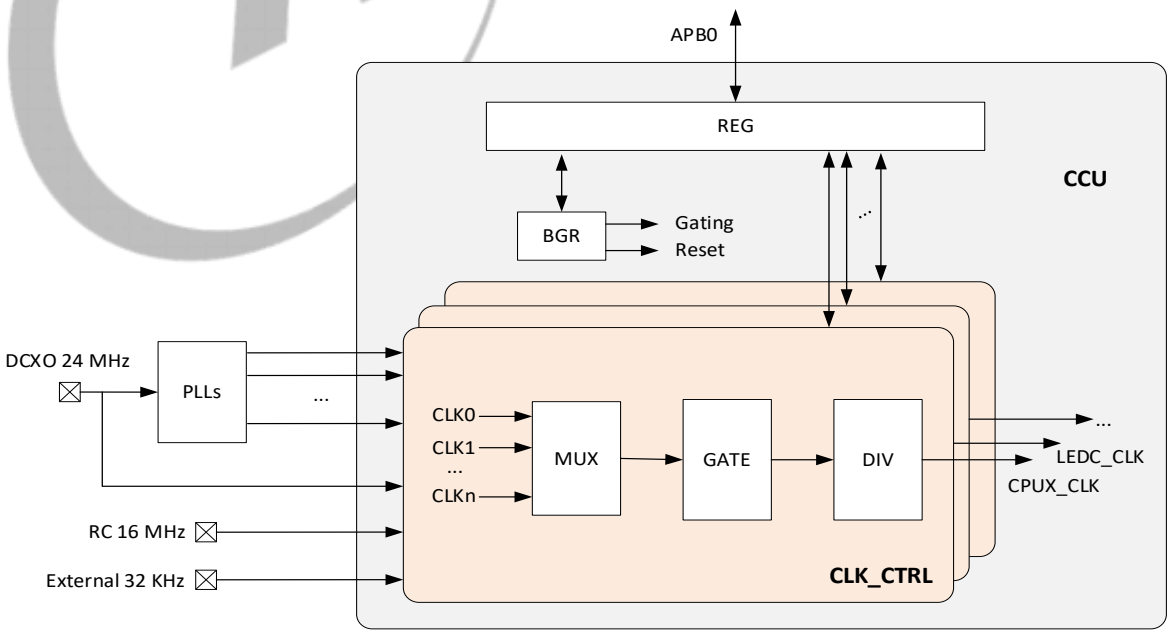
The CCU includes the following features:

- 8 PLLs
- Bus source and divisions
- Clock output control
- Configuring modules clock
- Bus clock gating
- Bus software reset

3.3.2 Block Diagram

The following figure shows the functional block diagram of the CCU.

Figure 3-2 CCU Block Diagram



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3.3.3 Functional Description

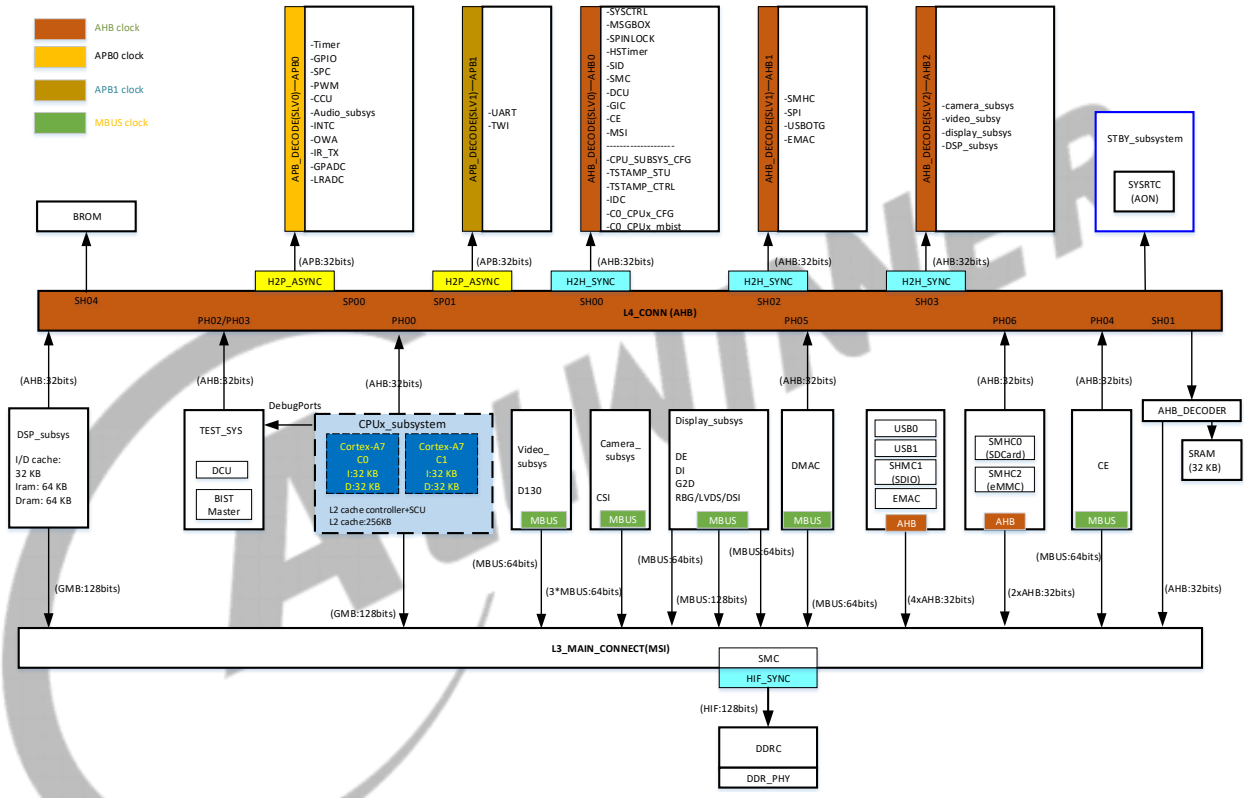
3.3.3.1 System Bus Tree

The system buses include advanced high-performance buses (AHBs), advanced peripheral buses (APBs), and MBUS.

All devices mounted at the bus should use the related bus clocks, and the gating signals for the bus are from the CCU module.

The following figure shows the diagram of the System Bus Tree.

Figure 3-3 System Bus Tree

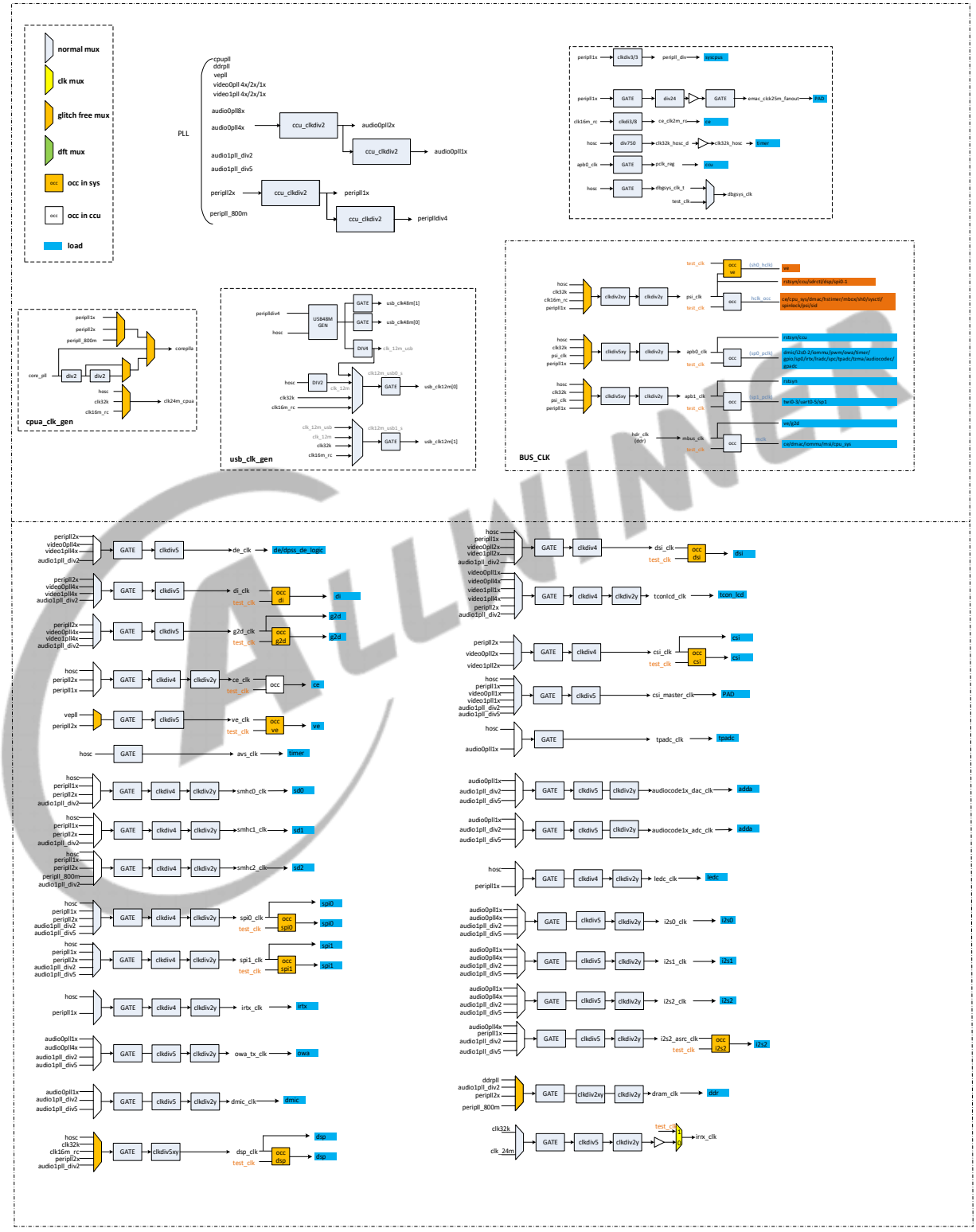


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3.3.3.2 Module Clock Generation

The following figure describes module clock generation.

Figure 3-4 Module Clock Generation

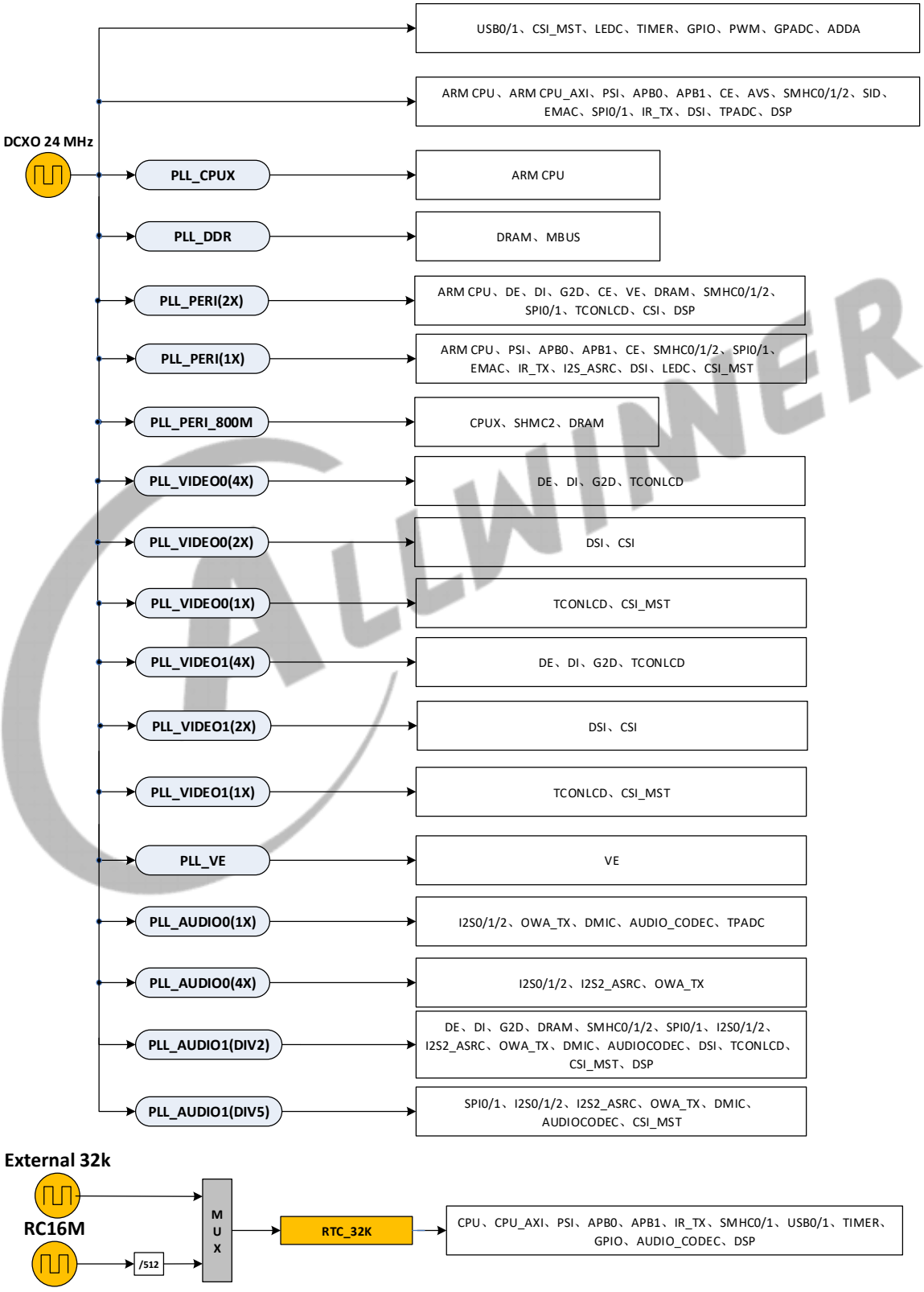


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3.3.3.3 PLL Distribution

The following figure shows the block diagram of the PLL distribution.

Figure 3-5 PLL Distribution



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Table 3-3 PLL Typical Application

PLL Type	Application Module	Notes
PLL_CPU	ARM CPU	Support DVFS
PLL_DDR	MBUS, DRAM	Support spread spectrum No support linear FM
PLL_PERI(2X)	ARM CPU, DE, DI, G2D, CE, VE, DRAM, SMHC0/1/2, SPI0/1, TCONLCD, CSI, DSP	No support dynamic FM
PLL_PERI(1X)	ARM CPU, PSI, APB0, APB1, CE, SMHC0/1/2, SPI0/1, EMAC, IR_TX, I2S_ASRC, DSI, LEDC, CSI_MST	No support dynamic FM
PLL_PERI(800M)	ARM CPU, SHMC2, DRAM	No support dynamic FM
PLL_VIDEO0(4X)	DE, DI, G2D, TCONLCD	No support DVFS
PLL_VIDEO0(2X)	DSI, CSI	No support DVFS
PLL_VIDEO0(1X)	TCONLCD, CSI_MST	No support DVFS
PLL_VIDEO1(4X)	DE, DI, G2D, TCONLCD	No support DVFS
PLL_VIDEO1(2X)	DSI, CSI	
PLL_VIDEO1(1X)	TCONLCD, CSI_MST	No support DVFS
PLL_VE	VE	No support dynamic FM
PLL_AUDIO0	I2S0/1/2, OWA_TX, DMIC, AUDIO_CODEC, TPADC	No support DVFS
PLL_AUDIO0(4X)	I2S0/1/2, I2S2_ASRC, OWA_TX	No support DVFS
PLL_AUDIO1(DIV2)	DE, DI, G2D, DRAM, SMHC0/1/2, SPI0/1, I2S0/1/2, I2S2_ASRC, OWA_TX, DMIC, AUDIOCODEC, DSI, TCONLCD, CSI_MST, DSP	No support DVFS
PLL_AUDIO1(DIV5)	SPI0/1, I2S0/1/2, I2S2_ASRC, OWA_TX, DMIC, AUDIOCODEC, CSI_MST	No support DVFS

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3.3.3.4 PLL Features

The following table shows the PLL features.

Table 3-4 PLL Features

PLL	Stable Operating Frequency	Actual Operating Frequency	Default Frequency	Spread Spectrum	Linear FM	Rate Control	Pk-Pk	Lock Time
PLL_CPU	288 MHz to 3.0 GHz (24*N)	288 MHz to 1.8 GHz	408 MHz	No	Yes	No	< 200 ps	1.5 ms
PLL_AUDIO0	180 MHz to 3.0 GHz (24MHz*N.x/M1/M0/P)	24.576 MHz 22.5792 MHz 24.576*4 MHz 22.5792*4 MHz	24.576 MHz	Yes	No	No	< 200 ps	500 us
PLL_AUDIO1	180 MHz to 3.0 GHz	Fvco/Div (Div: 1–8)	Integer mode: 1/2x: 1.536 GHz 1/5x: 614.4 MHz Decimal mode: 1/2x: 1.1179648 GHz 1/5x: 471.8592 MHz	Yes	No	No	< 200 ps	500 us
PLL_PERI	180 MHz to 3.2 GHz (24*N/M1/M0)	Fvco/Div (Div:1–8)	1/2x: 1.2 GHz 1/3x: 800 MHz	Yes	No	No	< 200ps	500 us
PLL_VIDEO0(4X)	252 MHz to 3.0 GHz (24*N/M)	192 MHz to 2400 MHz	1x: 297 MHz 2x: 594 MHz 4x: 1188 MHz	Yes	No	No	< 200ps	500 us
PLL_VIDEO1(4X)	252 MHz to 3.0 GHz (24*N/M)	192 MHz to 2400 MHz	1x: 297 MHz 2x: 594 MHz 4x: 1188 MHz	Yes	No	No	< 200ps	500 us
PLL_VE	180 MHz to 3.0 GHz (24*N/M1/M0)	192 MHz to 600 MHz	432 MHz	Yes	No	No	< 200ps	500 us
PLL_DDR	180 MHz to 3.0 GHz (24*N/M1/M0)	192 MHz to 2.0 GHz	432 MHz	Yes	No	No	200 MHz to 800 MHz (< 200 ps) 800 MHz to 1.3 GHz (< 140 ps) 1.3 GHz to 2.0 GHz (< 100 ps)	2 ms

3.3.3.5 The Usage Notes of PLL Frequencies

Table 3-5 The Usage Notes of PLL Frequencies

PLL Type	PLL Calculate Formula	PLL Output Frequency Range	Post Frequency-Divider of Module	Typical Working-Frequency of Module	Recommended PLL Parameter Configuration
PLL_CPU	24*N	200 MHz to 3 GHz	/P (1/2/4)	Based on the requirement of CPU	When the output clock is less than 288 MHz, the clock frequency can be outputted by dividing P.
PLL_PERI(1X)	24MHz*N/M/P0/2	600 MHz (P0=2)	1 to 64	600 MHz/300 MHz/ 200 MHz/150 MHz/ 100 MHz	N=100, M=1, P0=2, P1=3

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PLL Type	PLL Calculate Formula	PLL Output Frequency Range	Post Frequency-Divider of Module	Typical Working-Frequency of Module	Recommended PLL Parameter Configuration
PLL_PERI(2X)	24MHz*N/M/P0	1.2 GHz (P0=2)	1 to 64	1.2 GHz/600 MHz/ 400 MHz/300 MHz/ 240 MHz/200 MHz/ 150 MHz/100 MHz	
PLL_PERI(800M)	24MHz*N/M/P1	800 MHz (P1=3)	1 to 64	800 MHz	
PLL_VIDEO0	24MHz*N/M	4x:0<=1188 MHz 1x: 0<=297 MHz	1 to 64	1188 MHz/585 MHz/ 537 MHz/ 501 MHz/ 468 MHz/462 MHz/ 426 MHz/390 MHz/ 357 MHz/297 MHz…	N=99, M=2
PLL_VIDEO1	24MHz*N/M	4x:0<=1188 MHz 1x: 0<=297 MHz	1 to 64	1188 MHz/585 MHz/ 537 MHz/ 501 MHz/ 468 MHz/462 MHz/ 426 MHz/390 MHz/ 357 MHz/297 MHz…	N=99, M=2,
PLL_VE	24MHz*N/M1/M0	200 MHz to 600 MHz	1 to 64	600 MHz/450 MHz/ 360 MHz/270 MHz	N=25, M1=1, M0=2
PLL_DDR	24MHz*N/M1/M0	192 MHz to 2.0 GHz	1 to 64	200 MHz/400 MHz/ 800 MHz	N=100, M1=M0=1, P=3
PLL_AUDIO0(1X) PLL_AUDIO0(4X) Decimal	24MHz*N.x/M1/M0/P/4 24MHz*N.x/M1/M0/P	24.576/22.5792 MHz (24.576/22.5792)*4 MHz	1 to 64	24.576/22.5792 MHz (24.576/22.5792)*4 MHz	24.571:N.x=14.336, P=14, M0=1, M1=1 22.5792:N.x=7.5264, P=8, M0=1, M1=1
PLL_AUDIO1(DIV2) Integral	24MHz*N/M/P0	1536 MHz (P0=2)	4	384 MHz	N=128, M=1, P0=2, P1=5
			5	307 MHz	
			6	256 MHz	
			8	192 MHz	
			10	154 MHz	
			16	96 MHz	
			……	……	
PLL_AUDIO1(DIV5) Integral	24MHz*N/M/P1	614.4 MHz (P1=5)	25	24.576 MHz The jitter of this frequency point is better. The frequency point is used for audio module.	
PLL_AUDIO0(DIV2) Decimal	24MHz*N.x/M/P0	1179.648 MHz (P0=2)	2	600 MHz	N.x=98.304, M=1, P0=2, P1=1 to 8
			3	393 MHz	
			4	295 MHz	
			5	236 MHz	
			6	197 MHz	
			8	147 MHz	
			12	98 MHz	
			48	24.576 MHz The jitter of this frequency point is relatively poor. The frequency point is used for audio module.	
			……	.....	
PLL_AUDIO0(DIV5) Decimal	24MHz*N.x/M/P1	295 MHz to 2400 MHz	1 to 64	Select based on peripherals	

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3.3.4 Programming Guidelines

3.3.4.1 Configuring the Frequency of PLL_CPU

The frequency configuration formula of PLL_CPU:

PLL_CPU = 24 MHz*N/P

The parameter N is the frequency-doubling factor of PLL. The next parameter configuration can proceed after the PLL relock. The parameter P (**CPU_AXI_CFG_REG**[17:16]) is a digital post-frequency-division factor, which can be dynamically switched in real-time, without affecting the normal work of PLL.

NOTE

PLL_CPU supports dynamic frequency adjustment (modifying the value of N). However, for the system stability, to configure the frequency of the PLL_CPU from a higher value to a lower one, switch the clock source of the CPU to another clock whose frequency is not higher than the current one first, and configure PLL_CPU to the target low frequency, and then switch the clock source of the CPU back to PLL_CPU.

Follow the steps below to adjust the frequency of PLL_CPU:

Step 1 Before you configure PLL_CPU, switch the clock source of CPU to PLL_PERI(1X).

Step 2 Modify the parameters N and P of PLL_CPU.

Step 3 Write the PLL Lock Enable bit (bit[29]) of **PLL_CPU_CTRL_REG** to 0 and then to 1.

Step 4 Wait for the Lock bit (bit[28]) of **PLL_CPU_CTRL_REG** to change to 1.

Step 5 Switch the clock source of the CPU to PLL_CPU.

3.3.4.2 Configuring the Frequency of PLL_AUDIO

NOTE

PLL_AUDIO includes PLL_AUDIO0 and PLL_AUDIO1.

The frequency configuration formula of PLL_AUDIO:

PLL_AUDIO0 = 24 MHz*N/M0/M1/P/4

PLL_AUDIO1 = 24 MHz*N/M

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PLL_AUDIO does not support dynamic adjustment because changing any parameter of N, M0, M1, and P will affect the normal work of PLL, and the PLL will need to be relocked.

Generally, PLL_AUDIO only needs two frequency points: 24.576*4 MHz or 22.5792*4 MHz. For these two frequencies, there are usually special recommended matching factors. To implement the desired frequency point of PLL_AUDIO, you need to use the decimal frequency-division function, so follow the steps below:

Step 1 Configure the N, M0, M1 and P factors.

Step 2 Configure PLL_AUDIOx Control Register[PLL_SDM_ENABLE] to 1.

Step 3 Configure PLL_AUDIOx Pattern0 Control Register to enable the digital spread spectrum.

Step 4 Write PLL_AUDIOx Control Register[Lock Enable] to 0 and then to 1.

Step 5 Wait for PLL_AUDIOx Control Register[Lock] to 1.

NOTE

When the P factor of PLL_AUDIO is an odd number, the clock output is an unequal-duty-cycle signal.

The recommended values for configuration factors of PLL_AUDIO1 are as follows.

Table 3-6 Recommended Values for Configuration Factors of PLL_AUDIO1

Mode	Clock Source (MHz)	Frequency-doubling N	VCO (MHz)	Post Frequency-Division	PLL Output (MHz)	Divisor	Actual Operating Frequency (MHz)	Description
Integer divider	24	128	3072	2	1536	4	384	Provide clock source for peripherals
						8	192	
						16	96	
						.....		
				5	614.4	25	24.576	For audio-related modules
Decimal divider	24	98.304	2359.296	2	1179.648	2	589.824	Provides clock source for peripheral devices
						3	393.216	
						6	196.608	
						12	98.304	

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Mode	Clock Source (MHz)	Frequency-doubling N	VCO (MHz)	Post Frequency-Division	PLL Output (MHz)	Divisor	Actual Operating Frequency (MHz)	Description
						48	24.576	For audio-related modules
				5	471.8592			

3.3.4.3 Configuring the Frequency of General PLLs

Step 1 Make sure the PLL is enabled. If not, refer to section 3.3.4.4 Enabling the PLL to enable the PLL.

Step 2 Configure the PLL_OUTPUT_ENABLE bit (bit[27]) of the PLL control register as 0 to disable the output gate of the PLL because general PLLs are unavailable in the process of frequency modulation.

Step 3 Configure the N and M factors. (It is not suggested to configure M1 factor)

Step 4 Write the LOCK_ENABLE bit (bit[29]) of the PLL control register to 0 and then to 1.

Step 5 Wait for the LOCK bit (bit[28]) of the PLL control register to 1.

Step 6 Configure PLL_OUTPUT_ENABLE bit (bit[27]) of the PLL control register to 1.

3.3.4.4 Enabling the PLL

Follow the steps below to enable the PLL:

Step 1 Configure the N, M, and P factors of the PLL control register.

Step 2 Write the PLL_ENABLE bit and the LDO_EN bit of the PLL control register to 1, write the PLL_OUTPUT_GATE bit of the PLL control register to 0.

Step 3 Write the LOCK_ENABLE bit of the PLL control register to 1.

Step 4 Wait for the status of the Lock to change to 1.

Step 5 Delay 20 us.

Step 6 Write the PLL_OUTPUT_GATE bit of the PLL control register to 1 and then the PLL will be available.

3.3.4.5 Disabling the PLL

Follow the steps below to disable the PLL:

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Step 1 Write the PLL_ENABLE bit (bit[31]) and the LDO_EN bit of the PLL control register to 0.

Step 2 Write the LOCK_ENABLE bit (bit[29]) of the PLL control register to 0.

CAUTION

In the normal use of PLLs, it is unsuggested to enable and disable the PLLs frequently. Turning on and off the PLLs will cause mutual interference between PLLs, which will affect the stability of the system. When the clock is unnecessary, you can write 0 to the PLL_OUTPUT_EN bit of the PLL control register to disable the output gate of the PLL, instead of writing 0 to the Enable bit to disable the PLL.

3.3.4.6 Configuring Bus Clock

The bus clock supports dynamic switching, but the process of switching needs to follow the following two rules.

- From a higher frequency to a lower frequency: switch the clock source first, and then set the frequency division factor;
- From a lower frequency to a higher frequency: configure the frequency division factor first, and then switch the clock source.

3.3.4.7 Configuring Module Clocks

For the Bus Gating Reset register of a module, the reset bit is de-asserted first, and then the clock gating bit is enabled to avoid potential problems caused by the asynchronous release of the reset signal.

For all module clocks except the DDR clock, configure the clock source and frequency division factor first, and then release the clock gating (that is, set to 1). For the configuration order of the clock source and frequency division factor, follow the rules below:

- With the increasing of the clock source frequency, configure the frequency division factor before the clock source;
- With the decreasing of the clock source frequency, configure the clock source before the frequency division factor.

3.3.4.8 Implementing Spread Spectrum

The spread spectrum technology is to convert a narrowband signal into a wideband signal. It helps to reduce the effect of electromagnetic interference (EMI) associated with the fundamental frequency of the signal.

For the general PLL frequency, the calculation formula is as follows:

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$$f = \frac{N+1+X}{P\cdot(M0+1)\cdot(M1+1)}\cdot 24MHz, 0<X<1$$

Where,

P is the frequency division factor of module or PLL;

M0 is the post-frequency division factor of PLL;

M1 is the pre-frequency division factor of PLL;

N is the frequency doubling factor of PLL;

X is the amplitude coefficient of the spread spectrum.

The parameters N, P, M1, and M0 are for the frequency division.

When M1 = 0, M0 = 0, and P = 1 (no frequency division), the calculation formula of PLL frequency can be simplified as follows:

$$f = (N+1+X)\cdot 24MHz,\ 0<X<1$$

$$[f_1, f_2] = (N+1+[X_1, X_2])\cdot 24MHz$$

SDM_BOT = $2^{17} * X_1$

WAVE_STEP = $2^{17} * (X_2 – X_1)/(24MHz/PREQ)*2$

Where, SDM_BOT and WAVE_STEP are bits of the PLL pattern control register, and PREQ is the frequency of the spread spectrum.

NOTE

Different PLLs have different calculate formulas, refer to the CTRL register of the corresponding PLL in section 3.3.6 Register Description.

Configuration Procedure

Follow the steps below to implement the spread spectrum:

Step 1 Configure the control register of the corresponding PLL

a) Calculate the factor N and decimal value X according to the PLL frequency and PLL frequency formula. Refer to the control register of the corresponding PLL (named PLL_xxx_CTRL_REG, where xxx is the module name) in 3.3.6 Register Description for the corresponding PLL frequency formula.

b) Write M0, M1, N, and PLL frequency to the PLL control register.

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c) Configure the SDM_Enable bit (bit[24]) of the PLL control register to 1 to enable the spread spectrum function.

Step 2 Configure the pattern control register of the corresponding PLL

a) Calculate the SDM_BOT and WAVE_STEP of the pattern control register according to decimal value X and spread spectrum frequency (the bit[18:17] of the PLL_PAT register)

b) Configure the spread spectrum mode (SPR_FREQ_MODE) to 2 or 3.

c) If the bit PLL_INPUT_DIV2 of the PLL control register is 1, configure the spread spectrum clock source select bit (SDM_CLK_SEL) of the PLL pattern control register to 1. Otherwise, configure SDM_CLK_SEL to the default value 0.

d) Write SDM_BOT, WAVE_STEP, PREQ, SPR_FREQ_MODE, and SDM_CLK_SEL to the PLL pattern control register, and configure the SIG_DELT_PAT_EN bit (bit[31]) of this register to 1.

Step 3 Delay 20 us.

Configuration Example

The following example shows how to configure the spread spectrum frequency as 605.3 MHz to 609.7 MHz.

If M1 = 0, M0 = 0, P = 1, according to the formula $[f_1, f_2] = (N + 1 + [X_1, X_2]) \cdot 24MHz$, you can get:

$$N + 1 + [X_1, X_2] = \frac{[605.3, 609.7]}{24} = \frac{600 + [5.3, 9.7]}{24} = 24 + 1 + [5.3/24, 9.7/24]$$

Obviously,

N = 24, X_1 = 5.3/24, X_2 = 9.7/24

SDM_BOT = 2^{17} * X_1 = 0x7111

WAVE_STEP = 2^{17} * (X_2 – X_1) /(24M/PREQ)*2 = 0x3f; PREQ = 31.5 kHz

If M0 = 1, M1=0, P = 1, then total frequency division factor is (M0 + 1) *1 = 2, so the actual output frequency of PLL is 1212.1 MHz to 1219.4 MHz.

Similarly, you can get:

N = 49, X1 = 12.1/24, X2 = 19.4/24

Then calculate the values of SDM_BOT and WAVE_STEP according to the formulas, and follow the steps described in

Configuration Procedure

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3.3.5 Register List

Module Name	Base Address
CCU	0x02001000

Register Name	Offset	Description
PLL_CPU_CTRL_REG	0x0000	PLL_CPU Control Register
PLL_DDR_CTRL_REG	0x0010	PLL_DDR Control Register
PLL_PERI_CTRL_REG	0x0020	PLL_PERI Control Register
PLL_VIDEO0_CTRL_REG	0x0040	PLL_VIDEO0 Control Register
PLL_VIDEO1_CTRL_REG	0x0048	PLL_VIDEO1 Control Register
PLL_VE_CTRL_REG	0x0058	PLL_VE Control Register
PLL_AUDIO0_CTRL_REG	0x0078	PLL_AUDIO0 Control Register
PLL_AUDIO1_CTRL_REG	0x0080	PLL_AUDIO1 Control Register
PLL_DDR_PAT0_CTRL_REG	0x0110	PLL_DDR Pattern0 Control Register
PLL_DDR_PAT1_CTRL_REG	0x0114	PLL_DDR Pattern1 Control Register
PLL_PERI_PAT0_CTRL_REG	0x0120	PLL_PERI Pattern0 Control Register
PLL_PERI_PAT1_CTRL_REG	0x0124	PLL_PERI Pattern1 Control Register
PLL_VIDEO0_PAT0_CTRL_REG	0x0140	PLL_VIDEO0 Pattern0 Control Register
PLL_VIDEO0_PAT1_CTRL_REG	0x0144	PLL_VIDEO0 Pattern1 Control Register
PLL_VIDEO1_PAT0_CTRL_REG	0x0148	PLL_VIDEO1 Pattern0 Control Register
PLL_VIDEO1_PAT1_CTRL_REG	0x014C	PLL_VIDEO1 Pattern1 Control Register
PLL_VE_PAT0_CTRL_REG	0x0158	PLL_VE Pattern0 Control Register
PLL_VE_PAT1_CTRL_REG	0x015C	PLL_VE Pattern1 Control Register
PLL_AUDIO0_PAT0_CTRL_REG	0x0178	PLL_AUDIO0 Pattern0 Control Register
PLL_AUDIO0_PAT1_CTRL_REG	0x017C	PLL_AUDIO0 Pattern1 Control Register
PLL_AUDIO1_PAT0_CTRL_REG	0x0180	PLL_AUDIO1 Pattern0 Control Register
PLL_AUDIO1_PAT1_CTRL_REG	0x0184	PLL_AUDIO1 Pattern1 Control Register
PLL_CPU_BIAS_REG	0x0300	PLL_CPU Bias Register
PLL_DDR_BIAS_REG	0x0310	PLL_DDR Bias Register
PLL_PERI_BIAS_REG	0x0320	PLL_PERI Bias Register
PLL_VIDEO0_BIAS_REG	0x0340	PLL_VIDEO0 Bias Register
PLL_VIDEO1_BIAS_REG	0x0348	PLL_VIDEO1 Bias Register
PLL_VE_BIAS_REG	0x0358	PLL_VE Bias Register
PLL_AUDIO0_BIAS_REG	0x0378	PLL_AUDIO0 Bias Register

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Register Name	Offset	Description
PLL_AUDIO1_BIAS_REG	0x0380	PLL_AUDIO1 Bias Register
PLL_CPU_TUN_REG	0x0400	PLL_CPU Tuning Register
CPU_AXI_CFG_REG	0x0500	CPU_AXI Configuration Register
CPU_GATING_REG	0x0504	CPU_GATING Configuration Register
PSI_CLK_REG	0x0510	PSI Clock Register
APB0_CLK_REG	0x0520	APB0 Clock Register
APB1_CLK_REG	0x0524	APB1 Clock Register
MBUS_CLK_REG	0x0540	MBUS Clock Register
DE_CLK_REG	0x0600	DE Clock Register
DE_BGR_REG	0x060C	DE Bus Gating Reset Register
DI_CLK_REG	0x0620	DI Clock Register
DI_BGR_REG	0x062C	DI Bus Gating Reset Register
G2D_CLK_REG	0x0630	G2D Clock Register
G2D_BGR_REG	0x063C	G2D Bus Gating Reset Register
CE_CLK_REG	0x0680	CE Clock Register
CE_BGR_REG	0x068C	CE Bus Gating Reset Register
VE_CLK_REG	0x0690	VE Clock Register
VE_BGR_REG	0x069C	VE Bus Gating Reset Register
DMA_BGR_REG	0x070C	DMA Bus Gating Reset Register
MSGBOX_BGR_REG	0x071C	MSGBOX Bus Gating Reset Register
SPINLOCK_BGR_REG	0x072C	SPINLOCK Bus Gating Reset Register
HSTIMER_BGR_REG	0x073C	HSTIMER Bus Gating Reset Register
AVS_CLK_REG	0x0740	AVS Clock Register
DBGSYS_BGR_REG	0x078C	DBGSYS Bus Gating Reset Register
PWM_BGR_REG	0x07AC	PWM Bus Gating Reset Register
IOMMU_BGR_REG	0x07BC	IOMMU Bus Gating Reset Register
DRAM_CLK_REG	0x0800	DRAM Clock Register
MBUS_MAT_CLK_GATING_REG	0x0804	MBUS Master Clock Gating Register
DRAM_BGR_REG	0x080C	DRAM Bus Gating Reset Register
SMHC0_CLK_REG	0x0830	SMHC0 Clock Register
SMHC1_CLK_REG	0x0834	SMHC1 Clock Register
SMHC2_CLK_REG	0x0838	SMHC2 Clock Register
SMHC_BGR_REG	0x084C	SMHC Bus Gating Reset Register
UART_BGR_REG	0x090C	UART Bus Gating Reset Register

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Register Name	Offset	Description
TWI_BGR_REG	0x091C	TWI Bus Gating Reset Register
SPI0_CLK_REG	0x0940	SPI0 Clock Register
SPI1_CLK_REG	0x0944	SPI1 Clock Register
SPI_BGR_REG	0x096C	SPI Bus Gating Reset Register
EMAC_25M_CLK_REG	0x0970	EMAC_25M Clock Register
EMAC_BGR_REG	0x097C	EMAC Bus Gating Reset Register
IRTX_CLK_REG	0x09C0	IRTX Clock Register
IRTX_BGR_REG	0x09CC	IRTX Bus Gating Reset Register
GPADC_BGR_REG	0x09EC	GPADC Bus Gating Reset Register
THS_BGR_REG	0x09FC	THS Bus Gating Reset Register
I2S0_CLK_REG	0x0A10	I2S0 Clock Register
I2S1_CLK_REG	0x0A14	I2S1 Clock Register
I2S2_CLK_REG	0x0A18	I2S2 Clock Register
I2S2_ASRC_CLK_REG	0x0A1C	I2S2_ASRC Clock Register
I2S_BGR_REG	0x0A20	I2S Bus Gating Reset Register
OWA_TX_CLK_REG	0x0A24	OWA_TX Clock Register
OWA_BGR_REG	0x0A2C	OWA Bus Gating Reset Register
DMIC_CLK_REG	0x0A40	DMIC Clock Register
DMIC_BGR_REG	0x0A4C	DMIC Bus Gating Reset Register
AUDIO_CODEC_DAC_CLK_REG	0x0A50	AUDIO_CODEC_DAC Clock Register
AUDIO_CODEC_ADC_CLK_REG	0x0A54	AUDIO_CODEC_ADC Clock Register
AUDIO_CODEC_BGR_REG	0x0A5C	AUDIO_CODEC Bus Gating Reset Register
USB0_CLK_REG	0x0A70	USB0 Clock Register
USB1_CLK_REG	0x0A74	USB1 Clock Register
USB_BGR_REG	0x0A8C	USB Bus Gating Reset Register
DPSS_TOP_BGR_REG	0x0ABC	DPSS_TOP Bus Gating Reset Register
DSI_CLK_REG	0x0B24	DSI Clock Register
DSI_BGR_REG	0x0B4C	DSI Bus Gating Reset Register
TCONLCD_CLK_REG	0x0B60	TCONLCD Clock Register
TCONLCD_BGR_REG	0x0B7C	TCONLCD Bus Gating Reset Register
LVDS_BGR_REG	0x0BAC	LVDS Bus Gating Reset Register
LEDC_CLK_REG	0x0BF0	LEDC Clock Register
LEDC_BGR_REG	0x0BFC	LEDC Bus Gating Reset Register
CSI_CLK_REG	0x0C04	CSI Clock Register

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Register Name	Offset	Description
CSI_MASTER_CLK_REG	0x0C08	CSI Master Clock Register
CSI_BGR_REG	0x0C1C	CSI Bus Gating Reset Register
TPADC_CLK_REG	0x0C50	TPADC Clock Register
TPADC_BGR_REG	0x0C5C	TPADC Bus Gating Reset Register
TZMA_BGR_REG	0x0C6C	TZMA Bus Gating Reset Register
DSP_CLK_REG	0x0C70	DSP Clock Register
DSP_BGR_REG	0x0C7C	DSP Bus Gating Reset Register
CCU_SEC_SWITCH_REG	0x0F00	CCU Security Switch Register
PLL_LOCK_DBG_CTRL_REG	0x0F04	PLL Lock Debug Control Register
FRE_DET_CTRL_REG	0x0F08	Frequency Detect Control Register
FRE_UP_LIM_REG	0x0F0C	Frequency Up Limit Register
FRE_DOWN_LIM_REG	0x0F10	Frequency Down Limit Register
CCU_FAN_GATE_REG	0x0F30	CCU FANOUT CLOCK GATE Register
CLK27M_FAN_REG	0x0F34	CLK27M FANOUT Register
PCLK_FAN_REG	0x0F38	PCLK FANOUT Register
CCU_FAN_REG	0x0F3C	CCU FANOUT Register

3.3.6 Register Description

NOTE

In secure mode, these registers from 0x0000 offset to 0x0540 offset are secure registers and can only be accessed by the secure host.

For 0x0000 offset to 0x0400 offset, the secure control bit is in the bit0 of **CCU_SEC_SWITCH_REG**.

For 0x0500 offset to 0x0524 offset, the secure control bit is in the bit1 of **CCU_SEC_SWITCH_REG**.

For 0x0540, 0x0804 offset, the secure control bit is in the bit2 of **CCU_SEC_SWITCH_REG**

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3.3.6.1 0x0000 PLL_CPU Control Register (Default Value: 0x4A00_1000)

Offset: 0x0000			Register Name: PLL_CPU_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	PLL_EN PLL Enable 0: Disable 1: Enable The PLL_CPU= InputFreq*N. **The PLL_CPU output frequency must be in the range from 200 MHz to 3 GHz. And the default value of PLL_CPU is 408 MHz when the crystal oscillator is 24 MHz.**
30	R/W	0x1	PLL_LDO_EN LDO Enable 0: Disable 1: Enable
29	R/W	0x0	LOCK_ENABLE Lock Enable 0: Disable 1: Enable
28	R	0x0	LOCK PLL Lock Status 0: Unlocked 1: Locked (It indicates that the PLL has been stable.)
27	R/W	0x1	PLL_OUTPUT_GATE PLL Output Gating Enable 0: Disable 1: Enable The bit is used to control the output enable of the PLL.
26:24	R/W	0x2	PLL_LOCK_TIME. PLL Lock Time The bit indicates the step amplitude from one frequency to another.
23:16	/	/	/
15:8	R/W	0x10	PLL_N PLL N N= PLL_N +1 PLL_N is from 0 to 254. In application, PLL_N shall be more than or equal to 12.

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Offset: 0x0000			Register Name: PLL_CPU_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
7:6	R/W	0x0	PLL_UNLOCK_MDSEL PLL Unlock Level 00: 21-29 Clock Cycles 01: 22-28 Clock Cycles 1X: 20-30 Clock Cycles
5	R/W	0x0	PLL_LOCK_MDSEL PLL Lock Level 0: 24-26 Clock Cycles 1: 23-27 Clock Cycles
4:2	/	/	/
1:0	R/W	0x0	PLL_M PLL_M M = PLL_FACTOR_M + 1 PLL_FACTOR_M is from 0 to 3. **Note: The M factor is only for testing.**

3.3.6.2 0x0010 PLL_DDR Control Register (Default Value: 0x4800_2301)

Offset: 0x0010			Register Name: PLL_DDR_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	PLL_EN 0: Disable 1: Enable PLL_DDR = InputFreq*N/M1/M0. **The default value of PLL_DDR is 432 MHz when the crystal oscillator is 24 MHz.**
30	R/W	0x1	PLL_LDO_EN LDO ENABLE 0: Disable 1: Enable
29	R/W	0x0	LOCK_ENABLE Lock Enable 0: Disable 1: Enable

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Offset: 0x0010			Register Name: PLL_DDR_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
28	R	0x0	LOCK PLL Lock 0: Unlocked 1: Locked (It indicates that the PLL has been stable.)
27	R/W	0x1	PLL_OUTPUT_GATE PLL Output Gating Enable 0: Disable 1: Enable The bit is used to control the output enable of the PLL.
26:25	/	/	/
24	R/W	0x0	PLL_SDM_EN PLL SDM Enable 0: Disable 1: Enable
23:16	/	/	/
15:8	R/W	0x23	PLL_N PLL N N= PLL_N +1 PLL_N is from 0 to 254. In application, PLL_N shall be more than or equal to 12.
7:6	R/W	0x0	PLL_UNLOCK_MDSEL PLL Unlock Level 00: 21-29 Clock Cycles 01: 22-28 Clock Cycles 1X: 20-30 Clock Cycles
5	R/W	0x0	PLL_LOCK_MDSEL PLL Lock Level 0: 24-26 Clock Cycles 1: 23-27 Clock Cycles
4:2	/	/	/
1	R/W	0x0	PLL_INPUT_DIV2 PLL Input Div M1 M1=PLL_INPUT_DIV2 + 1 PLL_INPUT_DIV2 is from 0 to 1.

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Offset: 0x0010			Register Name: PLL_DDR_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x1	PLL_OUTPUT_DIV2 PLL Output Div M0 M0=PLL_OUTPUT_DIV2 + 1 PLL_OUTPUT_DIV2 is from 0 to 1.

3.3.6.3 0x0020 PLL_PERI Control Register (Default Value: 0x4821_6300)

Offset: 0x0020			Register Name: PLL_PERI_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	PLL_EN PLL Enable 0: Disable 1: Enable PLL_PERI(2X) = 24 MHz*N/M/P0 PLL_PERI(1X) = 24 MHz*N/M/P0/2 PLL_PERI(800M) = 24 MHz*N/M/P1. When the crystal oscillator is 24 MHz, the default frequency of PLL_PERI(2X) is 1.2 GHz, the default frequency of PLL_PERI(1X) is 600 MHz, and the default frequency of PLL_PERI(800M) is 800 MHz. **The output clock of PLL_PERI(2X) is fixed to 1.2 GHz and not suggested to change the parameter.**
30	R/W	0x1	PLL_LDO_EN LDO Enable 0: Disable 1: Enable
29	R/W	0x0	LOCK_ENABLE Lock Enable 0: Disable 1: Enable
28	R	0x0	LOCK PLL Lock 0: Unlocked 1: Locked (It indicates that the PLL has been stable.)

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Offset: 0x0020			Register Name: PLL_PERI_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
27	R/W	0x1	PLL_OUTPUT_GATE PLL Output Gating Enable 0: Disable 1: Enable The bit is used to control the output enable of PLL.
26:25	/	/	/
24	R/W	0x0	PLL_SDM_EN PLL SDM Enable 0: Disable 1: Enable Enable spread spectrum and decimal division.
23	/	/	/
22:20	R/W	0x2	PLL_P1 PLL Output Div P1 P1=PLL_OUTPUT_DIV_P1 + 1 PLL_OUTPUT_DIV_P1 is from 0 to 7.
19	/	/	/
18:16	R/W	0x1	PLL_P0 PLL Output Div P0 P0=PLL_OUTPUT_DIV_P0 + 1 PLL_OUTPUT_DIV_P0 is from 0 to 7.
15:8	R/W	0x63	PLL_N PLL N N= PLL_N +1 PLL_N is from 0 to 254. In application, PLL_N shall be more than or equal to 12.
7:6	R/W	0x0	PLL_UNLOCK_MDSEL PLL Unlock Level 00: 21-29 Clock Cycles 01: 22-28 Clock Cycles 1X: 20-30 Clock Cycles
5	R/W	0x0	PLL_LOCK_MDSEL PLL Lock Level 0: 24-26 Clock Cycles 1: 23-27 Clock Cycles
4:2	/	/	/

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Offset: 0x0020			Register Name: PLL_PERI_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	PLL_INPUT_DIV2 PLL Input Div M M1=PLL_INPUT_DIV2 + 1 PLL_INPUT_DIV2 is from 0 to 1.
0	/	/	/

3.3.6.4 0x0040 PLL_VIDEO0 Control Register (Default Value: 0x4800_6203)

Offset: 0x0040			Register Name: PLL_VIDEO0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	PLL_EN PLL Enable 0: Disable 1: Enable For application, PLL_VIDEO0(4X)=InputFreq *N/M. PLL_VIDEO0(2X)= InputFreq *N/M/2. PLL_VIDEO0(1X)= InputFreq *N/M/4. When the HOSC is 24 MHz, the default frequency of PLL_VIDEO0(4X) is 1188 MHz.
30	R/W	0x1	PLL_LDO_EN LDO Enable 0: Disable 1: Enable
29	R/W	0x0	LOCK_ENABLE Lock Enable 0: Disable 1: Enable
28	R	0x0	LOCK PLL Lock 0: Unlocked 1: Locked (It indicates that the PLL has been stable.)

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Offset: 0x0040			Register Name: PLL_VIDEO0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
27	R/W	0x1	PLL_OUTPUT_GATE PLL Output Gating Enable 0: Disable 1: Enable The bit is used to control the output enable of PLL.
26:25	/	/	/
24	R/W	0x0	PLL_SDM_EN PLL SDM Enable 0: Disable 1: Enable
23:16	/	/	/
15:8	R/W	0x62	PLL_N PLL N N= PLL_N +1 PLL_N is from 0 to 254. In application, PLL_N shall be more than or equal to 12.
7:6	R/W	0x0	PLL_UNLOCK_MDSEL PLL Unlock Level 00: 21-29 Clock Cycles 01: 22-28 Clock Cycles 1X: 20-30 Clock Cycles
5	R/W	0x0	PLL_LOCK_MDSEL PLL Lock Level 0: 24-26 Clock Cycles 1: 23-27 Clock Cycles
4:2	/	/	/
1	R/W	0x1	PLL_INPUT_DIV2 PLL Input Div M M1=PLL_INPUT_DIV_M + 1 PLL_INPUT_DIV_M is from 0 to 1.
0	R/W	0x1	PLL_OUTPUT_DIV2 PLL Output Div D (The factor is only for testing) M0=PLL_OUTPUT_DIV_D + 1 PLL_OUTPUT_DIV_D is from 0 to 1. For test, PLL_VIDEO0(4X) =24MHz*N/M/D

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3.3.6.5 0x0048 PLL_VIDEO1 Control Register (Default Value: 0x4800_6203)

Offset: 0x0048			Register Name: PLL_VIDEO1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	PLL_EN PLL Enable 0: Disable 1: Enable For application, PLL_VIDEO1(4X)=InputFreq *N/M. PLL_VIDEO1(2X)= InputFreq *N/M/2. PLL_VIDEO1(1X)= InputFreq *N/M/4. When the HOSC is 24 MHz, the default frequency of PLL_VIDEO1(4X) is 1188 MHz.
30	R/W	0x1	PLL_LDO_EN LDO Enable 0: Disable 1: Enable
29	R/W	0x0	LOCK_ENABLE Lock Enable 0: Disable 1: Enable
28	R	0x0	LOCK PLL Lock 0: Unlocked 1: Locked (It indicates that the PLL has been stable.)
27	R/W	0x1	PLL_OUTPUT_GATE PLL Output Gating Enable 0: Disable 1: Enable The bit is used to control the output enable of PLL.
26:25	/	/	/
24	R/W	0x0	PLL_SDM_EN PLL SDM Enable 0: Disable 1: Enable
23:16	/	/	/

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Offset: 0x0048			Register Name: PLL_VIDEO1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
15:8	R/W	0x62	PLL_FACTOR_N PLL FACTOR N N= PLL_FACTOR_N +1 PLL_FACTOR_N is from 0 to 254. In application, PLL_FACTOR_N shall be more than or equal to 12.
7:6	R/W	0x0	PLL_UNLOCK_MDSEL PLL Unlock Level 00: 21-29 Clock Cycles 01: 22-28 Clock Cycles 1X: 20-30 Clock Cycles
5	R/W	0x0	PLL_LOCK_MDSEL PLL Lock Level 0: 24-26 Clock Cycles 1: 23-27 Clock Cycles
4:2	/	/	/
1	R/W	0x1	PLL_INPUT_DIV2 PLL Input Div M M1=PLL_INPUT_DIV_M + 1 PLL_INPUT_DIV_M is from 0 to 1.
0	R/W	0x1	PLL_OUTPUT_DIV2 PLL Output Div D.(The factor is only for testing) M0=PLL_OUTPUT_DIV_D + 1 PLL_OUTPUT_DIV_D is from 0 to 1. For test, PLL_VIDEO1(4X) =24MHz*N/M/D

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3.3.6.6 0x0058 PLL_VE Control Register (Default Value: 0x4800_2301)

Offset: 0x0058			Register Name: PLL_VE_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	PLL_EN PLL Enable 0: Disable 1: Enable PLL_VE = InputFreq*N/M1/M0. When the HOSC is 24 MHz, the default frequency of PLL_VE is 432 MHz.
30	R/W	0x1	PLL_LDO_EN LDO Enable 0: Disable 1: Enable
29	R/W	0x0	LOCK_ENABLE Lock Enable 0: Disable 1: Enable
28	R	0x0	LOCK PLL Lock 0: Unlocked 1: Locked (It indicates that the PLL has been stable.)
27	R/W	0x1	PLL_OUTPUT_GATE PLL Output Gating Enable 0: Disable 1: Enable The bit is used to control the output enable of PLL.
26:25	/	/	/
24	R/W	0x0	PLL_SDM_EN PLL SDM Enable 0: Disable 1: Enable
23:16	/	/	/

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Offset: 0x0058			Register Name: PLL_VE_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
15:8	R/W	0x23	PLL_N PLL N N= PLL_N +1 PLL_N is from 0 to 254. In application, PLL_N shall be more than or equal to 12.
7:6	R/W	0x0	PLL_UNLOCK_MDSEL PLL Unlock Level 00: 21-29 Clock Cycles 01: 22-28 Clock Cycles 1X: 20-30 Clock Cycles
5	R/W	0x0	PLL_LOCK_MDSEL PLL Lock Level 0: 24-26 Clock Cycles 1: 23-27 Clock Cycles
4:2	/	/	/
1	R/W	0x0	PLL_INPUT_DIV2 PLL Input Div M1 M1=PLL_INPUT_DIV2 + 1 PLL_INPUT_DIV2 is from 0 to 1.
0	R/W	0x1	PLL_OUTPUT_DIV2 PLL Output Div M0 M0=PLL_OUTPUT_DIV2 + 1 PLL_OUTPUT_DIV2 is from 0 to 1.

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3.3.6.7 0x0078 PLL_AUDIO0 Control Register (Default Value: 0x4814_5500)

Offset: 0x0078			Register Name: PLL_AUDIO0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	PLL_EN PLL Enable 0: Disable 1: Enable PLL_AUDIO0(4X) = 24MHz*N/M1/M0/P PLL_AUDIO0(2X) = (24MHz*N/M1/M0)/P/2 PLL_AUDIO0(1X) = (24MHz*N/M1/M0)/P/4 **Note: 7.5≤N/M0/M1≤125 and 12≤N** The working frequency range of 24MHz*N/M0/M1 is from 180 MHz to 3.0 GHz. The default frequency of PLL_AUDIO0(1X) is 24.5714 MHz.
30	R/W	0x1	PLL_LDO_EN LDO Enable 0: Disable 1: Enable
29	R/W	0x0	LOCK_ENABLE Lock Enable 0: Disable 1: Enable
28	R	0x0	LOCK PLL Lock 0: Unlocked 1: Locked (It indicates that the PLL has been stable.) **Note: The bit is only valid when the bit29 is set to 1.**
27	R/W	0x1	PLL_OUTPUT_GATE 0: Disable 1: Enable The bit is used to control the output enable of PLL.
26:25	/	/	/
24	R/W	0x0	PLL_SDM_EN PLL SDM Enable 0: Disable 1: Enable Enable spread spectrum and decimal division.
23:22	/	/	/

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Offset: 0x0078			Register Name: PLL_AUDIO0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
21:16	R/W	0x14	PLL_P PLL Post-div P P= PLL_POST_DIV_P +1 PLL_POST_DIV_P is from 0 to 63.
15:8	R/W	0x55	PLL_N PLL N N= PLL_N +1 PLL_N is from 0 to 254. In application, PLL_N shall be more than or equal to 12.
7:6	R/W	0x0	PLL_UNLOCK_MDSEL PLL Unlock Level 00: 21-29 Clock Cycles 01: 22-28 Clock Cycles 1X: 20-30 Clock Cycles
5	R/W	0x0	PLL_LOCK_MDSEL PLL Lock Level 0: 24-26 Clock Cycles 1: 23-27 Clock Cycles
4:2	/	/	/
1	R/W	0x0	PLL_INPUT_DIV2 PLL Input Div M1 M1=PLL_INPUT_DIV2 + 1 PLL_INPUT_DIV2 is from 0 to 1.
0	R/W	0x0	PLL_OUTPUT_DIV2 PLL Output Div M0 M0=PLL_OUTPUT_DIV2 + 1 PLL_OUTPUT_DIV2 is from 0 to 1.

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3.3.6.8 0x0080 PLL_AUDIO1 Control Register (Default Value: 0x4841_7F00)

Offset: 0x0080			Register Name: PLL_AUDIO1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	PLL_EN PLL Enable 0: Disable 1: Enable PLL_AUDIO1 = 24MHz*N/M PLL_AUDIO1(DIV2) = 24MHz*N/M/P0 PLL_AUDIO1(DIV5) = 24MHz*N/M/P1 The working frequency range of 24 MHz/M*N is from 180 MHz to 3.5 GHz. The default frequency of PLL_AUDIO1 is 3072 MHz. The default frequency of PLL_AUDIO1(DIV2) is 1536 MHz. The default frequency of PLL_AUDIO1(DIV5) is 614.4 MHz (24.576 MHz*25).
30	R/W	0x1	PLL_LDO_EN LDO Enable 0: Disable 1: Enable
29	R/W	0x0	LOCK_ENABLE Lock Enable 0: Disable 1: Enable
28	R	0x0	LOCK 0: Unlocked 1: Locked (It indicates that the PLL has been stable.) **Note: The bit is only valid when the bit29 is set to 1.**
27	R/W	0x1	PLL_OUTPUT_GATE 0: Disable 1: Enable The bit is used to control the output enable of PLL.
26:25	/	/	/
24	R/W	0x0	PLL_SDM_EN 0: Disable 1: Enable Enable spread spectrum and decimal division.
23	/	/	/

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Offset: 0x0080			Register Name: PLL_AUDIO1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
22:20	R/W	0x4	PLL_P1 PLL Output Div P1 P1=PLL_OUTPUT_DIV_P1 + 1 PLL_OUTPUT_DIV_P1 is from 0 to 7.
19	/	/	/
18:16	R/W	0x1	PLL_P0 PLL Output Div P0 P0=PLL_OUTPUT_DIV_P0 + 1 PLL_OUTPUT_DIV_P0 is from 0 to 7.
15:8	R/W	0x7F	PLL_N PLL N N= PLL_N +1 PLL_N is from 0 to 254. In application, PLL_N shall be more than or equal to 12.
7:6	R/W	0x0	PLL_UNLOCK_MDSEL PLL Unlock Level 00: 21-29 Clock Cycles 01: 22-28 Clock Cycles 1X: 20-30 Clock Cycles
5	R/W	0x0	PLL_LOCK_MDSEL PLL Lock Level 0: 24-26 Clock Cycles 1: 23-27 Clock Cycles
4:2	/	/	/
1	R/W	0x0	PLL_INPUT_DIV2 PLL Input Div M M=PLL_INPUT_DIV_M + 1 PLL_INPUT_DIV_M is from 0 to 1.
0	/	/	/

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3.3.6.9 0x0110 PLL_DDR Pattern0 Control Register (Default Value: 0x0000_0000)

Offset: 0x0110			Register Name: PLL_DDR_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SIG_DELT_PAT_EN Sigma-Delta Pattern Enable
30:29	R/W	0x0	SPR_FREQ_MODE Spread Frequency Mode 00: DC=0 01: DC=1 10: Triangular(1-bit) 11: Triangular(n-bit)
28:20	R/W	0x0	WAVE_STEP Wave Step
19	R/W	0x0	SDM_CLK_SEL SDM Clock Select 0: 24 MHz 1: 12 MHz **Note: When the PLL_INPUT_DIV2 is 1, the bit needs to be set to 1.**
18:17	R/W	0x0	FREQ Frequency 00: 31.5 kHz 01: 32 kHz 10: 32.5 kHz 11: 33 kHz
16:0	R/W	0x0	WAVE_BOT Wave Bottom

3.3.6.10 0x0114 PLL_DDR Pattern1 Control Register (Default Value: 0x0000_0000)

Offset: 0x0114			Register Name: PLL_DDR_PAT1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	DITHER_EN Dither Enable
23:21	/	/	/

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Offset: 0x0114			Register Name: PLL_DDR_PAT1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
20	R/W	0x0	FRAC_EN Fraction Enable
19:17	/	/	/
16:0	R/W	0x0	FRAC_IN Fraction In

3.3.6.11 0x0120 PLL_PERI Pattern0 Control Register (Default Value: 0x0000_0000)

Offset: 0x0120			Register Name: PLL_PERI_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SIG_DELT_PAT_EN Sigma-Delta Pattern Enable
30:29	R/W	0x0	SPR_FREQ_MODE Spread Frequency Mode 00: DC=0 01: DC=1 10: Triangular(1-bit) 11: Triangular(n-bit)
28:20	R/W	0x0	WAVE_STEP Wave Step
19	R/W	0x0	SDM_CLK_SEL SDM Clock Select 0: 24 MHz 1: 12 MHz **Note: When the PLL_INPUT_DIV2 is 1, the bit needs to be set to 1.**
18:17	R/W	0x0	FREQ Frequency 00: 31.5 kHz 01: 32 kHz 10: 32.5 kHz 11: 33 kHz
16:0	R/W	0x0	WAVE_BOT Wave Bottom

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3.3.6.12 0x0124 PLL_PERI Pattern1 Control Register (Default Value: 0x0000_0000)

Offset: 0x0124			Register Name: PLL_PERI_PAT1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	DITHER_EN Dither Enable
23:21	/	/	/
20	R/W	0x0	FRAC_EN Fraction Enable
19:17	/	/	/
16:0	R/W	0x0	FRAC_IN Fraction In

3.3.6.13 0x0140 PLL_VIDEO0 Pattern0 Control Register (Default Value: 0x0000_0000)

Offset: 0x0140			Register Name: PLL_VIDEO0_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SIG_DELT_PAT_EN Sigma-Delta Pattern Enable
30:29	R/W	0x0	SPR_FREQ_MODE Spread Frequency Mode 00: DC=0 01: DC=1 10: Triangular(1-bit) 11: Triangular(n-bit)
28:20	R/W	0x0	WAVE_STEP Wave Step
19	R/W	0x0	SDM_CLK_SEL SDM Clock Select 0: 24 MHz 1: 12 MHz **Note: When the PLL_INPUT_DIV2 is 1, the bit needs to be set to 1.**

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Offset: 0x0140			Register Name: PLL_VIDEO0_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
18:17	R/W	0x0	FREQ Frequency 00: 31.5 kHz 01: 32 kHz 10: 32.5 kHz 11: 33 kHz
16:0	R/W	0x0	WAVE_BOT Wave Bottom

3.3.6.14 0x0144 PLL_VIDEO0 Pattern1 Control Register (Default Value: 0x0000_0000)

Offset: 0x0144			Register Name: PLL_VIDEO0_PAT1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	DITHER_EN Dither Enable
23:21	/	/	/
20	R/W	0x0	FRAC_EN Fraction Enable
19:17	/	/	/
16:0	R/W	0x0	FRAC_IN Fraction In

3.3.6.15 0x0148 PLL_VIDEO1 Pattern0 Control Register (Default Value: 0x0000_0000)

Offset: 0x0148			Register Name: PLL_VIDEO1_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SIG_DELT_PAT_EN Sigma-Delta Pattern Enable

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Offset: 0x0148			Register Name: PLL_VIDEO1_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
30:29	R/W	0x0	SPR_FREQ_MODE Spread Frequency Mode 00: DC=0 01: DC=1 10: Triangular(1-bit) 11: Triangular(n-bit)
28:20	R/W	0x0	WAVE_STEP Wave Step
19	R/W	0x0	SDM_CLK_SEL SDM Clock Select 0: 24 MHz 1: 12 MHz **Note: When the PLL_INPUT_DIV2 is 1, the bit needs to be set to 1.**
18:17	R/W	0x0	FREQ Frequency 00: 31.5 kHz 01: 32 kHz 10: 32.5 kHz 11: 33 kHz
16:0	R/W	0x0	WAVE_BOT Wave Bottom

3.3.6.16 0x014C PLL_VIDEO1 Pattern1 Control Register (Default Value: 0x0000_0000)

Offset: 0x014C			Register Name: PLL_VIDEO1_PAT1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	DITHER_EN Dither Enable
23:21	/	/	/
20	R/W	0x0	FRAC_EN Fraction Enable
19:17	/	/	/

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Offset: 0x014C			Register Name: PLL_VIDEO1_PAT1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
16:0	R/W	0x0	FRAC_IN Fraction In

3.3.6.17 0x0158 PLL_VE Pattern0 Control Register (Default Value: 0x0000_0000)

Offset: 0x0158			Register Name: PLL_VE_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SIG_DELT_PAT_EN Sigma-Delta Pattern Enable
30:29	R/W	0x0	SPR_FREQ_MODE Spread Frequency Mode 00: DC=0 01: DC=1 10: Triangular(1-bit) 11: Triangular(n-bit)
28:20	R/W	0x0	WAVE_STEP Wave Step
19	R/W	0x0	SDM_CLK_SEL SDM Clock Select 0: 24 MHz 1: 12 MHz **Note: When the PLL_INPUT_DIV2 is 1, the bit needs to be set to 1.**
18:17	R/W	0x0	FREQ Frequency 00: 31.5 kHz 01: 32 kHz 10: 32.5 kHz 11: 33 kHz
16:0	R/W	0x0	WAVE_BOT Wave Bottom

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3.3.6.18 0x015C PLL_VE Pattern1 Control Register (Default Value: 0x0000_0000)

Offset: 0x015C			Register Name: PLL_VE_PAT1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	DITHER_EN Dither Enable
23:21	/	/	/
20	R/W	0x0	FRAC_EN Fraction Enable
19:17	/	/	/
16:0	R/W	0x0	FRAC_IN Fraction In

3.3.6.19 0x0178 PLL_AUDIO0 Pattern0 Control Register (Default Value: 0x0000_0000)

Offset: 0x0178			Register Name: PLL_AUDIO0_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SIG_DELT_PAT_EN Sigma-Delta Pattern Enable
30:29	R/W	0x0	SPR_FREQ_MODE Spread Frequency Mode 00: DC=0 01: DC=1 10: Triangular(1-bit) 11: Triangular(n-bit)
28:20	R/W	0x0	WAVE_STEP Wave Step
19	R/W	0x0	SDM_CLK_SEL SDM Clock Select 0: 24 MHz 1: 12 MHz **Note: When the PLL_INPUT_DIV2 is 1, the bit needs to be set to 1.**

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Offset: 0x0178			Register Name: PLL_AUDIO0_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
18:17	R/W	0x0	FREQ Frequency 00: 31.5 kHz 01: 32 kHz 10: 32.5 kHz 11: 33 kHz
16:0	R/W	0x0	WAVE_BOT Wave Bottom

3.3.6.20 0x017C PLL_AUDIO0 Pattern1 Control Register (Default Value: 0x0000_0000)

Offset: 0x017C			Register Name: PLL_AUDIO0_PAT1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	DITHER_EN Dither Enable
23:21	/	/	/
20	R/W	0x0	FRAC_EN Fraction Enable
19:17	/	/	/
16:0	R/W	0x0	FRAC_IN Fraction In

3.3.6.21 0x0180 PLL_AUDIO1 Pattern0 Control Register (Default Value: 0x0000_0000)

Offset: 0x0180			Register Name: PLL_AUDIO1_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SIG_DELT_PAT_EN Sigma-Delta Pattern Enable

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Offset: 0x0180			Register Name: PLL_AUDIO1_PAT0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
30:29	R/W	0x0	SPR_FREQ_MODE Spread Frequency Mode 00: DC=0 01: DC=1 10: Triangular(1-bit) 11: Triangular(n-bit)
28:20	R/W	0x0	WAVE_STEP Wave Step
19	R/W	0x0	SDM_CLK_SEL SDM Clock Select 0: 24 MHz 1: 12 MHz **Note: When the PLL_INPUT_DIV2 is 1, the bit needs to be set to 1.**
18:17	R/W	0x0	FREQ Frequency 00: 31.5 kHz 01: 32 kHz 10: 32.5 kHz 11: 33 kHz
16:0	R/W	0x0	WAVE_BOT Wave Bottom

3.3.6.22 0x0184 PLL_AUDIO1 Pattern1 Control Register (Default Value: 0x0000_0000)

Offset: 0x0184			Register Name: PLL_AUDIO1_PAT1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	DITHER_EN Dither Enable
23:21	/	/	/
20	R/W	0x0	FRAC_EN Fraction Enable
19:17	/	/	/

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Offset: 0x0184			Register Name: PLL_AUDIO1_PAT1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
16:0	R/W	0x0	FRAC_IN Fraction In

3.3.6.23 0x0300 PLL_CPU Bias Register (Default Value: 0x8010_0000)

Offset: 0x0300			Register Name: PLL_CPU_BIAS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x1	PLL_VCO_RST_IN VCO reset in
30:21	/	/	/
20:16	R/W	0x10	PLL_CP PLL current bias control
15:0	/	/	/

3.3.6.24 0x0310 PLL_DDR Bias Register (Default Value: 0x0003_0000)

Offset: 0x0310			Register Name: PLL_DDR_BIAS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:21	/	/	/
20:16	R/W	0x3	PLL_CP PLL bias control
15:0	/	/	/

3.3.6.25 0x0320 PLL_PERI Bias Register (Default Value: 0x0003_0000)

Offset: 0x0320			Register Name: PLL_PERI_BIAS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:21	/	/	/
20:16	R/W	0x3	PLL_CP PLL bias control
15:0	/	/	/

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3.3.6.26 0x0340 PLL_VIDEO0 Bias Register (Default Value: 0x0003_0000)

Offset: 0x0340			Register Name: PLL_VIDEO0_BIAS_REG
Bit	Read/Write	Default/Hex	Description
31:21	/	/	/
20:16	R/W	0x3	PLL_CP PLL bias control
15:0	/	/	/

3.3.6.27 0x0348 PLL_VIDEO1 Bias Register (Default Value: 0x0003_0000)

Offset: 0x0348			Register Name: PLL_VIDEO1_BIAS_REG
Bit	Read/Write	Default/Hex	Description
31:21	/	/	/
20:16	R/W	0x3	PLL_CP PLL bias control
15:0	/	/	/

3.3.6.28 0x0358 PLL_VE Bias Register (Default Value: 0x0003_0000)

Offset: 0x0358			Register Name: PLL_VE_BIAS_REG
Bit	Read/Write	Default/Hex	Description
31:21	/	/	/
20:16	R/W	0x3	PLL_CP PLL bias control
15:0	/	/	/

3.3.6.29 0x0378 PLL_AUDIO0 Bias Register (Default Value: 0x0003_0000)

Offset: 0x0378			Register Name: PLL_AUDIO0_BIAS_REG
Bit	Read/Write	Default/Hex	Description
31:21	/	/	/
20:16	R/W	0x3	PLL_CP PLL bias control

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Offset: 0x0378			Register Name: PLL_AUDIO0_BIAS_REG
Bit	Read/Write	Default/Hex	Description
15:0	/	/	/

3.3.6.30 0x0380 PLL_AUDIO1 Bias Register (Default Value: 0x0003_0000)

Offset: 0x0380			Register Name: PLL_AUDIO1_BIAS_REG
Bit	Read/Write	Default/Hex	Description
31:21	/	/	/
20:16	R/W	0x3	PLL_CP PLL bias control
15:0	/	/	/

3.3.6.31 0x0400 PLL_CPU Tuning Register (Default Value: 0x4440_4000)

Offset: 0x0400			Register Name: PLL_CPU_TUN_REG
Bit	Read/Write	Default/Hex	Description
31	/	/	/
30:28	R/W	0x4	PLL_VCO VCO range control
27	/	/	/
26:24	R/W	0x4	PLL_VCO_GAIN KVCO gain control
23	/	/	/
22:16	R/W	0x40	PLL_CNT_INT Counter initial control
15	R/W	0x0	PLL_REG_OD PLL-REG-OD0 for verify
14:8	R/W	0x40	PLL_B_IN PLL-B-IN [6:0] for verify
7	R/W	0x0	PLL_REG_OD1 PLL-REG-OD1 for verify
6:0	R	0x0	PLL_B_OUT PLL-B-OUT [6:0] for verify

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3.3.6.32 0x0500 CPU_AXI Configuration Register (Default Value: 0x0000_0301)

Offset: 0x0500			Register Name: CPU_AXI_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:27	/	/	/
26:24	R/W	0x0	CPU_CLK_SEL Clock Source Select 000: HOSC 001: CLK32K 010: CLK16M_RC 011: PLL_CPU/P 100: PLL_PERI(1X) 101: PLL_PERI(2X) 110: PLL_PERI(800M) CPU Clock = Clock Source CPU_AXI Clock = Clock Source/M **Note: The clock select is lack of glitch switching and supports dynamic configuration.**
23:18	/	/	/
17:16	R/W	0x0	PLL_CPU_OUT_EXT_DIVP PLL Output External Divider P 00: 1 01: 2 10: 4 11: / When the output clock is less than 288 MHz, the clock frequency can be get by dividing P.
15:10	/	/	/
9:8	R/W	0x3	CPU_DIV2. Factor N (N = FACTOR_N +1) FACTOR_N is from 1 to 3. **Note: The clock division is lack of glitch switching and supports dynamic configuration.**
7:2	/	/	/

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Offset: 0x0500			Register Name: CPU_AXI_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
1:0	R/W	0x1	CPU_DIV1. Factor M (M= FACTOR_M +1) FACTOR_M is from 1 to 3. **Note: The clock division is lack of glitch switching and supports dynamic configuration.**

3.3.6.33 0x0504 CPU_GATING Configuration Register (Default Value: 0x8000_0000)

Offset: 0x0504			Register Name: CPU_GATING_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x1	CPU_GATING Gating Special Clock 0: Clock is OFF 1: Clock is ON
30:16	/	/	/
15:0	W	0x0	CPU_GATING_FIELD CPU Gating Field If CPU_GATING_FIELD==16'h16AA, the bit31 can be configured.

3.3.6.34 0x0510 PSI Clock Register (Default Value: 0x0000_0000)

Offset: 0x0510			Register Name: PSI_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/
25:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: HOSC 001: CLK32K 010: CLK16M_RC 011: PLL_PERI(1X) PSI_CLK = Clock Source/M/N. **Note: The clock select is lack of glitch switching and supports dynamic configuration.**
23:10	/	/	/

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Offset: 0x0510			Register Name: PSI_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8 **Note: The clock division is lack of glitch switching and supports dynamic configuration.**
7:2	/	/	/
1:0	R/W	0x0	FACTOR_M Factor M. M= FACTOR_M +1 FACTOR_M is from 0 to 3. **Note: The clock division is lack of glitch switching and supports dynamic configuration.**

3.3.6.35 0x0520 APB0 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0520			Register Name: APB0_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/
25:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 00: HOSC 01: CLK32K 10: PSI_CLK 11: PLL_PERI(1X) APB0_CLK = Clock Source/M/N. **Note: The clock select is lack of glitch switching and supports dynamic configuration.**
23:10	/	/	/

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Offset: 0x0520			Register Name: APB0_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
9:8	R/W	0x0	FACTOR_N. Factor N 00: 1 01: 2 10: 4 11: 8 **Note: The clock division is lack of glitch switching and supports dynamic configuration.**
7:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M = FACTOR_M+1 FACTOR_M is from 0 to 31. **Note: The clock division is lack of glitch switching and supports dynamic configuration.**

3.3.6.36 0x0524 APB1 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0524			Register Name: APB1_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/
25:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 00: HOSC 01: CLK32K 10: PSI_CLK 11: PLL_PERI(1X) APB1_CLK = Clock Source/M/N. **Note: The clock select is lack of glitch switching and supports dynamic configuration.**
23:10	/	/	/

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Offset: 0x0524			Register Name: APB1_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8 **Note: The clock division is lack of glitch switching and supports dynamic configuration.**
7:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M = FACTOR_M+1 FACTOR_M is from 0 to 31. **Note: The clock division is lack of glitch switching and supports dynamic configuration.**

3.3.6.37 0x0540 MBUS Clock Register (Default Value: 0xC000_0000)

Offset: 0x0540			Register Name: MBUS_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	/	/	/
30	R/W	0x1	MBUS_RST MBUS Reset 0: Assert 1: De-assert
29:0	/	/	/

NOTE

The MBUS clock is from the 4 frequency-division of PLL_DDR, and it has the same source with the DRAM clock.

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3.3.6.38 0x0600 DE Clock Register (Default Value: 0xC000_0000)

Offset: 0x0600			Register Name: DE_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	DE_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON DE_CLK = Clock Source/M.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: PLL_PERI(2X) 001: PLL_VIDEO0(4X) 010: PLL_VIDEO1(4X) 011: PLL_AUDIO1(DIV2)
23:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.39 0x060C DE Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x060C			Register Name: DE_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	DE_RST DE Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	DE_GATING DE Gating Clock 0: Mask 1: Pass

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3.3.6.40 0x0620 DI Clock Register (Default Value: 0x0000_0000)

Offset: 0x0620			Register Name: DI_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	DI_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON DI_CLK = Clock Source/M.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: PLL_PERI(2X) 001: PLL_VIDEO0(4X) 010: PLL_VIDEO1(4X) 011: PLL_AUDIO1(DIV2)
23:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M = FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.41 0x062C DI Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x062C			Register Name: DI_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	DI_RST DI Reset 0: Assert 1: DE-assert
15:1	/	/	/
0	R/W	0x0	DI_GATING DI Gating Clock 0: Mask 1: Pass

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3.3.6.42 0x0630 G2D Clock Register (Default Value: 0x0000_0000)

Offset: 0x0630			Register Name: G2D_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	G2D_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON G2D_CLK = Clock Source/M.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: PLL_PERI(2X) 001: PLL_VIDEO0(4X) 010: PLL_VIDEO1(4X) 011: PLL_AUDIO1(DIV2)
23:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.43 0x063C G2D Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x063C			Register Name: G2D_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	G2D_RST G2D Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	G2D_GATING G2D Gating Clock 0: Mask 1: Pass

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3.3.6.44 0x0680 CE Clock Register (Default Value: 0x0000_0000)

Offset: 0x0680			Register Name: CE_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	CE_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON CE_CLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 00: HOSC 01: PLL_PERI(2X) 10: PLL_PERI(1X)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8
7:4	/	/	/
3:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 15.

3.3.6.45 0x068C CE Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x068C			Register Name: CE_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	CE_RST CE Reset 0: Assert 1: De-assert

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Offset: 0x068C			Register Name: CE_BGR_REG
Bit	Read/Write	Default/Hex	Description
15:1	/	/	/
0	R/W	0x0	CE_GATING CE Gating Clock 0: Mask 1: Pass

3.3.6.46 0x0690 VE Clock Register (Default Value: 0x0000_0000)

Offset: 0x0690			Register Name: VE_CLK_REG
Bit	Read/Write	Default/Hex	Description
31	R/W	0x0	VE_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON VE_CLK = Clock Source/M.
30:25	/	/	/
24	R/W	0x0	CLK_SRC_SEL Clock Source Select 0: PLL_VE 1: PLL_PERI(2X)
23:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.47 0x069C VE Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x069C			Register Name: VE_BGR_REG
Bit	Read/Write	Default/Hex	Description
31:17	/	/	/

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Offset: 0x069C			Register Name: VE_BGR_REG
Bit	Read/Write	Default/Hex	Description
16	R/W	0x0	VE_RST VE Reset For VE_PROT 0: Assert 1: DE-assert
15:1	/	/	/
0	R/W	0x0	VE_GATING Gating Clock For VE_PROT 0: Mask 1: Pass

3.3.6.48 0x070C DMA Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x070C			Register Name: DMA_BGR_REG
Bit	Read/Write	Default/Hex	Description
31:17	/	/	/
16	R/W	0x0	DMA_RST DMA Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	DMA_GATING DMA Gating Clock 0: Mask 1: Pass **Note: The working clock is from PSI_CLK.**

3.3.6.49 0x071C MSGBOX Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x071C			Register Name: MSGBOX_BGR_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/

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Offset: 0x071C			Register Name: MSGBOX_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
17	R/W	0x0	MSGBOX1_RST DSP MSGBOX Reset 0: Assert 1: De-assert
16	R/W	0x0	MSGBOX0_RST CPU MSGBOX Reset 0: Assert 1: De-assert
15:2	/	/	/
1	R/W	0x0	MSGBOX1_GATING Gating Clock for DSP MSGBOX 0: Mask 1: Pass
0	R/W	0x0	MSGBOX0_GATING Gating Clock for CPU MSGBOX 0: Mask 1: Pass

3.3.6.50 0x072C SPINLOCK Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x072C			Register Name: SPINLOCK_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	SPINLOCK_RST SPINLOCK Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	SPINLOCK_GATING Gating Clock For SPINLOCK 0: Mask 1: Pass

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3.3.6.51 0x073C HSTIMER Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x073C			Register Name: HSTIMER_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	HSTIMER_RST HSTIMER Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	HSTIMER_GATING Gating Clock for HSTIMER 0: Mask 1: Pass

3.3.6.52 0x0740 AVS Clock Register (Default Value: 0x0000_0000)

Offset: 0x0740			Register Name: AVS_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	AVS_CLK_GATING Gating Clock The AVS_CLK is from HOSC. 0: Clock is OFF 1: Clock is ON
30:0	/	/	/

3.3.6.53 0x078C DBGSYS Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x078C			Register Name: DBGSYS_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	DBGSYS_RST DBGSYS Reset 0: Assert 1: De-assert
15:1	/	/	/

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Offset: 0x078C			Register Name: DBGSYS_BGR_REG
Bit	Read/Write	Default/Hex	Description
0	R/W	0x0	DBGSYS_GATING Gating Clock for DBGSYS The clock of DBGSYS is from HOSC. 0: Mask 1: Pass

3.3.6.54 0x07AC PWM Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x07AC			Register Name: PWM_BGR_REG
Bit	Read/Write	Default/Hex	Description
31:17	/	/	/
16	R/W	0x0	PWM_RST PWM Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	PWM_GATING Gating Clock for PWM 0: Mask 1: Pass

3.3.6.55 0x07BC IOMMU Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x07BC			Register Name: IOMMU_BGR_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/W	0x0	IOMMU_GATING Gating Clock for IOMMU 0: Mask 1: Pass

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3.3.6.56 0x0800 DRAM Clock Register (Default Value: 0x8000_0000)

Offset: 0x0800			Register Name: DRAM_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x1	DRAM_CLK_GATING Gating Clock DRAM_CLK = Clock Source/M/N. 0: Clock is OFF 1: Clock is ON
30:28	/	/	/
27	R/WAC	0x0	SDRCLK_UPD SDRCLK Configuration 0 Update 0: Invalid 1: Valid Setting 1 will validate the bit. It will be automatically cleared after the bit is valid. Here supports dram req/ack signal. When dram_update is set to 1, dram_clk_sel/dram_div2/dram_clk1 will be updated.
26:24	R/W	0x0	DRAM_CLK_SEL Clock Source Select 00: PLL_DDR 01: PLL_AUDIO1(DIV2) 10: PLL_PERI(2X) 11: PLL_PERI(800M) **Note: The clock select is lack of glitch switching and supports dynamic configuration.**
23:10	/	/	/
9:8	R/W	0x0	DRAM_DIV2 Factor N 00: 1 01: 2 10: 4 11: 8
7:2	/	/	/

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Offset: 0x0800			Register Name: DRAM_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
1:0	R/W	0x0	DRAM_DIV1 Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 3. **Note: The clock division is lack of glitch switching and supports dynamic configuration.**

3.3.6.57 0x0804 MBUS Master Clock Gating Register (Default Value: 0x0000_0000)

Offset: 0x0804			Register Name: MBUS_MAT_CLK_GATING_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:11	/	/	/
10	R/W	0x0	G2D_MCLK_EN Gating MBUS Clock For G2D 0: Mask 1: Pass
9	/	/	/
8	R/W	0x0	CSI_MCLK_EN Gating MBUS Clock For CSI 0: Mask 1: Pass
7	R/W	0x0	Reserved
6:3	/	/	/
2	R/W	0x0	CE_MCLK_EN Gating MBUS Clock For CE 0: Mask 1: Pass
1	R/W	0x0	VE_MCLK_EN Gating MBUS Clock For VE 0: Mask 1: Pass
0	R/W	0x0	DMA_MCLK_EN Gating MBUS Clock For DMA 0: Mask 1: Pass

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3.3.6.58 0x080C DRAM Bus Gating Reset Register (Default Value: 0x0000_0001)

Offset: 0x080C			Register Name: DRAM_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	DRAM_RST DRAM Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x1	DRAM_GATING Gating Clock for DRAM 0: Mask 1: Pass

3.3.6.59 0x0830 SMHC0 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0830			Register Name: SMHC0_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SMHC0_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON SMHC0_CLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: HOSC 001: PLL_PERI(1X) 010: PLL_PERI(2X) 011: PLL_AUDIO1(DIV2) Others: Reserved
23:10	/	/	/

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Offset: 0x0830			Register Name: SMHC0_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8
7:4	/	/	/
3:0	R/W	0x0	FACTOR_M Factor M M = FACTOR_M +1 FACTOR_M is from 0 to 15.

3.3.6.60 0x0834 SMHC1 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0834			Register Name: SMHC1_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SMHC1_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON SCLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: HOSC 001: PLL_PERI(1X) 010: PLL_PERI(2X) 011: PLL_AUDIO1(DIV2) Others: Reserved
23:10	/	/	/

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Offset: 0x0834			Register Name: SMHC1_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8
7:4	/	/	/
3:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 15.

3.3.6.61 0x0838 SMHC2 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0838			Register Name: SMHC2_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SMHC2_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON SCLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: HOSC 001: PLL_PERI(1X) 010: PLL_PERI(2X) 011: PLL_PERI(800M) 100: PLL_AUDIO1(DIV2) Others: Reserved
23:10	/	/	/

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Offset: 0x0838			Register Name: SMHC2_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8
7:4	/	/	/
3:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 15.

3.3.6.62 0x084C SMHC Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x084C			Register Name: SMHC_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	/	/	/
18	R/W	0x0	SMHC2_RST SMHC2 Reset 0: Assert 1: De-assert
17	R/W	0x0	SMHC1_RST SMHC1 Reset 0: Assert 1: De-assert
16	R/W	0x0	SMHC0_RST SMHC0 Reset 0: Assert 1: De-assert
15:3	/	/	/
2	R/W	0x0	SMHC2_GATING Gating Clock for SMHC2 0: Mask 1: Pass

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Offset: 0x084C			Register Name: SMHC_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	SMHC1_GATING Gating Clock for SMHC1 0: Mask 1: Pass
0	R/W	0x0	SMHC0_GATING Gating Clock for SMHC0 0: Mask 1: Pass

3.3.6.63 0x090C UART Bus Gating Reset Register (Default Value: 0x0000_0000)

NOTE

The clock of the UART is from APB1.

Offset: 0x090C			Register Name: UART_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21	R/W	0x0	UART5_RST UART5 Reset 0: Assert 1: De-assert
20	R/W	0x0	UART4_RST UART4 Reset 0: Assert 1: De-assert
19	R/W	0x0	UART3_RST UART3 Reset 0: Assert 1: De-assert
18	R/W	0x0	UART2_RST UART2 Reset 0: Assert 1: De-assert

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Offset: 0x090C			Register Name: UART_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
17	R/W	0x0	UART1_RST UART1 Reset 0: Assert 1: De-assert
16	R/W	0x0	UART0_RST UART0 Reset 0: Assert 1: De-assert
15:6	/	/	/
5	R/W	0x0	UART5_GATING Gating Clock for UART5 0: Mask 1: Pass
4	R/W	0x0	UART4_GATING Gating Clock for UART4 0: Mask 1: Pass
3	R/W	0x0	UART3_GATING Gating Clock for UART3 0: Mask 1: Pass
2	R/W	0x0	UART2_GATING Gating Clock for UART2 0: Mask 1: Pass
1	R/W	0x0	UART1_GATING Gating Clock for UART1 0: Mask 1: Pass
0	R/W	0x0	UART0_GATING Gating Clock for UART0 0: Mask 1: Pass

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3.3.6.64 0x091C TWI Bus Gating Reset Register (Default Value: 0x0000_0000)

NOTE

The clock of the TWI is from APB1.

Offset: 0x091C			Register Name: TWI_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:20	/	/	/
19	R/W	0x0	TWI3_RST TWI3 Reset 0: Assert 1: De-assert
18	R/W	0x0	TWI2_RST TWI2 Reset 0: Assert 1: De-assert
17	R/W	0x0	TWI1_RST TWI1 Reset 0: Assert 1: De-assert
16	R/W	0x0	TWI0_RST TWI0 Reset 0: Assert 1: De-assert
15:4	/	/	/
3	R/W	0x0	TWI3_GATING Gating Clock for TWI3 0: Mask 1: Pass
2	R/W	0x0	TWI2_GATING Gating Clock for TWI2 0: Mask 1: Pass

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Offset: 0x091C			Register Name: TWI_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	TWI1_GATING Gating Clock for TWI1 0: Mask 1: Pass
0	R/W	0x0	TWI0_GATING Gating Clock for TWI0 0: Mask 1: Pass

3.3.6.65 0x0940 SPI0 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0940			Register Name: SPI0_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SPI0_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON SCLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: HOSC 001: PLL_PERI(1X) 010: PLL_PERI(2X) 011: PLL_AUDIO1(DIV2) 100: PLL_AUDIO1(DIV5) Others: Reserved
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8
7:4	/	/	/

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Offset: 0x0940			Register Name: SPI0_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 15.

3.3.6.66 0x0944 SPI1 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0944			Register Name: SPI1_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	SCLK_GATING Gating Special Clock 0: Clock is OFF 1: Clock is ON SCLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: HOSC 001: PLL_PERI(1X) 010: PLL_PERI(2X) 011: PLL_AUDIO1(DIV2) 100: PLL_AUDIO1(DIV5) Others: /
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8
7:4	/	/	/
3:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 15.

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3.3.6.67 0x096C SPI Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x096C			Register Name: SPI_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/W	0x0	SPI1_RST SPI1 Reset 0: Assert 1: De-assert
16	R/W	0x0	SPI0_RST SPI0 Reset 0: Assert 1: De-assert
15:2	/	/	/
1	R/W	0x0	SPI1_GATING Gating Clock for SPI1 0: Mask 1: Pass
0	R/W	0x0	SPI0_GATING Gating Clock for SPI0 0: Mask 1: Pass

3.3.6.68 0x0970 EMAC_25M Clock Register (Default: 0x0000_0000)

Offset: 0x0970			Register Name: EMAC_25M_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	EMAC_25M_CLK_GATING Gating Special Clock 0: Clock is OFF 1: Clock is ON CLK = PLL_PERI(1X)/24 = 25 MHz

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Offset: 0x0970			Register Name: EMAC_25M_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
30	R/W	0x0	EMAC_25M_CLK_SRC_GATING Gating the Source Clock of Special Clock It is for low power design. 0: Clock is OFF 1: Clock is ON
29:0	/	/	/

3.3.6.69 0x097C EMAC Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x097C			Register Name: EMAC_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	EMAC_RST EMAC Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	EMAC_GATING Gating Clock for EMAC 0: Mask 1: Pass

3.3.6.70 0x09C0 IRTX Clock Register (Default: 0x0000_0000)

Offset: 0x09C0			Register Name: IRTX_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	IRTX_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON IRTX_CLK = Clock Source/M/N.
30:27	/	/	/

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Offset: 0x09C0			Register Name: IRTX_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 0: HOSC 1: PLL_PERI(1X)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8
7:4	/	/	/
3:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 15.

3.3.6.71 0x09CC IRTX Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x09CC			Register Name: IRTX_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	IRTX_RST IRTX Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	IRTX_GATING Gating Clock for IRTX 0: Mask 1: Pass

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3.3.6.72 0x09EC GPADC Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x09EC			Register Name: GPADC_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	GPADC_RST GPADC Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	GPADC_GATING Gating Clock For GPADC 0: Mask 1: Pass

3.3.6.73 0x09FC THS Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x09FC			Register Name: THS_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	THS_RST THS Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	THS_GATING Gating Clock For THS 0: Mask 1: Pass

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3.3.6.74 0x0A10 I2S/PCM0 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0A10			Register Name: I2S/PCM0_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	I2S/PCM0_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON I2S/PCM0_CLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 00: PLL_AUDIO0(1X) 01: PLL_AUDIO0(4X) 10: PLL_AUDIO1(DIV2) 11: PLL_AUDIO1(DIV5)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: /1 01: /2 10: /4 11: /8
7:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 The value of FACTOR_M is from 0 to 31.

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3.3.6.75 0x0A14 I2S/PCM1 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0A14			Register Name: I2S/PCM1_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	I2S/PCM1_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON I2S/PCM1_CLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 00: PLL_AUDIO0(1X) 01: PLL_AUDIO0(4X) 10: PLL_AUDIO1(DIV2) 11: PLL_AUDIO1(DIV5)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: /1 01: /2 10: /4 11: /8
7:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

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3.3.6.76 0x0A18 I2S/PCM2 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0A18			Register Name: I2S/PCM2_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	I2S/PCM2_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON I2S/PCM2_CLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 00: PLL_AUDIO0(1X) 01: PLL_AUDIO0(4X) 10: PLL_AUDIO1(DIV2) 11: PLL_AUDIO1(DIV5)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: /1 01: /2 10: /4 11: /8
7:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

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3.3.6.77 0x0A1C I2S/PCM2_ASRC Clock Register (Default Value: 0x0000_0000)

Offset: 0x0A1C			Register Name: I2S/PCM2_ASRC_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	I2S/PCM2_ASRC_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON I2S/PCM2_ASRC_CLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 00: PLL_AUDIO0(4X) 01: PLL_PERI(1X) 10: PLL_AUDIO1(DIV2) 11: PLL_ AUDIO1(DIV5)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: /1 01: /2 10: /4 11: /8
7:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M = FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.78 0x0A20 I2S/PCM Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0A20			Register Name: I2S/PCM_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	/	/	/

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Offset: 0x0A20			Register Name: I2S/PCM_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
18	R/W	0x0	I2S/PCM2_RST I2S/PCM2 Reset 0: Assert 1: De-assert
17	R/W	0x0	I2S/PCM1_RST I2S/PCM1 Reset 0: Assert 1: De-assert
16	R/W	0x0	I2S/PCM0_RST I2S/PCM0 Reset 0: Assert 1: De-assert
15:3	/	/	/
2	R/W	0x0	I2S/PCM2_GATING Gating Clock for I2S/PCM2 0: Mask 1: Pass
1	R/W	0x0	I2S/PCM1_GATING Gating Clock for I2S/PCM1 0: Mask 1: Pass
0	R/W	0x0	I2S/PCM0_GATING Gating Clock for I2S/PCM0 0: Mask 1: Pass

3.3.6.79 0x0A24 OWA_TX Clock Register (Default Value: 0x0000_0000)

Offset: 0x0A24			Register Name: OWA_TX_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	OWA_TX_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON OWA_TX_CLK = Clock Source/M/N.

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Offset: 0x0A24			Register Name: OWA_TX_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 00: PLL_AUDIO0(1X) 01: PLL_AUDIO0(4X) 10: PLL_AUDIO1(DIV2) 11: PLL_AUDIO1(DIV5)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: /1 01: /2 10: /4 11: /8
7:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.80 0x0A2C OWA Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0A2C			Register Name: OWA_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	OWA_RST OWA Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	OWA_GATING Gating Clock for OWA 0: Mask 1: Pass

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3.3.6.81 0x0A40 DMIC Clock Register (Default Value: 0x0000_0000)

Offset: 0x0A40			Register Name: DMIC_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	DMIC_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON DMIC_CLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 00: PLL_AUDIO0(1X) 01: PLL_AUDIO1(DIV2) 10: PLL_AUDIO1(DIV5)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: /1 01: /2 10: /4 11: /8
7:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.82 0x0A4C DMIC Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0A4C			Register Name: DMIC_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/

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Offset: 0x0A4C			Register Name: DMIC_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
16	R/W	0x0	DMIC_RST DMIC Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	DMIC_GATING Gating Clock for DMIC 0: Mask 1: Pass

3.3.6.83 0x0A50 AUDIO_CODEC_DAC Clock Register (Default Value: 0x0000_0000)

Offset: 0x0A50			Register Name: AUDIO_CODEC_DAC_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	AUDIO_CODEC_DAC_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON AUDIO_CODEC_DAC_CLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SE. Clock Source Select 00: PLL_AUDIO0(1X) 01: PLL_AUDIO1(DIV2) 10: PLL_AUDIO1(DIV5)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N (clkdiv2y,0) 00: /1 01: /2 10: /4 11: /8
7:5	/	/	/

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Offset: 0x0A50			Register Name: AUDIO_CODEC_DAC_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.84 0x0A54 AUDIO_CODEC_ADC Clock Register (Default Value: 0x0000_0000)

Offset: 0x0A54			Register Name: AUDIO_CODEC_ADC_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	AUDIO_CODEC_ADC_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON AUDIO_CODEC_ADC_CLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SE Clock Source Select 00: PLL_AUDIO0(1X) 01: PLL_AUDIO1(DIV2) 10: PLL_AUDIO1(DIV5)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: /1 01: /2 10: /4 11: /8
7:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

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3.3.6.85 0x0A5C AUDIO_CODEC Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0A5C			Register Name: AUDIO_CODEC_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	AUDIO_CODEC_RST AUDIO_CODEC Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	AUDIO_CODEC_GATING Gating Clock For AUDIO_CODEC 0: Mask 1: Pass

3.3.6.86 0x0A70 USB0 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0A70			Register Name: USB0_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	USB0_CLKEN Gating Special Clock For OHCI0 0: Clock is OFF 1: Clock is ON
30	R/W	0x0	USBPHY0_RSTN USB PHY0 Reset 0: Assert 1: De-assert
29:26	/	/	/
25:24	R/W	0x0	USB0_CLK12M_SEL OHCI0 12M Source Select 00: 12M divided from 48 MHz 01: 12M divided from 24 MHz 10: RTC_32K 11: /
23:0	/	/	/

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3.3.6.87 0x0A74 USB1 Clock Register (Default Value: 0x0000_0000)

Offset: 0x0A74			Register Name: USB1_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	USB1_CLKEN Gating Special Clock For OHCI1 0: Clock is OFF 1: Clock is ON
30	R/W	0x0	USBPHY1_RSTN USB PHY1 Reset 0: Assert 1: De-assert
29:26	/	/	/
25:24	R/W	0x0	USB1_CLK12M_SEL OHCI0 12M Source Select 00: 12M divided from 48 MHz 01: 12M divided from 24 MHz 10: RTC_32K 11: /
23:0	/	/	/

3.3.6.88 0x0A8C USB Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0A8C			Register Name: USB_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	USBOTG0_RST USBOTG0 Reset 0: Assert 1: De-assert
23:22	/	/	/
21	R/W	0x0	USBEHCI1_RST USBEHCI1 Reset 0: Assert 1: De-assert

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Offset: 0x0A8C			Register Name: USB_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
20	R/W	0x0	USBEHCI0_RST USBEHCI0 Reset 0: Assert 1: De-assert
19:18	/	/	/
17	R/W	0x0	USBOHCI1_RST USBOHCI1 Reset 0: Assert 1: De-assert
16	R/W	0x0	USBOHCI0_RST USBOHCI0 Reset 0: Assert 1: De-assert
15:9	/	/	/
8	R/W	0x0	USBOTG0_GATING Gating Clock For USBOTG0 0: Mask 1: Pass
7:6	/	/	/
5	R/W	0x0	USBEHCI1_GATING Gating Clock For USBEHCI1 0: Mask 1: Pass
4	R/W	0x0	USBEHCI0_GATING Gating Clock For USBEHCI0 0: Mask 1: Pass
3:2	/	/	/
1	R/W	0x0	USBOHCI1_GATING Gating Clock For USBOHCI1 0: Mask 1: Pass
0	R/W	0x0	USBOHCI0_GATING Gating Clock For USBOHCI0 0: Mask 1: Pass

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3.3.6.89 0x0A9C LRADC Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0A9C			Register Name: LRADC_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	LRADC_RST LRADC Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	LRADC_GATING Gating Clock For LRADC 0: Mask 1: Pass

3.3.6.90 0x0ABC DPSS_TOP Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0ABC			Register Name: DPSS_TOP_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	DPSS_TOP_RST DPSS_TOP Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	DPSS_TOP_GATING Gating Clock For DPSS_TOP 0: Mask 1: Pass

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3.3.6.91 0x0B24 DSI Clock Register (Default Value: 0x0000_0000)

Offset: 0x0B24			Register Name: DSI_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	DSI_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON DSI_CLK = Clock Source/M.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: HOSC 001: PLL_PERI(1X) 010: PLL_VIDEO0(2X) 011: PLL_VIDEO1(2X) 100: PLL_AUDIO1(DIV2)
23:4	/	/	/
3:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 15.

3.3.6.92 0x0B4C DSI Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0B4C			Register Name: DSI_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	DSI_RST DSI Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	DSI_GATING Gating Clock For DSI 0: Mask 1: Pass

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3.3.6.93 0x0B60 TCONLCD Clock Register (Default Value: 0x0000_0000)

Offset: 0x0B60			Register Name: TCONLCD_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	TCONLCD_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON TCONLCD_CLK = Clock Source/M/N.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: PLL_VIDEO0(1X) 001: PLL_VIDEO0(4X) 010: PLL_VIDEO1(1X) 011: PLL_VIDEO1(4X) 100: PLL_PERI(2X) 101: PLL_AUDIO1(DIV2)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8
7:4	/	/	/
3:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1. FACTOR_M is from 0 to 15.

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3.3.6.94 0x0B7C TCONLCD Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0B7C			Register Name: TCONLCD_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	TCONLCD_RST TCON LCD Reset 0: Assert 1: DE-assert
15:1	/	/	/
0	R/W	0x0	TCONLCD_GATING Gating Clock For TCON LCD 0: Mask 1: Pass

3.3.6.95 0x0BAC LVDS Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0BAC			Register Name: LVDS_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	LVDS0_RST LVDS0 Reset 0: Assert 1: De-assert
15:0	/	/	/

3.3.6.96 0x0BF0 LEDC Clock Register (Default Value: 0x0000_0000)

Offset: 0x0BF0			Register Name: LEDC_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	LDEC_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON LEDC_CLK = Clock Source/M/N.
30:25	/	/	/

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Offset: 0x0BF0			Register Name: LEDC_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
24	R/W	0x0	CLK_SRC_SEL Clock Source Select 0: HOSC 1: PLL_PERI(1X)
23:10	/	/	/
9:8	R/W	0x0	FACTOR_N Factor N 00: 1 01: 2 10: 4 11: 8
7:4	/	/	/
3:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 15.

3.3.6.97 0x0BFC LEDC Bus Gating Reset Register (Default: 0x0000_0000)

Offset: 0x0BFC			Register Name: LEDC_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	LEDC_RST LEDC Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	LEDC_GATING Gating Clock For LEDC 0: Mask 1: Pass

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3.3.6.98 0x0C04 CSI Clock Register (Default Value: 0x0000_0000)

Offset: 0x0C04			Register Name: CSI_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	CSI_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON CSI_CLK = Clock Source/M.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: PLL_PERI(2X) 001: PLL_VIDEO0(2X) 010: PLL_VIDEO1(2X)
23:4	/	/	/
3:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 15.

3.3.6.99 0x0C08 CSI Master Clock Register (Default Value: 0x0000_0000)

Offset: 0x0C08			Register Name: CSI_MASTER_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	CSI_MASTER_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON CSI_MASTER_CLK = Clock Source/M.
30:27	/	/	/

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Offset: 0x0C08			Register Name: CSI_MASTER_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: HOSC 001: PLL_PERI(1X) 010: PLL_VIDEO0(1X) 011: PLL_VIDEO1(1X) 100: PLL_AUDIO1(DIV2) 101: PLL_AUDIO1(DIV5)
23:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.100 0x0C1C CSI Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0C1C			Register Name: CSI_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	CSI_RST CSI Reset 0: Assert 1: DE-assert
15:1	/	/	/
0	R/W	0x0	CSI_GATING Gating Clock For CSI 0: Mask 1: Pass

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3.3.6.101 0x0C50 TPADC Clock Register (Default Value: 0x0000_0000)

Offset: 0x0C50			Register Name: TPADC_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	TPADC_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON TPADC_CLK = Clock Source.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: HOSC 001: PLL_AUDIO0(1X)
23:0	/	/	/

3.3.6.102 0x0C5C TPADC Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0C5C			Register Name: TPADC_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	TPADC_RST TPADC Reset 0: Assert 1: De-assert
15:1	/	/	/
0	R/W	0x0	TPADC_GATING Gating Clock For TPADC 0: Mask 1: Pass

3.3.6.103 0x0C6C TZMA Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0C6C			Register Name: TZMA_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/

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Offset: 0x0C6C			Register Name: TZMA_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	TZMA_GATING Gating Clock For TZMA 0: Mask 1: Pass

3.3.6.104 0x0C70 DSP Clock Register (Default Value: 0x0000_0000)

Offset: 0x0C70			Register Name: DSP_CLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	DSP_CLK_GATING Gating Clock 0: Clock is OFF 1: Clock is ON DSP_CLK = Clock Source/M.
30:27	/	/	/
26:24	R/W	0x0	CLK_SRC_SEL Clock Source Select 000: HOSC 001: CLK32K 010: CLK16M_RC 011: PLL_PERI(2X) 100: PLL_AUDIO1(DIV2)
23:5	/	/	/
4:0	R/W	0x0	FACTOR_M Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.105 0x0C7C DSP Bus Gating Reset Register (Default Value: 0x0000_0000)

Offset: 0x0C7C			Register Name: DSP_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	/	/	/

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Offset: 0x0C7C			Register Name: DSP_BGR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
18	R/W	0x0	DSP_DBG_RST DSP_DBG Reset 0: Assert 1: De-assert
17	R/W	0x0	DSP_CFG_RST DSP_CFG Reset 0: Assert 1: De-assert
16	R/W	0x0	DSP_RST DSP Reset 0: Assert 1: De-assert
15:2	/	/	/
1	R/W	0x0	DSP_CFG_GATING Gating Clock For DSP_CFG 0: Mask 1: Pass
0	/	/	/

3.3.6.106 0x0F00 CCU Security Switch Register (Default Value: 0x0000_0000)

Offset: 0x0F00			Register Name: CCU_SEC_SWITCH_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/
2	R/W	0x0	MBUS_SEC MBUS Clock Register Security 0: Secure 1: Non-secure
1	R/W	0x0	BUS_SEC Bus Relevant Registers Security 0: Secure 1: Non-secure

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Offset: 0x0F00			Register Name: CCU_SEC_SWITCH_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	PLL_SEC PLL Relevant Registers Security 0: Secure 1: Non-secure

3.3.6.107 0x0F04 PLL Lock Debug Control Register (Default Value: 0x0000_0000)

Offset: 0x0F04			Register Name: PLL_LOCK_DBG_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	PLL_LOCK_FLAG_EN Debug Enable 0: Disable 1: Enable
30:23	/	/	/
22:20	R/W	0x0	PLL_LOCK_FLAG_SEL Debug Select 000: PLL_CPU 001: PLL_DDR 010: PLL_PERI(2X) 011: PLL_VIDEO0(4X) 100: PLL_VIDEO1(4X) 101: PLL_VE 110: PLL_AUDIO0 111: PLL_AUDIO1 Others: /
19:0	/	/	/

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3.3.6.108 0x0F08 Frequence Detect Control Register (Default Value: 0x0000_0020)

Offset: 0x0F08			Register Name: FRE_DET_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W0C	0x0	ERROR_FLAG Error Flag 0: Write 0 to clear 1: Error
30:9	/	/	/
8:4	R/W	0x2	DET_TIME Detect Time Time=1/32k*(2^RegValue) RegValue is from 0 to 16.
3:2	/	/	/
1	R/W	0x0	FRE_DET_IRQ_EN Frequence Detect IRQ Enable 0: Disable 1: Enable
0	R/W	0x0	FRE_DET_FUN_EN Frequence Detect Function Enable 0: Disable 1: Enable

3.3.6.109 0x0F0C Frequence Up Limit Register (Default Value: 0x0000_0000)

Offset: 0x0F0C			Register Name: FRE_UP_LIM_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	FRE_UP_LIM Frequence Up Limit **The value of the register must be an integral multiple of 32. The unit is kHz.**

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3.3.6.110 0x0F10 Frequence Down Limit Register (Default Value: 0x0000_0000)

Offset: 0x0F10			Register Name: FRE_DOWN_LIM_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	FRE_DOWN_LIM Frequence Down Limit **The value of the register must be an integral multiple of 32. The unit is kHz.**

3.3.6.111 0x0F30 CCU FANOUT Clock Gate Register (Default Value: 0x0000_0000)

Offset: 0x0F30			Register Name: CCU_FAN_GATE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:5	/	/	/
4	R/W	0x0	CLK32K_EN Gating for CLK32K 0: Clock is OFF 1: Clock is ON
3	R/W	0x0	CLK25M_EN Gating for CLK25M 0: Clock is OFF 1: Clock is ON
2	R/W	0x0	CLK16M_EN Gating for CLK16M 0: Clock is OFF 1: Clock is ON
1	R/W	0x0	CLK12M_EN Gating for CLK12M 0: Clock is OFF 1: Clock is ON
0	R/W	0x0	CLK24M_EN Gating for CLK24M 0: Clock is OFF 1: Clock is ON

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3.3.6.112 0x0F34 CLK27M FANOUT Register (Default Value: 0x0000_0000)

Offset: 0x0F34			Register Name: CLK27M_FAN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	CLK27M_EN Gating for CLK27M 0: Clock is OFF 1: Clock is ON SCLK = Clock Source/M/N.
30:26	/	/	/
25:24	R/W	0x0	CLK27M_SCR_SEL Clock Source Select 000: PLL_VIDEO0(1X) 001: PLL_VIDEO1(1X) 010: / 011: /
23:10	/	/	/
9:8	R/W	0x0	CLK27M_DIV1 Factor N N= FACTOR_N +1. FACTOR_N is from 0 to 3.
7:5	/	/	/
4:0	R/W	0x0	CLK27M_DIV0 Factor M M= FACTOR_M +1. FACTOR_M is from 0 to 31.

3.3.6.113 0x0F38 PCLK FANOUT Register (Default Value: 0x0000_0000)

Offset: 0x0F38			Register Name: PCLK_FAN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	PCLK_DIV_EN Gating for PCLK 0: Clock is OFF 1: Clock is ON PCLK = APB0_CLK/M.
30:5	/	/	/

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Offset: 0x0F38			Register Name: PCLK_FAN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
4:0	R/W	0x0	PCLK_DIV Factor M M= FACTOR_M +1 FACTOR_M is from 0 to 31.

3.3.6.114 0x0F3C CCU FANOUT Register (Default Value: 0x0000_0000)

Offset: 0x0F3C			Register Name: CCU_FAN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:27	/	/	/
26:24	R/W	0x0	Reserved
23	R/W	0x0	CLK_FANOUT2_EN Gating for CLK_FANOUT2 0: Clock is OFF 1: Clock is ON
22	R/W	0x0	CLK_FANOUT1_EN Gating for CLK_FANOUT1 0: Clock is OFF 1: Clock is ON
21	R/W	0x0	CLK_FANOUT0_EN Gating for CLK_FANOUT0 0: Clock is OFF 1: Clock is ON
20:18	/	/	/
17:9	R/W	0x0	Reserved
8:6	R/W	0x0	CLK_FANOUT2_SEL 000:CLK32K (From PLL_PERI(2X)) 001:CLK12M (From DCXO/2) 010:CLK16M (From PLL_PERI(2X)) 011:CLK24M (From DCXO) 100:CLK25M (From PLL_PERI(1X)) 101:CLK27M 110:PCLK CLK_FANOUT2 can be selected to output from the above seven sources.

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Offset: 0x0F3C			Register Name: CCU_FAN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
5:3	R/W	0x0	CLK_FANOUT1_SEL 000:CLK32K (From PLL_PERI(2X)) 001:CLK12M (From DCXO/2) 010:CLK16M (From PLL_PERI(2X)) 011:CLK24M (From DCXO) 100:CLK25M (From PLL_PERI(1X)) 101:CLK27M 110:PCLK CLK_FANOUT1 can be selected to output from the above seven sources.
2:0	R/W	0x0	CLK_FANOUT0_SEL 000:CLK32K (From PLL_PERI(2X)) 001:CLK12M (From DCXO) 010:CLK16M (From PLL_PERI(2X)) 011:CLK24M (From DCXO) 100:CLK25M (From PLL_PERI(1X)) 101:CLK27M 110:PCLK CLK_FANOUT0 can be selected to output from the above seven sources.

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3.4 BROM System

3.4.1 Overview

The system has several ways to boot. It has an integrated on-chip Boot ROM (BROM) that is considered the primary program-loader. On the startup process, the R528 starts to fetch the first instruction from address 0x0, where is the BROM located at.

The BROM system is divided into two parts: the firmware exchange launch (FEL) module and the Medium Boot module. FEL is responsible for writing the external data to the local NVM, and Medium Boot is responsible for loading an effective and legitimate BOOT0 from NVM and running.

The BROM system includes the following features:

- Supports CPU0 boot process
- Supports mandatory upgrade process through USB and SD card
- Supports GPIO pin and eFuse to select the boot media type
- Supports normal booting and secure booting
- Secure BROM loads only certified firmware
- Secure BROM ensures that the Secure Boot is in a trusted environment

3.4.2 Functional Description

3.4.2.1 Selecting the Boot Medium

The BROM system supports the following boot media:

- SD card
- eMMC
- SPI NOR FLASH
- SPI NAND FLASH

There are two ways to select the boot medium: GPIO Pin Select and eFuse Select. On startup, the BROM will read the state of BOOT_MODE, and decide whether the GPIO or eFuse to select the type of boot medium based on the state of BOOT_MODE.

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The following table shows BOOT_MODE Setting.

Table 3-7 BOOT_MODE Setting

BOOT_MODE	Boot_Select Type
0	GPIO boot select, indicates that the boot medium is decided by the value of the GPIO pin.
1	eFuse boot select, indicates that the boot medium is decided by the value of the eFuse type.

GPIO Boot Select

If the state of the BOOT_MODE is 0, the boot medium is decided by the value of the GPIO pin. The following table shows the boot medium priority. The boot medium priority describes the possibility that each medium to be selected as the boot medium. The BROM reads the boot0 of the medium with the highest priority first. If the medium does not exist or has any problems, the BROM will try the next medium. Otherwise, the medium will be selected as the boot medium.

Table 3-8 GPIO Boot Select Configuration

Pin_Boot_Select[1:0]	Boot Medium Priority
00	SPI NOR->SPI NAND
01	SMHC0->SPI NOR->other media
10	SMHC0->SPI NAND->other media
11	SMHC0->EMMC2_BOOT->EMMC2_USR->other media

NOTE

The status of the GPIO boot select pin can be read by the bit[12:11] of the system configuration module (register: 0x03000024).

eFuse Boot Select

If the state of the BOOT_MODE is 1, the boot medium is decided by the value of eFuse_Boot_Select_Cfg. The eFuse_Boot_Select_Cfg is divided into 4 groups and each group is 3-bit. The following table shows the groups of eFUSE_Boot_Select.

NOTE

The status of the efuse boot select pin can be read by the bit[27:16] of the SID module (register: 0x03006210).

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Table 3-9 Groups of eFuse_Boot_Select

eFuse_Boot_Select_Cfg[11:0]	Group
eFuse_Boot_Select_Cfg[2:0]	eFuse_Boot_Select_1
eFuse_Boot_Select_Cfg[5:3]	eFuse_Boot_Select_2
eFuse_Boot_Select_Cfg[8:6]	eFuse_Boot_Select_3
eFuse_Boot_Select_Cfg[11:9]	eFuse_Boot_Select_4

The four groups take effect with the following priority:

eFuse_Boot_Select_1 -> eFuse_Boot_Select_2 -> eFuse_Boot_Select_3 -> eFuse_Boot_Select_4

For example, eFuse_Boot_Select_2 will not take effect unless eFuse_Boot_Select_1 is set as 0x111, eFuse_Boot_Select_3 will not take effect unless eFuse_Boot_Select_2 is set as 0x111, and so on.

The following table shows the boot medium priority for the different values of eFuse_Boot_Select_n, where n = [4:1]. The eFuse_Boot_Select_1 to eFuse_Boot_Select_3 are the same setting. But for eFuse_Boot_Select_4, if its value is 0x111, the BROM will select the boot medium in the Try mode. The BROM in the Try mode follows the order below to select the boot medium:

SMHC0 -> SPI NOR -> SPI NAND -> SMHC2

Table 3-10 eFuse Boot Select Setting

eFuse_Boot_Select_n	Boot Medium Priority
000	Select the boot medium in Try mode.
001	Reserved
010	SHMC2
011	SPI NOR
100	SPI NAND
101	Reserved
110	Reserved
111	When n is 1 to 3: The boot medium is decided by the value of **eFuse_Boot_Select_(n + 1)**. When n is 4: Select the boot medium in Try mode.

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3.4.2.2 Selecting the Boot Mode

For SoCs that have implemented and enabled the ARM TrustZone technology, there are two boot modes: Normal BROM Mode and Secure BROM Mode. Secure BROM Mode is designed to protect against the potential threat that attackers modify the code or data areas in programmable memory.

On startup, the BROM will select the boot mode according to the value of the Secure Enable bit. If the value of Secure Enable bit is 0, the system will boot in Normal BROM Mode. Otherwise, it will boot in Secure BROM Mode.

NOTE

The ARM TrustZone feature is the minimal security functionality an ARM-TrustZone-technology-based system must implement for its Trusted Boot. You can enable the ARM TrustZone feature by configuring the Secure Enable Bit as enabled.

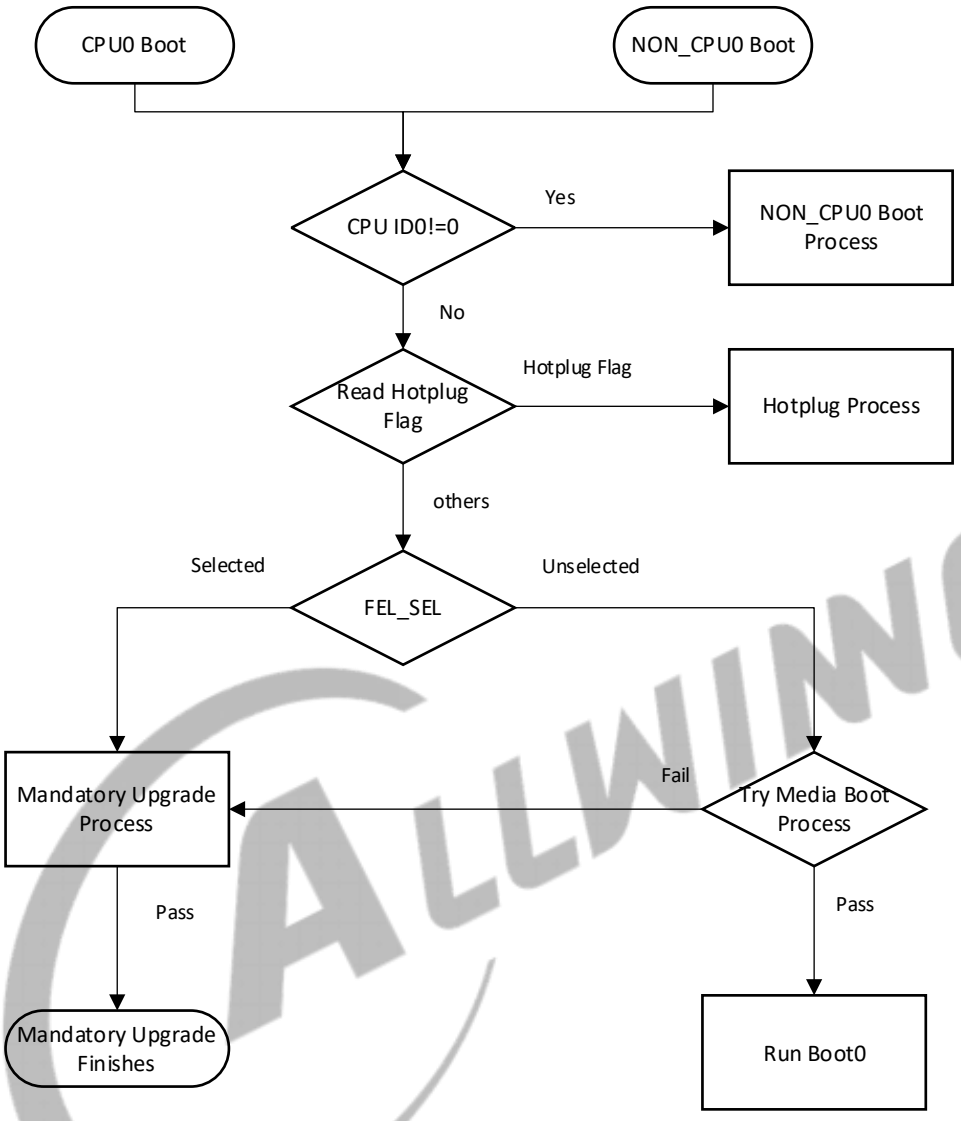
Normal BROM Mode

In Normal BROM Mode, the system boot starts from CPU0, and then the BROM will read the state of the FEL pin. If the FEL pin is high, the system will jump to the fast boot process. If it is low, the system will jump to the mandatory upgrade process.

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The following figure shows the boot process in Normal BROM Mode.

Figure 3-6 Boot Process in Normal BROM Mode



Secure BROM Mode

The Secure BROM Mode has the following features:

- Supports X509 certificate

  The certificate is used to check whether the Security Boot software is modified or replaced. Before running the Security Boot software, the system checks the integrity of the certificate make sure the software has not been modified or replaced.

- Supports cryptographic algorithms

  - SHA-256

  - RSA-2048

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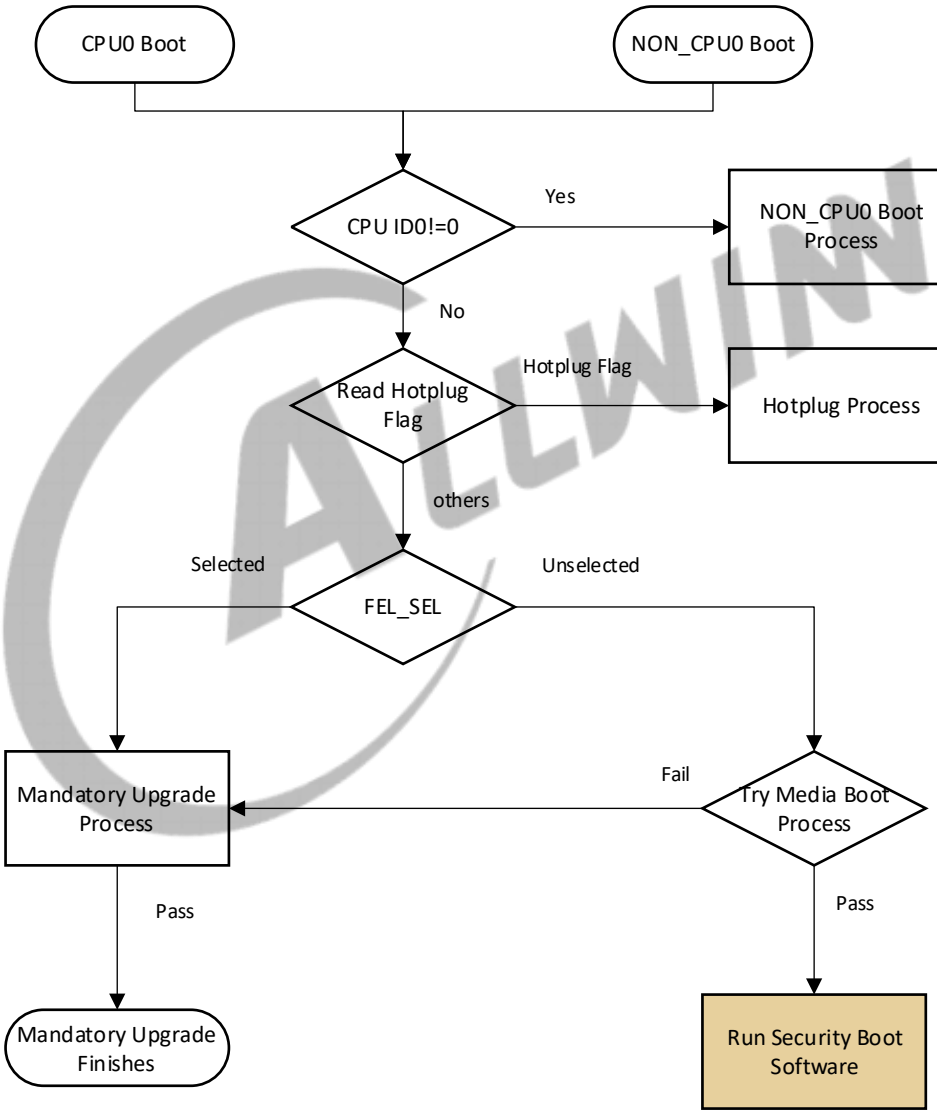
The system uses the Crypto Engine (CE) hardware module to accelerate the speed of encryption and decryption. The use of standard cryptography ensures the reliability of the firmware images. The reliable firmware image ensures that the system security state can be as expected.

- Supports OTP/eFuse

The process of selecting the boot medium in Secure BROM Mode is the same as that in Normal BROM Mode.

In Secure BROM Mode, after the boot medium is selected, the system additionally runs the Security Boot software to authenticate the Sboot bin file.

Figure 3-7 Boot Process in Secure BROM Mode

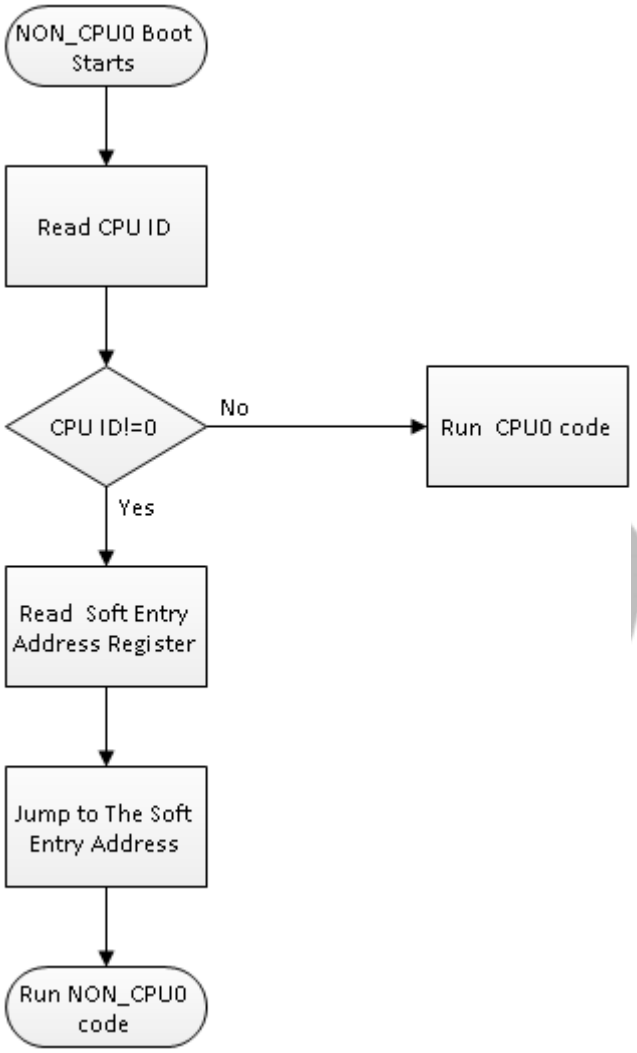


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3.4.2.3 NON_CPU0 Boot Process

If CPU ID is greater than 0, the system boot from NON_CPU0, the BROM will read the Soft Entry Address Register, then jump the Soft Entry Address, and run NON_CPU0 boot code. The following figure shows the NON_CPU0 Boot Process.

Figure 3-8 NON_CPU0 Boot Process Diagram



NOTE

The Soft Entry Address Register of CPU0 is 0x070005C4.

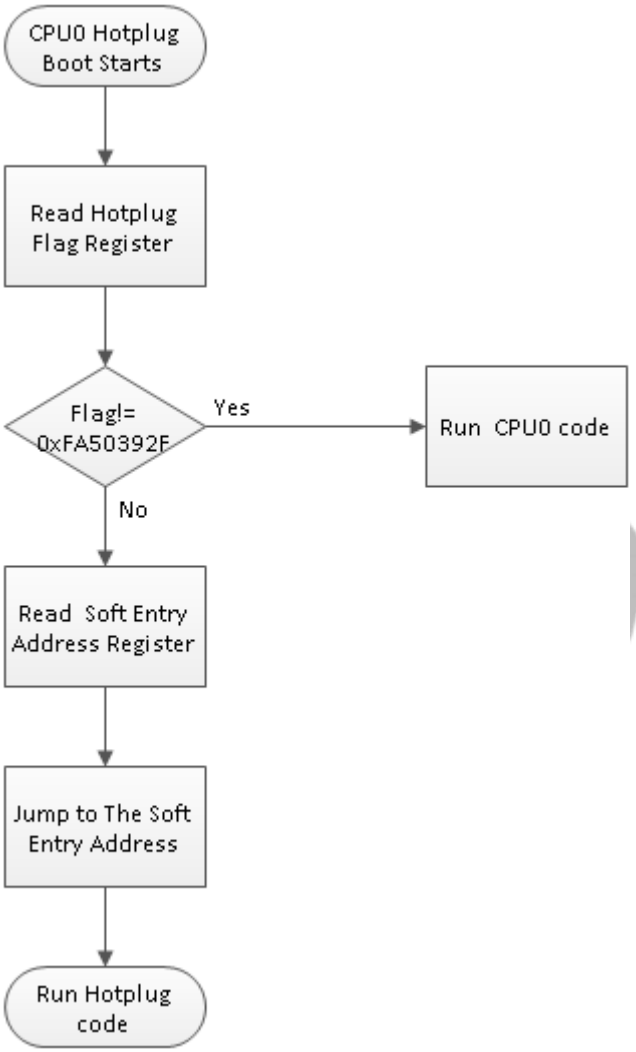
The Soft Entry Address Register of CPU1 is 0x070005C8.

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3.4.2.4 CPU0 Hotplug Process

The Hotplug Flag determines whether the system will do Hotplug boot, if the CPU Hotplug Flag value is equal to 0xFA50392F, then read the Soft Entry Register and the system will jump to the Soft Entry Address. The following figure shows the CPU0 Hotplug Process.

Figure 3-9 CPU0 Hotplug Process Diagram



NOTE

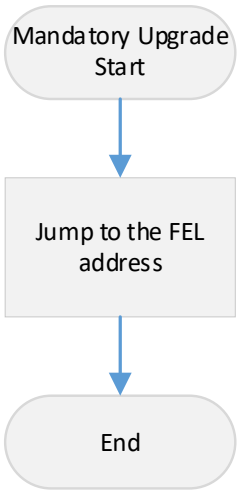
- The Hotplug Flag Register is 0x070005C0.
- The Soft Entry Address Register is 0x070005C4.

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3.4.2.5 Mandatory Upgrade Process

If the FEL pin is detected to pull low, the system will jump to the mandatory upgrade process. The following figure shows the mandatory upgrade process.

Figure 3-10 Mandatory Upgrade Process



NOTE

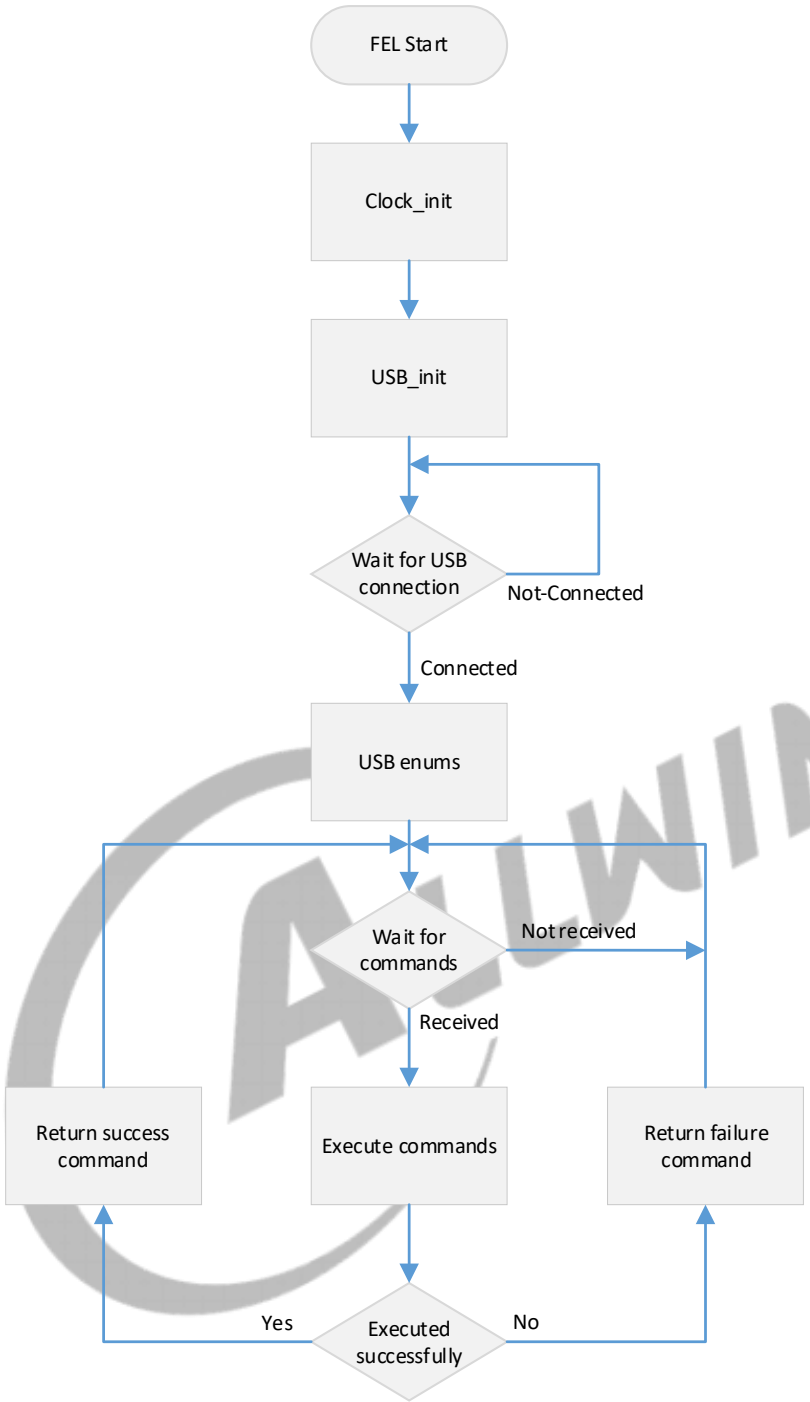
- The FEL address of the Normal BROM is 0x20.
- The FEL address of the Secure BROM is 0x64.
- The status of the FEL pin is the bit[8] of the SYSCTRL_REG (0x03000024).

3.4.2.6 FEL Process

When the system chooses to enter the Mandatory Upgrade Process, the system will jump to the FEL process. The following figure shows the FEL upgrade process.

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Figure 3-11 USB FEL Process



3.4.2.7 Fast Boot Process

If the value of the Fast Boot register (0x07090120) in RTC module is not zero, the system will enter the Fast Boot Process. The following table shows the boot medium priority for different values of the Fast Boot register.

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Table 3-11 Fast Boot Select Setting

Reg_bit[31:28]	Boot Medium Priority
1	Try process
2	SMHC0->EMMC2_USER->EMMC2_BOOT->Other media
3	SMHC0->SPI NOR->Other media
4	SMHC0->SPI NAND->Other media
5	EMMC2_BOOT->EMMC2_USER->Other media
6	SMHC0->Try process
7	SMHC0->Try process

NOTE

- The bit[28:0] of Fast Boot register is used to record the media information.
- The try process is SMHC0->SPI NOR->SPI NAND->EMMC2_USER->EMMC2_BOOT.

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3.5 System Configuration

3.5.1 Overview

The system configuration module is used to configure parameters for system domain, such as SRAM, CPU, PLL, BROM, and so on.

3.5.2 Register List

Module Name	Base Address
SYS_CFG	0x03000000

Register Name	Offset	Description
DSP_BOOT_RAMMAP_REG	0x0008	DSP Boot SRAM Remap Control Register
VER_REG	0x0024	Version Register
EMAC_EPHY_CLK_REG0	0x0030	EMAC-EPHY Clock Register 0
SYS_LDO_CTRL_REG	0x0150	System LDO Control Register
RESCAL_CTRL_REG	0x0160	Resistor Calibration Control Register
RES240_CTRL_REG	0x0168	240ohms Resistor Manual Control Register
RESCAL_STATUS_REG	0x016C	Resistor Calibration Status Register

3.5.3 Register Description

3.5.3.1 0x0008 DSP Boot SRAM Remap Register (Default Value: 0x0000_0001)

Offset: 0x0008			Register Name: DSP_BOOT_RAMMAP_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x1	DSP BOOT SRAM REMAP ENABLE 0: DSP 128K Local SRAM Remap for DSP_SYS 1: DSP 128K Local SRAM Remap for System Boot After system boots up, this bit must be set to 0 before using DSP.

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3.5.3.2 0x0024 Version Register (Default Value: UDF)

Offset: 0x0024			Register Name: VER_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:13	/	/	/
12:11	R	UDF	BOOT_SEL_PAD_STA The value of this bit decides the priority order for each medium type to be selected as the boot media.
10:9	/	/	/
8	R	UDF	FEL_SEL_PAD_STA Fel_Select_Pin_Status 0: Run_FEL 1: Try Media Boot
7:0	/	/	/

3.5.3.3 0x0030 EMAC-EPHY Clock Register 0 (Default Value: 0x0005_8000)

Offset: 0x0030			Register Name: EMAC_EPHY_CLK_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	BPS_EFUSE
27	R/W	0x0	XMII_SEL 0: Internal SMI and MII 1: External SMI and MII
26:25	R/W	0x0	EPHY_MODE Operation Mode Selection 00: Normal Mode 01: Simulation Mode 10: AFE Test Mode 11: Reserved
24:20	R/W	0x0	PHY_ADDR PHY Address
19	R/W	0x0	Reserved
18	R/W	0x1	CLK_SEL 0: 25 MHz 1: 24 MHz

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Offset: 0x0030			Register Name: EMAC_EPHY_CLK_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
17	R/W	0x0	LED_POL 0: High active 1: Low active
16	R/W	0x1	SHUTDOWN 0: Power up 1: Shut down
15	R/W	0x1	PHY_SELECT 0: External PHY 1: Internal PHY
14	/	/	/
13	R/W	0x0	RMII_EN 0: Disable RMII Module 1: Enable RMII Module This bit is prior to bit[2]. When this bit is asserted, the MII and RGMII interfaces will be both disabled.
12:10	R/W	0x0	ETXDC Configure EMAC Transmit Clock Delay Chain
9:5	R/W	0x0	ERXDC Configure EMAC Receive Clock Delay Chain
4	R/W	0x0	ERXIE Enable EMAC Receive Clock Invertor 0: Disabled 1: Enabled
3	R/W	0x0	ETXIE Enable EMAC Transmit Clock Invertor 0: Disabled 1: Enabled
2	R/W	0x0	EPIT EMAC PHY Interface Type 0: MII 1: RGMII

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Offset: 0x0030			Register Name: EMAC_EPHY_CLK_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
1:0	R/W	0x0	ETCS EMAC Transmit Clock Source 00: Transmit clock source for MII 01: External transmit clock source for GMII and RGMII 10: Internal transmit clock source for GMII and RGMII 11: Reserved

3.5.3.4 0x0150 System LDO Control Register (Default Value: 0x0000_0E0F)

Offset: 0x0150			Register Name: SYS_LDO_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	R/W	0x0	SPARE Reserved spare register
23:22	/	/	/
21	R/W	0x0	reserved
20	R/W	0x0	reserved
19:18	/	/	/
17	R/W	0x0	reserved
16	R/W	0x0	reserved
15:8	R/W	0xE	LDOB_TRIM LDOB Trimming. Adjust LDOB output, only the low 6-bit is used. 000000:1.167 000001:1.18 000010:1.193 000011:1.207 000100:1.22 000101:1.233 000110:1.247 000111:1.260 001000:1.273 001001:1.287 001010:1.3 001011:1.313 001100:1.327

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Offset: 0x0150			Register Name: SYS_LDO_CTRL_REG
Bit	Read/Write	Default/Hex	Description
			001101:1.340 001110:1.353 (default) 001111:1.367 010000:1.38 010001:1.393 010010:1.407 010011:1.42 010100:1.433 010101:1.447 010110:1.46 010111:1.473 011000:1.487 011001:1.5 011010:1.513 011011:1.527 011100:1.54 011101:1.553 011110:1.567 011111:1.58 100000:1.593 100001:1.607 100010:1.627 100011:1.64 100100:1.653 100101:1.667 100110:1.680 100111:1.693 101000:1.707 101001:1.720 101010:1.733 101011:1.747 101100:1.76 101101:1.773 101110:1.787 101111:1.8 110000:1.813 110001:1.827

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Offset: 0x0150			Register Name: SYS_LDO_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			110010:1.84 110011:1.853 110100:1.867 110101:1.88 110110:1.893 110111:1.907 111000:1.92 111001:1.933 111010:1.947 111011:1.96 111100:1.973 111101:1.987 111110:2 111111:2.013
7:0	R/W	0xF	LDOA_TIM. LDOA Trimming Adjust LDOA output, only the low 5-bit is used. 00000:1.593 00001:1.607 00010:1.627 00011:1.64 00100:1.653 00101:1.667 00110:1.680 00111:1.693 01000:1.707 01001:1.720 01010:1.733 01011:1.747 01100:1.76 01101:1.773 01110:1.787 01111:1.8 (default) 10000:1.813 10001:1.827 10010:1.84 10011:1.853

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Offset: 0x0150			Register Name: SYS_LDO_CTRL_REG
Bit	Read/Write	Default/Hex	Description
			10100:1.867 10101:1.88 10110:1.893 10111:1.907 11000:1.92 11001:1.933 11010:1.947 11011:1.96 11100:1.973 11101:1.987 11110:2 11111:2.013

3.5.3.5 0x0160 Resistor Calibration Control Register (Default Value: 0x0033_0003)

Offset: 0x0160			Register Name: RESCAL_CTRL_REG
Bit	Read/Write	Default/Hex	Description
31:25	/	/	/
24	R/W	0x0	Reserved
23:22	/	/	/
21:16	R/W	0x33	Reserved
15:9	/	/	/
8	R/W	0x0	DDR_RES240_Trimming_SEL 240ohms Resistor Trimming Source Select 0: Trimming value from RESCAL 1: Trimming value from RES240_TRIM
7:3	/	/	/
2	R/W	0x0	RESCAL_MODE RESCAL Calibration Mode Select 0: Auto Calibration 1: Reserved
1	R/W	0x1	CAL_ANA_EN. Calibration Circuits Analog Enable 0: Disable 1: Enable

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Offset: 0x0160			Register Name: RESCAL_CTRL_REG
Bit	Read/Write	Default/Hex	Description
0	R/W	0x1	CAL_EN Auto Calibration Enable 0: Disable 1: Enable

3.5.3.6 0x0168 240ohms Resistor Manual Control Register (Default Value: 0x0000_0033)

Offset: 0x0168			Register Name: RES240_CTRL_REG
Bit	Read/Write	Default/Hex	Description
31:6	/	/	/
5:0	R/W	0x33	DDR_RES240_TRIM 240ohms Resistor trimming bit

3.5.3.7 0x016C Resistor Calibration Status Register (Default Value: 0x0000_0000)

Offset: 0x016C			Register Name: RESCAL_STATUS_REG
Bit	Read/Write	Default/Hex	Description
31:9	/	/	/
8	RO	0x0	COUT Calibration Circuits Analog Compare Output
7:6	/	/	/
5:0	RO	0x0	RES_CAL_DO RESCAL Calibration Results Output

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3.6 Timer

3.6.1 Overview

The timer module implements the timing and counting functions. The timer module includes timer0, timer1, watchdog and audio video synchronization (AVS).

The timer0 and timer1 are completely consistent. The main features for timer0 and timer1 are as follows:

- Alternative count clock: LOSC or OSC24M. The LOSC can be either the internal or external low-frequency clock, and the external one has more accuracy.
- Supports 8 prescale factors
- Programmable 32-bit down timer
- Supports two timing modes: periodic mode and single counting mode
- Generates an interrupt when the count is decreased to 0

The watchdog is used to transmit a reset signal to reset the entire system when an exception occurs in the system. The main features for the watchdog are as follows:

- Single clock source: OSC24M/750.
- Supports 12 initial values
- Supports the generation of timeout interrupts
- Supports the generation of reset signals
- Supports Watchdog Restart

The AVS is used to synchronize the audio and video. The AVS module includes AVS0 and AVS1, which are completely consistent. The main features for the AVS are as follows:

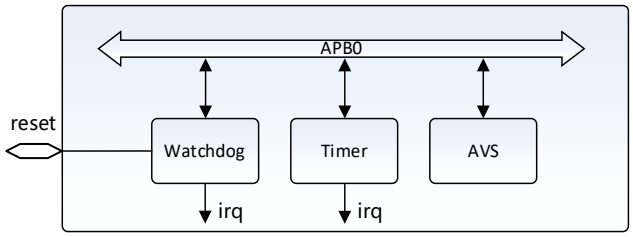
- Single clock source: OSC24M
- Programmable 33-bit up timer
- Supports updating the initial value anytime
- 12-bit frequency divider factor
- Supports Pause/Start function

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3.6.2 Block Diagram

The following figure shows the functional block diagram of the timer module.

Figure 3-12 Timer Block Diagram



The watchdog, timer (including timer0 and timer1), and AVS are all mounted at the APB0 bus. The system configures the parameters of their configure registers via APB0 bus.

The timer and watchdog are both down counters and support generating interrupts after the counting value reaches 0.

For watchdog, the system is responsible for configuring the interval value. If the system fails to restart the watchdog regularly because of some exceptional situations, such as the bus hang, the watchdog will send out a Watchdog Reset External signal to reset the system. And the signal will be transmitted to the Reset pad to reset the PMIC.

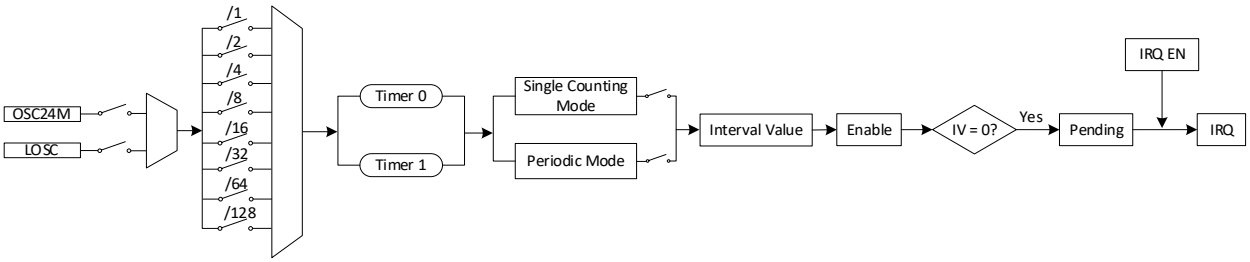
3.6.3 Functional Description

3.6.3.1 Timer

The timer (including timer0 and timer1) is a 32-bit down counter. The counter value is decremented by 1 on each rising edge of the timer clock.

The following figure shows the block diagram for the timer.

Figure 3-13 Block Diagram for the Timer



The clock source for the timer can be either OSC24M or LOSC. For LOSC, it can be either the internal or external low-frequency clock. The external one has more accuracy.

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Each timer has a prescale that divides the working clock frequency by 1, 2, 4, 8, 16, 32, 64, or 128. And each timer can generate independent interrupts.

Timing Modes

The timer has two timing modes: the single counting mode and periodic mode. You can configure the timing mode via the bit[7] of **TMRn_CTRL_REG** (n = 0 or 1). The value 0 is for the period mode and value 1 is for the single counting mode.

- Single Counting Mode

  In the single counting mode, the timer starts counting from the interval value and generates an interrupt after the counter decreases to 0, and then stops counting. It starts to count again only when a new interval value is loaded.

- Periodic Mode

  In the periodic mode, the timer restarts another round of counting after generating the interrupt. It reloads data from the **TMRn_INTV_VALUE_REG** and then continues to count.

Formula for Calculating the Timer Time

The following formula decribes the relationship among timer parameters.

$$T_{timer} = \frac{TMRn_INTV_VALUE_REG - TMRn_CUR_VALUE_REG}{TMRn_CLK_SRC} \times TMRn_CLK_PRES$$

Where,

The parameter n is either 0 or 1;

T_{timer} is the remaining time of the timer;

TMRn_INTV_VALUE_REG is the interval value of the timer;

TMRn_CUR_VALUE_REG is the current value of the timer;

TMRn_CLK_SRC is the frequency of the timer clock source;

TMRn_CLK_PRES is the prescale ratio of the timer clock.

Initializing the Timer

Follow the steps below to initialize the timer:

1. Configure the timer parameters clock source, prescale factor, and timing mode by writing **TMRn_CTRL_REG.** There is no sequence requirement of configuring the parameters.
2. Write the interval value.
   a) Write **TMRn_INTV_VALUE_REG** to configure the interval value for the timer.

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b) Write bit[1] of TMRn_CTRL_REG to load the interval value to the timer. The value of the bit will be cleared automatically after loading the interval value.

3. Write bit[0] of TMRn_CTRL_REG to start the timer. To get the current value of the timer, read TMRn_CUR_VALUE_REG.

Processing the Interrupt

Follow the steps below to process the interrupt:

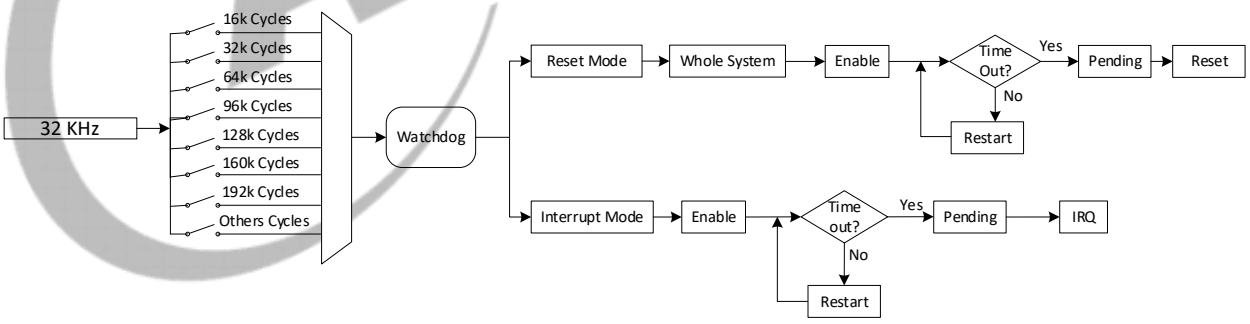
1. Enable interrupts for the timer: write the enable bit of the corresponding interrupt in TMR_IRQ_EN_REG for the timer. The timer will generate an interrupt everytime the count value reaches 0.
2. After entering the interrupt process, write the pending bit of the corresponding interrupt in TMR_IRQ_STA_REG to clear the interrupt pending, and execute the process of waiting for the interrupt.
3. Resume the interrupt and continue to execute the interrupted process.

3.6.3.2 Watchdog

The watchdog is a 32-bit down counter. The counter value is decremented by 1 on each rising edge of the count clock.

The following figure shows the block diagram for the watchdog.

Figure 3-14 Block Diagram for the Watchdog



The clock source of the watchdog is OSC24M/750. There are 12 configurable initial count values.

Operating Modes

The watchdog has two operating modes: the interrupt mode and reset mode.

- In the interrupt mode, when the counter value reaches 0 and WDOG_IRQ_EN_REG is enabled, the watchdog generates an interrupt.
- In the reset mode, when the counter value reaches 0, the watchdog generates a reset signal to reset the entire system.

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You can configure the operating mode for the watchdog via the bit[1:0] of the WDOG_CFG_REG. The value 0x2 is for the interrupt mode and the value 0x1 is for the reset mode.

Both the interrupt mode and reset mode support Watchdog Restart. You can make the watchdog to count from the initial value at any time by configuring the WDOG_CTRL_REG: write 0xA57 to bit[12:1], then write 1 to bit[0].

Initializing the Watchdog

Follow the steps below to initialize the watchdog:

1. Write the bit[1:0] of **WDOG_CFG_REG** to configure the watchdog operating mode so that the watchdog can generate interrupts or output reset signals.
2. Write the bit[7:4] of **WDOG_MODE_REG** to configure the initial count value.
3. Write the bit[0] of **WDOG_MODE_REG** to enable the watchdog.

Processing the Interrupt

In the interrupt mode, the watchdog is used as a counter. It generates an interrupt everytime the count value reaches 0.

Follow the steps below to process the interrupt:

1. Write the enable bit of **WDOG_IRQ_EN_REG** to enable the interrupt.
2. After entering the interrupt process, write the pending bit of **WDOG_IRQ_STA_REG** to clear the interrupt pending and execute the process of waiting for the interrupt.
3. Resume the interrupt and continue to execute the interrupted process.

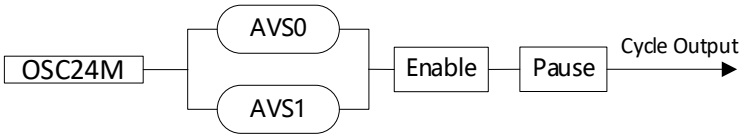
3.6.3.3 AVS

The AVS is a 33-bit up counter. The counter value is increased by 1 on each rising edge of the count clock. There is a clock gate in CCU module to control the output of the AVS counter. To operate the AVS, open the clock gate first.

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The following figure shows the block diagram for the AVS.

Figure 3-15 Block Diagram for the AVS



The clock source of the AVS is OSC24M. There is a 12-bit division factor for each AVS, N0 for AVS0 and N1 for AVS1. When the timer increases from 0 to N1 or N2, the AVS counter adds 1. When the counter reaches 33-bit upper limit, the AVS will start to count from the initial value again.

The AVS supports changing the initial value and division factor at anytime. And the AVS supports restarting from the initial value or pausing at anytime.

Starting or Pausing the AVS

Follow the steps below to

1. Write **AVS_CNT_DIV_REG** to configure the division factor.
2. Write **AVS_CNTn_REG** (n = 0 or 1) to configure the initial value.
3. Write **AVS_CNT_CTL_REG** to enable the AVS. You can pause the AVS at any time.

3.6.4 Programming Guidelines

3.6.4.1 Configuring the Timer

The following example shows how to make a one-millisecond delay with the clock source selected as OSC24M, the operating mode sets as single counting mode, and the pre-scale sets as 2.

```
writel(0x2EE0, TMR_0_INTV);                    //Set the interval value
writel(0x94, TMR_0_CTRL);                      //Select Single mode, 24 MHz clock source, 2 pre-scale
writel(readl(TMR_0_CTRL)|(1<<1), TMR_0_CTRL);  //Set the Reload bit
while((readl(TMR_0_CTRL)>>1)&1);               //Waiting the Reload bit turns to 0
writel(readl(TMR_0_CTRL)|(1<<0), TMR_0_CTRL);  //Enable Timer0
```

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3.6.4.2 Resetting the Watchdog

The following example shows how to make the watchdog to generate a reset signal to the whole system after 1 second. The clock source for the watchdog is OSC24M/750.

```
writel(0x1, WDOG_CONFIG);                    //Set the operating mode as the reset mode.
writel(0x10, WDOG_MODE);                     //Set the interval value as 1 s.
writel(readl(WDOG_MODE)|(1<<0), WDOG_MODE);  //Enable the Watchdog.
```

3.6.4.3 Restarting the Watchdog

The following example shows how to restart the watchdog. In this example, the clock source is OSC24M/750, the interval value is 1 second, and the watchdog operating mode is the reset mode.

If the execution time of "other codes" is shorter than 1 second, the watchdog will restart from the interval value before it count to zero and generates the reset signal. Otherwise, the watchdog will reset the whole system before the code "writel(readl(WDOG_CTRL)|(0xA57<<1)|(1<<0), WDOG_CTRL)" is executed.

```
writel(0x1, WDOG_CONFIG);                    //To whole system
writel(0x10, WDOG_MODE);                     //Interval Value set 1s
writel(readl(WDOG_MODE)|(1<<0), WDOG_MODE);  //Enable Watchdog
----other codes---
writel(readl(WDOG_CTRL)|(0xA57<<1)|(1<<0), WDOG_CTRL); //Write 0xA57 at Key Field and Restart Watchdog
```

3.6.5 Register List

Module Name	Base Address
Timer	0x02050000

Register Name	Offset	Description
TMR_IRQ_EN_REG	0x0000	Timer IRQ Enable Register
TMR_IRQ_STA_REG	0x0004	Timer Status Register
TMR0_CTRL_REG	0x0010	Timer0 Control Register
TMR0_INTV_VALUE_REG	0x0014	Timer0 Interval Value Register
TMR0_CUR_VALUE_REG	0x0018	Timer0 Current Value Register

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Register Name	Offset	Description
TMR1_CTRL_REG	0x0020	Timer1 Control Register
TMR1_INTV_VALUE_REG	0x0024	Timer1 Interval Value Register
TMR1_CUR_VALUE_REG	0x0028	Timer1 Current Value Register
WDOG_IRQ_EN_REG	0x00A0	Watchdog IRQ Enable Register
WDOG_IRQ_STA_REG	0x00A4	Watchdog Status Register
WDOG_SOFT_RST_REG	0x00A8	Watchdog Software Reset Register
WDOG_CTRL_REG	0x00B0	Watchdog Control Register
WDOG_CFG_REG	0x00B4	Watchdog Configuration Register
WDOG_MODE_REG	0x00B8	Watchdog Mode Register
WDOG_OUTPUT_CFG_REG	0x00BC	Watchdog Output Configuration Register
AVS_CNT_CTL_REG	0x00C0	AVS Control Register
AVS_CNT0_REG	0x00C4	AVS Counter 0 Register
AVS_CNT1_REG	0x00C8	AVS Counter 1 Register
AVS_CNT_DIV_REG	0x00CC	AVS Divisor Register

3.6.6 Register Description

3.6.6.1 0x0000 Timer IRQ Enable Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: TMR_IRQ_EN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R/W	0x0	TMR1_IRQ_EN Timer1 Interrupt Enable 0: Disabled 1: Enabled
0	R/W	0x0	TMR0_IRQ_EN Timer0 Interrupt Enable 0: Disabled 1: Enabled

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3.6.6.2 0x0004 Timer IRQ Status Register (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: TMR_IRQ_STA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R/W1C	0x0	TMR1_IRQ_PEND The IRQ pending bit for Timer1 0: No effect 1: Pending, indicates that the interval value of the timer 1 is reached. Write 1 to clear the pending status.
0	R/W1C	0x0	TMR0_IRQ_PEND The IRQ pending bit for Timer0 0: No effect 1: Pending, indicates that the interval value of the timer 0 is reached. Write 1 to clear the pending status.

3.6.6.3 0x0010 Timer0 Control Register (Default Value: 0x0000_0004)

Offset: 0x0010			Register Name: TMR0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	TMR0_MODE Select the timing mode for timer0 0: Periodic mode. When the interval value of the timer 0 is reached, the timer will restart another round of counting automatically. 1: Single counting mode. When the interval value of the timer 0 is reached, the timer will stop counting.

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Offset: 0x0010			Register Name: TMR0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
6:4	R/W	0x0	TMR0_CLK_PRES Select the pre-scale of timer0 clock source 000: /1 001: /2 010: /4 011: /8 100: /16 101: /32 110: /64 111: /128
3:2	R/W	0x1	TMR0_CLK_SRC Select the clock source for timer0 00: LOSC 01: OSC24M 10: / 11: /
1	R/W	0x0	TMR0_RELOAD Timer0 Reload 0: No effect 1: Reload the Interval value for timer0 After the bit is set, it can not be written again before it is cleared automatically.
0	R/W	0x0	TMR0_EN Timer0 Enable 0: Stop/Pause 1: Start By setting the bit to 1, the timer will be started. It reloads the interval value register and then counts from the interval value to 0. By setting the bit to 0 before the timer counts to 0, the timer will be paused. The bit will be locked to 0 for at least 2 cycles. Within the 2 cycles, you cannot set the bit to 1 to restart the timer. The timer supports updating the interval value in the pause state. To start to down-count from the updated interval value, set both the reload bit and enable bit to 1. Additionally, in the single counting mode, after the count value reaches 0, the system will automatically change the bit to 0 to stop the timer.

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3.6.6.4 0x0014 Timer0 Interval Value Register (Default Value: 0x0000_0000)

Offset: 0x0014			Register Name: TMR0_INTV_VALUE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TMR0_INTV_VALUE Timer0 Interval Value

NOTE

Take the system clock and timer clock source into consideration when setting the interval value.

3.6.6.5 0x0018 Timer0 Current Value Register (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: TMR0_CUR_VALUE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TMR0_CUR_VALUE Timer0 Current Value Timer0 current value is a 32-bit down-counter (from interval value to 0).

3.6.6.6 0x0020 Timer1 Control Register (Default Value: 0x0000_0004)

Offset: 0x0020			Register Name: TMR1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	TMR1_MODE Select the timing mode for timer1 0: Periodic mode. When the interval value of the timer 1 is reached, the timer will restart another round of counting automatically. 1: Single counting mode. When the interval value of the timer 1 is reached, the timer will stop counting.

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Offset: 0x0020			Register Name: TMR1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
6:4	R/W	0x0	TMR1_CLK_PRES Select the pre-scale of timer1 clock source 000: /1 001: /2 010: /4 011: /8 100: /16 101: /32 110: /64 111: /128
3:2	R/W	0x1	TMR1_CLK_SRC Select the pre-scale of timer1 clock source 00: LOSC 01: OSC24M 10: / 11: /
1	R/W	0x0	TMR1_RELOAD Timer1 Reload 0: No effect 1: Reload the interval value for timer1 After the bit is set, it can not be written again before it is cleared automatically.
0	R/W	0x0	TMR1_EN Timer1 Enable 0: Stop/Pause 1: Start By setting the bit to 1, the timer will be started. It reloads the interval value register and then counts from the interval value to 0. By setting the bit to 0 before the timer counts to 0, the timer will be paused. The bit will be locked to 0 for at least 2 cycles. Within the 2 cycles, you cannot set the bit to 1 to restart the timer. The timer supports updating the interval value in the pause state. To start to down-count from the updated interval value, set both the reload bit and enable bit to 1. Additionally, in the single counting mode, after the count value reaches 0, the system will automatically change the bit to 0 to stop the timer.

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3.6.6.7 0x0024 Timer1 Interval Value Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: TMR1_INTV_VALUE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TMR1_INTV_VALUE Timer1 Interval Value

NOTE

Take the system clock and timer clock source into consideration when setting the interval value.

3.6.6.8 0x0028 Timer1 Current Value Register (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: TMR1_CUR_VALUE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TMR1_CUR_VALUE Timer1 Current Value Timer1 current value is a 32-bit down-counter (from interval value to 0).

3.6.6.9 0x00A0 Watchdog IRQ Enable Register (Default Value: 0x0000_0000)

Offset: 0x00A0			Register Name: WDOG_IRQ_EN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	WDOG_IRQ_EN Watchdog Interrupt Enable 0: Disabled 1: Enabled

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3.6.6.10 0x00A4 Watchdog Status Register (Default Value: 0x0000_0000)

Offset: 0x00A4			Register Name: WDOG_IRQ_STA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W1C	0x0	WDOG_IRQ_PEND The IRQ pending bit for the watchdog Write 1 to clear the pending status. 0: No effect 1: Pending, indicates that the interval value of the watchdog is reached.

3.6.6.11 0x00A8 Watchdog Software Reset Register (Default Value: 0x0000_0000)

Offset: 0x00A8			Register Name: WDOG_SOFT_RST_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	W	0x0	KEY_FIELD Key Field To change the value of bit[0], this field should be filled with 0x16AA.
15:1	/	/	/
0	R/W1C	0x0	Soft Reset Enable 0: De-assert 1: Reset the system **Note: To use the bit to reset the system, the watchdog first needs to be disabled.**

3.6.6.12 0x00B0 Watchdog Control Register (Default Value: 0x0000_0000)

Offset: 0x00B0			Register Name: WDOG_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:13	/	/	/
12:1	W	0x0	WDOG_KEY_FIELD Watchdog Key Field It should be written to 0xA57. Writing any other value in this field aborts the write operation.

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Offset: 0x00B0			Register Name: WDOG_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W1S	0x0	WDOG_RESTART Watchdog Restart 0: No effect 1: Restart the watchdog

3.6.6.13 0x00B4 Watchdog Configuration Register (Default Value: 0x0000_0001)

Offset: 0x00B4			Register Name: WDOG_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	W	0x0	KEY_FIELD Key Field To change the value of bit[15:0], this field should be filled with 0x16AA.
15:9	/	/	/
8	R/W	0x0	WDOG_CLK_SRC Select the clock source for the watchdog. 0: HOSC_32K, that is, OSC24M/750. It is a 32 KHz clock divided from the OSC24M. 1: LOSC_32K. A clock provided by the LOSC.
7:2	/	/	/
1:0	R/W	0x1	WDOG_MODE Configure the operating mode for the watchdog 00: / 01: To whole system 10: Only interrupt mode 11: /

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3.6.6.14 0x00B8 Watchdog Mode Register (Default Value: 0x0000_0000)

Offset: 0x00B8			Register Name: WDOG_MODE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	W	0x0	KEY_FIELD Key Field To change the value of bit[15:0], this field should be filled with 0x16AA.
15:8	/	/	/
7:4	R/W	0x0	WDOG_INTV_VALUE Watchdog Interval Value 0000: 16000 cycles (0.5 s) 0001: 32000 cycles (1 s) 0010: 64000 cycles (2 s) 0011: 96000 cycles (3 s) 0100: 128000 cycles (4 s) 0101: 160000 cycles (5 s) 0110: 192000 cycles (6 s) 0111: 256000 cycles (8 s) 1000: 320000 cycles (10 s) 1001: 384000 cycles (12 s) 1010: 448000 cycles (14 s) 1011: 512000 cycles (16 s) Others: Reserved **Note: The corresponding clock cycles for the interval value (IV) depends on the frequency of the clock: Cycles = F_{CLK} * IV.** For example, to get a interval value of 0.5 second, if the clock source is HOSC_32K (whose frequency is 32 KHz), the cycle number is 16,000; if the clock source is LOSC_32K (whose frequency is 32.768 kHz), the cycle number is 16,384.
3:1	/	/	/
0	R/W	0x0	WDOG_EN Watchdog Enable 0: No effect 1: Enable the Watchdog

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3.6.6.15 0x00BC Watchdog Output Configuration Register (Default Value: 0x0000_001F)

Offset: 0x00BC			Register Name: WDOG_OUTPUT_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:0	R/W	0x1F	WDOG OUTPUT CONFIG Configure the valid time for the watchdog reset signal. T = 1/32ms*(N + 1) The default value is 1 ms.

3.6.6.16 0x00C0 AVS Counter Control Register (Default Value: 0x0000_0000)

Offset: 0x00C0			Register Name: AVS_CNT_CTL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:10	/	/	/
9	R/W	0x0	AVS_CNT1_PS Audio/Video Sync Counter 1 Pause Control 0: Do not pause. 1: Pause the AVS counter1.
8	R/W	0x0	AVS_CNT0_PS Audio/Video Sync Counter 0 Pause Control 0: Do not pause. 1: Pause the AVS counter0.
7:2	/	/	/
1	R/W	0x0	AVS_CNT1_EN Audio/Video Sync Counter 1 Enable/Disable The clock source is OSC24M. 0: Disabled 1: Enabled
0	R/W	0x0	AVS_CNT0_EN Audio/Video Sync Counter 0 Enable/Disable The clock source is OSC24M. 0: Disabled 1: Enabled

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3.6.6.17 0x00C4 AVS Counter 0 Register (Default Value: 0x0000_0000)

Offset: 0x00C4			Register Name: AVS_CNT0_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	AVS_CNT0 The higher 32 bits of AVS counter0. AVS counter0 is a 33-bit up counter. The initial value consists of two parts: this register forms the bit[32:1] of AVS counter0 and the bit[0] is zero. You can set the initial value of the AVS counter0 by software. The initial value can be updated at anytime. You can also pasuse the counter by setting AVS_CNT0_PS to ”1”. The counter value will not increase when it is paused.

3.6.6.18 0x00C8 AVS Counter 1 Register (Default Value: 0x0000_0000)

Offset: 0x00C8			Register Name: AVS_CNT1_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	AVS_CNT1 The higher 32 bits of AVS counter1. AVS counter1 is a 33-bit up counter. The initial value consists of two parts: this register forms the bit[32:1] of AVS counter0 and the bit[0] is zero. You can set the initial value of the AVS counter1 by software. The initial value can be updated at anytime. You can also pasuse the counter by setting AVS_CNT1_PS to ”1”. The counter value will not increase when it is paused.

3.6.6.19 0x00CC AVS Counter Divisor Register (Default Value: 0x05DB_05DB)

Offset: 0x00CC			Register Name: AVS_CNT_DIV_REG
Bit	Read/Write	Default/Hex	Description
31:28	/	/	/

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Offset: 0x00CC			Register Name: AVS_CNT_DIV_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
27:16	R/W	0x5DB	AVS_CNT1_D N1, the divisor factor for AVS1. The clock for AVS1 is 24 MHz/N1. N1 = Bit[27:16] + 1. The valid value for N1 is from 1 to 0x7ff. There is an internal 12-bit counter maintained by the engine of the 33-bit AVS1. The 12-bit counter is used for counting the cycle number of the clock OSC24M. When the value of the 12-bit counter reaches N1, the internal 33-bit counter register will increase 1 and the 12-bit counter will reset to zero and restart again. You can change the value of N1 via the software at any time.
15:12	/	/	/
11:0	R/W	0x5DB	AVS_CNT0_D N0, the divisor factor for AVS0. The clock for AVS0 is 24MHz/N0. N0 = Bit[11:0] + 1. The valid value for N0 is from 1 to 0x7ff. There is an internal 12-bit counter maintained by the engine of the 33-bit AVS0. The 12-bit counter is used for counting the cycle number of the clock OSC24M. When the value of the 12-bit counter reaches N0, the internal 33-bit counter register will increase 1 and the 12-bit counter will reset to zero and restart again. You can change the value of N0 via the software at any time.

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3.7 High Speed Timer

3.7.1 Overview

The high speed timer (HSTimer) module consists of HSTimer0 and HSTimer1. HSTimer0 and HSTimer1 are down counters that implement timing and counting functions. They are completely consistent. Compared with the timer module, the HSTimer module provides more precise timing and counting.

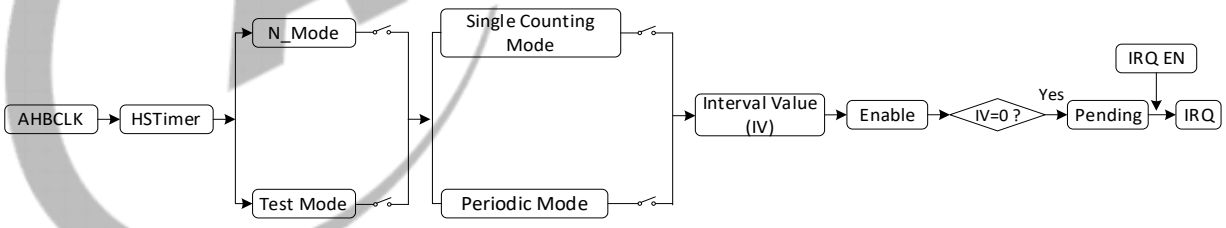
The HSTimer has the following features:

- Single clock source: AHB0
- Supports 5 prescale factors
- Configurable 56-bit down timer
- Supports 2 timing modes: periodic mode and one-shot mode
- Supports the test mode
- Generates an interrupt when the count is decreased to 0

3.7.2 Block Diagram

The following figure shows the block diagram of the HSTimer.

Figure 3-16 HSTimer Block Diagram



3.7.3 Functional Description

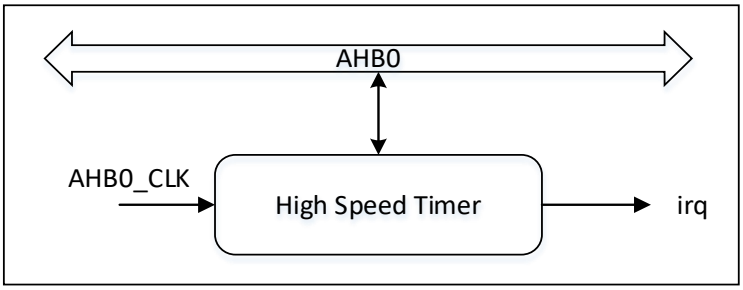
The HSTimers are 56-bit down counters. The counter value is decremented by 1 on each rising edge of the count clock. Each HSTimer has a prescaler that divides the working clock frequency of each working timer by 1, 2, 4, 8, or 16.

3.7.3.1 Typical Application

The following figure shows a typical application of HSTimer module.

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Figure 3-17 Typical Application for HSTimer



The HSTimer module is mounted at AHB0, and can control the registers via AHB0. AHB0 is the clock source of the HSTimer. When the count value reaches zero, the HSTimer generates an interrupt.

3.7.3.2 Count Modes

The HSTimer has two count modes: one-shot mode and periodic mode. You can configure the timing mode via the bit[7] of **HS_TMRn_CTRL_REG** (n = 0 or 1). The value 0 is for the period mode and value 1 is for the one-shot mode.

- One-shot Mode

  When the count value of the HSTimer reaches 0, the HSTimer stops counting. The HSTimer starts to count again only when a new value is loaded.

- Periodic Mode

  The HSTimer counts continuously. When the count value of the HSTimer reaches 0, the HSTimer reloads an initial value from **HS_TMRn_INTV_LO_REG** and **HS_TMRn_INTV_HI_REG** and then continues to count.

3.7.3.3 Operating Modes

The HSTimer has two operating modes: the normal mode and test mode. You can configure the operating mode via the bit[31] of **HS_TMRn_CTRL_REG**. The value 0 is for the normal mode and value 1 is for the test mode.

- Normal Mode

  In the normal mode, the HSTimer is used as a 56-bit down counter, which can finish one-shot counting and periodic counting. The interval value for the HSTimer consists of two parts: **HS_TMRn_INTV_LO_REG** forms the bit[31:0] and **HS_TMRn_INTV_HI_REG** forms the bit[55:32]. To read or write the interval value, **HS_TMRn_INTV_LO_REG** should be done before **HS_TMRn_INTV_HI_REG**.

- Test Mode

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In the test mode, the HSTimer is used as a 24-bit down counter. **HS_TMRn_INTV_LO_REG** must be set to 0x1, and **HS_TMRn_INTV_HI_REG** acts as the initial value for the HSTimer.

3.7.3.4 HSTimer Formula

The following formula describes the relationship among HSTimer parameters in the normal mode.

$$T_{HSTimer} = \frac{(HS_TMRn_INTV_HI_REG<<32 + HS_TMRn_INTV_LO_REG) - (HS_TMRn_CURNT_HI_REG<<32 + HS_TMRn_CURNT_LO_REG)}{AHB0CLK} \times HS_TMRn_CLK$$

Where,

The parameter n is either 0 or 1;

$T_{HSTimer}$ is the remaining time of the timer;

HS_TMRn_INTV_HI_REG is bit[55:32] of the HSTimer interval value;

HS_TMRn_INTV_LO_REG is bit[31:0] of the HSTimer interval value;

HS_TMRn_CURNT_HI_REG is bit[55:32] of the HSTimer current value;

HS_TMRn_CURNT_LO_REG is bit[31:0] of the HSTimer current value;

AHB0CLK is the frequency of AHB0 Clock (the HSTimer clock source);

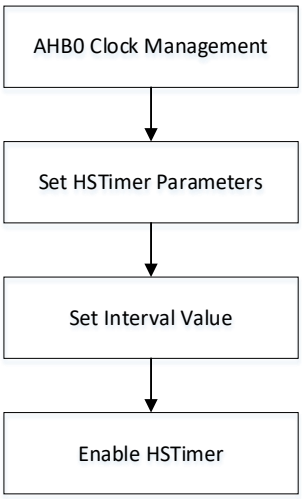
HS_TMRn_CLK is the prescale ratio of the HSTimer clock.

3.7.3.5 Initializing the HSTimer

The following figure shows the process of HSTimer initialization.

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Figure 3-18 HSTimer Initialization Process



1. AHB0 clock management: Open the clock gate of AHB0 and de-assert the soft reset of AHB0 in CCU.
2. Configure the corresponding parameters of the HSTimer: clock source, prescaler factor, operating mode, and timing mode. There is no sequence requirement when writing the above parameters to **HS_TMRn_CTRL_REG**.
3. Write the initial value: Write the lower 32 bits of the initial value to **HS_TMRn_INTV_LO_REG** first, and then the higher 24 bits to **HS_TMRn_INTV_HI_REG**. Normally, write the bit[1] of **HS_TMRn_CTRL_REG** to load the initial value. If the HSTimer is in the timing stop stage, write 1 to the bit[1] and bit[0] of **HS_TMRn_CTRL_REG** at the same time to reload the initial value.
4. Enable HSTimer: Write the bit[0] of **HS_TMRn_CTRL_REG** to enable HSTimer to count.
5. Reading **HS_TMRn_CURNT_LO_REG** and **HS_TMRn_CURNT_HI_REG** can get current counting value.

3.7.3.6 Processing the HSTimer Interrupt

Follow the steps below to process the HSTimer interrupt:

1. Enable interrupt: Write the corresponding interrupt enable bit of **HS_TMR_IRQ_EN_REG**, when the counting time of HSTimer reaches, the corresponding interrupt generates.
2. After entering the interrupt process, write **HS_TMR_IRQ_STAS_REG** to clear the interrupt pending.
3. Resume the interrupt and continue to execute the interrupted process.

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3.7.4 Programming Guidelines

The following example shows how to make a 1 us delay with HSTimer0. The frequency of the AHB0 clock is 100 MHz, the operating mode is the normal mode, the timing mode is single counting mode, and the pre-scale is 2.

```
writel(0x32, HS_TMR0_INTV_LO);                  //Set bit[31:0] of the interval value as 0x32.
writel(0x0, HS_TMR0_INTV_HI);                   //Set bit[55:32] of the interval value as 0x0.
writel(0x90, HS_TMR0_CTRL);
//Set the operating mode as Normal Mode, the pre-scale as 2, and the timing mode as Single Counting Mode.
writel(readl(HS_TMR0_CTRL)|(1<<1), HS_TMR0_CTRL);   //Set the reload bit.
writel(readl(HS_TMR0_CTRL)|(1<<0), HS_TMR0_CTRL);   //Enable HSTimer0.
while(!(readl(HS_TMR_IRQ_STAS)&1));             //Wait for HSTimer0 to generate pending.
writel(1, HS_TMR_IRQ_STAS);                         //Clear HSTimer0 pending.
```

3.7.5 Register List

Module Name	Base Address
HSTimer	0x03008000

Register Name	Offset	Description
HS_TMR_IRQ_EN_REG	0x0000	HS Timer IRQ Enable Register
HS_TMR_IRQ_STAS_REG	0x0004	HS Timer Status Register
HS_TMR0_CTRL_REG	0x0020	HS Timer0 Control Register
HS_TMR0_INTV_LO_REG	0x0024	HS Timer0 Interval Value Low Register
HS_TMR0_INTV_HI_REG	0x0028	HS Timer0 Interval Value High Register
HS_TMR0_CURNT_LO_REG	0x002C	HS Timer0 Current Value Low Register
HS_TMR0_CURNT_HI_REG	0x0030	HS Timer0 Current Value High Register
HS_TMR1_CTRL_REG	0x0040	HS Timer1 Control Register
HS_TMR1_INTV_LO_REG	0x0044	HS Timer1 Interval Value Low Register
HS_TMR1_INTV_HI_REG	0x0048	HS Timer1 Interval Value High Register
HS_TMR1_CURNT_LO_REG	0x004C	HS Timer1 Current Value Low Register
HS_TMR1_CURNT_HI_REG	0x0050	HS Timer1 Current Value High Register

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3.7.6 Register Description

3.7.6.1 0x0000 HS Timer IRQ Enable Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: HS_TMR_IRQ_EN_REG
Bit	Read/Write	Default/Hex	Description
31:2	/	/	/
1	R/W	0x0	HS_TMR1_INT_EN HSTimer1 Interrupt Enable 0: Disabled 1: Enabled
0	R/W	0x0	HS_TMR0_INT_EN HSTimer0 Interrupt Enable 0: Disabled 1: Enabled

3.7.6.2 0x0004 HS Timer IRQ Status Register (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: HS_TMR_IRQ_STAS_REG
Bit	Read/Write	Default/Hex	Description
31:2	/	/	/
1	R/W1C	0x0	HS_TMR1_IRQ_PEND HSTimer1 IRQ Pending The IRQ pending bit for HSTimer1. Write 1 to clear the pending status. 0: No effect 1: Pending, indicates that the initial value of the HSTimer is reached.
0	R/W1C	0x0	HS_TMR0_IRQ_PEND HSTimer0 IRQ Pending The IRQ pending bit for HSTimer0. Write 1 to clear the pending status. 0: No effect 1: Pending, indicates that the initial value of the HSTimer is reached.

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3.7.6.3 0x0020 HS Timer0 Control Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: HS_TMR0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	HS_TMR0_TEST Select the operating mode for HSTimer0 0: Normal mode 1: Test mode In the test mode, the **HS_TMR0_INTV_LO_REG** must be set to 0x1, and **HS_TMR0_INTV_HI_REG** acts as the initial value for HSTimer0.
30:8	/	/	/
7	R/W	0x0	HS_TMR0_MODE Select the timing mode for HSTimer0 0: Periodic mode. When the count value is decreased to 0, the timer will restart another round of counting automatically. 1: One-shot mode. When the count value is decreased to 0, the timer will stop counting.
6:4	R/W	0x0	HS_TMR0_CLK Select the pre-scale for the HSTimer0 clock sources 000: /1 001: /2 010: /4 011: /8 100: /16 101: / 110: / 111: /
3:2	/	/	/
1	R/W1S	0x0	HS_TMR0_RELOAD HSTimer0 Reload 0: No effect 1: Reload the interval value of the HSTimer0

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Offset: 0x0020			Register Name: HS_TMR0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	HS_TMR0_EN HSTimer0 Enable 0: Stop/Pause 1: Start By setting the bit to 1, the timer will be started. It reloads the interval value register and then counts from the interval value to 0. By setting the bit to 0 before the timer counts to 0, the timer will be paused. The bit will be locked to 0 for at least 2 cycles. Within the 2 cycles, you cannot set the bit to 1 to restart the timer. The timer supports updating the interval value in the pause state. To start from the updated interval value, set both the reload bit and enable bit to 1. Additionally, in the one-shot mode, after the count value reaches 0, the system will automatically change the bit to 0 to stop the timer.

3.7.6.4 0x0024 HS Timer0 Interval Value Lo Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: HS_TMR0_INTV_LO_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	HS_TMR0_INTV_VALUE_LO Bit[31:0] of the HSTimer0 interval value.

3.7.6.5 0x0028 HS Timer0 Interval Value Hi Register (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: HS_TMR0_INTV_HI_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:0	R/W	0x0	HS_TMR0_INTV_VALUE_HI Bit[55:32] of the HSTimer0 interval value.

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NOTE

HSTimer0 is a 56-bit counter. The interval value consists of two parts: HS_TMR0_INTV_VALUE_LO acts as the bit[31:0] and HS_TMR0_INTV_VALUE_HI acts as the bit[55:32]. To read or write the interval value, HS_TMR0_INTV_LO_REG should be done before HS_TMR0_INTV_HI_REG.

3.7.6.6 0x002C HS Timer0 Current Value Lo Register (Default Value: 0x0000_0000)

Offset: 0x002C			Register Name: HS_TMR0_CURNT_LO_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	HS_TMR0_CUR_VALUE_LO Bit[31:0] of the HSTimer0 current value.

3.7.6.7 0x0030 HS Timer0 Current Value Hi Register (Default Value: 0x0000_0000)

Offset: 0x0030			Register Name: HS_TMR0_CURNT_HI_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:0	R/W	0x0	HS_TMR0_CUR_VALUE_HI Bit[55:32] of the HSTimer0 current value.

NOTE

HSTimer0 is a 56-bit counter. The current value consists of two parts: HS_TMR0_CUR_VALUE_LO acts as the bit[31:0] and HS_TMR0_CUR_VALUE_HI acts as the bit[55:32]. To read or write the current value, HS_TMR0_CUR_VALUE_LO should be done before HS_TMR0_CUR_VALUE_HI.

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3.7.6.8 0x0040 HS Timer1 Control Register (Default Value: 0x0000_0000)

Offset: 0x0040			Register Name: HS_TMR1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	HS_TMR1_TEST Select the operating mode for HSTimer1. 0: Normal mode 1: Test mode In the test mode, the **HS_TMR1_INTV_LO_REG** must be set to 0x1, and **HS_TMR1_INTV_HI_REG** acts as the interval value for HSTimer1.
30:8	/	/	/
7	R/W	0x0	HS_TMR1_MODE Select the timing mode for HSTimer1. 0: Periodic mode. When the count value is decreased to 0, the timer will restart another round of counting automatically. 1: One-shot mode. When the count value is decreased to 0, the timer will stop counting.
6:4	R/W	0x0	HS_TMR1_CLK Select the pre-scale of the HSTimer1 clock sources. 000: /1 001: /2 010: /4 011: /8 100: /16 101: / 110: / 111: /
3:2	/	/	/
1	R/W1S	0x0	HS_TMR1_RELOAD HSTimer1 Reload 0: No effect 1: Reload the HSTimer1 interval value.

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Offset: 0x0040			Register Name: HS_TMR1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	HS_TMR1_EN HSTimer1 Enable 0: Stop/Pause 1: Start By setting the bit to 1, the timer will be started. It reloads the interval value register and then counts from the interval value to 0. By setting the bit to 0 before the timer counts to 0, the timer will be paused. The bit will be locked to 0 for at least 2 cycles. Within the 2 cycles, you cannot set the bit to 1 to restart the timer. The timer supports updating the interval value in the pause state. To start from the updated interval value, set both the reload bit and enable bit to 1. Additionally, in the one-shot mode, after the count value reaches 0, the system will automatically change the bit to 0 to stop the timer.

3.7.6.9 0x0044 HS Timer1 Interval Value Lo Register (Default Value: 0x0000_0000)

Offset: 0x0044			Register Name: HS_TMR1_INTV_LO_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	HS_TMR1_INTV_VALUE_LO Bit[31:0] of the HSTimer1 interval value

3.7.6.10 0x0048 HS Timer1 Interval Value Hi Register (Default Value: 0x0000_0000)

Offset: 0x0048			Register Name: HS_TMR1_INTV_HI_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:0	R/W	0x0	HS_TMR1_INTV_VALUE_HI Bit[55:32] of the HSTimer1 interval value

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NOTE

HSTimer1 is a 56-bit counter. The interval value consists of two parts: HS_TMR1_INTV_VALUE_LO acts as the bit[31:0] and HS_TMR1_INTV_VALUE_HI acts as the bit[55:32]. To read or write the interval value, HS_TMR1_INTV_LO_REG should be done before HS_TMR1_INTV_HI_REG.

3.7.6.11 0x004C HS Timer1 Current Value Lo Register (Default Value: 0x0000_0000)

Offset: 0x004C			Register Name: HS_TMR1_CURNT_LO_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	HS_TMR1_CUR_VALUE_LO Bit[31:0] of the HSTimer1 current value

3.7.6.12 0x0050 HS Timer1 Current Value Hi Register (Default Value: 0x0000_0000)

Offset: 0x0050			Register Name: HS_TMR1_CURNT_HI_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:0	R/W	0x0	HS_TMR1_CUR_VALUE_HI Bit[55:32] of the HSTimer1 current value

NOTE

HSTimer1 is a 56-bit counter. The current value consists of two parts: HS_TMR1_CUR_VALUE_LO acts as the bit[31:0] and HS_TMR1_CUR_VALUE_HI acts as the bit[55:32]. To read or write the current value, HS_TMR1_CUR_VALUE_LO should be done before HS_TMR1_CUR_VALUE_HI.

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3.8 Generic Interrupt Controller (GIC)

3.8.1 Overview

The GIC-400 is a high-performance, area-optimized interrupt controller with an Advanced Microcontroller Bus Architecture (AMBA) Advanced eXtensible Interface (AXI) interface. It detects, manages, and distributes interrupts in System on Chip (SoC) configurations. You can configure the GIC-400 to provide the optimum features, performance, and gate count required for your intended application.

For details about GIC, please refer to the *GIC PL400 technical reference* manual and *ARM GIC Architecture Specification V2.0*.

3.8.2 Functional Description

The following table describes the details of interrupt sources.

CAUTION

The CPU interrupt seen by DSP is subtracted 32 from the following interrupt number. For example, the interrupt number of MSGBOX is 32, then the interrupt number seen by DSP is 0.

Table 3-12 Interrupt Sources

Interrupt Number	Interrupt Source	Interrupt Vector	Description
0	SGI 0	0x0000	SGI 0 interrupt
1	SGI 1	0x0004	SGI 1 interrupt
2	SGI 2	0x0008	SGI 2 interrupt
3	SGI 3	0x000C	SGI 3 interrupt
4	SGI 4	0x0010	SGI 4 interrupt
5	SGI 5	0x0014	SGI 5 interrupt
6	SGI 6	0x0018	SGI 6 interrupt
7	SGI 7	0x001C	SGI 7 interrupt
8	SGI 8	0x0020	SGI 8 interrupt
9	SGI 9	0x0024	SGI 9 interrupt
10	SGI 10	0x0028	SGI 10 interrupt
11	SGI 11	0x002C	SGI 11 interrupt

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Interrupt Number	Interrupt Source	Interrupt Vector	Description
12	SGI 12	0x0030	SGI 12 interrupt
13	SGI 13	0x0034	SGI 13 interrupt
14	SGI 14	0x0038	SGI 14 interrupt
15	SGI 15	0x003C	SGI 15 interrupt
16	PPI 0	0x0040	PPI 0 interrupt
17	PPI 1	0x0044	PPI 1 interrupt
18	PPI 2	0x0048	PPI 2 interrupt
19	PPI 3	0x004C	PPI 3 interrupt
20	PPI 4	0x0050	PPI 4 interrupt
21	PPI 5	0x0054	PPI 5 interrupt
22	PPI 6	0x0058	PPI 6 interrupt
23	PPI 7	0x005C	PPI 7 interrupt
24	PPI 8	0x0060	PPI 8 interrupt
25	PPI 9	0x0064	PPI 9 interrupt
26	PPI 10	0x0068	PPI 10 interrupt
27	PPI 11	0x006C	PPI 11 interrupt
28	PPI 12	0x0070	PPI 12 interrupt
29	PPI 13	0x0074	PPI 13 interrupt
30	PPI 14	0x0078	PPI 14 interrupt
31	PPI 15	0x007C	PPI 15 interrupt
32	CPUX_MSGBOX_R	0x0080	CPUX MSGBOX READ IRQ
33		0x0084	
34	UART0	0x0088	
35	UART1	0x008C	
36	UART2	0x0090	
37	UART3	0x0094	
38	UART4	0x0098	
39	UART5	0x009C	
40		0x00A0	
41	TWI0	0x00A4	
42	TWI1	0x00A8	
43	TWI2	0x00AC	
44	TWI3	0x00B0	
45		0x00B4	

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Interrupt Number	Interrupt Source	Interrupt Vector	Description
46		0x00B8	
47	SPI0	0x00BC	
48	SPI1	0x00C0	
49		0x00C4	
50	PWM	0x00C8	
51	IR_TX	0x00CC	
52	LEDC	0x00D0	
53		0x00D4	
54		0x00D8	
55	OWA	0x00DC	
56	DMIC	0x00E0	
57	AUDIO_CODEC	0x00E4	
58	I2S/PCM0	0x00E8	
59	I2S/PCM1	0x00EC	
60	I2S/PCM2	0x00F0	
61	USB0_DEVICE	0x00F4	
62	USB0_EHCI	0x00F8	
63	USB0_OHCI	0x00FC	
64		0x0100	
65	USB1_EHCI	0x0104	
66	USB1_OHCI	0x0108	
67		0x010C	
68		0x0110	
69		0x0114	
70		0x0118	
71		0x011C	
72	SMHC0	0x0120	
73	SMHC1	0x0124	
74	SMHC2	0x0128	
75	MSI	0x012C	
76	SMC	0x0130	
77		0x0134	
78	EMAC	0x0138	
79	TZMA_ERR	0x013C	SRAM_A1 TZMA IRQ

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Interrupt Number	Interrupt Source	Interrupt Vector	Description
80	CCU_FERR	0x0140	
81	AHB_HREADY_TIME_OUT	0x0144	SYS_CTRL ahb_hready time out
82	DMAC_NS	0x0148	
83	DMAC_S	0x014C	
84	CE_NS	0x0150	
85	CE_S	0x0154	
86	SPINLOCK	0x0158	
87	HSTIMER0	0x015C	
88	HSTIMER1	0x0160	
89	GPADC	0x0164	
90	THS	0x0168	Thermal Sensor IRQ
91	TIMER0	0x016C	
92	TIMER1	0x0170	
93	LRADC	0x0174	
94	TPADC	0x0178	
95	WATCHDOG	0x017C	
96	IOMMU	0x0180	
97		0x0184	
98	VE	0x0188	
99		0x018C	
100		0x0190	
101	GPIOB_NS	0x0194	
102	GPIOB_S	0x0198	
103	GPIOC_NS	0x019C	
104	GPIOC_S	0x01A0	
105	GPIOD_NS	0x01A4	
106	GPIOD_S	0x01A8	
107	GPIOE_NS	0x01AC	
108	GPIOE_S	0x01B0	
109	GPIOF_NS	0x01B4	
110	GPIOF_S	0x01B8	
111	GPIOG_NS	0x01BC	
112	GPIOG_S	0x01C0	

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Interrupt Number	Interrupt Source	Interrupt Vector	Description
113		0x01C4	
114		0x01C8	
115		0x01CC	
116		0x01D0	
117	CPUX_MSGBOX_DSP_W	0x01D4	CPUX MSGBOX WRITE IRQ for DSP
118		0x01D8	
119	DE	0x01DC	
120	DI	0x01E0	
121	G2D	0x01E4	
122	LCD	0x01E8	
123		0x01EC	
124	DSI	0x01F0	
125		0x01F4	
126		0x01F8	
127	CSI_DMA0	0x01FC	
128	CSI_DMA1	0x0200	
129		0x0204	
130		0x0208	
131		0x020C	
132	CSI_PARSER0	0x0210	
133		0x0214	
134		0x0218	
135		0x021C	
136		0x0220	
137		0x0224	
138	CSI_TOP_PKT	0x0228	
139		0x022C	
140		0x0230	
141		0x0234	
142		0x0238	
143		0x023C	
144		0x0240	
145		0x0244	

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Interrupt Number	Interrupt Source	Interrupt Vector	Description
146		0x0248	
147		0x024C	
148		0x0250	
149		0x0254	
150		0x0258	
151		0x025C	
152	DSP_DEE	0x0260	DSP_SYS[0]: DoubleExceptionError
153	DSP_PFE	0x0264	DSP_SYS[1]: PFatalError
154	DSP_WDG	0x0268	
155	DSP_MBOX_CPUX_W	0x026C	
156		0x0270	
157	DSP_TZMA	0x0274	
158		0x0278	
159		0x027C	
160		0x0280	
161		0x0284	
162		0x0288	
163		0x028C	
164		0x0290	
165		0x0294	
166		0x0298	
167		0x029C	
CPUS Related			
168	NMI	0x02A0	
169	PPU	0x02A4	
170	TWD	0x02A8	
171		0x02AC	
172	TIMER0	0x02B0	
173	TIMER1	0x02B4	
174	TIMER2	0x02B8	
175	TIMER3	0x02BC	
176	ALARM0	0x02C0	
177		0x02C4	

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Interrupt Number	Interrupt Source	Interrupt Vector	Description
178		0x02C8	
179		0x02CC	
180		0x02D0	
181		0x02D4	
182		0x02D8	
183	IRRX	0x02DC	CPUS_IRRX_IRQ[9:0] OR to 1-bit in syscpus top
184		0x02E0	
185		0x02E4	
186	AHBS_HREADY_TIME_OUT	0x02EC	CPUS AHB READY TIME OUT IRQ
187		0x02F0	
188		0x02F4	
189		0x02F8	
190		0x02FC	
191		0x0300	
CPUX Related			
192	C0_CTI0	0x0304	C0_CTI0 interrupt
193	C0_CTI1	0x0308	C0_CTI1 interrupt
194		0x030C	
195		0x0310	
196	C0_COMMTX0	0x0314	C0_COMMTX0 interrupt
197	C0_COMMTX1	0x0318	C0_COMMTX1 interrupt
198		0x031C	
199		0x0320	
200	C0_COMMRX0	0x0324	C0_COMMRX0 interrupt
201	C0_COMMRX1	0x0328	C0_COMMRX1 interrupt
202		0x032C	
203		0x0330	
204	C0_PMU0	0x0334	C0_PMU0 interrupt
205	C0_PMU1	0x0338	C0_PMU1 interrupt
206		0x033C	
207		0x0340	
208	C0_AXI_ERROR	0x0344	C0_AXI_ERROR interrupt

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Interrupt Number	Interrupt Source	Interrupt Vector	Description
209		0x0348	
210	AXI_WR_IRQ	0x034C	
211	AXI_RD_IRQ	0x0350	
212	DBGPWRUPREQ_out[0]	0x0354	
213	DBGPWRUPREQ_out[1]	0x0358	
214		0x035C	
215		0x0360	
216		0x0364	
217		0x0368	
218		0x036C	
219		0x0370	
220		0x0374	
221		0x0378	
222		0x037C	
223		0x0380	

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3.9 Direct Memory Access Controller (DMAC)

3.9.1 Overview

The direct memory access (DMA) is a method of transferring data between peripherals and memories (including the SRAM and DRAM) without using the CPU. It is an efficient way to offload data transfer duties from the CPU. Without DMA, the CPU has to control all the data transfers. While with DMA, the DMAC directly transfers data between a peripheral and a memory, between peripherals, or between memories.

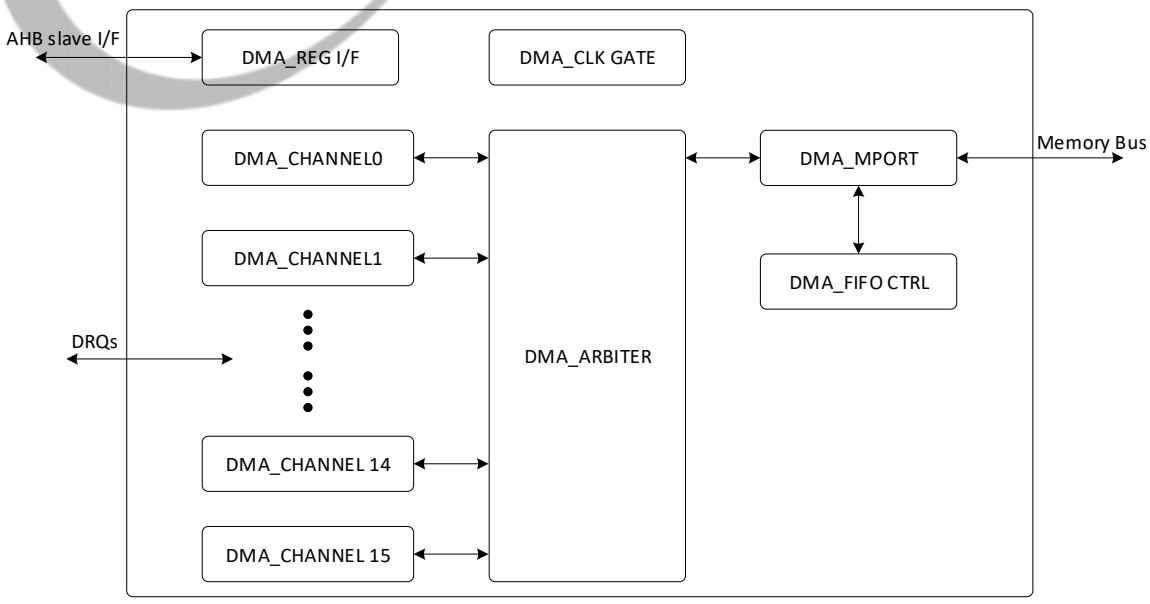
The DMAC has the following features:

- Up to 16 DMA channels
- Provides 32 peripheral DMA requests for data reading and 32 peripheral DMA requests for data writing
- Supports transferring data with a linked list
- Supports programmable 8-bit, 16-bit, 32-bit, and 64-bit data width
- Supports programmable DMA burst length
- DRQ response includes the waiting mode and handshake mode
- DMA channel supports pause function
- Memory devices support non-aligned transform

3.9.2 Block Diagram

The following figure shows a block diagram of DMAC.

Figure 3-19 DMAC Block Diagram



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DMAC contains the following sub-blocks:

Table 3-13 DMAC Sub-blocks

Sub-block	Description
DMA_ARBITER	Arbitrates the DMA read/write requests from all channels, and converts the requests to the read/write requests of ports.
DMA_CHANNELs	DMA transfer engine. Each channel is independent. When the DMA requests from multiple peripherals are valid simultaneously, the channel with the highest priority starts data transfer first. The system uses the polling mechanism to decide the priorities of DMA channels. When DMA_ARBITER is idle, channel 0 has the highest priority, whereas channel 15 has the lowest priority. When DMA_ARBITER is busy processing the request from channel n, channel (n+1) has the highest priority. For n = 15, the channel (n + 1) should be channel 0.
DRQs	DMA requests. Peripherals use the DMA request signals to request a data transfer.
DMA_MPORT	Receives the read/write requests from DMA_ARBITER, and converts the requests to the corresponding MBUS access requests. It is mainly used for accessing the DRAM.
DMA_HPORT	The port for accessing the AHB Master. It is mainly used for accessing the SRAM and IO devices.
DMA_FIFO CTRL	Internal FIFO cell control module.
DMA_REG Interface	DMA_REG is the common register module that is mainly used to resolve AHB demands.
DMA_CLKGATE	The control module for hardware auto clock gating.

The DMAC integrates 16 independent DMA channels and each channel has an independent FIFO controller. When the DMA channel starts, the DMAC gets a DMA descriptor from the DMA_DESC_ADDR_REG and uses it as the configuration information for the data transfer of the current DMA package. Then the DMAC can transfer data between the specified devices. After transferring a DMA package, the DMAC judges if the current channel transfer is finished via the linked address in the descriptor. If the linked address shows all the packages are transferred, the DMAC will end the chain transmission and close the channel.

3.9.3 Functional Description

3.9.3.1 Clock

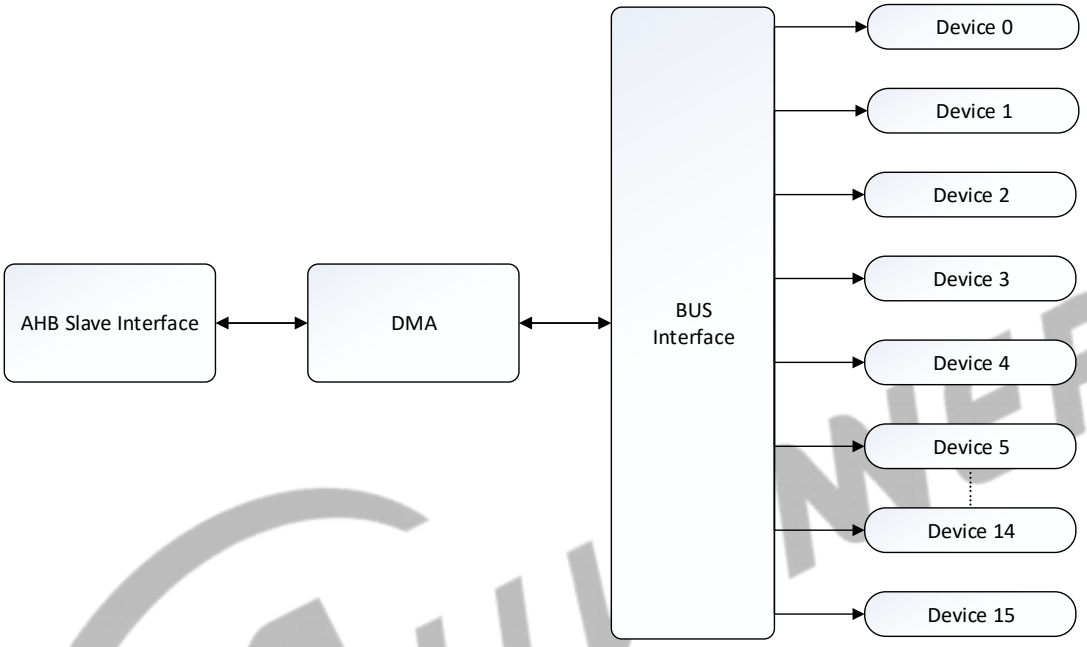
The DMAC is on MBUS. The clock of MBUS influences the transfer efficiency of the DMAC.

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3.9.3.2 Typical Application

The following figure shows a typical application of the DMAC.

Figure 3-20 DMAC Typical Application Diagram



3.9.3.3 DRQ Port of Peripherals

The following table shows the source DRQ types and destination DRQ types of different ports.

Table 3-14 DMA DRQ Type

Source DRQ Type		Destination DRQ Type	
port0	SRAM	port0	SRAM
port1	DRAM	port1	DRAM
port2		port2	OWA-TX
port3	I2S/PCM0-RX	port3	I2S/PCM0-TX
port4	I2S/PCM1-RX	port4	I2S/PCM1-TX
port5	I2S/PCM2-RX	port5	I2S/PCM2-TX
port6		port6	
port7	Audio_Codec	port7	Audio_Codec
port8	DMIC	port8	

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Source DRQ Type		Destination DRQ Type	
port9		port9	
port10		port10	
port11		port11	
port12	GPADC	port12	
port13	TPADC	port13	IR-TX
port14	UART0-RX	port14	UART0-TX
port15	UART1-RX	port15	UART1-TX
port16	UART2-RX	port16	UART2-TX
port17	UART3-RX	port17	UART3-TX
port18	UART4-RX	port18	UART4-TX
port19	UART5-RX	port19	UART5-TX
port20		port20	
port21		port21	
port22	SPI0-RX	port22	SPI0-TX
port23	SPI1-RX	port23	SPI1-TX
port24		port24	
port25		port25	
port26		port26	
port27		port27	
port28		port28	
port29		port29	
Port30	USB0_EP1	Port30	USB0_EP1
Port31	USB0_EP2	Port31	USB0_EP2
Port32	USB0_EP3	Port32	USB0_EP3
Port33	USB0_EP4	Port33	USB0_EP4
Port34	USB0_EP5	Port34	USB0_EP5
Port35		Port35	
Port36		Port36	
Port37		Port37	
Port38		Port38	
Port39		Port39	
Port40		Port40	
Port41		Port41	
Port42		Port42	LEDC

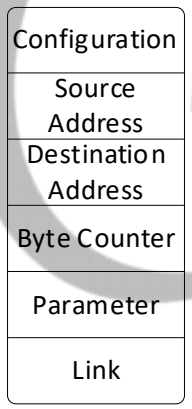
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Source DRQ Type		Destination DRQ Type	
Port43	TWI0	Port43	TWI0
Port44	TWI1	Port44	TWI1
Port45	TWI2	Port45	TWI2
Port46	TWI3	Port46	TWI3
Port47		Port47	
Port48		Port48	
Port49		Port49	
Port50		Port50	
Port51		Port51	
Port52		Port52	
Port53		Port53	

3.9.3.4 DMA Descriptor

The DMAC descriptor is the configuration information of DMA transfer that decides the DMA working mode. Each descriptor includes 6 words: Configuration, Source Address, Destination Address, Byte Counter, Parameter, and Link. The following figure shows the structure of the DMA descriptor.

Figure 3-21 DMA Descriptor



- **Configuration:** Configure the following information by DMA_CFG_REG.
  - DRQ type: DRQ type of the source and destination devices.
  - Address counting mode: For both the source and destination devices, there are two address counting modes: the IO mode and linear mode. The IO mode is for IO devices whose address is fixed during the data transfer and the linear mode is for the memory whose address is increasing during the data transfer.

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- Transferred block length: The amount of data that non-memory peripherals can transfer in a valid DRQ. The block length supports 1 bit, 4 bits, 8 bits, and 16 bits.
- Transferred data width: The data width of operating the non-memory peripherals. The data width supports 8 bits, 16 bits, 32 bits, and 64 bits.

NOTE

The configuration supports BMODE mode. The BMODE is used in the following scenario: the source is an IO device, and the destination is a memory device. Setting the BMODE mode can limit the amount of block data transferred in DMA block transmission to the amount of data transferred when the DRQ threshold of the source IO device is 1. For example,

- **Source Address:** Configure the address of the source device.
- **Destination Address:** Configure the address of the destination device.

DMA reads data from the source address and then writes data to the destination address.

Both the DMA source and destination addresses have 34 bits. In the descriptor, because there are only 32 bits in the **Source/Destination Address** field, another 2 bits are stored in the **Parameter** field.

The following table shows the details of the related fields in the descriptor.

Table 3-15 Source/Destination Address Distribution

Descriptor Group	Bit	Description
Source Address	31:0	DMA transfers the lower 32 bits of the 34-bit source address
Destination Address	31:0	DMA transfers the lower 32 bits of the 34-bit destination address
Parameter	31:20	Reserved
	19:18	DMA transfers the higher 2 bits of the 34-bit destination address
	17:16	DMA transfers the high 2 bits of the 34-bit source address
	15:8	Reserved
	7:0	Wait Clock Cycles Set the waiting time in DRQ mode
Link	31:2	The address of the next group descriptor, the lower 30 bits of the word address
	1:0	The address of the next group descriptor, the higher 2 bits of the word address

From the above table, you can get:

Real DMA source address (in byte mode) = {Parameter [17:16], Source Address [31:0]};

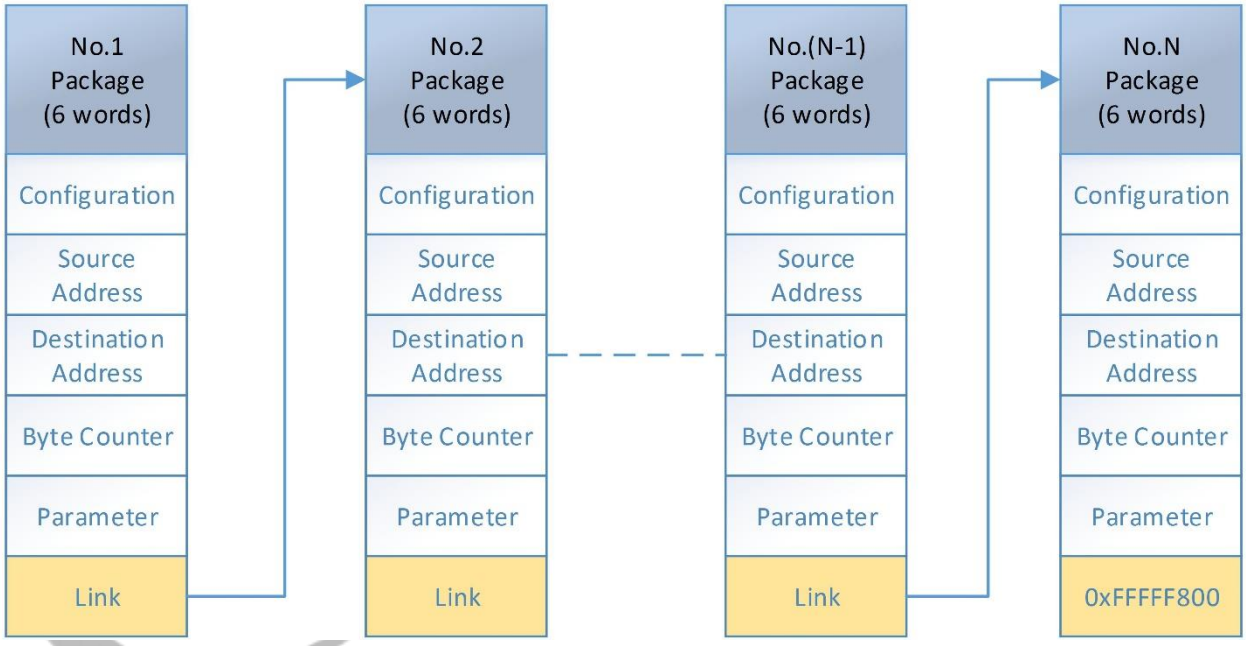
Real DMA destination address (in byte mode) = {Parameter [19:18], Destination Address [31:0]};

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Real link address (in byte mode) = {Link[1:0], Link[31:2], 2'b00}.

- **Byte counter: Configure the data amount of a package. The maximum value is (2^25-1) bytes. If the data amount of the package reaches the maximum value, even if DRQ is valid, the DMA will stop the current transfer.**
- **Parameter: Configure the interval between the data block. The parameter is valid for non-memory peripherals. When DMA detects that the DRQ is high, the DMA transfers the data block and ignores the status changes of the DRQ until the data transfer finishes. After that, the DMA waits for certain clock cycles (WAIT_CYC) and executes the next DRQ detection.**
- **Link: If the value of the link is 0xFFFFF800, the current package is at the end of the linked list. The DMAC will stop the data transfer after transferring the package; otherwise, the value of the link is considered as the descriptor address of the next package.**

Figure 3-22 DMA Chain Transfer



3.9.3.5 Interrupts

There are three kinds of DMA interrupts: the half package interrupt, package end interrupt, and queue end interrupt.

Half package interrupt: When enabled, the DMAC sends out a half package interrupt after transferring half of a package.

Package end interrupt: When enabled, the DMAC sends out a package end interrupt after transferring a complete package.

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Queue end interrupt: When enabled, the DMAC sends out a queue end interrupt after transferring a complete queue.

Notice that when CPU does not respond to the interrupts timely, or two DMA interrupts are generated very closely, the later interrupt may override the former one. That is, from the perspective of the CPU, the DMAC has only a system interrupt source.

NOTE

The DMAC has 16 channels and 2 groups of interrupts. The channel [7:0] corresponds to one group of interrupt, the channel [15:8] corresponds to anther group of interrupt. Each group of interrupt includes the secure and non-secure interrupts. The DSP is fixed to use the interrupt of the channel [15:8].

3.9.3.6 Security

The DMAC supports the system Trustzone and the security mode configuration of the DMA channel.

Each DMA channel is secure by default. When system Trustzone is enabled, the DMAC is secure, only the secure devices can access the DMAC.

When a DMA channel is configured to the non-secure mode, this channel can only access the non-secure area of the memory, that is, the DMAC cannot write data to the secure area of the memory, and the read-back data from the secure area of the memory is 0.

3.9.3.7 Clock Gating

The DMA_CLK_GATE module is a hardware module for controlling the clock gating automatically. It provides clock sources for sub-modules in DMAC and the module local circuits.

The DMA_CLK_GATE module consists of two parts: the channel clock gate and the common clock gate.

Channel clock gate: Controls the DMA clock of the DMA channels. When the system accesses the register of the current DMA channel and the DMA channel is enabled, the channel clock gate automatically opens the DMA clock. With a 16-HCLK-cycle delay after the system finishes accessing the register or the DMA data transfer is completed, the channel clock gate automatically closes the DMA clock. Also, the clock for the related circuits, such as for the channel control and FIFO control modules, will be closed.

Common clock gate: Controls the clocks of the DMA common circuits. The common circuits include the common circuit of the FIFO control module, MPORT module, and MBUS. When all the DMA channels are enabled, the common clock gate automatically closes the clocks for the above circuits.

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The DMA clock gating can support all the functions stated above or not by software.

3.9.3.8 Transfer Mode

The peripherals initiate data transfer by transmitting DMA request signals to the DMAC. After receiving the request signal, the DMAC converts it to the internal DRQ signal and controls the DMA data transfer.

The DMAC supports two data transfer modes: the waiting mode and handshake mode.

The principle of waiting mode

- When the DMAC detects a valid external request signal, the DMAC starts to operate the peripheral device. The internal DRQ always holds high before the transferred data amount reaches the transferred block length.
- When the transferred data amount reaches the transferred block length, the internal DRQ pulls low automatically.
- The internal DRQ holds low for certain clock cycles (WAIT_CYC), and then the DMAC restarts to detect the external requests. If the external request signal is valid, then the next transfer starts.

The principle of handshake mode

- When the DMAC detects a valid external request signal, the DMAC starts to operate the peripheral device. The internal DRQ always holds high before the transferred data amount reaches the transferred block length.
- When the transferred data amount reaches the transferred block length, the internal DRQ will be pulled down automatically. For the last data transfer of the block, the DMAC sends a DMA Last signal with the DMA commands to the peripheral device. The DMA Last signal will be packed as part of the DMA commands and transmitted on the bus. It is used to inform the peripheral device that it is the end of the data transfer for the current DRQ.
- When the peripheral device receives the DMA Last signal, it can judge that the data transfer for the current DRQ is finished. To continue the data transfer, it sends a DMA Active signal to the DMAC.

> **NOTE**
>
> One DMA Active signal will be converted to one DRQ signal in the DMA module. To generate multiple DRQs, the peripheral device needs to send out multiple DMA Active signals via the bus protocol.

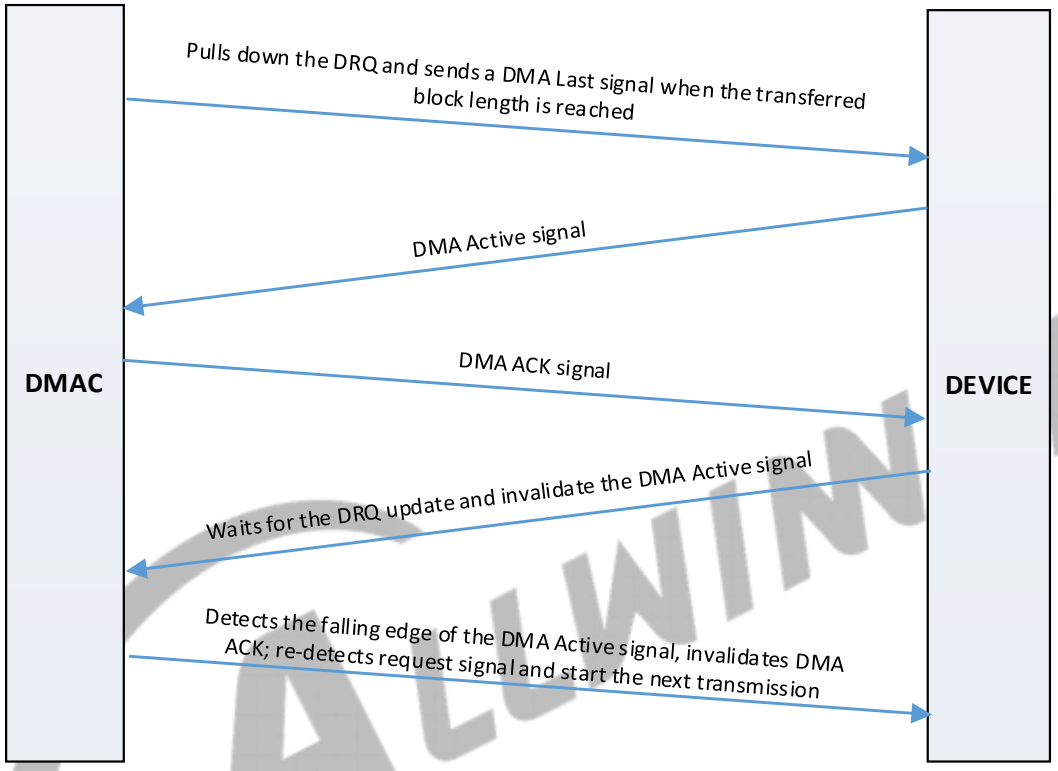
- When the DMAC received the DMA Active signal, it sends back a DMA ACK signal to the peripheral device.
- When the peripheral device receives the DMA ACK signal, it waits for all the operations on the local device completed, and both the FIFO and DRQ status refreshed. Then it invalidates the DMA Active signal.

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- When the DMAC detects the falling edge of the DMA Active signal, it invalidates the corresponding DMA ACK signal, and restarts to detect the external request signals. If a valid request signal is detected, the next data transfer starts.

The following figure shows the workflow of the handshake mode.

Figure 3-23 Workflow of the DMAC Handshake Mode



3.9.3.9 Address Auto-Alignment

For the non-IO devices whose start address is not 32-byte-aligned, the DMAC will adjust the address to 32-byte-aligned through the burst transfer within 32 bytes. Adjusting address to 32-byte-aligned improves the DRAM access efficiency.

The following example shows how the DMAC adjusts the address: when the peripheral device of a DMA channel is a non-IO device whose start address is 0x86 (not 32-byte-aligned), the DMAC firstly uses a 26-byte burst transfer to align the address to 0xA0 (32-byte-aligned), and then transfers data by 64-byte burst (the maximum transfer amount that MBUS allows).

The IO devices do not support address alignment, so the bit width of IO devices must match the address offset; otherwise, the DMAC will ignore the inconsistency and directly transmit data of the corresponding bit width to the address.

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The address of the DMA descriptor does not support the address auto-alignment. Make sure the address is word-aligned; otherwise the DMAC cannot identify the descriptor.

3.9.3.10 DMAC Clock Control

- The DMAC clock is synchronous with the AHB0 clock. Make sure that the DMAC gating bit of AHB0 clock is enabled before accessing the DMAC register.
- The reset input signal of the DMAC is asynchronous with AHB0 and is low valid by default. Make sure that the reset signal of the DMAC is de-asserted before accessing the DMA register.
- To avoid the indefinite state within registers, de-assert the reset signal first, and then open the gating bit of AHB0.
- The DMAC supports Clock Auto Gating function to reduce power consumption, the system will automatically disable the DMAC clock in the DMAC idle state. Clock Auto Gating is enabled by default.

3.9.4 Programming Guidelines

3.9.4.1 Using DMAC Transfer Process

The DMAC transfer process is as follows.

Step 1 Request DMA channel, and check if the DMA channel is idle by checking if it is enabled. A disabled channel indicates it is idle, while an enabled channel indicates it is busy.

Step 2 Write the descriptor with 6 words into the memory. The descriptor must be word-aligned. For more details, refer to section 3.9.3.4 "DMA Descriptor".

Step 3 Write the start address of the descriptor to **DMA_DESC_ADDR_REGN**.

Step 4 Enable the DMA channel, and write the corresponding channel to **DMAC_EN_REGN**.

Step 5 The DMA obtains the descriptor information.

Step 6 Start to transmit a package. When half of the package is completed, the DMA sends a Half Package Transfer Interrupt; when a total package is completed, the DMA sends a Package End Transfer Interrupt. These interrupt status can be read by **DMAC_IRQ_PEND_REG0**.

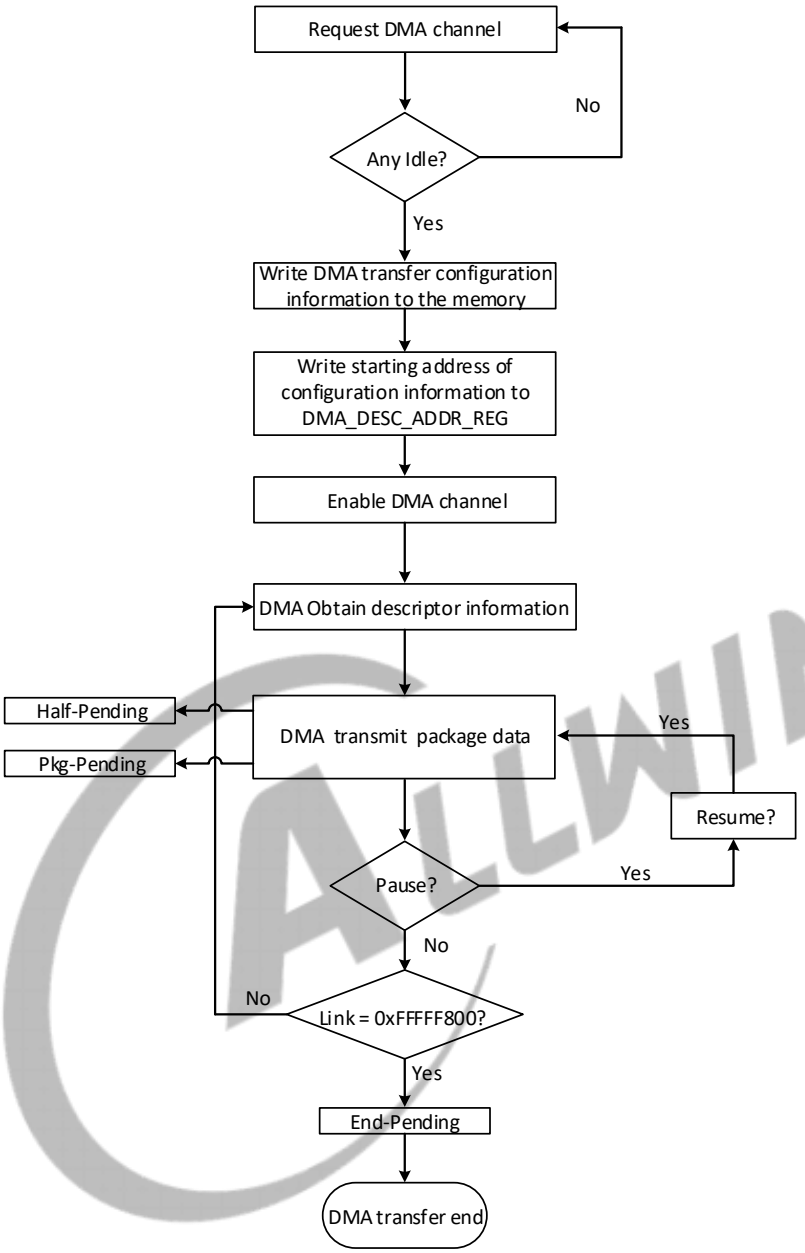
Step 7 Set **DMAC_PAU_REGN** to pause or resume the data transfer.

Step 8 After completing a total package transfer, the DMA decides to start the next package transfer or end the transfer by the link of the descriptor. If the link is 0xFFFFF800, the transfer ends; otherwise, the next package starts to transmit. When the transfer ends, the DMA sends a Queue End Transfer Interrupt.

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Step 9 Disable the DMA channel.

Figure 3-24 DMAC Transfer Process



3.9.4.2 Processing DMAC Interrupt

Follow the steps below to process the DMAC interrupt:

Step 1 Enable interrupt: write the corresponding interrupt enable bit of **DMAC_IRQ_EN_REG0**. The system generates an interrupt when the corresponding condition is satisfied.

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Step 2 After entering the interrupt process, write to clear the interrupt pending and execute the process of waiting for the interrupt.

Step 3 Resume the interrupt and continue to execute the interrupted process.

3.9.4.3 Configuring DMAC

To configure the DMAC, follow the guidelines below:

- Make sure the transfer bit width of IO devices is consistent with the offset of the start address.
- The MBUS protocol does not support the read operation of non-integer words. For the devices whose bit width is not word-aligned, after receiving the read command, they should resolve the read command according to their FIFO bit width instead of the command bit width, and ignore the redundant data caused by the inconsistency of the bit width.
- When the DMA transfer is paused, this is equivalent to invalid DRQ. Because there is a certain time delay between DMA transfer commands, the DMAC will not stop data transfer until the DMAC finishes processing the current command and the commands in Arbiter (at most 32 bytes data).

DMAC application example:

```
writel(0x00000000, mem_address + 0x00);   //Set configurations. The mem_address must be word-aligned.
writel(0x00001000, mem_address + 0x04);    // Set the start address for the source device.
writel(0x20000000, mem_address + 0x08);   //Set the start address for the destination device.
writel(0x00000020, mem_address + 0x0C);   // Set the data package size.
writel(0x00000000, mem_address + 0x10);   //Set the parameters.
writel(0xFFFFF800, mem_address + 0x14);   //Set the start address for the next descriptor.
writel(mem_address, 0x01C02000+ 0x100 + 0x08); //Set the start address for the DMA channel0 descriptor.
do{
If(mem_address == readl(0x01C02000 + 0x100 + 0x08));
break;
}while(1);              //Make sure that the writing operation is valid.
writel(0x000000001, 0x01C02000 + 0x100 + 0x00);      // Enable DMA channel0 transfer.
```

The DMAC supports increasing data package in transfer, pay attention to the following points:

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- The 0xFFFFF800 value of DMAC_FDESC_ADDR_REGN indicates that the DMA channel has got back the descriptor of the last package. The DMA channel will automatically stop the data transfer after transferring the current package.
- To add a package during the data transfer, check if the DMA channel has got back the descriptor of the last package. If yes, you cannot add any package in the current queue. Request another DMA channel with a new DRQ to transfer the package. Otherwise, you can add the package by modifying the DMAC_FDESC_ADDR_REGN of the last package from 0xFFFFF800 to the start address of the to-be-added package.

  To ensure that the modification is valid, read the value of DMAC_FDESC_ADDR_REGN after the modification. The value 0xFFFFF800 indicates the modification fails and the other values indicate you have successfully added packages to the queue.

  Another problem is, the system needs some time to process the modification, during which the DMA channel may get back the descriptor of the last package. You can read DMAC_CUR_SRC_REGN and DMAC_CUR_DEST_REGN and check if the increasing memory address accords with the information of the added package. If yes, the package is added successfully; otherwise, the modification failed.

  To ensure a higher rate of success, it is suggested that you add the package before the half package interrupt of the penultimate package.

3.9.5 Register List

Module Name	Base Address
DMAC	0x03002000

Register Name	Offset	Description
DMAC_IRQ_EN_REG0	0x0000	DMAC IRQ Enable Register 0
DMAC_IRQ_EN_REG1	0x0004	DMAC IRQ Enable Register 1
DMAC_IRQ_PEND_REG0	0x0010	DMAC IRQ Pending Register 0
DMAC_IRQ_PEND_REG1	0x0014	DMAC IRQ Pending Register 1
DMAC_SEC_REG	0x0020	DMAC Security Register
DMAC_AUTO_GATE_REG	0x0028	DMAC Auto Gating Register
DMAC_STA_REG	0x0030	DMAC Status Register
DMAC_EN_REGN	0x0100 + N*0x0040	DMAC Channel Enable Register N (N = 0 to 15)
DMAC_PAU_REGN	0x0104 + N*0x0040	DMAC Channel Pause Register N (N = 0 to 15)
DMAC_DESC_ADDR_REGN	0x0108 + N*0x0040	DMAC Channel Start Address Register N (N = 0 to 15)
DMAC_CFG_REGN	0x010C + N*0x0040	DMAC Channel Configuration Register N (N = 0 to 15)

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Register Name	Offset	Description
DMAC_CUR_SRC_REGN	0x0110 + N*0x0040	DMAC Channel Current Source Register N (N = 0 to 15)
DMAC_CUR_DEST_REGN	0x0114 + N*0x0040	DMAC Channel Current Destination Register N (N = 0 to 15)
DMAC_BCNT_LEFT_REGN	0x0118 + N*0x0040	DMAC Channel Byte Counter Left Register N (N = 0 to 15)
DMAC_PARA_REGN	0x011C + N*0x0040	DMAC Channel Parameter Register N (N = 0 to 15)
DMAC_MODE_REGN	0x0128 + N*0x0040	DMAC Mode Register N (N = 0 to 15)
DMAC_FDESC_ADDR_REGN	0x012C + N*0x0040	DMAC Former Descriptor Address Register N (N = 0 to 15)
DMAC_PKG_NUM_REGN	0x0130 + N*0x0040	DMAC Package Number Register N (N = 0 to 15)

3.9.6 Register Description

3.9.6.1 0x0000 DMAC IRQ Enable Register0 (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: DMAC_IRQ_EN_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31	/	/	/
30	R/W	0x0	DMA7_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 7 0: Disabled 1: Enabled
29	R/W	0x0	DMA7_PKG_IRQ_EN Enable the package end interrupt of DMA channel 7 0: Disabled 1: Enabled
28	R/W	0x0	DMA7_HLAF_IRQ_EN Enable the half package interrupt of DMA channel 7 0: Disabled 1: Enabled
27	/	/	/
26	R/W	0x0	DMA6_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 6 0: Disabled 1: Enabled

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Offset: 0x0000			Register Name: DMAC_IRQ_EN_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
25	R/W	0x0	DMA6_PKG_IRQ_EN Enable the package end interrupt of DMA channel 6 0: Disabled 1: Enabled
24	R/W	0x0	DMA6_HLAF_IRQ_EN Enable the half package interrupt of DMA channel 6 0: Disabled 1: Enabled
23	/	/	/
22	R/W	0x0	DMA5_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 5 0: Disabled 1: Enabled
21	R/W	0x0	DMA5_PKG_IRQ_EN Enable the package end interrupt of DMA channel 5 0: Disabled 1: Enabled
20	R/W	0x0	DMA5_HLAF_IRQ_EN Enable the half package interrupt of DMA channel 5 0: Disabled 1: Enabled
19	/	/	/
18	R/W	0x0	DMA4_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 4 0: Disabled 1: Enabled
17	R/W	0x0	DMA4_PKG_IRQ_EN Enable the package end interrupt of DMA channel 4 0: Disabled 1: Enabled
16	R/W	0x0	DMA4_HLAF_IRQ_EN Enable the half package interrupt of DMA channel 4 0: Disabled 1: Enabled
15	/	/	/

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Offset: 0x0000			Register Name: DMAC_IRQ_EN_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
14	R/W	0x0	DMA3_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 3 0: Disabled 1: Enabled
13	R/W	0x0	DMA3_PKG_IRQ_EN Enable the package end interrupt of DMA channel 3 0: Disabled 1: Enabled
12	R/W	0x0	DMA3_HLAF_IRQ_EN Enable the half package interrupt of DMA channel 3 0: Disabled 1: Enabled
11	/	/	/
10	R/W	0x0	DMA2_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 2 0: Disabled 1: Enabled
9	R/W	0x0	DMA2_PKG_IRQ_EN Enable the package end interrupt of DMA channel 2 0: Disabled 1: Enabled
8	R/W	0x0	DMA2_HLAF_IRQ_EN Enable the half package interrupt of DMA channel 2 0: Disabled 1: Enabled
7	/	/	/
6	R/W	0x0	DMA1_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 1 0: Disabled 1: Enabled
5	R/W	0x0	DMA1_PKG_IRQ_EN Enable the package end interrupt of DMA channel 1 0: Disabled 1: Enabled

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Offset: 0x0000			Register Name: DMAC_IRQ_EN_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W	0x0	DMA1_HLAF_IRQ_EN Enable the half package interrupt of DMA channel 1 0: Disabled 1: Enabled
3	/	/	/
2	R/W	0x0	DMA0_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 0 0: Disabled 1: Enabled
1	R/W	0x0	DMA0_PKG_IRQ_EN Enable the package end interrupt of DMA channel 0 0: Disabled 1: Enabled
0	R/W	0x0	DMA0_HLAF_IRQ_EN Enable the half package interrupt of DMA channel 0 0: Disabled 1: Enabled

3.9.6.2 0x0004 DMAC IRQ Enable Register1 (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: DMAC_IRQ_EN_REG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31	/	/	/
30	R/W	0x0	DMA15_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 15 0: Disabled 1: Enabled
29	R/W	0x0	DMA15_PKG_IRQ_EN Enable the package end interrupt of DMA channel 15 0: Disabled 1: Enabled
28	R/W	0x0	DMA15_HALF_IRQ_EN Enable the half package interrupt of DMA channel 15 0: Disabled 1: Enabled

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Offset: 0x0004			Register Name: DMAC_IRQ_EN_REG1
Bit	**Read/Write**	**Default/Hex**	**Description**
27	/	/	/
26	R/W	0x0	DMA14_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 14 0: Disabled 1: Enabled
25	R/W	0x0	DMA14_PKG_IRQ_EN Enable the package end interrupt of DMA channel 14 0: Disabled 1: Enabled
24	R/W	0x0	DMA14_HALF_IRQ_EN Enable the half package interrupt of DMA channel 14 0: Disabled 1: Enabled
23	/	/	/
22	R/W	0x0	DMA13_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 13 0: Disabled 1: Enabled
21	R/W	0x0	DMA13_PKG_IRQ_EN Enable the package end interrupt of DMA channel 13 0: Disabled 1: Enabled
20	R/W	0x0	DMA13_HALF_IRQ_EN Enable the half package interrupt of DMA channel 13 0: Disabled 1: Enabled
19	/	/	/
18	R/W	0x0	DMA12_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 12 0: Disabled 1: Enabled
17	R/W	0x0	DMA12_PKG_IRQ_EN Enable the package end interrupt of DMA channel 12 0: Disabled 1: Enabled

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Offset: 0x0004			Register Name: DMAC_IRQ_EN_REG1
Bit	**Read/Write**	**Default/Hex**	**Description**
16	R/W	0x0	DMA12_HALF_IRQ_EN Enable the half package interrupt of DMA channel 12 0: Disabled 1: Enabled
15	/	/	/
14	R/W	0x0	DMA11_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 11 0: Disabled 1: Enabled
13	R/W	0x0	DMA11_PKG_IRQ_EN Enable the package end interrupt of DMA channel 11 0: Disabled 1: Enabled
12	R/W	0x0	DMA11_HALF_IRQ_EN Enable the half package interrupt of DMA channel 11 0: Disabled 1: Enabled
11	/	/	/
10	R/W	0x0	DMA10_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 10 0: Disabled 1: Enabled
9	R/W	0x0	DMA10_PKG_IRQ_EN Enable the package end interrupt of DMA channel 10 0: Disabled 1: Enabled
8	R/W	0x0	DMA10_HALF_IRQ_EN Enable the half package interrupt of DMA channel 10 0: Disabled 1: Enabled
7	/	/	/
6	R/W	0x0	DMA9_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 9 0: Disabled 1: Enabled

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Offset: 0x0004			Register Name: DMAC_IRQ_EN_REG1
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R/W	0x0	DMA9_PKG_IRQ_EN Enable the package end interrupt of DMA channel 9 0: Disabled 1: Enabled
4	R/W	0x0	DMA9_HALF_IRQ_EN Enable the half package interrupt of DMA channel 9 0: Disabled 1: Enabled
3	/	/	/
2	R/W	0x0	DMA8_QUEUE_IRQ_EN Enable the queue end interrupt of DMA channel 8 0: Disabled 1: Enabled
1	R/W	0x0	DMA8_PKG_IRQ_EN Enable the package end interrupt of DMA channel 8 0: Disabled 1: Enabled
0	R/W	0x0	DMA8_HALF_IRQ_EN Enable the half package interrupt of DMA channel 8 0: Disabled 1: Enabled

3.9.6.3 0x0010 DMAC IRQ Pending Status Register 0 (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: DMAC_IRQ_PEND_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31	/	/	/
30	R/W1C	0x0	DMA7_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 7. Write 1 to clear the pending status. 0: No effect 1: Pending

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Offset: 0x0010			Register Name: DMAC_IRQ_PEND_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
29	R/W1C	0x0	DMA7_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 7. Write 1 to clear the pending status. 0: No effect 1: Pending
28	R/W1C	0x0	DMA7_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 7. Write 1 to clear the pending status. 0: No effect 1: Pending
27	/	/	/
26	R/W1C	0x0	DMA6_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 6. Write 1 to clear the pending status. 0: No effect 1: Pending
25	R/W1C	0x0	DMA6_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 6. Write 1 to clear the pending status. 0: No effect 1: Pending
24	R/W1C	0x0	DMA6_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 6. Write 1 to clear the pending status. 0: No effect 1: Pending
23	/	/	/
22	R/W1C	0x0	DMA5_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 5. Write 1 to clear the pending status. 0: No effect 1: Pending
21	R/W1C	0x0	DMA5_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 5. Write 1 to clear the pending status. 0: No effect 1: Pending

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Offset: 0x0010			Register Name: DMAC_IRQ_PEND_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
20	R/W1C	0x0	DMA5_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 5. Write 1 to clear the pending status. 0: No effect 1: Pending
19	/	/	/
18	R/W1C	0x0	DMA4_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 4. Write 1 to clear the pending status. 0: No effect 1: Pending
17	R/W1C	0x0	DMA4_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 4. Write 1 to clear the pending status. 0: No effect 1: Pending
16	R/W1C	0x0	DMA4_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 4. Write 1 to clear the pending status. 0: No effect 1: Pending
15	/	/	/
14	R/W1C	0x0	DMA3_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 3. Write 1 to clear the pending status. 0: No effect 1: Pending
13	R/W1C	0x0	DMA3_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 3. Write 1 to clear the pending status. 0: No effect 1: Pending
12	R/W1C	0x0	DMA3_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 3. Write 1 to clear the pending status. 0: No effect 1: Pending

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Offset: 0x0010			Register Name: DMAC_IRQ_PEND_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
11	/	/	/
10	R/W1C	0x0	DMA2_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 2. Write 1 to clear the pending status. 0: No effect 1: Pending
9	R/W1C	0x0	DMA2_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 2. Write 1 to clear the pending status. 0: No effect 1: Pending
8	R/W1C	0x0	DMA2_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 2. Write 1 to clear the pending status. 0: No effect 1: Pending
7	/	/	/
6	R/W1C	0x0	DMA1_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 1. Write 1 to clear the pending status. 0: No effect 1: Pending
5	R/W1C	0x0	DMA1_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 1. Write 1 to clear the pending status. 0: No effect 1: Pending
4	R/W1C	0x0	DMA1_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 1. Write 1 to clear the pending status. 0: No effect 1: Pending
3	/	/	/

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Offset: 0x0010			Register Name: DMAC_IRQ_PEND_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W1C	0x0	DMA0_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 0. Write 1 to clear the pending status. 0: No effect 1: Pending
1	R/W1C	0x0	DMA0_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 0. Write 1 to clear the pending status. 0: No effect 1: Pending
0	R/W1C	0x0	DMA0_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 0. Write 1 to clear the pending status. 0: No effect 1: Pending

3.9.6.4 0x0014 DMAC IRQ Pending Status Register 1 (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: DMAC_IRQ_PEND_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31	/	/	/
30	R/W1C	0x0	DMA15_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 15. Write 1 to clear the pending status. 0: No effect 1: Pending
29	R/W1C	0x0	DMA15_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 15. Write 1 to clear the pending status. 0: No effect 1: Pending
28	R/W1C	0x0	DMA15_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 15. Write 1 to clear the pending status. 0: No effect 1: Pending

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Offset: 0x0010			Register Name: DMAC_IRQ_PEND_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
27	/	/	/
26	R/W1C	0x0	DMA14_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 14. Write 1 to clear the pending status. 0: No effect 1: Pending
25	R/W1C	0x0	DMA14_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 14. Write 1 to clear the pending status. 0: No effect 1: Pending
24	R/W1C	0x0	DMA14_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 14. Write 1 to clear the pending status. 0: No effect 1: Pending
23	/	/	/
22	R/W1C	0x0	DMA13_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 13. Write 1 to clear the pending status. 0: No effect 1: Pending
21	R/W1C	0x0	DMA13_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 13. Write 1 to clear the pending status. 0: No effect 1: Pending.
20	R/W1C	0x0	DMA13_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 13. Write 1 to clear the pending status. 0: No effect 1: Pending
19	/	/	/

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Offset: 0x0010			Register Name: DMAC_IRQ_PEND_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
18	R/W1C	0x0	DMA12_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 12. Write 1 to clear the pending status. 0: No effect 1: Pending
17	R/W1C	0x0	DMA12_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 12. Write 1 to clear the pending status. 0: No effect 1: Pending
16	R/W1C	0x0	DMA12_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 12. Write 1 to clear the pending status. 0: No effect 1: Pending
15	/	/	/
14	R/W1C	0x0	DMA11_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 11. Write 1 to clear the pending status. 0: No effect 1: Pending
13	R/W1C	0x0	DMA11_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 11. Write 1 to clear the pending status. 0: No effect 1: Pending
12	R/W1C	0x0	DMA11_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 11. Write 1 to clear the pending status. 0: No effect 1: Pending
11	/	/	/
10	R/W1C	0x0	DMA10_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 10. Write 1 to clear the pending status. 0: No effect 1: Pending

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Offset: 0x0010			Register Name: DMAC_IRQ_PEND_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
9	R/W1C	0x0	DMA10_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 10. Write 1 to clear the pending status. 0: No effect 1: Pending
8	R/W1C	0x0	DMA10_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 10. Write 1 to clear the pending status. 0: No effect 1: Pending
7	/	/	/
6	R/W1C	0x0	DMA9_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 9. Write 1 to clear the pending status. 0: No effect 1: Pending
5	R/W1C	0x0	DMA9_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 9. Write 1 to clear the pending status. 0: No effect 1: Pending
4	R/W1C	0x0	DMA9_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 9. Write 1 to clear the pending status. 0: No effect 1: Pending
3	/	/	/
2	R/W1C	0x0	DMA8_QUEUE_IRQ_PEND The IRQ pending bit for the queue end interrupt of the DMA channel 8. Write 1 to clear the pending status. 0: No effect 1: Pending
1	R/W1C	0x0	DMA8_PKG_IRQ_PEND The IRQ pending bit for the package end interrupt of the DMA channel 8. Write 1 to clear the pending status. 0: No effect 1: Pending

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Offset: 0x0010			Register Name: DMAC_IRQ_PEND_REG0
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W1C	0x0	DMA8_HALF_IRQ_PEND The IRQ pending bit for the half package interrupt of the DMA channel 8. Write 1 to clear the pending status. 0: No effect 1: Pending

3.9.6.5 0x0028 DMAC Auto Gating Register (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: DMAC_AUTO_GATE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/
2	R/W	0x0	DMA_MCLK_CIRCUIT Auto gating bit of DMA MCLK interface circuit 0: Auto gating enabled 1: Auto gating disabled
1	R/W	0x0	DMA_COMMON_CIRCUIT Auto gating bit of DMA common circuit 0: Auto gating enabled 1: Auto gating disabled
0	R/W	0x0	DMA_CHAN_CIRCUIT Auto gating bit of DMA channel circuit 0: Auto gating enabled 1: Auto gating disabled

NOTE

When initializing the DMA Controller, the bit[2] should be set up.

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3.9.6.6 0x0030 DMAC Status Register (Default Value: 0x0000_0000)

Offset: 0x0030			Register Name: DMAC_STA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R	0x0	MBUS FIFO Status 0: Empty 1: Not Empty
30:16	/	/	/
15:0	R	0x0	DMA_STATUS DMA Channel[15:0] Status The meaning of each bit: 0: Idle 1: Busy

3.9.6.7 0x0100 + N*0x0040 DMAC Channel Enable Register N (Default Value: 0x0000_0000)

Offset: 0x0100 + N*0x0040 (N = 0 to 15)			Register Name: DMAC_EN_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	DMA_EN DMA Channel Enable 0: Disabled 1: Enabled

3.9.6.8 0x0104 + N*0x0040 DMAC Channel Pause Register N (Default Value: 0x0000_0000)

Offset: 0x0104 + N*0x0040 (N = 0 to 15)			Register Name: DMAC_PAU_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	DMA_PAUSE Pause the DMA Channel Transfer Data 0: Resume Transferring 1: Pause Transferring

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3.9.6.9 0x0108 + N*0x0040 DMAC Channel Descriptor Address Register N (Default Value: 0x0000_0000)

Offset: 0x0108 + N*0x0040 (N = 0 to 15)			Register Name: DMAC_DESC_ADDR_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	R/W	0x0	DMA_DESC_ADDR Lower 30 bits of DMA channel descriptor address The descriptor address must be word-aligned.
1:0	R/W	0x0	DMA_DESC_HIGH_ADDR Higher 2 bits of DMA channel descriptor high address The real address is as follows. DMA Channel Descriptor Address = {bit[1:0], bit[31:2], 2'b00}

3.9.6.10 0x010C + N*0x0040 DMAC Channel Configuration Register N (Default Value: 0x0000_0000)

Offset: 0x010C + N*0x0040 (N = 0 to 15)			Register Name: DMAC_CFG_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31	/	/	/
30	R	0x0	BMODE_SEL 0: Normal Mode 1: BMODE
29:27	/	/	/
26:25	R	0x0	DMA_DEST_DATA_WIDTH DMA Destination Data Width 00: 8-bit 01: 16-bit 10: 32-bit 11: 64-bit
24	R	0x0	DMA_ADDR_MODE DMA Destination Address Mode 0: Linear Mode 1: IO Mode

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Offset: 0x010C + N*0x0040 (N = 0 to 15)			Register Name: DMAC_CFG_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
23:22	R	0x0	DMA_DEST_BLOCK_SIZE DMA Destination Block Size 00: 1 01: 4 10: 8 11: 16
21:16	R	0x0	DMA_DEST_DRQ_TYPE DMA Destination DRQ Type The details in DRQ Type and Port Corresponding Relation.
15:11	/	/	/
10:9	R	0x0	DMA_SRC_DATA_WIDTH DMA Source Data Width 00: 8-bit 01: 16-bit 10: 32-bit 11: 64-bit
8	R	0x0	DMA_SRC_ADDR_MODE DMA Source Address Mode 0: Linear Mode 1: IO Mode
7:6	R	0x0	DMA_SRC_BLOCK_SIZE DMA Source Block Size 00: 1 01: 4 10: 8 11: 16
5:0	R	0x0	DMA_SRC_DRQ_TYPE DMA Source DRQ Type The details in DRQ Type and Port Corresponding Relation.

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3.9.6.11 0x0110 + N*0x0040 DMAC Channel Current Source Address Register N (Default Value: 0x0000_0000)

Offset: 0x0110 + N*0x0040 (N = 0 to 15)			Register Name: DMAC_CUR_SRC_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	DMA_CUR_SRC DMA Channel Current Source Address.

3.9.6.12 0x0114 + N*0x0040 DMAC Channel Current Destination Address Register N (Default Value: 0x0000_0000)

Offset: 0x0114 + N*0x0040 (N = 0 to 15)			Register Name: DMAC_CUR_DEST_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	DMA_CUR_DEST DMA Channel Current Destination Address.

3.9.6.13 0x0118 + N*0x0040 DMAC Channel Byte Counter Left Register N (Default Value: 0x0000_0000)

Offset: 0x0118 + N*0x0040 (N = 0 to 15)			Register Name: DMAC_BCNT_LEFT_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24:0	R	0x0	DMA_BCNT_LEFT DMA Channel Byte Counter Left.

3.9.6.14 0x011C + N*0x0040 DMAC Channel Parameter Register N (Default Value: 0x0000_0000)

Offset: 0x011C + N*0x0040 (N = 0 to 15)			Register Name: DMAC_PARA_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R	0x0	WAIT_CYC Wait Clock Cycles

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3.9.6.15 0x0128 + N*0x0040 DMAC Mode Register N (Default Value: 0x0000_0000)

Offset: 0x0128 + N*0x0040 (N = 0 to 15)			Register Name: DMAC_MODE_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3	R/W	0x0	DMA_DST_MODE Destination Communication Mode Select 0: Waiting mode 1: Handshake mode
2	R/W	0x0	DMA_SRC_MODE Source Communication Mode Select 0: Waiting mode 1: Handshake mode
1:0	/	/	/

3.9.6.16 0x012C + N*0x0040 DMAC Former Descriptor Address Register N (Default Value: 0x0000_0000)

Offset: 0x012C + N*0x0040 (N = 0 to 15)			Register Name: DMAC_FDESC_ADDR_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	DMA_FDESC_ADDR This register is used to store the former value of DMA Channel Descriptor Address Register.

3.9.6.17 0x0130 + N*0x0040 DMAC Package Number Register N (Default Value: 0x0000_0000)

Offset: 0x0130 + N*0x0040 (N = 0 to 15)			Register Name: DMAC_PKG_NUM_REGN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	DMA_PKG_NUM This register records the number of packages which has been completed in one transmission.

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3.10 Thermal Sensor Controller (THS)

3.10.1 Overview

The thermal sensors are common elements in wide range of modern system on chips (SoCs) platform. The thermal sensors are used to constantly monitor the temperature on the chip.

The thermal sensor controller (THS) embeds one thermal sensor located in the CPU. When the temperature reaches a certain thermal threshold, the thermal sensor can generate interrupts to the software to lower the temperature via the dynamic voltage and frequency scaling (DVFS) technology.

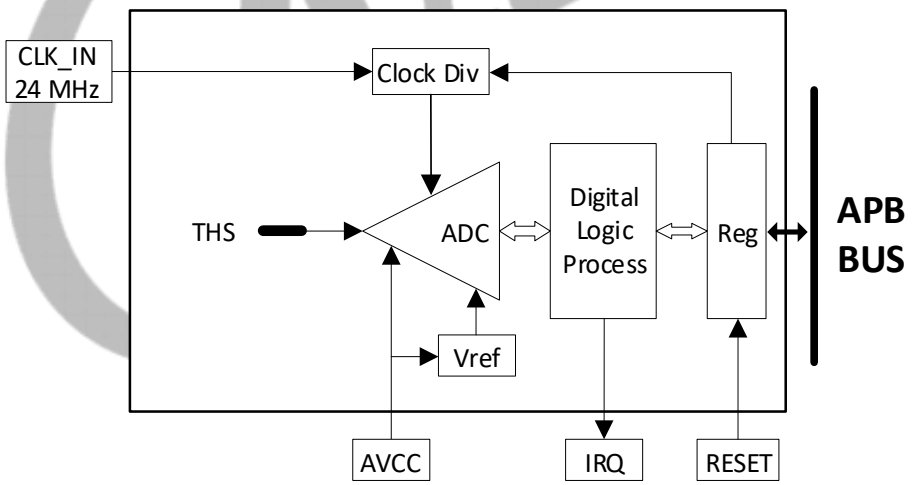
The THS has the following features:

- Temperature accuracy: ±3°C from 0°C to +100°C, ±5°C from -25°C to +125°C
- Averaging filter for thermal sensor reading
- Supports over-temperature protection interrupt and over-temperature alarm interrupt

3.10.2 Block Diagram

The following figure shows a block diagram of the THS.

Figure 3-25 THS Block Diagram



3.10.3 Functional Description

3.10.3.1 Clock Source

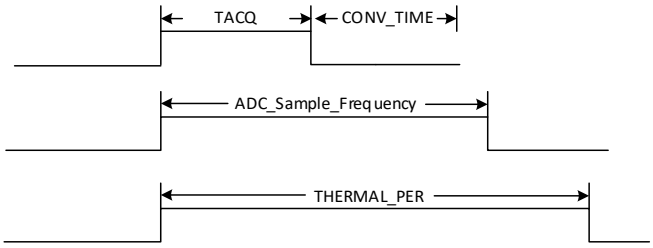
The THS gets one clock source: OSC24M. For details about clock configurations, refer to section 3.3 “CCU”.

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3.10.3.2 Timing Requirements

The following figure shows the timing requirements for the THS.

Figure 3-26 Thermal Sensor Timing Requirement



CLK_IN = 24 MHz

CONV_TIME (Conversion Time) = 1/24 MHz x 14 Cycles = 0.583 us

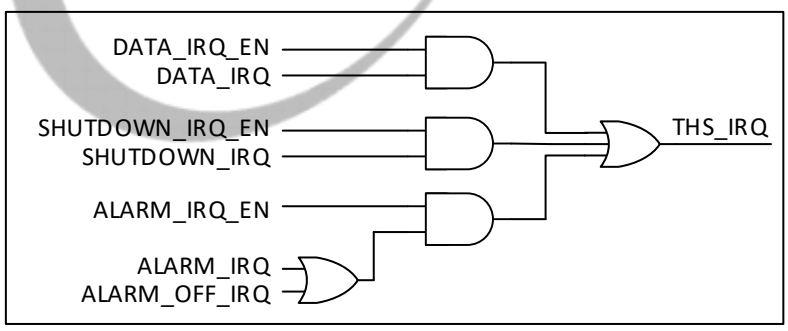
TACQ > 1/24 MHz x 24 Cycles

THERMAL_PER > ADC_Sample_Frequency > TACQ + CONV_TIME

3.10.3.3 Interrupts

The THS has four interrupt sources: DATA_IRQ, SHUTDOWN_IRQ, ALARM_IRQ, and ALARM_OFF_IRQ. The following figure shows thermal sensor interrupt sources.

Figure 3-27 Thermal Sensor Controller Interrupt Source



DATA_IRQ: The interrupt is generated when the measured sensor_data is updated.

SHUTDOWN_IRQ: The interrupt is generated when the temperature is higher than the shutdown threshold.

ALARM_IRQ: The interrupt is generated when the temperature is higher than the Alarm_Threshold.

ALARM_OFF_IRQ: The interrupt is generated when the temperature drops to lower than the Alarm_Off_Thershold. It is triggered at the fall edge.

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3.10.3.4 THS Temperature Conversion Formula

T = (sensor_data - 2800)/(-14.85)

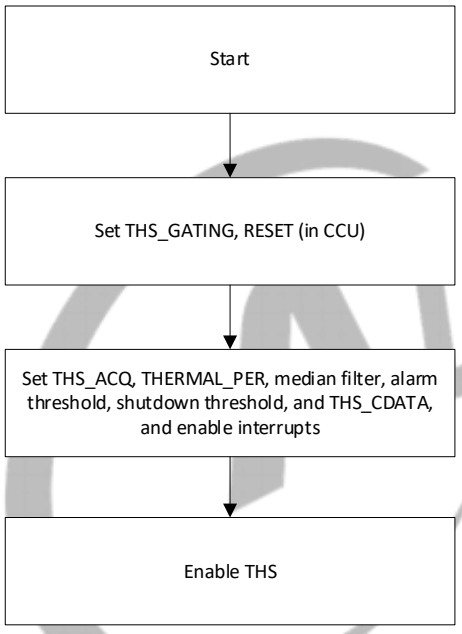
Unit of T: Celsius degree (°C).

The sensor_data is read from the sensor data register.

3.10.4 Programming Guidelines

The initial process of the THS is as follows.

Figure 3-28 THS Initial Process



In the final test (FT) stage, the THS is calibrated through the ambient temperature, and the calibration value is written in the SID module. The following table shows the THS information in the SID.

Table 3-16 THS Information in the SID

Base Address: 0x14	Register Name: THS
Bit	**Description**
27:16	The calibration value of the T-sensor.

Before enabling THS, read eFuse value and write the value to THS_CDATA.

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Query Mode

Step 1 Write 0x1 to the bit[16] of **THS_BGR_REG** to dessert the reset.

Step 2 Write 0x1 to the bit[0] of **THS_BGR_REG** to open the THS clock.

Step 3 Write 0x2F to the bit[15:0] of **THS_CTRL** to set the ADC acquire time.

Step 4 Write 0x1DF to the bit[31:16] of **THS_CTRL** to set the ADC sample frequency divider.

Step 5 Write 0x3A to the bit[31:12] of **THS_PER** to set the THS work period.

Step 6 Write 0x1 to the bit[2] of **THS_FILTER** to enable the temperature convert filter.

Step 7 Write 0x1 to the bit[1:0] of **THS_FILTER** to select the filter type.

Step 8 Read THS eFuse value from SID, then write the eFuse value to **THS_CDATA** to calibrate THS.

Step 9 Write 0x1 to the bit[0] 0f THS0_EN to enable THS.

Step 10 Read the bit[0] of **THS_DATA_INTS**. If it is 1, the temperature conversion is complete.

Step 11 Read the bit[11:0] of **THS_DATA**, and calculate the THS temperature based on section 3.10.3.4 "THS Temperature Conversion Formula".

Interrupt Mode

Step 1 Write 0x1 to the bit16 of **THS_BGR_REG** to dessert the reset.

Step 2 Write 0x1 to the bit0 of **THS_BGR_REG** to open the THS clock.

Step 3 Write 0x2F to the bit[15:0] of **THS_CTRL** to set the ADC acquire time.

Step 4 Write 0x1DF to the bit[31:16] of **THS_CTRL** to set the ADC sample frequency divider.

Step 5 Write 0x3A to the bit[31:12] of **THS_PER** to set the THS work period.

Step 6 Write 0x1 to the bit2 of **THS_FILTER** to enable the temperature convert filter.

Step 7 Write 0x1 to the bit[1:0] of **THS_FILTER** to select the filter type.

Step 8 Read THS eFuse value from SID, and then write the eFuse value to **THS_CDATA** to calibrate THS.

Step 9 Write 0x1 to the bit[0] of **THS_DATA_INTC** to enable the interrupt of THS.

Step 10 Set GIC interface based on IRQ 90.

Step 11 Put the interrupt handler address into the interrupt vector table.

Step 12 Write 0x1 to the bit[0] 0f THS0_EN to enable THS.

Step 13 Read the bit[0] of **THS_DATA_INTS**. If it is 1, the temperature conversion is complete.

Step 14 Read the bit[11:0] of **THS_DATA**, and calculate the THS temperature based on section 3.10.3.4 "THS Temperature Conversion Formula".

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3.10.5 Register List

Module Name	Base Address
THS	0x02009400

Register Name	Offset	Description
THS_CTRL	0x0000	THS Control Register
THS_EN	0x0004	THS Enable Register
THS_PER	0x0008	THS Period Control Register
THS_DATA_INTC	0x0010	THS Data Interrupt Control Register
THS_SHUT_INTC	0x0014	THS Shut Interrupt Control Register
THS_ALARM_INTC	0x0018	THS Alarm Interrupt Control Register
THS_DATA_INTS	0x0020	THS Data Interrupt Status Register
THS_SHUT_INTS	0x0024	THS Shut Interrupt Status Register
THS_ALARMO_INTS	0x0028	THS Alarm off Interrupt Status Register
THS_ALARM_INTS	0x002C	THS Alarm Interrupt Status Register
THS_FILTER	0x0030	THS Median Filter Control Register
THS_ALARM_CTRL	0x0040	THS Alarm Threshold Control Register
THS_SHUTDOWN_CTRL	0x0080	THS Shutdown Threshold Control Register
THS_CDATA	0x00A0	THS Calibration Data
THS_DATA	0x00C0	THS Data Register

3.10.6 Register Description

3.10.6.1 0x0000 THS Control Register (Default Value: 0x01DF_002F)

Offset: 0x0000			Register Name: THS_CTRL
Bit	Read/Write	Default/Hex	Description
31:16	R/W	0x1DF	TACQ ADC acquire time CLK_IN/(n + 1) The default value is 2 us.
15:0	R/W	0x2F	Reserved

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3.10.6.2 0x0004 THS Enable Register (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: THS_EN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	THS_EN Enable temperature measurement sensor 0: Disable 1: Enable

3.10.6.3 0x0008 THS Period Control Register (Default Value: 0x0003_A000)

Offset: 0x0008			Register Name: THS_PER
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	R/W	0x3A	THERMAL_PER Temperature measurement period 4096*(n + 1)/CLK_IN The default value is 10 ms.
11:0	/	/	/

3.10.6.4 0x0010 THS Data Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: THS_DATA_INTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	THS_DATA_IRQ_EN Enable the interrupt of sensor_data update If enabled, when the measured sensor_data is updated, it will generate an interrupt. 0: Disabled 1: Enabled

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3.10.6.5 0x0014 THS Shut Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0014			Register Name: THS_SHUT_INTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	SHUT_INT_EN Enable the shutdown interrupt for the sensor 0: Disabled 1: Enabled

3.10.6.6 0x0018 THS Alarm Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: THS_ALARM_INTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	ALARM_INT_EN Enable the alarm interrupt for the sensor 0: Disabled 1: Enabled

3.10.6.7 0x0020 THS Data Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: THS_DATA_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W1C	0x0	THS_DATA_IRQ_STS Indicates the pending status of the sensor's data interrupt. Write 1 to clear the pending status. 0: No effect 1: Pending

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3.10.6.8 0x0024 THS Shut Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: THS_SHUT_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W1C	0x0	SHUT_INT_STS Indicates the pending status of the sensor's shutdown interrupt. Write 1 to clear the pending status. 0: No effect 1: Pending

3.10.6.9 0x0028 THS Alarm Off Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: THS_ALARM_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W1C	0x0	ALARM_OFF_STS Alarm interrupt off pending for sensor Write 1 to clear the pending status. 0: No effect 1: Pending

3.10.6.10 0x002C THS Alarm Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x002C			Register Name: THS_ALARM_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W1C	0x0	ALARM_INT_STS Alarm interrupt pending for sensor Write 1 to clear the pending status. 0: No effect 1: Pending

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3.10.6.11 0x0030 Median Filter Control Register (Default Value: 0x0000_0001)

Offset: 0x0030			Register Name: THS_FILTER
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/
2	R/W	0x0	FILTER_EN Filter enable 0: Disabled 1: Enabled
1:0	R/W	0x1	FILTER_TYPE Averaging filter type 00: 2 01: 4 10: 8 11: 16

3.10.6.12 0x0040 THS Alarm Threshold Control Register (Default Value: 0x05A0_0684)

Offset: 0x0040			Register Name: THS_ALARM_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/
27:16	R/W	0x5A0	ALARM_T_HOT Thermal sensor alarm threshold for hot temperature
15:12	/	/	/
11:0	R/W	0x684	ALARM_T_HYST Thermal sensor alarm threshold for hysteresis temperature

3.10.6.13 0x0080 THS Shutdown Threshold Control Register (Default Value: 0x0000_04E9)

Offset: 0x0080			Register Name: THS_SHUTDOWN_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/
11:0	R/W	0x4E9	SHUT_T_HOT Thermal sensor shutdown threshold for hot temperature

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3.10.6.14 0x00A0 THS Calibration Data Register (Default Value: 0x0000_0800)

Offset: 0x00A0			Register Name: THS_CDATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:0	R/W	0x800	THS_CDATA Thermal sensor calibration data

3.10.6.15 0x00C0 THS Data Register (Default Value: 0x0000_0000)

Offset: 0x00C0			Register Name: THS_DATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:0	R	0x0	THS_DATA Temperature measurement data of sensor

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3.11 IOMMU

3.11.1 Overview

The I/O Memory management unit (IOMMU) is designed for product specific memory requirements. It maps the virtual address (sent by peripheral access memory) to the physical address. The IOMMU allows multiple ways to manage the location of physical address, and it can use physical address which has potentially conflict mapping for different processes to allocate memory space, and also allow application of non-continuous address mapping to continuous virtual address space.

Features:

- Supports virtual address to physical address mapping by hardware implementation
- Supports VE, CSI, DE, G2D, DI parallel address mapping
- Supports VE, CSI, DE, G2D, DI bypass function independently
- Supports VE, CSI, DE, G2D, DI pre-fetch independently
- Supports VE, CSI, DE, G2D, DI interrupt handing mechanism independently
- Supports 2 levels TLB (level1 TLB for special using, and level2 TLB for sharing)
- Supports TLB Fully cleared and Partially disabled
- Supports trigger PTW behavior when TLB miss
- Supports checking the permission

3.11.2 Block Diagram

The internal module of IOMMU mainly has the following parts.

Micro TLB: level1 TLB, 64 words. Each peripheral corresponds to a TLB, which caching the level2 page table for the peripheral.

Macro TLB: level2 TLB, 4K words. Each peripheral shares a level2 TLB for caching the level2 page table.

Prefetch Logic: Each Micro TLB corresponds to a Prefetch Logic. By monitoring each master device to predict the bus access, the secondary page table corresponding to the address to be accessed can be read from memory and stored in the secondary TLB to improve hit ratio.

PTW Logic: Page Table Walk, mainly contains PTW Cache and PTW. The PTW Cache is used to store the level1 page table; when the virtual address VA missed in the level1 and level2 TLB, it will trigger the PTW. PTW Cache can store 512 level1 page tables, that is, 512 words.

PMU: Performance Monitoring Unit, which is used to count hit efficiency and latency.

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APB Interface: IOMMU register instantiation module. CPU reads and writes the IOMMU register by APB bus.

The following figure shows the internal block diagram of IOMMU.

Figure 3-29 IOMMU Block Diagram

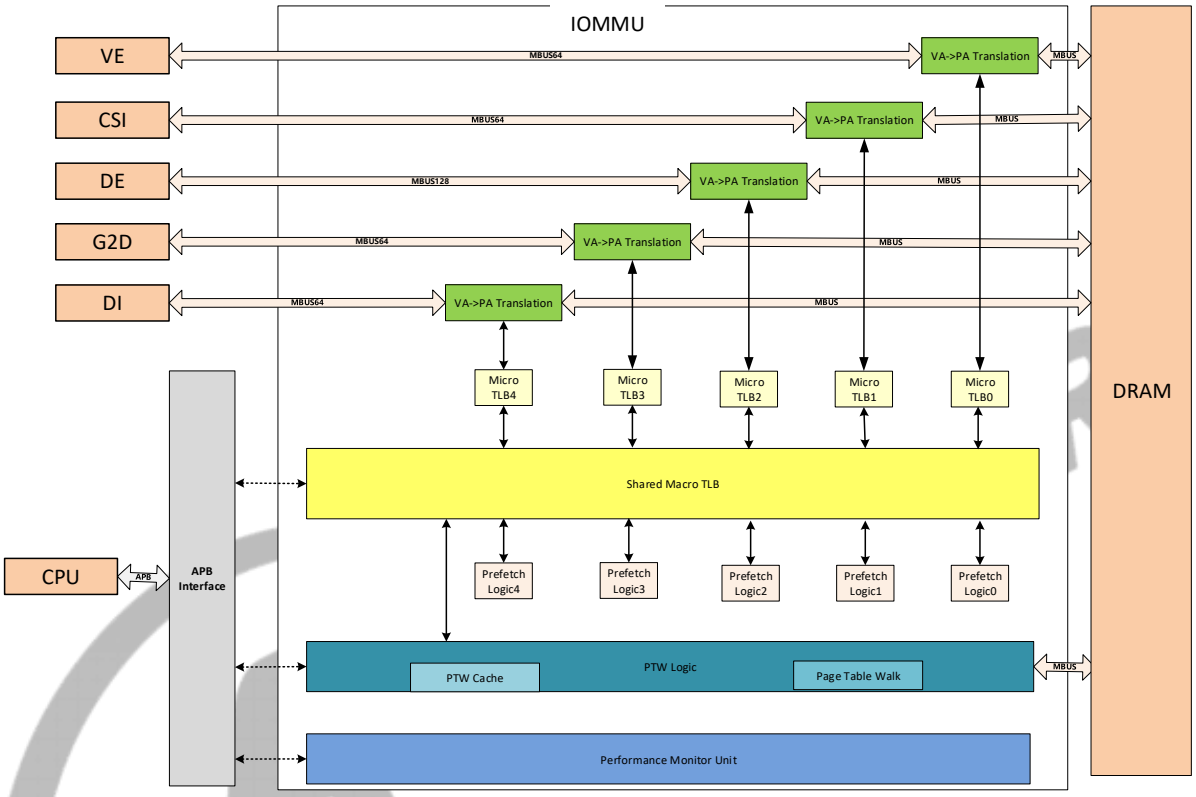


Table 3-17 Correspondence Relation between Master and Module

Master Number	Module
Master0	VE
Master1	CSI
Master2	DE
Master3	G2D
Master4	DI

3.11.3 Functional Description

3.11.3.1 Initialization

- Release the IOMMU reset signal by writing 1 to the bit[31] of the ***IOMMU Reset Register***;

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- Write the base address of the first TLB to the ***IOMMU Translation Table Base Register***;
- Set the ***IOMMU Interrupt Enable Register***;
- Enable the IOMMU by configuring the ***IOMMU Enable Register*** in the final.

3.11.3.2 Address Changing

In the process of address mapping, The peripheral virtual address VA[31:12] are retrieved in the Level1 TLB, when TLB hits, the mapping finished, or they are retrieved in the Level2 TLB in the same way. If TLB hits, it will write the hit mapping to the Level1 TLB, and hits in Level1 TLB. If Level1 and Level2 TLB are retrieved fail, it will trigger the PTW. After opening peripheral bypass function by setting IOMMU Bypass Register, IOMMU will not map the address for peripheral typed the address, and it will output the virtual address as physical address. The typical scenarios are as follows.

Micro TLB hit

Step 1 The master device sends a transfer command to send the address to the corresponding Micro TLB, and searches the Level2 page table corresponding to virtual address;

Step 2 If Micro TLB hits, it will return a corresponding physical addresses and the Level2 page table of permission Index;

Step 3 Address transform module converts the virtual address into physical address, and checks the permissions at the same time. If pass, the transfer is completed.

Micro TLB miss, Macro TLB hit

Step 1 The master device sends a transfer command to send the address to the corresponding Micro TLB, and searches the Level2 page table corresponding to virtual address;

Step 2 If Micro TLB misses, then continue to search Macro TLB;

Step 3 If Macro TLB hits, it will return the Level2 page table to Micro TLB;

Step 4 Micro TLB receives the page table and puts it to Micro TLB (if this Micro TLB is full, there will happen the replace activity), at the same time, the page table entry is sent to address translation module;

Step 5 Address transform module converts the virtual address into physical address, and checks the permissions at the same time. If pass, the transfer is completed.

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Micro TLB miss, Macro TLB miss, PTW Cache hit

Step 1 The master device sends a transfer command to send the address to the corresponding Micro TLB, and searches the Level2 page table corresponding to virtual address;

Step 2 If Micro TLB misses, then continue to search Macro TLB;

Step 3 If Macro TLB misses, then it will send the request to the PTW to return the corresponding page table;

Step 4 PTW first accesses PTW Cache, confirms that the required Level1 page table exists in the PTW Cache, sends the page table to PTW logic;

Step 5 PTW logic returns the corresponding Level2 page table from memory page table according to Level1 page table, checks the effectiveness, and sends to Macro TLB;

Step 6 Macro TLB stores the Level2 page table (there may happen the replace activity), and will return the Level2 page table to Micro TLB;

Step 7 Micro TLB receives the page table entries and puts it to the Micro TLB (if this Micro TLB is full, there will happen the replace activity), and sends page table entries to address translation module;

Step 8 Address transform module converts the virtual address into physical address, and checks the permissions at the same time. If pass, the transfer is completed.

Micro TLB miss, Macro TLB miss, PTW Cache miss

Step 1 The master device sends a transfer command to send the address to the corresponding Micro TLB, and searches the Level2 page table corresponding to virtual address;

Step 2 If Micro TLB misses, then continue to search Macro TLB;

Step 3 If Macro TLB misses, there will send the request to the PTW to return the corresponding page table;

Step 4 PTW accesses PTW Cache, the Level1 page table is unnecessary;

Step 5 PTW accesses memory to get the corresponding Level1 page table and stores it to the PTW Cache (there may happen the replace activity);

Step 6 PTW logic returns the corresponding Level2 page table from memory page table according to Level1 page table, checks the effectiveness, and sends to Macro TLB;

Step 7 Macro TLB stores the Level2 page table (there may happen the replace activity), and returns the Level 2 page table to Micro TLB;

Step 8 Micro TLB receives the page table entries and puts it to the Micro TLB (if this Micro TLB is full, there will happen the replace activity), and sends page table entries to address translation module;

Step 9 Address transform module converts the virtual address into physical address, and checks the permissions at the same time. If pass, the transfer is completed.

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Permission error

Step 1 Permission checking always performs in the address conversion;

Step 2 Once the permission checking makes mistake, the new access of the master suspends, but continues before this access;

Step 3 Set the error status register;

Step 4 Trigger interrupt.

Invalid Level1 page table

Step 1 Invalid Level1 page table is checked when PTW logic reads the new level page table from memory;

Step 2 The PTW reads sequentially two page table entries from the memory (64-bit data, a complete cache line), and stores in the PTW cache;

Step 3 If the current page table is detected invalid, then the error flag is set, and the interrupt is triggered, the cache line need to be invalidated.

NOTE

- Invalid page table has two situations: the reading target page table from the memory is invalid; and the page table stored in PTW Cache with target page table is found to be invalid after using;
- If a page table is invalid, then the total cache line (that is two page tables) need to be invalidated.

Invalid Level2 page table

Step 1 Invalid Level2 page table checks when Macro TLB reads the new level page table from memory;

Step 2 The Macro TLB reads sequentially two page table entries from the memory (64-bit data, a complete cache line), and stores in the Macro TLB;

Step 3 If the current page table is detected invalid, then the error flag is set, and the interrupt is triggered, the cache line need to be invalidated.

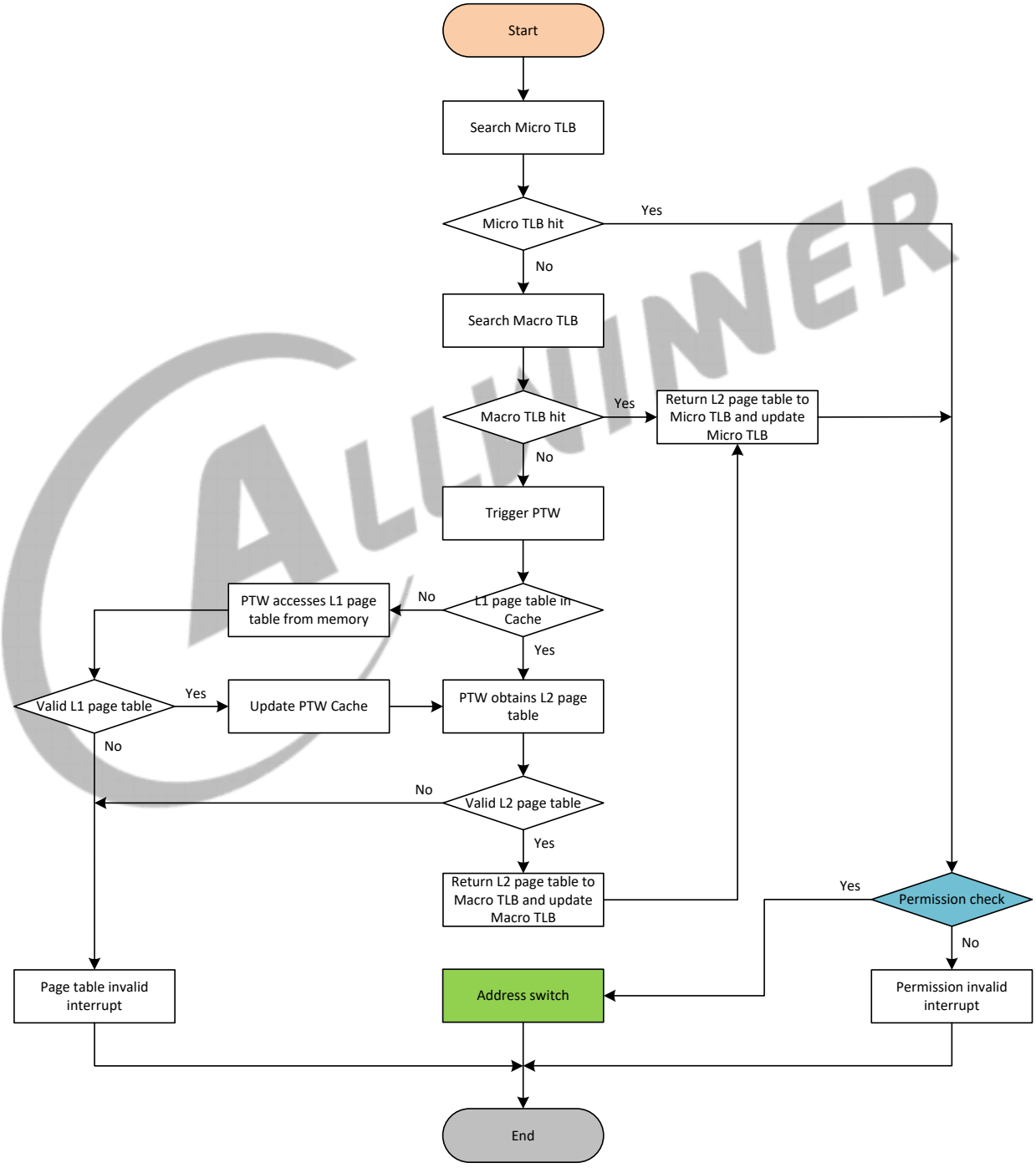
NOTE

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- Invalid page table has two situations: the reading target page table from the memory is invalid; and the page table stored in Macro TLB with target page table is found to be invalid after using.
- If a page table is invalid, then the total cache line (that is two page tables) need to be invalidated.

The internal address switch process shows in the following figure.

Figure 3-30 Internal Switch Process



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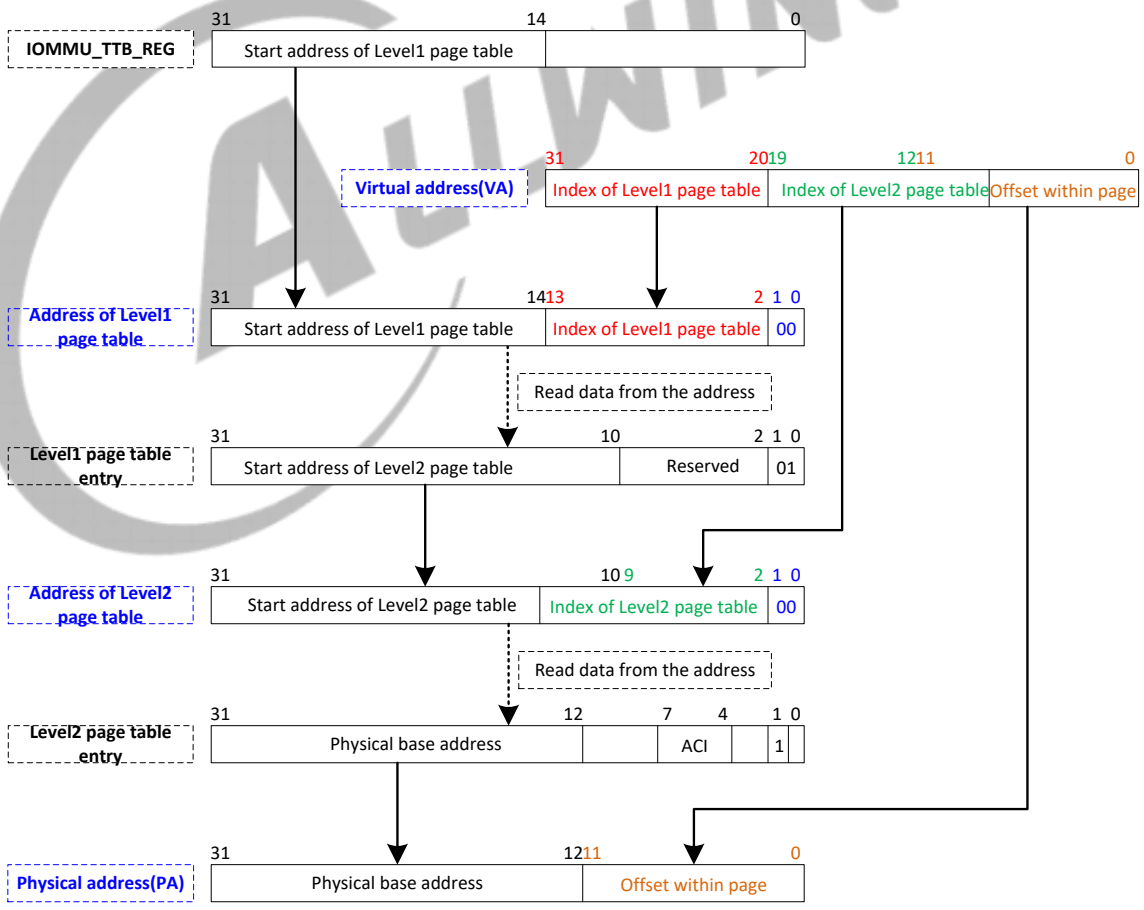
3.11.3.3 VA-PA Mapping

IOMMU page table is defined as Level2 mapping, the first level is 1M address space mapping, the second level is 4K address space. This version does not support 1K, 16K and other page table size. IOMMU supports a page table only, its meaning is:

- All peripherals connected to IOMMU use the same virtual address space;
- The virtual address space of the peripherals can overlap;
- Different virtual addresses can map to the same physical address space;

Base address of the page table is defined by software, and it needs 16 KB address alignment; Page table of the Level2 table item needs 1 KB address alignment. The following figure shows a complete VA-PA address translation process.

Figure 3-31 VA-PA Switch Process



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3.11.3.4 Clear and Invalidate TLB

When the content of multi page tables refreshes or the address of page table changes, all VA-PA mapping which has been cached in TLB will no longer be valid, then you need configure **IOMMU TLB Flush Enable Register** to clear the TLB or PTW Cache. First suspend the access to TLB or Cache, then configure the corresponding Flush bit of **IOMMU TLB Flush Enable Register**, after the operation takes effect, the related peripherals can continue to send new access memory operations.

When some page table is invalid or incorrect mapping, you can set the TLB Invalidation relevant register to invalidate some TLB VA-PA mapping pairs. There are two modes to invalidate the TLB operation.

(1) Mode0 (Old mode)

Step 1 Set **IOMMU TLB Invalidation Mode Select Register** to 0 to select mode0;

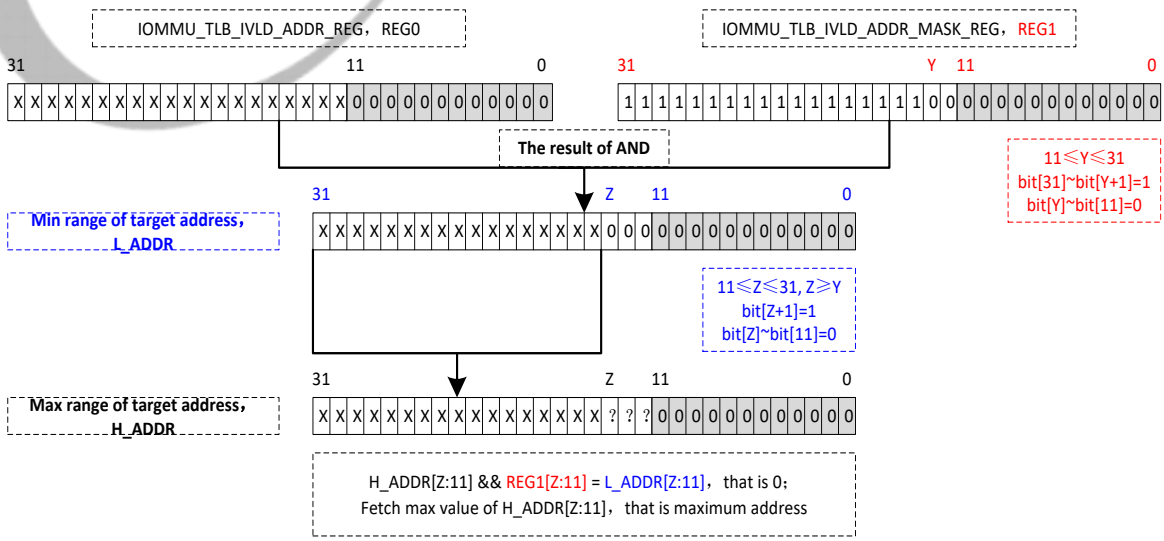
Step 2 Write target address to **IOMMU TLB Invalidation Address Register**;

Step 3 Set configuration values to **IOMMU TLB Invalidation Address Mask Register**, the requirements are as follows:

- The value of **IOMMU TLB Invalidation Address Mask Register** cannot be less than the **IOMMU TLB Invalidation Address Register**.
- The higher bit of **IOMMU TLB Invalidation Address Mask Register** must be continuous 1, the lower bit must be continuous 0. For example, 0xfffff000, 0xffffe000, 0xffffc000, 0xffff8000, 0xffff0000 belongs to the legal value; and 0xffffd000, 0xffffb000, 0xffffa000, 0xffff9000, 0xffff7000 belongs to the illegal values.

Step 4 Configure **IOMMU TLB Invalidation Enable Register** to enable the invalid operation. Among the way to determine the invalid address is to get maximum valid bit and determine target address range by target address AND mask address. The following figure shows this process.

Figure 3-32 Invalid TLB Address Range



For example:

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a) When the value of **IOMMU TLB Invalidation Address Mask Register** is 0xFFFFF000 by default, the result of AND is target address, that is, only target address is invalid.

b) When the value of **IOMMU TLB Invalidation Address Mask Register** is 0xFFFF0000, the value of **IOMMU TLB Invalidation Address Register** is 0xEEEE1000, then the range of target address is from 0xEEEE0000 to 0xEEEEF000.

c) When the value of **IOMMU TLB Invalidation Address Mask Register** is 0xFFFFC000, the value of **IOMMU TLB Invalidation Address Register** is 0xEEEE8000, then the range of target address is from 0xEEEE8000 to 0xEEEEB000.

d) When the value of **IOMMU TLB Invalidation Address Mask Register** is 0xFFFF8000, the value of **IOMMU TLB Invalidation Address Register** is 0xEEEEC000, then the range of target address is from 0xEEEE8000 to 0xEEEEF000.

e) When the value of **IOMMU TLB Invalidation Address Mask Register** is 0xFFFFC000, the value of **IOMMU TLB Invalidation Address Register** is 0xEEEE0000, then the range of target address is from 0xEEEE0000 to 0xEEEE3000.

(2) Mode1 (New mode)

Step 1 Set **IOMMU TLB Invalidation Mode Select Register** to 1 to select mode1;

Step 2 Set the starting address of invalid TLB by **IOMMU TLB Invalidation Start Address Register,** and set the ending address of invalid TLB by **IOMMU TLB Invalidation Start Address Register;**

Step 3 Configure **IOMMU TLB Invalidation Enable Register** to enable invalid operation, then the related TLB operation is invalidated.

3.11.3.5 Clear and Invalidate PTW Cache

There are two modes to invalidate the PTW cache operation.

(1) Mode0 (Old mode)

Step 1 Set **IOMMU PC Invalidation Mode Select Register** to 0 to select mode0;

Step 2 Set the address register that needs to be invalidated to **IOMMU PC Invalidation Address Register** (the addresses need to be aligned with 1 MB);

Step 3 Configure **IOMMU PC Invalidation Enable Register** to enable the invalid operation. That is, the PTW cache operation of a cacheline is invalidated.

(2) Mode1 (New mode)

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Step 1 Set **IOMMU PC Invalidation Mode Select Register** to 1 to select mode1;

Step 2 Set the starting address of invalid TLB by **IOMMU PTW Invalidation Start Address Register,** and set the ending address of invalid TLB by **IOMMU PC Invalidation Start Address Register;**

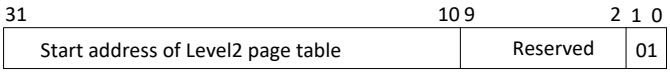
Step 3 Configure **IOMMU PC Invalidation Enable Register** to enable invalid operation, then to invalid the related PWM cache operation is completed.

3.11.3.6 Page Table Format

Level1 Page Table

The format of Level1 page table is as follows.

Figure 3-33 Level1 Page Table Format



Bit[31:10]: Base address of Level2 page table;

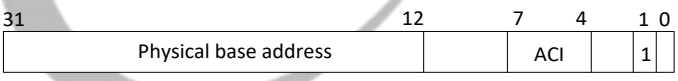
Bit[9:2]: Reserved;

Bit[1:0]: 01 is valid page table; others are fault;

Level2 Page Table

The format of Level2 page table is as follows.

Figure 3-34 Level1 Page Table Format



Bit[31:12]: Physical address of 4K address;

Bit[11:8]: Reserved;

Bit[7:4]: ACI, permission control index; correspond to permission control bit of **IOMMU Domain Authority Control Register**;

Bit[3:2]: Reserved;

Bit[1]: 1 is valid page table; 0 is fault;

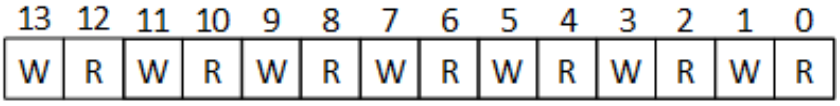
Bit[0]: Reserved

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Permission Index

The read/write access control of series register such as **IOMMU Domain Authority Control Register** is as follows.

Figure 3-35 Read/Write Permission Control



Bit[1:0]/Bit[17:16]: Master0 read/write permission control;

Bit[3:2]/Bit[19:18]: Master1 read/write permission control;

Bit[5:4]/Bit[21:20]: Master2 read/write permission control;

Bit[7:6]/Bit[23:22]: Master3 read/write permission control;

Bit[9:8]/Bit[25:24]: Master4 read/write permission control;

Bit[11:10]/Bit[27:26]: Master5 read/write permission control;

Bit[13:12]/Bit[29:28]: Master6 read/write permissiom control.

The value of **IOMMU Domain Authority Control Register** is read-only by default. Other registers can configure through system requirement. In address switch process, the corresponding relation between ACI and Domain is as follows.

Table 3-18 Relation between ACI and Domain

ACI	Domain	Register
0	Domain 0	IOMMU Domain Authority Control Register 0
1	Domain 1	IOMMU Domain Authority Control Register 0
2	Domain 2	IOMMU Domain Authority Control Register 1
3	Domain 3	IOMMU Domain Authority Control Register 1
4	Domain 4	IOMMU Domain Authority Control Register 2
5	Domain 5	IOMMU Domain Authority Control Register 2
6	Domain 6	IOMMU Domain Authority Control Register 3
7	Domain 7	IOMMU Domain Authority Control Register 3
8	Domain 8	IOMMU Domain Authority Control Register 4
9	Domain 9	IOMMU Domain Authority Control Register 4
10	Domain 10	IOMMU Domain Authority Control Register 5
11	Domain 11	IOMMU Domain Authority Control Register 5

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ACI	Domain	Register
12	Domain 12	IOMMU Domain Authority Control Register 6
13	Domain 13	IOMMU Domain Authority Control Register 6
14	Domain 14	IOMMU Domain Authority Control Register 7
15	Domain 15	IOMMU Domain Authority Control Register 7

After enabled **IOMMU Domain Authority Overwrite Register**, the read/write control permission can override all **IOMMU Domain Authority Control Register**.

3.11.4 Programming Guidelines

3.11.4.1 Resetting IOMMU

Before the IOMMU module software reset operation, make sure IOMMU is never opened, or all bus operations are completed, or DRAM and peripherals already open the corresponding switch, to shield the influence of IOMMU reset.

3.11.4.2 Enabling IOMMU

Before opening the IOMMU address mapping function, the **Translation Table Base Register** should be correctly configured, or all the masters are in the bypass state, or all the masters do not send the bus command.

3.11.4.3 Configuring TTB

Operating the register must close the address mapping function of IOMMU, that is, the IOMMU_ENABLE_REG[0] is 0; or the bypass function of all masters is set to 1; or the state of the TX bus command is none.

3.11.4.4 Clearing TTB

In the Flush operation, all TLB/Cache access will be suspended; but the operation entered the TLB will continue to complete before the Flush starts.

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3.11.4.5 Reading/Writing VA Data

For target virtual address, read and write the corresponding physical address data to make sure whether IOMMU module address mapping function is normal. First, make sure to read or write, and then configure the target virtual address or write data, then start to read or write function, check whether the results are as expected after the operation is finished.

3.11.4.6 Using PMU Statistics Function

When PMU function is used for the first time, set **IOMMU PMU Enable Register** to enable statistics function; when reading the relevant Register, clear the enable bit of **IOMMU PMU Enable Register**; when PMU function is used next time, first **IOMMU PMU Clear Register** is set, after counter is cleared, set the enable bit of **IOMMU PMU Enable Register**.

Given a Level2 page table administers continuous 4 KB address, if Micro TLB misses in continuous virtual address, there may need to return a Level2 page table to hit from Macro TLB; but the hit number is not recorded in the Macro TLB hit and Micro TLB hit related register. So the true hit rate calculation is as follows:

Hit Rate = N1/M1 + (1-N1/M1)*N2/M2

N1: Micro TLB hit number
M1: Micro TLB access number
N2: Macro TLB hit number
M2: Macro TLB access number

3.11.5 Register List

Module Name	Base Address
IOMMU	0x02010000

Register Name	Offset	Description
IOMMU_RESET_REG	0x0010	IOMMU Reset Register
IOMMU_ENABLE_REG	0x0020	IOMMU Enable Register
IOMMU_BYPASS_REG	0x0030	IOMMU Bypass Register
IOMMU_AUTO_GATING_REG	0x0040	IOMMU Auto Gating Register
IOMMU_WBUF_CTRL_REG	0x0044	IOMMU Write Buffer Control Register
IOMMU_OOO_CTRL_REG	0x0048	IOMMU Out of Order Control Register
IOMMU_4KB_BDY_PRT_CTRL_REG	0x004C	IOMMU 4KB Boundary Protect Control Register

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Register Name	Offset	Description
IOMMU_TTB_REG	0x0050	IOMMU Translation Table Base Register
IOMMU_TLB_ENABLE_REG	0x0060	IOMMU TLB Enable Register
IOMMU_TLB_PREFETCH_REG	0x0070	IOMMU TLB Prefetch Register
IOMMU_TLB_FLUSH_ENABLE_REG	0x0080	IOMMU TLB Flush Enable Register
IOMMU_TLB_IVLD_MODE_SEL_REG	0x0084	IOMMU TLB Invalidation Mode Select Register
IOMMU_TLB_IVLD_STA_ADDR_REG	0x0088	IOMMU TLB Invalidation Start Address Register
IOMMU_TLB_IVLD_END_ADDR_REG	0x008C	IOMMU TLB Invalidation End Address Register
IOMMU_TLB_IVLD_ADDR_REG	0x0090	IOMMU TLB Invalidation Address Register
IOMMU_TLB_IVLD_ADDR_MASK_REG	0x0094	IOMMU TLB Invalidation Address Mask Register
IOMMU_TLB_IVLD_ENABLE_REG	0x0098	IOMMU TLB Invalidation Enable Register
IOMMU_PC_IVLD_MODE_SEL_REG	0x009C	IOMMU PC Invalidation Mode Select Register
IOMMU_PC_IVLD_ADDR_REG	0x00A0	IOMMU PC Invalidation Address Register
IOMMU_PC_IVLD_STA_ADDR_REG	0x00A4	IOMMU PC Invalidation Start Address Register
IOMMU_PC_IVLD_ENABLE_REG	0x00A8	IOMMU PC Invalidation Enable Register
IOMMU_PC_IVLD_END_ADDR_REG	0x00AC	IOMMU PC Invalidation End Address Register
IOMMU_DM_AUT_CTRL0_REG	0x00B0	IOMMU Domain Authority Control 0 Register
IOMMU_DM_AUT_CTRL1_REG	0x00B4	IOMMU Domain Authority Control 1 Register
IOMMU_DM_AUT_CTRL2_REG	0x00B8	IOMMU Domain Authority Control 2 Register
IOMMU_DM_AUT_CTRL3_REG	0x00BC	IOMMU Domain Authority Control 3 Register
IOMMU_DM_AUT_CTRL4_REG	0x00C0	IOMMU Domain Authority Control 4 Register
IOMMU_DM_AUT_CTRL5_REG	0x00C4	IOMMU Domain Authority Control 5 Register
IOMMU_DM_AUT_CTRL6_REG	0x00C8	IOMMU Domain Authority Control 6 Register
IOMMU_DM_AUT_CTRL7_REG	0x00CC	IOMMU Domain Authority Control 7 Register
IOMMU_DM_AUT_OVWT_REG	0x00D0	IOMMU Domain Authority Overwrite Register
IOMMU_INT_ENABLE_REG	0x0100	IOMMU Interrupt Enable Register
IOMMU_INT_CLR_REG	0x0104	IOMMU Interrupt Clear Register
IOMMU_INT_STA_REG	0x0108	IOMMU Interrupt Status Register
IOMMU_INT_ERR_ADDR0_REG	0x0110	IOMMU Interrupt Error Address 0 Register
IOMMU_INT_ERR_ADDR1_REG	0x0114	IOMMU Interrupt Error Address 1 Register
IOMMU_INT_ERR_ADDR2_REG	0x0118	IOMMU Interrupt Error Address 2 Register
IOMMU_INT_ERR_ADDR3_REG	0x011C	IOMMU Interrupt Error Address 3 Register
IOMMU_INT_ERR_ADDR4_REG	0x0120	IOMMU Interrupt Error Address 4 Register
IOMMU_INT_ERR_ADDR5_REG	0x0124	IOMMU Interrupt Error Address 5 Register
IOMMU_INT_ERR_ADDR6_REG	0x0128	IOMMU Interrupt Error Address 6 Register

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Register Name	Offset	Description
IOMMU_INT_ERR_ADDR7_REG	0x0130	IOMMU Interrupt Error Address 7 Register
IOMMU_INT_ERR_ADDR8_REG	0x0134	IOMMU Interrupt Error Address 8 Register
IOMMU_INT_ERR_DATA0_REG	0x0150	IOMMU Interrupt Error Data 0 Register
IOMMU_INT_ERR_DATA1_REG	0x0154	IOMMU Interrupt Error Data 1 Register
IOMMU_INT_ERR_DATA2_REG	0x0158	IOMMU Interrupt Error Data 2 Register
IOMMU_INT_ERR_DATA3_REG	0x015C	IOMMU Interrupt Error Data 3 Register
IOMMU_INT_ERR_DATA4_REG	0x0160	IOMMU Interrupt Error Data 4 Register
IOMMU_INT_ERR_DATA5_REG	0x0164	IOMMU Interrupt Error Data 5 Register
IOMMU_INT_ERR_DATA6_REG	0x0168	IOMMU Interrupt Error Data 6 Register
IOMMU_INT_ERR_DATA7_REG	0x0170	IOMMU Interrupt Error Data 7 Register
IOMMU_INT_ERR_DATA8_REG	0x0174	IOMMU Interrupt Error Data 8 Register
IOMMU_L1PG_INT_REG	0x0180	IOMMU L1 Page Table Interrupt Register
IOMMU_L2PG_INT_REG	0x0184	IOMMU L2 Page Table Interrupt Register
IOMMU_VA_REG	0x0190	IOMMU Virtual Address Register
IOMMU_VA_DATA_REG	0x0194	IOMMU Virtual Address Data Register
IOMMU_VA_CONFIG_REG	0x0198	IOMMU Virtual Address Configuration Register
IOMMU_PMU_ENABLE_REG	0x0200	IOMMU PMU Enable Register
IOMMU_PMU_CLR_REG	0x0210	IOMMU PMU Clear Register
IOMMU_PMU_ACCESS_LOW0_REG	0x0230	IOMMU PMU Access Low 0 Register
IOMMU_PMU_ACCESS_HIGH0_REG	0x0234	IOMMU PMU Access High 0 Register
IOMMU_PMU_HIT_LOW0_REG	0x0238	IOMMU PMU Hit Low 0 Register
IOMMU_PMU_HIT_HIGH0_REG	0x023C	IOMMU PMU Hit High 0 Register
IOMMU_PMU_ACCESS_LOW1_REG	0x0240	IOMMU PMU Access Low 1 Register
IOMMU_PMU_ACCESS_HIGH1_REG	0x0244	IOMMU PMU Access High 1 Register
IOMMU_PMU_HIT_LOW1_REG	0x0248	IOMMU PMU Hit Low 1 Register
IOMMU_PMU_HIT_HIGH1_REG	0x024C	IOMMU PMU Hit High 1 Register
IOMMU_PMU_ACCESS_LOW2_REG	0x0250	IOMMU PMU Access Low 2 Register
IOMMU_PMU_ACCESS_HIGH2_REG	0x0254	IOMMU PMU Access High 2 Register
IOMMU_PMU_HIT_LOW2_REG	0x0258	IOMMU PMU Hit Low 2 Register
IOMMU_PMU_HIT_HIGH2_REG	0x025C	IOMMU PMU Hit High 2 Register
IOMMU_PMU_ACCESS_LOW3_REG	0x0260	IOMMU PMU Access Low 3 Register
IOMMU_PMU_ACCESS_HIGH3_REG	0x0264	IOMMU PMU Access High 3 Register
IOMMU_PMU_HIT_LOW3_REG	0x0268	IOMMU PMU Hit Low 3 Register
IOMMU_PMU_HIT_HIGH3_REG	0x026C	IOMMU PMU Hit High 3 Register

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Register Name	Offset	Description
IOMMU_PMU_ACCESS_LOW4_REG	0x0270	IOMMU PMU Access Low 4 Register
IOMMU_PMU_ACCESS_HIGH4_REG	0x0274	IOMMU PMU Access High 4 Register
IOMMU_PMU_HIT_LOW4_REG	0x0278	IOMMU PMU Hit Low 4 Register
IOMMU_PMU_HIT_HIGH4_REG	0x027C	IOMMU PMU Hit High 4 Register
IOMMU_PMU_ACCESS_LOW5_REG	0x0280	IOMMU PMU Access Low 5 Register
IOMMU_PMU_ACCESS_HIGH5_REG	0x0284	IOMMU PMU Access High 5 Register
IOMMU_PMU_HIT_LOW5_REG	0x0288	IOMMU PMU Hit Low 5 Register
IOMMU_PMU_HIT_HIGH5_REG	0x028C	IOMMU PMU Hit High 5 Register
IOMMU_PMU_ACCESS_LOW6_REG	0x0290	IOMMU PMU Access Low 6 Register
IOMMU_PMU_ACCESS_HIGH6_REG	0x0294	IOMMU PMU Access High 6 Register
IOMMU_PMU_HIT_LOW6_REG	0x0298	IOMMU PMU Hit Low 6 Register
IOMMU_PMU_HIT_HIGH6_REG	0x029C	IOMMU PMU Hit High 6 Register
IOMMU_PMU_ACCESS_LOW7_REG	0x02D0	IOMMU PMU Access Low 7 Register
IOMMU_PMU_ACCESS_HIGH7_REG	0x02D4	IOMMU PMU Access High 7 Register
IOMMU_PMU_HIT_LOW7_REG	0x02D8	IOMMU PMU Hit Low 7 Register
IOMMU_PMU_HIT_HIGH7_REG	0x02DC	IOMMU PMU Hit High 7 Register
IOMMU_PMU_ACCESS_LOW8_REG	0x02E0	IOMMU PMU Access Low 8 Register
IOMMU_PMU_ACCESS_HIGH8_REG	0x02E4	IOMMU PMU Access High 8 Register
IOMMU_PMU_HIT_LOW8_REG	0x02E8	IOMMU PMU Hit Low 8 Register
IOMMU_PMU_HIT_HIGH8_REG	0x02EC	IOMMU PMU Hit High 8 Register
IOMMU_PMU_TL_LOW0_REG	0x0300	IOMMU Total Latency Low 0 Register
IOMMU_PMU_TL_HIGH0_REG	0x0304	IOMMU Total Latency High 0 Register
IOMMU_PMU_ML0_REG	0x0308	IOMMU Max Latency 0 Register
IOMMU_PMU_TL_LOW1_REG	0x0310	IOMMU Total Latency Low 1 Register
IOMMU_PMU_TL_HIGH1_REG	0x0314	IOMMU Total Latency High 1 Register
IOMMU_PMU_ML1_REG	0x0318	IOMMU Max Latency 1 Register
IOMMU_PMU_TL_LOW2_REG	0x0320	IOMMU Total Latency Low 2 Register
IOMMU_PMU_TL_HIGH2_REG	0x0324	IOMMU Total Latency High 2 Register
IOMMU_PMU_ML2_REG	0x0328	IOMMU Max Latency 2 Register
IOMMU_PMU_TL_LOW3_REG	0x0330	IOMMU Total Latency Low 3 Register
IOMMU_PMU_TL_HIGH3_REG	0x0334	IOMMU Total Latency High 3 Register
IOMMU_PMU_ML3_REG	0x0338	IOMMU Max Latency 3 Register
IOMMU_PMU_TL_LOW4_REG	0x0340	IOMMU Total Latency Low 4 Register
IOMMU_PMU_TL_HIGH4_REG	0x0344	IOMMU Total Latency High 4 Register

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Register Name	Offset	Description
IOMMU_PMU_ML4_REG	0x0348	IOMMU Max Latency 4 Register
IOMMU_PMU_TL_LOW5_REG	0x0350	IOMMU Total Latency Low 5 Register
IOMMU_PMU_TL_HIGH5_REG	0x0354	IOMMU Total Latency High 5 Register
IOMMU_PMU_ML5_REG	0x0358	IOMMU Max Latency 5 Register
IOMMU_PMU_TL_LOW6_REG	0x0360	IOMMU Total Latency Low 6 Register
IOMMU_PMU_TL_HIGH6_REG	0x0364	IOMMU Total Latency High 6 Register
IOMMU_PMU_ML6_REG	0x0368	IOMMU Max Latency 6 Register

3.11.6 Register Description

3.11.6.1 0x0010 IOMMU Reset Register (Default Value: 0x8003_007F)

Offset: 0x0010			Register Name: IOMMU_RESET _REG
Bit	Read/Write	Default/Hex	Description
31	R/W	0x1	IOMMU_RESET IOMMU Software Reset Switch 0: Set reset signal 1: Release reset signal Before IOMMU software reset operation, ensure IOMMU never be opened; or all bus operations are completed; or DRAM and the peripherals have opened the corresponding switch, for shielding the effects of IOMMU reset.
30:18	/	/	/
17	R/W	0x1	PC_RST PTW Cache Reset PTW Cache address convert lane software reset switch. 0: Set reset signal 1: Release reset signal When PTW Cache occurs abnormal, the bit is used to reset PTW Cache individually.
16	R/W	0x1	MTLB_RST Macrotlb Reset Macro TLB address convert lane software reset switch. 0: Set reset signal 1: Release reset signal When Macro TLB occurs abnormal, the bit is used to reset Macro TLB individually.

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Offset: 0x0010			Register Name: IOMMU_RESET _REG
Bit	**Read/Write**	**Default/Hex**	**Description**
15:7	/	/	/
6	R/W	0x1	M6_RST Master6 Reset Master6 address convert lane software reset switch. 0: Set reset signal 1: Release reset signal When Master6 occurs abnormal, the bit is used to reset Master6 individually. **Note: This bit is not used.**
5	R/W	0x1	M5_RST Master5 Reset Master5 address convert lane software reset switch. 0: Set reset signal 1: Release reset signal When Master5 occurs abnormal, the bit is used to reset Master5 individually.
4	R/W	0x1	M4_RST Master4 Reset Master4 address convert lane software reset switch. 0: Set reset signal 1: Release reset signal When Master4 occurs abnormal, the bit is used to reset Master4 individually.
3	R/W	0x1	M3_RST Master3 Reset Master3 address convert lane software reset switch. 0: Set reset signal 1: Release reset signal When Master3 occurs abnormal, the bit is used to reset Master3 individually.
2	R/W	0x1	M2_RST Master2 Reset Master2 address convert lane software reset switch. 0: Set reset signal 1: Release reset signal When Master2 occurs abnormal, the bit is used to reset Master2 individually.

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Offset: 0x0010			Register Name: IOMMU_RESET _REG
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x1	M1_RST Master1 Reset Master1 address convert lane software reset switch. 0: Set reset signal 1: Release reset signal When Master1 occurs abnormal, the bit is used to reset Master1 individually.
0	R/W	0x1	M0_RST Master0 Reset Master0 address convert lane software reset switch. 0: Set reset signal 1: Release reset signal When Master0 occurs abnormal, the bit is used to reset Master0 individually.

3.11.6.2 0x0020 IOMMU Enable Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: IOMMU_ENABLE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	ENABLE IOMMU module enable switch 0: Disable IOMMU 1: Enable IOMMU Before IOMMU address mapping function opens, configure the Translation Table Base register; or ensure all masters are in bypass status or no the status of sending bus demand(such as reset)

3.11.6.3 0x0030 IOMMU Bypass Register (Default Value: 0x0000_007F)

Offset: 0x0030			Register Name: IOMMU_BYPASS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6	R/W	0x1	M6_BP Master6 bypass switch

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Offset: 0x0030			Register Name: IOMMU_BYPASS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			After bypass function is opened, IOMMU can not map the address of Master6 sending, and directly output the virtual address to MBUS as physical address. 0: Disable bypass function 1: Enable bypass function **Note: The bit is not used.**
5	R/W	0x1	M5_BP Master5 bypass switch After bypass function is opened, IOMMU can not map the address of Master5 sending, and directly output the virtual address to MBUS as physical address. 0: Disable bypass function 1: Enable bypass function
4	R/W	0x1	M4_BP Master4 bypass switch After bypass function is opened, IOMMU can not map the address of Master4 sending, and directly output the virtual address to MBUS as physical address. 0: Disable bypass function 1: Enable bypass function
3	R/W	0x1	M3_BP Master3 bypass switch After bypass function is opened, IOMMU can not map the address of Master3 sending, and directly output the virtual address to MBUS as physical address. 0: Disable bypass function 1: Enable bypass function
2	R/W	0x1	M2_BP Master2 bypass switch After bypass function is opened, IOMMU can not map the address of Master2 sending, and directly output the virtual address to MBUS as physical address. 0: Disable bypass function 1: Enable bypass function
1	R/W	0x1	M1_BP Master1 bypass switch

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Offset: 0x0030			Register Name: IOMMU_BYPASS_REG
Bit	Read/Write	Default/Hex	Description
			After bypass function is opened, IOMMU can not map the address of Master1 sending, and directly output the virtual address to MBUS as physical address. 0: Disable bypass function 1: Enable bypass function
0	R/W	0x1	M0_BP Master0 bypass switch After bypass function is opened, IOMMU can not map the address of Master0 sending, and directly output the virtual address to MBUS as physical address. 0: Disable bypass function 1: Enable bypass function

NOTE

- Operating the register belongs to non-accurate timing sequence control function. That is, before the function is valid, master operation will complete address mapping function, and any subsequent operation will not perform address mapping.
- It is suggested that master is in reset state or in no any bus operation before operating the register.

3.11.6.4 0x0040 IOMMU Auto Gating Register (Default Value: 0x0000_0001)

Offset: 0x0040			Register Name: IOMMU_AUTO_GATING_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/W	0x1	IOMMU_AUTO_GATING IOMMU circuit auto gating control The purpose is to decrease power consumption of the module. 0: Disable auto gating function 1: Enable auto gating function

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3.11.6.5 0x0044 IOMMU Write Buffer Control Register (Default Value: 0x0000_007F)

Offset: 0x0044			Register Name: IOMMU_WBUF_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6	R/W	0x1	Reserved
5	R/W	0x1	Reserved
4	R/W	0x1	Reserved
3	R/W	0x1	Reserved
2	R/W	0x1	Reserved
1	R/W	0x1	Reserved
0	R/W	0x1	Reserved

3.11.6.6 0x0048 IOMMU Out Of Order Control Register (Default Value: 0x0000_007F)

Offset: 0x0048			Register Name: IOMMU_OOO_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6	R/W	0x1	M6_OOO_CTRL Master6 out-of-order control bit 0: Disable out-of-order 1: Enable out-of-order **Note: This bit is not used.**
5	R/W	0x1	M5_OOO_CTRL Master5 out-of-order control bit 0: Disable out-of-order 1: Enable out-of-order
4	R/W	0x1	M4_OOO_CTRL Master4 out-of-order control bit 0: Disable out-of-order 1: Enable out-of-order
3	R/W	0x1	M3_OOO_CTRL Master3 out-of-order control bit 0: Disable out-of-order 1: Enable out-of-order
2	R/W	0x1	M2_OOO_CTRL Master2 out-of-order control bit

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Offset: 0x0048			Register Name: IOMMU_OOO_CTRL_REG
Bit	Read/Write	Default/Hex	Description
			0: Disable out-of-order 1: Enable out-of-order
1	R/W	0x1	M1_OOO_CTRL Master1 out-of-order control bit 0: Disable out-of-order 1: Enable out-of-order
0	R/W	0x1	M0_OOO_CTRL Master0 out-of-order control bit 0: Disable out-of-order 1: Enable out-of-order

3.11.6.7 0x004C IOMMU 4KB Boundary Protect Control Register (Default Value: 0x0000_007F)

NOTE

When the virtual address sent by master is over the 4 KB boundary, 4 KB protection unit will split it into two serial access.

Offset: 0x004C			Register Name: IOMMU_4KB_BDY_PRT_CTRL_REG
Bit	Read/Write	Default/Hex	Description
31:7	/	/	/
6	R/W	0x1	M6_4KB_BDY_PRT_CTRL Master6 4 KB boundary protect control bit 0: Disable 4 KB boundary protect 1: Enable 4 KB boundary protect **Note: This bit is not used.**
5	R/W	0x1	M5_4KB_BDY_PRT_CTRL Master4 4 KB boundary protect control bit 0: Disable 4 KB boundary protect 1: Enable 4 KB boundary protect
4	R/W	0x1	M4_4KB_BDY_PRT_CTRL Master4 4 KB boundary protect control bit 0: Disable 4 KB boundary protect

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Offset: 0x004C			Register Name: IOMMU_4KB_BDY_PRT_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: Enable 4 KB boundary protect
3	R/W	0x1	M3_4KB_BDY_PRT_CTRL Master3 4 KB boundary protect control bit 0: Disable 4 KB boundary protect 1: Enable 4 KB boundary protect
2	R/W	0x1	M2_4KB_BDY_PRT_CTRL Master2 4 KB boundary protect control bit 0: Disable 4 KB boundary protect 1: Enable 4 KB boundary protect
1	R/W	0x1	M1_4KB_BDY_PRT_CTRL Master1 4 KB boundary protect control bit 0: Disable 4 KB boundary protect 1: Enable 4 KB boundary protect
0	R/W	0x1	M0_4KB_BDY_PRT_CTRL Master0 4 KB boundary protect control bit 0: Disable 4 KB boundary protect 1: Enable 4 KB boundary protect

3.11.6.8 0x0050 IOMMU Translation Table Base Register (Default Value: 0x0000_0000)

Offset: 0x0050			Register Name: IOMMU_TTB_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	R/W	0x0	TTB Translation Table Base Level1 page table starting address, aligned to 16 KB. When operating the register, IOMMU address mapping function must be closed, namely IOMMU_ENABLE_REG is 0; Or Bypass function of all main equipment is set to 1, or no the state of transfer bus commands (such as setting).
13:0	/	/	/

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3.11.6.9 0x0060 IOMMU TLB Enable Register (Default Value: 0x0003_007F)

Offset: 0x0060			Register Name: IOMMU_TLB_ENABLE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/W	0x1	PTW_CACHE_ENABLE PTW Cache enable bit 0: Disable 1: Enable
16	R/W	0x1	MACRO_TLB_ENABLE Macro TLB enable bit 0: Disable 1: Enable
15:7	/	/	/
6	R/W	0x1	MICRO_TLB6_ENABLE Micro TLB6 enable bit 0: Disable 1: Enable
5	R/W	0x1	MICRO_TLB5_ENABLE Micro TLB5 enable bit 0: Disable 1: Enable
4	R/W	0x1	MICRO_TLB4_ENABLE Micro TLB4 enable bit 0: Disable 1: Enable
3	R/W	0x1	MICRO_TLB3_ENABLE Micro TLB3 enable bit 0: Disable 1: Enable
2	R/W	0x1	MICRO_TLB2_ENABLE Micro TLB2 enable bit 0: Disable 1: Enable
1	R/W	0x1	MICRO_TLB1_ENABLE Micro TLB1 enable bit 0: Disable 1: Enable

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Offset: 0x0060			Register Name: IOMMU_TLB_ENABLE_REG
Bit	Read/Write	Default/Hex	Description
0	R/W	0x1	MICRO_TLB0_ENABLE Micro TLB0 enable bit 0: Disable 1: Enable

3.11.6.10 0x0070 IOMMU TLB Prefetch Register (Default Value: 0x0000_0000)

Offset: 0x0070			Register Name: IOMMU_TLB_PREFETCH_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17	R/W	0x1	PF_VL_PT_TO_PC Prefetch Value Pagetable to PTW Cache 0: Disable 1: Enable If the function is enabled, the prefetch function will not update the invalid Level1 page table to PTW cache.
16	R/W	0x1	PF_VL_PT_TO_MT Prefetch Value Pagetable to Macro TLB 0: Disable 1: Enable If the function is enabled, the prefetch function will not update the invalid Level2 page table to Macro TLB.
15:7	/	/	/
6	R/W	0x0	MI_TLB6_PF Micro TLB6 prefetch enable 0: Disable 1: Enable
5	R/W	0x0	MI_TLB5_PF Micro TLB5 prefetch enable 0: Disable 1: Enable
4	R/W	0x0	MI_TLB4_PF Micro TLB4 prefetch enable 0: Disable 1: Enable
3	R/W	0x0	MI_TLB3_PF

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Offset: 0x0070			Register Name: IOMMU_TLB_PREFETCH_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Micro TLB3 prefetch enable 0: Disable 1: Enable **Note: If G2D accesses DDR, it is suggested that disable the prefetch function.**
2	R/W	0x0	MI_TLB2_PF Micro TLB2 prefetch enable 0: Disable 1: Enable
1	R/W	0x0	MI_TLB1_PF Micro TLB1 prefetch enable 0: Disable 1: Enable
0	R/W	0x0	MI_TLB0_PF Micro TLB0 prefetch enable 0: Disable 1: Enable

3.11.6.11 0x0080 IOMMU TLB Flush Enable Register (Default Value: 0x0000_0000)

When performing flush operations, all TLB/Cache access will be paused.

Before flush starts, the operation that has entered TLB continues to complete.

Offset: 0x0080			Register Name: IOMMU_TLB_FLUSH_ENABLE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/WAC	0x0	PC_FS PTW Cache Flush Clear PTW Cache 0: No clear operation or clear operation is completed 1: Enable clear operation After the Flush operation is completed, the bit can clear automatically.
16	R/WAC	0x0	MA_TLB_FS Macro TLB Flush Clear Macro TLB 0: No clear operation or clear operation is completed

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Offset: 0x0080			Register Name: IOMMU_TLB_FLUSH_ENABLE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: Enable clear operation After the Flush operation is completed, the bit can clear automatically.
15:7	/	/	/
6	R/WAC	0x0	MI_TLB6_FS Micro TLB6 Flush Clear Micro TLB6 0: No clear operation or clear operation is completed 1: Enable clear operation After the Flush operation is completed, the bit can clear automatically.
5	R/WAC	0x0	MI_TLB5_FS Micro TLB5 Flush Clear Micro TLB5 0: No clear operation or clear operation is completed 1: Enable clear operation After the Flush operation is completed, the bit can clear automatically.
4	R/WAC	0x0	MI_TLB4_FS Micro TLB4 Flush Clear Micro TLB4 0: No clear operation or clear operation is completed 1: Enable clear operation After the Flush operation is completed, the bit can clear automatically.
3	R/WAC	0x0	MI_TLB3_FS Micro TLB3 Flush Clear Micro TLB3 0: No clear operation or clear operation is completed 1: Enable clear operation After the Flush operation is completed, the bit can clear automatically.
2	R/WAC	0x0	MI_TLB2_FS Micro TLB2 Flush Clear Micro TLB2 0: No clear operation or clear operation is completed 1: Enable clear operation

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Offset: 0x0080			Register Name: IOMMU_TLB_FLUSH_ENABLE_REG
Bit	Read/Write	Default/Hex	Description
			After the Flush operation is completed, the bit can clear automatically.
1	R/WAC	0x0	MI_TLB1_FS Micro TLB1 Flush Clear Micro TLB1 0: No clear operation or clear operation is completed 1: Enable clear operation After the Flush operation is completed, the bit can clear automatically.
0	R/WAC	0x0	MI_TLB0_FS Micro TLB0 Flush Clear Micro TLB0 0: No clear operation or clear operation is completed 1: Enable clear operation After the Flush operation is completed, the bit can clear automatically.

3.11.6.12 0x0084 IOMMU TLB Invalidation Mode Select Register (Default Value: 0x0000_0000)

Offset: 0x0084			Register Name: IOMMU_TLB_IVLD_MODE_SEL_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/W	0x0	TLB_IVLD_MODE_SEL 0: Invalidate TLB by using the Mask mode 1: Invalidate TLB by using the Start and End mode

3.11.6.13 0x0088 IOMMU TLB Invalidation Start Address Register (Default Value: 0x0000_0000)

Offset: 0x0088			Register Name: IOMMU_TLB_IVLD_STA_ADDR_REG
Bit	Read/Write	Default/Hex	Description
31:12	R/W	0x0	TLB_IVLD_STA_ADDR TLB invalid start address, 4 KB aligned.
11:0	/	/	/

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3.11.6.14 0x008C IOMMU TLB Invalidation End Address Register (Default Value: 0x0000_0000)

Offset: 0x008C			Register Name: IOMMU_TLB_IVLD_END_ADDR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	R/W	0x0	TLB_IVLD_END_ADDR TLB invalid end address, 4 KB aligned.
11:0	/	/	/

3.11.6.15 0x0090 IOMMU TLB Invalidation Address Register (Default Value: 0x0000_0000)

Offset: 0x0090			Register Name: IOMMU_TLB_IVLD_ADDR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	R/W	0x0	TLB_IVLD_ADDR TLB invalid address, 4 KB aligned
11:0	/	/	/

Operation:

1) Set the virtual address that needs to be operated in **IOMMU_TLB_IVLD_ADDR_REG**.
2) Set the mask of virtual address that needs to be operated in **IOMMU_TLB_IVLD_ADDR_MASK_REG**.
3) Write '1' to **IOMMU_TLB_IVLD_ENABLE_REG[0].**
4) Read **IOMMU_TLB_IVLD_ENABLE_REG[0]**, when it is '0', it indicates that invalidation behavior is finished.

NOTE

- When performing invalidation operation, TLB/Cache operation has not affected.
- After or before invalidation operation starts, there is no absolute relationship between the same address switch operation and invalidation operation.

3.11.6.16 0x0094 IOMMU TLB Invalidation Address Mask Register (Default Value: 0x0000_0000)

Offset: 0x0094			Register Name: IOMMU_TLB_IVLD_ADDR_MASK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	R/W	0x0	TLB_IVLD_ADDR_MASK TLB invalid address mask register, 4 KB aligned
11:0	/	/	/

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3.11.6.17 0x0098 IOMMU TLB Invalidation Enable Register (Default Value: 0x0000_0000)

Offset: 0x0098			Register Name: IOMMU_TLB_IVLD_ENABLE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/WAC	0x0	TLB_IVLD_ENABLE Enable TLB invalidation operation 0: No operation or operation is completed 1: Enable invalidation operation After invalidation operation is completed, the bit can clear automatically. When operating invalidation operation, TLB/Cache operation has not affected. After or before invalidation operation starts, there is no absolute relationship between the same address switch operation and invalidation operation.

3.11.6.18 0x009C IOMMU PC Invalidation Mode Select Register (Default Value: 0x0000_0000)

Offset: 0x009C			Register Name: IOMMU_PC_IVLD_MODE_SEL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	PC_IVLD_MODE_SEL PTW Cache Invalid Mode Select 0: Invalidate PTW by using the Mask mode 1: Invalidate PTW by using the Start and End mode

3.11.6.19 0x00A0 IOMMU PC Invalidation Address Register (Default Value: 0x0000_0000)

Offset: 0x00A0			Register Name: IOMMU_PC_IVLD_ADDR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:20	R/W	0x0	PC_IVLD_ADDR PTW Cache invalid address, 1 MB aligned.
19:0	/	/	/

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3.11.6.20 0x00A4 IOMMU PC Invalidation Start Address Register (Default Value: 0x0000_0000)

Offset: 0x00A4			Register Name: IOMMU_PC_IVLD_STA_ADDR_REG
Bit	Read/Write	Default/Hex	Description
31:20	R/W	0x0	PC_IVLD_SA PTW Cache invalid start address, 1 MB aligned.
19:0	/	/	/

3.11.6.21 0x00A8 IOMMU PC Invalidation Enable Register (Default Value: 0x0000_0000)

Offset: 0x00A8			Register Name: IOMMU_PC_IVLD_ENABLE_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/WAC	0x0	PC_IVLD_ENABLE Enable PTW Cache invalidation operation 0: No operation or operation is completed 1: Enable invalidation operation After invalidation operation is completed, the bit can clear automatically. After or before invalidation operation starts, there is no absolute relationship between the same address switch operation and invalidation operation.

3.11.6.22 0x00AC IOMMU PC Invalidation End Address Register (Default Value: 0x0000_0000)

Offset: 0x00AC			Register Name: IOMMU_PC_IVLD_END_ADDR_REG
Bit	Read/Write	Default/Hex	Description
31:20	R/W	0x0	PC_IVLD_EA PTW Cache invalid end address, 1 MB aligned.
19:0	/	/	/

3.11.6.23 0x00B0 IOMMU Domain Authority Control 0 Register (Default Value: 0x0000_0000)

Software can set 15 different permission control types in IOMMU_DM_AUT_CTRL_REG0–7. A default access control type is DOMAIN0. The read/write operation of DOMAIN1–15 is unlimited by default.

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Software needs to set the index of the permission control domain corresponding to the page table item in the bit[7:4] of the Level2 page table, the default value is 0 (use domian0), that is, the read/write operation is not controlled.

Setting REG_ARD_OVWT can mask the Domain control defined by IOMMU_DM_AUT_CTRL_REG0–7. All Level2 page table type are covered by the type of REG_ARD_OVWT. The read/write operation is permitted by default.

Offset: 0x00B0			Register Name: IOMMU_DM_AUT_CTRL0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29	R/W	0x0	DM1_M6_WT_AUT_CTRL Domain1 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
28	R/W	0x0	DM1_M6_RD_AUT_CTRL Domain1 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
27	R/W	0x0	DM1_M5_WT_AUT_CTRL Domain1 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
26	R/W	0x0	DM1_M5_RD_AUT_CTRL Domain1 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
25	R/W	0x0	DM1_M4_WT_AUT_CTRL Domain1 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
24	R/W	0x0	DM1_M4_RD_AUT_CTRL Domain1 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
23	R/W	0x0	DM1_M3_WT_AUT_CTRL Domain1 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
22	R/W	0x0	DM1_M3_RD_AUT_CTRL

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Offset: 0x00B0			Register Name: IOMMU_DM_AUT_CTRL0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Domain1 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
21	R/W	0x0	DM1_M2_WT_AUT_CTRL Domain1 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
20	R/W	0x0	DM1_M2_RD_AUT_CTRL Domain1 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
19	R/W	0x0	DM1_M1_WT_AUT_CTRL Domain1 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
18	R/W	0x0	DM1_M1_RD_AUT_CTRL Domain1 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
17	R/W	0x0	DM1_M0_WT_AUT_CTRL Domain1 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
16	R/W	0x0	DM1_M0_RD_AUT_CTRL Domain1 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited
15:14	/	/	/
13	R	0x0	DM0_M6_WT_AUT_CTRL Domain0 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
12	R	0x0	DM0_M6_RD_AUT_CTRL Domain0 read permission control for master6 0: The read-operation is permitted

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Offset: 0x00B0			Register Name: IOMMU_DM_AUT_CTRL0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: The read-operation is prohibited **Note: The bit is not used.**
11	R	0x0	DM0_M5_WT_AUT_CTRL Domain0 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
10	R	0x0	DM0_M5_RD_AUT_CTRL Domain0 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
9	R	0x0	DM0_M4_WT_AUT_CTRL Domain0 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
8	R	0x0	DM0_M4_RD_AUT_CTRL Domain0 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
7	R	0x0	DM0_M3_WT_AUT_CTRL Domain0 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
6	R	0x0	DM0_M3_RD_AUT_CTRL Domain0 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
5	R	0x0	DM0_M2_WT_AUT_CTRL Domain0 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
4	R	0x0	DM0_M2_RD_AUT_CTRL Domain0 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
3	R	0x0	DM0_M1_WT_AUT_CTRL Domain0 write permission control for master1

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Offset: 0x00B0			Register Name: IOMMU_DM_AUT_CTRL0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			0: The write-operation is permitted 1: The write-operation is prohibited
2	R	0x0	DM0_M1_RD_AUT_CTRL Domain0 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
1	R	0x0	DM0_M0_WT_AUT_CTRL Domain0 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
0	R	0x0	DM0_M0_RD_AUT_CTRL Domain0 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited

3.11.6.24 0x00B4 IOMMU Domain Authority Control 1 Register (Default Value: 0x0000_0000)

Offset: 0x00B4			Register Name: IOMMU_DM_AUT_CTRL1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29	R/W	0x0	DM3_M6_WT_AUT_CTRL Domain3 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
28	R/W	0x0	DM3_M6_RD_AUT_CTRL Domain3 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
27	R/W	0x0	DM3_M5_WT_AUT_CTRL Domain3 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
26	R/W	0x0	DM3_M5_RD_AUT_CTRL Domain3 read permission control for master5

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Offset: 0x00B4			Register Name: IOMMU_DM_AUT_CTRL1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			0: The read-operation is permitted 1: The read-operation is prohibited
25	R/W	0x0	DM3_M4_WT_AUT_CTRL Domain3 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
24	R/W	0x0	DM3_M4_RD_AUT_CTRL Domain3 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
23	R/W	0x0	DM3_M3_WT_AUT_CTRL Domain3 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
22	R/W	0x0	DM3_M3_RD_AUT_CTRL Domain3 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
21	R/W	0x0	DM3_M2_WT_AUT_CTRL Domain3 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
20	R/W	0x0	DM3_M2_RD_AUT_CTRL Domain3 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
19	R/W	0x0	DM3_M1_WT_AUT_CTRL Domain3 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
18	R/W	0x0	DM3_M1_RD_AUT_CTRL Domain3 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
17	R/W	0x0	DM3_M0_WT_AUT_CTRL Domain3 write permission control for master0

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Offset: 0x00B4			Register Name: IOMMU_DM_AUT_CTRL1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			0: The write-operation is permitted 1: The write-operation is prohibited
16	R/W	0x0	DM3_M0_RD_AUT_CTRL Domain3 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited
15:14	/	/	/
13	R/W	0x0	DM2_M6_WT_AUT_CTRL Domain2 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
12	R/W	0x0	DM2_M6_RD_AUT_CTRL Domain2 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
11	R/W	0x0	DM2_M5_WT_AUT_CTRL Domain2 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
10	R/W	0x0	DM2_M5_RD_AUT_CTRL Domain2 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
9	R/W	0x0	DM2_M4_WT_AUT_CTRL Domain2 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
8	R/W	0x0	DM2_M4_RD_AUT_CTRL Domain2 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
7	R/W	0x0	DM2_M3_WT_AUT_CTRL Domain2 write permission control for master3 0: The write-operation is permitted

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Offset: 0x00B4			Register Name: IOMMU_DM_AUT_CTRL1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: The write-operation is prohibited
6	R/W	0x0	DM2_M3_RD_AUT_CTRL Domain2 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
5	R/W	0x0	DM2_M2_WT_AUT_CTRL Domain2 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
4	R/W	0x0	DM2_M2_RD_AUT_CTRL Domain2 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
3	R/W	0x0	DM2_M1_WT_AUT_CTRL Domain2 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
2	R/W	0x0	DM2_M1_RD_AUT_CTRL Domain2 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
1	R/W	0x0	DM2_M0_WT_AUT_CTRL Domain2 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
0	R/W	0x0	DM2_M0_RD_AUT_CTRL Domain2 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited

3.11.6.25 0x00B8 IOMMU Domain Authority Control 2 Register (Default Value: 0x0000_0000)

Offset: 0x00B8			Register Name: IOMMU_DM_AUT_CTRL2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29	R/W	0x0	DM5_M6_WT_AUT_CTRL

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Offset: 0x00B8			Register Name: IOMMU_DM_AUT_CTRL2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Domain5 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
28	R/W	0x0	DM5_M6_RD_AUT_CTRL Domain5 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
27	R/W	0x0	DM5_M5_WT_AUT_CTRL Domain5 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
26	R/W	0x0	DM5_M5_RD_AUT_CTRL Domain5 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
25	R/W	0x0	DM5_M4_WT_AUT_CTRL Domain5 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
24	R/W	0x0	DM5_M4_RD_AUT_CTRL Domain5 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
23	R/W	0x0	DM5_M3_WT_AUT_CTRL Domain5 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
22	R/W	0x0	DM5_M3_RD_AUT_CTRL Domain5 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
21	R/W	0x0	DM5_M2_WT_AUT_CTRL Domain5 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited

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Offset: 0x00B8			Register Name: IOMMU_DM_AUT_CTRL2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
20	R/W	0x0	DM5_M2_RD_AUT_CTRL Domain5 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
19	R/W	0x0	DM5_M1_WT_AUT_CTRL Domain5 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
18	R/W	0x0	DM5_M1_RD_AUT_CTRL Domain5 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
17	R/W	0x0	DM5_M0_WT_AUT_CTRL Domain5 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
16	R/W	0x0	DM5_M0_RD_AUT_CTRL Domain5 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited
15:14	/	/	/
13	R/W	0x0	DM4_M6_WT_AUT_CTRL Domain4 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
12	R/W	0x0	DM4_M6_RD_AUT_CTRL Domain4 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
11	R/W	0x0	DM4_M5_WT_AUT_CTRL Domain4 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
10	R/W	0x0	DM4_M5_RD_AUT_CTRL

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Offset: 0x00B8			Register Name: IOMMU_DM_AUT_CTRL2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Domain4 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
9	R/W	0x0	DM4_M4_WT_AUT_CTRL Domain4 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
8	R/W	0x0	DM4_M4_RD_AUT_CTRL Domain4 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
7	R/W	0x0	DM4_M3_WT_AUT_CTRL Domain4 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
6	R/W	0x0	DM4_M3_RD_AUT_CTRL Domain4 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
5	R/W	0x0	DM4_M2_WT_AUT_CTRL Domain4 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
4	R/W	0x0	DM4_M2_RD_AUT_CTRL Domain4 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
3	R/W	0x0	DM4_M1_WT_AUT_CTRL Domain4 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
2	R/W	0x0	DM4_M1_RD_AUT_CTRL Domain4 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
1	R/W	0x0	DM4_M0_WT_AUT_CTRL

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Offset: 0x00B8			Register Name: IOMMU_DM_AUT_CTRL2_REG
Bit	Read/Write	Default/Hex	Description
			Domain4 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
0	R/W	0x0	DM4_M0_RD_AUT_CTRL Domain4 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited

3.11.6.26 0x00BC IOMMU Domain Authority Control 3 Register (Default Value: 0x0000_0000)

Offset: 0x00BC			Register Name: IOMMU_DM_AUT_CTRL3_REG
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29	R/W	0x0	DM7_M6_WT_AUT_CTRL Domain7 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
28	R/W	0x0	DM7_M6_RD_AUT_CTRL Domain7 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
27	R/W	0x0	DM7_M5_WT_AUT_CTRL Domain7 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
26	R/W	0x0	DM7_M5_RD_AUT_CTRL Domain7 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
25	R/W	0x0	DM7_M4_WT_AUT_CTRL Domain7 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
24	R/W	0x0	DM7_M4_RD_AUT_CTRL

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Offset: 0x00BC			Register Name: IOMMU_DM_AUT_CTRL3_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Domain7 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
23	R/W	0x0	DM7_M3_WT_AUT_CTRL Domain7 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
22	R/W	0x0	DM7_M3_RD_AUT_CTRL Domain7 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
21	R/W	0x0	DM7_M2_WT_AUT_CTRL Domain7 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
20	R/W	0x0	DM7_M2_RD_AUT_CTRL Domain7 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
19	R/W	0x0	DM7_M1_WT_AUT_CTRL Domain7 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
18	R/W	0x0	DM7_M1_RD_AUT_CTRL Domain7 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
17	R/W	0x0	DM7_M0_WT_AUT_CTRL Domain7 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
16	R/W	0x0	DM7_M0_RD_AUT_CTRL Domain7 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited
15:14	/	/	/

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Offset: 0x00BC			Register Name: IOMMU_DM_AUT_CTRL3_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
13	R/W	0x0	DM6_M6_WT_AUT_CTRL Domain6 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
12	R/W	0x0	DM6_M6_RD_AUT_CTRL Domain6 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
11	R/W	0x0	DM6_M5_WT_AUT_CTRL Domain6 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
10	R/W	0x0	DM6_M5_RD_AUT_CTRL Domain6 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
9	R/W	0x0	DM6_M4_WT_AUT_CTRL Domain6 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
8	R/W	0x0	DM6_M4_RD_AUT_CTRL Domain6 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
7	R/W	0x0	DM6_M3_WT_AUT_CTRL Domain6 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
6	R/W	0x0	DM6_M3_RD_AUT_CTRL Domain6 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
5	R/W	0x0	DM6_M2_WT_AUT_CTRL Domain6 write permission control for master2 0: The write-operation is permitted

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Offset: 0x00BC			Register Name: IOMMU_DM_AUT_CTRL3_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: The write-operation is prohibited
4	R/W	0x0	DM6_M2_RD_AUT_CTRL Domain6 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
3	R/W	0x0	DM6_M1_WT_AUT_CTRL Domain6 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
2	R/W	0x0	DM6_M1_RD_AUT_CTRL Domain6 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
1	R/W	0x0	DM6_M0_WT_AUT_CTRL Domain6 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
0	R/W	0x0	DM6_M0_RD_AUT_CTRL Domain6 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited

3.11.6.27 0x00C0 IOMMU Domain Authority Control 4 Register (Default Value: 0x0000_0000)

Offset: 0x00C0			Register Name: IOMMU_DM_AUT_CTRL4_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29	R/W	0x0	DM9_M6_WT_AUT_CTRL Domain9 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
28	R/W	0x0	DM9_M6_RD_AUT_CTRL Domain9 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited

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Offset: 0x00C0			Register Name: IOMMU_DM_AUT_CTRL4_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Note: The bit is not used.
27	R/W	0x0	DM9_M5_WT_AUT_CTRL Domain9 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
26	R/W	0x0	DM9_M5_RD_AUT_CTRL Domain9 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
25	R/W	0x0	DM9_M4_WT_AUT_CTRL Domain9 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
24	R/W	0x0	DM9_M4_RD_AUT_CTRL Domain9 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
23	R/W	0x0	DM9_M3_WT_AUT_CTRL Domain9 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
22	R/W	0x0	DM9_M3_RD_AUT_CTRL Domain9 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
21	R/W	0x0	DM9_M2_WT_AUT_CTRL Domain9 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
20	R/W	0x0	DM9_M2_RD_AUT_CTRL Domain9 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
19	R/W	0x0	DM9_M1_WT_AUT_CTRL Domain9 write permission control for master1 0: The write-operation is permitted

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Offset: 0x00C0			Register Name: IOMMU_DM_AUT_CTRL4_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: The write-operation is prohibited
18	R/W	0x0	DM9_M1_RD_AUT_CTRL Domain9 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
17	R/W	0x0	DM9_M0_WT_AUT_CTRL Domain9 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
16	R/W	0x0	DM9_M0_RD_AUT_CTRL Domain9 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited
15:14	/	/	/
13	R/W	0x0	DM8_M6_WT_AUT_CTRL Domain8 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
12	R/W	0x0	DM8_M6_RD_AUT_CTRL Domain8 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
11	R/W	0x0	DM8_M5_WT_AUT_CTRL Domain8 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
10	R/W	0x0	DM8_M5_RD_AUT_CTRL Domain8 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
9	R/W	0x0	DM8_M4_WT_AUT_CTRL Domain8 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited

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Offset: 0x00C0			Register Name: IOMMU_DM_AUT_CTRL4_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
8	R/W	0x0	DM8_M4_RD_AUT_CTRL Domain8 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
7	R/W	0x0	DM8_M3_WT_AUT_CTRL Domain8 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
6	R/W	0x0	DM8_M3_RD_AUT_CTRL Domain8 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
5	R/W	0x0	DM8_M2_WT_AUT_CTRL Domain8 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
4	R/W	0x0	DM8_M2_RD_AUT_CTRL Domain8 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
3	R/W	0x0	DM8_M1_WT_AUT_CTRL Domain8 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
2	R/W	0x0	DM8_M1_RD_AUT_CTRL Domain8 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
1	R/W	0x0	DM8_M0_WT_AUT_CTRL Domain8 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
0	R/W	0x0	DM8_M0_RD_AUT_CTRL Domain8 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited

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3.11.6.28 0x00C4 IOMMU Domain Authority Control 5 Register (Default Value: 0x0000_0000)

Offset: 0x00C4			Register Name: IOMMU_DM_AUT_CTRL5_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29	R/W	0x0	DM11_M6_WT_AUT_CTRL Domain11 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
28	R/W	0x0	DM11_M6_RD_AUT_CTRL Domain11 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
27	R/W	0x0	DM11_M5_WT_AUT_CTRL Domain11 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
26	R/W	0x0	DM11_M5_RD_AUT_CTRL Domain11 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
25	R/W	0x0	DM11_M4_WT_AUT_CTRL Domain11 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
24	R/W	0x0	DM11_M4_RD_AUT_CTRL Domain11 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
23	R/W	0x0	DM11_M3_WT_AUT_CTRL Domain11 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
22	R/W	0x0	DM11_M3_RD_AUT_CTRL Domain11 read permission control for master3

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Offset: 0x00C4			Register Name: IOMMU_DM_AUT_CTRL5_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			0: The read-operation is permitted 1: The read-operation is prohibited
21	R/W	0x0	DM11_M2_WT_AUT_CTRL Domain11 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
20	R/W	0x0	DM11_M2_RD_AUT_CTRL Domain11 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
19	R/W	0x0	DM11_M1_WT_AUT_CTRL Domain11 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
18	R/W	0x0	DM11_M1_RD_AUT_CTRL Domain11 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
17	R/W	0x0	DM11_M0_WT_AUT_CTRL Domain11 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
16	R/W	0x0	DM11_M0_RD_AUT_CTRL Domain11 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited
15:14	/	/	/
13	R/W	0x0	DM10_M6_WT_AUT_CTRL Domain10 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
12	R/W	0x0	DM10_M6_RD_AUT_CTRL Domain10 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited

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Offset: 0x00C4			Register Name: IOMMU_DM_AUT_CTRL5_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Note: The bit is not used.
11	R/W	0x0	DM10_M5_WT_AUT_CTRL Domain10 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
10	R/W	0x0	DM10_M5_RD_AUT_CTRL Domain10 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
9	R/W	0x0	DM10_M4_WT_AUT_CTRL Domain10 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
8	R/W	0x0	DM10_M4_RD_AUT_CTRL Domain10 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
7	R/W	0x0	DM10_M3_WT_AUT_CTRL Domain10 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
6	R/W	0x0	DM10_M3_RD_AUT_CTRL Domain10 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
5	R/W	0x0	DM10_M2_WT_AUT_CTRL Domain10 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
4	R/W	0x0	DM10_M2_RD_AUT_CTRL Domain10 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
3	R/W	0x0	DM10_M1_WT_AUT_CTRL Domain10 write permission control for master1 0: The write-operation is permitted

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Offset: 0x00C4			Register Name: IOMMU_DM_AUT_CTRL5_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: The write-operation is prohibited
2	R/W	0x0	DM10_M1_RD_AUT_CTRL Domain10 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
1	R/W	0x0	DM10_M0_WT_AUT_CTRL Domain10 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
0	R/W	0x0	DM10_M0_RD_AUT_CTRL Domain10 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited

3.11.6.29 0x00C8 IOMMU Domain Authority Control 6 Register (Default Value: 0x0000_0000)

Offset: 0x00C8			Register Name: IOMMU_DM_AUT_CTRL6_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29	R/W	0x0	DM13_M6_WT_AUT_CTRL Domain13 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited
28	R/W	0x0	DM13_M6_RD_AUT_CTRL Domain13 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited
27	R/W	0x0	DM13_M5_WT_AUT_CTRL Domain13 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
26	R/W	0x0	DM13_M5_RD_AUT_CTRL Domain13 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
25	R/W	0x0	DM13_M4_WT_AUT_CTRL

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Offset: 0x00C8			Register Name: IOMMU_DM_AUT_CTRL6_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Domain13 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
24	R/W	0x0	DM13_M4_RD_AUT_CTRL Domain13 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
23	R/W	0x0	DM13_M3_WT_AUT_CTRL Domain13 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
22	R/W	0x0	DM13_M3_RD_AUT_CTRL Domain13 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
21	R/W	0x0	DM13_M2_WT_AUT_CTRL Domain13 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
20	R/W	0x0	DM13_M2_RD_AUT_CTRL Domain13 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
19	R/W	0x0	DM13_M1_WT_AUT_CTRL Domain13 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
18	R/W	0x0	DM13_M1_RD_AUT_CTRL Domain13 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
17	R/W	0x0	DM13_M0_WT_AUT_CTRL Domain13 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
16	R/W	0x0	DM13_M0_RD_AUT_CTRL

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Offset: 0x00C8			Register Name: IOMMU_DM_AUT_CTRL6_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Domain13 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited
15:14	/	/	/
13	R/W	0x0	DM12_M6_WT_AUT_CTRL Domain12 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited
12	R/W	0x0	DM12_M6_RD_AUT_CTRL Domain12 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited
11	R/W	0x0	DM12_M5_WT_AUT_CTRL Domain12 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
10	R/W	0x0	DM12_M5_RD_AUT_CTRL Domain12 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
9	R/W	0x0	DM12_M4_WT_AUT_CTRL Domain12 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
8	R/W	0x0	DM12_M4_RD_AUT_CTRL Domain12 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
7	R/W	0x0	DM12_M3_WT_AUT_CTRL Domain12 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
6	R/W	0x0	DM12_M3_RD_AUT_CTRL Domain12 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited

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Offset: 0x00C8			Register Name: IOMMU_DM_AUT_CTRL6_REG
Bit	Read/Write	Default/Hex	Description
5	R/W	0x0	DM12_M2_WT_AUT_CTRL Domain12 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
4	R/W	0x0	DM12_M2_RD_AUT_CTRL Domain12 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
3	R/W	0x0	DM12_M1_WT_AUT_CTRL Domain12 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
2	R/W	0x0	DM12_M1_RD_AUT_CTRL Domain12 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
1	R/W	0x0	DM12_M0_WT_AUT_CTRL Domain12 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
0	R/W	0x0	DM12_M0_RD_AUT_CTRL Domain12 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited

3.11.6.30 0x00CC IOMMU Domain Authority Control 7 Register (Default Value: 0x0000_0000)

Offset: 0x00CC			Register Name: IOMMU_DM_AUT_CTRL7_REG
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29	R/W	0x0	DM15_M6_WT_AUT_CTRL Domain15 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
28	R/W	0x0	DM15_M6_RD_AUT_CTRL

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Offset: 0x00CC			Register Name: IOMMU_DM_AUT_CTRL7_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Domain15 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
27	R/W	0x0	DM15_M5_WT_AUT_CTRL Domain15 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
26	R/W	0x0	DM15_M5_RD_AUT_CTRL Domain15 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
25	R/W	0x0	DM15_M4_WT_AUT_CTRL Domain15 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
24	R/W	0x0	DM15_M4_RD_AUT_CTRL Domain15 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
23	R/W	0x0	DM15_M3_WT_AUT_CTRL Domain15 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
22	R/W	0x0	DM15_M3_RD_AUT_CTRL Domain15 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
21	R/W	0x0	DM15_M2_WT_AUT_CTRL Domain15 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
20	R/W	0x0	DM15_M2_RD_AUT_CTRL Domain15 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited

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Offset: 0x00CC			Register Name: IOMMU_DM_AUT_CTRL7_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
19	R/W	0x0	DM15_M1_WT_AUT_CTRL Domain15 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
18	R/W	0x0	DM15_M1_RD_AUT_CTRL Domain15 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
17	R/W	0x0	DM15_M0_WT_AUT_CTRL Domain15 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
16	R/W	0x0	DM15_M0_RD_AUT_CTRL Domain15 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited
15:14	/	/	/
13	R/W	0x0	DM14_M6_WT_AUT_CTRL Domain14 write permission control for master6 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
12	R/W	0x0	DM14_M6_RD_AUT_CTRL Domain14 read permission control for master6 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
11	R/W	0x0	DM14_M5_WT_AUT_CTRL Domain14 write permission control for master5 0: The write-operation is permitted 1: The write-operation is prohibited
10	R/W	0x0	DM14_M5_RD_AUT_CTRL Domain14 read permission control for master5 0: The read-operation is permitted 1: The read-operation is prohibited
9	R/W	0x0	DM14_M4_WT_AUT_CTRL

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Offset: 0x00CC			Register Name: IOMMU_DM_AUT_CTRL7_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Domain14 write permission control for master4 0: The write-operation is permitted 1: The write-operation is prohibited
8	R/W	0x0	DM14_M4_RD_AUT_CTRL Domain14 read permission control for master4 0: The read-operation is permitted 1: The read-operation is prohibited
7	R/W	0x0	DM14_M3_WT_AUT_CTRL Domain14 write permission control for master3 0: The write-operation is permitted 1: The write-operation is prohibited
6	R/W	0x0	DM14_M3_RD_AUT_CTRL Domain14 read permission control for master3 0: The read-operation is permitted 1: The read-operation is prohibited
5	R/W	0x0	DM14_M2_WT_AUT_CTRL Domain14 write permission control for master2 0: The write-operation is permitted 1: The write-operation is prohibited
4	R/W	0x0	DM14_M2_RD_AUT_CTRL Domain14 read permission control for master2 0: The read-operation is permitted 1: The read-operation is prohibited
3	R/W	0x0	DM14_M1_WT_AUT_CTRL Domain14 write permission control for master1 0: The write-operation is permitted 1: The write-operation is prohibited
2	R/W	0x0	DM14_M1_RD_AUT_CTRL Domain14 read permission control for master1 0: The read-operation is permitted 1: The read-operation is prohibited
1	R/W	0x0	DM14_M0_WT_AUT_CTRL Domain14 write permission control for master0 0: The write-operation is permitted 1: The write-operation is prohibited
0	R/W	0x0	DM14_M0_RD_AUT_CTRL

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Offset: 0x00CC			Register Name: IOMMU_DM_AUT_CTRL7_REG
Bit	Read/Write	Default/Hex	Description
			Domain14 read permission control for master0 0: The read-operation is permitted 1: The read-operation is prohibited

3.11.6.31 0x00D0 IOMMU Domain Authority Overwrite Register (Default Value: 0x0000_0000)

Setting the REG_ARD_OVWT can mask the Domain control defined by IOMMU_DM_AUT_CTRL_REG0–7. All the property of Level2 are covered by the property defined in REG_ARD_OVWT. Allow read and write for all by default.

Offset: 0x00D0			Register Name: IOMMU_DM_AUT_OVWT_REG
Bit	Read/Write	Default/Hex	Description
31	R/W	0x0	DM_AUT_OVWT_ENABLE Domain write/read permission overwrite enable 0: Disable 1: Enable
30:14	/	/	/
13	R/W	0x0	M6_WT_AUT_OVWT_CTRL Master6 write permission overwrite control 0: The write-operation is permitted 1: The write-operation is prohibited **Note: The bit is not used.**
12	R/W	0x0	M6_RD_AUT_OVWT_CTRL Master6 read permission overwrite control 0: The read-operation is permitted 1: The read-operation is prohibited **Note: The bit is not used.**
11	R/W	0x0	M5_WT_AUT_OVWT_CTRL Master5 write permission overwrite control 0: The write-operation is permitted 1: The write-operation is prohibited
10	R/W	0x0	M5_RD_AUT_OVWT_CTRL Master5 read permission overwrite control 0: The read-operation is permitted 1: The read-operation is prohibited
9	R/W	0x0	M4_WT_AUT_OVWT_CTRL Master5 write permission overwrite control

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Offset: 0x00D0			Register Name: IOMMU_DM_AUT_OVWT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			0: The write-operation is permitted 1: The write-operation is prohibited
8	R/W	0x0	M4_RD_AUT_OVWT_CTRL Master5 read permission overwrite control 0: The read-operation is permitted 1: The read-operation is prohibited
7	R/W	0x0	M3_WT_AUT_OVWT_CTRL Master3 write permission overwrite control 0: The write-operation is permitted 1: The write-operation is prohibited
6	R/W	0x0	M3_RD_AUT_OVWT_CTRL Master3 read permission overwrite control 0: The read-operation is permitted 1: The read-operation is prohibited
5	R/W	0x0	M2_WT_AUT_OVWT_CTRL Master2 write permission overwrite control 0: The write-operation is permitted 1: The write-operation is prohibited
4	R/W	0x0	M2_RD_AUT_OVWT_CTRL Master2 read permission overwrite control 0: The read-operation is permitted 1: The read-operation is prohibited
3	R/W	0x0	M1_WT_AUT_OVWT_CTRL Master1 write permission overwrite control 0: The write-operation is permitted 1: The write-operation is prohibited
2	R/W	0x0	M1_RD_AUT_OVWT_CTRL Master1 read permission overwrite control 0: The read-operation is permitted 1: The read-operation is prohibited
1	R/W	0x0	M0_WT_AUT_OVWT_CTRL Master0 write permission overwrite control 0: The write-operation is permitted 1: The write-operation is prohibited
0	R/W	0x0	M0_RD_AUT_OVWT_CTRL Master0 read permission overwrite control

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Offset: 0x00D0			Register Name: IOMMU_DM_AUT_OVWT_REG
Bit	Read/Write	Default/Hex	Description
			0: The read-operation is permitted 1: The read-operation is prohibited

3.11.6.32 0x0100 IOMMU Interrupt Enable Register (Default Value: 0x0000_0000)

Invalid page table and permission error can not make one device or multi-devices in system work normally.

Permission error usually happens in MicroTLB. The error generates interrupt and waits for processing through software.

Invalid page table usually happens in MacroTLB. The error can not influence the access of other devices. So the error page table needs go back the way it comes, but the error should not be written in each level TLB.

Offset: 0x0100			Register Name: IOMMU_INT_ENABLE_REG
Bit	Read/Write	Default/Hex	Description
31:21	/	/	/
20	R/W	0x0	DBG_PF_L2_IV_PT_EN. Debug or Prefetch Invalid Page Table Enable 0: Mask interrupt 1: Enable interrupt
19	R/W	0x0	DBG_PF_PC_IV_L1_PT_EN. Debug or Prefetch PTW Cache Invalid Level1 Page Table Enable 0: Mask interrupt 1: Enable interrupt
18	R/W	0x0	DBG_PF_DRAM_IV_L1_PT_EN. Debug or Prefetch DRAM Invalid Level1 Page Table Enable 0: Mask interrupt 1: Enable interrupt
17	R/W	0x0	L2_PAGE_TABLE_INVALID_EN Level2 page table invalid interrupt enable 0: Mask interrupt 1: Enable interrupt
16	R/W	0x0	L1_PAGE_TABLE_INVALID_EN Level1 page table invalid interrupt enable 0: Mask interrupt 1: Enable interrupt
15:7	/	/	/
6	R/W	0x0	MICRO_TLB6_INVALID_EN

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Offset: 0x0100			Register Name: IOMMU_INT_ENABLE_REG
Bit	Read/Write	Default/Hex	Description
			Micro TLB6 permission invalid interrupt enable 0: Mask interrupt 1: Enable interrupt
5	R/W	0x0	MICRO_TLB5_INVALID_EN Micro TLB5 permission invalid interrupt enable 0: Mask interrupt 1: Enable interrupt
4	R/W	0x0	MICRO_TLB4_INVALID_EN Micro TLB4 permission invalid interrupt enable 0: Mask interrupt 1: Enable interrupt
3	R/W	0x0	MICRO_TLB3_INVALID_EN Micro TLB3 permission invalid interrupt enable 0: Mask interrupt 1: Enable interrupt
2	R/W	0x0	MICRO_TLB2_INVALID_EN Micro TLB2 permission invalid interrupt enable 0: Mask interrupt 1: Enable interrupt
1	R/W	0x0	MICRO_TLB1_INVALID_EN Micro TLB1 permission invalid interrupt enable 0: Mask interrupt 1: Enable interrupt
0	R/W	0x0	MICRO_TLB0_INVALID_EN Micro TLB0 permission invalid interrupt enable 0: Mask interrupt 1: Enable interrupt

3.11.6.33 0x0104 IOMMU Interrupt Clear Register (Default Value: 0x0000_0000)

Offset: 0x0104			Register Name: IOMMU_INT_CLR_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17	W	0x0	L2_PAGE_TABLE_INVALID_CLR Level2 page table invalid interrupt clear bit 0: Invalid operation

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Offset: 0x0104			Register Name: IOMMU_INT_CLR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: Clear interrupt
16	W	0x0	L1_PAGE_TABLE_INVALID_CLR Level1 page table invalid interrupt clear bit 0: Invalid operation 1: Clear interrupt
15:7	/	/	/
6	W	0x0	MICRO_TLB6_INVALID_CLR Micro TLB6 permission invalid interrupt clear bit 0: Invalid operation 1: Clear interrupt **Note: The bit is not used.**
5	W	0x0	MICRO_TLB5_INVALID_CLR Micro TLB5 permission invalid interrupt clear bit 0: Invalid operation 1: Clear interrupt
4	W	0x0	MICRO_TLB4_INVALID_CLR Micro TLB4 permission invalid interrupt clear bit 0: Invalid operation 1: Clear interrupt
3	W	0x0	MICRO_TLB3_INVALID_CLR Micro TLB3 permission invalid interrupt clear bit 0: Invalid operation 1: Clear interrupt
2	W	0x0	MICRO_TLB2_INVALID_CLR Micro TLB2 permission invalid interrupt clear bit 0: Invalid operation 1: Clear interrupt
1	W	0x0	MICRO_TLB1_INVALID_CLR Micro TLB1 permission invalid interrupt clear bit 0: Invalid operation 1: Clear interrupt
0	W	0x0	MICRO_TLB0_INVALID_CLR Micro TLB0 permission invalid interrupt clear bit 0: Invalid operation 1: Clear interrupt

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3.11.6.34 0x0108 IOMMU Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0108			Register Name: IOMMU_INT_STA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R	0x0	L2_PAGE_TABLE_INVALID_STA Level2 page table invalid interrupt status bit 0: Interrupt does not happen or interrupt is cleared 1: Interrupt happens
16	R	0x0	L1_PAGE_TABLE_INVALID_STA Level1 page table invalid interrupt status bit 0: Interrupt does not happen or interrupt is cleared 1: Interrupt happens
15:7	/	/	/
6	R	0x0	MICRO_TLB6_INVALID_STA Micro TLB6 permission invalid interrupt status bit 0: Interrupt does not happen or interrupt is cleared 1: Interrupt happens **Note: The bit is not used.**
5	R	0x0	MICRO_TLB5_INVALID_STA Micro TLB5 permission invalid interrupt status bit 0: Interrupt does not happen or interrupt is cleared 1: Interrupt happens
4	R	0x0	MICRO_TLB4_INVALID_STA Micro TLB4 permission invalid interrupt status bit 0: Interrupt does not happen or interrupt is cleared 1: Interrupt happens
3	R	0x0	MICRO_TLB3_INVALID_STA Micro TLB3 permission invalid interrupt status bit 0: Interrupt does not happen or interrupt is cleared 1: Interrupt happens
2	R	0x0	MICRO_TLB2_INVALID_STA Micro TLB2 permission invalid interrupt status bit 0: Interrupt does not happen or interrupt is cleared 1: Interrupt happens
1	R	0x0	MICRO_TLB1_INVALID_STA Micro TLB1 permission invalid interrupt status bit 0: Interrupt does not happen or interrupt is cleared 1: Interrupt happens

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Offset: 0x0108			Register Name: IOMMU_INT_STA_REG
Bit	Read/Write	Default/Hex	Description
0	R	0x0	MICRO_TLB0_INVALID_STA Micro TLB0 permission invalid interrupt status bit 0: Interrupt does not happen or interrupt is cleared 1: Interrupt happens

3.11.6.35 0x0110 IOMMU Interrupt Error Address 0 Register (Default Value: 0x0000_0000)

Offset: 0x0110			Register Name: IOMMU_INT_ERR_ADDR0_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_ADDR0 Virtual address that caused Micro TLB0 to interrupt

3.11.6.36 0x0114 IOMMU Interrupt Error Address 1 Register (Default Value: 0x0000_0000)

Offset: 0x0114			Register Name: IOMMU_INT_ERR_ADDR1_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_ADDR1 Virtual address that caused Micro TLB1 to interrupt

3.11.6.37 0x0118 IOMMU Interrupt Error Address 2 Register (Default Value: 0x0000_0000)

Offset: 0x0118			Register Name: IOMMU_INT_ERR_ADDR2_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_ADDR2 Virtual address that caused Micro TLB2 to interrupt

3.11.6.38 0x011C IOMMU Interrupt Error Address 3 Register (Default Value: 0x0000_0000)

Offset: 0x011C			Register Name: IOMMU_INT_ERR_ADDR3_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_ADDR3 Virtual address that caused Micro TLB3 to interrupt

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3.11.6.39 0x0120 IOMMU Interrupt Error Address 4 Register (Default Value: 0x0000_0000)

Offset: 0x0120			Register Name: IOMMU_INT_ERR_ADDR4_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_ADDR4 Virtual address that caused Micro TLB4 to interrupt

3.11.6.40 0x0124 IOMMU Interrupt Error Address 5 Register (Default Value: 0x0000_0000)

Offset: 0x0124			Register Name: IOMMU_INT_ERR_ADDR5_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_ADDR5 Virtual address that caused Micro TLB5 to interrupt

3.11.6.41 0x0128 IOMMU Interrupt Error Address 6 Register (Default Value: 0x0000_0000)

Offset: 0x0128			Register Name: IOMMU_INT_ERR_ADDR6_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_ADDR6 Virtual address that caused Micro TLB6 to interrupt

3.11.6.42 0x0130 IOMMU Interrupt Error Address 7 Register (Default Value: 0x0000_0000)

Offset: 0x0130			Register Name: IOMMU_INT_ERR_ADDR7_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_ADDR7 Virtual address that caused L1 page table to interrupt

3.11.6.43 0x0134 IOMMU Interrupt Error Address 8 Register (Default Value: 0x0000_0000)

Offset: 0x0134			Register Name: IOMMU_INT_ERR_ADDR8_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_ADDR8 Virtual address that caused L2 page table to interrupt

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3.11.6.44 0x0150 IOMMU Interrupt Error Data 0 Register (Default Value: 0x0000_0000)

Offset: 0x0150			Register Name: IOMMU_INT_ERR_DATA0_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_DATA0 Corresponding page table of virtual address that caused Micro TLB0 to interrupt

3.11.6.45 0x0154 IOMMU Interrupt Error Data 1 Register (Default Value: 0x0000_0000)

Offset: 0x0154			Register Name: IOMMU_INT_ERR_DATA1_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_DATA1 Corresponding page table of virtual address that caused Micro TLB1 to interrupt

3.11.6.46 0x0158 IOMMU Interrupt Error Data 2 Register (Default Value: 0x0000_0000)

Offset: 0x0158			Register Name: IOMMU_INT_ERR_DATA2_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_DATA2 Corresponding page table of virtual address that caused Micro TLB2 to interrupt

3.11.6.47 0x015C IOMMU Interrupt Error Data 3 Register (Default Value: 0x0000_0000)

Offset: 0x015C			Register Name: IOMMU_INT_ERR_DATA3_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_DATA3 Corresponding page table of virtual address that caused Micro TLB3 to interrupt

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3.11.6.48 0x0160 IOMMU Interrupt Error Data 4 Register (Default Value: 0x0000_0000)

Offset: 0x0160			Register Name: IOMMU_INT_ERR_DATA4_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_DATA4 Corresponding page table of virtual address that caused Micro TLB4 to interrupt

3.11.6.49 0x0164 IOMMU Interrupt Error Data 5 Register (Default Value: 0x0000_0000)

Offset: 0x0164			Register Name: IOMMU_INT_ERR_DATA5_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_DATA5 Corresponding page table of virtual address that caused Micro TLB5 to interrupt

3.11.6.50 0x0168 IOMMU Interrupt Error Data 6 Register (Default Value: 0x0000_0000)

Offset: 0x0168			Register Name: IOMMU_INT_ERR_DATA6_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_DATA6 Corresponding page table of virtual address that caused Micro TLB6 to interrupt **Note: This field is not used.**

3.11.6.51 0x0170 IOMMU Interrupt Error Data 7 Register (Default Value: 0x0000_0000)

Offset: 0x0170			Register Name: IOMMU_INT_ERR_DATA7_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_DATA7 Corresponding page table of virtual address that caused L1 page table to interrupt

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3.11.6.52 0x0174 IOMMU Interrupt Error Data 8 Register (Default Value: 0x0000_0000)

Offset: 0x0174			Register Name: IOMMU_INT_ERR_DATA8_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	INT_ERR_DATA8 Corresponding page table of virtual address that caused L2 page table to interrupt

3.11.6.53 0x0180 IOMMU L1 Page Table Interrupt Register (Default Value: 0x0000_0000)

Offset: 0x0180			Register Name: IOMMU_L1PG_INT_REG
Bit	Read/Write	Default/Hex	Description
31	R	0x0	DBG_MODE_L1PG_INT Debug mode address switch causes L1 page table to occur interrupt.
30:7	/	/	/
6	R	0x0	MASTER6_L1PG_INT Master6 address switch causes L1 page table to occur interrupt. **Note: The bit is not used.**
5	R	0x0	MASTER5_L1PG_INT Master5 address switch causes L1 page table to occur interrupt.
4	R	0x0	MASTER4_L1PG_INT Master4 address switch causes L1 page table to occur interrupt.
3	R	0x0	MASTER3_L1PG_INT Master3 address switch causes L1 page table to occur interrupt.
2	R	0x0	MASTER2_L1PG_INT Master2 address switch causes L1 page table to occur interrupt.
1	R	0x0	MASTER1_L1PG_INT Master1 address switch causes L1 page table to occur interrupt.
0	R	0x0	MASTER0_L1PG_INT Master0 address switch causes L1 page table to occur interrupt.

3.11.6.54 0x0184 IOMMU L2 Page Table Interrupt Register (Default Value: 0x0000_0000)

Offset: 0x0184			Register Name: IOMMU_L2PG_INT_REG
Bit	Read/Write	Default/Hex	Description
31	R	0x0	DBG_MODE_L2PG_INT

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Offset: 0x0184			Register Name: IOMMU_L2PG_INT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Debug mode address switch causes L2 page table to occur interrupt.
30:7	/	/	/
6	R	0x0	MASTER6_L2PG_INT Master6 address switch causes L2 page table to occur interrupt. **Note: The bit is not used.**
5	R	0x0	MASTER5_L2PG_INT Master5 address switch causes L2 page table to occur interrupt.
4	R	0x0	MASTER4_L2PG_INT Master4 address switch causes L2 page table to occur interrupt.
3	R	0x0	MASTER3_L2PG_INT Master3 address switch causes L2 page table to occur interrupt.
2	R	0x0	MASTER2_L2PG_INT Master2 address switch causes L2 page table to occur interrupt.
1	R	0x0	MASTER1_L2PG_INT Master1 address switch causes L2 page table to occur interrupt.
0	R	0x0	MASTER0_L2PG_INT Master0 address switch causes L2 page table to occur interrupt.

3.11.6.55 0x0190 IOMMU Virtual Address Register (Default Value: 0x0000_0000)

Offset: 0x0190			Register Name: IOMMU_VA _REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	VA Virtual address of read/write

3.11.6.56 0x0194 IOMMU Virtual Address Data Register (Default Value: 0x0000_0000)

Offset: 0x0194			Register Name: IOMMU_VA_DATA _REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	VA_DATA Data corresponding to read/write virtual address

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3.11.6.57 0x0198 IOMMU Virtual Address Configuration Register (Default Value: 0x0000_0000)

Offset: 0x0198			Register Name: IOMMU_VA_CONFIG _REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	MODE_SEL 0: Prefetch 1: Debug Mode It is used to chose prefetch mode or Debug mode.
31:9	/	/	/
8	R/W	0x0	VA_CONFIG Virtual Address Configuration 0: Read operation 1: Write operation
7:1	/	/	/
0	R/WAC	0x0	VA_CONFIG_START 0: No operation or operation is completed 1: Start After the operation is completed, the bit can clear automatically.

Read operation process:

a) Write IOMMU_VA_REG[31:0];

b) Write IOMMU_VA_CONFIG_REG[8] to 0;

c) Write IOMMU_VA_CONFIG_REG[0] to 1 to start read-process;

d) Query IOMMU_VA_CONFIG_REG[0] until it is 0;

e) Read IOMMU_VA_DATA_REG[31:0];

Write operation process:

a) Write IOMMU_VA_REG[31:0];

b) Write IOMMU_VA_DATA_REG[31:0];

c) Write IOMMU_VA_CONFIG_REG[8] to 1;

d) Write IOMMU_VA_CONFIG_REG[0] to 1 to start write-process;

e) Query IOMMU_VA_CONFIG_REG[0] until it is 0;

3.11.6.58 0x0200 IOMMU PMU Enable Register (Default Value: 0x0000_0000)

Offset: 0x0200			Register Name: IOMMU_PMU_ENABLE _REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	PMU_ENABLE

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Offset: 0x0200			Register Name: IOMMU_PMU_ENABLE _REG
Bit	Read/Write	Default/Hex	Description
			0: Disable statistical function 1: Enable statistical function

3.11.6.59 0x0210 IOMMU PMU Clear Register (Default Value: 0x0000_0000)

Offset: 0x0210			Register Name: IOMMU_PMU_CLR _REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/WAC	0x0	PMU_CLR 0: No clear operation or clear operation is completed 1: Clear counter data After the operation is completed, the bit can clear automatically.

3.11.6.60 0x0230 IOMMU PMU Access Low 0 Register (Default Value: 0x0000_0000)

Offset: 0x0230			Register Name: IOMMU_PMU_ACCESS_LOW0_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ACCESS_LOW0 Record total number of Micro TLB0 access, lower 32-bit register

3.11.6.61 0x0234 IOMMU PMU Access High 0 Register (Default Value: 0x0000_0000)

Offset: 0x0234			Register Name: IOMMU_PMU_ACCESS_HIGH0_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_ACCESS_HIGH0 Record total number of Micro TLB0 access, higher 11-bit register

3.11.6.62 0x0238 IOMMU PMU Hit Low 0 Register (Default Value: 0x0000_0000)

Offset: 0x0238			Register Name: IOMMU_PMU_HIT_LOW0_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_HIT_LOW0

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Offset: 0x0238			Register Name: IOMMU_PMU_HIT_LOW0_REG
Bit	Read/Write	Default/Hex	Description
			Record total number of Micro TLB0 hit, lower 32-bit register

3.11.6.63 0x023C IOMMU PMU Hit High 0 Register (Default Value: 0x0000_0000)

Offset: 0x023C			Register Name: IOMMU_PMU_HIT_HIGH0_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_HIT_HIGH0 Record total number of Micro TLB0 hit, higher 11-bit register

3.11.6.64 0x0240 IOMMU PMU Access Low 1 Register (Default Value: 0x0000_0000)

Offset: 0x0240			Register Name: IOMMU_PMU_ACCESS_LOW1_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ACCESS_LOW1 Record total number of Micro TLB1 access, lower 32-bit register

3.11.6.65 0x0244 IOMMU PMU Access High 1 Register (Default Value: 0x0000_0000)

Offset: 0x0244			Register Name: IOMMU_PMU_ACCESS_HIGH1_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_ACCESS_HIGH1 Record total number of Micro TLB1 access, higher 11-bit register

3.11.6.66 0x0248 IOMMU PMU Hit Low 1 Register (Default Value: 0x0000_0000)

Offset: 0x0248			Register Name: IOMMU_PMU_HIT_LOW1_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_HIT_LOW1 Record total number of Micro TLB1 hit, lower 32-bit register

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3.11.6.67 0x024C IOMMU PMU Hit High 1 Register (Default Value: 0x0000_0000)

Offset: 0x024C			Register Name: IOMMU_PMU_HIT_HIGH1_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_HIT_HIGH1 Record total number of Micro TLB1 hit, higher 11-bit register

3.11.6.68 0x0250 IOMMU PMU Access Low 2 Register (Default Value: 0x0000_0000)

Offset: 0x0250			Register Name: IOMMU_PMU_ACCESS_LOW2_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ACCESS_LOW2 Record total number of Micro TLB2 access, lower 32-bit register

3.11.6.69 0x0254 IOMMU PMU Access High 2 Register (Default Value: 0x0000_0000)

Offset: 0x0254			Register Name: IOMMU_PMU_ACCESS_HIGH2_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_ACCESS_HIGH2 Record total number of Micro TLB2 access, higher 11-bit register

3.11.6.70 0x0258 IOMMU PMU Hit Low 2 Register (Default Value: 0x0000_0000)

Offset: 0x0258			Register Name: IOMMU_PMU_HIT_LOW2_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_HIT_LOW2 Record total number of Micro TLB2 hit, lower 32-bit register

3.11.6.71 0x025C IOMMU PMU Hit High 2 Register (Default Value: 0x0000_0000)

Offset: 0x025C			Register Name: IOMMU_PMU_HIT_HIGH2_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/

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Offset: 0x025C			Register Name: IOMMU_PMU_HIT_HIGH2_REG
Bit	Read/Write	Default/Hex	Description
10:0	R	0x0	PMU_HIT_HIGH2 Record total number of Micro TLB2 hit, higher 11-bit register

3.11.6.72 0x0260 IOMMU PMU Access Low 3 Register (Default Value: 0x0000_0000)

Offset: 0x0260			Register Name: IOMMU_PMU_ACCESS_LOW3_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ACCESS_LOW3 Record total number of Micro TLB3 access, lower 32-bit register

3.11.6.73 0x0264 IOMMU PMU Access High 3 Register (Default Value: 0x0000_0000)

Offset: 0x0264			Register Name: IOMMU_PMU_ACCESS_HIGH3_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_ACCESS_HIGH3 Record total number of Micro TLB3 access, higher 11-bit register

3.11.6.74 0x0268 IOMMU PMU Hit Low 3 Register (Default Value: 0x0000_0000)

Offset: 0x0268			Register Name: IOMMU_PMU_HIT_LOW3_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_HIT_LOW3 Record total number of Micro TLB3 hit, lower 32-bit register

3.11.6.75 0x026C IOMMU PMU Hit High 3 Register (Default Value: 0x0000_0000)

Offset: 0x026C			Register Name: IOMMU_PMU_HIT_HIGH3_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_HIT_HIGH3 Record total number of Micro TLB3 hit, higher 11-bit register

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3.11.6.76 0x0270 IOMMU PMU Access Low 4 Register (Default Value: 0x0000_0000)

Offset: 0x0270			Register Name: IOMMU_PMU_ACCESS_LOW4_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ACCESS_LOW4 Record total number of Micro TLB4 access, lower 32-bit register

3.11.6.77 0x0274 IOMMU PMU Access High 4 Register (Default Value: 0x0000_0000)

Offset: 0x0274			Register Name: IOMMU_PMU_ACCESS_HIGH4_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_ACCESS_HIGH4 Record total number of Micro TLB4 access, higher 11-bit register

3.11.6.78 0x0278 IOMMU PMU Hit Low 4 Register (Default Value: 0x0000_0000)

Offset: 0x0278			Register Name: IOMMU_PMU_HIT_LOW4_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_HIT_LOW4 Record total number of Micro TLB4 hit, lower 32-bit register

3.11.6.79 0x027C IOMMU PMU Hit High 4 Register (Default Value: 0x0000_0000)

Offset: 0x027C			Register Name: IOMMU_PMU_HIT_HIGH4_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_HIT_HIGH4 Record total number of Micro TLB4 hit, higher 11-bit register

3.11.6.80 0x0280 IOMMU PMU Access Low 5 Register (Default Value: 0x0000_0000)

Offset: 0x0280			Register Name: IOMMU_PMU_ACCESS_LOW5_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ACCESS_LOW5 Record total number of Micro TLB5 access, lower 32-bit register

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3.11.6.81 0x0284 IOMMU PMU Access High 5 Register (Default Value: 0x0000_0000)

Offset: 0x0284			Register Name: IOMMU_PMU_ACCESS_HIGH5_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_ACCESS_HIGH5 Record total number of Micro TLB5 access, higher 11-bit register

3.11.6.82 0x0288 IOMMU PMU Hit Low 5 Register (Default Value: 0x0000_0000)

Offset: 0x0288			Register Name: IOMMU_PMU_HIT_LOW5_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_HIT_LOW5 Record total number of Micro TLB5 hit, lower 32-bit register

3.11.6.83 0x028C IOMMU PMU Hit High 5 Register (Default Value: 0x0000_0000)

Offset: 0x028C			Register Name: IOMMU_PMU_HIT_HIGH5_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_HIT_HIGH5 Record total number of Micro TLB5 hit, higher 11-bit register

3.11.6.84 0x0290 IOMMU PMU Access Low 6 Register (Default Value: 0x0000_0000)

Offset: 0x0290			Register Name: IOMMU_PMU_ACCESS_LOW6_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ACCESS_LOW6 Record total number of Micro TLB6 access, lower 32-bit register **Note: The field is not used.**

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3.11.6.85 0x0294 IOMMU PMU Access High 6 Register (Default Value: 0x0000_0000)

Offset: 0x0294			Register Name: IOMMU_PMU_ACCESS_HIGH6_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_ACCESS_HIGH6 Record total number of Micro TLB6 access, higher 11-bit register **Note: The field is not used.**

3.11.6.86 0x0298 IOMMU PMU Hit Low 6 Register (Default Value: 0x0000_0000)

Offset: 0x0298			Register Name: IOMMU_PMU_HIT_LOW6_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_HIT_LOW6 Record total number of Micro TLB6 hit, lower 32-bit register **Note: The field is not used.**

3.11.6.87 0x029C IOMMU PMU Hit High 6 Register (Default Value: 0x0000_0000)

Offset: 0x029C			Register Name: IOMMU_PMU_HIT_HIGH6_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_HIT_HIGH6 Record total number of Micro TLB6 hit, higher 11-bit register **Note: The field is not used.**

3.11.6.88 0x02D0 IOMMU PMU Access Low 7 Register (Default Value: 0x0000_0000)

Offset: 0x02D0			Register Name: IOMMU_PMU_ACCESS_LOW7_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ACCESS_LOW7 Record total number of Micro TLB7 access, lower 32-bit register

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3.11.6.89 0x02D4 IOMMU PMU Access High 7 Register (Default Value: 0x0000_0000)

Offset: 0x02D4			Register Name: IOMMU_PMU_ACCESS_HIGH7_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_ACCESS_HIGH7 Record total number of Micro TLB7 access, higher 11-bit register

3.11.6.90 0x02D8 IOMMU PMU Hit Low 7 Register (Default Value: 0x0000_0000)

Offset: 0x02D8			Register Name: IOMMU_PMU_HIT_LOW7_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_HIT_LOW7 Record total number of Micro TLB7 hit, lower 32-bit register

3.11.6.91 0x02DC IOMMU PMU Hit High 7 Register (Default Value: 0x0000_0000)

Offset: 0x02DC			Register Name: IOMMU_PMU_HIT_HIGH7_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_HIT_HIGH7 Record total number of Micro TLB7 hit, higher 11-bit register

3.11.6.92 0x02E0 IOMMU PMU Access Low 8 Register (Default Value: 0x0000_0000)

Offset: 0x02E0			Register Name: IOMMU_PMU_ACCESS_LOW8_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ACCESS_LOW8 Record total number of PTW Cache access, lower 32-bit register

3.11.6.93 0x02E4 IOMMU PMU Access High 8 Register (Default Value: 0x0000_0000)

Offset: 0x02E4			Register Name: IOMMU_PMU_ACCESS_HIGH8_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/

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Offset: 0x02E4			Register Name: IOMMU_PMU_ACCESS_HIGH8_REG
Bit	Read/Write	Default/Hex	Description
10:0	R	0x0	PMU_ACCESS_HIGH8 Record total number of PTW Cache access, higher 11-bit register

3.11.6.94 0x02E8 IOMMU PMU Hit Low 8 Register (Default Value: 0x0000_0000)

Offset: 0x02E8			Register Name: IOMMU_PMU_HIT_LOW8_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_HIT_LOW8 Record total number of PTW Cache hit, lower 32-bit register

3.11.6.95 0x02EC IOMMU PMU Hit High 8 Register (Default Value: 0x0000_0000)

Offset: 0x02EC			Register Name: IOMMU_PMU_HIT_HIGH8_REG
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R	0x0	PMU_HIT_HIGH8 Record total number of PTW Cache hit, higher 11-bit register

3.11.6.96 0x0300 IOMMU Total Latency Low 0 Register (Default Value: 0x0000_0000)

Offset: 0x0300			Register Name: IOMMU_PMU_TL_LOW0_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_TL_LOW0 Record total latency of Master0, lower 32-bit register

3.11.6.97 0x0304 IOMMU Total Latency High 0 Register (Default Value: 0x0000_0000)

Offset: 0x0304			Register Name: IOMMU_PMU_TL_HIGH0_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17:0	R	0x0	PMU_TL_HIGH0 Record total latency of Master0, higher 18-bit register

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3.11.6.98 0x0308 IOMMU Max Latency 0 Register (Default Value: 0x0000_0000)

Offset: 0x0308			Register Name: IOMMU_PMU_ML0_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ML0 Record the max latency of Master0.

3.11.6.99 0x0310 IOMMU Total Latency Low 1 Register (Default Value: 0x0000_0000)

Offset: 0x0310			Register Name: IOMMU_PMU_TL_LOW1_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_TL_LOW1 Record total latency of Master1, lower 32-bit register

3.11.6.100 0x0314 IOMMU Total Latency High 1 Register (Default Value: 0x0000_0000)

Offset: 0x0314			Register Name: IOMMU_PMU_TL_HIGH1_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17:0	R	0x0	PMU_TL_HIGH1 Record total latency of Master1, higher 18-bit register

3.11.6.101 0x0318 IOMMU Max Latency 1 Register (Default Value: 0x0000_0000)

Offset: 0x0318			Register Name: IOMMU_PMU_ML1_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ML1 Record the max latency of Master1.

3.11.6.102 0x0320 IOMMU Total Latency Low 2 Register (Default Value: 0x0000_0000)

Offset: 0x0320			Register Name: IOMMU_PMU_TL_LOW2_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_TL_LOW2 Record total latency of Master2, lower 32-bit register

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3.11.6.103 0x0324 IOMMU Total Latency High 2 Register (Default Value: 0x0000_0000)

Offset: 0x0324			Register Name: IOMMU_PMU_TL_HIGH2_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17:0	R	0x0	PMU_TL_HIGH2 Record total latency of Master2, higher 18-bit register

3.11.6.104 0x0328 IOMMU Max Latency 2 Register (Default Value: 0x0000_0000)

Offset: 0x0328			Register Name: IOMMU_PMU_ML2_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ML2 Record the max latency of Master2.

3.11.6.105 0x0330 IOMMU Total Latency Low 3 Register (Default Value: 0x0000_0000)

Offset: 0x0330			Register Name: IOMMU_PMU_TL_LOW3_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_TL_LOW3 Record total latency of Master3, lower 32-bit register

3.11.6.106 0x0334 IOMMU Total Latency High 3 Register (Default Value: 0x0000_0000)

Offset: 0x0334			Register Name: IOMMU_PMU_TL_HIGH3_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17:0	R	0x0	PMU_TL_HIGH3 Record total latency of Master3, higher 18-bit register

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3.11.6.107 0x0338 IOMMU Max Latency 3 Register (Default Value: 0x0000_0000)

Offset: 0x0338			Register Name: IOMMU_PMU_ML3_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ML3 Record the max latency of Master3.

3.11.6.108 0x0340 IOMMU Total Latency Low 4 Register (Default Value: 0x0000_0000)

Offset: 0x0340			Register Name: IOMMU_PMU_TL_LOW4_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_TL_LOW4 Record total latency of Master4, lower 32-bit register

3.11.6.109 0x0344 IOMMU Total Latency High 4 Register (Default Value: 0x0000_0000)

Offset: 0x0344			Register Name: IOMMU_PMU_TL_HIGH4_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17:0	R	0x0	PMU_TL_HIGH4 Record total latency of Master4, higher 18-bit register

3.11.6.110 0x0348 IOMMU Max Latency 4 Register (Default Value: 0x0000_0000)

Offset: 0x0348			Register Name: IOMMU_PMU_ML4_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ML4 Record the max latency of Master4.

3.11.6.111 0x0350 IOMMU Total Latency Low 5 Register (Default Value: 0x0000_0000)

Offset: 0x0350			Register Name: IOMMU_PMU_TL_LOW5_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_TL_LOW5 Record total latency of Master5, lower 32-bit register

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3.11.6.112 0x0354 IOMMU Total Latency High 5 Register (Default Value: 0x0000_0000)

Offset: 0x0354			Register Name: IOMMU_PMU_TL_HIGH5_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17:0	R	0x0	PMU_TL_HIGH5 Record total latency of Master5, higher 18-bit register

3.11.6.113 0x0358 IOMMU Max Latency 5 Register (Default Value: 0x0000_0000)

Offset: 0x0358			Register Name: IOMMU_PMU_ML5_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_ML5 Record the max latency of Master5.

3.11.6.114 0x0360 IOMMU Total Latency Low 6 Register (Default Value: 0x0000_0000)

Offset: 0x0360			Register Name: IOMMU_PMU_TL_LOW6_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	PMU_TL_LOW6 Record total latency of Master6, lower 32-bit register **Note: The field is not used.**

3.11.6.115 0x0364 IOMMU Total Latency High 6 Register (Default Value: 0x0000_0000)

Offset: 0x0364			Register Name: IOMMU_PMU_TL_HIGH6_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17:0	R	0x0	PMU_TL_HIGH6 Record total latency of Master6, higher 18-bit register **Note: The field is not used.**

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3.11.6.116 0x0368 IOMMU Max Latency 6 Register (Default Value: 0x0000_0000)

Offset: 0x0368			Register Name: IOMMU_PMU_ML6_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	PMU_ML6 Record the max latency of Master6. **Note: The field is not used.**

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3.12 Message Box

3.12.1 Overview

The Message Box (MSGBOX) provides interrupt communication mechanism for on-chip processor.

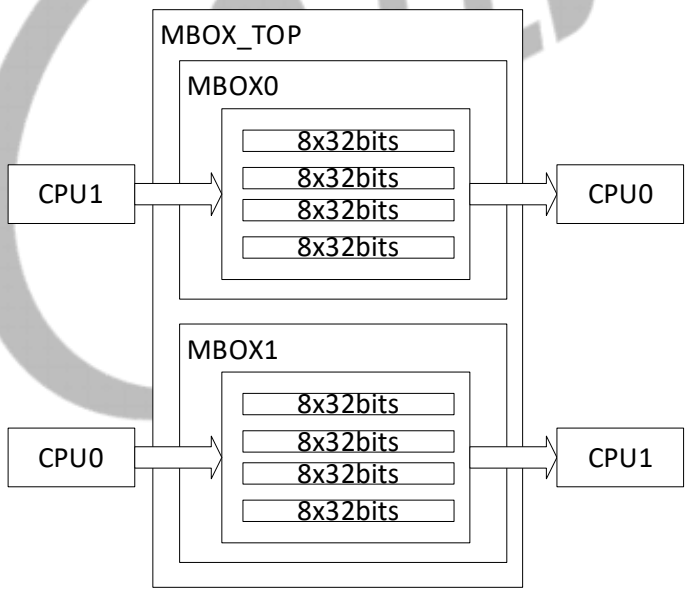
The MSGBOX has the following features:

- Supports 2 CPU to transmit information through channels. Each CPU has a MSGBOX.
  - CPU 0: ARM CPUX
  - CPU 1: DSP
- The channel between two CPU has 4 channels, and the FIFO depth of a channel is 8 x 32 bits
- Supports interrupts

3.12.2 Block Diagram

The following figure shows the block diagram of the message box.

Figure 3-36 Message Box Block Diagram



For MSGBOX0, CPU1: write; CPU0: read
For MSGBOX1, CPU0: write; CPU1: read

Each CPU has 4 channels. The two channels can be configured to be secure by software, the other two channels can be configured to be non-secure by software. The two secure channels or two non-secure channels can be configured as one synchronous box (Sending a message requires a response) or one asynchronous box (Sending a message does not require a response).

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3.12.3 Functional Description

3.12.3.1 Clock and Reset

The MSGBOX is mounted on AHB0. Before accessing the MSGBOX registers, you need to de-assert the MSGBOX reset signal on AHB0 bus and then open the MSGBOX gating signal on AHB0 bus.

3.12.3.2 Typical Application

Several masters can build communication by configuring the MSGBOX. The communication parties have 4 channels. In a channel, the user1 is fixed as the transmitter and the user0 is fixed as the receiver. During the communication process, the current status can be judged through the interrupt or FIFO status.

3.12.3.3 Transmitter/Receiver Mode

At the same channel, user1 is fixed as transmitter, user0 is fixed as receiver.

3.12.3.4 Interrupt

Each channel can configure indepedently the interrupt enable bit, a read interrupt will be generated when the channel is empty, a write interrupt will be generated when the channel is non-full. For each CPU, all channels generate a read interrupt together, that is, if only a channel is non-full, the read interrupt will be generated, this channel can be obtained by quering the interrupt status register.

3.12.3.5 FIFO Status

When channel FIFO is non-full, the FIFO_FULL_FLAG is 0, at the moment the FIFO can be written.

When channel FIFO is full, the FIFO_FULL_FLAG is 1, at the moment if FIFO is written again, the first data of FIFO can be covered.

See **MSGBOX_MSG_STATUS_REG** for FIFO status.

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3.12.4 Programming Guidelines

3.12.4.1 Checking the Transfer Status via the Interrupt

Follow the steps below to check the transfer status:

Step 1 Enable the interrupt for the channel: Configure the interrupt enable bits of transmitter/receiver through MSGBOX_WR_IRQ_EN_REG/MSGBOX_RD_IRQ_EN_REG. (user0: RX interrupt enable; user1: TX interrupt enable)

Step 2 Check the IRQ status of the corresponding queue through MSGBOX_WR_IRQ_STATUS_REG/MSGBOX_RD_IRQ_STATUS_REG.

- If the FIFO is not full, the channel generates a transmission interrupt to remind the transmitter to transmit data. Write data to the FIFO in the interrupt handler, then clear the pending bit of the transmitter in MSGBOX_WR_IRQ_STATUS_REG and the enable bit of the transmitter in MSGBOX_WR_IRQ_EN_REG.
- If the FIFO has new data, the channel generates a reception interrupt to remind the receiver to receive data. Read data from the FIFO in interrupt handler, then clear the pending bit of the receiver in MSGBOX_RD_IRQ_STATUS_REG and the enable bit of the receiver in MSGBOX_RD_IRQ_EN_REG.

3.12.4.2 Checking the Transfer Status via the FIFO

Follow the steps below to check the FIFO status of the corresponding queue:

- If the FIFO is not full, the transmitter fills the FIFO to 8*32 bits.
- If the FIFO is full, the receiver reads the FIFO data, and reads MSGBOX_FIFO_STATUS_REG to acquire the current FIFO data amount and the FIFO data amount before reading, which means no data is dropped.

3.12.4.3 Transmitting/Receiving Message

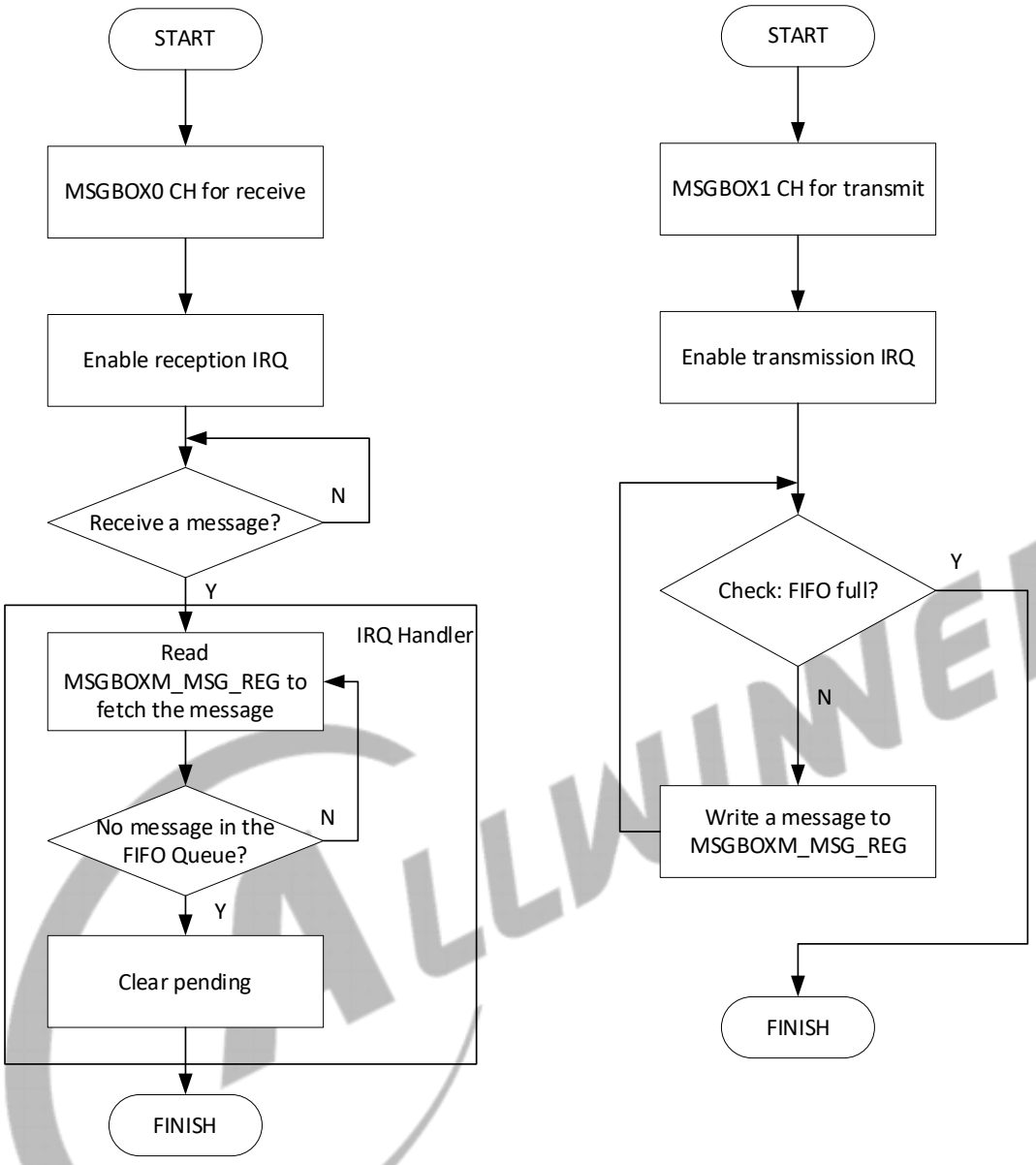
The following figure shows the communication process between MSGBOX0 and MSGBOX1.

MSGBOX0: receiving message

MSGBOX1: transmitting message

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Figure 3-37 The Communication Process between MSGBOX0 and MSGBOX1



3.12.5 Register List

Module Name	Base Address
ARM CPUX_MSGBOX	0x03003000
DSP_MSGBOX	0x01701000

Symbol	Description	Value
N	The CPU numbers that communicates with the current CPU	0–1
P	The channel numbers between two communication CPU	0–3

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MSGBOX	CPU	The Value of N
MSGBOX (ARM CPUX)	DSP -> ARM CPUX	N=0
MSGBOX (DSP)	ARM CPUX -> DSP	N=0

Register Name	Offset	Description
MSGBOX_RD_IRQ_EN_REG	0x0020+N*0x0100 (N=0–1)	MSGBOX Read IRQ Enable Register
MSGBOX_RD_IRQ_STATUS_REG	0x0024+N*0x0100 (N=0–1)	MSGBOX Read IRQ Status Register
MSGBOX_WR_IRQ_EN_REG	0x0030+N*0x0100 (N=0–1)	MSGBOX Write IRQ Enable Register
MSGBOX_WR_IRQ_STATUS_REG	0x0034+N*0x0100 (N=0–1)	MSGBOX Write IRQ Status Register
MSGBOX_DEBUG_REG	0x0040+N*0x0100 (N=0–1)	MSGBOX Debug Register
MSGBOX_FIFO_STATUS_REG	0x0050+N*0x0100+P*0x0004 (N=0–1)(P=0–3)	MSGBOX FIFO Status Register
MSGBOX_MSG_STATUS_REG	0x0060+N*0x0100+P*0x0004 (N=0–1)(P=0–3)	MSGBOX Message Status Register
MSGBOX_MSG_REG	0x0070+N*0x0100+P*0x0004 (N=0–1)(P=0–3)	MSGBOX Message Queue Register
MSGBOX_WR_INT_THRESHOLD_REG	0x0080+N*0x0100+P*0x0004 (N=0–1)(P=0–3)	MSGBOX Write IRQ Threshold Register

3.12.6 Register Description

3.12.6.1 0x0020 + N*0x0100 MSGBox Read IRQ Enable Register (Default Value: 0x0000_0000)

Offset: 0x0020 + N*0x0100 (N=0–1)			Register Name: MSGBOX_RD_IRQ_EN_REG
Bit	Read/Write	Default/Hex	Description
31:7	/	/	/

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Offset: 0x0020 + N*0x0100 (N=0–1)			Register Name: MSGBOX_RD_IRQ_EN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
6	R/W	0x0	RECEPTION_MQ3_IRQ_EN Reception Channel3 Interrupt Enable 0: Disable 1: Enable (It notifies user 0 by interrupt when Message Queue 3 received a new message.)
5	/	/	/
4	R/W	0x0	RECEPTION_MQ2_IRQ_EN Reception Channel2 Interrupt Enable 0: Disable 1: Enable (It notifies user 0 by interrupt when Message Queue 2 received a new message.)
3	/	/	/
2	R/W	0x0	RECEPTION_MQ1_IRQ_EN Reception Channel1 Interrupt Enable 0: Disable 1: Enable (It notifies user 0 by interrupt when Message Queue 1 received a new message.)
1	/	/	/
0	R/W	0x0	RECEPTION_MQ0_IRQ_EN Reception Channel0 Interrupt Enable 0: Disable 1: Enable (It notifies user 0 by interrupt when Message Queue 0 received a new message.)

3.12.6.2 0x0024 + N*0x0100 MSGBox Read IRQ Status Register (Default Value: 0x0000_0000)

Offset: 0x0024 + N*0x0100 (N=0–1)			Register Name: MSGBOX_RD_IRQ_STATUS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6	R/W1C	0x0	RECEPTION_MQ3_IRQ_PEND 0: No effect 1: Pending. This bit will be pending for user 0 when Message Queue 3 received a new message. Setting 1 to this bit clears it.
5	/	/	/

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Offset: 0x0024 + N*0x0100 (N=0–1)			Register Name: MSGBOX_RD_IRQ_STATUS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W1C	0x0	RECEPTION_MQ2_IRQ_PEND 0: No effect 1: Pending. This bit will be pending for user 0 when Message Queue 2 received a new message. Setting 1 to this bit clears it.
3	/	/	/
2	R/W1C	0x0	RECEPTION_MQ1_IRQ_PEND 0: No effect 1: Pending. This bit will be pending for user 0 when Message Queue 1 received a new message. Setting 1 to this bit clears it.
1	/	/	/
0	R/W1C	0x0	RECEPTION_MQ0_IRQ_PEND 0: No effect 1: Pending. This bit will be pending for user 0 when Message Queue 0 received a new message. Setting 1 to this bit clears it.

3.12.6.3 0x0030 + N*0x0100 MSGBox Write IRQ Enable Register (Default Value: 0x0000_0000)

Offset: 0x0030 + N*0x0100 (N=0–1)			Register Name: MSGBOX_WR_IRQ_EN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	TRANSMIT_MQ3_IRQ_EN 0: Disable 1: Enable (It notifies user 1 by interrupt when Message Queue 3 empty level reaches the configured threshold.)
6	/	/	/
5	R/W	0x0	TRANSMIT_MQ2_IRQ_EN 0: Disable 1: Enable (It notifies user 1 by interrupt when Message Queue 2 empty level reaches the configured threshold.)
4	/	/	/
3	R/W	0x0	TRANSMIT_MQ1_IRQ_EN 0: Disable 1: Enable (It notifies user 1 by interrupt when Message Queue 1 empty level reaches the configured threshold.)
2	/	/	/

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Offset: 0x0030 + N*0x0100 (N=0–1)			Register Name: MSGBOX_WR_IRQ_EN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	TRANSMIT_MQ0_IRQ_EN 0: Disable 1: Enable (It notifies user 1 by interrupt when Message Queue 0 empty level reaches the configured threshold.)
0	/	/	/

3.12.6.4 0x0034 + N*0x0100 MSGBox Write IRQ Status Register (Default Value: 0x0000_0000)

Offset: 0x0034 + N*0x0100 (N=0–1)			Register Name: MSGBOX_WR_IRQ_STATUS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W1C	0x0	TRANSMIT_MQ3_IRQ_PEND 0: No effect 1: Pending. This bit will be pending for user 1 when Message Queue 3 empty level reaches the configured threshold. Setting 1 to this bit clears it.
6	/	/	/
5	R/W1C	0x0	TRANSMIT_MQ2_IRQ_PEND 0: No effect 1: Pending. This bit will be pending for user 1 when Message Queue 2 empty level reaches the configured threshold. Setting 1 to this bit clears it.
4	/	/	/
3	R/W1C	0x0	TRANSMIT_MQ1_IRQ_PEND 0: No effect 1: Pending. This bit will be pending for user 1 when Message Queue 1 empty level reaches the configured threshold. Setting 1 to this bit clears it.
2	/	/	/
1	R/W1C	0x0	TRANSMIT_MQ0_IRQ_PEND 0: No effect 1: Pending. This bit will be pending for user 1 when Message Queue 0 empty level reaches the configured threshold. Setting 1 to this bit clears it.
0	/	/	/

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3.12.6.5 0x0050+N*0x0100+P*0x0004 MSGBox FIFO Status Register (Default Value: 0x0000_0000)

Offset: 0x0050+N*0x0100+P*0x0004 (N=0–1)(P=0–3)			Register Name: MSGBOX_FIFO_STATUS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31: 1	/	/	/
0	R	0x0	FIFO_NOT_AVA_FLAG FIFO is not available flag 0: The Message FIFO queue empty level reaches the configured threshold 1: The Message FIFO queue empty level does not reach the configured threshold This FIFO status register has the status related to the message queue.

3.12.6.6 0x0060+N*0x0100+P*0x0004 MSGBox Message Status Register m (Default Value: 0x0000_0000)

Offset: 0x0060+N*0x0100+P*0x0004 (N=0–1)(P=0–3)			Register Name: MSGBOX_MSG_STATUS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3:0	R	0x0	MSG_NUM Message Number Number of unread messages in the message queue. Here, limited to eight messages per message queue. 0000: There is no message in the message FIFO queue. 0001: There is 1 message in the message FIFO queue. 0010: There are 2 messages in the message FIFO queue. 0011: There are 3 messages in the message FIFO queue. 0100: There are 4 messages in the message FIFO queue. 0101: There are 5 messages in the message FIFO queue. 0110: There are 6 messages in the message FIFO queue. 0111: There are 7 messages in the message FIFO queue. 1000: There are 8 messages in the message FIFO queue. 1001~1111:/

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3.12.6.7 0x0070+N*0x0100+P*0x0004 MSGBox Message Queue Register (Default Value: 0x0000_0000)

Offset: 0x0070+N*0x0100+P*0x0004 (N=0–1)(P=0–3)			Register Name: MSGBOX_MSG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	MSG_QUE The message register stores the next to be read message of the message FIFO queue.

3.12.6.8 0x0080+N*0x0100+P*0x0004 MSGBox Write IRQ Threshold Register (Default Value: 0x0000_0000)

Offset: 0x0080+N*0x0100+P*0x0004 (N=0–1)(P=0–3)			Register Name: MSGBOX_WR_INT_THRESHOLD_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1:0	R/W	0x0	MSG_WR_INT_THRESHOLD_CFG Configure the FIFO empty level to trigger the write interrupt for user1 00: 1 01: 2 10: 4 11: 8

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3.13 Spinlock

3.13.1 Overview

The spinlock provides hardware synchronization mechanism in multi-core systems. With the lock operation, the spinlock prevents multiple processors from handling the sharing data simultaneously and thus ensure the coherence of data.

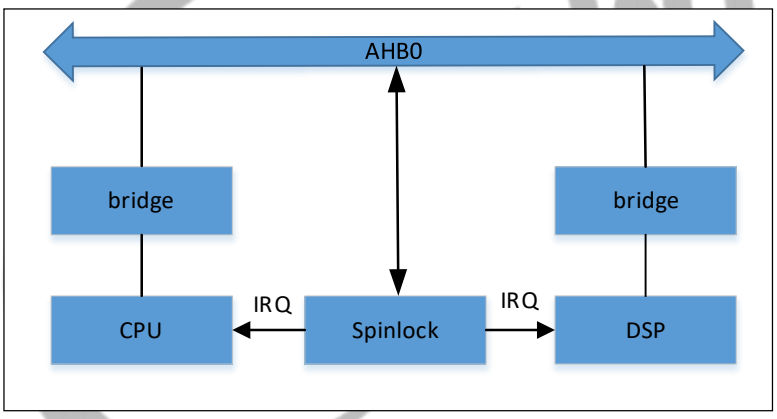
The spinlock has the following features:

- Supports 32 lock units
- Two kinds of lock status: locked and unlocked
- Lock time of the processor is predictable (less than 200 cycles)

3.13.2 Block Diagram

The following figure shows the block diagram of the spinlock.

Figure 3-38 Spinlock Block Diagram



3.13.3 Functional Description

3.13.3.1 Clock and Reset

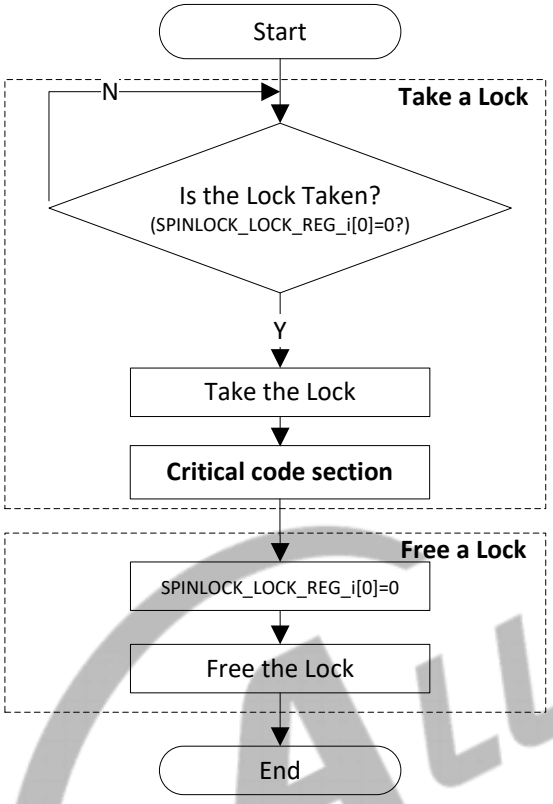
The spinlock is mounted on AHB0. Before accessing the spinlock registers, you need to de-assert the reset signal on AHB0 bus and then open the corresponding gating signal on AHB0 bus.

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3.13.3.2 Typical Application

The following figure shows a typical application of the spinlock. A processor locks spinlock0 before executing specific codes, and then unlocks the codes. After the lock is freed, other processors can read or write the data.

Figure 3-39 Spinlock Typical Application Diagram



3.13.3.3 Spinlock State Machine

When a processor uses spinlock, it needs to acquire the spinlock status through **SPINLOCK_STATUS_REG**.

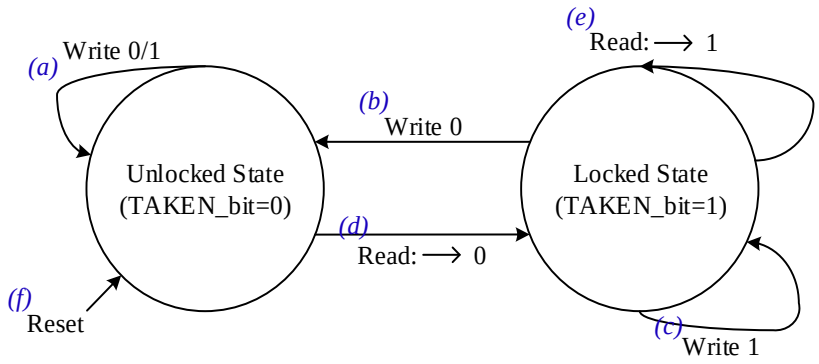
Reading operation: when the return value is 0, it indicates that the spinlock enters the locked status; reading this status bit again can return 1, it indicates that the spinlock is the locked status.

Writing operation: when the spinlock is in the locked status, writing 0 can convert the spinlock to the unlocked status, the writing operation for other status is invalid.

The following figure shows the spinlock state machine.

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Figure 3-40 Spinlock State Machine



a) When the spinlock is in the unlocked state, writing 0/1 has no effect;

b) When the spinlock is in the locked state, writing 0 can convert the corresponding spinlock to the unlocked state;

c) When the spinlock is in the locked state, writing 1 has no effect;

d) When the spinlock is in the unlocked state, reading the bit can return 0 (it indicates spinlock enters into the locked state);

e) When the spinlock is in the locked state, reading the bit can return 1 (it indicates spinlock is in the locked state);

f) After reset, the spinlock is in the unlock state by default.

3.13.4 Programming Guidelines

3.13.4.1 Switching the Status

Follow the steps below to switch the lock status of a spinlock.

Step 1 When the read value from **SPINLOCKN_LOCK_REG (N=0–31)** is 0, the spinlock comes into the locked status.

Step 2 Execute the application codes, and the status of **SPINLOCK_STATUS_REG** is 1.

Step 3 Write 0 to **SPINLOCKN_LOCK_REG (N=0–31)**, the spinlock converts into the unlocked status, and the corresponding spinlock is released.

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3.13.4.2 Processing the Interrupt

The spinlock generates an interrupt when a lock is freed (the lock status converts from the locked status to the unlocked status).

Follow the steps below to process the interrupt:

Step 1 Configure the interrupt enable bit of the corresponding spinlock in **SPINLOCK_IRQ_EN_REG** to enable the interrupt.

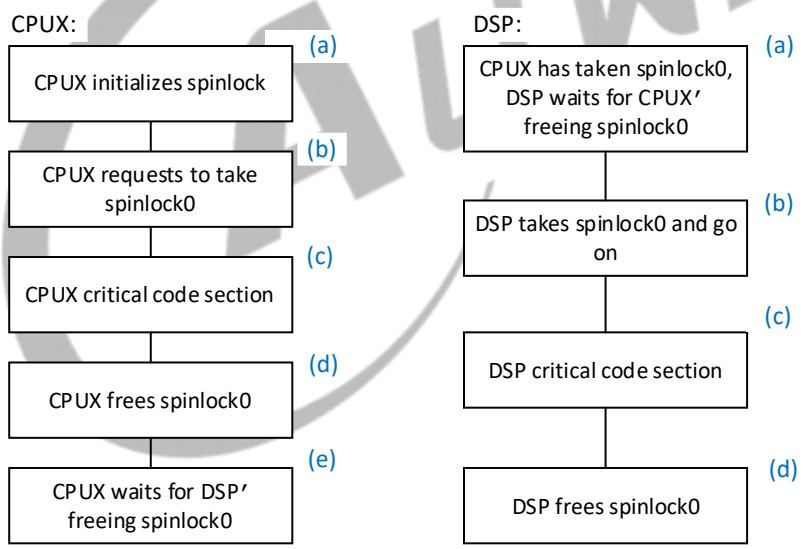
Step 2 The spinlock generates an interrupt when its status converts from the locked status to the unlocked status, and the corresponding bit of the **SPINLOCK_IRQ_STA_REG** turns to 1.

Step 3 Execute the interrupt handle function and clear the pending bit.

3.13.4.3 Taking/Freeing Spinlock

Take the synchronization between CPUX and DSP with Spinlock0 as an example, the CPUX and DSP perform the following steps.

Figure 3-41 CPUX and DSP Taking/Freeing Spinlock0 Process



CPUX:

(a) The CPUX initializes Spinlock.

(b) Check lock register0 (SPINLOCK_STATUS_REG0) status. If it is taken, check until CPUX frees spinlock0 and then request to take spinlock0. Otherwise, retry until the lock register0 is taken.

(c) Execute CPUX critical code.

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(d) After executing CPUX critical code, the CPUX frees spinlock0.

(e) The CPUX waits for DSP to free spinlock0.

DSP:

(a) If the CPUX has taken spinlock0, the DSP waits for CPUX to free spinlock0.

(b) The DSP requests to take spinlock0. If it fails, retry until the lock register0 is taken.

(c) Execute DSP critical code.

(d) After executing DSP critical code, the DSP frees spinlock0.

The following codes are for reference.

----------**CPUX**----------

Step 1 CPUX initializes Spinlock

```
put_wvalue(SPINLOCK_BGR_REG,0x00010000);
put_wvalue(SPINLOCK_BGR_REG,0x00010001);
```

Step 2 CPUX requests to take spinlock0

```
rdata=readl(SPINLOCK_STATUS_REG0);              //Check lock register0 status
if(rdata != 0) writel(0, SPINLOCK_LOCK_REG0);   //If it is taken, check till CPUX frees spinlock0
rdata=readl(SPINLOCK_LOCK_REG0);                //Request to take spinlock0
if(rdata != 0) rdata=readl(SPINLOCK_LOCK_REG0); //If it fails, retry till lock register0 is taken
```

---------- **CPUX critical code section** ----------

Step 3 CPUX frees spinlock0

```
writel(0, SPINLOCK_LOCK_REG0);                  //CPUX frees spinlock0
```

Step 4 CPUX waits for DSP' freeing spinlock0

```
writel(readl(SPINLOCK_STATUS_REG0) == 1);       //CPUX waits for DSP' freeing spinlock0
```

----------**DSP**----------

Step 1 CPUX has taken spinlock0, DSP waits for CPUX' freeing spinlock0

```
while(readl(SPINLOCK_STATUS_REG0) == 1);        //DSP waits for CPUX' freeing spinlock0
```

Step 2 DSP takes spinlock0 and go on

```
rdata=readl(SPINLOCK_LOCK_REG0);                //Request to take spinlock0
if(rdata != 0) rdata=readl(SPINLOCK_LOCK_REG0); //If it fails, retry till lock register0 is taken
```

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---------- **DSP critical code section** ----------

Step 3 DSP frees spinlock0

```
writel(0, SPINLOCK_LOCK_REG0);                    //DSP frees spinlock0
```

3.13.5 Register List

Module Name	Base Address
Spinlock	0x03005000

Register Name	Offset	Description
SPINLOCK_SYSTATUS_REG	0x0000	Spinlock System Status Register
SPINLOCK_STATUS_REG	0x0010	Spinlock Status Register
SPINLOCK_IRQ_EN_REG	0x0020	Spinlock Interrupt Enable Register
SPINLOCK_IRQ_STA_REG	0x0040	Spinlock Interrupt Status Register
SPINLOCK_LOCKID0_REG	0x0080	Spinlock Lockid0 Register
SPINLOCK_LOCKID1_REG	0x0084	Spinlock Lockid1 Register
SPINLOCK_LOCKID2_REG	0x0088	Spinlock Lockid2 Register
SPINLOCK_LOCKID3_REG	0x008C	Spinlock Lockid3 Register
SPINLOCK_LOCKID4_REG	0x0090	Spinlock Lockid4 Register
SPINLOCK_LOCK_REGN	0x0100 + N*0x0004	Spinlock Register N (N = 0 to 31)

3.13.6 Register Description

3.13.6.1 0x0000 Spinlock System Status Register (Default Value: 0x1000_0000)

Offset: 0x0000			Register Name: SPINLOCK_SYSTATUS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R	0x1	LOCKS_NUM Number of lock registers implemented 00: This instance has 256 lock registers 01: This instance has 32 lock registers 10: This instance has 64 lock registers 11: This instance has 128 lock registers

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Offset: 0x0000			Register Name: SPINLOCK_SYSTATUS_REG
Bit	Read/Write	Default/Hex	Description
27:9	/	/	/
8	R	0x0	IU0 In-Use flag0, covering lock register0-31 0: All lock registers 0-31 are in the NotTaken state. 1: At least one of the lock register 0-31 is in the Taken state.
7:0	/	/	/

3.13.6.2 0x0010 Spinlock Register Status Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: SPINLOCK_STATUS_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	LOCK_REG_STATUS SpinLock[i] status 0: The Spinlock is free 1: The Spinlock is taken

3.13.6.3 0x0020 Spinlock Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: SPINLOCK_IRQ_EN_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	LOCK_IRQ_EN SpinLock[i] interrupt enable 0: Disable 1: Enable

3.13.6.4 0x0040 Spinlock Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0040			Register Name: SPINLOCK_IRQ_STA_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W1C	0x0	LOCK_IRQ_STATUS SpinLock[i] interrupt status 0: No effect 1: Pending Writing 1 clears this bit.

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3.13.6.5 0x0080 Spinlock Lockid0 Register (Default Value: 0x7777_7777)

Offset: 0x0080			Register Name: SPINLOCK_LOCKIN0_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x77777777	LOCKID0

3.13.6.6 0x0084 Spinlock Lockid1 Register (Default Value: 0x7777_7777)

Offset: 0x0084			Register Name: SPINLOCK_LOCKIN1_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x77777777	LOCKID1

3.13.6.7 0x0088 Spinlock Lockid2 Register (Default Value: 0x7777_7777)

Offset: 0x0088			Register Name: SPINLOCK_LOCKIN2_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x77777777	LOCKID2

3.13.6.8 0x008C Spinlock Lockid3 Register (Default Value: 0x7777_7777)

Offset: 0x008C			Register Name: SPINLOCK_LOCKIN3_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x77777777	LOCKID3

3.13.6.9 0x0090 Spinlock Lockid4 Register (Default Value: 0x7777_7777)

Offset: 0x0090			Register Name: SPINLOCK_LOCKIN4_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x77777777	LOCKID4

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3.13.6.10 0x0100 + N*0x04 Spinlock Register N (N = 0 to 31) (Default Value: 0x0000_0000)

Offset: 0x0100 + N*0x0004 (N = 0 to 31)			Register Name: SPINLOCKN_LOCK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	TAKEN Lock State Read 0x0: The lock was previously Not Taken (free). The requester is granted the lock. Write 0x0: Set the lock to Not Taken (free). Read 0x1: The lock was previously Taken. The requester is not granted the lock and must retry. Write 0x1: No update to the lock value.

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3.14 RTC

3.14.1 Overview

The Real Time Clock (RTC) is used to implement time counter and timing wakeup functions. The RTC can display the year, month, day, week, hour, minute, second in real time. The RTC has the independent power to continue to work in system power-off.

The RTC has the following features:

- Provides a 16-bit counter for counting day, 5-bit counter for counting hour, 6-bit counter for counting minute, 6-bit counter for counting second
- External connect a 32.768 kHz low-frequency oscillator for count clock
- Timer frequency is 1 kHz
- Configurable initial value by software anytime
- Supports timing alarm, and generates interrupt and wakeup the external devices
- Eight 32-bit user registers for storing power-off information

CAUTION

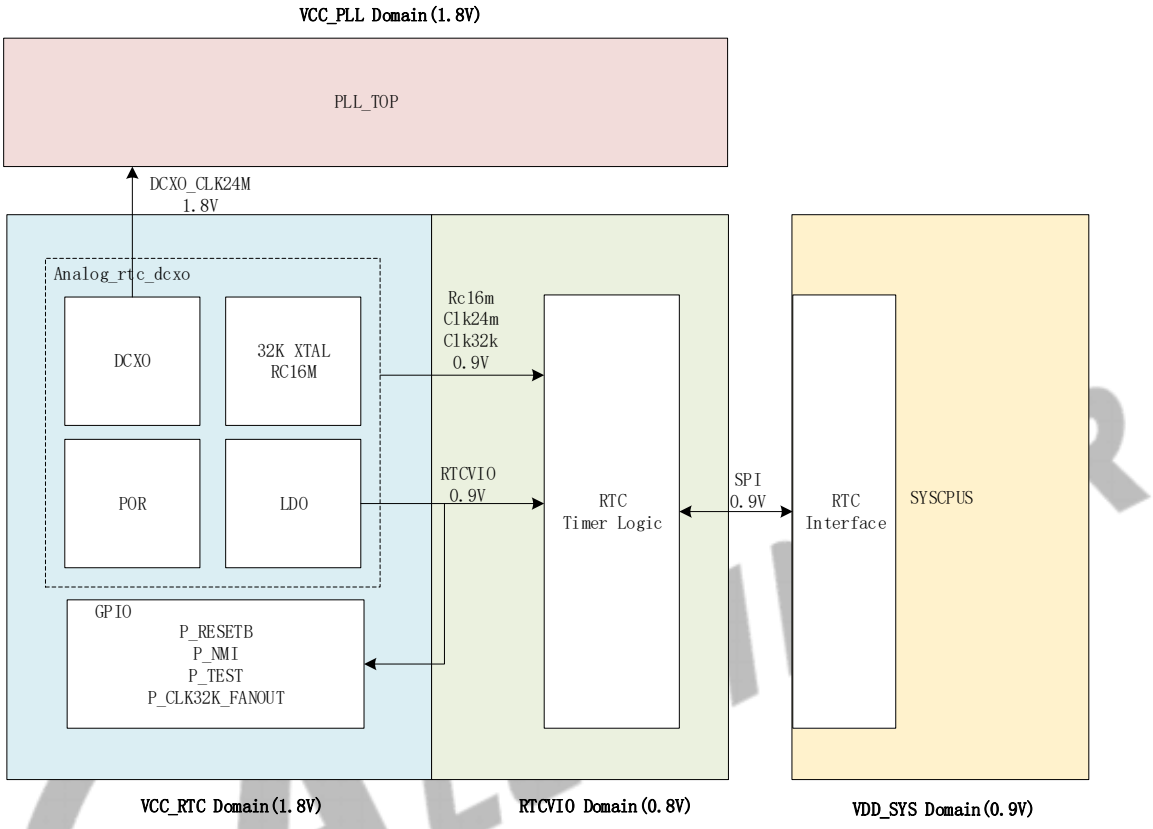
The register configuration of RTC is AHB bus, it only can support word operation, not byte operation and half-word operation.

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3.14.2 Block Diagram

The following figure shows the block diagram of the RTC.

Figure 3- 42 RTC Block Diagram



3.14.3 Functional Description

3.14.3.1 External Signals

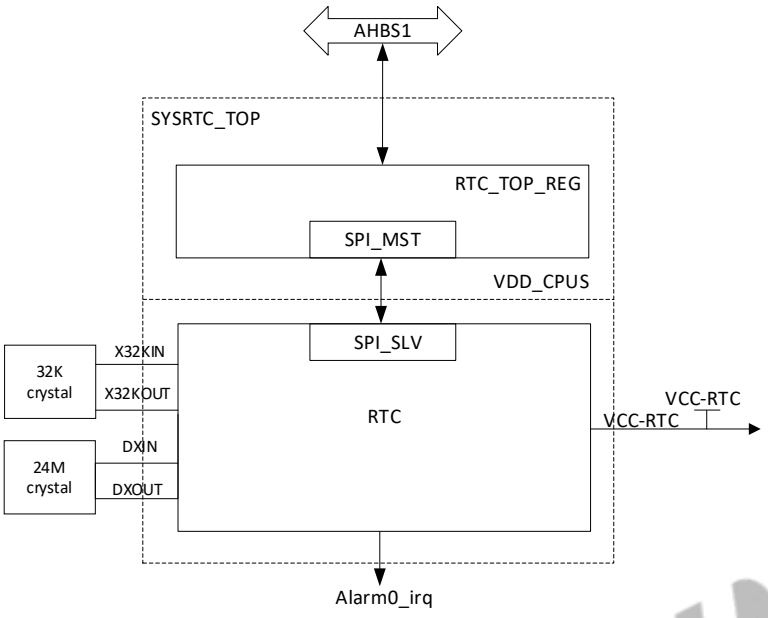
Table 3-19 RTC External Signals

Signal	Description	Type
X32KIN	32.768 kHz oscillator input	AI
X32KOUT	32.768 kHz oscillator output	AO
VCC-RTC	RTC high voltage, generated via external power	P

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3.14.3.2 Typical Application

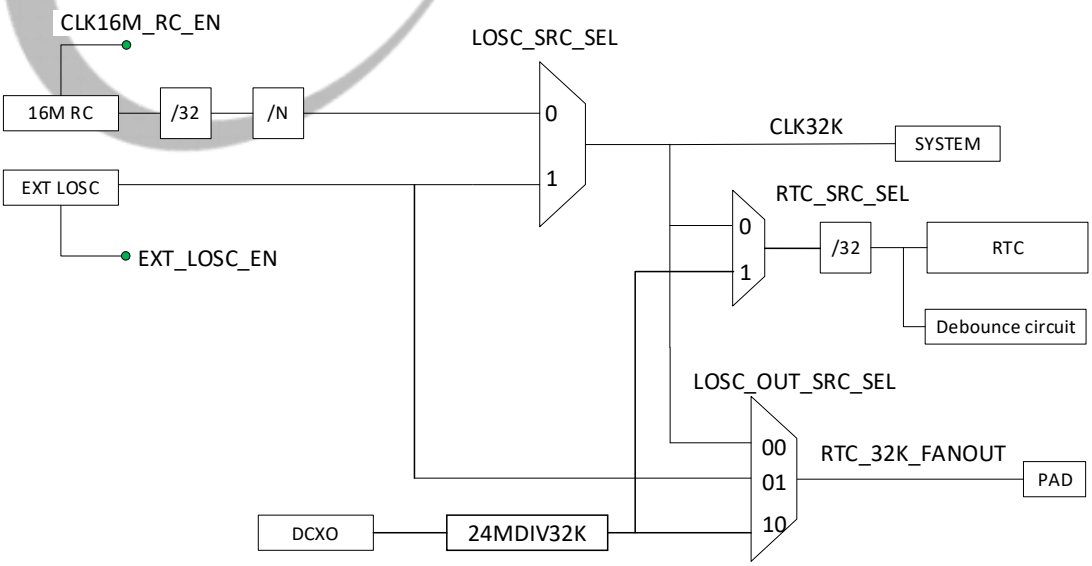
Figure 3-43 RTC Application Diagram



3.14.3.3 Clock Tree

The following figure shows the clock tree of the RTC.

Figure 3-44 RTC Clock Tree



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- **LOSC**

The LOSC has 2 clock sources: internal RC, external low frequency crystal. The LOSC selects the internal RC by default, when the system starts, the LOSC can select by software the external low frequency crystal to provide much accuracy clock. The clock accurate of the LOSC is related to the accurate of the external low frequency crystal. Usually select 32.768 kHz crystal with ±20 ppm frequency tolerance. When using internal RC, the clock can be changed by changing division ratio. When using external clock, the clock cannot be changed.

- **RTC**

The clock sources of RTC can be selected by related switches, including 32K divided by internal 16 MHz RC, 32K divided by external DCXO, and external 32.768 kHz crystal.

- **System 32K**

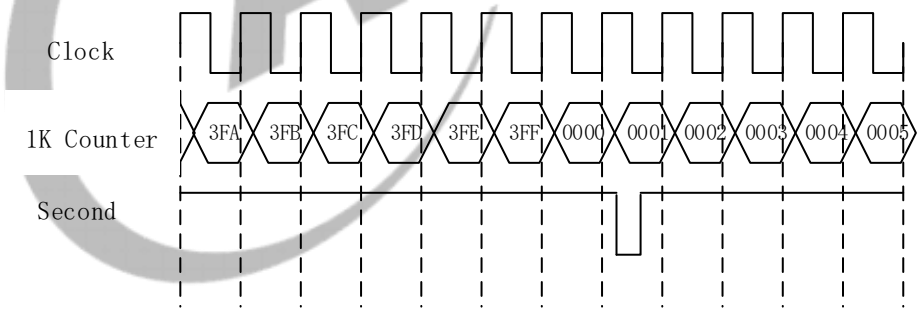
The clock sources of system 32K are from external 32.768 kHz crystal and 32K divided by the internal 16 MHz RC.

- **RTC_32K_FANOUT**

The clock source of RTC_32K_FANOUT can select CLK32K, external 32.768 kHz crystal or 32K divided by external DCXO.

3.14.3.4 Real Time Clock

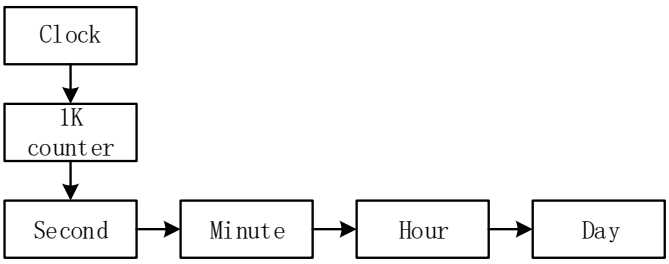
Figure 3-45 RTC Counter



The 1K counter adds 1 on each rising edge of the clock. When the clock number reaches 0x3FF, 1K counter starts to count again from 0, and the second counter adds 1. The step structure of 1 kHz counter is as follows.

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Figure 3-46 RTC 1 kHz Counter Step Structure



According to above implementation, the changing range of each counter is as follows.

Table 3-20 RTC Counter Changing Range

Counter	Range
Second	0 to 59
Minute	0 to 59
Hour	0 to 23
Day	0 to 65535 (The year, month, day need be transformed by software according to day counter)

CAUTION

Because there is no error correction mechanism in the hardware, note that each counter configuration should not exceed a reasonable counting range.

3.14.3.5 Alarm 0

The principle of alarm0 is a comparator. When RTC timer reaches the scheduled time, the RTC generates the interrupt, or outputs low level signal by NMI pin to wakeup power management chip.

The RTC only generates one interrupt when RTC timer reached the scheduled day, hour, minute and second counter, then the RTC needs to be set a new scheduled time, the next interrupt can be generated.

3.14.3.6 Power-off Information Storage

The RTC provides eight 32-bit general purpose register to store power-off information.

Because VCC-RTC always holds non-power-off state after VCC-RTC cold starts, when the system is in shutdown or standby scene, the CPU can judge software process by the storing information.

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3.14.3.7 RTC_VIO

The RTC module has a LDO, the input source of the LDO is VCC_RTC, the output of the LDO is RTC_VIO, the value of RTC_VIO is adjustable, the RTC_VIO is mainly used for internal digital logic.

3.14.3.8 RC Calibration Usage Scenario

- Power-on: Select non-accurate 32K divided by internal RC.
- Normal scenario: Select external accurate 32K, or external calibrated 32K.
- Standby or power-off scenario: Select external accurate 32K, or external calibrated 32K.

3.14.4 Programming Guidelines

3.14.4.1 RTC Clock Control

Step 1 Select clock source: Select clock source by the bit0 of **LOSC_CTRL_REG**, the clock source is the internal RC oscillator by default. When the system starts, the clock source can be switched to the external 32K oscillator by software.

Step 2 Auto switch: After enabled the bit[15:14] of **LOSC_CTRL_REG**, the RTC automatically switches clock source to the internal oscillator when the external crystal could not output waveform, the switch status can query by the bit[1] of **LOSC_AUTO_SWT_STA_REG**.

NOTE

If only configuring the bit[15] of **LOSC_CTRL_REG**, the clock source status bit cannot be changed after the auto switch is valid, because the two functions are independent.

Here is the basic code samples.

```
Write (0x16aa4000,LOSC_Ctrl);    //Write key field
Write (0x16aa4001,LOSC_Ctrl);    //Select the external 32K clock
```

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3.14.4.2 RTC Calendar

Step 1 Write time initial value: Write the current time to RTC_DAY_REG and RTC_HH_MM_SS_REG.

Step 2 After updated time, the RTC restarts to count again. The software can read the current time anytime.

NOTE

- The RTC can only provide day counter, so the current day counter need be converted to year, month, day and week by software.
- Ensure the bit[8:7] of LOSC_CTRL_REG is 0 before the next time configuration is performed.

Here is the basic code samples.

For example: set time to 21st, 07:08:09 and read it.

RTC_DAY_REG = 0x00000015;

RTC_HH_MM_SS_REG = 0x00070809; //0000 0000 000|0 0000(Hour) 00|00 0000(Minute) 00|00 0000(Second)

Read (RTC_DAY_REG);

Read (RTC_HH_MM_SS_REG);

3.14.4.3 Alarm0

Step 1 Enable alram0 interrupt by writing ALARM0_IRQ_EN.

Step 2 Set the counter comparator, write the count-down day, hour, minute, second number to ALARM0_DAY_SET_REG and ALARM0_HH-MM-SS_SET_REG.

Step 3 Enable alarm0 function by writing ALARM0_ENABLE_REG, then the software can query alarm count value in real time by ALARM0_DAY_SET_REG and ALARM0_HH-MM-SS_SET_REG**.** When the setting time reaches, ALARM0_IRQ_STA_REG is set to 1 to generate interrupt.

Step 4 After enter the interrupt process, write ALARM0_IRQ_STA_REG to clear the interrupt pending, and execute the interrupt process.

Step 5 Resume the interrupt and continue to execute the interrupted process.

Step 6 The power-off wakeup is generated via SoC hardware and PMIC, the software only needs to set the pending condition of alarm0, and set ALARM_CONFIG_REG to 1.

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Here is the basic code samples.

```
irq_request(GIC_SRC_R_Alarm0, Alm0_handler);

irq_enable(GIC_SRC_R_Alarm0);

writel(1, ALARM0_DAY_SET_REG);

writel(1, RTC_HH_MM_SS_REG); //set 1 second corresponding to normal mode;

writel(1, ALM0_EN);

writel(1, ALM_CONFIG); //NMI output

while(!readl(ALM0_IRQ_STA));

writel(1, ALM0_IRQ_EN);

while(readl(ALM0_IRQ_STA));
```

3.14.5 Register List

Module Name	Base Address
RTC	0x07090000

Register Name	Offset	Description
LOSC_CTRL_REG	0x0000	Low Oscillator Control Register
LOSC_AUTO_SWT_STA_REG	0x0004	LOSC Auto Switch Status Register
INTOSC_CLK_PRESCAL_REG	0x0008	Internal OSC Clock Pre-scalar Register
RTC_DAY_REG	0x0010	RTC Year-Month-Day Register
RTC_HH_MM_SS_REG	0x0014	RTC Hour-Minute-Second Register
ALARM0_DAY_SET_REG	0x0020	Alarm 0 Day Setting Register
ALARM0_CUR_VLU_REG	0x0024	Alarm 0 Counter Current Value Register
ALARM0_ENABLE_REG	0x0028	Alarm 0 Enable Register
ALARM0_IRQ_EN	0x002C	Alarm 0 IRQ Enable Register
ALARM0_IRQ_STA_REG	0x0030	Alarm 0 IRQ Status Register
ALARM_CONFIG_REG	0x0050	Alarm Configuration Register
32K_FOUT_CTRL_GATING_REG	0x0060	32K Fanout Control Gating Register
GP_DATA_REG	0x0100 + N*0x04	General Purpose Register (N=0 to 7)
FBOOT_INFO_REG0	0x0120	Fast Boot Information Register0
FBOOT_INFO_REG1	0x0124	Fast Boot Information Register1

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Register Name	Offset	Description
DCXO_CTRL_REG	0x0160	DCXO Control Register
RTC_VIO_REG	0x0190	RTC_VIO Regulation Register
IC_CHARA_REG	0x01F0	IC Characteristic Register
VDD_OFF_GATING_CTRL_REG	0x01F4	VDD Off Gating Control Register
EFUSE_HV_PWRSWT_CTRL_REG	0x0204	Efuse High Voltage Power Switch Control Register
RTC_SPI_CLK_CTRL_REG	0x0310	RTC SPI Clock Control Register

NOTE

The offset addresses less than 0x0300 are in VDD_RTC power domain, and the offset addresses large than or equal to 0x300 are in VDD_SYS power domain.

3.14.6 Register Description

3.14.6.1 0x0000 LOSC Control Register (Default Value: 0x0000_4010)

Offset:0x0000			Register Name: LOSC_CTRL_REG
Bit	Read/Write	Default/Hex	Description
31:16	W	0x0	KEY_FIELD Key Field This field should be filled with 0x16AA, and then the bit0 and bit1 can be written with the new value.
15	R/W	0x0	LOSC_AUTO_SWT_FUNCTION LOSC auto switch function disable 0: Enable 1: Disable
14	R/W	0x1	LOSC_AUTO_SWT_32K_SEL_EN LOSC auto switch 32K clk source select enable 0: Disable. When the losc losts, the 32k clk source will not change to RC 1: Enable. When the losc losts, the 32k clk source will change to RC (LOSC_SRC_SEL will be changed from 1 to 0)
13:9	/	/	/
8	R/W	0x0	RTC_HHMMSS_ACCE RTC Hour Minute Second access

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Offset:0x0000			Register Name: LOSC_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			After writing the RTC HH-MM-SS Register, this bit is set and it will be cleared until the real writing operation is finished. After writing the RTC HH-MM-SS Register, the RTC HH-MM-SS Register will be refreshed for at most one second. **Note: Make sure that the bit is 0 for time configuration.**
7	R/W	0x0	RTC_DAY_ACCE RTC DAY access After writing the RTC DAY register, this bit is set and it will be cleared until the real writing operation is finished. After writing the RTC DAY register, the DAY register will be refreshed for at most one second. **Note: Make sure that the bit is 0 for time configuration.**
6:5	/	/	/
4	R/W	0x1	EXT_LOSC_EN External 32.768 kHz Crystal Enable 0: Disable 1: Enable
3:2	R/W	0x0	EXT_LOSC_GSM External 32.768 kHz Crystal GSM 00: Low 01: / 10: / 11: High When GSM is changed, the 32K oscillation circuit will arise transient instability. If the autoswitch function (bit 15) is enabled, 32K changes to RC16M with certain probability. The GSM can influence the time of 32K starting oscillation, the more the GSM, the shorter the time of starting oscillation. So modifying GSM is not recommended. If you need to modify the GSM, firstly disable the auto switch function (bit 15), with a delay of 50 us, then change the GSM, the 32K clock source is changed to external clock.
1	R/W	0x0	RTC_SRC_SEL RTC_TIMER Clock Source Select 0: LOSC_SRC 1: 24MDIV32K Before switching the bit, make sure that the 24MDIV32K function is enabled, that is, the bit16 of the 32K Fanout Control Register is 1.

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Offset:0x0000			Register Name: LOSC_CTRL_REG
Bit	Read/Write	Default/Hex	Description
0	R/W	0x0	LOSC_SRC_SEL LOSC Clock Source Select 0: Low frequency clock from 16M RC 1: External 32.768 kHz OSC

NOTE

If the bit[8:7] of LOSC_CTRL_REG is set, the RTC HH-MM-SS, DD and ALARM DD-HH-MM-SS register cannot be written.

3.14.6.2 0x0004 LOSC Auto Switch Status Register (Default Value: 0x0000_0000)

Offset:0x0004			Register Name: LOSC_AUTO_SWT_STA_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2	R	0x0	EXT_LOSC_STA Work only when the auto switch function is enabled. 0: External 32.768 kHz OSC work normally 1: External 32.768 kHz OSC work abnormally
1	R/W1C	0x0	LOSC_AUTO_SWT_PEND LOSC auto switch pending 0: No effect 1: Auto switch pending, it means LOSC_SRC_SEL is changed from 1 to 0. Setting 1 to this bit will clear it.
0	R	0x0	LOSC_SRC_SEL_STA Checking LOSC clock source status 0: Low frequency clock from 16M RC 1: External 32.768 kHz OSC

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3.14.6.3 0x0008 Internal OSC Clock Prescalar Register (Default Value: 0x0000_000F)

Offset:0x0008			Register Name: INTOSC_CLK_PRESCAL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:5	/	/	/
4:0	R/W	0xF	INTOSC_32K_CLK_PRESCAL Internal OSC 32K Clock Prescalar value N. The clock output = Internal RC/32/N. 00000: 1 00001: 2 00002: 3 ..... 11111: 32

3.14.6.4 0x0010 RTC Year-Month-DAY Register (Default Value: UDF)

Offset:0x0010			Register Name: RTC_DAY_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	UDF	DAY Set Day Range from 0 to 65535.

3.14.6.5 0x0014 RTC Hour-Minute-Second Register (Default Value: UDF)

Offset:0x0014			Register Name: RTC_HH_MM_SS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:21	/	/	/
20:16	R/W	UDF	HOUR Set hour Range from 0 to 23.
15:14	/	/	/
13:8	R/W	UDF	MINUTE Set minute Range from 0 to 59.
7:6	/	/	/
5:0	R/W	UDF	SECOND

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Offset:0x0014			Register Name: RTC_HH_MM_SS_REG
Bit	Read/Write	Default/Hex	Description
			Set second Range from 0 to 59.

3.14.6.6 0x0020 Alarm 0 Day Setting Register (Default Value: 0x0000_0000)

Offset:0x0020			Register Name: ALARM0_DAY_SET_REG
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0	ALARM0_COUNTER Alarm 0 Counter is based on Day.

3.14.6.7 0x0024 Alarm 0 Counter Current Value Register (Default Value: UDF)

Offset:0x0024			Register Name: ALARM0_CUR_VLU_REG
Bit	Read/Write	Default/Hex	Description
31:21	/	/	/
20:16	R/W	UDF	HOUR Current hour Range from 0 to 23.
15:14	/	/	/
13:8	R/W	UDF	MINUTE Current minute Range from 0 to 59.
7:6	/	/	/
5:0	R/W	UDF	SECOND Current second Range from 0 to 59.

3.14.6.8 0x0028 Alarm 0 Enable Register (Default Value: 0x0000_0000)

Offset:0x0028			Register Name: ALARM0_ENABLE_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/W	0x0	ALM_0_EN

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Offset:0x0028			Register Name: ALARM0_ENABLE_REG
Bit	Read/Write	Default/Hex	Description
			Alarm 0 Enable 0: Disable 1: Enable

3.14.6.9 0x002C Alarm 0 IRQ Enable Register (Default Value: 0x0000_0000)

Offset:0x002C			Register Name: ALARM0_IRQ_EN
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/W	0x0	ALARM0_IRQ_EN Alarm 0 IRQ Enable 0: Disable 1: Enable

3.14.6.10 0x0030 Alarm 0 IRQ Status Register (Default Value: 0x0000_0000)

Offset:0x0030			Register Name: ALARM0_IRQ_STA_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/W1C	0x0	ALARM0_IRQ_PEND Alarm 0 IRQ Pending bit 0: No effect 1: Pending, alarm 0 counter value is reached If alarm 0 irq enable is set to 1, the pending bit will be sent to the interrupt controller.

3.14.6.11 0x0050 Alarm Configuration Register (Default Value: 0x0000_0000)

Offset:0x0050			Register Name: ALARM_CONFIG_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/W	0x0	ALARM_WAKEUP Configuration of alarm wake up output. 0: Disable alarm wake up output

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Offset:0x0050			Register Name: ALARM_CONFIG_REG
Bit	Read/Write	Default/Hex	Description
			1: Enable alarm wake up output

3.14.6.12 0x0060 32K Fanout Control Gating Register (Default Value: 0x0000_0000)

Offset:0x0060			Register Name: 32K_FOUT_CTRL_GATING_REG
Bit	Read/Write	Default/Hex	Description
31:17	/	/	/
16	R/W	0x0	HOSC_TO_32K_DIVIDER_ENABLE HOSC to 32k divider enable 0: Disable the hosc 24M to 32K divider circuit 1: Enable the hosc 24M to 32K divider circuit
15:3	/	/	/
2:1	R/W	0x0	LOSC_OUT_SRC_SEL LOSC output source select 00: RTC_32K (select by RC_CLK_SRC_SEL & LOSC_SRC_SEL) 01: LOSC 10: HOSC divided 32K
0	R/W	0x0	32K_FANOUT_GATING LOSC out gating enable Configuration of LOSC output, and there is no LOSC output by default. 0: Mask LOSC output gating 1: Enable LOSC output gating

3.14.6.13 0x0100+N*0x0004 General Purpose Register (Default Value: 0x0000_0000)

Offset:0x0100+N*0x0004 (N=0 to 7)			Register Name: GP_DATA_REGN
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	GP_DATA Data [31:0]

NOTE

General purpose register 0 to 7 value can be stored if the RTC-VIO is larger than 0.7 V.

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3.14.6.14 0x0120 Fast Boot Information Register0 (Default Value: 0x0000_0000)

Offset:0x0120			Register Name: FBOOT_INFO_REG0
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	FBOOT_INFO0 Fast Boot info Fast Boot Information 0, refer to BROM spec.

3.14.6.15 0x0124 Fast Boot Information Register1 (Default Value: 0x0000_0000)

Offset:0x0124			Register Name: FBOOT_INFO_REG1
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	FBOOT_INFO1 Fast Boot info Fast Boot Information 1, refer to BROM spec.

3.14.6.16 0x0160 DCXO Control Register (Default Value: 0x883F_10F7)

Offset:0x0160			Register Name: DCXO_CTRL_REG
Bit	Read/Write	Default/Hex	Description
31	R/W	0x1	CLK_REQ_ENB Clock REQ enable 0: Enable DCXO wake up function 1: Disable DCXO wake up function
30:28	/	/	/
27:24	R/W	0x8	DCXO_ICTRL DCXO current control value
23	/	/	/
22:16	R/W	0x3F	DCXO_TRIM DCXO cap array value The capacity cell is 55 fF.
15:13	/	/	/
12:8	R/W	0x10	DCXO_BG DCXO bandgap output voltage
7	R/W	0x1	DCXO_LDO_INRUSHB

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Offset:0x0160			Register Name: DCXO_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			DCXO LDO driving capacity signal, active high
6	R/W	0x1	XTAL_MODE Xtal mode enable signal, active high 0: For external clk input mode 1: For normal mode
5:4	R/W	0x3	DCXO_RFCLK_ENHANCE DCXO rfclk enhance Enhance driving capacity of output OUT_RF_REFCLK, 0x0 for 5 pF, 0x1 for 10 pF, 0x2 for 15 pF, 0x3 for 20 pF.
3	/	/	/
2	R/W	0x1	RSTO_DLY_SEL For Debug Use Only. It cannot configure to 0 in normal state.
1	R/W	0x1	DCXO_EN DCXO enable 1: Enable 0: Disable
0	R/W	0x1	CLK16M_RC_EN 1: Enable 0: Disable The related register configuration is necessary to ensure the reset debounce circuit has a stable clock source. The first time SoC starts up, by default, the reset debounce circuit of SoC uses 32K divided by RC16M. In power-off, software reads the related bit to ensure whether EXT32K is working normally, if it is normal, first switch the clock source of debounce circuit to EXT32K, then close RC16M. Without EXT32K scenario or external RTC scenario, software confirms firstly whether EXT32K is working normally before switching, or software does not close RC16M.

3.14.6.17 0x0190 RTC_VIO Regulation Register (Default Value: 0x0000_0004)

Offset:0x0190			Register Name:RTC_VIO_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:5	/	/	/
4	R/W	0x0	V_SEL

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Offset:0x0190			Register Name:RTC_VIO_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			VDD Select 0: Resistance divider 1: Band gap
3	/	/	/
2:0	R/W	0x4	RTC_VIO_REGU RTC_VIO Voltage Select The RTC-VIO is provided power for RTC digital part. These bits are useful for regulating the RTC_VIO from 0.65 V to 1.3 V. 000: 1.0 V 001: 0.65 V (the configuration can cause RTC reset) 010: 0.7 V 011: 0.8 V 100: 0.9 V 101: 1.1 V 110: 1.2 V 111: 1.3 V

3.14.6.18 0x01F0 IC Characteristic Register (Default Value: 0x0000_0000)

Offset:0x01F0			Register Name: IC_CHARA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0	KEY_FIELD Key Field The field should be written as 0x16AA. Writing any other value in this field aborts the write-operation.
15:0	R/W	0x0	ID_DATA Return 0x16AA only if the KEY_FIELD is set as 0x16AA when read those bits, otherwise return 0x0.

3.14.6.19 0x01F4 VDD Off Gating Control Register (Default Value: 0x0000_0021)

Offset:0x01F4			Register Name: VDD_OFF_GATING_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	W	0x0	KEY_FIELD Key Field

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Offset:0x01F4			Register Name: VDD_OFF_GATING_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			This field should be filled with 0x16AA, and then the bit 15 can be configured.
15	WAC	0x0	PWROFF_GAT_RTC_CFG (For Debug Use Only) Power off gating control signal When use vdd_sys to RTC isolation software control, write this bit to 1. It will only be cleared by resetb release.
14:12	/	/	/
11:4	R/W	0x2	VCCIO_DET_SPARE Bit[7:5]: Reserved, default=0 Bit[4]: Bypass debounce circuit, defaule=0 Bit[3]: Enable control, defaule=0 0: Disable VCC-IO detection 1: Force the detection output Bit[2:0]: Gear adjustment 000: Detection threshold is 2.5 V 001: Detection threshold is 2.6 V 010: Detection threshold is 2.7 V (default) 011: Detection threshold is 2.8 V 100: Detection threshold is 2.9 V 101: Detection threshold is 3 V 110: N/A 111: N/A
3:1	/	/	/
0	R/W	0x1	VCCIO_DET_BYPASS_EN 0: not bypass 1: bypass

3.14.6.20 0x0204 Efuse High Voltage Power Switch Control Register (Default Value: 0x0000_0000)

Offset:0x0204			Register Name: EFUSE_HV_PWRSWT_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	EFUSE_1.8V_POWER_SWITCH_CONTROL 1: Open power switch 0: Close power switch

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3.14.6.21 0x0310 RTC SPI Clock Control Register (Default Value: 0x0000_0009)

Offset:0x0310			Register Name: RTC_SPI_CLK_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	RTC Reg CFG SPI Clock Gating 0: Gating 1: Not Gating Before configurating RTC register, the clock divider of SPI needs be configured firstly, then clock gating needs be enabled. **Note: Frequency division and clock gating can not be set at the same time.**
30:5	/	/	/
4:0	R/W	0x9	RTC Reg CFG SPI Clock Divider: M Actual SPI Clock = AHBS1/(M+1), (0 to 15) The default frequency of AHBS1 is 200 MHz, and the default frequency of SPI Clock is 20 MHz. **Note: The SPI clock can not exceed 50 MHz, or else the RTC register may be abnormal.**

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4 DSP

4.1 DSP Watchdog Timer

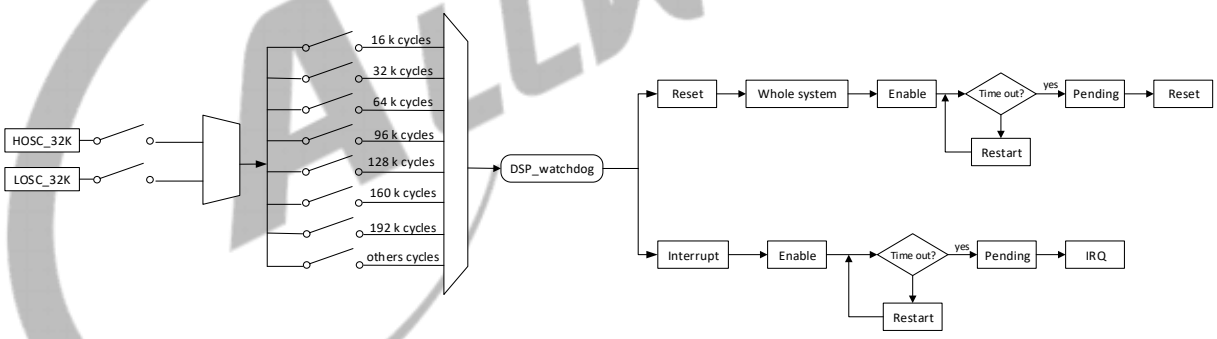
4.1.1 Overview

The DSP watchdog timer (DSP WDT) is used to transmit a reset signal to reset the entire system when an exception occurs in the system. The main features for the watchdog are as follows:

- Supports 12 initial values
- Supports the generation of timeout interrupts
- Supports the generation of reset signals
- Supports Watchdog Restart

4.1.2 Block Diagram

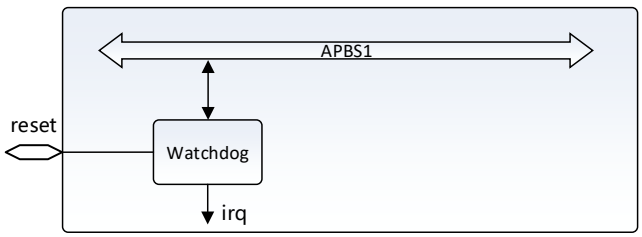
Figure 4- 1 DSP WDT Block Diagram



4.1.3 Functional Description

4.1.3.1 Typical Application

Figure 4- 2 DSP WDT Typical Application



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4.1.3.2 Operationg Modes

The watchdog has two operating modes: the interrupt mode and reset mode.

- In the interrupt mode, when the counter value reaches 0 and RWDOG_IRQ_EN_REG is enabled, the watchdog generates an interrupt.
- In the reset mode, when the counter value reaches 0, the watchdog generates a reset signal to reset the entire system.

You can configure the operating mode for the watchdog via the bit[1:0] of the RWDOG_CFG_REG. The value 0x2 is for the interrupt mode and the value 0x1 is for the reset mode.

Both the interrupt mode and reset mode support Watchdog Restart. You can make the watchdog to count from the initial value at any time by configuring the RWDOG_CTRL_REG: write 0xA57 to bit[12:1], then write 1 to bit[0].

4.1.3.3 Initializing the Watchdog

Follow the steps below to initialize the watchdog:

1. Write the bit[1:0] of RWDOG_CFG_REG to configure the watchdog operating mode so that the watchdog can generate interrupts or output reset signals.
2. Write the bit[7:4] of RWDOG_MODE_REG to configure the initial count value.
3. 3Write the bit[0] of RWDOG_MODE_REG to enable the watchdog.

4.1.3.4 Processing the Interrupt

In the interrupt mode, the watchdog is used as a counter. It generates an interrupt everytime the count value reaches 0.

Follow the steps below to process the interrupt:

1. Write the enable bit of RWDOG_IRQ_EN_REG to enable the interrupt.
2. After entering the interrupt process, write the pending bit of RWDOG_IRQ_STA_REG to clear the interrupt pending and execute the process of waiting for the interrupt.
3. Resume the interrupt and continue to execute the interrupted process.

4.1.4 Register List

Module Name	Base Address	Comments
DSP_Watchdog	0x0170 1000	DSP Watchdog configuration register

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Register Name	Offset	Description
RWDOG_IRQ_EN_REG	0x0000	DSP_Watchdog IRQ Enable Register
RWDOG_IRQ_STA_REG	0x0004	DSP_Watchdog Status Register
RWDOG_CTRL_REG	0x0010	DSP_Watchdog Control Register
RWDOG_CFG_REG	0x0014	DSP_Watchdog Configuration Register
RWDOG_MODE_REG	0x0018	DSP_Watchdog Mode Register
RWDOG_OUTPUT_CFG_REG	0x001C	DSP_Watchdog Output Config Register

4.1.5 Register Description

4.1.5.1 0x0000 DSP_Watchdog IRQ Enable Register (Default Value: 0x0000_0000)

Offset:0x0000			Register Name: RWDOG_IRQ_EN_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/W	0x0	RWDOG_IRQ_EN. DSP_Watchdog Interrupt Enable. 0: DSP_Watchdog interrupt mask, 1: DSP_Watchdog interrupt enable.

4.1.5.2 0x0004 DSP_Watchdog Status Register (Default Value: 0x0000_0000)

Offset:0x0004			Register Name: RWDOG_IRQ_STA_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/W	0x0	RWDOG_IRQ_PEND. DSP_Watchdog IRQ Pending, Set 1 to the bit will clear it. 0: No effect, 1: Pending, DSP_Watchdog interval value is reached.

4.1.5.3 0x0010 DSP_Watchdog Control Register (Default Value: 0x0000_0000)

Offset:0x0010			Register Name: RWDOG_CTRL_REG
Bit	Read/Write	Default/Hex	Description
31:13	/	/	/
12:1	W	0x0	RWDOG_KEY_FIELD. DSP_Watchdog Key Field. Should be written at value 0xA57. Writing any other value in this field aborts the write operation.
0	R/W	0x0	RWDOG_RESTART. DSP_Watchdog Restart. 0: No effect,

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Offset:0x0010			Register Name: RWDOG_CTRL_REG
Bit	Read/Write	Default/Hex	Description
			1: Restart the DSP_Watchdog.

4.1.5.4 0x0014 DSP_Watchdog Configuration Register (Default Value: 0x0000_0001)

Offset:0x0014			Register Name: RWDOG_CFG_REG
Bit	Read/Write	Default/Hex	Description
31:16	W	0x0	KEY_FIELD. Key Field. This field should be filled with 0x16AA, and then the bit 0 can be written with the new value.
15:7	/	/	/
8	R/W	0x0	RWDOG_CLK_SRC. Select DSP_Watchdog clock sources. 0: HOSC_32K 1: LOSC_32K
7:2	/	/	/
1:0	R/W	0x1	DSP_WDOG_CONFIG. DSP_Watchdog generates a reset signal 00:/ 01: to whole system 10: only interrupt 11: /

4.1.5.5 0x0018 DSP_Watchdog Mode Register (Default Value: 0x0000_0000)

Offset:0x0018			Register Name: RWDOG_MODE_REG
Bit	Read/Write	Default/Hex	Description
31:16	W	0x0	KEY_FIELD. Key Field. This field should be filled with 0x16AA, and then the bit 0 can be written with the new value.
15:8	/	/	/
7:4	R/W	0x0	DSP_WDOG_INTV_VALUE. DSP_Watchdog Interval Value. When the clock source is HOSC_32K, the time of 16000 cycles is equal to 0.5 sec, and when the clock source is 32K, the time of 16000 cycles is based on the number of 32K. 0000: 16000 cycles 0001: 32000 cycles 0010: 64000 cycles 0011: 96000 cycles 0100: 128000 cycles 0101: 160000 cycles

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Offset:0x0018			Register Name: RWDOG_MODE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			0110: 192000 cycles 0111: 256000 cycles 1000: 320000 cycles 1001: 384000 cycles 1010: 448000 cycles 1011: 512000 cycles 1100: / 1101: / 1110: / 1111: /
3:1	/	/	/
0	R/W	0x0	DSP_WDOG_EN. DSP_Watchdog Enable. 0: No effect; 1: Enable the DSP_Watchdog.

4.1.5.6 0x001C DSP_Watchdog Output Config Register (Default Value: 0x0000_001F)

Offset: 0x001C			Register Name:RWDOG_OUTPUT_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:0	R/W	0x1F	DSP_Watchdog_Output_Config DSP_Watchdog rst valid time config T=1/32ms*(N+1) Default 1ms

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4.2 DSP Interrupt List

4.2.1 DSP_CORE Interrupt Source

BInterrupt Pin	Interrupt Name	Priority	Bit In Source	Description
0	nmi	nmi	136	External Non-Mask Interrupt
	timer.1	3		DSP inter timer1 Interrupt
	timer.0	3		DSP inter timer0 Interrupt
1	DSP_Msgbox	3		DSP_SYS Massage box read irq
2	Msgbox0	3	85	CPUX Massage box 0 irq(for DSP)
		3		
4	Dmac_irq_dsp_s	3	127	Dmac 8~15 channel secure irq
	sw	3		DSP inter software Interrupt
5	Dmac_irq_dsp_ns	3	126	Dmac 8~15 channel non-secure irq
6	GIC_OUT_CO	3	160	GIC_OUT_CO cpucfg interrupt
7	I2S0	2	26	I2S0 irq
8	I2S1	2	27	I2S1 irq
9	I2S2	2	28	I2S2 irq
10	AUDIO_Codec	2	25	AUDIO codec irq
11	DMIC	2	24	DMIC irq
12	Spinlock	2	54	SPLOCK irq
13	DSP_WDOG	2	122	DSP_SYS WDOG interrupt.
14	DSP_TZMA	2	125	DSP_SYS TZMA interrupt
15	HSTIMER0	2	55	
16	HSTIMER1	2	56	
17	INTC	1		DSP_SYS int ctrl module
18	TIMER0	1	59	
19	TIMER1	1	60	
20	GPA	1	57	
21	LR	1	61	
22	TPA	1	62	
23	M_TIMER0	1	140	
24	M_TIMER1	1	141	
25	M_TIMER2	1	142	
26	M_TIMER3	1	143	
27	M_ALARM0	1	144	
	writeerr	1		DSPAXI Response Write Error

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4.2.2 DSP_INTC Interrupts

BInterrupt Pin	Interrupt Name	Priority	Bit In Source	Description
0	NA		0	Not Used
			1	
			2	
1	UART0		3	SYS uart0 interrupt
2	UART1		4	SYS uart1 interrupt
3	UART2		5	SYS uart2 interrupt
4	UART3		6	SYS uart3 interrupt
5	UART4		7	SYS uart4 interrupt
6	UART5		8	SYS uart5 interrupt
			9	
7	TWI0		10	SYS twi0 interrupt
8	TWI1		11	SYS twi1 interrupt
9	TWI2		12	SYS twi2 interrupt
10	TWI3		13	SYS twi3 interrupt
			14	
			15	
11	SPI0		16	SYS spi0 interrupt
12	SPI1		17	SYS spi1 interrupt
			18	
13	PWM		19	SYS pwm interrupt
14	IR_TX		20	SYS irrx interrupt
15	LEDC		21	LED control interrupt
16			22	
17			23	
	OWA		24	SYS OWA interrupt audio
	DMIC		25	DMIC interrupt
	AUDIO_CODEC		26	AUDIO CODEC interrupt
	I2S_PCM0		27	SYS i2s0 interrupt
	I2S_PCM1		28	SYS i2s1 interrupt
	I2S_PCM2		29	SYS i2s2 interrupt
18	USB0_DEVICE		30	SYS usb0 interrupt
19	USB0_EHCI		31	SYS usb0_ehci interrupt
20	USB0_OHCI		32	SYS usb0_ohci interrupt
			33	
21	USB1_EHCI		34	SYS usb1_ehci interrupt
22	USB1_OHCI		35	SYS usb1_ohci interrupt
			36	
			37	
			38	
			39	

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BInterrupt Pin	Interrupt Name	Priority	Bit In Source	Description
			40	
23	SD0		41	SYS sd0 interrupt
24	SD1		42	SYS sd1 interrupt
25	SD2		43	SYS sd2 interrupt
26	MSI		44	SYS msi interrupt
27	SMC		45	SYS smc interrupt
			46	
28	GMAC		47	SYS gmac0 interrupt
29	TZMA_ERR		48	TZMA_ERR interrrupt
30	CCU_FERR		49	SYS ccu err interrupt
31	AHB_HREADY_TIME_OUT		50	SYS hready timeout interrupt
32	DMA_NS		51	Dmac 0~7 channel non-secure irq
33	DMA_S		52	Dmac 0~7 channel secure irq
34	CE_NS		53	CE irq, (ce_irq_ns)
35	CE_S		54	CE irq, (ce_irq_s)
	SPINLOCK		55	SYS splock interrupt AUDIO
	HSTIMER0		56	SYSCPUS hstimer 0 interrupt
	HSTIMER1		57	SYSCPUS hstimer 1 interrupt
	GPA		58	GPADC_IRQ
36	THS		59	THS_IRQ
	TIMER0		60	SYSCPUS timer 0 interrupt
	TIMER1		61	SYSCPUS timer 1 interrupt
	LR		62	LRADC_IRQ
	TPA		63	TPADC_IRQ
37	WATCHDOG		64	SYS watchdog interrupt
38	IOMMU		65	IOMMU interrupt
			66	
39	VE		67	VE interrupt
			68	
			69	
40	GPIOB_NS		70	SYS gpiob_ns interrupt
41	GPIOB_S		71	SYS gpiob_s interrupt
42	GPIOC_NS		72	SYS gpioc_ns interrupt
43	GPIOC_S		73	SYS gpioc_s interrupt
44	GPIOD_NS		74	SYS gpiod_ns interrupt
45	GPIOD_S		75	SYS gpiod_s interrupt
46	GPIOE_NS		76	SYS gpioe_ns interrupt
47	GPIOE_S		77	SYS gpioe_s interrupt
48	GPIOF_NS		78	SYS gpiof_ns interrupt
49	GPIOF_S		79	SYS gpiof_s interrupt

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BInterrupt Pin	Interrupt Name	Priority	Bit In Source	Description
50	GPIOG_NS		80	SYS gpiog_ns interrupt
51	GPIOG_S		81	SYS gpiog_s interrupt
			82	
			83	
			84	
			85	
52	CPUX_MSGBOX_DSP_W		86	CPUX MSGBOX WRITE IRQ FOR DSP
			87	
53	DE		88	DE interrupt
54	DI		89	DI interrupt
55	G2D		90	G2D interrupt
56	LCD		91	LCD interrupt
57			92	
58	DSI		93	DSI interrupt
59			94	
60			95	
61	CSI_DMA0		96	CSI_DMA0 interrupt
62	CSI_DMA1		97	CSI_DMA1 interrupt
			98	CSI_DMA2 interrupt
			99	CSI_DMA3 interrupt
			100	Not Used
63	CSI_PARSER0		101	CSI_PARSER0 interrupt
			102	
			103	
			104	
			105	
			106	
64	CSI_TOP_PKT		107	CSI_TOP_PKT interrupt
65			108	
			109	
			110	
			111	
			112	
			113	
			114	
			115	
			116	
			117	
			118	
			119	

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BInterrupt Pin	Interrupt Name	Priority	Bit In Source	Description
			120	
66	DSP_DEE		121	DSP DoubleExceptionError interrupt
67	DSP_PFE		122	DSP PFatalError interrupt
68	DSP_WDG		123	DSP wdg interrupt
69	DSP_MBOX_CPUX_W		124	DSP to CPUX mbox interrupt
70			125	
71	DSP_TZMA		126	DSP TZMA interrupt
	DMAC_IRQ_DSP_NS		127	Dmac 8~15 channel non-secure irq
	DMAC_IRQ_DSP_S		128	Dmac 8~15 channel secure irq
72			129	
73			130	
74			131	
75			132	
76			133	
77			134	
78			135	
79			136	
80	NMI		137	CPUS NMI interrupt
81	PPU		138	CPUS PPU interrupt
82	TWD		139	CPUS TWD interrupt
			140	
83	TIMER0		141	CPUS TIMER0 IRQ
84	TIMER1		142	CPUS TIMER1 IRQ
85	TIMER2		143	CPUS TIMER2 IRQ
86	TIMER3		144	CPUS TIMER3 IRQ
87	ALARM0		145	CPUS ALARM0 IRQ
			146	
			147	
			148	
			149	
			150	
			151	
88	IRRX		152	CPUS IRRX_IRQ[9:0] XOR to 1bit
			153	
			154	
89	AHBS_HREADY_TOUT		155	CPUS AHB READY TIME OUT IRQ

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BInterrupt Pin	Interrupt Name	Priority	Bit In Source	Description
			156	
			157	
			158	
			159	
			160	
90	GIC_OUT_CO		161	

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4.3 DSP Message Box

4.3.1 Overview

The DSP Message Box (DSP MSGBOX) provides interrupt communication mechanism for on-chip processor.

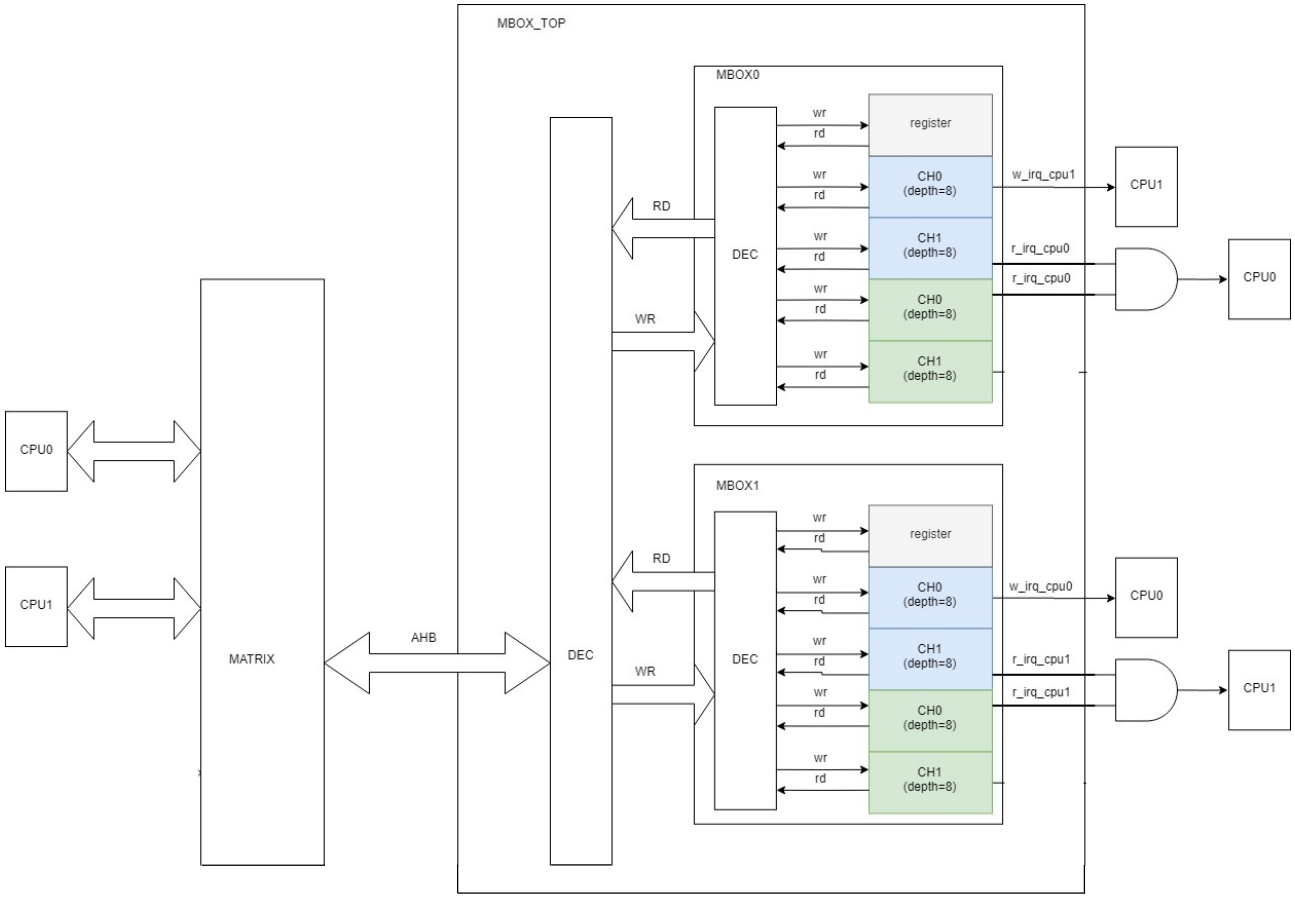
The MSGBOX has the following features:

- Supports maximum 2 CPUs to transmit information through channels. Each CPU has a MSGBOX. The number of CPU can be flexibly configured based on needs. This section will take 2 CPUs as an example:
  - CPU 0: ARM CPUX
  - CPU 1: DSP
- The channels of each CPU can be flexibly configured (this section will take 2 channels as an eaxmple), and the FIFO depth of a channel is 8 x 32 bits
- Supports interrupts

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4.3.2 Block Diagram

Figure 4- 3 DSP MSGBOX Block Diagram



4.3.3 Functional Description

4.3.3.1 Clock and Reset

The MSGBOX is mounted on AHB. Before accessing the MSGBOX registers, you need to de-assert the MSGBOX reset signal on AHB bus and then open the MSGBOX gating signal on AHB bus.

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4.3.3.2 Typical Application

Several masters can build communication by configuring the MSGBOX. The communication parties have at least two dua channels. During the communication process, the current status can be judged through the interrupt or FIFO status.

4.3.3.3 Transmitter/Receiver Mode

At the same channel, user1 is fixed as transmitter, user0 is fixed as receiver.

4.3.3.4 Interrupt

Each channel can configure indepedently the interrupt enable bit, a read interrupt will be generated when the channel is empty, a write interrupt will be generated when the channel is non-full. For each CPU, all channels generate a read interrupt together, that is, if only a channel is non-full, the read interrupt will be generated, this channel can be obtained by quering the interrupt status register.

4.3.3.5 FIFO Status

When channel FIFO is non-full, the FIFO_FULL_FLAG is 0, at the moment the FIFO can be written.

When channel FIFO is full, the FIFO_FULL_FLAG is 1, at the moment if FIFO is written again, the first data of FIFO can be covered.

See **MSGBOX_MSG_STATUS_REG** for FIFO status.

4.3.4 Programming Guidelines

4.3.4.1 Checking the Transfer Status via the Interrupt

Follow the steps below to check the transfer status:

Step 1 Enable the interrupt for the channel: Configure the interrupt enable bits of transmitter/receiver through **MSGBOX_WR_IRQ_EN_REG**/**MSGBOX_RD_IRQ_EN_REG**. (user0: RX interrupt enable; user1: TX interrupt enable)

Step 2 Check the IRQ status of the corresponding queue through **MSGBOX_WR_IRQ_STATUS_REG** **or** **MSGBOX_RD_IRQ_STATUS_REG**.

- If the FIFO is not full, the channel generates a transmission interrupt to remind the transmitter to transmit data. Write data to the FIFO in the interrupt handler, then clear the pending bit of the transmitter in **MSGBOX_WR_IRQ_STATUS_REG** and the enable bit of the transmitter in **MSGBOX_WR_IRQ_EN_REG**.

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- If the FIFO has new data, the channel generates a reception interrupt to remind the receiver to receive data. Read data from the FIFO in interrupt handler, then clear the pending bit of the receiver in MSGBOX_RD_IRQ_STATUS_REG and the enable bit of the receiver in MSGBOX_RD_IRQ_EN_REG.

4.3.4.2 Checking the Transfer Status via the FIFO

Follow the steps below to check the FIFO status of the corresponding queue:

- If the FIFO is not full, the transmitter fills the FIFO to 8*32 bits.
- If the FIFO is full, the receiver reads the FIFO data, and reads MSGBOX_FIFO_STATUS_REG to acquire the current FIFO data amount and the FIFO data amount before reading, which means no data is dropped.

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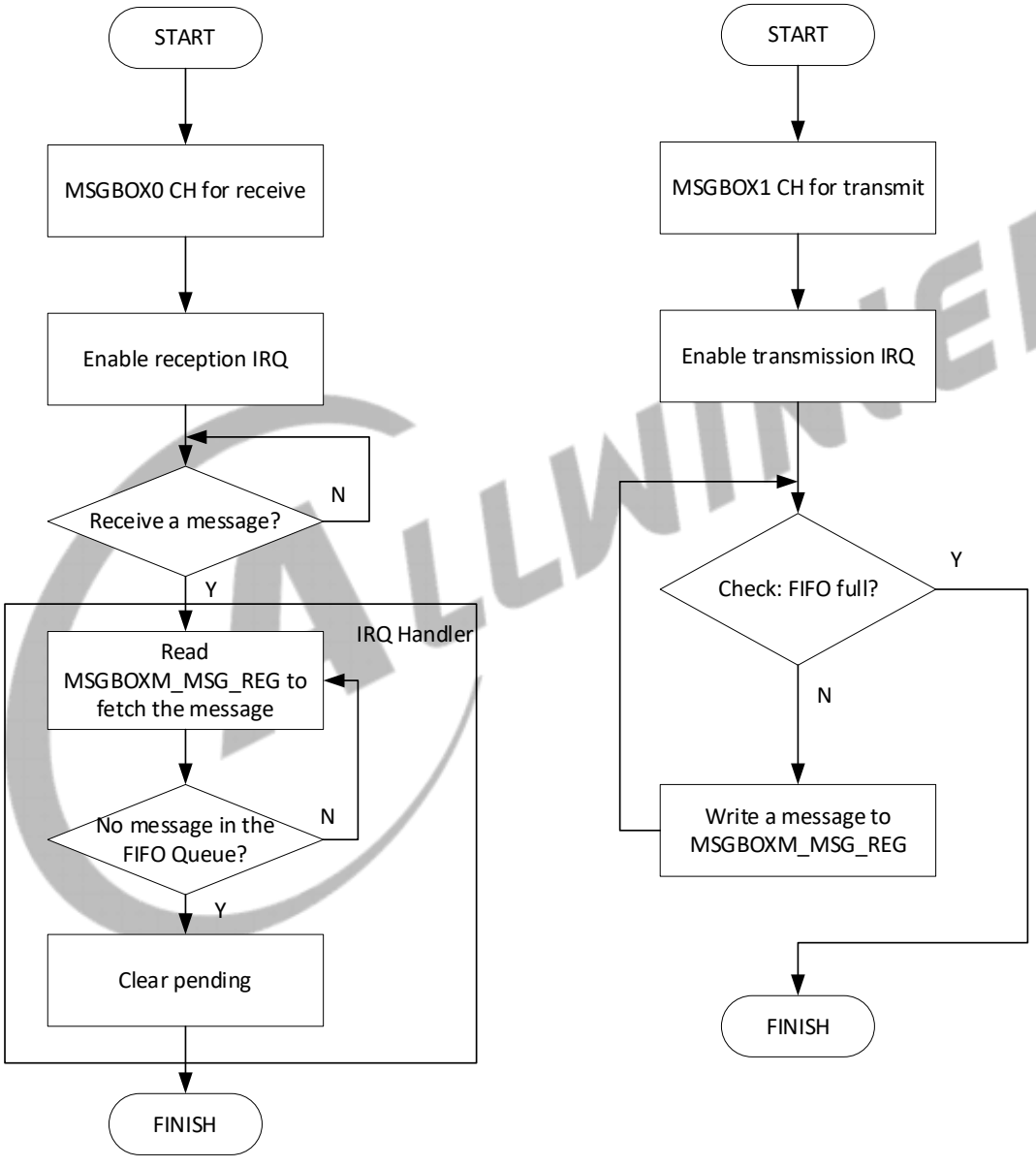
4.3.4.3 Transmitting/Receiving Message

Taking CPU0 as an example, the following figure shows the communication process between MSGBOX0 and MSGBOX1.

MSGBOX0: receiving message

MSGBOX1: transmitting message

Figure 4-4 The Communication Process between MSGBOX0 and MSGBOX1



4.3.5 Register List

Parameter	Description
M	MBOX Num(0-3)

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Parameter	Description
N	Dual channel Num in every MBox(0-3)
P	2(Dual channel, one for sync, one for async)

Module Name	Base Address	Comments
DSP_MSGBOX	0x0170_1000	DSP MSGBOX configuration register

Register Name	Offset	Description
MSGBOX_RD_IRQ_EN_REG	0x0020+M*0x400+N*0x100	MSGBox Read IRQ Enable Register
MSGBOX_RD_IRQ_STATUS_REG	0x0024+M*0x400+N*0x100	MSGBox Read IRQ Status Register
MSGBOX_WR_IRQ_EN_REG	0x0030+M*0x400+N*0x100	MSGBox Write IRQ Enable Register
MSGBOX_WR_IRQ_STATUS_REG	0x0034+M*0x400+N*0x100	MSGBox Write IRQ Status Register
MSGBOX_DEBUG_REG	0x0040+M*0x400+N*0x100	MSGBox Debug Register
MSGBOX_FIFO_STATUS_REG	0x0050+M*0x400+N*0x100 +P*0x0004(P=0~1)	MSGBox FIFO Status Register
MSGBOX_MSG_STATUS_REG	0x0060+M*0x400+N*0x100 +P*0x0004(P=0~1)	MSGBox Message Status Register m
MSGBOX_MSG_REG	0x0070+M*0x400+N*0x100 +P*0x0004(P=0~1)	MSGBox Message Queue Register

4.3.6 Register Description

4.3.6.1 MSGBox Read IRQ Enable Register (Default Value:0x00000000)

Offset: 0x0020+M*0x400+N*0x100			Register Name: MSGBOX_RD_IRQ_EN_REG
Bit	**R/W**	**Default/Hex**	**Description**
31:3	/	/	/
2	R/W	0x0	RECEPTION_MQ1_IRQ_EN. Reception MQ1 Interrupt Enable 0: Disable 1: Enable (It will notify user 0 by interrupt when Message Queue 1 has received a new message.)
1	/	/	/
0	R/W	0x0	RECEPTION_MQ0_IRQ_EN. Reception MQ0 Interrupt Enable 0: Disable 1: Enable (It will notify user 0 by interrupt when Message Queue 0 has received a new message.)

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4.3.6.2 MSGBox Read IRQ Status Register (Default Value:0x00000000)

Offset: 0x0024+M*0x400+N*0x100			Register Name: MSGBOX_RD_IRQ_STATUS_REG
Bit	**R/W**	**Default/Hex**	**Description**
31:3	/	/	/
2	R/W	0x0	RECEPTION_MQ1_IRQ_PEND. RECEPTION MQ1 IRQ PENDING 0: No effect, 1: Pending. This bit will be pending for user 0 when Message Queue 1 has received a new message. Set one to this bit will clear it.
1	/	/	/
0	R/W	0x0	RECEPTION_MQ0_IRQ_PEND. RECEPTION MQ0 IRQ PENDING 0: No effect, 1: Pending. This bit will be pending for user 0 when Message Queue 0 has received a new message. Set one to this bit will clear it.

4.3.6.3 MSGBox Write IRQ Enable Register (Default Value:0x00000000)

Offset: 0x0030+M*0x400+N*0x100			Register Name: MSGBOX_WR_IRQ_EN_REG
Bit	**R/W**	**Default/Hex**	**Description**
31:4	/	/	/
3	R/W	0x0	TRANSMIT_MQ1_IRQ_EN. TRANSMIT MQ1 IRQ Enable 0: Disable 1: Enable (It will Notify user 1 by interrupt when Message Queue 1 is not full.)
2	/	/	/
1	R/W	0x0	TRANSMIT_MQ0_IRQ_EN. TRANSMIT MQ0 IRQ Enable 0: Disable 1: Enable (It will Notify user 1 by interrupt when Message Queue 0 is not full.)
0	/	/	/

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4.3.6.4 MSGBox Write IRQ Status Register (Default Value:0x0000000A)

Offset: 0x0034+M*0x400+N*0x100			Register Name: MSGBOX_WR_IRQ_STATUS_REG
Bit	**R/W**	**Default/Hex**	**Description**
31:16	/	/	/
3	R/W	0x1	TRANSMIT_MQ1_IRQ_PEND. TRANSMIT MQ1 IRQ Pending 0: No effect, 1: Pending. This bit will be pending for user 1 when Message Queue 1 is not full. Set one to this bit will clear it.
2	/	/	/
1	R/W	01	TRANSMIT_MQ0_IRQ_PEND. TRANSMIT MQ0 IRQ Pending 0: No effect, 1: Pending. This bit will be pending for user 1 when Message Queue 0 is not full. Set one to this bit will clear it.
0	/	/	/

4.3.6.5 MSGBox Debug Register (Default Value:0x00000000)

Offset: 0x0040+M*0x400+N*0x100			Register Name: MSGBOX_DEBUG_REG
Bit	**R/W**	**Default/Hex**	**Description**
31:16	/	/	/
15:8	R/W	0x0	FIFO_CTRL. MQ[7:0] Control. In the debug mode, the corresponding FIFO channel will disable and only one register space valid for a message exchange. 0: Normal Mode. 1: Disable the corresponding FIFO (Clear FIFO).
7:1	/	/	/
0	R/W	0x0	DEBUG_MODE. In the Debug Mode, each user can transmit messages to itself through each Message Queue. 0: Normal Mode 1: Debug Mode.

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4.3.6.6 MSGBox FIFO Status Register (Default Value:0x00000000)

Offset:0x0050+M*0x400+N*0x100+P*0x0004(P=0~1)			Register Name: MSGBOX_FIFO_STATUS_REG
Bit	**R/W**	**Default/Hex**	**Description**
31: 1	/	/	/
0	R	0x0	FIFO_FULL_FLAG. FIFO FULL FLAG 0: The Message FIFO queue is not full (space is available), 1: The Message FIFO queue is full. This FIFO status register has the status related to the message queue.

4.3.6.7 MSGBox Message Status Register m (Default Value:0x00000000)

Offset:0x0060+M*0x400+N*0x100+P*0x0004(P=0~1)			Register Name: MSGBOX_MSG_STATUS_REG
Bit	**R/W**	**Default/Hex**	**Description**
31:4	/	/	/
3:0	R	0x0	MSG_NUM. Number of unread messages in the message queue. Here, limited to eight messages per message queue. 0000: There is no message in the message FIFO queue. 0001: There is 1 message in the message FIFO queue. 0010: There are 2 messages in the message FIFO queue. 0011: There are 3 messages in the message FIFO queue. 0100: There are 4 messages in the message FIFO queue. 0101: There are 5 messages in the message FIFO queue. 0110: There are 6 messages in the message FIFO queue. 0111: There are 7 messages in the message FIFO queue. 1000: There are 8 messages in the message FIFO queue. 1001~1111:/

4.3.6.8 MSGBox Message Queue Register (Default Value:0x00000000)

Offset:0x0070+M*0x400+N*0x100+P*0x0004(P=0~1)			Register Name: MSGBOX_MSG_REG
Bit	**R/W**	**Default/Hex**	**Description**
31:0	R/W	0x0	The message register stores the next to be read message of the message FIFO queue. Reads remove the message from the FIFO queue.

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5 Video and Graphics

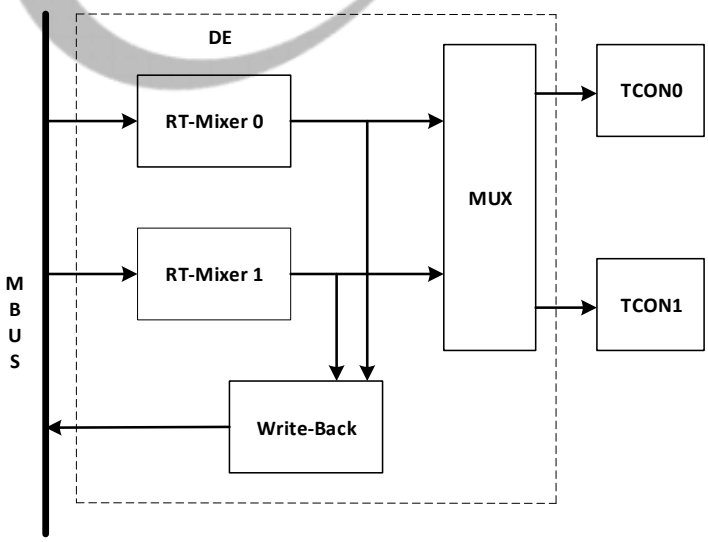
5.1 DE

The Display Engine (DE) is a hardware composer to transfer image layers from a local bus or a video buffer to the LCD interface. The DE supports four overlay windows to blend, and supports image post-processing in the video channel. The block diagram of DE is shown in Figure 4-1.

The DE has the following features:

- Output size up to 2048 x 2048
- Four alpha blending channels for main display, three channels for aux display
- Four overlay layers in each channel, and has a independent scaler
- Potter-duff compatible blending operation
- Supports input format Semi-planar YUV422/YUV420/YUV411 and Planar YUV422/YUV420/YUV411, ARGB8888/XRGB8888/RGB888/ARGB4444/ARGB1555/RGB565/palette
- Supports SmartColor2.0 for excellent display experience
  - Adaptive detail/edge enhancement
  - Adaptive color enhancement
  - Adaptive contrast enhancement and fresh tone rectify
- Supports write back for aux display

Figure 5-1 DE Block Diagram



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5.2 DI

The De-interlacer (DI) converts the interlaced input video frame to progressive video frame.

The DI has the following features:

- Supports YUV420 (Planar/NV12/NV21) and YUV422 (Planar/NV16/NV61) data format
- Supports video resolution from 32x32 to 2048x1280 pixel
- Supports Inter-field interpolation/motion adaptive de-interlace method
- Performance: module clock 600M for 1080p@60Hz YUV420

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5.3 G2D

The Graphic 2D (G2D) engine is hardware accelerator for 2D graphic.

The G2D has the following features:

- Supports layer size up to 2048 x 2048 pixels
- Supports pre-multiply alpha image data
- Supports color key
- Supports two pipes Porter-Duff alpha blending
- Supports multiple video formats 4:2:0, 4:2:2, 4:1:1 and multiple pixel formats (8/16/24/32 bits graphics layer)
- Supports memory scan order option
- Supports any format convert function
- Supports 1/16× to 32× resize ratio
- Supports 32-phase 8-tap horizontal anti-alias filter and 32-phase 4-tap vertical anti-alias filter
- Supports window clip
- Supports FillRectangle, BitBlit, StretchBlit and MaskBlit
- Supports horizontal and vertical flip, clockwise 0/90/180/270 degree rotate for normal buffer
- Supports horizontal flip, clockwise 0/90/270 degree rotate for LBC buffer

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5.4 Video Decoding

5.4.1 Overview

The Video Decoding consists of Video Control Firmware (VCF) running on ARM processor and embedded hardware Video Engine (VE). VCF gets the bitstream from topper software, parses bitstream, invokes the Video Engine, and generates the decoding image sequence. The decoder image sequence is transmitted by the video output controller to the display device under the control of the topper software.

The Video Decoding has the following features:

- Supports H.265 MP@L4.1
  - Maximum video resolution: 1920 x 1080
  - Maximum decoding rate: 60 Mbit/s, 1080p@60fps
- Supports H.264 BP/MP/HP@L4.2
  - Maximum video resolution: 1920 x 1080
  - Maximum decoding rate: 60 Mbit/s, 1080p@60fps
- Supports H.263 BP
  - Maximum video resolution: 1920 x 1080
  - Maximum decoding rate: 60 Mbit/s, 1080p@60fps
- Supports MPEG-4 SP/ASP L5.0
  - Maximum video resolution: 1920 x 1080
  - Maximum decoding rate: 60 Mbit/s, 1080p@60fps
- Supports MPEG-2 MP/HL
  - Maximum video resolution: 1920 x 1080
  - Maximum decoding rate: 60 Mbit/s, 1080p@60fps
- Supports MPEG-1 MP/HL
  - Maximum video resolution: 1920 x 1080
  - Maximum decoding rate: 60 Mbit/s, 1080p@60fps
- Supports JPEG/Xvid/Sorenson Spark
  - Maximum video resolution: 1920 x 1080
  - Maximum decoding rate: 60 Mbit/s, 1080p@60fps
- Supports MJPEG

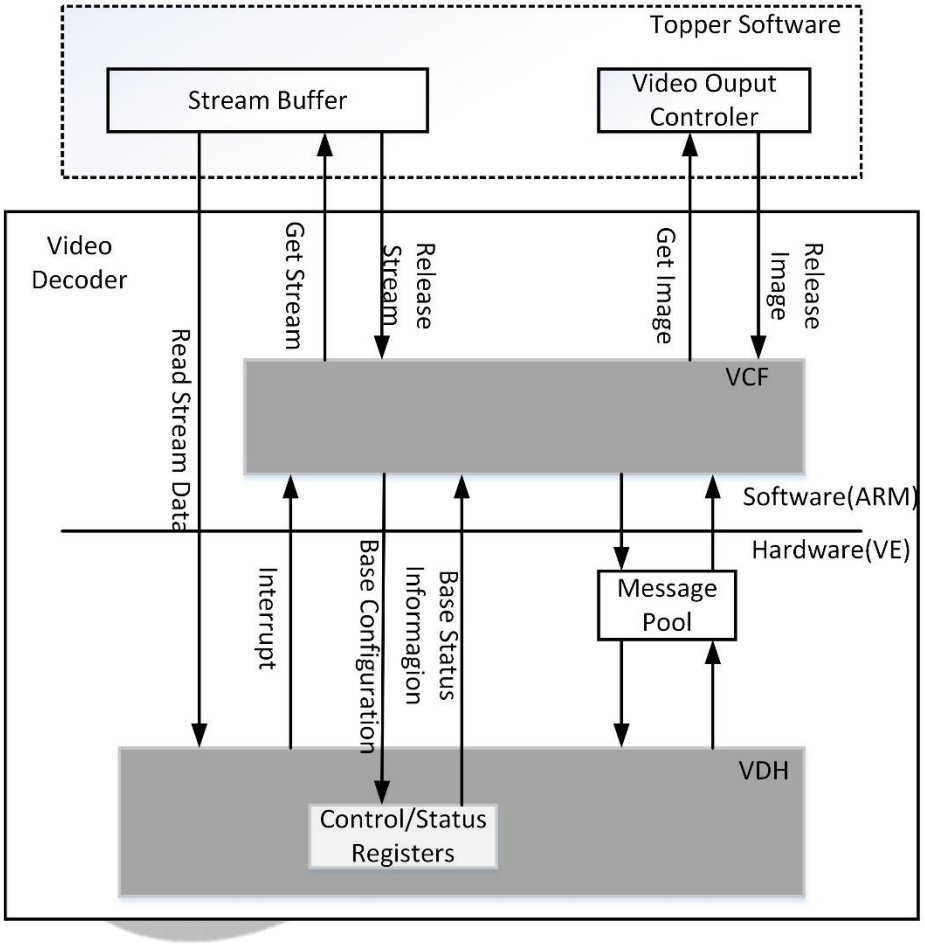
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- Maximum video resolution: 1920 x 1080
- Maximum decoding rate: 60 Mbit/s, 1080p@30fps

5.4.2 Block Diagram

The functional block diagram of the Video Decoding is as follows.

Figure 5 -2 Video Decoding Block Diagram



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5.5 Video Encoding

5.5.1 Overview

The Video Encoding supports JPEG/MJPEG encoding (JPGE).

The JPGE is a high-performance JPEG encoder implemented by using hardware. It supports 64-megapixel snapshot or HD MJPEG encoding.

The JPGE has the following features:

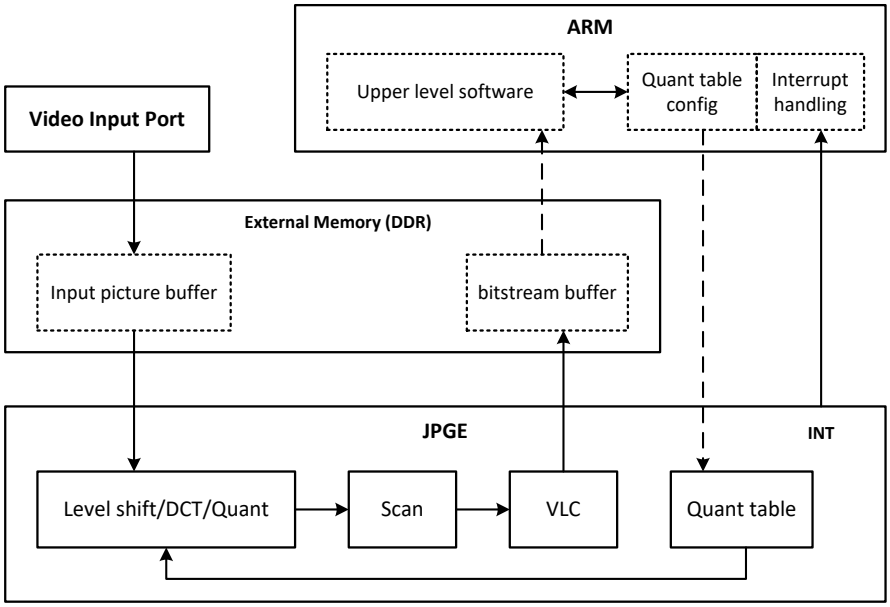
- Supports ISO/IEC 10918-1 (CCITT T.81) baseline process (DCT sequential) encoding
- Encodes the pictures in the chrominance sampling format of YCbCr4:2:0 and YCbCr4:2:2
- Supports multiple input picture formats:
  - Semi-planar YCbCr4:2:0
  - Semi-planar YCbCr4:2:2
- Supports JPEG encoding with the performance of 1080p@60fps
- Supports configurable picture resolutions
  - Minimum picture resolution: 192 x 96
  - Maximum picture resolution: 4096 x 4096
- Supports the picture width or height step of 8
- Supports configurable quantization tables for the Y component, Cb component and Cr component respectively
- Supports OSD front-end overlapping
  - OSD overlaying before encoding for a maximum of 16 regions
  - OSD overlaying with any size and at any position (within the size and position range of the picture)
  - 16-level alpha blending
  - OSD overlaying control (enabled or disabled)
- Supports the color-to-gray function
- Supports the MJPEG output bit rate ranging from 2 kbit/s to 60 Mbit/s

5.5.2 Block Diagram

The functional block diagram of the JPGE is as follows.

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Figure 5-3 JPGE Block Diagram



The JPGE realizes various protocol processing with large computation such as OSD, level shift, DCT, quantization, scanning, VLC encoding, and stream generation. The ARM software completes the encoding control processing such as quantization table configuration and interrupt processing.

Before the JPGE starts encoding, the software allocates two types of buffers mainly in the external DDR SDRAM:

- **Input picture buffer**

The JPGE reads the source pictures to be encoded from this buffer during encoding. This buffer is generally written by the Video Input Port module.

- **Stream buffer**

This buffer stores encoded streams. The JPGE writes streams to this buffer during encoding. This buffer is read by software.

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6 Video Output Interfaces

6.1 TCON LCD

6.1.1 Overview

The Timing Controller_LCD (TCON_LCD) is a module that processes video signals received from system through a complicated arithmetic and then generates control signals and transmits them to the LCD panel driver IC.

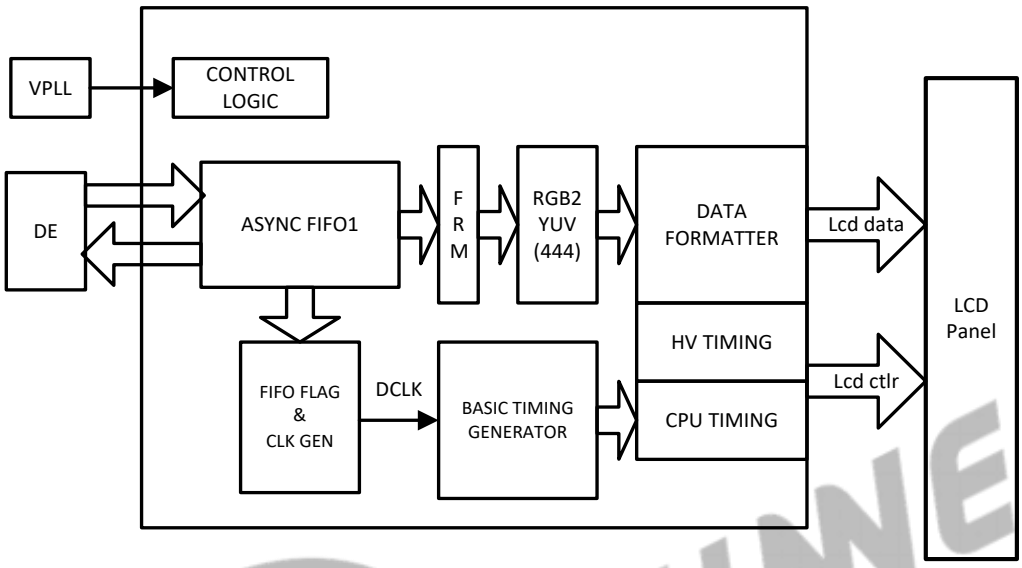
The TCON_LCD includes the following features:

- Supports RGB interface with DE/SYNC mode, up to 1920x1080@60fps
- Supports serial RGB/dummy RGB interface, up to 800x480@60fps
- Supports LVDS interface with dual link, up to 1920x1080@60fps
- Supports LVDS interface with single link, up to 1366x768@60fps
- Supports i8080 interface, up to 800x480@60fps
- Supports BT656 interface for NTSC and PAL
- Supports RGB666 and RGB565 with dither function
- Supports Gamma correction with R/G/B channel independence

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6.1.2 Block Diagram

Figure 6-1 TCON_LCD Block Diagram



6.1.3 Functional Description

6.1.3.1 External Signals

The LCD external signals are used to connect to panel interface. The panel interface has various types.

Table 6-1 LCD External Signals

Signal Name	Description	Type
LCD0-D[23:0]	LCD Data Output	O
LCD0-CLK	LCD Clock The pixel data are synchronized by this clock	O
LCD0-VSYNC	LCD Vertical Sync It indicates one new frame	O
LCD0-HSYNC	LCD Horizontal Sync It indicates one new scan line	O
LCD0-DE	LCD Data Output Enable	O
TCON-TRIG	LCD Sync (TCON outputs to LCD for sync)	O
LVDS0-CKP	LVDS0 Positive Port of Clock	O
LVDS0-CKN	LVDS0 Negative Port of Clock	O
LVDS0-V[3:0]P	LVDS0 Positive Port of Data Channel [3:0]	O

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Signal Name	Description	Type
LVDS0-V[3:0]N	LVDS0 Negative Port of Data Channel [3:0]	O
LVDS1-CKP	LVDS1 Positive Port of Clock	O
LVDS1-CKN	LVDS1 Negative Port of Clock	O
LVDS1-V[3:0]P	LVDS1 Positive Port of Data Channel [3:0]	O
LVDS1-V[3:0]N	LVDS1 Negative Port of Data Channel [3:0]	O

For parallel RGB, the data of LCD is high-aligned. The correspondence is as follows.

Table 6-2 The Correspondence between LCD and RGB

LCD I/O	Parallel RGB I/O		
	RGB565	RGB666	RGB888
LCD0-D23	R4	R5	R7
LCD0-D22	R3	R4	R6
LCD0-D21	R2	R3	R5
LCD0-D20	R1	R2	R4
LCD0-D19	R0	R1	R3
LCD0-D18	-	R0	R2
LCD0-D17	-	-	R1
LCD0-D16	-	-	R0
LCD0-D15	G5	G5	G7
LCD0-D14	G4	G4	G6
LCD0-D13	G3	G3	G5
LCD0-D12	G2	G2	G4
LCD0-D11	G1	G1	G3
LCD0-D10	G0	G0	G2
LCD0-D9	-	-	G1
LCD0-D8	-	-	G0
LCD0-D7	B4	B5	B7
LCD0-D6	B3	B4	B6
LCD0-D5	B2	B3	B5
LCD0-D4	B1	B2	B4
LCD0-D3	B0	B1	B3
LCD0-D2	-	B0	B2
LCD0-D1	-	-	B1
LCD0-D0	-	-	B0

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The multiplex relationship between LCD and LVDS is shown as follows.

Table 6-3 The Correspondence between LCD and LVDS

LCD I/O	LVDS I/O
LCD0-D2	LVDS0-V0P
LCD0-D3	LVDS0-V0N
LCD0-D4	LVDS0-V1P
LCD0-D5	LVDS0-V1N
LCD0-D6	LVDS0-V2P
LCD0-D7	LVDS0-V2N
LCD0-D10	LVDS0-CKP
LCD0-D11	LVDS0-CKN
LCD0-D12	LVDS0-V3P
LCD0-D13	LVDS0-V3N
LCD0-D14	LVDS1-V0P
LCD0-D15	LVDS1-V0N
LCD0-D18	LVDS1-V1P
LCD0-D19	LVDS1-V1N
LCD0-D20	LVDS1-V2P
LCD0-D21	LVDS1-V2N
LCD0-D22	LVDS1-CKP
LCD0-D23	LVDS1-CKN
LCD0-CLK	LVDS1-V3P
LCD0-DE	LVDS1-V3N

6.1.3.2 Control Signal and Data Port Mapping

		SYNC RGB					CPU Cmd	CPU 18-bit	CPU 16bit								CPU 8bit					CPU 9bit		LVDS		
External I/O	Internal pin	Para RGB	Serial RGB			CCIR 656		256K	256K							65K	256K				65K	256K		Single Link		Dual Link
			1st	2nd	3rd				1st	2nd	3rd	1st	2nd	1st	2nd		1st	2nd	3rd	1st	2n	1st	2n	1	2	
LCD0_VSYN	IO0	VSYNC					CS																			
LCD0_HSYN	IO1	HSYNC					RD																			

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LCD0_CLK	IO2	DCLK					WR																	D3P2	D3P2
LCD0_DE	IO3	DE					RS																	D3N2	D3N2
LCD0_D23	D23	R7				CK	D23	R5	R5	B5	G5	R5		R5	B5	R4								CKN2	CKN2
LCD0_D22	D22	R6				CKP	D22	R4	R4	B4	G4	R4		R4	B4	R3								CKP2	CKP2
LCD0_D21	D21	R5				D2	D21	R3	R3	B3	G3	R3		R3	B3	R2								D2N2	D2N2
LCD0_D20	D20	R4				D2	D20	R2	R2	B2	G2	R2		R2	B2	R1								D2P2	D2P2
LCD0_D19	D19	R3				D1	D19	R1	R1	B1	G1	R1		R1	B1	R0								D1N2	D1N2
LCD0_D18	D18	R2				D1	D18	R0	R0	B0	G0	R0		R0	B0	G5								D1P2	D1P2
LCD0_D17	D17	R1					D17																		
LCD0_D16	D16	R0					D16																		
LCD0_D15	D15	G7				D0	D15	G5								G4								D0N2	D0N2
LCD0_D14	D14	G6				D0	D14	G4								G3								D0P2	D0P2
LCD0_D13	D13	G5					D13	G3															D3N1		D3N1
LCD0_D12	D12	G4	D71	D72	D73	D7	D12	G2	G5	R5	B5	G5	B5	G5		G2	R5	G5	B5	R4	G2	R5	G2	D3P1		D3P1
LCD0_D11	D11	G3	D61	D62	D63	D6	D11	G1	G4	R4	B4	G4	B4	G4		G1	R4	G4	B4	R3	G1	R4	G1	CKN1		CKN1
LCD0_D10	D10	G2	D51	D52	D53	D5	D10	G0	G3	R3	B3	G3	B3	G3		G0	R3	G3	B3	R2	G0	R3	G0	CKP1		CKP1
LCD0_D9	D9	G1					D9																		
LCD0_D8	D8	G0					D8																		
LCD0_D7	D7	B7	D41	D42	D43	D4	D7	B5	G2	R2	B2	G2	B2	G2		B4	R2	G2	B2	R1	B4	R2	B5	D2N1		D2N1
LCD0_D6	D6	B6	D31	D32	D33	D3	D6	B4	G1	R1	B1	G1	B1	G1		B3	R1	G1	B1	R0	B3	R1	B4	D2P1		D2P1
LCD0_D5	D5	B5	D21	D22	D23	D2	D5	B3	G0	R0	B0	G0	B0	G0		B2	R0	G0	B0	G5	B2	R0	B3	D1N1		D1N1
LCD0_D4	D4	B4	D11	D12	D13	D1	D4	B2								B1				G4	B1	G5	B2	D1P1		D1P1
LCD0_D3	D3	B3	D01	D02	D03	D0	D3	B1								B0				G3	B0	G4	B1	D0N1		D0N1
LCD0_D2	D2	B2					D2	B0														G3	B0	D0P1		D0P1
LCD0_D1	D1	B1					D1																			
LCD0_D0	D0	B0					D0																			

6.1.3.3 HV interface (Sync+DE mode)

HV I/F is also known as Sync + DE mode, which is widely used in TFT LCD module for PMP/MP4 applications.

Its signals are define as:

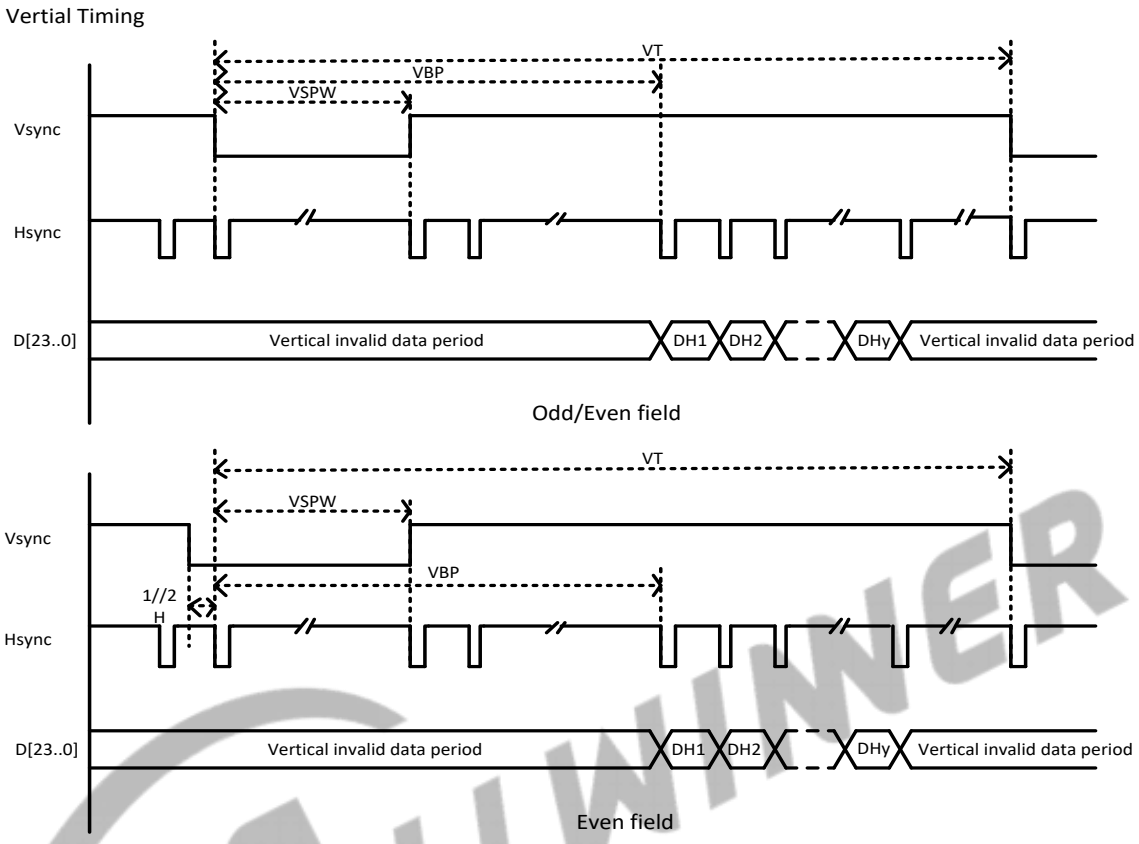
Table 6-4 HV Panel Signals

Signal Name	Description	Type
Vsync	Vertical sync, indicates one new frame	O
Hsync	Horizontal sync, indicates one new scan line	O
DCLK	Dot clock, pixel data are sync by this clock	O
DE	LCD data enable	O
D[23..0]	24-bit RGB output from input FIFO for panel	O

The timing diagram of HV interface is as follows.

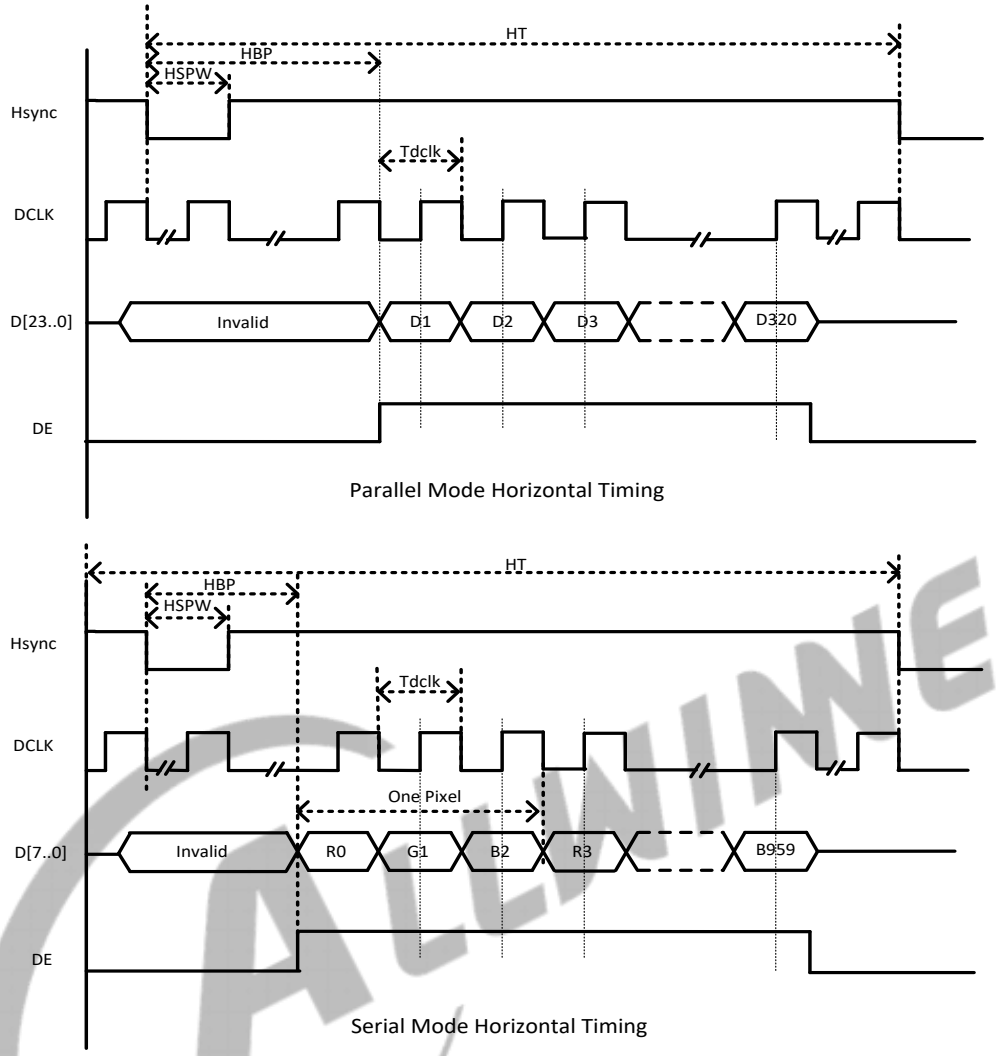
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Figure 6-2 HV Interface Vertical Timing



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Figure 6-3 HV Interface Horizontal Timing



6.1.3.4 BT656 Interface

In HV serial YUV output mode, its timing is BT656 compatible. SAV adds right before active area every line; EAV adds right after active area every line.

Table 6-5 BT656 Panel Signals

Signal Name	Description	Type
DCLK	Clock signal	O
DATA[7:0]	Data signal	O

Its logic is:

F = “0” for Field 1 F = “1” for Field 2

V = “1” during vertical blanking

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H = “0” at SAV H = “1” at EAV

P3-P0 = protection bits

P3 = V ⊕ H

P2 = F ⊕ H

P1 = F ⊕ V

P0 = F ⊕ V ⊕ H

Where ⊕ represents the exclusive-OR function.

The 4 byte SAV/EAV sequence is as follows.

Table 6-6 EAV and SAV Sequence

	8-bit Data								10-bit Data	
	D9 (MSB)	D8	D7	D6	D5	D4	D3	D2	D1	D0
Preamble	1	1	1	1	1	1	1	1	1	1
	0	0	0	0	0	0	0	0	0	0
	0	0	0	0	0	0	0	0	0	0
Status word	1	F	V	H	P3	P2	P1	P0	0	0

6.1.3.5 i8080 Interface

The i8080 I/F LCD panel is most common interface for small size, low resolution LCD panels. The CPU control signals are active low.

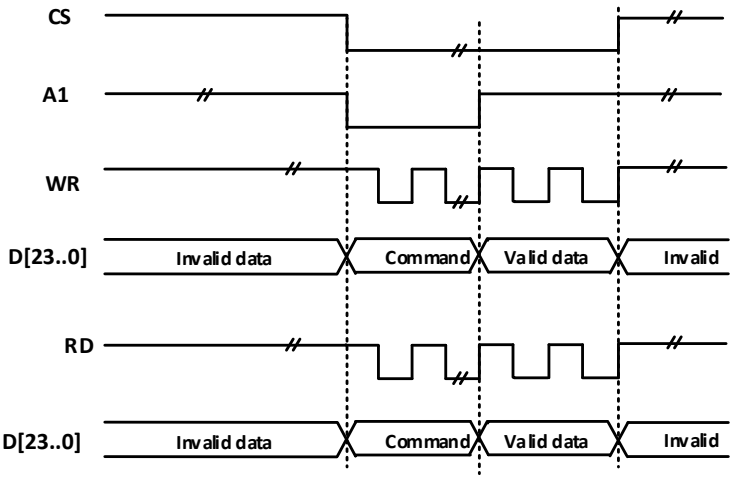
Table 6-7 CPU Panel Signals

Signal Name	Description	Type
CS	Chip select, active low	O
WR	Write strobe, active low	O
RD	Read strobe, active low	O
A1	Address bit, controlled by "LCD_CPUI/F" BIT26/25	O
D[23..0]	Digital RGB output signal	I/O

The following figure relationship between basic timing and CPU timing. WR is 180^{o} delay of DCLK; CS is active when pixel data is valid; RD is always set to 1; A1 is set by “LCD_CPUI/F”.

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Figure 6-4 i8080 Interface Timing



When CPU I/F is in IDLE state, it can generate WR/RD timing by setting "**Lcd_CPUI/F**". The CS strobe is one DCLK width, and the WR/RD strobe is half DCLK width.

6.1.3.6 LVDS Interface

Table 6-8 LVDS Panel Signals

Signal Name	Description	Type
CKP	The positive port of clock	O
CKN	The negative port of clock	O
D0P	The positive port of data channel 0	O
D0N	The negative port of data channel 0	O
D1P	The positive port of data channel 1	O
D1N	The negative port of data channel 1	O
D2P	The positive port of data channel 2	O
D2N	The negative port of data channel 2	O
D3P	The positive port of data channel 3	O
D3N	The negative port of data channel 3	O

The following figures show the timing of LVDS interface.

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Figure 6-5 LVDS Single Link JEDIA Mode Interface Timing

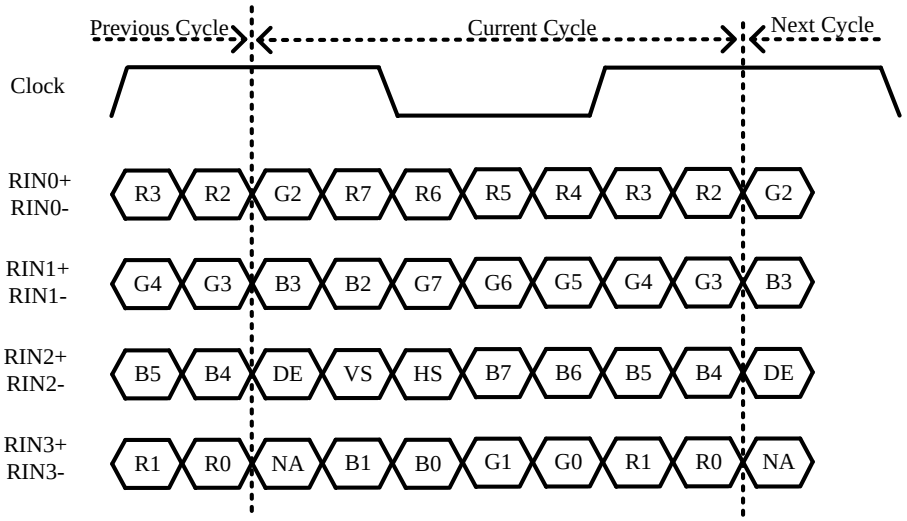
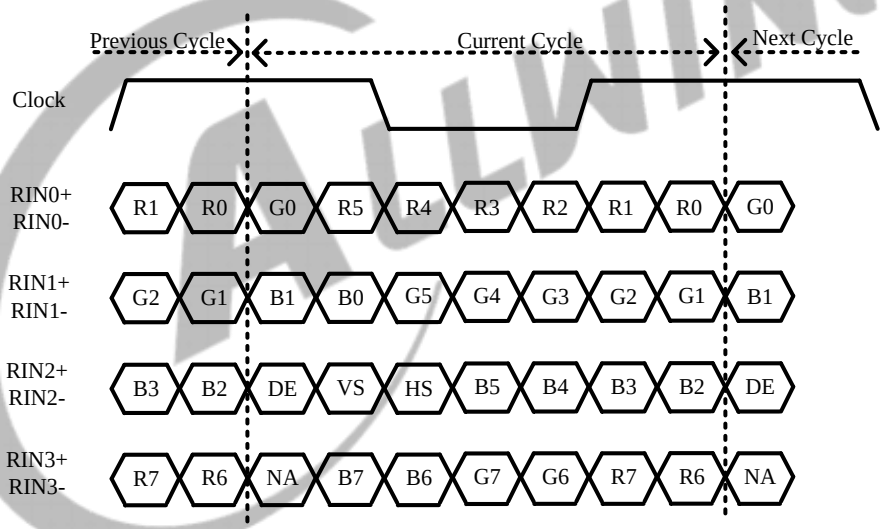
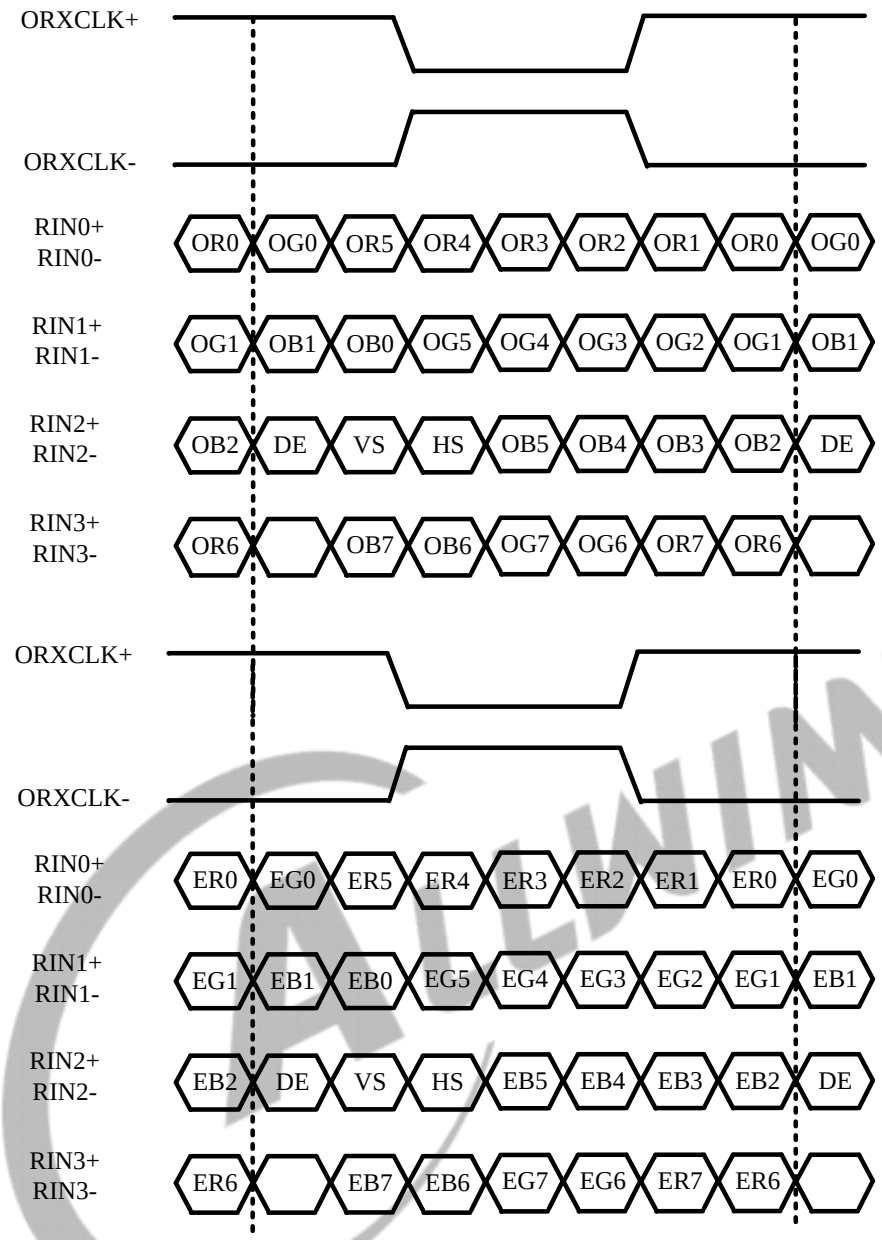


Figure 6-6 LVDS Single Link NS Mode Interface Timing



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Figure 6-7 LVDS Dual Link NS Mode Interface Timing



6.1.3.7 Clock Sources

The following table describes the clock sources of TCON_LCD. Table 6-9 describes the clock sources of TCON_LCD.

Table 6-9 TCON_LCD Clock Sources

Clock Sources	Description
PLL_VIDEO0(1X)	By default, PLL_VIDEO0(4X) is 1188 MHz, PLL_VIDEO0(1X) is 297 MHz
PLL_VIDEO0(4X)	

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Clock Sources	Description
PLL_VIDEO1(1X)	By default, PLL_VIDEO1(4X) is 1188 MHz, PLL_VIDEO1(1X) is 297 MHz
PLL_VIDEO1(4X)	
PLL_PERI(2X)	By default, PLL_PERI(2X) is 1.2 GHz
PLL_AUDIO1(DIV2)	By default, PLL_AUDIO1 is 3072 MHz, PLL_AUDIO1(DIV2) is 1536 MHz

6.1.3.8 RGB Gamma Correction

Function: This module correct the RGB input data of DE.

A 256*8*3 Byte register file is used to store the gamma table.

Table 6-10 RGB Gamma Correction Table

Offset	Value
0x400	{B0[7:0], G0[7:0], R0[7:0]}
0x404	{B1[7:0], G1[7:0], R1[7:0]}
.....	.....
0x7FC	{B255[7:0], G255[7:0], R255[7:0]}

6.1.3.9 CEU Module

This module enhances color data from DE .

R' = Rr*R + Rg*G + Rb*B + Rc

G' = Gr*R + Gg*G + Gb*B + Gc

B' = Br*R + Bg*G + Bb*B + Bc

Rr, Rg, Rb, Gr, Gg, Gb, Br, Bg, Bb s13 (-16, 16)

Rc, Gc, Bc s19 (-16384, 16384)

R, G, B u8 [0-255]

R' has the range of [Rmin ,Rmax]

G' has the range of [Rmin ,Rmax]

B' has the range of [Rmin ,Rmax]

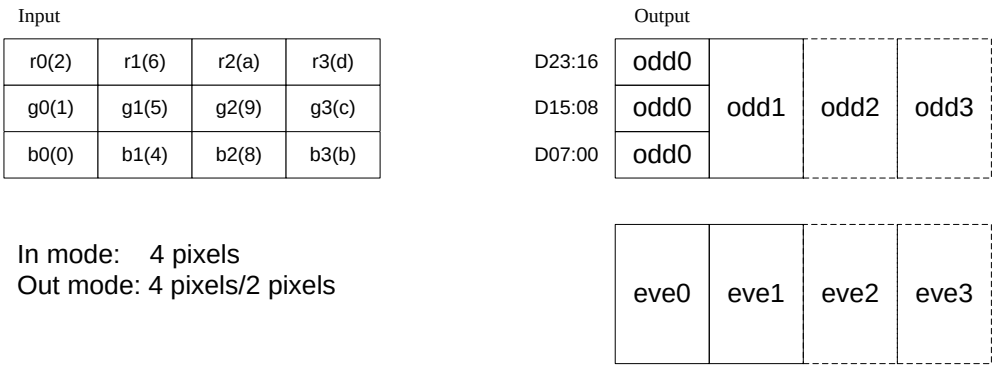
6.1.3.10 CMAP Module

Function: This module map color data from DE.

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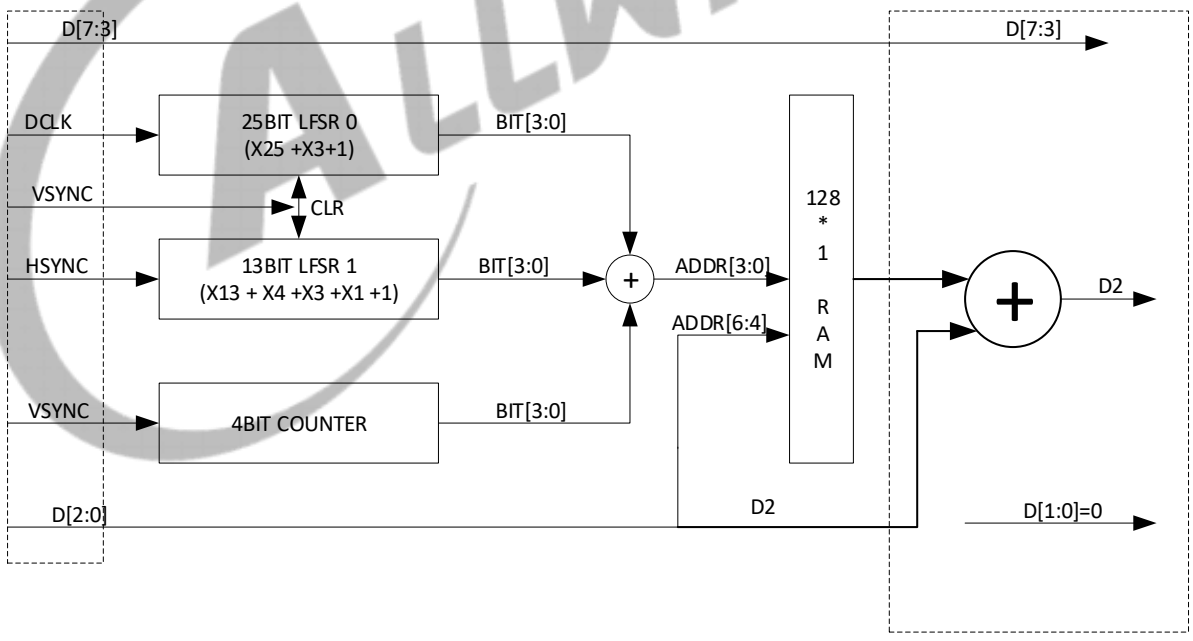
Every 4 input pixels are as a unit. A unit is divided into 12 bytes. Output byte can select one of those 12 bytes. Note that even line and odd line can be different, and output can be 12 bytes (4 pixels) or reduce to 6 bytes (2 pixels).

Figure 6-8 CMAP Module



6.1.3.11 FRM Module

Figure 6-9 FRM Module



6.1.3.12 MIPI DSI

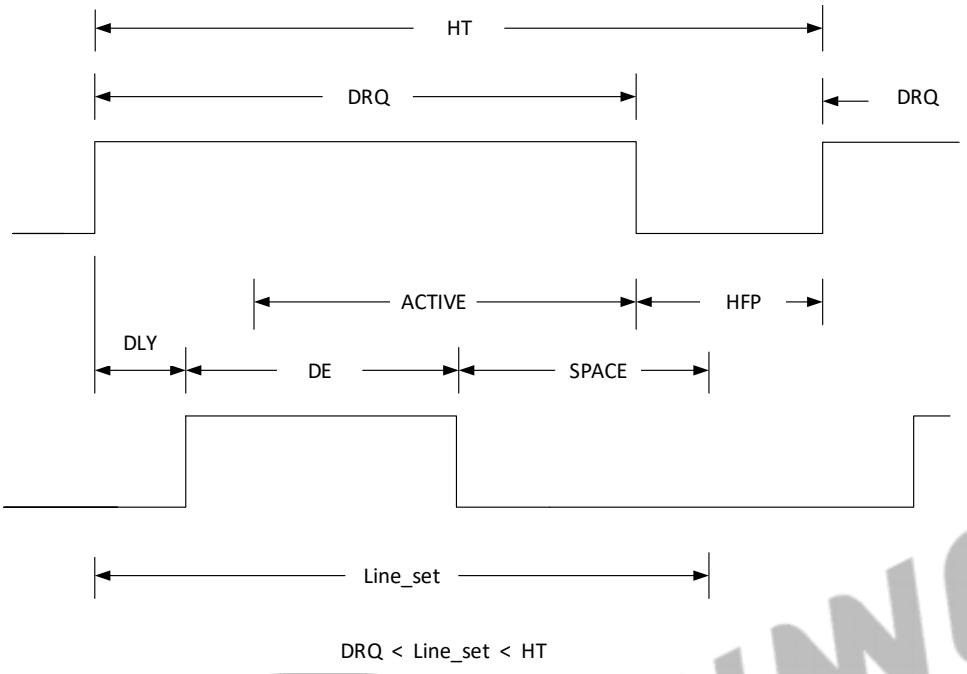
The requirements on MIPI DSI mode are as follows.

(1). When using MIPI DSI as display interface, the data clk of TCON needs be started firstly.

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(2). When it is used with DSI video mode, the setting of block space needs to meet the following relationship.

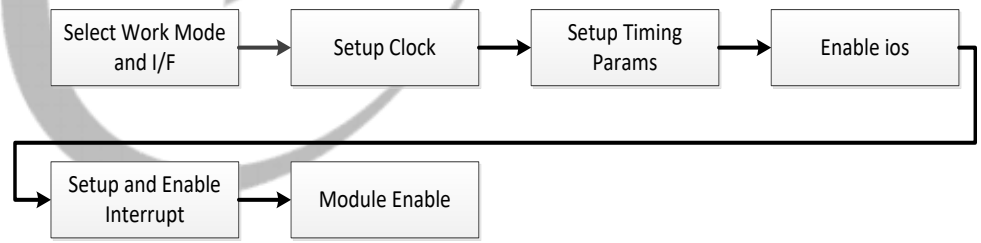
Figure 6-10 The Data Timing of MIPI DSI Video Mode



6.1.4 Programming Guidelines

6.1.4.1 HV Mode Configuration Process

Figure 6-11 HV Mode Initial Process



(1) Parallel RGB

Step 1 Select HV interface type

Configure LCD_CTL_REG[LCD_IF] (reg0x40) to 0 to select HV (Sync+DE) mode, and configure LCD_HV_IF_REG[HV_MODE] (reg0x58) to 0 to select 24bit/1cycle parallel mode.

```
lcd_dev[sel]->lcd_ctl.lcd_if = HV(Sync+DE);

lcd_dev[sel]->lcd_ctl.src_sel = src;      //src = DE/color/grayscale/...
```

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lcd_dev[sel]->lcd_hv_ctl.hv_mode = 24bit/1cycle parallel mode;

Step 2 Clock configuration

NOTE

- In parallel RGB mode, the displayed pixel clock (pixel_CLK) is required to be consistent with the DCLK, the pixel_clk(pixel_clk=Ht*Vt*frame rate) is decided by external LCD.
- When using phase adjustment function, the LCD_IO_POL_REG.DCLK_SEL (reg0x88) selects dclk0–2 of different phase, and LCD_IO_POL_REG.IO2_INV can achieve 180°phase delay.

Configure corresponding frequency by setting PLL_VIDEO0/1 register, and configure TCON LCD0 Clock register.

Configure internal frequency division of TCON_LCD. Based on clock source of TCON and DCLK clock ratio, configure LCD_DCLK_REG[LCD_DCLK_DIV]. If using phase adjustment function, LCD_DCLK_REG[LCD_DCLK_EN] needs be set, usually is 0xf. When the dclk1 and dclk2 in LCD_DCLK_REG[LCD_DCLK_EN] are used, the value of LCD_DCLK_REG[LCD_DCLK_DIV] needs no less than 6.

lcd_dev[sel]->lcd_dclk.dclk_en = en;

lcd_dev[sel]->lcd_dclk.dclk_div = div;

Step 3 Set sequence parameters

The sequence parameters include x,ht,hbp,hspw,y,vt,vbp,vspw, and correspond to LCD_BASE_REG from reg0x48 to reg 0x54. Note that hbp includes hspw, and vbp includes vspw. And LCD_BASE2_REG.VT needs be set to the twice of the actual value.

lcd_dev[sel]->lcd_basic0.x = x-1;

lcd_dev[sel]->lcd_basic0.y = y-1;

lcd_dev[sel]->lcd_basic1.ht = ht-1;

lcd_dev[sel]->lcd_basic1.hbp = hbp-1;

lcd_dev[sel]->lcd_basic2.vt = vt*2;

lcd_dev[sel]->lcd_basic2.vbp = vbp-1;

lcd_dev[sel]->lcd_basic3.hspw = hspw-1;

lcd_dev[sel]->lcd_basic3.vspw = vspw-1;

Step 4 Open IO output

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Set the corresponding data IO enable and control signal IO enable of LCD_IO_TRI_REG (reg0x8C) to 0 to start enable. Note that except the internal IO of TCON_LCD, the external GPIO mapping needs to be set to LCD mode.

When some control signals require polarity reversal, it can realize by setting LCD_IO_POL_REG.IO0~3_INV (reg0x88).

Step 5 Set and open interrupt function

The LCD_GINT0_REG (reg0x4) controls interrupt mode and flag, and the LCD_GINT1_REG (reg0x8) sets the interrupt line position of Line interrupt mode.

V interrupt:

lcd_dev[sel]->lcd_gint0.vb_en = 1;

Line interrupt:

lcd_dev[sel]->lcd_gint1.lcd_line_int_num = line;

lcd_dev[sel]->lcd_gint0.line_en = 1;

Step 6 Open module enable

Enable LCD_CTL_REG.LCD_EN (reg0x40) and LCD_GCTL_REG.LCD_EN (reg0x00).

lcd_dev[sel]->lcd_ctl.lcd_en = 1;

lcd_dev[sel]->lcd_gctl.lcd_en = 1;

(2) Serial RGB

The serial RGB mode is consistent with parallel RGB mode, the main difference is the definition of clock and the sequence of serial data. The difference is as follows.

Step 1 Select HV interface type

Set LCD_CTL_REG.LCD_IF (reg0x40) to 0 to select HV(Sync+DE) mode; set LCD_HV_IF_REG.HV_MODE (reg0x58) to select 8bit/3cycle RGB serial mode (RGB888), 8bit/4cycle Dummy RGB mode (DRGB) or 8bit/4cycle RGB Dummy mode (RGBD).

lcd_dev[sel]->lcd_ctl.lcd_if = HV(Sync+DE);

lcd_dev[sel]->lcd_ctl.src_sel = src; //src = DE/color/grayscale/...

lcd_dev[sel]->lcd_hv_ctl.hv_mode = Serial mode;

Step2、Step3: Set clock and sequence parameters

In serial RGB mode, DCLK is the transfer clock of each byte data. In the same resolution, pixel_clk of serial RGB is three times of its clock in parallel RGB, and ht,hbp,hspw own the same conversion

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relation. When display is split into odd field and even field, LCD_BASE2_REG.VT needs not to be set to the twice of the actual value.

lcd_dev[sel]->lcd_basic2.vt = vt;

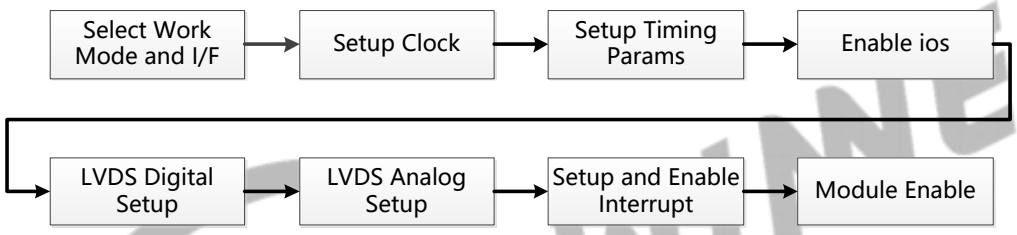
Set LCD_HV_IF_REG.RGB888_ODD_ORDER/LCD_HV_IF_REG.RGB888_ODD_EVEN to select RGB output sequence of the selected odd and even lines.

lcd_dev[lcd_sel]->lcd_hv_ctl.srgb_seq_even = seq_even;

lcd_dev[lcd_sel]->lcd_hv_ctl.srgb_seq_odd = seq_odd;

6.1.4.2 LVDS Mode Configuration Process

Figure 6-12 LVDS Mode Configuration Process



The LVDS interface configuration process is similar to the parallel mode of HV mode, and adds the digital/analog configuration of LVDS interface.

Step 1 Same as in step1 of parallel mode

Step 2 Clock configuration

NOTE

In parallel mode, the displayed pixel clock (pixel_CLK) is required to be consistent with the DCLK, pixel_clk=Ht*Vt*frame rate.

- Configure LCD_DCLK_REG.LCD_DCLK_DIV (reg0x44) to 7 after DCLK is determined;
- Configure the PLL clock in CCU based on proportional relationship;
- Release the LVDS reset of TCON LCD BUS GATING RESET register;
- Other configurations remain unchanged.

  lcd_dev[sel]->lcd_dclk.dclk_en = en;

  lcd_dev[sel]->lcd_dclk.dclk_div = 7;

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Step 3 **Same as in step3 of parallel mode**

Step 4 **Same as in step4 of parallel mode**

Step 5 **LVDS digital logic configuration**

Includes clock source select of module, LVDS link number, data mode and bit width configuration.

- Configure LCD_LVDS_IF_REG.LCD_LVDS_CLK_SEL (reg0x84) to set LCD CLK;
- Configure LCD_LVDS_IF_REG.LCD_LVDS_LINK to set the required LVDS port number;
- Configure LCD_LVDS_IF_REG.LCD_LVDS_MODE to set JEDIA and NS mode;
- Configure LCD_LVDS_IF_REG.LCD_LVDS_BITWIDTH to select 24-bit or 18-bit width;
- Lastly configure LCD_LVDS_IF_REG.LCD_LVDS_EN to start LVDS mode.

```
lcd_dev[sel]->lcd_lvds_ctl.lvds_link = link_num-1;
lcd_dev[sel]->lcd_lvds_ctl.lvds_mode = mode;
lcd_dev[sel]->lcd_lvds_ctl.lvds_bitwidth = bitwidth;
lcd_dev[sel]->lcd_lvds_ctl.lvds_clk_sel = clk_src;
lcd_dev[sel]->lcd_lvds_ctl.lvds_en = 1;
```

NOTE

If configuring the same source data output mode of dual link, except the reg0x84 register of TCON_LCD0 needs be configured, the LCD_LVDS_IF_REG.LCD_LVDS_CLK_SEL, LCD_LVDS_IF_REG.LCD_LVDS_LINK, LCD_LVDS_IF_REG.LCD_LVDS_MODE, and LCD_LVDS_IF_REG.LCD_LVDS_BITWIDTH of the reg0x244 register need be configured.

Step 6 **LVDS controller configuration**

NOTE

The TCON LCD0 PHY0 is controlled by COMBO_PHY_REG (reg0x1110, reg0x1114). The TCON LCD0 PHY1 is controlled by LCD_LVDS0_ANA_REG (reg0x220).

For PHY0:

- Configure the reg_verf1p6 (differential mode voltage) in reg0x1114 to 4;

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- Configure the reg_vref0p8 reg0x1114 (common mode voltage) in reg0x1114 to 3;
- Start en_cp, en_mipi, en_lvds, and en_comboldo in reg0x1110, in turn.

For PHY1:

The LVDS analog configuration process is to start clock and data channel, and set the common mode and differential mode voltage, and start module power.

- Configure LVDS_HPREN_DRVC and LVDS_HPREN_DRV. When LVDS signal is 18-bit, LVDS_HPREN_DRV=0x7; when LVDS signal is 24-bit, LVDS_HPREN_DRV=0xF;
- Configure LVDS0_REG_C (differential mode voltage) to 4;
- Configure LVDS0_REG_V (common mode voltage) to 3;
- Lastly, start module voltage, and enable EN_LVDS and EN_24M.

```
lcd_dev[sel]->lcd_lvds_ana_ctl[lvds_num].bits.en_drvd = 0x7; //18-bit=0x7, 24-bit=0xf
lcd_dev[sel]->lcd_lvds_ana_ctl[lvds_num].bits.en_drvc = 1;
lcd_dev[sel]->lcd_lvds_ana_ctl[lvds_num].bits.diff_level = diff;
lcd_dev[sel]->lcd_lvds_ana_ctl[lvds_num].bits.com_level = com;
lcd_dev[sel]->lcd_lvds_ana_ctl[lvds_num].bits.dual_src = link_src;
lcd_dev[sel]->lcd_lvds_ana_ctl[lvds_num].bits.en_24M = 1;
lcd_dev[sel]->lcd_lvds_ana_ctl[lvds_num].bits.en_lvds = 1;
lcd_dev[sel]->lcd_lvds_ana_ctl[lvds_num].bits.en_mb = 1;
```

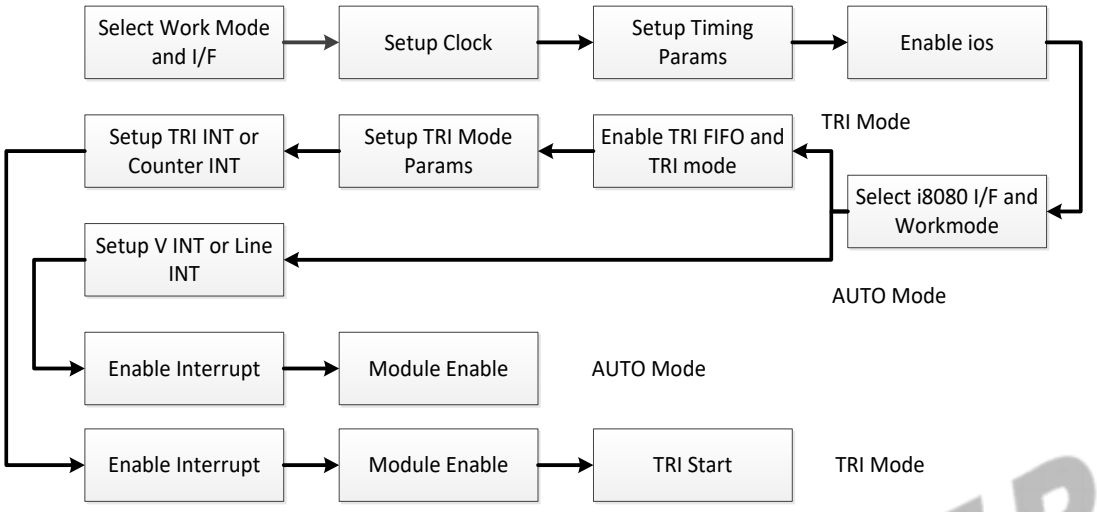
Step 7 **Same as in step5 of parallel mode**

Step 8 **Same as in step6 of parallel mode**

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6.1.4.3 i8080 Mode Configuration Process

Figure 6-13 i8080 Mode Initial Process



Step 1 Select i8080 interface type.

Step 2 The step is the same as HV mode, but pulse adjustment function is invalid.

Step 3 The step is the same as HV mode. When using TRI mode, it is best to configure LCD timing parameters in HV mode , or a handful of functions such as CMAP will not be able to apply.

Step 4 The step is the same as HV mode.

Step 5 Select type and operating mode of i8080, the operating mode includes TRI mode and AUTO mode, and the two operating modes are different.

----------**If For TRI mode**----------

Step 6 Open TRI FIFO switch, and TRI mode function.

Step 7 Set parameters of TRI mode, including block size, block space and block number.

NOTE

- When output interface is parallel mode, then the setting value of block space parameter is not less than 20.
- When output interface is 2 cycle serial mode, then the setting value of block space parameter is not less than 40.
- When output interface is 3 cycle serial mode, then the setting value of block space parameter is not less than 60.

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- When output interface is 4 cycle serial mode, then the setting value of block space parameter is not less than 80.

Step 8 Set the tri interrupt or counter interrupt. When using the two interrupts, mainly in the interrupt service function the tri start operation need be operated (the bit1 of LCD_CPU_IF_REG is set to"1"). If using TE trigger interrupt, you select the external input pin as a trigger signal, the 24-bit for offset 0x8C register is set to "1", to open up input of pad.

Step 9 Open the total switch of interrupt.

Step 10 Open the total enable of interrupt.

Step 11 Operate “tri start” operation (the bit1 of LCD_CPU_IF_REG is set to "1").

----------**If For Auto mode**----------

Step 6 Set and open V interrupt or Line interrupt, the step is the same as HV mode.

Step 7 Open module total enable.

6.1.5 Register List

Module Name	Base Address
TCON_LCD0	0x05461000

Register Name	Offset	Description
LCD_GCTL_REG	0x0000	LCD Global Control Register
LCD_GINT0_REG	0x0004	LCD Global Interrupt Register0
LCD_GINT1_REG	0x0008	LCD Global Interrupt Register1
LCD_FRM_CTL_REG	0x0010	LCD FRM Control Register
LCD_FRM_SEED_REG	0x0014+N*0x04	LCD FRM Seed Register (N=0,1,2,3,4,5)
LCD_FRM_TAB_REG	0x002C+N*0x04	LCD FRM Table Register (N=0,1,2,3)
LCD_3D_FIFO_REG	0x003C	LCD 3D FIFO Register
LCD_CTL_REG	0x0040	LCD Control Register
LCD_DCLK_REG	0x0044	LCD Data Clock Register
LCD_BASIC0_REG	0x0048	LCD Basic Timing Register0
LCD_BASIC1_REG	0x004C	LCD Basic Timing Register1
LCD_BASIC2_REG	0x0050	LCD Basic Timing Register2
LCD_BASIC3_REG	0x0054	LCD Basic Timing Register3
LCD_HV_IF_REG	0x0058	LCD HV Panel Interface Register

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Register Name	Offset	Description
LCD_CPU_IF_REG	0x0060	LCD CPU Panel Interface Register
LCD_CPU_WR_REG	0x0064	LCD CPU Panel Write Data Register
LCD_CPU_RD0_REG	0x0068	LCD CPU Panel Read Data Register0
LCD_CPU_RD1_REG	0x006C	LCD CPU Panel Read Data Register1
LCD_LVDS_IF_REG	0x0084	LCD LVDS Configure Register
LCD_IO_POL_REG	0x0088	LCD IO Polarity Register
LCD_IO_TRI_REG	0x008C	LCD IO Control Register
LCD_DEBUG_REG	0x00FC	LCD Debug Register
LCD_CEU_CTL_REG	0x0100	LCD CEU Control Register
LCD_CEU_COEF_MUL_REG	0x0110+N*0x04	LCD CEU Coefficient Register0 (N=0–10)
LCD_CEU_COEF_ADD_REG	0x011C+N*0x10	LCD CEU Coefficient Register1 (N=0,1,2)
LCD_CEU_COEF_RANG_REG	0x0140+N*0x04	LCD CEU Coefficient Register2 (N=0,1,2)
LCD_CPU_TRI0_REG	0x0160	LCD CPU Panel Trigger Register0
LCD_CPU_TRI1_REG	0x0164	LCD CPU Panel Trigger Register1
LCD_CPU_TRI2_REG	0x0168	LCD CPU Panel Trigger Register2
LCD_CPU_TRI3_REG	0x016C	LCD CPU Panel Trigger Register3
LCD_CPU_TRI4_REG	0x0170	LCD CPU Panel Trigger Register4
LCD_CPU_TRI5_REG	0x0174	LCD CPU Panel Trigger Register5
LCD_CMAP_CTL_REG	0x0180	LCD Color Map Control Register
LCD_CMAP_ODD0_REG	0x0190	LCD Color Map Odd Line Register0
LCD_CMAP_ODD1_REG	0x0194	LCD Color Map Odd Line Register1
LCD_CMAP_EVEN0_REG	0x0198	LCD Color Map Even Line Register0
LCD_CMAP_EVEN1_REG	0x019C	LCD Color Map Even Line Register1
LCD_SAFE_PERIOD_REG	0x01F0	LCD Safe Period Register
LCD_LVDS0_ANA_REG	0x0220	LCD LVDS Analog Register 0
LCD_LVDS1_ANA_REG	0x0224	LCD LVDS Analog Register 1
LCD_SYNC_CTL_REG	0x0230	LCD Sync Control Register
LCD_SYNC_POS_REG	0x0234	LCD Sync Position Register
LCD_SLAVE_STOP_POS_REG	0x0238	LCD Slave Stop Position Register
LCD_GAMMA_TABLE_REG	0x0400-0x07FF	LCD Gamma Table Register

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6.1.6 Register Description

6.1.6.1 0x0000 LCD Global Control Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: LCD_GCTL_REG
Bit	Read/Write	Default/Hex	Description
31	R/W	0x0	LCD_EN When it is disabled, the module will be reset to idle state. 0: Disable 1: Enable
30	R/W	0x0	LCD_GAMMA_EN Enable the Gamma correction function. 0: Disable 1: Enable
29:0	/	/	/

6.1.6.2 0x0004 LCD Global Interrupt Register0 (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: LCD_GINT0_REG
Bit	Read/Write	Default/Hex	Description
31	R/W	0x0	LCD_VB_INT_EN Enable the Vb interrupt 0: Disable 1: Enable
30	/	/	/
29	R/W	0x0	LCD_LINE_INT_EN Enable the line interrupt 0: Disable 1: Enable
28	/	/	/
27	R/W	0x0	LCD_TRI_FINISH_INT_EN Enable the trigger finish interrupt 0: Disable 1: Enable
26	R/W	0x0	LCD_TRI_COUNTER_INT_EN Enable the trigger counter interrupt 0: Disable 1: Enable
25:16	/	/	/

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Offset: 0x0004			Register Name: LCD_GINT0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
15	R/W0C	0x0	LCD_VB_INT_FLAG Asserted during vertical no-display period every frame Write 0 to clear it.
14	/	/	/
13	R/W0C	0x0	LCD_LINE_INT_FLAG Trigger when SY0 match the current LCD scan line Write 0 to clear it.
12	/	/	/
11	R/W0C	0x0	LCD_TRI_FINISH_INT_FLAG Trigger when cpu trigger mode finished Write 0 to clear it.
10	R/W0C	0x0	LCD_TRI_COUNTER_INT_FLAG Trigger when tri counter reaches this value Write 0 to clear it.
9	R/W0C	0x0	LCD_TRI_UNDERFLOW_FLAG Only used in dsi video mode, tri when sync by dsi but not finish Write 0 to clear it.
8:3	/	/	/
2	R/W0C	0x0	FSYNC_INT_INV Enable the fsync interrupt to set signal inverse polarity. When FSYNC is positive, this bit must be 1. And vice versa.
1	R/W0C	0x0	DE_INT_FLAG Asserted at the first valid line in every frame Write 0 to clear it.
0	R/W0C	0x0	FSYNC_INT_FLAG Asserted at the fsync signal in every frame Write 0 to clear it.

6.1.6.3 0x0008 LCD Global Interrupt Register1 (Default Value: 0x0000_0000)

Offset: 0x0008			Register Name: LCD_GINT1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/
27:16	R/W	0x0	LCD_LINE_INT_NUM Scan line for LCD line trigger (including inactive lines). Setting it for the specified line for trigger0. **Note: SY0 is writable only when LINE_TRG0 is disabled.**
15:0	/	/	/

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6.1.6.4 0x0010 LCD FRM Control Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: LCD_FRM_CTL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	LCD_FRM_EN Enable the dither function 0: Disable 1: Enable
30:7	/	/	/
6	R/W	0x0	LCD_FRM_MODE_R The R component output bits in dither function 0: 6-bit frm output 1: 5-bit frm output
5	R/W	0x0	LCD_FRM_MODE_G The G component output bits in dither function 0: 6-bit frm output 1: 5-bit frm output
4	R/W	0x0	LCD_Frm_MODE_B The B component output bits in dither function 0: 6-bit frm output 1: 5-bit frm output
3:2	/	/	/
1:0	R/W	0x0	LCD_FRM_TEST Set the test mode of dither function 00: FRM 01: Half 5-/6-bit, half FRM 10: Half 8-bit, half FRM 11: Half 8-bit, half 5-/6-bit

6.1.6.5 0x0014+ N*0x04 (N=0–5) LCD FRM Seed Register (Default Value: 0x0000_0000)

Offset: 0x0014+N*0x04 (N=0–5)			Register Name:
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/

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Offset: 0x0014+N*0x04 (N=0–5)			Register Name:
Bit	**Read/Write**	**Default/Hex**	**Description**
24:0	R/W	0x0	SEED_VALUE Set the seed used in dither function N=0: Pixel_Seed_R N=1: Pixel_Seed_G N=2: Pixel_Seed_B N=3: Line_Seed_R N=4: Line_Seed_G N=5: Line_Seed_B **Note: Avoid setting it to 0.**

6.1.6.6 0x002C+ N*0x04 (N=0–3) LCD FRM Table Register (Default Value: 0x0000_0000)

Offset: 0x002C+N*0x04 (N=0–3)			Register Name: LCD_FRM_TAB_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	FRM_TABLE_VALUE Set the data used in dither function Usually set as follows: Table0 = 0x01010000 Table1 = 0x15151111 Table2 = 0x57575555 Table3 = 0x7f7f7777

6.1.6.7 0x003C LCD 3D FIFO Register (Default Value: 0x0000_0000)

Offset: 0x003C			Register Name: LCD_3D_FIFO_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	3D_FIFO_BIST_EN Enable the 3D fifo bist test function 0: Disable 1: Enable
30:14	/	/	/
13:4	R/W	0x0	3D_FIFO_HALF_LINE_SIZE The number of data in half line=3D_FIFO_HALF_LINE_SIZE+1, only valid when 3D_FIFO_SETTING is set as 2.
3:2	/	/	/

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Offset: 0x003C			Register Name: LCD_3D_FIFO_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
1:0	R/W	0x0	3D_FIFO_SETTING Set the work mode of 3D FIFO 00: Bypass 01: Used as normal FIFO 10: Used as 3D interlace FIFO 11: Reserved

6.1.6.8 0x0040 LCD Control Register (Default Value: 0x0000_0000)

Offset: 0x0040			Register Name: LCD_CTL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	LCD_EN It executes at the beginning of the first blank line of LCD timing. 0: Disable 1: Enable
30:26	/	/	/
25:24	R/W	0x0	LCD_IF Set the interface type of LCD controller. 00: HV(Sync+DE) 01: 8080 I/F 1x: Reserved
23	R/W	0x0	LCD_RB_SWAP Enable the function to swap red data and blue data in fifo1. 0: Default 1: Swap RED and BLUE data at FIFO1
22	/	/	/
21	R/W	0x0	LCD_FIFO1_RST Writing 1 and then 0 to this bit will reset FIFO 1 Note: 1 holding time must more than 1 DCLK
20	R/W	0x0	LCD_INTERLACE_EN This flag is valid only when LCD_EN == 1 0: Disable 1: Enable
19:9	/	/	/
8:4	R/W	0x0	LCD_START_DLY The unit of delay is T_{line}. Note: Valid only when LCD_EN == 1
3	/	/	/

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Offset: 0x0040			Register Name: LCD_CTL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
2:0	R/W	0x0	LCD_SRC_SEL LCD Source Select 000: DE 001: Color Check 010: Grayscale Check 011: Black by White Check 100: Test Data all 0 101: Test Data all 1 110: Reversed 111: Gridding Check

6.1.6.9 0x0044 LCD Data Clock Register (Default Value: 0x0000_0000)

Offset: 0x0044			Register Name: LCD_DCLK_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	LCD_DCLK_EN LCD clock enable 0000: dclk_en = 0; dclk1_en = 0; dclk2_en = 0; dclkm2_en = 0; 0001: dclk_en = 1; dclk1_en = 0; dclk2_en = 0; dclkm2_en = 0; 0010: dclk_en = 1; dclk1_en = 0; dclk2_en = 0; dclkm2_en = 1; 0011: dclk_en = 1; dclk1_en = 1; dclk2_en = 0; dclkm2_en = 0; 0101: dclk_en = 1; dclk1_en = 0; dclk2_en = 1; dclkm2_en = 0; 1111: dclk_en = 1; dclk1_en = 1; dclk2_en = 1; dclkm2_en = 1; Others:Reversed
27:7	/	/	/
6:0	R/W	0x0	LCD_DCLK_DIV Tdclk = Tsclk/DCLKDIV Note: 1.If dclk1&dclk2 are used, DCLKDIV >=6 2.If only dclk is used, DCLKDIV >=1

6.1.6.10 0x0048 LCD Basic Timing Register0 (Default Value: 0x0000_0000)

Offset: 0x0048			Register Name: LCD_BASIC0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/
27:16	R/W	0x0	WIDTH_X Panel width is X+1

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Offset: 0x0048			Register Name: LCD_BASIC0_REG
Bit	Read/Write	Default/Hex	Description
15:12	/	/	/
11:0	R/W	0x0	HEIGHT_Y Panel height is Y+1

6.1.6.11 0x004C LCD Basic Timing Register1 (Default Value: 0x0000_0000)

Offset: 0x004C			Register Name: LCD_BASIC1_REG
Bit	Read/Write	Default/Hex	Description
31:29	/	/	/
28:16	R/W	0x0	HT Thcycle = (HT+1) * Tdclk Computation: 1) parallel: HT = X + BLANK Limitation: 1) parallel: HT >= (HBP +1) + (X+1) +2 2) serial 1: HT >= (HBP +1) + (X+1) *3+2 3) serial 2: HT >= (HBP +1) + (X+1) *3/2+2
15:12	/	/	/
11:0	R/W	0x0	HBP Horizontal back porch (in dclk) Thbp = (HBP +1) * Tdclk

6.1.6.12 0x0050 LCD Basic Timing Register2 (Default Value: 0x0000_0000)

Offset: 0x0050			Register Name: LCD_BASIC2_REG
Bit	Read/Write	Default/Hex	Description
31:29	/	/	/
28:16	R/W	0x0	VT TVT = (VT)/2 * Thsync VT/2 >= (VBP+1) + (Y+1) +2
15:12	/	/	/
11:0	R/W	0x0	VBP Tvbp = (VBP +1) * Thsync

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6.1.6.13 0x0054 LCD Basic Timing Register3 (Default Value: 0x0000_0000)

Offset: 0x0054			Register Name: LCD_BASIC3_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/
25:16	R/W	0x0	HSPW Thspw = (HSPW+1) * Tdclk HT > (HSPW+1)
15:10	/	/	/
9:0	R/W	0x0	VSPW Tvspw = (VSPW+1) * Thsync VT/2 > (VSPW+1)

6.1.6.14 0x0058 LCD HV Panel Interface Register (Default Value: 0x0000_0000)

Offset: 0x0058			Register Name: LCD_HV_IF_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	HV_MODE Set the HV mode of LCD controller 0000: 24-bit/1-cycle parallel mode 1000: 8-bit/3-cycle RGB serial mode (RGB888) 1010: 8-bit/4-cycle Dummy RGB (DRGB) 1011: 8-bit/4-cycle RGB Dummy (RGBD) 1100: 8-bit/2-cycle YUV serial mode (CCIR656)
27:26	R/W	0x0	RGB888_ODD_ORDER Serial RGB888 mode Output sequence at odd lines of the panel (line 1, 3, 5, 7…). 00: R→G→B 01: B→R→G 10: G→B→R 11: R→G→B
25:24	R/W	0x0	RGB888_EVEN_ORDER Serial RGB888 mode Output sequence at even lines of the panel (line 2, 4, 6, 8…). 00: R→G→B 01: B→R→G 10: G→B→R 11: R→G→B

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Offset: 0x0058			Register Name: LCD_HV_IF_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
23:22	R/W	0x0	YUV_SM Serial YUV mode Output sequence 2-pixel-pair of every scan line. 00: YUYV 01: YVYU 10: UYVY 11: VYUY
21:20	R/W	0x0	YUV_EAV_SAV_F_LINE_DLY Set the delay line mode. 00: F toggle right after active video line 01: delay 2 line (CCIR PAL) 10: delay 3 line (CCIR NTSC) 11: reserved
19	R/W	0x0	CCIR_CSC_DIS LCD convert source from RGB to YUV. 0: Enable 1: Disable Only valid when HV mode is “1100”.
18:0	/	/	/

6.1.6.15 0x0060 LCD CPU Panel Interface Register (Default Value: 0x0000_0000)

Offset: 0x0060			Register Name: LCD_CPU_IF_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	CPU_MODE Set the cpu interface work mode 0000: 18-bit/256K mode 0010: 16-bit mode0 0100: 16-bit mode1 0110: 16-bit mode2 1000: 16-bit mode3 1010: 9-bit mode 1100: 8-bit 256K mode 1110: 8-bit 65K mode xxx1: 24-bit for DSI
27	/	/	/
26	R/W	0x0	DA Pin A1 value in 8080 mode auto/flash states
25	R/W	0x0	CA Pin A1 value in 8080 mode WR/RD execute

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Offset: 0x0060			Register Name: LCD_CPU_IF_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
24	/	/	/
23	R	0x0	WR_FLAG The status of write operation. 0: Write operation is finishing 1: Write operation is pending
22	R	0x0	RD_FLAG The status of read operation. 0: Read operation is finishing 1: Read operation is pending
21:18	/	/	/
17	R/W	0x0	AUTO Auto transfer mode If it is 1, all the valid data during this frame are written to panel. **Note: This bit is sampled by Vsync.**
16	R/W	0x0	FLUSH Direct transfer mode If it is enabled, FIFO1 is regardless of the HV timing, the pixels data keep being transferred unless the input FIFO was empty. Data output rate is controlled by DCLK.
15:4	/	/	/
3	R/W	0x0	TRI_FIFO_BIST_EN Entry address is 0xFF8 0: Disable 1: Enable
2	R/W	0x0	TRI_FIFO_EN Enable the trigger FIFO 0: Disable 1: Enable
1	R/W1S	0x0	TRI_START Software must make sure that write ‘1’ only when this flag is ‘0’. Writing ‘1’ starts a frame flush and writing ’0’ has no effect. This flag indicates the frame flush is running.
0	R/W	0x0	TRI_EN Enable trigger mode 0: Trigger mode disable 1: Trigger mode enable

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6.1.6.16 0x0064 LCD CPU Panel Write Data Register (Default Value: 0x0000_0000)

Offset: 0x0064			Register Name: LCD_CPU_WR_REG
Bit	Read/Write	Default/Hex	Description
31:24	/	/	/
23:0	W	0x0	DATA_WR Data write on 8080 bus, launch a write operation on 8080 bus.

6.1.6.17 0x0068 LCD CPU Panel Read Data Register0 (Default Value: 0x0000_0000)

Offset: 0x0068			Register Name: LCD_CPU_RD0_REG
Bit	Read/Write	Default/Hex	Description
31:24	/	/	/
23:0	R	0x0	DATA_RD0 Data read on 8080 bus, launch a new read operation on 8080 bus.

6.1.6.18 0x006C LCD CPU Panel Read Data Register1 (Default Value: 0x0000_0000)

Offset: 0x006C			Register Name: LCD_CPU_RD1_REG
Bit	Read/Write	Default/Hex	Description
31:24	/	/	/
23:0	R	0x0	DATA_RD1 Data read on 8080 bus, without a new read operation on 8080 bus.

6.1.6.19 0x0084 LCD LVDS Interface Register (Default Value: 0x0000_0000)

Offset: 0x0084			Register Name: LCD_LVDS_IF_REG
Bit	Read/Write	Default/Hex	Description
31	R/W	0	LCD_LVDS_EN Enable LVDS interface 0: Disable 1: Enable

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Offset: 0x0084			Register Name: LCD_LVDS_IF_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
30	R/W	0	LCD_LVDS_LINK Select work in single link mode or dual link mode 0: Single link 1: Dual link
29	R/W	0	LCD_LVDS_EVEN_ODD_DIR Set the order of even field and odd field 0: normal 1: reverse
28	R/W	0	LCD_LVDS_DIR Set the LVDS direction 0: Normal 1: Reverse
27	R/W	0	LCD_LVDS_MODE Set the LVDS data mode 0: NS mode 1: JEIDA mode
26	R/W	0	LCD_LVDS_BITWIDTH Set the bit width of data 0: 24-bit 1: 18-bit
25	R/W	0	LCD_LVDS_DEBUG_EN Enable LVDS debug function 0: Disable 1: Enable
24	R/W	0	LCD_LVDS_DEBUG_MODE Set the output signal in debug mode 0: Mode0—Random data 1: Mode1—Output CLK period=7/2 LVDS CLK period
23	R/W	0	LCD_LVDS_CORRECT_MODE Set the LVDS correct mode 0: Mode0 1: Mode1
22:21	/	/	/
20	R/W	0	LCD_LVDS_CLK_SEL Select the clock source of LVDS 0: Reserved 1: LCD CLK
19:5	/	/	/
4	R/W	0	LCD_LVDS_CLK_POL Set the clock polarity of LVDS 0: Reverse 1: Normal

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Offset: 0x0084			Register Name: LCD_LVDS_IF_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0	LCD_LVDS_DATA_POL Set the data polarity of LVDS 0: Reverse 1: Normal

6.1.6.20 0x0088 LCD IO Polarity Register (Default Value: 0x0000_0000)

Offset: 0x0088			Register Name: LCD_IO_POL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	IO_OUTPUT_SEL When it is set as '1', the d[23:0], io0, io1, io3 are sync to dclk. 0: Normal output 1: Register output
30:28	R/W	0x0	DCLK_SEL Set the phase offset of clock and data in hv mode. 000: Used DCLK0 (normal phase offset) 001: Used DCLK1 (1/3 phase offset) 010: Used DCLK2 (2/3 phase offset) 100: DCLK0/2 phase 0 101: DCLK0/2 phase 90 Others: Reserved
27	R/W	0x0	IO3_INV Enable invert function of IO3 0: Not invert 1: Invert
26	R/W	0x0	IO2_INV Enable invert function of IO2 0: Not invert 1: Invert
25	R/W	0x0	IO1_INV Enable invert function of IO1 0: Not invert 1: Invert
24	R/W	0x0	IO0_INV Enable invert function of IO0 0: Not invert 1: Invert

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Offset: 0x0088			Register Name: LCD_IO_POL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
23:0	R/W	0x0	Data_INV LCD output port D[23:0] polarity control, with independent bit control. 0: Normal polarity 1: Invert the specify output

6.1.6.21 0x008C LCD IO Control Register (Default Value: 0x0FFF_FFFF)

Offset: 0x008C			Register Name: LCD_IO_TRI_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28	R/W	0x0	RGB_ENDIAN Set the endian of data bits 0: Normal 1: Bits_invert
27	R/W	0x1	IO3_OUTPUT_TRI_EN Enable the output of IO3 1: Disable 0: Enable
26	R/W	0x1	IO2_OUTPUT_TRI_EN Enable the output of IO2 1: Disable 0: Enable
25	R/W	0x1	IO1_OUTPUR_TRI_EN Enable the output of IO1 1: Disable 0: Enable
24	R/W	0x1	IO0_OUTPUT_TRI_EN Enable the output of IO0 1: Disable 0: Enable
23:0	R/W	0xFFFFFF	DATA_OUTPUT_TRI_EN LCD output port D[23:0] output enable, with independent bit control. 1: Disable 0: Enable

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6.1.6.22 0x00FC LCD Debug Register (Default Value: 0x0000_0000)

Offset: 0x00FC			Register Name: LCD_DEBUG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R	0x0	LCD_FIFO_UNDERFLOW The flag shows whether the fifos in underflow status 0: Not underflow 1: Underflow
30	/	/	/
29	R	0x0	LCD_FIELD_POL The flag indicates the current field polarity 0: Second field 1: First field
28	/	/	/
27:16	R	0x0	LCD_CURRENT_LINE The current scan line
15:0	/	/	/

6.1.6.23 0x0100 LCD CEU Control Register (Default Value: 0x0000_0000)

Offset: 0x0100			Register Name: LCD_CEU_CTL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	CEU_EN Enable CEU function 0: Bypass 1: Enable
30	R/W	0x0	BT656_F_MASK BT656 F Mask 0: Disable 1: Enable
29	R/W	0x0	BT656_F_MASK_VALUE BT656 F Mask Value
28:0	/	/	/

6.1.6.24 0x0110+N*0x04 (N=0–10) LCD CEU Coefficient Register0 (Default Value: 0x0000_0000)

Offset: 0x0110+N*0x04 (N=0–10)			Register Name: LCD_CEU_COEF_MUL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:13	/	/	/

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Offset: 0x0110+N*0x04 (N=0–10)			Register Name: LCD_CEU_COEF_MUL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
12:0	R/W	0x0	CEU_COEF_MUL_VALUE Signed 13-bit value, range of (-16,16). N=0: Rr N=1: Rg N=2: Rb N=4: Gr N=5: Gg N=6: Gb N=8: Br N=9: Bg N=10: Bb

6.1.6.25 0x011C+N*0x10 (N=0–2) LCD CEU Coefficient Register1 (Default Value: 0x0000_0000)

Offset: 0x011C+N*0x10 (N=0–2)			Register Name: LCD_CEU_COEF_ADD_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	/	/	/
18:0	R/W	0x0	CEU_COEF_ADD_VALUE Signed 19-bit value, range of (-16384, 16384). N=0: Rc N=1: Gc N=2: Bc

6.1.6.26 0x0140+N*0x04 (N=0–2) LCD CEU Coefficient Register2 (Default Value: 0x0000_0000)

Offset: 0x0140+N*0x04 (N=0–2)			Register Name: LCD_CEU_COEF_RANG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:16	R/W	0x0	CEU_COEF_RANGE_MIN Unsigned 8-bit value, range of [0, 255].
15:8	/	/	/
7:0	R/W	0x0	CEU_COEF_RANGE_MAX Unsigned 8-bit value, range of [0, 255].

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6.1.6.27 0x0160 LCD CPU Panel Trigger Register0 (Default Value: 0x0000_0000)

Offset: 0x0160			Register Name: LCD_CPU_TRI0_REG
Bit	Read/Write	Default/Hex	Description
31:28	/	/	/
27:16	R/W	0x0	BLOCK_SPACE The spaces between data blocks. It should be set >20*pixel.
15:12	/	/	/
11:0	R/W	0x0	BLOCK_SIZE The size of data block. It is usually set as X.

6.1.6.28 0x0164 LCD CPU Panel Trigger Register1 (Default Value: 0x0000_0000)

Offset: 0x0164			Register Name: LCD_CPU_TRI1_REG
Bit	Read/Write	Default/Hex	Description
31:16	R	0x0	BLOCK_CURRENT_NUM Shows the current data block transmitting to panel.
15:0	R/W	0x0	BLOCK_NUM The number of data blocks. It is usually set as Y.

6.1.6.29 0x0168 LCD CPU Panel Trigger Register2 (Default Value: 0x0020_0000)

Offset: 0x0168			Register Name: LCD_CPU_TRI2_REG
Bit	Read/Write	Default/Hex	Description
31:16	R/W	0x20	START_DLY T_{dly} = (Start_Delay +1) * be_clk*8.
15	R/W	0x0	TRANS_START_MODE Select the FIFOs used in CPU mode. 0: ECC_FIFO+TRI_FIFO 1: TRI_FIFO
14:13	R/W	0x0	SYNC_MODE Set the sync mode in CPU interface. 0x: Auto 10: 0 11: 1
12:0	R/W	0x0	TRANS_START_SET Usual set as the length of a line.

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6.1.6.30 0x016C LCD CPU Panel Trigger Register3 (Default Value: 0x0000_0000)

Offset: 0x016C			Register Name: LCD_CPU_TRI3_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x0	TRI_INT_MODE When set as 01, the Tri_Counter_Int occurs in cycle of (Count_N+1)×(Count_M+1)×4 dclk. When set as 10 or 11, the io0 is map as TE input. 00: Disable 01: Counter mode 10: Te rising mode 11: Te falling mode
27:24	/	/	/
23:8	R/W	0x0	COUNTER_N The value of counter factor
7:0	R/W	0x0	COUNTER_M The value of counter factor

6.1.6.31 0x0170 LCD CPU Panel Trigger Register4 (Default Value: 0x0000_0000)

Offset: 0x0170			Register Name: LCD_CPU_TRI4_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28	R/W	0x0	PLUG_MODE_EN Enable the plug mode used in dsi command mode. 0: Disable 1: Enable
27:25	/	/	/
24	R/W	0x0	A1_First_Valid Valid in first Block.
23:0	R/W	0x0	D23_TO_D0_First_Valid Valid in first Block.

6.1.6.32 0x0174 LCD CPU Panel Trigger Register5 (Default Value: 0x0000_0000)

Offset: 0x0174			Register Name: LCD_CPU_TRI5_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/

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Offset: 0x0174			Register Name: LCD_CPU_TRI5_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
24	R/W	0x0	A1_NON_First_Valid Valid in Block except first.
23:0	R/W	0x0	D23_TO_D0_NON_First_Valid Valid in Block except first.

6.1.6.33 0x0180 LCD Color Map Control Register (Default Value: 0x0000_0000)

Offset: 0x0180			Register Name: LCD_CMAP_CTL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	COLOR_MAP_EN Enable the color map function. This module only works when X is divided by 4. 0: Bypass 1: Enable
30:1	/	/	/
0	R/W	0x0	OUT_FORMAT Set the pixel output format in color map function. 0: 4 pixel output mode: Out0 -> Out1 -> Out2 -> Out3 1: 2 pixel output mode: Out0 -> Out1

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6.1.6.34 0x0190 LCD Color Map Odd Line Register0 (Default Value: 0x0000_0000)

Offset: 0x0190			Register Name: LCD_CMAP_ODD0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0	OUT_ODD1 Indicates the output order of components. bit15-12: Reserved bit11-08: Out_Odd0[23:16] bit07-04: Out_Odd0[15:8] bit03-00: Out_Odd0[7:0] 0000: in_b0 0001: in_g0 0010: in_r0 0011: Reserved 0100: in_b1 0101: in_g1 0110: in_r1 0111:Reserved 1000: in_b2 1001: in_g2 1010: in_r2 1011: Reserved 1100: in_b3 1101: in_g3 1110: in_r3 1111: Reserved

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Offset: 0x0190			Register Name: LCD_CMAP_ODD0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R/W	0x0	OUT_ODD0 Indicates the output order of components. bit15-12: Reserved bit11-08: Out_Odd0[23:16] bit07-04: Out_Odd0[15:8] bit03-00: Out_Odd0[7:0] 0000: in_b0 0001: in_g0 0010: in_r0 0011: Reserved 0100: in_b1 0101: in_g1 0110: in_r1 0111:Reserved 1000: in_b2 1001: in_g2 1010: in_r2 1011: Reserved 1100: in_b3 1101: in_g3 1110: in_r3 1111: Reserved

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6.1.6.35 0x0194 LCD Color Map Odd Line Register1 (Default Value: 0x0000_0000)

Offset: 0x0194			Register Name: LCD_CMAP_ODD1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0	OUT_ODD3 Indicates the output order of components. bit15-12: Reserved bit11-08: Out_Odd0[23:16] bit07-04: Out_Odd0[15:8] bit03-00: Out_Odd0[7:0] 0000: in_b0 0001: in_g0 0010: in_r0 0011: Reserved 0100: in_b1 0101: in_g1 0110: in_r1 0111:Reserved 1000: in_b2 1001: in_g2 1010: in_r2 1011: Reserved 1100: in_b3 1101: in_g3 1110: in_r3 1111: Reserved

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Offset: 0x0194			Register Name: LCD_CMAP_ODD1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R/W	0x0	OUT_ODD2 Indicates the output order of components. bit15-12: Reserved bit11-08: Out_Odd0[23:16] bit07-04: Out_Odd0[15:8] bit03-00: Out_Odd0[7:0] 0000: in_b0 0001: in_g0 0010: in_r0 0011: Reserved 0100: in_b1 0101: in_g1 0110: in_r1 0111:Reserved 1000: in_b2 1001: in_g2 1010: in_r2 1011: Reserved 1100: in_b3 1101: in_g3 1110: in_r3 1111: Reserved

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6.1.6.36 0x0198 LCD Color Map Even Line Register0 (Default Value: 0x0000_0000)

Offset: 0x0198			Register Name: LCD_CMAP_EVEN0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0	OUT_EVEN1 Indicates the output order of components. bit15-12: Reserved bit11-08: Out_Odd0[23:16] bit07-04: Out_Odd0[15:8] bit03-00: Out_Odd0[7:0] 0000: in_b0 0001: in_g0 0010: in_r0 0011: Reserved 0100: in_b1 0101: in_g1 0110: in_r1 0111:Reserved 1000: in_b2 1001: in_g2 1010: in_r2 1011: Reserved 1100: in_b3 1101: in_g3 1110: in_r3 1111: Reserved

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Offset: 0x0198			Register Name: LCD_CMAP_EVEN0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R/W	0x0	OUT_EVEN0 Indicates the output order of components. bit15-12: Reserved bit11-08: Out_Odd0[23:16] bit07-04: Out_Odd0[15:8] bit03-00: Out_Odd0[7:0] 0000: in_b0 0001: in_g0 0010: in_r0 0011: Reserved 0100: in_b1 0101: in_g1 0110: in_r1 0111:Reserved 1000: in_b2 1001: in_g2 1010: in_r2 1011: Reserved 1100: in_b3 1101: in_g3 1110: in_r3 1111: Reserved

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6.1.6.37 0x019C LCD Color Map Even Line Register1 (Default Value: 0x0000_0000)

Offset: 0x019C			Register Name: LCD_CMAP_EVEN1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0	OUT_EVEN3 Indicates the output order of components. bit15-12: Reserved bit11-08: Out_Odd0[23:16] bit07-04: Out_Odd0[15:8] bit03-00: Out_Odd0[7:0] 0000: in_b0 0001: in_g0 0010: in_r0 0011: Reserved 0100: in_b1 0101: in_g1 0110: in_r1 0111:Reserved 1000: in_b2 1001: in_g2 1010: in_r2 1011: Reserved 1100: in_b3 1101: in_g3 1110: in_r3 1111: Reserved

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Offset: 0x019C			Register Name: LCD_CMAP_EVEN1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R/W	0x0	OUT_EVEN2 Indicates the output order of components. bit15-12: Reserved bit11-08: Out_Odd0[23:16] bit07-04: Out_Odd0[15:8] bit03-00: Out_Odd0[7:0] 0000: in_b0 0001: in_g0 0010: in_r0 0011: Reserved 0100: in_b1 0101: in_g1 0110: in_r1 0111: Reserved 1000: in_b2 1001: in_g2 1010: in_r2 1011: Reserved 1100: in_b3 1101: in_g3 1110: in_r3 1111: Reserved

6.1.6.38 0x01F0 LCD Safe Period Register (Default Value: 0x0000_0000)

Offset: 0x01F0			Register Name: LCD_SAFE_PERIOD_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x0	SAFE_PERIOD_FIFO_NUM When the data length in line buffer is more than SAFE_PERIOD_FIFO_NUM, the LCD controller will allow dram controller to stop working to change frequency.
15:4	R/W	0x0	SAFE_PERIOD_LINE Set a fixed line and during the line time, the LCD controller allow dram controller to change frequency. The fixed line should be set in the blanking area.
3	/	/	/

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Offset: 0x01F0			Register Name: LCD_SAFE_PERIOD_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
2:0	R/W	0x0	SAFE_PERIOD_MODE Select the save mode 000: unsafe 001: safe 010: safe at FIFO_CURR_NUM > SAFE_PERIOD_FIFO_NUM 011: safe at 2 and safe at sync active 100: safe at line

6.1.6.39 0x0220 LCD LVDS Analog Register0 (Default Value: 0x0000_0000)

Offset: 0x0220			Register Name: LCD_LVDS_ANA0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	LVDS_EN_MB Enable the bias circuit of the LVDS_Ana module. 0: Disable 1: Enable
30	R/W	0x0	Reserved
29	R/W	0x0	EN_LVDS Enable LVDS
28	R/W	0x0	EN_24M Enable the 24M clock
27:25	/	/	/
24	R/W	0x0	LVDS_HPREN_DRVC Enable clock channel drive 0: Disable 1: Enable
23:20	R/W	0x0	LVDS_HPREN_DRV Enable data channel[3:0] drive 0: Disable 1: Enable

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Offset: 0x0220			Register Name: LCD_LVDS_ANA0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
19:17	R/W	0x0	LVDS_REG_C Adjust current flowing through Rload of Rx to change the differential signals amplitude. 000: 216 mV 001: 252 mV 010: 276 mV 011: 312 mV 100: 336 mV 101: 372 mV 110: 395 mV 111: 432 mV
16	R/W	0x0	LVDS_REG_DENC Choose data output or PLL test clock output in LVDS_tx.
15:12	R/W	0x0	LVDS_REG_DEN Choose data output or PLL test clock output in LVDS_tx.
11	/	/	/
10:8	R/W	0x0	LVDS_REG_R Adjust current flowing through R_{load} of R_x to change the common signals amplitude. 000: 0.925 V 001: 0.950 V 010: 0.975 V 011: 1.000 V 100: 1.025 V 101: 1.050 V 110: 1.075 V 111: 1.100 V
7:5	/	/	/
4	R/W	0x0	LVDS_REG_PLRC LVDS clock channel direction. 0: Normal 1: Reverse
3:0	R/W	0x0	LVDS_REG_PLR LVDS data channel [3:0] direction. 0: Normal 1: Reverse

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6.1.6.40 0x0228 LCD FSYNC Generate Control Register (Default Value: 0x0000_0000)

Offset: 0x0228			Register Name: FSYNC_GEN_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	/	/	/
18:8	R/W	0x0	SENSOR_DIS_TIME Delay 0–2047 Hsync Period When hsync_pol_sel is 0, the actual delay is sensor_dis_time-1. When hsync_pol_sel is 1, the actual delay is sensor_dis_time.
7	/	/	/
6	R/W	0x0	SENSOR_ACT1_VALUE Sensor Active1 Value 0: Fsync active_1 period output 0 1: Fsync active_1 period output 1
5	R/W	0x0	SENSOR_ACT0_VALUE Sensor Active0 Value 0: Fsync active_0 period output 0 1: Fsync active_0 period output 1
4	R/W	0x0	SENSOR_DIS_VALUE Sensor Disable Value 0: Fsync disable period output 0 1: Fsync disable period output 1
3	/	/	/
2	R/W	0x0	HSYNC_POL_SEL Hsync Polarity Select 0: Normal 1: Opposite hsync to hysnc counter
1	R/W	0x0	SEL_VSYNC_EN Select Vsync Enable 0: Select vsync falling edge to start state machine 1: Select vsync rising edge to start state machine
0	R/W	0x0	FSYNC_GEN_EN Fsync Generate Enable 0: Disable 1: Enable

6.1.6.41 0x022C LCD FSYNC Generate Delay Register (Default Value: 0x0000_0000)

Offset: 0x022C			Register Name: FSYNC_GEN_DLY_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/

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Offset: 0x022C			Register Name: FSYNC_GEN_DLY_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
27:16	R/W	0x0	SENSOR_ACT0_TIME Delay 0–4095 Pixel clk Period The actual delay is sensor_act0_time+1.
15:12	/	/	/
11:0	R/W	0x0	SENSOR_ACT1_TIME Delay 0–4095 Pixel clk Period The actual delay is sensor_act1_time+1.

6.1.6.42 0x0230 LCD Sync Control Register (Default Value: 0x0000_0000)

Offset: 0x0230			Register Name: LCD_SYNC_CTL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:9	/	/	/
8	R/W	0x0	LCD_CTRL_WORK_MODE LCD Controller Work mode 0: Single DSI mode 1: Dual DSI mode
7:5	/	/	/
4	R/W	0x0	LCD_CYRL_SYNC_MASTER_SLAVE LCD Controller Sync Master Slave 0: Master 1: Slave **Note: Only use in Single DSI mode.**
3:1	/	/	/
0	R/W	0x0	LCD_CTRL_SYNC_MODE LCD Controller Sync Mode 0: Sync in the first time 1: Sync every frame **Note: Only use in Single DSI mode.**

6.1.6.43 0x0234 LCD Sync Position Register (Default Value: 0x0000_0000)

Offset: 0x0234			Register Name: LCD_SYNC_POS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/

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Offset: 0x0234			Register Name: LCD_SYNC_POS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
27:16	R/W	0x0	LCD_Sync_Pixel_Num Set the pixel number of master LCD controller which is used to trigger the slave LCD controller to start working.This value is the number of pixels between the trigger point and the end of the line. Tri pos = Tline*LCD_Sync_Line_Num+Tpixel*(HT-LCD_Sync_Pixel_Num) **Note: Only use in Single DSI mode.**
15:12	/	/	/
11:0	R/W	0x0	LCD_Sync_Line_Num Set the line number of master LCD controller which is used to trigger the slave LCD controller to start working. Note:It is only set in master LCD controller.It is not necessarily to set in slave LCD controller. Tri pos = Tline*LCD_Sync_Line_Num+Tpixel*(HT-LCD_Sync_Pixel_Num) **Note: Only use in Single DSI mode.**

6.1.6.44 0x0238 LCD Slave Stop Position Register (Default Value: 0x0000_0000)

Offset: 0x0238			Register Name: LCD_SLAVE_STOP_POS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x0	STOP_VAL Set the stop position of the slave LCD. This value is the number of pixels between the stop position and the end of the HFP. Stop_pos = HFP - Stop_val. 0<Stop_pos<HFP-2 **Note: Only use in Single DSI mode.**

6.1.6.45 0x0400-0x07FF LCD Gamma Table Registers (Default Value: 0x0000_0000)

Offset: 0x0400–0x07FF			Register Name: LCD_GAMMA_TABLE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:16	R/W	0x0	RED_COMP Red Component

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Offset: 0x0400–0x07FF			Register Name: LCD_GAMMA_TABLE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
15:8	R/W	0x0	GREEN_COMP Green Component
7:0	R/W	0x0	BLUE_COMP Blue Component

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6.2 MIPI DSI

6.2.1 Overview

The Display Serial Interface is a high-speed interface between a host processor and peripheral devices that adhere to MIPI Alliance specifications for mobile device interfaces. This DSI module is composed of a DSI controller which is compliance with MIPI DSI specification V1.01 and a D-PHY module which is compliance with MIPI DPHY specification V1.00.

The MIPI DSI includes the following features:

- Compliance with MIPI DSI v1.01
- Up to 4 lanes
- Supports 1280 x 720@60fps and 1920 x 1200@60fps
- Supports non-burst mode with sync pulse/sync event and burst mode
- Supports pixel format: RGB888, RGB666, RGB666 loosely packed and RGB565
- Supports continuous lane clock mode and non-continuous lane clock mode
- Compliance with MIPI DCS v1.01, bidirectional communication in LP through data lane 0
- Supports bidirectional communication of all generic commands in LP through data lane 0
- Supports low power data transmission
- Supports ULPS and Escape modes
- Hardware checksum capabilities

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7 Video Input Interfaces

7.1 CSIC

7.1.1 Overview

The CMOS Sensor Interface Controller (CSIC) is an image or video data receiver, which can receive image or video data via camera interface and store the data in memory directly.

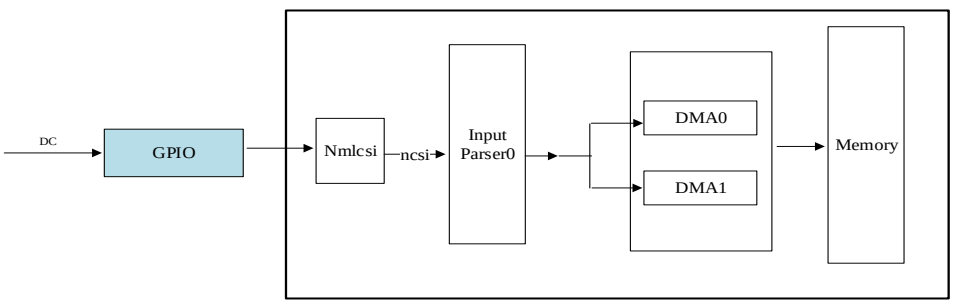
The CSIC includes the following features:

- Supports 8-bit digital camera interface
- Supports BT656 Interface
  - Supports time-multiplexed format
  - Supports dual data rate sample mode with pixel clock up to 148.5 MHz
- Supports BT601 Interface
- Supports crop function
- Supports frame rate down
- Supports 2 DMA for 2 video stream storage
  - Supports de-interlacing for interlace video input
  - Supports conversion from YUV422 to YUV420, YUV422 to YUV400, YUV420 to YUV400
  - Supports horizontal and vertical flip

7.1.2 Block Diagram

Figure 7-1 shows block diagram of the CSIC.

Figure 7-1 CSIC Block Diagram



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7.1.3 Functional Description

7.1.3.1 External Signals

Table 7-1 CSIC External Signals

Port Name	Description	Type
NCSI0-PCLK	Parallel CSI Pixel Clock	I
NCSI0-MCLK	Parallel CSI Master Clock	O
NCSI0-HSYNC	Parallel CSI Horizontal Sync	I
NCSI0-VSYNC	Parallel CSI Vertical Sync	I
NCSI0-D[7:0]	Parallel CSI Data Bit	I
NCSI0-FIELD	Parallel CSI Field Index	I

7.1.3.2 CSIC FIFO Distribution

Table 7-2 CSIC FIFO Distribution

Interface	MIPI Interface		
Input format	YUV422		Raw
Output format	Planar	UV combined	Raw/RGB/PRGB
CH0_FIFO0	Y	Y	All pixels data
CH0_FIFO1	Cb (U)	CbCr (UV)	-
CH0_FIFO2	Cr (V)	-	-

7.1.3.3 Pixel Format Arrangement

Figure 7-2 RAW-10 Format

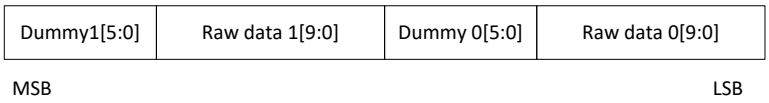
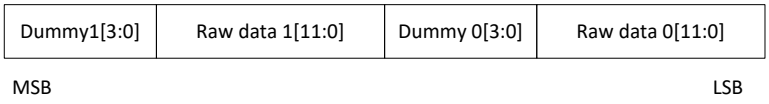


Figure 7-3 RAW-12 Format



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Figure 7-4 YUV-10 Format

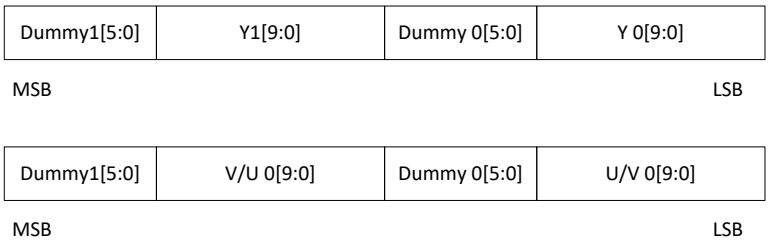


Figure 7-5 RGB888 Format

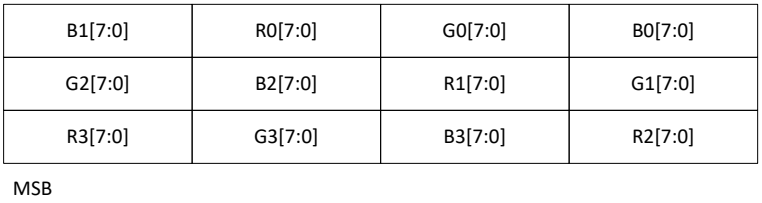
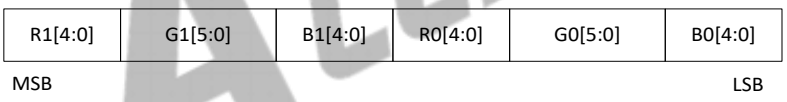


Figure 7-6 PRGB888 Format



Figure 7-7 RGB565 Format



7.1.3.4 Offset Definition

Offset in horizontal and vertical can be added when receiving image. Unit is pixel.

For YUV422 format, pixel unit is a YU/YV combination.

For YUV420 format, pixel unit is a YU/YV combination in YC line, and only a Y in Y line.

For Bayer and RAW format, pixel unit is a R/G/B single component.

For RGB565, pixel unit is 2 bytes of RGB565 package.

For RGB888, pixel unit is 3 bytes of RGB combination.

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7.1.3.5 Flip Definition

Both horizontal and vertical flip are supported at the same time. This function is implemented in the process of each FIFO writing data to memory, only flipping the data of separate FIFO, not changing component to FIFO distribution.

If horizontal flip is enabled, one or more pixels will be took as a unit:

For YUV format, a unit of $Y_0U_0Y_1V_1$ will parser and flip the Y component in one channel, and UV will be treated as a whole. In planar output mode, U and V will be flipped separately. In UV combined output mode, UV will be flipped as a whole. So, a sequence of $Y_1U_0Y_0V_1$ will be.

For Bayer_raw format, situation is much like. A GR/BG sequence will be changed to BG/RG. A unit of square has four pixels.

For RGB565/RGB888, one unit of two/three bytes of component will be flipped with original sequence.

7.1.4 Register List

Module Name	Base Address
CSIC_CCU	0x05800000
CSIC_TOP	0x05800800
CSIC_PARSER0	0x05801000
CSIC_DMA0	0x05809000
CSIC_DMA1	0x05809200

CCU register list:

Register Name	Offset	Register Description
CCU_CLK_MODE_REG	0x0000	CCU Clock Mode Register
CCU_PARSER_CLK_EN_REG	0x0004	CCU Parser Clock Enable Register
CCU_POST0_CLK_EN_REG	0x000C	CCU Post0 Clock Enable Register

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CSIC TOP register list:

Register Name	Offset	Register Description
CSIC_TOP_EN_REG	0x0000	CSIC TOP Enable Register
CSIC_PTN_GEN_EN_REG	0x0004	CSIC Pattern Generation Enable Register
CSIC_PTN_CTRL_REG	0x0008	CSIC Pattern Control Register
CSIC_PTN_LEN_REG	0x0020	CSIC Pattern Generation Length Register
CSIC_PTN_ADDR_REG	0x0024	CSIC Pattern Generation Address Register
CSIC_PTN_ISP_SIZE_REG	0x0028	CSIC Pattern ISP Size Register
CSIC_DMA0_INPUT_SEL_REG	0x00A0	CSIC DMA0 Input Select Register
CSIC_DMA1_INPUT_SEL_REG	0x00A4	CSIC DMA1 Input Select Register
CSIC_BIST_CS_REG	0x00DC	CSIC BIST CS Register
CSIC_BIST_CONTROL_REG	0x00E0	CSIC BIST Control Register
CSIC_BIST_START_REG	0x00E4	CSIC BIST Start Register
CSIC_BIST_END_REG	0x00E8	CSIC BIST End Register
CSIC_BIST_DATA_MASK_REG	0x00EC	CSIC BIST Data Mask Register
CSIC_MBUS_REQ_MAX_REG	0x00F0	CSIC MBUS REQ MAX Register
CSIC_MULF_MOD_REG	0x0100	CSIC Multi-Frame Mode Register
CSIC_MULF_INT_REG	0x0104	CSIC Multi-Frame Interrupt Register

PARSER0 register list:

Register Name	Offset	Register Description
PRS_EN_REG	0x0000	Parser Enable Register
PRS_NCSIC_IF_CFG_REG	0x0004	Parser NCSIC Interface Configuration Register
PRS_CAP_REG	0x000C	Parser Capture Register
CSIC_PRS_SIGNAL_STA_REG	0x0010	CSIC Parser Signal Status Register
CSIC_PRS_NCSIC_BT656_HEAD_CFG_REG	0x0014	CSIC Parser NCSIC BT656 Header Configuration Register
PRS_C0_INFMT_REG	0x0024	Parser Channel_0 Input Format Register
PRS_C0_OUTPUT_HSIZE_REG	0x0028	Parser Channel_0 Output Horizontal Size Register
PRS_C0_OUTPUT_VSIZE_REG	0x002C	Parser Channel_0 Output Vertical Size Register
PRS_C0_INPUT_PARA0_REG	0x0030	Parser Channel_0 Input Parameter0 Register
PRS_C0_INPUT_PARA1_REG	0x0034	Parser Channel_0 Input Parameter1 Register
PRS_C0_INPUT_PARA2_REG	0x0038	Parser Channel_0 Input Parameter2 Register
PRS_C0_INPUT_PARA3_REG	0x003C	Parser Channel_0 Input Parameter3 Register
PRS_C0_INT_EN_REG	0x0040	Parser Channel_0 Interrupt Enable Register
PRS_C0_INT_STA_REG	0x0044	Parser Channel_0 Interrupt Status Register
PRS_CH0_LINE_TIME_REG	0x0048	Parser Channel_0 Line Time Register
PRS_C1_INFMT_REG	0x0124	Parser Channel_1 Input Format Register
PRS_C1_OUTPUT_HSIZE_REG	0x0128	Parser Channel_1 Output Horizontal Size Register
PRS_C1_OUTPUT_VSIZE_REG	0x012C	Parser Channel_1 Output Vertical Size Register

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Register Name	Offset	Register Description
PRS_C1_INPUT_PARA0_REG	0x0130	Parser Channel_1 Input Parameter0 Register
PRS_C1_INPUT_PARA1_REG	0x0134	Parser Channel_1 Input Parameter1 Register
PRS_C1_INPUT_PARA2_REG	0x0138	Parser Channel_1 Input Parameter2 Register
PRS_C1_INPUT_PARA3_REG	0x013C	Parser Channel_1 Input Parameter3 Register
PRS_C1_INT_EN_REG	0x0140	Parser Channel_1 Interrupt Enable Register
PRS_C1_INT_STA_REG	0x0144	Parser Channel_1 Interrupt Status Register
PRS_CH1_LINE_TIME_REG	0x0148	Parser Channel_1 Line Time Register
PRS_C2_INFMT_REG	0x0224	Parser Channel_2 Input Format Register
PRS_C2_OUTPUT_HSIZE_REG	0x0228	Parser Channel_2 Output Horizontal Size Register
PRS_C2_OUTPUT_VSIZE_REG	0x022C	Parser Channel_2 Output Vertical Size Register
PRS_C2_INPUT_PARA0_REG	0x0230	Parser Channel_2 Input Parameter0 Register
PRS_C2_INPUT_PARA1_REG	0x0234	Parser Channel_2 Input Parameter1 Register
PRS_C2_INPUT_PARA2_REG	0x0238	Parser Channel_2 Input Parameter2 Register
PRS_C2_INPUT_PARA3_REG	0x023C	Parser Channel_2 Input Parameter3 Register
PRS_C2_INT_EN_REG	0x0240	Parser Channel_2 Interrupt Enable Register
PRS_C2_INT_STA_REG	0x0244	Parser Channel_2 Interrupt Status Register
PRS_CH2_LINE_TIME_REG	0x0248	Parser Channel_2 Line Time Register
PRS_C3_INFMT_REG	0x0324	Parser Channel_3 Input Format Register
PRS_C3_OUTPUT_HSIZE_REG	0x0328	Parser Channel_3 Output Horizontal Size Register
PRS_C3_OUTPUT_VSIZE_REG	0x032C	Parser Channel_3 Output Vertical Size Register
PRS_C3_INPUT_PARA0_REG	0x0330	Parser Channel_3 Input Parameter0 Register
PRS_C3_INPUT_PARA1_REG	0x0334	Parser Channel_3 Input Parameter1 Register
PRS_C3_INPUT_PARA2_REG	0x0338	Parser Channel_3 Input Parameter2 Register
PRS_C3_INPUT_PARA3_REG	0x033C	Parser Channel_3 Input Parameter3 Register
PRS_C3_INT_EN_REG	0x0340	Parser Channel_3 Interrupt Enable Register
PRS_C3_INT_STA_REG	0x0344	Parser Channel_3 Interrupt Status Register
PRS_CH3_LINE_TIME_REG	0x0348	Parser Channel_3 Line Time Register
CSIC_PRS_NCSIC_RX_SIGNAL0_DLY_ADJ_REG	0x0500	CSIC Parser NCSIC RX Signal0 Delay Adjust Register
CSIC_PRS_NCSIC_RX_SIGNAL5_DLY_ADJ_REG	0x0514	CSIC Parser NCSIC RX Signal5 Delay Adjust Register
CSIC_PRS_NCSIC_RX_SIGNAL6_DLY_ADJ_REG	0x0518	CSIC Parser NCSIC RX Signal6 Delay Adjust Register

DMA0/1 register list:

Register Name	Offset	Register Description
CSIC_DMA_EN_REG	0x0000	CSIC DMA Enable Register
CSIC_DMA_CFG_REG	0x0004	CSIC DMA Configuration Register
CSIC_DMA_HSIZE_REG	0x0010	CSIC DMA Horizontal Size Register
CSIC_DMA_VSIZE_REG	0x0014	CSIC DMA Vertical Size Register

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Register Name	Offset	Register Description
CSIC_DMA_F0_BUFA_REG	0x0020	CSIC DMA FIFO 0 Output Buffer-A Address Register
CSIC_DMA_F0_BUFA_RESULT_REG	0x0024	CSIC DMA FIFO 0 Output Buffer-A Address Result Register
CSIC_DMA_F1_BUFA_REG	0x0028	CSIC DMA FIFO 1 Output Buffer-A Address Register
CSIC_DMA_F1_BUFA_RESULT_REG	0x002C	CSIC DMA FIFO 1 Output Buffer-A Address Result Register
CSIC_DMA_F2_BUFA_REG	0x0030	CSIC DMA FIFO 2 Output Buffer-A Address Register
CSIC_DMA_F1_BUFA_RESULT_REG	0x0034	CSIC DMA FIFO 2 Output Buffer-A Address Result Register
CSIC_DMA_BUF_LEN_REG	0x0038	CSIC DMA Buffer Length Register
CSIC_DMA_FLIP_SIZE_REG	0x003C	CSIC DMA Flip Size Register
CSIC_DMA_VI_TO_TH0_REG	0x0040	CSIC DMA Video Input Timeout Threshold0 Register
CSIC_DMA_VI_TO_TH1_REG	0x0044	CSIC DMA Video Input Timeout Threshold1 Register
CSIC_DMA_VI_TO_CNT_VAL_REG	0x0048	CSIC DMA Video Input Timeout Counter Value Register
CSIC_DMA_CAP_STA_REG	0x004C	CSIC DMA Capture Status Register
CSIC_DMA_INT_EN_REG	0x0050	CSIC DMA Interrupt Enable Register
CSIC_DMA_INT_STA_REG	0x0054	CSIC DMA Interrupt Status Register
CSIC_DMA_LINE_CNT_REG	0x0058	CSIC DMA LINE Counter Register
CSIC_DMA_FRM_CNT_REG	0x005C	CSIC DMA Frame Counter Register
CSIC_DMA_FRM_CLK_CNT_REG	0x0060	CSIC DMA Frame Clock Counter Register
CSIC_DMA_ACC_ITNL_CLK_CNT_REG	0x0064	CSIC DMA Accumulated And Internal Clock Counter Register
CSIC_DMA_FIFO_STAT_REG	0x0068	CSIC DMA FIFO Statistic Register
CSIC_DMA_FIFO_THRS_REG	0x006C	CSIC DMA FIFO Threshold Register
CSIC_DMA_PCLK_STAT_REG	0x0070	CSIC DMA PCLK Statistic Register
CSIC_DMA_BUF_ADDR_FIFO0_ENTRY_REG	0x0080	CSIC DMA BUF Address FIFO0 Entry Register
CSIC_DMA_BUF_ADDR_FIFO1_ENTRY_REG	0x0084	CSIC DMA BUF Address FIFO1 Entry Register
CSIC_DMA_BUF_ADDR_FIFO2_ENTRY_REG	0x0088	CSIC DMA BUF Address FIFO2 Entry Register
CSIC_DMA_BUF_TH_REG	0x008C	CSIC DMA BUF Threshold Register
CSIC_DMA_BUF_ADDR_FIFO_CON_REG	0x0090	CSIC DMA BUF Address FIFO Content Register
CSIC_DMA_STORED_FRM_CNT_REG	0x0094	CSIC DMA Stored Frame Counter Register
CSIC_FEATURE_REG	0x01F4	CSIC DMA Feature List Register

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7.1.5 CCU Register Description

7.1.5.1 0x0000 CCU Clock Mode Register(Default Value:0x8000_0000)

Offset: 0x0000			Register Name: CCU_CLK_MODE_REG
Bit	Read/Write	Default/Hex	Description
31	R/W	0x1	CCU_CLK_GATING_DISABLE 0: CCU Clock Gating Registers (0x0004~0x0010) effect 1: CCU Clock Gating Registers (0x0004~0x0010) not effect
30:0	/	/	/

7.1.5.2 0x0004 CCU Parser Clock Enable Register(Default Value:0x0000_0000)

Offset: 0x0004			Register Name: CCU_PARSER_CLK_EN_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R/W	0x0	MCSI_PARSER0_CLK_ENABLE 0: CSI Parser0 clock disable 1: CSI Parser0 clock enable

7.1.5.3 0x000C CCU Post0 Clock Enable Register(Default Value:0x0000_0000)

Offset: 0x000C			Register Name: CCU_POST0_CLK_EN_REG
Bit	Read/Write	Default/Hex	Description
31:17	/	/	/
16	R/W	0x0	MCSI_POST0_CLK_ENABLE 0: POST0 clock disable 1: POST0 clock enable
15:2	/	/	/
1	R/W	0x0	MCSI_BK1_CLK_ENABLE 0: BK1 clock disable 1: BK1 clock enable, when MCSI_POST0_CLK_ENABLE is 1
0	R/W	0x0	MCSI_BK0_CLK_ENABLE 0: BK0 clock disable 1: BK0 clock enable, when MCSI_POST0_CLK_ENABLE is 1

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7.1.6 CSIC Top Register Description

7.1.6.1 0x0000 CSIC TOP Enable Register (Default Value:0x0000_0000)

Offset: 0x0000			Register Name: CSIC_TOP_EN_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2	R/W	0x0	BIST_MODE_EN 0: Closed 1: EN BIST TEST
1	/	/	/
0	R/W	0x0	CSIC_TOP_EN 0: Reset and disable the CSIC module 1: Enable the CSIC module

7.1.6.2 0x0004 CSIC Pattern Generation Enable Register (Default Value:0x0000_0000)

Offset: 0x0004			Register Name: CSIC_PTN_GEN_EN_REG
Bit	Read/Write	Default/Hex	Description
31:24	/	/	/
23:16	R/W	0x0	PTN_CYCLE Pattern generating cycle counter. The pattern in dram will be generated in cycles of PTN_CYCLE+1.
15:5	/	/	/
4	R/WAC	0x0	PTN_START CSIC Pattern Generating Start 0: Finish 1: Start Software writes this bit to “1” to start pattern generating from DRAM. When finished, the hardware will clear this bit to “0” automatically. Generating cycles depends on PTN_CYCLE.
3:1	/	/	/
0	R/W	0x0	PTN_GEN_EN Pattern Generation Enable

7.1.6.3 0x0008 CSIC Pattern Control Register (Default Value:0x0000_000F)

Offset: 0x0008			Register Name: CSIC_PTN_CTRL_REG
Bit	Read/Write	Default/Hex	Description
31:26	/	/	/

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Offset: 0x0008			Register Name: CSIC_PTN_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
25:24	R/W	0x0	PTN_PORT_SEL Pattern Generator output port selection 10:NCSIC0 others:reserved
23:22	/	/	/
21:20	R/W	0x0	PTN_GEN_DATA_WIDTH 00:8-bit 01:10-bit 10:12-bit 11:reserved
19:16	R/W	0x0	PTN_MODE Pattern mode selection 0000–0011:reserved 0100:NCSIC YUV 8 bits width 0101:NCSIC YUV 16 bits width 0110:reserved 0111:reserved 1000:BT656 8 bits width 1001:BT656 16 bits width 1010:reserved 1011:reserved 1100:BAYER 12 bits for ISPFE 1101:UYVY422 12 bits for ISPFE 1110:UYVY420 12 bits for ISPFE 1111:reserved
15:10	/	/	/
9:8	R/W	0x0	PTN_GEN_CLK_DIV Packet generator clock divider
7:0	R/W	0xF	PTN_GEN_DLY Clocks delayed before pattern generating start.

7.1.6.4 0x0020 CSIC Pattern Generation Length Register (Default Value:0x0000_0000)

Offset: 0x0020			Register Name: CSIC_PTN_LEN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	PTN_LEN The pattern length in byte when generating pattern.

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7.1.6.5 0x0024 CSIC Pattern Generation Address Register (Default Value:0x0000_0000)

Offset: 0x0024			Register Name: CSIC_PTN_ADDR_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	PTN_ADDR The pattern DRAM address when generating pattern.

7.1.6.6 0x0028 CSIC Pattern ISP Size Register (Default Value:0x0000_0000)

Offset: 0x0028			Register Name: CSIC_PTN_ISP_SIZE_REG
Bit	Read/Write	Default/Hex	Description
31:29	/	/	/
28:16	R/W	0x0	Height Vertical size, only valid for ISP mode pattern generation.
15:13	/	/	/
12:0	R/W	0x0	Width Horizontal size, only valid for ISP mode pattern generation.

7.1.6.7 0x00A0 CSIC DMA0 Input Select Register (Default Value:0x0000_0000)

Offset: 0x00A0			Register Name: CSIC_DMA0_INPUT_SEL_REG
Bit	Read/Write	Default/Hex	Description
31:4	/	/	/
3:0	R/W	0x0	DMA0 Input Select 0000: input from ISP0 CH0 0001: input from ISP0 CH1 0010: input from ISP0 CH2 0011: input from ISP0 CH3 Others: Reserved

7.1.6.8 0x00A4 CSIC DMA1 Input Select Register (Default Value:0x0000_0000)

Offset: 0x00A4			Register Name: CSIC_DMA1_INPUT_SEL_REG
Bit	Read/Write	Default/Hex	Description
31:4	/	/	/
3:0	R/W	0x0	DMA1 Input Select 0000: input from ISP0 CH0 0001: input from ISP0 CH1 0010: input from ISP0 CH2

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Offset: 0x00A4			Register Name: CSIC_DMA1_INPUT_SEL_REG
Bit	Read/Write	Default/Hex	Description
			0011: input from ISP0 CH3 Others: Reserved

7.1.6.9 0x00DC CSIC BIST CS Register (Default Value:0x0000_0000)

Offset: 0x00DC			Register Name: CSIC_BIST_CS_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2:0	R/W	0x0	BIST_CS 000: Set when BK0 memory bist 001: Set when BK1 memory bist Others: Reserved

7.1.6.10 0x00E0 CSIC BIST Control Register (Default Value:0x0000_0200)

Offset :0x00E0			Register Name: CSIC_BIST_CTRL_REG
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15	R	0x0	BIST_ERR_STA BIST Error Status 0: No effect 1: Error
14:12	R	0x0	BIST_ERR_PAT BIST Error Pattern
11:10	R	0x0	BIST_ERR_CYC BIST Error Cycle
9	R	0x1	BIST_STOP BIST STOP 0: Running 1: Stop
8	R	0x0	BIST_BUSY BIST Busy 0: Idle 1: Busy
7:5	R/W	0x0	BIST_REG_SEL BIST REG select
4	R/W	0x0	BIST_ADDR_Mode_SEL BIST Address Mode Select
3:1	R/W	0x0	BIST_WDATA_PAT

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Offset :0x00E0			Register Name: CSIC_BIST_CTRL_REG
Bit	Read/Write	Default/Hex	Description
			BIST Write Data Pattern 000: 0x00000000 001: 0x55555555 010: 0x33333333 011: 0x0F0F0F0F 100: 0x00FF00FF 101: 0x0000FFFF others: Reserved
0	R/W	0x0	BIST_EN BIST Enable A positive will trigger the BIST to start.

7.1.6.11 0x00E4 CSIC BIST Start Address Register (Default Value:0x0000_0000)

Offset :0x00E4			Register Name: CSIC_BIST_START_ADDR_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	BIST Start Address BIST Start Address. It is 32-bit aligned.

7.1.6.12 0x00E8 CSIC BIST End Address Register (Default Value:0x0000_0000)

Offset :0x00E8			Register Name: CSIC_BIST_END_ADDR_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	BIST END Address BIST END Address. It is 32-bit aligned.

7.1.6.13 0x00EC CSIC BIST Data Mask Register (Default Value:0x0000_0000)

Offset :0x00EC			Register Name: CSIC_BIST_DATA_MASK_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	BIST_DATA_MASK BIST Data Mask 0: Unmask 1: Mask

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7.1.6.14 0x00F0 CSIC MBUS REQ MAX Register (Default Value:0x000F_0F0F)

Offset: 0x00F0			Register Name: CSIC_MBUS_REQ_MAX_REG
Bit	Read/Write	Default/Hex	Description
31:5	/	/	/
4:0	R/W	0x0F	MCSI_MEM_REQ_MAX Maximum of request commands for the master granted in MCSI_MEM arbiter is N+1.

7.1.6.15 0x0100 CSIC Multi-Frame Mode Register (Default Value:0x0000_0000)

Offset: 0x0100			Register Name: CSIC_MULF_MOD_REG
Bit	Read/Write	Default/Hex	Description
31:24	R	0x0	MULF_STATUS
23:16	/	/	/
15:8	R/W	0x0	MULF_CS
7:1	/	/	/
0	R/W	0x0	MULF_EN

7.1.6.16 0x0104 CSIC Multi-Frame Interrupt Register (Default Value:0x0000_0000)

Offset: 0x0104			Register Name: CSIC_MULF_INT_REG
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17	R/W1C	0x0	MULF_ERR_PD
16	R/W1C	0x0	MULF_DONE_PD
15:2	/	/	/
1	R/W	0x0	MULF_ERR_EN
0	R/W	0x0	MULF_DONE_EN

7.1.7 Parser Register Description

7.1.7.1 0x0000 Parser Enable Register (Default Value:0x0000_0000)

Offset: 0x0000			Register Name: PRS_EN_REG
Bit	Read/Write	Default/Hex	Description
31:17	/	/	/
16	R/W	0x0	NCSIC_EN 0: Reset and disable the NCSIC module

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Offset: 0x0000			Register Name: PRS_EN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: Enable the NCSIC module
15	R/W	0x0	PCLK_EN 0: Gate pclk input 1: Enable pclk input
14:3	/	/	/
2	R/W	0x0	PRS_CH_MODE 0: Parser output channel 0–3 corresponding from input channel 0–3 1: Parser output channel 0–3 all from input channel 0 (MIPI SEHDR)
1	R/W	0x0	PRS_MODE 0: Reserved 1: MCSI
0	R/W	0x0	PRS_EN 0: Reset and disable the parser module 1: Enable the parser module

7.1.7.2 0x0004 Parser NCSIC Interface Configuration Register (Default Value:0x0105_0080)

Offset: 0x0004			Register Name: PRS_NCSI_IF_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	YUV420_LINE_ORDER 0: YUV420 input in Y-YC-Y-YC Line Order 1: YUV420 input in YC-Y-YC-Y Line Order
30:28	/	/	/
27:24	R/W	0x1	FIELD_DT_PCLK_SHIFT Only for vsync detected field mode, the odd field permitted pclk shift = 4* FIELD_DT_PCLK_SHIFT
23:20	R/W	0x0	Source type Bit 20–23 corresponding to the SRC_TYPEs for channel0–3 0: Progressed 1: Interlaced
19	R/W	0x0	FIELD Field polarity (For YUV HV timing) 0: negative (field=0 indicates odd, field=1 indicates even) 1: positive (field=1 indicates odd, field=0 indicates even) Field sequence (For BT656 timing) 0: Normal sequence (field 0 first) 1: Inverse sequence (field 1 first)
18	R/W	0x1	VREF_POL Vref polarity

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Offset: 0x0004			Register Name: PRS_NCSI_IF_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			0: negative 1: positive This register is not applied to CCIR656 interface.
17	R/W	0x0	HERF_POL Href polarity 0: negative 1: positive This register is not applied to CCIR656 interface.
16	R/W	0x1	CLK_POL Data clock type 0: active in rising edge 1: active in falling edge
15:14	R/W	0x0	Field_DT_MODE (only valid when CSI_IF is YUV and source type is interlaced) 00: by both field and vsync 01: by field 10: by vsync 11: reserved
13	R/W	0x0	DDR_SAMPLE_MODE_EN 0: disable 1: enable
12:11	R/W	0x0	SEQ_8PLUS2 When select IF_DATA_WIDTH to be 8+2bit, odd/even pixel byte at CSI-D[11:4] will be rearranged to D[11:2]+2'b0 at the actual CSI data bus according to these sequences: 00: 6'bx+D[9:8], D[7:0] 01: D[9:2], 6'bx+D[1:0] 10: D[7:0], D[9:8]+6'bx 11: D[7:0], 6'bx+D[9:8]
10:8	R/W	0x0	IF_DATA_WIDTH 000: 8 bit data bus 001: 10 bit data bus 010: 12 bit data bus 011: 8+2bit data bus 100: 2x8bit data bus Others: Reserved
7:6	R/W	0x2	INPUT_SEQ Input data sequence, only valid for YUV422 and YUV420 input format. All data interleaved in one channel: 00: YUYV

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Offset: 0x0004			Register Name: PRS_NCSI_IF_CFG_REG
Bit	Read/Write	Default/Hex	Description
			01: YVYU 10: UYVY 11: VYUY Y and UV in separated channel: x0: UV x1: VU
5	/	/	/
4:0	R/W	0x0	CSI_IF YUV (separate syncs): 00000: RAW or YUV420/YUYV422 (each cycle one component input) Others: Reserved CCIR656 (embedded syncs): 00100: BT656 1 channel 01100: BT656 2 channels (All data interleaved in one data bus) 01110: BT656 4 channels (All data interleaved in one data bus) Others: Reserved

7.1.7.3 0x000C Parser Capture Register (Default Value:0x0000_0000)

Offset: 0x000C			Register Name: PRS_CAP_REG
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29:26	R/W	0x0	CH3_FPS_DS Fps down sample 0: no down sample 1: 1/2 fps, only receives the first frame every 2 frames 2: 1/3 fps, only receives the first frame every 3 frames 3: 1/4 fps, only receives the first frame every 4 frames 4: 1/5 fps, only receives the first frame every 4 frames …… 15: 1/16 fps, only receives the first frame every 16 frames
25	R/W	0x0	CH3_VCAP_ON Video capture control: Capture the video image data stream on channel 3. 0: Disable video capture If video capture is in progress, the CSI stops capturing image data at the end of the current frame, and all of the current frame data is written to output FIFO.

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Offset: 0x000C			Register Name: PRS_CAP_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: Enable video capture The CSI starts capturing image data at the start of the next frame.
24	RC/W	0x0	CH3_SCAP_ON Still capture control: Capture a single still image frame on channel 3. 0: Disable still capture 1: Enable still capture The CSI module starts capturing image data at the start of the next frame. The CSI module captures only one frame of image data. This bit is self cleared and always reads as a 0.
13:12	/	/	/
21:18	R/W	0x0	CH2_FPS_DS Fps down sample 0: no down sample 1: 1/2 fps, only receives the first frame every 2 frames 2: 1/3 fps, only receives the first frame every 3 frames 3: 1/4 fps, only receives the first frame every 4 frames 4: 1/5 fps, only receives the first frame every 4 frames …… 15: 1/16 fps, only receives the first frame every 16 frames
17	R/W	0x0	CH2_VCAP_ON Video capture control: Capture the video image data stream on channel 2. 0: Disable video capture If video capture is in progress, the CSI stops capturing image data at the end of the current frame, and all of the current frame data is written to output FIFO. 1: Enable video capture The CSI starts capturing image data at the start of the next frame.
16	RC/W	0x0	CH2_SCAP_ON Still capture control: Capture a single still image frame on channel 2. 0: Disable still capture 1: Enable still capture The CSI module starts capturing image data at the start of the next frame. The CSI module captures only one frame of image data. This bit is self cleared and always reads as a 0.
15:14	/	/	/

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Offset: 0x000C			Register Name: PRS_CAP_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
13:10	R/W	0x0	CH1_FPS_DS Fps down sample 0: no down sample 1: 1/2 fps, only receives the first frame every 2 frames 2: 1/3 fps, only receives the first frame every 3 frames 3: 1/4 fps, only receives the first frame every 4 frames 4: 1/5 fps, only receives the first frame every 4 frames …… 15: 1/16 fps, only receives the first frame every 16 frames
9	R/W	0x0	CH1_VCAP_ON Video capture control: Capture the video image data stream on channel 1. 0: Disable video capture If video capture is in progress, the CSI stops capturing image data at the end of the current frame, and all of the current frame data is written to output FIFO. 1: Enable video capture The CSI starts capturing image data at the start of the next frame.
8	RC/W	0x0	CH1_SCAP_ON Still capture control: Capture a single still image frame on channel 1. 0: Disable still capture 1: Enable still capture The CSI module starts capturing image data at the start of the next frame. The CSI module captures only one frame of image data. This bit is self cleared and always reads as a 0.
7:6	/	/	/
5:2	R/W	0x0	CH0_FPS_DS Fps down sample 0: no down sample 1: 1/2 fps, only receives the first frame every 2 frames 2: 1/3 fps, only receives the first frame every 3 frames 3: 1/4 fps, only receives the first frame every 4 frames 4: 1/5 fps, only receives the first frame every 4 frames …… 15: 1/16 fps, only receives the first frame every 16 frames
1	R/W	0x0	CH0_VCAP_ON Video capture control: Capture the video image data stream on channel 0. 0: Disable video capture

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Offset: 0x000C			Register Name: PRS_CAP_REG
Bit	Read/Write	Default/Hex	Description
			If video capture is in progress, the CSI stops capturing image data at the end of the current frame, and all of the current frame data is written to output FIFO. 1: Enable video capture The CSI starts capturing image data at the start of the next frame.
0	RC/W	0x0	CH0_SCAP_ON Still capture control: Capture a single still image frame on channel 0. 0: Disable still capture. 1: Enable still capture The CSI module starts capturing image data at the start of the next frame. The CSI module captures only one frame of image data. This bit is self cleared and always reads as a 0.

7.1.7.4 0x0010 Parser Signal Status Register (Default Value:0x0000_0000)

Offset: 0x0010			Register Name: CSIC_PRS_SIGNAL_STA_REG
Bit	Read/Write	Default/Hex	Description
31:25	/	/	/
24	R	0x0	PCLK_STA Indicates the pclk status 0: low 1: high
23:0	R	0x0	DATA_STA Indicates the Dn status (n=0–23), MSB for D23, LSB for D0 0: low 1: high

7.1.7.5 0x0014 Parser NCSIC BT656 Header Configuration Register (Default Value:0x0302_0100)

Offset: 0x0014			Register Name: CSIC_PRS_NCSIC_BT656_HEAD_CFG_REG
Bit	Read/Write	Default/Hex	Description
31:28	/	/	/
27:24	R/W	0x3	CH3_ID The low 4-bit of BT656 header for channel 3 Only valid in BT656 multi-channel mode
23:20	/	/	/

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Offset: 0x0014			Register Name: CSIC_PRS_NCSIC_BT656_HEAD_CFG_REG
Bit	Read/Write	Default/Hex	Description
19:16	R/W	0x2	CH2_ID The low 4-bit of BT656 header for channel 2 Only valid in BT656 multi-channel mode
15:12	/	/	/
11:8	R/W	0x1	CH1_ID The low 4-bit of BT656 header for channel 1 Only valid in BT656 multi-channel mode
7:4	/	/	/
3:0	R/W	0x0	CH0_ID The low 4-bit of BT656 header for channel 0 Only valid in BT656 multi-channel mode

7.1.7.6 0x0024 Parser Channel_0 Input Format Register (Default Value:0x0000_0003)

Offset: 0x0024			Register Name: PRS_CH0_INFMT_REG
Bit	Read/Write	Default/Hex	Description
31:4	/	/	/
3:0	R/W	0x3	INPUT_FMT Input data format 0000: RAW stream 0001: reserved 0010: reserved 0011: YUV422 0100: YUV420 Others: reserved

7.1.7.7 0x0028 Parser Channel_0 Output Horizontal Size Register (Default Value:0x0500_0000)

Offset: 0x0028			Register Name: PRS_CH0_OUTPUT_HSIZE_REG
Bit	Read/Write	Default/Hex	Description
31:29	/	/	/
28:16	R/W	0x500	HOR_LEN Horizontal pixel unit length. Valid pixel of a line.
15:13	/	/	/
12:0	R/W	0x0	HOR_START Horizontal pixel unit start. Pixel is valid from this pixel.

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7.1.7.8 0x002C Parser Channel_0 Output Vertical Size Register (Default Value:0x02D0_0000)

Offset: 0x002C			Register Name: PRS_CH0_OUTPUT_VSIZE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x2D0	VER_LEN Valid line number of a frame.
15:13	/	/	/
12:0	R/W	0x0	VER_START Vertical line start. data is valid from this line.

7.1.7.9 0x003C Parser Channel_0 Input Parameter0 Register (Default Value:0x0000_0000)

Offset: 0x0030			Register Name: PRS_CH0_INPUT_PARA0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R	0x0	INPUT_SRC_TYPE 0: Progress 1: Interlace

7.1.7.10 0x0034 Parser Channel_0 Input Parameter1 Register (Default Value:0x0000_0000)

Offset: 0x0034			Register Name: PRS_CH0_INPUT_PARA1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:16	R	0x0	INPUT_VT INPUT_VT = INPUT_VB+INPUT_Y
15:14	/	/	/
13:0	R	0x0	INPUT_HT INPUT_HT = INPUT_HB+INPUT_X

7.1.7.11 0x0038 Parser Channel_0 Input Parameter2 Register (Default Value:0x0000_0000)

Offset: 0x0038			Register Name: PRS_CH0_INPUT_PARA2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:16	R	0x0	INPUT_VB
15:14	/	/	/
13:0	R	0x0	INPUT_HB

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7.1.7.12 0x003C Parser Channel_0 Input Parameter3 Register (Default Value:0x0000_0000)

Offset: 0x003C			Register Name: PRS_CH0_INPUT_PARA3_REG
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29:16	R	0x0	INPUT_Y
15:14	/	/	/
13:0	R	0x0	INPUT_X

7.1.7.13 0x0040 Parser Channel_0 Interrupt Enable Register (Default Value:0x0000_0000)

Offset: 0x0040			Register Name: PRS_CH0_INT_EN_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2	R/W	0x0	MUL_ERR_INT_EN Multi-channel writing error Indicates error has been detected for writing data to a wrong channel.
1	R/W	0x0	INPUT_PARA1_INT_EN 0: disable 1: enable
0	R/W	0x0	INPUT_PARA0_INT_EN 0: disable 1: enable

7.1.7.14 0x0044 Parser Channel_0 Interrupt Status Register (Default Value:0x0000_0000)

Offset: 0x0044			Register Name: PRS_CH0_INT_STA_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2	R/W1C	0x0	MUL_ ERR_PD Multi-channel writing error
1	R/W1C	0x0	INPUT_SRC_PD1 When the parser input parameter0 register update,this flag set to 1. Write 1 to clear.
0	R/W1C	0x0	INPUT_SRC_PD0 When the parser input parameter1 register, parser input parameter2 register or parser input parameter3 register update, this flag set to 1. Write 1 to clear.

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7.1.7.15 0x0048 Parser Channel_0 Line Time Register (Default Value:0x0000_0000)

Offset: 0x0048			Register Name: PRS_CH0_LINE_TIME_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	RO	0x0	PRS_CH0_HBLK_TIME Time of H Blanking when vsync is valid The unit is csi_top_clk cycle
15:0	RO	0x0	PRS_CH0_HSYN_TIME Time of H SYNC when vsync is valid The unit is csi_top_clk cycle

7.1.7.16 0x0124 Parser Channel_1 Input Format Register (Default Value:0x0000_0003)

Offset: 0x0124			Register Name: PRS_CH1_INFMT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3:0	R/W	0x3	INPUT_FMT Input data format 0000: RAW stream 0001: reserved 0010: reserved 0011: YUV422 0100: YUV420 Others: reserved

7.1.7.17 0x0128 Parser Channel_1 Output Horizontal Size Register (Default Value:0x0500_0000)

Offset: 0x0128			Register Name: PRS_CH1_OUTPUT_HSIZE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x500	HOR_LEN Horizontal pixel unit length. Valid pixel of a line.
15:13	/	/	/
12:0	R/W	0x0	HOR_START Horizontal pixel unit start. Pixel is valid from this pixel.

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7.1.7.18 0x012C Parser Channel_1 Output Vertical Size Register (Default Value:0x02D0_0000)

Offset: 0x012C			Register Name: PRS_CH1_OUTPUT_VSIZE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x2d0	VER_LEN Valid line number of a frame.
15:13	/	/	/
12:0	R/W	0x0	VER_START Vertical line start. Data is valid from this line.

7.1.7.19 0x0130 Parser Channel_1 Input Parameter0 Register (Default Value:0x0000_0000)

Offset: 0x0130			Register Name: PRS_CH1_INPUT_PARA0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R	0x0	INPUT_SRC_TYPE 0: Progress 1: Interlace

7.1.7.20 0x0134 Parser Channel_1 Input Parameter1 Register (Default Value:0x0000_0000)

Offset: 0x0134			Register Name: PRS_CH1_INPUT_PARA1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:16	R	0x0	INPUT_VT INPUT_VT = INPUT_VB+INPUT_Y
15:14	/	/	/
13:0	R	0x0	INPUT_HT INPUT_HT = INPUT_HB+INPUT_X

7.1.7.21 0x0138 Parser Channel_1 Input Parameter2 Register (Default Value:0x0000_0000)

Offset: 0x0138			Register Name: PRS_CH1_INPUT_PARA2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:16	R	0x0	INPUT_VB
15:14	/	/	/

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Offset: 0x0138			Register Name: PRS_CH1_INPUT_PARA2_REG
Bit	Read/Write	Default/Hex	Description
13:0	R	0x0	INPUT_HB

7.1.7.22 0x013C Parser Channel_1 Input Parameter3 Register (Default Value:0x0000_0000)

Offset: 0x013C			Register Name: PRS_CH1_INPUT_PARA3_REG
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29:16	R	0x0	INPUT_Y
15:14	/	/	/
13:0	R	0x0	INPUT_X

7.1.7.23 0x0140 Parser Channel_1 Interrupt Enable Register (Default Value:0x0000_0000)

Offset: 0x0140			Register Name: PRS_CH1_INT_EN_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2	R/W	0x0	MUL_ERR_INT_EN Multi-channel writing error Indicates error has been detected for writing data to a wrong channel.
1	R/W	0x0	INPUT_PARA1_INT_EN 0: Disable 1: Enable
0	R/W	0x0	INPUT_PARA0_INT_EN 0: Disable 1: Enable

7.1.7.24 0x0144 Parser Channel_1 Interrupt Status Register (Default Value:0x0000_0000)

Offset: 0x0144			Register Name: PRS_CH1_INT_STA_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2	R/W1C	0x0	MUL_ ERR_PD Multi-channel writing error
1	R/W1C	0x0	INPUT_SRC_PD1 When the parser input parameter0 register update, this flag is set to 1. Write 1 to clear.

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Offset: 0x0144			Register Name: PRS_CH1_INT_STA_REG
Bit	Read/Write	Default/Hex	Description
0	R/W1C	0x0	INPUT_SRC_PD0 When the parser input parameter1 register, parser input parameter2 register or parser input parameter3 register update, this flag is set to 1. Write 1 to clear.

7.1.7.25 0x0148 Parser Channel_1 Line Time Register (Default Value:0x0000_0000)

Offset: 0x0148			Register Name: PRS_CH1_LINE_TIME_REG
Bit	Read/Write	Default/Hex	Description
31:16	RO	0x0	PRS_CH1_HBLK_TIME Time of H Blanking when vsync is valid The unit is csi_top_clk cycle.
15:0	RO	0x0	PRS_CH1_HSYN_TIME Time of H SYNC when vsync is valid The unit is csi_top_clk cycle.

7.1.7.26 0x0224 Parser Channel_2 Input Format Register (Default Value:0x0000_0003)

Offset: 0x0224			Register Name: PRS_CH2_INFMT_REG
Bit	Read/Write	Default/Hex	Description
31:4	/	/	/
3:0	R/W	0x3	INPUT_FMT Input data format 0000: RAW stream 0001: reserved 0010: reserved 0011: YUV422 0100: YUV420 Others: reserved

7.1.7.27 0x0228 Parser Channel_2 Output Horizontal Size Register (Default Value:0x0500_0000)

Offset: 0x0228			Register Name: PRS_CH2_OUTPUT_HSIZE_REG
Bit	Read/Write	Default/Hex	Description
31:29	/	/	/
28:16	R/W	0x500	HOR_LEN Horizontal pixel unit length. Valid pixel of a line.
15:13	/	/	/

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Offset: 0x0228			Register Name: PRS_CH2_OUTPUT_HSIZE_REG
Bit	Read/Write	Default/Hex	Description
12:0	R/W	0x0	HOR_START Horizontal pixel unit start. Pixel is valid from this pixel.

7.1.7.28 0x022C Parser Channel_2 Output Vertical Size Register (Default Value:0x02D0_0000)

Offset: 0x022C			Register Name: PRS_CH2_OUTPUT_VSIZE_REG
Bit	Read/Write	Default/Hex	Description
31:29	/	/	/
28:16	R/W	0x2D0	VER_LEN Valid line number of a frame.
15:13	/	/	/
12:0	R/W	0x0	VER_START Vertical line start. Data is valid from this line.

7.1.7.29 0x0230 Parser Channel_2 Input Parameter0 Register (Default Value:0x0000_0000)

Offset: 0x0230			Register Name: PRS_CH2_INPUT_PARA0_REG
Bit	Read/Write	Default/Hex	Description
31:1	/	/	/
0	R	0x0	INPUT_SRC_TYPE 0:Progress 1:Interlace

7.1.7.30 0x0234 Parser Channel_2 Input Parameter1 Register (Default Value:0x0000_0000)

Offset: 0x0234			Register Name: PRS_CH2_INPUT_PARA1_REG
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29:16	R	0x0	INPUT_VT INPUT_VT = INPUT_VB+INPUT_Y
15:14	/	/	/
13:0	R	0x0	INPUT_HT INPUT_HT = INPUT_HB+INPUT_X

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7.1.7.31 0x0238 Parser Channel_2 Input Parameter2 Register (Default Value:0x0000_0000)

Offset: 0x0238			Register Name: PRS_CH2_INPUT_PARA2_REG
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29:16	R	0x0	INPUT_VB
15:14	/	/	/
13:0	R	0x0	INPUT_HB

7.1.7.32 0x023C Parser Channel_2 Input Parameter3 Register (Default Value:0x0000_0000)

Offset: 0x023C			Register Name: PRS_CH2_INPUT_PARA3_REG
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29:16	R	0x0	INPUT_Y
15:14	/	/	/
13:0	R	0x0	INPUT_X

7.1.7.33 0x0240 Parser Channel_2 Interrupt Enable Register (Default Value:0x0000_0000)

Offset: 0x0240			Register Name: PRS_CH2_INT_EN_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2	R/W	0x0	MUL_ERR_INT_EN Multi-channel writing error Indicates error has been detected for writing data to a wrong channel.
1	R/W	0x0	INPUT_PARA1_INT_EN 0: disable 1: enable
0	R/W	0x0	INPUT_PARA0_INT_EN 0: disable 1: enable

7.1.7.34 0x0244 Parser Channel_2 Interrupt Status Register (Default Value:0x0000_0000)

Offset: 0x0244			Register Name: PRS_CH2_INT_STA_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/

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Offset: 0x0244			Register Name: PRS_CH2_INT_STA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W1C	0x0	MUL_ERR_PD Multi-channel writing error
1	R/W1C	0x0	INPUT_SRC_PD1 When the parser input parameter0 register update, this flag set to 1. Write 1 to clear.
0	R/W1C	0x0	INPUT_SRC_PD0 When the parser input parameter1 register, parser input parameter2 register or parser input parameter3 register update, this flag set to 1. Write 1 to clear.

7.1.7.35 0x0248 Parser Channel_2 Line Time Register (Default Value:0x0000_0000)

Offset: 0x0248			Register Name: PRS_CH2_LINE_TIME_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	RO	0x0	PRS_CH2_HBLK_TIME Time of H Blanking when vsync is valid The unit is csi_top_clk cycle
15:0	RO	0x0	PRS_CH2_HSYN_TIME Time of H SYNC when vsync is valid The unit is csi_top_clk cycle

7.1.7.36 0x0324 Parser Channel_3 Input Format Register (Default Value:0x0000_0003)

Offset: 0x0324			Register Name: PRS_CH3_INFMT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3:0	R/W	0x3	INPUT_FMT Input data format 0000: RAW stream 0001: reserved 0010: reserved 0011: YUV422 0100: YUV420 Others: reserved

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7.1.7.37 0x0328 Parser Channel_3 Output Horizontal Size Register (Default Value:0x0500_0000)

Offset: 0x0328			Register Name: PRS_CH3_OUTPUT_HSIZE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x500	HOR_LEN Horizontal pixel unit length. Valid pixel of a line.
15:13	/	/	/
12:0	R/W	0x0	HOR_START Horizontal pixel unit start. Pixel is valid from this pixel.

7.1.7.38 0x032C Parser Channel_3 Output Vertical Size Register (Default Value:0x02D0_0000)

Offset: 0x032C			Register Name: PRS_CH3_OUTPUT_VSIZE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x2d0	VER_LEN Valid line number of a frame.
15:13	/	/	/
12:0	R/W	0x0	VER_START Vertical line start. Data is valid from this line.

7.1.7.39 0x0330 Parser Channel_3 Input Parameter0 Register (Default Value:0x0000_0000)

Offset: 0x0330			Register Name: PRS_CH3_INPUT_PARA0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R	0x0	INPUT_SRC_TYPE 0:Progress 1:Interlace

7.1.7.40 Parser Channel_3 Input Parameter1 Register (Default Value:0x0000_0000)

Offset: 0x0334			Register Name: PRS_CH3_INPUT_PARA1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:16	R	0x0	INPUT_VT INPUT_VT = INPUT_VB+INPUT_Y

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Offset: 0x0334			Register Name: PRS_CH3_INPUT_PARA1_REG
Bit	Read/Write	Default/Hex	Description
15:14	/	/	/
13:0	R	0x0	INPUT_HT INPUT_HT = INPUT_HB+INPUT_X

7.1.7.41 0x0338 Parser Channel_3 Input Parameter2 Register (Default Value:0x0000_0000)

Offset: 0x0338			Register Name: PRS_CH3_INPUT_PARA2_REG
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29:16	R	0x0	INPUT_VB
15:14	/	/	/
13:0	R	0x0	INPUT_HB

7.1.7.42 0x033C Parser Channel_3 Input Parameter3 Register(Default Value:0x0000_0000)

Offset: 0x033C			Register Name: PRS_CH3_INPUT_PARA3_REG
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29:16	R	0x0	INPUT_Y
15:14	/	/	/
13:0	R	0x0	INPUT_X

7.1.7.43 0x0340 Parser Channel_3 Interrupt Enable Register (Default Value:0x0000_0000)

Offset: 0x0340			Register Name: PRS_CH3_INT_EN_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2	R/W	0x0	MUL_ERR_INT_EN Multi-channel writing error Indicates error has been detected for writing data to a wrong channel.
1	R/W	0x0	INPUT_PARA1_INT_EN 0:disable 1:enable
0	R/W	0x0	INPUT_PARA0_INT_EN 0:disable 1:enable

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7.1.7.44 0x0344 Parser Channel_3 Interrupt Status Register (Default Value:0x0000_0000)

Offset: 0x0344			Register Name: PRS_CH3_INT_STA_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2	R/W1C	0x0	MUL_ERR_PD Multi-channel writing error
1	R/W1C	0x0	INPUT_SRC_PD1 When the parser input parameter0 register update, this flag is set to 1. Write 1 to clear.
0	R/W1C	0x0	INPUT_SRC_PD0 When the parser input parameter1 register, parser input parameter2 register or parser input parameter3 register update, this flag is set to 1. Write 1 to clear.

7.1.7.45 0x0348 Parser Channel_3 Line Time Register (Default Value:0x0000_0000)

Offset: 0x0348			Register Name: PRS_CH3_LINE_TIME_REG
Bit	Read/Write	Default/Hex	Description
31:16	RO	0x0	PRS_CH3_HBLK_TIME Time of H Blanking when vsync is valid The unit is csi_top_clk cycle
15:0	RO	0x0	PRS_CH3_HSYN_TIME Time of H SYNC when vsync is valid The unit is csi_top_clk cycle

7.1.7.46 0x0500 CSIC Parser NCSIC RX Signal0 Delay Adjust Register (Default Value:0x0000_0000)

Offset: 0x0500			Register Name: CSIC_PRS_NCSIC_RX_SIGNAL0_DLY_ADJ_REG
Bit	Read/Write	Default/Hex	Description
31:29	/	/	/
28:24	R/W	0x0	Filed_dly 32 Step for adjust, 1 step = 0.2 ns
23:21	/	/	/
20:16	R/W	0x0	Vsync_dly 32 Step for adjust, 1 step = 0.2 ns
15:13	/	/	/
12:8	R/W	0x0	Hsync_dly 32 Step for adjust, 1 step = 0.2 ns

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Offset: 0x0500			Register Name: CSIC_PRS_NCSIC_RX_SIGNAL0_DLY_ADJ_REG
Bit	Read/Write	Default/Hex	Description
7:5	/	/	/
4:0	R/W	0x0	Pclk_dly 32 Step for adjust, 1 step = 0.2 ns

7.1.7.47 0x0514 CSIC Parser NCSIC RX Signal5 Delay Adjust Register (Default Value:0x0000_0000)

Offset: 0x0514			Register Name: CSIC_PRS_NCSIC_RX_SIGNAL5_DLY_ADJ_REG
Bit	Read/Write	Default/Hex	Description
31:29	/	/	/
28:24	R/W	0x0	D7_dly 32 Step for adjust, 1 step = 0.2 ns
23:21	/	/	/
20:16	R/W	0x0	D6_dly 32 Step for adjust, 1 step = 0.2 ns
15:13	/	/	/
12:8	R/W	0x0	D5_dly 32 Step for adjust, 1 step = 0.2 ns
7:5	/	/	/
4:0	R/W	0x0	D4_dly 32 Step for adjust, 1 step = 0.2 ns

7.1.7.48 0x0518 CSIC Parser NCSIC RX Signal6 Delay Adjust Register (Default Value:0x0000_0000)

Offset: 0x0518			Register Name: CSIC_PRS_NCSIC_RX_SIGNAL6_DLY_ADJ_REG
Bit	Read/Write	Default/Hex	Description
31:29	/	/	/
28:24	R/W	0x0	D3_dly 32 Step for adjust, 1 step = 0.2 ns
23:21	/	/	/
20:16	R/W	0x0	D2_dly 32 Step for adjust, 1 step = 0.2 ns
15:13	/	/	/
12:8	R/W	0x0	D1_dly 32 Step for adjust, 1 step = 0.2 ns
7:5	/	/	/
4:0	R/W	0x0	D0_dly 32 Step for adjust, 1 step = 0.2 ns

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7.1.8 CSIC DMA Register Description

7.1.8.1 0x0000 CSIC DMA Enable Register (Default Value:0x7000_0000)

Offset:0x0000			Register Name: CSIC_DMA_EN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	VER_EN
30	R/W	0x1	VFLIP_BUF_ADDR_CFG_MODE Vflip buffer address set by software or calculated by hardware 0: Hardware 1: Software
29	R/W	0x1	BUF_LENGTH_CFG_MODE Buffer length set by software or calculated by hardware 0: Hardware 1: Software
28	R/W	0x1	FLIP_SIZE_CFG_MODE FLIP SIZE set by software or calculated by hardware 0: Hardware 1: Software
27:8	/	/	/
7	R/W	0x0	BUF_ADDR_MODE 0: Buffer Address Register Mode 1: Buffer Address FIFO Mode
6	R/W	0x0	VI_TO_CNT_EN Enable Video Input Timeout counter, add 1 when there is no effective video input in a 12M clock, clear to 0 when detecting effective video input. 0: Disable 1: Enable
5	R/W	0x0	FRAME_CNT_EN When BK_TOP_EN is enabled, setting 1 to this bit indicates the Frame counter starts to add. 0: Disable 1: Enable
4	R/W	0x0	DMA_EN When BK_TOP_EN is enabled, setting 1 to this bit indicates the module works in DMA mode. 0: Disable 1: Enable
3	/	/	/
2	R/W	0x0	CLK_CNT_SPL Sampling time for clk counter per frame 0: Sampling clock counter every frame done 1: Sampling clock counter every vsync

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Offset:0x0000			Register Name: CSIC_DMA_EN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	CLK_CNT_EN clk count per frame enable
0	R/W	0x0	BK_TOP_EN 0: Disable 1: Enable

7.1.8.2 0x0004 CSIC DMA Configuration Register (Default Value:0x0000_0000)

Offset: 0x0004			Register Name: CSIC_DMA_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	R/W	0x0	PAD_VAL Padding value when OUTPUT_FMT is prgb888 0x00–0xff
23:22	/	/	/
21	R/W	0x0	YUV 10-bit input cut to 8-bit 0: Disable 1: Enable
20	R/W	0x0	YUV 10-bit store configuration 0: YUV 10-bit stored in low 10-bit of a 16-bit word 1: YUV 10-bit stored in high 10-bit of a 16-bit word
19:16	R/W	0x0	OUTPUT_FMT Output data format When the input format is set to RAW stream 0000: field-raw-8 0001: field-raw-10 0010: field-raw-12 0011: reserved 0100: field-rgb565 0101: field-rgb888 0110: field-prgb888 0111: reserved 1000: frame-raw-8 1001: frame-raw-10 1010: frame-raw-12 1011: reserved 1100: frame-rgb565 1101: frame-rgb888 1110: frame-prgb888 1111: reserved When the input format is set to YUV422

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Offset: 0x0004			Register Name: CSIC_DMA_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			0000: field planar YCbCr 422 0001: field planar YCbCr 420 0010: frame planar YCbCr 420 0011: frame planar YCbCr 422 0100: field planar YCbCr 422 UV combined (UV sequence) 0101: field planar YCbCr 420 UV combined (UV sequence) 0110: frame planar YCbCr 420 UV combined (UV sequence) 0111: frame planar YCbCr 422 UV combined (UV sequence) 1000: filed planar YCbCr 422 UV combined (VU sequence) 1001: field planar YCbCr 420 UV combined (VU sequence) 1010: frame planar YCbCr 420 UV combined (VU sequence) 1011: frame planar YCbCr 422 UV combined (VU sequence) 1100: reserved 1101: field YCbCr 400 1110: reserved 1111: frame YCbCr 400 When the input format is set to YUV420 0000: reserved 0001: field planar YCbCr 420 0010: frame planar YCbCr 420 0011: reserved 0100: reserved 0101: field planar YCbCr 420 UV combined (UV sequence) 0110: frame planar YCbCr 420 UV combined (UV sequence) 0111~1000: reserved 1001: field planar YCbCr 420 UV combined (VU sequence) 1010: frame planar YCbCr 420 UV combined (VU sequence) 1011~1100: reserved 1101: field YCbCr 400 1110: reserved 1111: frame YCbCr 400
15:14	/	/	/
13	R/W	0x0	VFLIP_EN Vertical flip enable When enabled, the received data will be arranged in vertical flip. 0: Disable 1: Enable
12	R/W	0x0	HFLIP_EN Horizontal flip enable When enabled, the received data will be arranged in horizontal flip. 0: Disable

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Offset: 0x0004			Register Name: CSIC_DMA_CFG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: Enable
11:10	R/W	0x0	FIELD_SEL Field selection 00: Capturing with field 0 01: Capturing with field 1 10: Capturing with either field 11: Reserved
9:6	R/W	0x0	FPS_DS Fps down sample 0: no down sample 1: 1/2 fps, only receives the first frame every 2 frames 2: 1/3 fps, only receives the first frame every 3 frames 3: 1/4 fps, only receives the first frame every 4 frames 4: 1/5 fps, only receives the first frame every 4 frames …… 15: 1/16 fps, only receives the first frame every 16 frames
5:2	/	/	/
1:0	R/W	0x0	MIN_SDR_WR_SIZE Minimum size of SDRAM block write 00: 256 bytes (if hflip is enabled, always select 256 bytes) 01: 512 bytes 10: 1K bytes 11: 2K bytes

7.1.8.3 0x0010 CSIC DMA Horizontal Size Register (Default Value:0x0500_0000)

Offset: 0x0010			Register Name: CSIC_DMA_HSIZE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x500	HOR_LEN When BK_TOP_EN is enabled, DMA_EN is enabled, these bits indicate Horizontal pixel unit length. Valid pixel of a line in DMA mode.
15:13	/	/	/
12:0	R/W	0x0	HOR_START Horizontal pixel unit start. Pixel is valid from this pixel.

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7.1.8.4 0x0014 CSIC DMA Vertical Size Register (Default Value:0x02D0_0000)

Offset: 0x0014			Register Name: CSIC_DMA_VSIZE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x2D0	VER_LEN When BK_TOP_EN is enabled, DMA_EN is enabled, these bits indicate Valid line number of a frame in DMA mode.
15:13	/	/	/
12:0	R/W	0x0	VER_START Vertical line start Data is valid from this line.

7.1.8.5 0x0020 CSIC DMA FIFO 0 Output Buffer-A Address Register (Default Value:0x0000_0000)

Offset: 0x0020			Register Name: CSIC_DMA_F0_BUFA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	F0_BUFA When BK_TOP_EN is enabled, FBC_EN is enabled, DMA_EN is disabled, these bits indicate output address of overhead data in FBC mode. When BK_TOP_EN is enabled, FBC_EN is disabled, DMA_EN is enabled, LBC_EN is disabled, these bits indicate FIFO 0 output buffer-A address in DMA mode. When BK_TOP_EN is enabled, FBC_EN is disabled, DMA_EN is enabled, LBC_EN is enabled, these bits indicate the output buffer address in LBC mode.

7.1.8.6 0x0024 CSIC DMA FIFO 0 Output Buffer-A Address Result Register (Default Value:0x0000_0000)

Offset: 0x0024			Register Name: CSIC_DMA_F0_BUFA_RESULT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	RO	0x0	F0_BUFA_RESULT Indicate the final F0_BUFA address used for DMA or FBC after software configuration or hardware calculation from Buffer-A address register or buffer address fifo. Only used for debug.

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7.1.8.7 0x0028 CSIC DMA FIFO 1 Output Buffer-A Address Register (Default Value:0x0000_0000)

Offset: 0x0028			Register Name: CSIC_DMA_F1_BUFA_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	F1_BUFA When BK_TOP_EN is enabled, FBC_EN is enabled, DMA_EN is disabled, these bits indicate the output address of compressed data in FBC mode. When BK_TOP_EN is enabled, FBC_EN is disabled, DMA_EN is enabled, these bits indicate the FIFO 1 output buffer-A address in DMA mode.

7.1.8.8 0x002C CSIC DMA FIFO 1 Output Buffer-A Address Result Register (Default Value:0x0000_0000)

Offset: 0x002C			Register Name: CSIC_DMA_F1_BUFA_RESULT_REG
Bit	Read/Write	Default/Hex	Description
31:0	RO	0x0	F1_BUFA_RESULT Indicate the final F1_BUFA address used for DMA or FBC after software configuration or hardware calculation from Buffer-A address register or buffer address fifo. Only used for debug.

7.1.8.9 0x0030 CSIC DMA FIFO 2 Output Buffer-A Address Register (Default Value:0x0000_0000)

Offset: 0x0030			Register Name: CSIC_DMA_F2_BUFA_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	F2_BUFA FIFO 2 output buffer-A address.

7.1.8.10 0x0034 CSIC DMA FIFO 2 Output Buffer-A Address Result Register (Default Value:0x0000_0000)

Offset: 0x0034			Register Name: CSIC_DMA_F2_BUFA_RESULT_REG
Bit	Read/Write	Default/Hex	Description
31:0	RO	0x0	F2_BUFA_RESULT Indicate the final F2_BUFA address used for DMA or FBC after software configuration or hardware calculation from Buffer-A address register or buffer address fifo. Only used for debug.

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7.1.8.11 0x0038 CSIC DMA Buffer Length Register (Default Value:0x0280_0500)

Offset: 0x0038			Register Name: CSIC_DMA_BUF_LEN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:16	R/W	0x280	BUF_LEN_C DMA_MODE: Buffer length of chroma C in a line. Unit is byte. LBC_MODE: Buffer length Stride of luminance Y in ONLY Y line. Unit is byte. Only Readable when BUF_LENGTH_CFG_MODE is set 0.
15:14	/	/	/
13:0	R/W	0x500	BUF_LEN DMA_MODE:Buffer length of luminance Y in a line. Unit is byte. LBC_MODE: Buffer length Stride of luminance Y and chroma C in YC line. Unit is byte. Only Readable when BUF_LENGTH_CFG_MODE is set 0.

7.1.8.12 0x003C CSIC DMA Flip Size Register (Default Value:0x02D0_0500)

Offset: 0x003C			Register Name: CSIC_DMA_FLIP_SIZE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x2d0	VER_LEN Vertical line number when in VFLIP mode. Unit is line. Only Readable when FLIP_SIZE_CFG_MODE is set to 0.
15:14	/	/	/
13:0	R/W	0x500	VALID_LEN Valid components of a line when in HFLIP mode. Unit is pixel component. Only Readable when FLIP_SIZE_CFG_MODE is set to 0.

7.1.8.13 0x0040 CSIC DMA Video Input Timeout Threshold0 Register (Default Value:0x0000_0000)

Offset: 0x0040			Register Name: CSIC_DMA_VI_TO_TH0_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	Video Input Timeout Threshold0 Set VIDEO_INPUT_TO_INT_PD when VI Counter reaches TH0 after VI_TO_CNT_EN is set, the Time Unit is a 12M clock period.

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7.1.8.14 0x0044 CSIC DMA Video Input Timeout Threshold1 Register(Default Value:0x0000_0000)

Offset: 0x0044			Register Name: CSIC_DMA_VI_TO_TH1_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	Video Input Timeout Threshold1 Set VIDEO_INPUT_TO_INT_PD when VI Counter reaches TH1 after getting the first frame has been input, the Time Unit is a 12M clock period.

7.1.8.15 0x0048 CSIC DMA Video Input Timeout Counter Value Register (Default Value:0x0000_0000)

Offset: 0x0048			Register Name: CSIC_DMA_VI_TO_CNT_VAL_REG
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	Video Input Timeout Counter Value Indicate the current value of Video Input Timeout Counter

7.1.8.16 0x004C CSIC DMA Capture Status Register (Default Value:0x0000_0000)

Offset: 0x004C			Register Name: CSIC_DMA_CAP_STA_REG
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2	R	0x0	FIELD_STA The status of the received field 0: Field 0 1: Field 1
1	R	0x0	VCAP_STA Video capture in progress Indicates the CSI is capturing video image data (multiple frames). The bit is set at the start of the first frame after enabling video capture. When software disables video capture, it clears itself after the last pixel of the current frame is captured.
0	R	0x0	SCAP_STA Still capture in progress Indicates the CSI is capturing still image data (single frame). The bit is set at the start of the first frame after enabling still frame capture. It clears itself after the last pixel of the first frame is captured. For CCIR656 interface, if the output format is frame planar YCbCr 420 mode, the frame end means the field2 end, the other frame end means filed end.

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7.1.8.17 0x0050 CSIC DMA Interrupt Enable Register (Default Value:0x0000_0000)

Offset: 0x0050			Register Name: CSIC_DMA_INT_EN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15	R/W	0x0	FRM_LOST_INT_EN Set an INT when frame starts with empty Buffer Address FIFO, only use in BUF Address FIFO MODE.
14	R/W	0x0	STORED_FRM_CNT_INT_EN Set an INT when the value of CSIC_DMA_STORED_FRM_CNT reaches CSIC_DMA_STORED_FRM_THRESHOLD, only use in BUF Address FIFO MODE.
13	R/W	0x0	BUF_ADDR_FIFO_INT_EN Set an INT when content in BUF Address FIFO less than CSIC_DMA_BUFA_FIFO_THRESHOLD, only use in BUF Address FIFO MODE.
12	R/W	0x0	VIDEO_INPUT_TO_INT_EN Set an INT when no video input exceeds the setting threshold time
11	R/W	0x0	CLR_FRAME_CNT_INT_EN Set a INT when clear Frame cnt.
10:8	/	/	/
7	R/W	0x0	VS_INT_EN vsync flag The bit is set when vsync come. And at this time load the buffer address for the coming frame. So after this irq come, changing the buffer address could only effect next frame
6	R/W	0x0	HB_OF_INT_EN Hblank FIFO overflow The bit is set when 3 FIFOs still overflow after the hblank.
5	R/W	0x0	LC_INT_EN Line counter flag The bit is set when the specific line has been written to dram every frame. The line number is set in the line counter register.
4	R/W	0x0	FIFO2_OF_INT_EN FIFO 2 overflow The bit is set when the FIFO 2 became overflow.
3	R/W	0x0	FIFO1_OF_INT_EN FIFO 1 overflow The bit is set when the FIFO 1 became overflow.
2	R/W	0x0	FIFO0_OF_INT_EN FIFO 0 overflow The bit is set when the FIFO 0 became overflow.
1	R/W	0x0	FD_INT_EN

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Offset: 0x0050			Register Name: CSIC_DMA_INT_EN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			Frame done Indicates the CSI has finished capturing an image frame. Applies to video capture mode. The bit is set after each completed frame capturing data is written to buffer as long as video capture remains enabled.
0	R/W	0x0	CD_INT_EN Capture done Indicates the CSI has completed capturing the image data. For still capture, the bit is set when one frame data has been written to buffer. For video capture, the bit is set when the last frame has been written to buffer after video capture has been disabled. For CCIR656 interface, if the output format is frame planar YCbCr 420 mode, the frame end means the field2 end, the other frame end means field end.

7.1.8.18 0x0054 CSIC DMA Interrupt Status Register (Default Value:0x0000_0000)

Offset: 0x0054			Register Name: CSIC_DMA_INT_STA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15	R/W1C	0x0	FRM_LOST_INT_PD Set an INT when frame starts with empty Buffer Address FIFO, only use in BUF Address FIFO MODE.
14	R/W1C	0x0	STORED_FRM_CNT_INT_PD Set an INT when the value of CSIC_DMA_STORED_FRM_CNT reaches CSIC_DMA_STORED_FRM_THRESHOLD, only use in BUF Address FIFO MODE.
13	R/W1C	0x0	BUF_ADDR_FIFO_INT_PD Set an INT when content in BUF Address FIFO less than CSIC_DMA_BUFA_FIFO_THRESHOLD, only use in BUF Address FIFO MODE.
12	R/W1C	0x0	VIDEO_INPUT_TO_INT_PD Set an INT Pending when no video input exceeds the setting threshold time.
11	R/W1C	0x0	CLR_FRAME_CNT_INT Set a INT when clear Frame cnt.
10:8	/	/	/
7	R/W1C	0x0	VS_PD vsync flag
6	R/W1C	0x0	LI_OF_PD

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Offset: 0x0054			Register Name: CSIC_DMA_INT_STA_REG
Bit	Read/Write	Default/Hex	Description
			Line information FIFO (16 lines) overflow
5	R/W1C	0x0	LC_PD Line counter flag
4	R/W1C	0x0	FIFO2_OF_PD FIFO 2 overflow
3	R/W1C	0x0	FIFO1_OF_PD FIFO 1 overflow
2	R/W1C	0x0	FIFO0_OF_PD FIFO 0 overflow
1	R/W1C	0x0	FD_PD Frame done
0	R/W1C	0x0	CD_PD Capture done

7.1.8.19 0x0058 CSIC DMA Line Counter Register (Default Value:0x0000_0000)

Offset: 0x0058			Register Name: CSIC_DMA_LINE_CNT_REG
Bit	Read/Write	Default/Hex	Description
31:13	/	/	/
12:0	R/W	0x0	LINE_CNT_NUM The LINE_CNT_NUM value is set by user,when internal line counter reach the set value, the LC_PD will be set.

7.1.8.20 0x005C CSIC DMA Frame Counter Register (Default Value:0x0001_0000)

Offset: 0x005C			Register Name: CSIC_DMA_FRM_CNT_REG
Bit	Read/Write	Default/Hex	Description
31	R/W1C	0x0	FRM_CNT_CLR When the bit set to 1, Frame cnt is cleared to 0.
30:16	R/W	0x1	PCLK_DMA_CLR_DISTANCE Frame cnt clear cycle $N*T_{SYNC}$
15:0	R	0x0	FRM_CNT Counter value of frame. When frame done comes, the internal counter value add 1, and when the reg full, it is cleared to 0 . When parser sent a sync signal, it is cleared to 0.

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7.1.8.21 0x0060 CSIC DMA Frame Clock Counter Register (Default Value:0x0000_0000)

Offset: 0x0060			Register Name: CSIC_DMA_FRM_CLK_CNT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:0	R	0x0	FRM_CLK_CNT Counter value between every frame. For instant hardware frame rate statics. The internal counter is added by one every 12 MHz clock cycle. When frame done or vsync comes, the internal counter value is sampled to FRM_CLK_CNT, and cleared to 0.

7.1.8.22 0x0064 CSIC DMA Accumulated and Internal Clock Counter Register (Default Value:0x0000_0000)

Offset: 0x0064			Register Name: CSIC_DMA_ACC_ITNL_CLK_CNT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	R/WC	0x0	ACC_CLK_CNT The accumulated value of FRM_CLK_CNT for software frame rate statics. Every interrupt of frame is done, the software checks this accumulated value and clears it to 0. If the ACC_CLK_CNT is larger than 1, the software has lost frame. When frame done or vsync comes, ACC_CLK_CNT = ACC_CLK_CNT + 1, and cleared to 0 when writing this register.
23:0	R	0x0	ITNL_CLK_CNT The instant value of internal frame clock counter. When frame done interrupt comes, the software can query this counter for judging whether it is the time for updating the double buffer address registers.

7.1.8.23 0x0068 CSIC DMA FIFO Statistic Register (Default Value:0x0000_0000)

Offset: 0x0068			Register Name: CSIC_DMA_FIFO_STAT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:16	R	0x0	Line Index Indicates the line index in current vsync.
15:13	/	/	/
12:0	R	0x0	FIFO_FRM_MAX Indicates the maximum depth of FIFO being occupied for whole frame. Update at every vsync or framedone.

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7.1.8.24 0x006C CSIC DMA FIFO Threshold Register (Default Value:0x0000_0400)

Offset: 0x006C			Register Name: CSIC_DMA_FIFO_THRS_REG
Bit	Read/Write	Default/Hex	Description
31:12	/	/	/
11:0	R/W	0x400	FIFO_THRS When FIFO occupied memory exceed the threshold, dram frequency can not change.

7.1.8.25 0x0070 CSIC DMA PCLK Statistic Register (Default Value:0x0000_7FFF)

Offset: 0x0070			Register Name: CSIC_DMA_PCLK_STAT_REG
Bit	Read/Write	Default/Hex	Description
31	/	/	/
30:16	R	0x0	PCLK_CNT_LINE_MAX Indicates maximum pixel clock counter value for each line. Update at every vsync or framedone.
15	/	/	/
14:0	R	0x7FFF	PCLK_CNT_LINE_MIN Indicates minimum pixel clock counter value for each line. Update at every vsync or framedone.

7.1.8.26 0x0080 CSIC DMA BUF Address FIFO0 Entry Register (Default Value:0x0000_0000)

Offset: 0x0080			Register Name: CSIC_DMA_BUF_ADDR_FIFO0_ENTRY_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	CSIC_DMA_BUF_ADDR_FIFO0_ENTRY FIFO Entry of Buffer Address FIFO0 for input frames to be stored, only used in Buffer Addr FIFO Mode

7.1.8.27 0x0084 CSIC DMA BUF Address FIFO1 Entry Register (Default Value:0x0000_0000)

Offset: 0x0084			Register Name: CSIC_DMA_BUF_ADDR_FIFO1_ENTRY_REG
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	CSIC_DMA_BUF_ADDR_FIFO1_ENTRY FIFO Entry of Buffer Address FIFO1 for input frames to be stored, only used in Buffer Addr FIFO Mode.

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7.1.8.28 0x0088 CSIC DMA BUF Address FIFO2 Entry Register (Default Value:0x0000_0000)

Offset: 0x0088			Register Name: CSIC_DMA_BUF_ADDR_FIFO2_ENTRY_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	CSIC_DMA_BUF_ADDR_FIFO2_ENTRY FIFO Entry of Buffer Address FIFO2 for input frames to be stored, only used in Buffer Addr FIFO Mode.

7.1.8.29 0x008C CSIC DMA BUF Threshold Register (Default Value:0x0020_0000)

Offset: 0x008C			Register Name: CSIC_DMA_BUF_TH_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:21	/	/	/
21:16	R/W	0x20	CSIC_DMA_STORED_FRM_THRESHOLD when stored frame counter value reaches the threshold , counter is cleared to 0 , only used in Buffer Addr FIFO Mode.
15:6	/	/	/
5:0	R/W	0x0	CSIC_DMA_BUF_ADDR_FIFO_THRESHOLD when content in Buffer Address FIFO less than the threshold, an interrupt is set, only used in Buffer Addr FIFO Mode.

7.1.8.30 0x0090 CSIC DMA BUF Address FIFO Content Register (Default Value:0x0000_0000)

Offset: 0x0090			Register Name: CSIC_DMA_BUF_ADDR_FIFO_CON_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21:16	RO	0x0	CSIC_DMA_BUF_ADDR_FIFO2_CONTENT FIFO Content of address buffered in Buffer Address FIFO2, only used in Buffer Addr FIFO Mode.
15:14	/	/	/
13:8	RO	0x0	CSIC_DMA_BUF_ADDR_FIFO1_CONTENT FIFO Content of address buffered in Buffer Address FIFO1, only used in Buffer Addr FIFO Mode.
7:6	/	/	/
5:0	RO	0x0	CSIC_DMA_BUF_ADDR_FIFO0_CONTENT FIFO Content of address buffered in Buffer Address FIFO0, only used in Buffer Addr FIFO Mode.

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7.1.8.31 0x0094 CSIC DMA Stored Frame Counter Register (Default Value:0x0000_0000)

Offset: 0x0094			Register Name: CSIC_DMA_STORED_FRM_CNT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	RO	0x0	CSIC_DMA_STORED_FRM_CNT Indicates value of stored frames counter. When the counter value reaches CSIC_DMA_STORED_FRM_THRESHOLD, the counter is cleared to 0. Only used in Buffer Addr FIFO Mode.

7.1.8.32 0x01F4 CSIC DMA Feature List Register(Default Value:0x0000_0000)

Offset: 0x01F4			Register Name: CSIC_FEATURE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R	0x0	DMA0_EMBEDDED_LBC 0: No Embedded LBC 1: Embedded LBC
0	R	0x0	DMA0_EMBEDDED_FBC 0: No Embedded DMA 1: Embedded FBC

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8 Memory

8.1 SDRAM Controller (DRAMC)

The DRAMC is embedded with 64 MB DDR2 or 128 MB DDR3.

The DRAMC has the following features:

- Embedded with 64 MB DDR2 (Only for R528-S2)
- Embedded with 128 MB DDR3 (Only for R528-S3)
- Supports clock frequency up to 533 MHz for DDR2
- Supports clock frequency up to 800 MHz for DDR3

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8.2 SD/MMC Host Controller (SMHC)

8.2.1 Overview

The SMHC controls the read/write operations on the secure digital (SD) cards, multimedia cards (MMC), and various extended devices that is based on the secure digital input/output (SDIO) protocol. The processor provides three SMHC interfaces for controlling the SD cards, MMCs, and SDIO devices.

The SMHC has the following features:

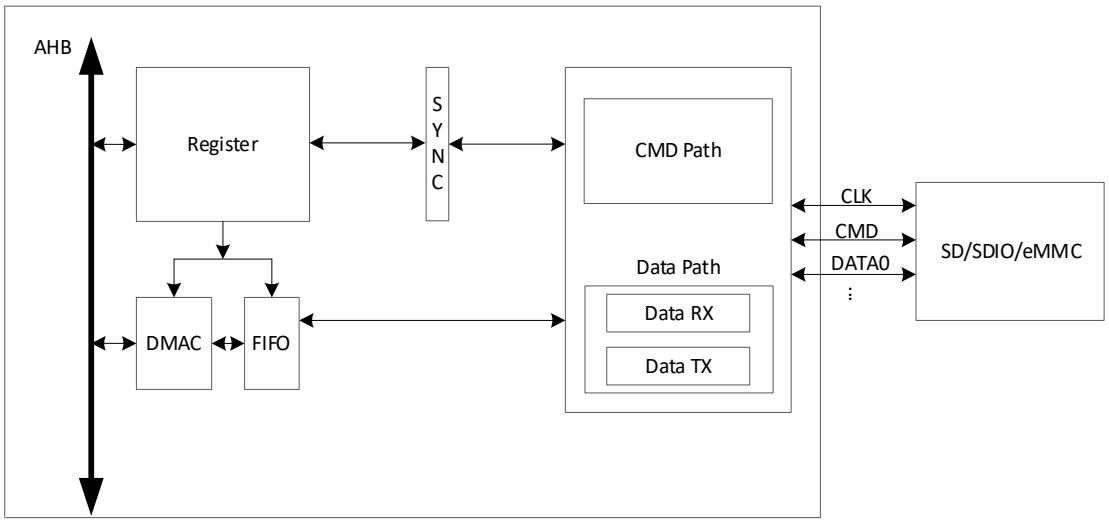
- Supports Command Completion signals and interrupts to host processor, and Command Completion signal disable feature
- The SMHC0 controls the devices that comply with the Secure Digital Memory (SD mem-version 3.0)
- The SMHC1 controls the device that complies with the protocol Secure Digital I/O (SDIO-version 3.0)
- The SMHC2 controls the device that complies with the Multimedia Card (eMMC-version 5.0)
- Maximum performance:
  - SDR mode: 150 MHz@1.8 V IO pad
  - DDR mode: 50 MHz@1.8 V IO pad
  - DDR mode: 50 MHz@3.3 V IO pad
- Supports 1-bit or 4-bit data width
- Hardware CRC generation and error detection
- Programmable baud rate
- Supports SDIO interrupt in 1-bit and 4-bit modes
- Block size of 1 to 65535 bytes
- Descriptor-based internal DMA controller
- Internal 1 KB RXFIFO and 1 KB TXFIFO

8.2.2 Block Diagram

The following figure shows a block diagram of the SMHC.

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Figure 8-1 SMHC Block Diagram



SMHC contains the following sub-blocks:

Table 8-1 SMHC Sub-blocks

Sub-block	Description
Register	Used to configure the control signal for reading or writing the SD/SDIO/eMMC.
DMAC	The DMA controller that controls the data transfer between the memory and SMHC.
FIFO	A buffer for the data stream between the memory and the SMHC asynchronous clock domain.
SYNC	Synchronizes the signals from the AHB clock domain to the SMHC clock domain.
CMD Path	Sends commands to or receives commands from the SD/SDIO/eMMC.
Data Path	Consists of Data TX and Data RX sub-modules. The Data TX sends data blocks and the CRC codes to the SD/SDIO/eMMC. The Data RX receives data blocks and the CRC codes from the SD/SDIO/eMMC.

8.2.3 Functional Description

8.2.3.1 External Signals

The following table describes the external signals of SMHC.

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Table 8-2 SMHC External Signals

Port Name	Type	Description
SDC0-CMD	I/O, OD	Command Signal for SD Card
SDC0-CLK	O	Clock for SD Card
SDC0-D[3:0]	I/O	Data Input and Output for SD Card
SDC0-RST	O	Reset for SD Card
SDC1-CMD	I/O, OD	Command Signal for SDIO Wi-Fi
SDC1-CLK	O	Clock for SDIO Wi-Fi
SDC1-D[3:0]	I/O	Data Input and Output for SDIO Wi-Fi
SDC2-CMD	I/O, OD	Command Signal for eMMC
SDC2-CLK	O	Clock for eMMC
SDC2-D[3:0]	I/O	Data Input and Output for eMMC

8.2.3.2 Clock Sources

The SMHC0/1 has 4 different clock sources. The SMHC2 has 5 different clock sources. You can select one of them as the SMHC clock source. The following table describes the clock sources of the SMHC.

For clock setting, configurations, and gating information, refer to section 3.3 "CCU".

Table 8-3 SMHC0/1 Clock Sources

Clock Sources	Description
HOSC	24 MHz Crystal
PLL_PERI(1X)	Peripheral Clock, the default value is 600 MHz
PLL_PERI(2X)	Peripheral Clock, the default value is 1.2 GHz
PLL_AUDIO1(DIV2)	Audio clock, the default value is 1536 MHz

Table 8-4 SMHC2 Clock Sources

Clock Sources	Description
HOSC	24 MHz Crystal
PLL_PERI(1X)	Peripheral Clock, the default value is 600 MHz
PLL_PERI(2X)	Peripheral Clock, the default value is 1.2 GHz
PLL_PERI(800M)	Peripheral Clock, the default value is 800 MHz
PLL_AUDIO1(DIV2)	Audio clock, the default value is 1536 MHz

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8.2.3.3 Timing Diagram

Refer to the following relative specifications:

- Physical Layer Specification Ver3.00 Final
- SDIO Specification Ver2.00
- Multimedia Cards (MMC – version 4.2)
- JEDEC Standard – JESD84-44, Embedded Multimedia Card (eMMC) Card Product Standard
- JEDEC Standard – JESD84-B45, Embedded Multimedia Card (eMMC) Electrical Standard (4.5 Device)
- JEDEC Standard – JESD84-B50, Embedded Multimedia Card (eMMC) Electrical Standard (5.0)

8.2.3.4 Data Path

The SMHC and SD/SDIO/eMMC contains the following interface buses: CLK, CMD, and DATA 1/4. During one clock cycle, the SMHC can transmit one bit command with one or two bits data in 1-ch DATA mode, or four or eight bits data in 4-ch DATA mode. The CMD is a bidirection channel for initializing the SD/SDIO/eMMC and transmitting commands. It can work in both the open-drain mode and push-pull mode. The DATA is also a bidirection channel. It works in the push-pull mode.

Reading Data from the SD/SDIO/eMMC

The register configures the signals for the read operation, and synchronize the signals to the SMHC clock domain. Then the Data RX reads data from the SD/SDIO/eMMC via the CLK/CMD/DATA interface buses and writes the data in the FIFO. After that, the DMAC transfers the data from the FIFO to the memory.

Writing Data to the SD/SDIO/eMMC

The register configures the signals for the write operation, and synchronize the signals to the SMHC clock domain. Then the DMAC reads data from the memory and writes the data to the FIFO. After that, the Data TX reads the data from the FIFO and writes the data to the SD/SDIO/eMMC via the CLK/CMD/DATA interface buses.

8.2.3.5 Package Format

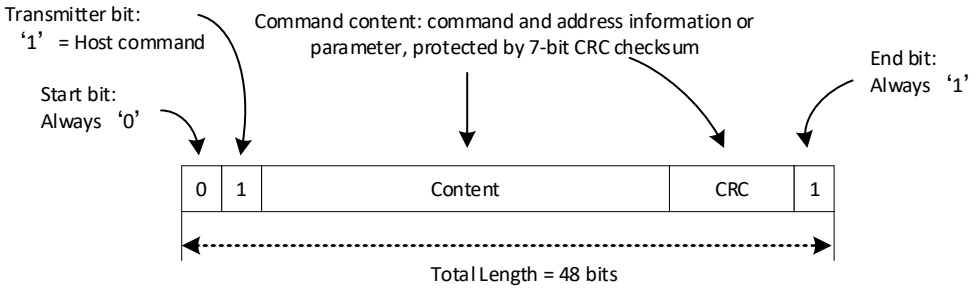
Data transfer over the SD/eMMC bus is based on command and data bitstreams that are initiated by a start bit and terminated by a stop bit. There are three types of SD/eMMC packets: command token, response token, and data packet.

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Command Tokens

The command token starts an operation. A command is sent from the host to a device. It is transferred serially on the CMD line. Command tokens have the following coding scheme:

Figure 8-2 Command Token Format



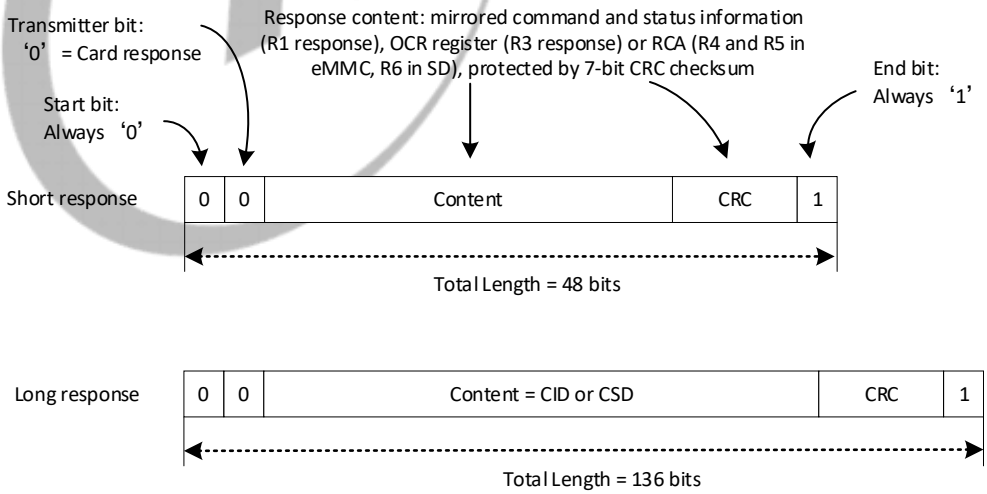
Each command token has 48 bits, preceded by a start bit ('0') and succeeded by an end bit ('1'). To detect transmission errors, each token is protected by CRC bits.

Response Tokens

After receiving a command, the card returns a 48-bit or 136-bit response based on the command type.

A response token is sent from the device to the host as an answer to a previously received command. It is transferred serially on the CMD line.

Figure 8-3 Response Token Format



Data Packets

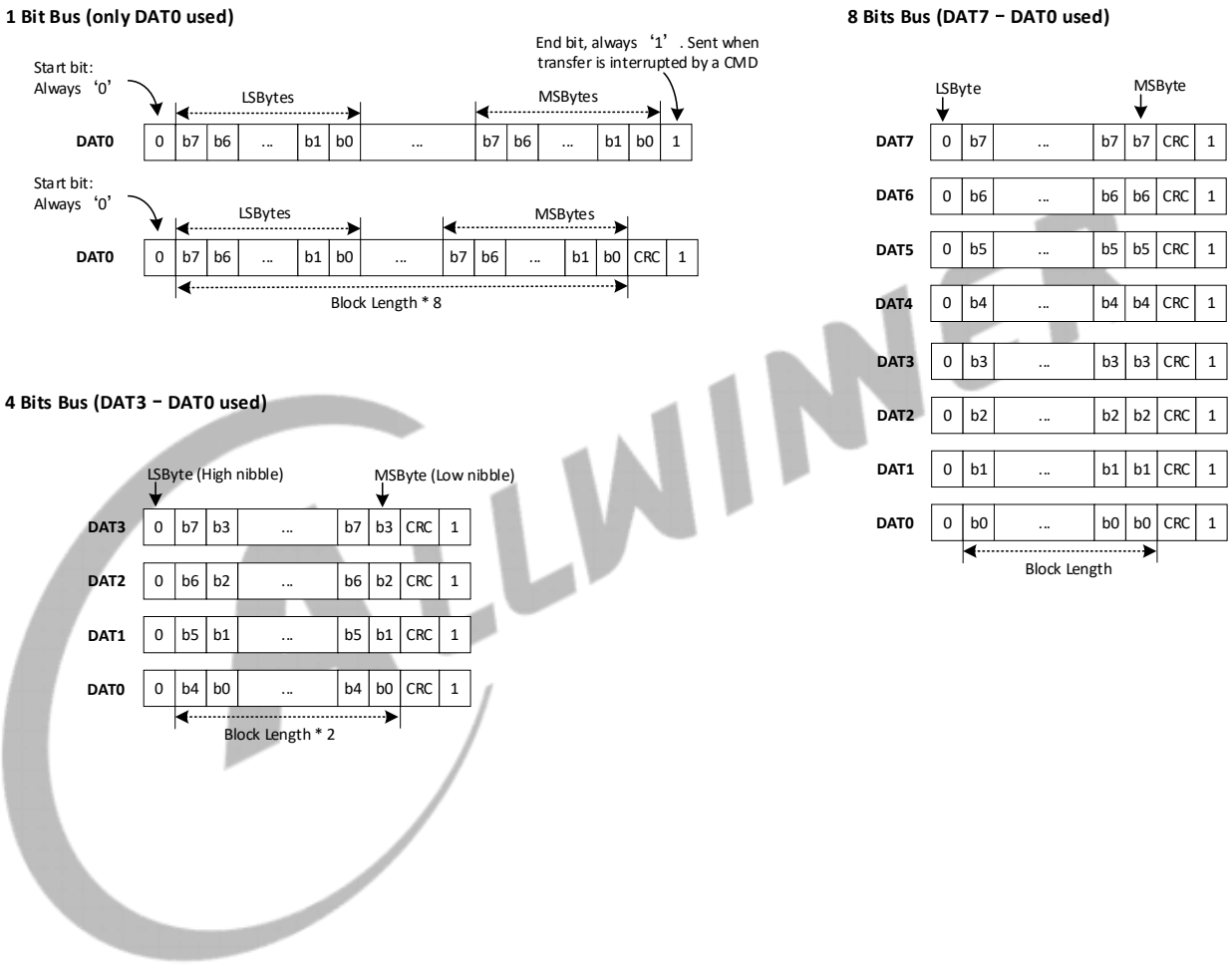
Data can be transferred from the device to the host or vice versa. Data are transferred via the data lines.

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NOTE

R528 does not support the bus width of 8 bits.

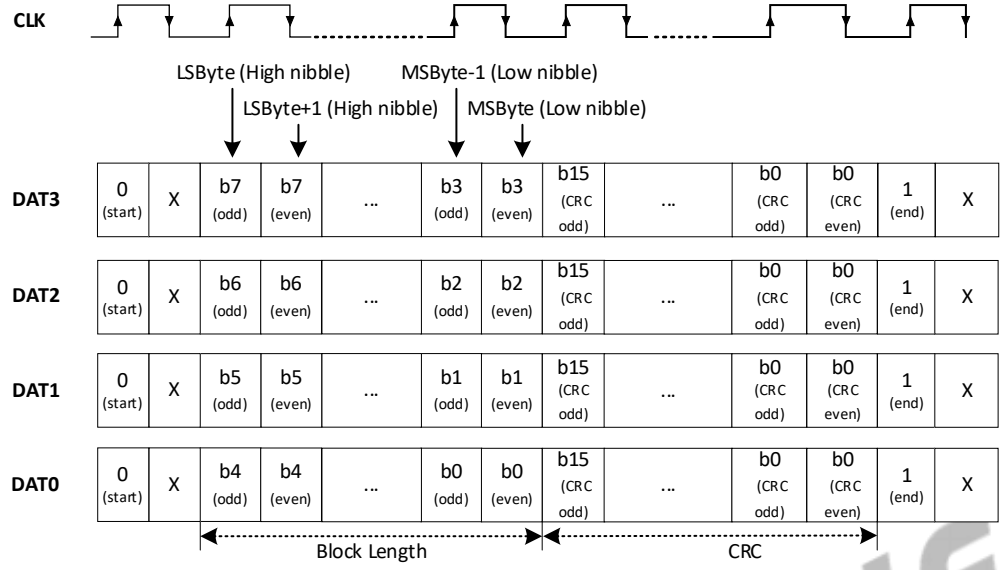
Figure 8-4 Data Packet Format for SDR



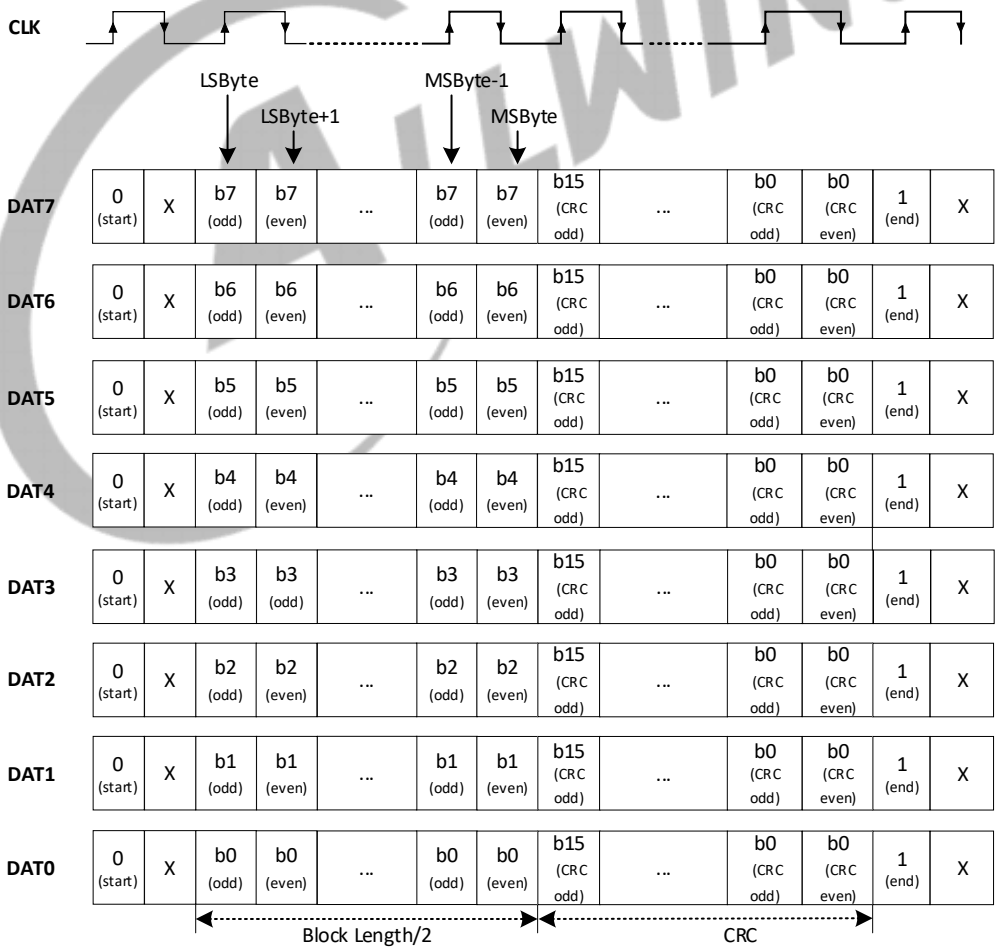
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Figure 8-5 Data Packet Format for DDR

4 Bits Bus DDR (DAT3 – DAT0 used)



8 Bits Bus DDR (DAT7 – DAT0 used)



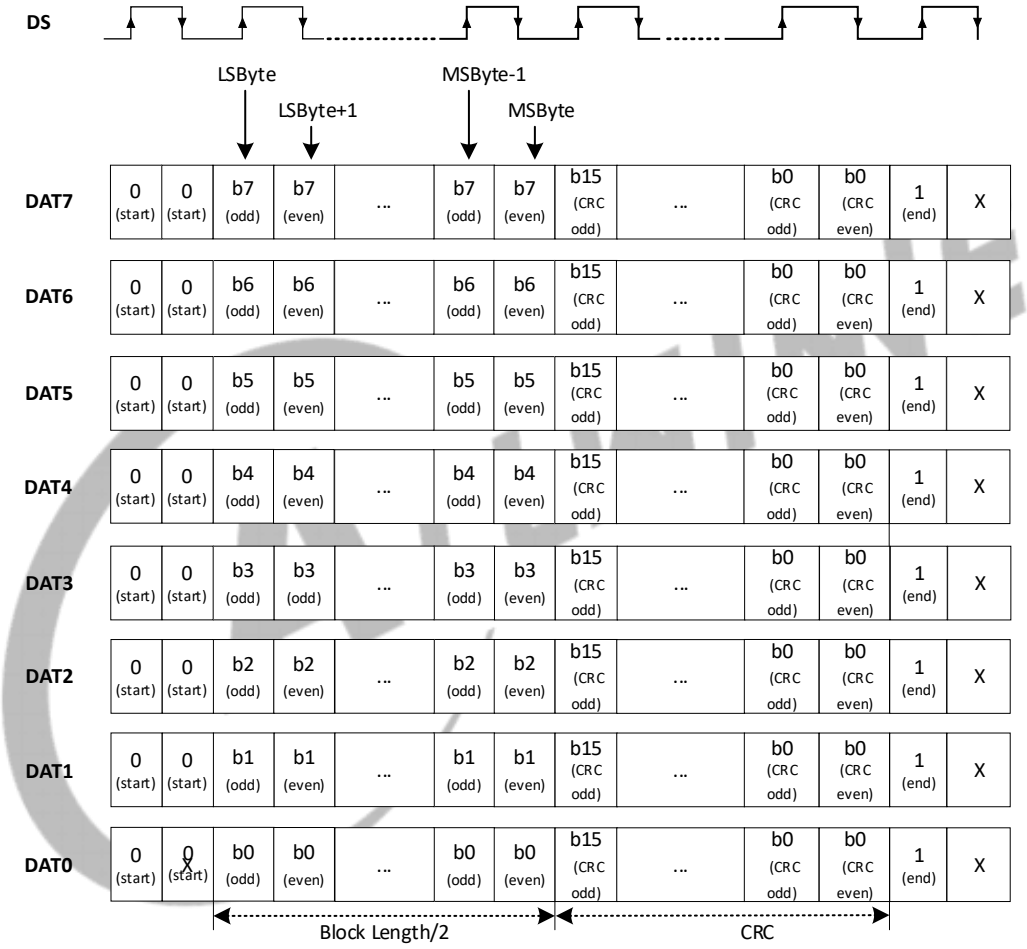
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NOTE

- Bytes data are not interleaved but CRCs are interleaved.
- Start and end bits are only valid on the rising edge (“X” indicates “undefined”).

Figure 8-6 Data Packet Format for DDR in HS400 Mode

8 Bits Bus DDR for HS400 Output (DAT7 – DAT0 used)



NOTE

- Bytes data are not interleaved but CRCs are interleaved.
- Start bits are valid when Data Strobe is High and Low.
- End bits are only valid when Data Strobe is High (“X” indicates “undefined”).

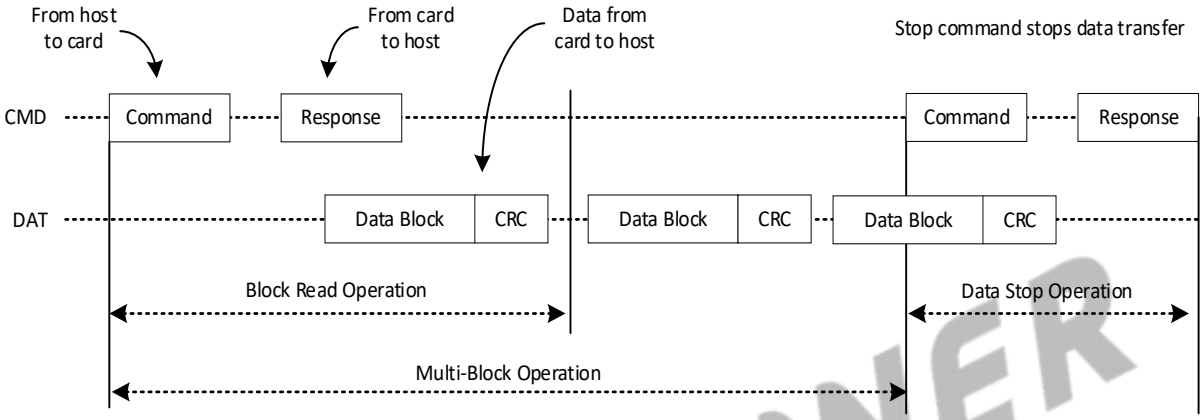
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8.2.3.6 Data Transfer

Data transfers to or from the SD/eMMC card are done in blocks. Single and multiple block operations are widely used during data transfer.

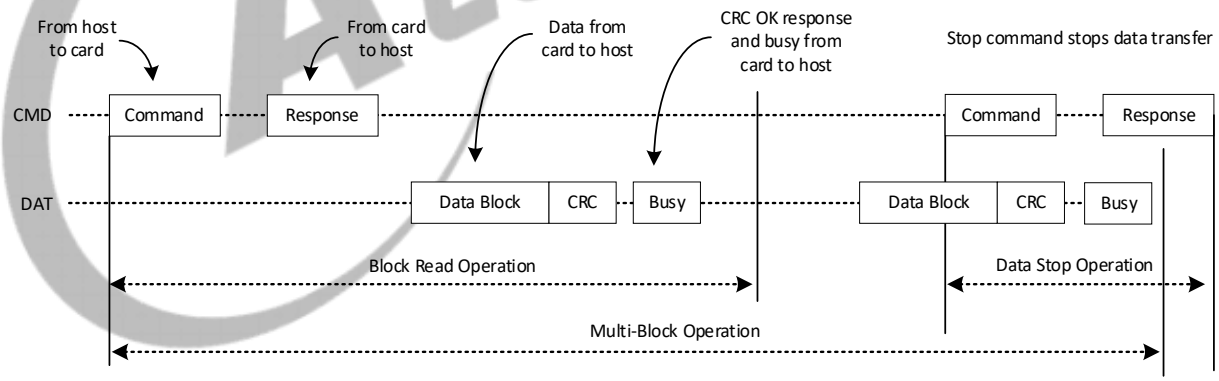
The following figure shows the single-block and multi-block read operation.

Figure 8-7 Single-Block and Multi-Block Read Operation



The following figure shows the single-block and multi-block write operation.

Figure 8-8 Single-Block and Multi-Block Read Operation



8.2.3.7 Bus Speed Modes

The following table shows the bus speed modes supported by SD 3.0.

Table 8-5 Speed Modes Supported by SD 3.0

Mode	I/O Voltage	Bus Width	Frequency	Throughput
SDR104	1.8 V	1, 4 bits	0 to 208 MHz	0 to 104 MB/s

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Mode	I/O Voltage	Bus Width	Frequency	Throughput
SDR50	1.8 V	1, 4 bits	0 to 100MHz	0 to 50 MB/s
DDR50	1.8 V	1, 4 bits	0 to 50 MHz	0 to 50 MB/s
SDR25	1.8 V	1, 4 bits	0 to 50 MHz	0 to 25 MB/s
SDR12	1.8 V	1, 4 bits	0 to 25 MHz	0 to 12 MB/s
High Speed Mode (HS)	3.3 V	1, 4 bits	0 to 50 MHz	0 to 25 MB/s
Default Speed Mode (DS)	3.3 V	1, 4 bits	0 to 25 MHz	0 to 12 MB/s

The following table shows the bus speed modes supported by eMMC 5.0.

Table 8-6 Speed Modes Supported by eMMC 5.0

Mode	Data Rate	I/O Voltage	Bus Width	Frequency	Throughput
Backwards Compatibility with legacy MMC card	Single	3.3 V/1.8 V	1, 4 bits	0 to 26 MHz	0 to 26 MB/s
High Speed SDR	Single	3.3 V/1.8 V	1, 4 bits	0 to 52 MHz	0 to 52 MB/s
High Speed DDR	Dual	3.3 V/1.8 V	4 bits	0 to 52 MHz	0 to 104 MB/s
HS200	Single	1.8 V	4 bits	0 to 200 MHz	0 to 200 MB/s

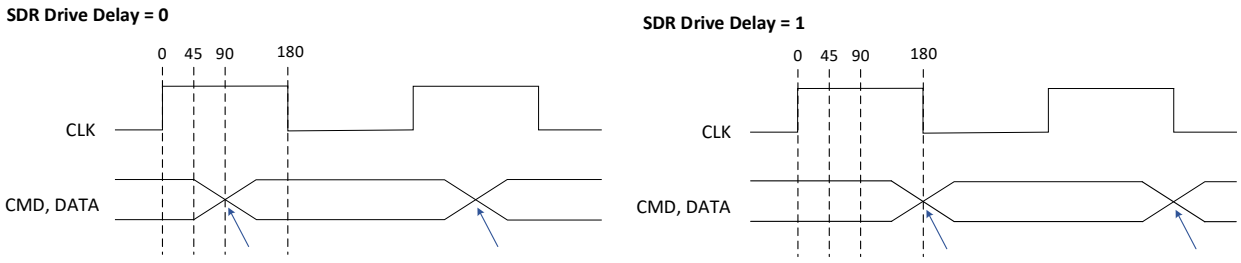
8.2.3.8 Phase Offset of the Command and Data

You can configure the phase offset of the command and data by the SMHC_DRV_DL register.

SDR Mode

The following figure shows the phase offset of SDR command and data.

Figure 8-9 Phase Offset of Command and Data in SDR Mode



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Table 8-7 Phase Offset of Command and Data in SDR Mode

Drive Delay	Command	Data
0	The command is updated in 90° clock position	The data is updated in 90° clock position
1	The command is updated in 180° clock position	The data is updated in 180° clock position

DDR4 Mode

The following figure shows the phase offset of DDR4 command and data.

Figure 8-10 Phase Offset of Command and Data in DDR4 Mode (SMHC_NTSR[31] = 0)

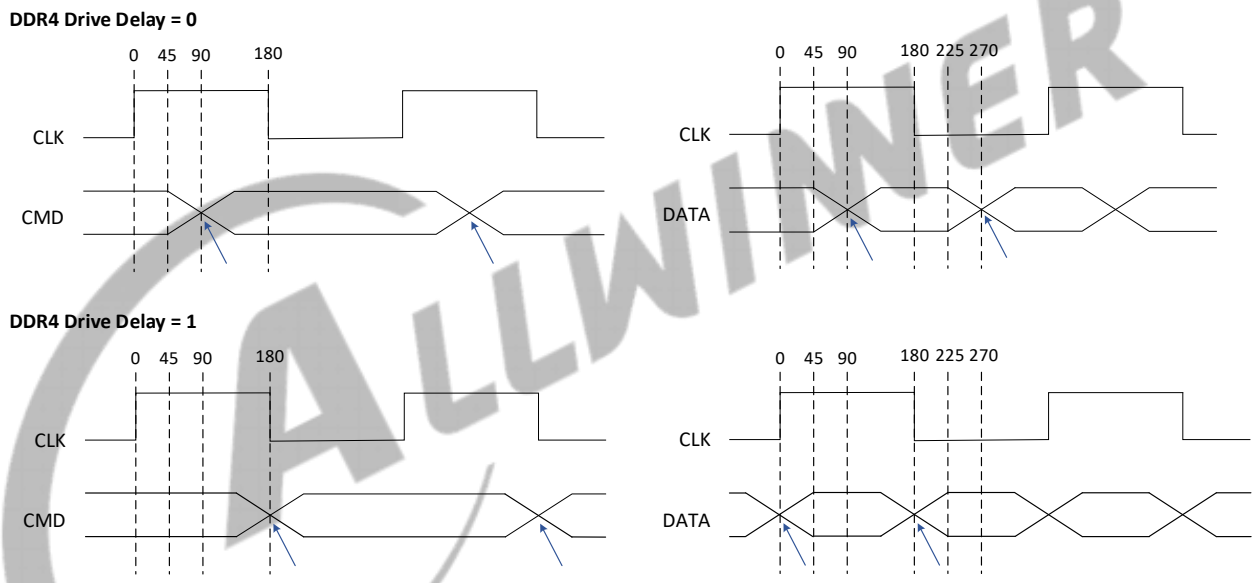


Figure 8-11 Phase Offset of Command and Data in DDR4 Mode

Drive Delay	Command	Data
0	The command is updated in 90° clock position	The data is updated in 90° clock position
1	The command is updated in 180° clock position	The data is updated in 0° or 180° clock position

DDR4 (2x) Mode

The following figure shows the phase offset of DDR4 (2x mode) command and data.

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Figure 8-12 Phase Offset of Command and Data in DDR4 (2x Mode) (SMHC_NTSR[31] = 1)

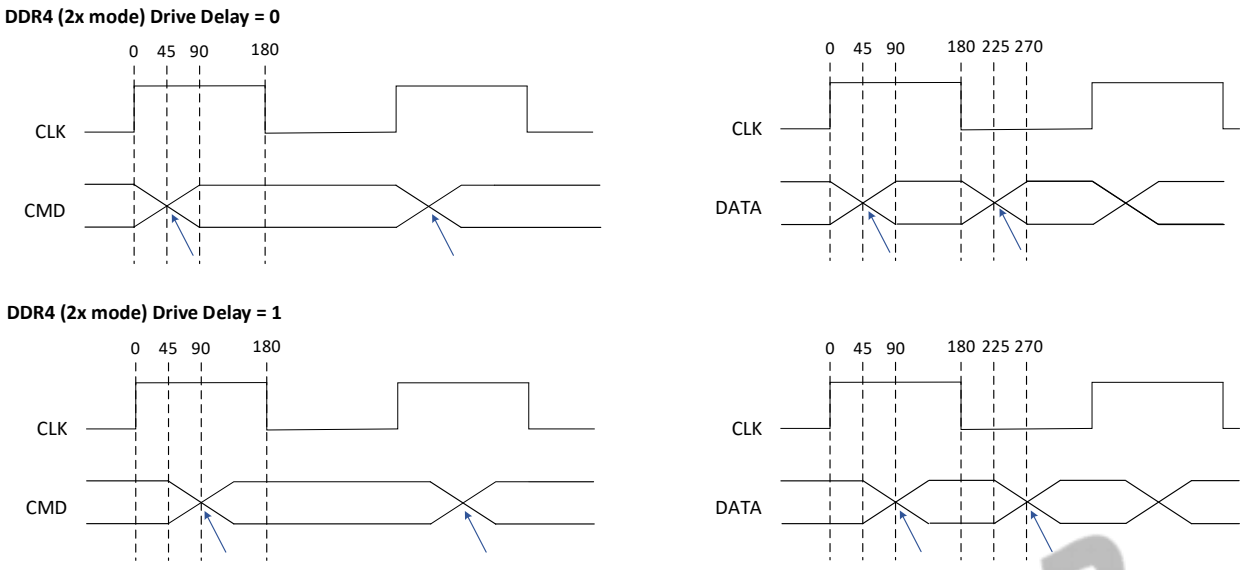


Table 8-8 Phase Offset of Command and Data in DDR4 (2x) Mode

Drive Delay	Command	Data
0	The command is updated in 45° clock position	The data is updated in 45° clock position
1	The command is updated in 90° clock position	The data is updated in 90° clock position

8.2.3.9 Internal DMA Controller Description

The SMHC has an internal DMA controller (IDMAC) to transfer data between the host memory and SMHC port. With a descriptor, the IDMAC can efficiently move data from the source to destination by automatically loading the next DMA transfer arguments, which needs less CPU intervention. Before transferring data in the IDMAC, the host driver should construct a descriptor list, configure arguments of every DMA transfer, and then launch the descriptor and start the DMA.

The IDMAC has an interrupt controller. When enabled, it generates an interrupt to the HOST CPU in situations such as data transmission is completed or some error is happened.

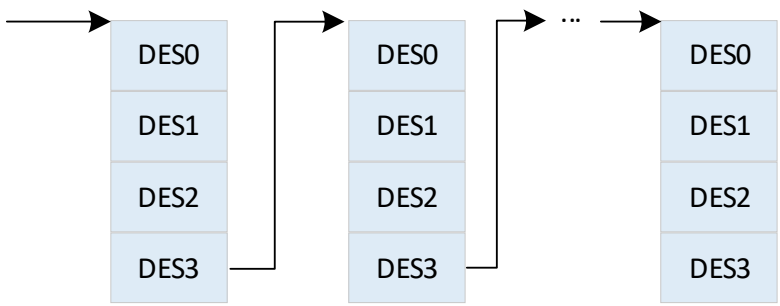
IDMAC Descriptor Structure

The IDMAC uses a descriptor with a chain structure, and each descriptor points to a unique buffer and the next descriptor.

The following figure shows the internal formats of a descriptor.

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Figure 8-13 IDMAC Descriptor Structure Diagram



This figure illustrates the internal formats of a descriptor. The descriptor address must be aligned to the bus width used for 32-bit buses. Each descriptor contains 16 bytes of control and status information.

DES0 corresponds to the [31:0] bits, DES1 corresponds to the [63:32] bits, DES2 corresponds to the [95:64] bits, and DES3 corresponds the [127:96] bits in a descriptor.

The following table shows the bit definition of DES0.

Table 8-9 DES0 Definition

Bits	Name	Description
31	HOLD	DES_OWN_FLAG When set, this bit indicates that the descriptor is owned by the IDMAC. When this bit is reset, it indicates that the descriptor is owned by the host. This bit is cleared when the transfer is over.
30	ERROR	ERR_FLAG When some errors happen in transfer, this bit will be set to 1.
29:5	/	/
4	Chain Flag	CHAIN_MOD When set to 1, this bit indicates that the second address in the descriptor is the next descriptor address. It must be set to 1.
3	First DES Flag	FIRST_FLAG When set to 1, this bit indicates that this descriptor contains the first buffer of data. It must be set to 1 in the first DES.
2	Last DES Flag	LAST_FLAG When set to 1, this bit indicates that the buffers this descriptor points to are the last data buffer.
1	Disable Interrupt on completion	CUR_TXRX_OVER_INT_DIS When set to 1, this bit will prevent the setting of the TX/RX interrupt bit of the IDMAC status register for data that ends in the buffer the descriptor points to.
0	/	/

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The following table shows the bit definition of DES1.

Table 8-10 DES1 Definition

Bits	Name	Description
31:13	/	/
12:0	Buffer size	BUFF_SIZE The bits indicate the data buffer byte size, which must be a multiple of 4 bytes. If this field is 0, the DMA ignores this buffer and proceeds to the next descriptor.

The following table shows the bit definition of DES2.

Table 8-11 DES2 Definition

Bits	Name	Descriptor
31:0	Buffer address pointer	BUFF_ADDR The bits indicate the physical address of the data buffer. It is a word address.

The following table shows the bit definition of DES3.

Table 8-12 DES3 Definition

Bits	Name	Descriptor
31:0	Next descriptor address	NEXT_DESP_ADDR The bits indicate the pointer to the physical memory where the next descriptor is present. It is a word address.

8.2.3.10 Calibrating the Delay Chain

There are two delay chains in SMHC: data strobe delay chain and sample delay chain.

Data strobe delay chain: used to generate delay to make proper timing between Data Strobe and data signals.

Sample delay chain: used to generate delay to make proper timing between the internal card clock signal and data signals.

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Each delay chain is made up with 64 delay cells. The delay time of one delay cell can be estimated through delay chain calibration.

Follow the steps below to calibrate the delay chain:

Step 1 Enable SMHC. In order to calibrate the delay chain by the operation registers in SMHC, the SMHC must be enabled through SMHC Bus Gating Reset Register and SMHCx Clock Register.

Step 2 Configure a proper clock for SMHC. The delay chain calibration is based on the clock for SMHC from Clock Control Unit (CCU). The delay chain calibration is an internal function in SMHC and needs no devices. So it is unnecessary to open the clock signal for devices. The recommended clock frequency is 200 MHz.

Step 3 Set proper initial delay value. Writing 0xA0 to **delay control register** enables **Delay Software Enable** (bit[7]) and sets initial delay value 0x20 to **Delay chain** (bit[5:0]). Then write 0x0 to **delay control register** to clear the value.

Step 4 Write 0x8000 to **delay control register** to start calibrating the delay chain.

Step 5 Wait until the flag (bit14 in **delay control register**) of calibration done is set. The number of delay cells is shown at bit[13:8] in **delay control register**. The delay time generated by these delay cells is equal to the cycle of the SMHC clock nearly. This value is the result of calibration.

Step 6 Calculate the delay time of one delay cell according to the cycle of the SMHC clock and the result of calibration.

8.2.4 Programming Guidelines

8.2.4.1 Initializing SMHC

Before data and commands are exchanged between a card and the SMHC, the SMHC needs to be initialized. Follow the steps below to initialize the SMHC:

Step 1 Configure the corresponding GPIO register as an SMHC by Port Controller module; reset clock by writing 1 to **SMHC_BGR_REG**[SMHCx_RST], and open clock gating by writing 1 to **SMHC_BGR_REG**[SMHCx_GATING]; select clock sources and set the division factor by configuring the **SMHCx_CLK_REG** (x = 0, 1) register.

Step 2 Configure **SMHC_CTRL** to reset the FIFO and controller, and enable the global interrupt; configure **SMHC_INTMASK** to 0xFFCE to enable normal interrupts and error abnormal interrupts, and then register the interrupt function.

Step 3 Configure **SMHC_CLKDIV** to open clock for devices; configure **SMHC_CMD** as the change clock command (for example 0x80202000); send the update clock command to deliver clocks to devices.

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Step 4 Configure SMHC_CMD as a normal command. Configure SMHC_CMDARG to set command parameters. Configure SMHC_CMD to set parameters like whether to send the response, the response type, and the response length and then send the commands. According to the initialization process in the protocol, you can finish SMHC initialization by sending the corresponding command one by one.

8.2.4.2 Writing a Single Data Block

To write a single data block, follow the steps below:

Step 1 Write 0x1 to SMHC_CTRL[DMA_RST] to reset the internal DMA controller; write 0x82 to SMHC_IDMAC to enable the IDMAC interrupt and configure AHB master burst transfers; configure SMHC_IDIE to enable the transfer interrupt, receive interrupt, and abnormal interrupt.

Step 2 Configure SMHC_FIFOTH to determine the burst size and TX/RX trigger level. For example, if SMHC_FIFOTH is configured as 0x300F00F0, it indicates the burst size is 16, TX_TL is 15, and RX_TL is 240. Configure SMHC_DLBA to determine the start address of the DMA descriptor.

Step 3 To write one block data to sector1, configure SMHC_BYTCNT[BYTE_CNT] to 0x200 and configure the descriptor according to the data size; set the data sector address of CMD24 (Single Data Block Write) to 0x1, write 0x80002758 to SMHC_CMD, and send CMD24 command to write data to the device.

Step 4 Check whether SMHC_RINTSTS[CC] is 1. If yes, the command is sent successfully; otherwise, continue to wait until timeout, and then exit the process.

Step 5 Check whether SMHC_IDST[TX_INT] is 1. If yes, the data transfer for writing DMA is completed. Write 0x337 to SMHC_IDST to clear the interrupt flag. Otherwise, continue to wait until timeout, and then exit the process.

Step 6 Check whether SMHC_RINTSTS[DTC] is 1. If yes, the data transfer and CMD24 writing operations are completed. Otherwise, abnormity exists. Read SMHC_RINTSTS and SMHC_STATUS to query the existing abnormity.

Step 7 Send CMD13 command to query whether the device writing operation is completed and returns to the idle status. For example, device RCA is 0x1234, first set SMHC_CMDARG to 0x12340000, write 0x8000014D to SMHC_CMD, go to step4 to ensure command transfer completed, and then check whether the highest bit of SMHC_RESP0 (CMD13 response) is 1. If yes, the device is in the idle status, and the next command can be sent. Otherwise, the device is in the busy status. Continue to send CMD13 to wait for the device to enter the idle status until timeout.

8.2.4.3 Reading a Single Data Block

To read a single data block, follow the steps below:

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Step 1 Write 0x1 to SMHC_CTRL[DMA_RST] to reset the internal DMA controller; write 0x82 to SMHC_IDMAC to enable the IDMAC interrupt and configure AHB master burst transfers; configure SMHC_IDIE to enable the transfer interrupt, receive interrupt, and abnormal interrupt.

Step 2 Configure SMHC_FIFOTH to determine the burst size and TX/RX trigger level. For example, if SMHC_FIFOTH is configured as 0x300F00F0, it indicates the burst size is 16, TX_TL is 15, and RX_TL is 240. Configure SMHC_DLBA to determine the start address of the DMA descriptor.

Step 3 To read one block data from sector1, configure SMHC_BYTCNT[BYTE_CNT] to 0x200 and configure the descriptor according to the data size; set the data sector address of CMD17 command (Single Data Block Read) to 0x1, write 0x80002351 to SMHC_CMD, and send CMD17 command to read data from the device to DRAM/SRAM.

Step 4 Check whether SMHC_RINTSTS[CC] is 1. If yes, the command is sent successfully; otherwise, continue to wait until timeout, and then exit the process.

Step 5 Check whether SMHC_IDST[RX_INT] is 1. If yes, the data transfer for writing DMA is completed. Write 0x337 to SMHC_IDST to clear the interrupt flag. Otherwise, continue to wait until timeout, and then exit the process.

Step 6 Check whether SMHC_RINTSTS[DTC] is 1. If yes, data transfer and CMD17 reading operation are completed. Otherwise, abnormity exists. Read SMHC_RINTSTS and SMHC_STATUS to query the existing abnormity.

8.2.4.4 Writing Open-Ended Multiple Data Blocks (CMD25 + Auto CMD12)

To write open-ended multiple data blocks, follow the steps below:

Step 1 Write 0x1 to SMHC_CTRL[DMA_RST] to reset the internal DMA controller; write 0x82 to SMHC_IDMAC to enable the IDMAC interrupt and configure AHB master burst transfers; configure SMHC_IDIE to enable the transfer interrupt, receive interrupt, and abnormal interrupt.

Step 2 Configure SMHC_FIFOTH to determine the burst size and TX/RX trigger level. For example, if SMHC_FIFOTH is configured as 0x300F00F0, it indicates the burst size is 16, TX_TL is 15, and RX_TL is 240. Configure SMHC_DLBA to determine the start address of the DMA descriptor.

Step 3 To write three blocks of data to sectors begin with sector0, configure SMHC_BYTCNT[BYTE_CNT] to 0x600 and configure the descriptor according to the data size; set the data sector address of CMD25 command (Multiple Data Blocks Write) to 0x0, write 0x80003759 to SMHC_CMD, and send CMD25 command to read data from the device to DRAM/SRAM.

Step 4 Check whether SMHC_RINTSTS[CC] is 1. If yes, the command is sent successfully; otherwise, continue to wait until timeout, and then exit the process.

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Step 5 Check whether SMHC_IDST[RX_INT] is 1. If yes, the data transfer for writing DMA is completed. Write 0x337 to SMHC_IDST to clear the interrupt flag. Otherwise, continue to wait until timeout, and then exit the process.

Step 6 Check whether SMHC_RINTSTS[ACD] and SMHC_RINTSTS[DTC] are both 1. If yes, the data transfer, CMD12 transfer, and CMD25 writing operations are completed. Otherwise, abnormity exists. Read SMHC_RINTSTS and SMHC_STATUS to query the existing abnormity.

Step 7 Send CMD13 command to query whether the device writing operation is completed and returns to the idle status. For example, device RCA is 0x1234, first set SMHC_CMDARG to 0x12340000, write 0x8000014D to SMHC_CMD, go to step4 to ensure command transfer completed, and then check whether the highest bit of SMHC_RESP0 (CMD13 response) is 1. If yes, the device is in the idle status, and the next command can be sent. Otherwise, the device is in the busy status. Continue to send CMD13 to wait for the device to enter the idle status until timeout.

8.2.4.5 Reading Open-Ended Multiple Data Blocks (CMD18 + Auto CMD12)

To read open-ended multiple data blocks, follow the steps below:

Step 1 Write 0x1 to SMHC_CTRL[DMA_RST] to reset the internal DMA controller; write 0x82 to SMHC_IDMAC to enable the IDMAC interrupt and configure AHB master burst transfers; configure SMHC_IDIE to enable the transfer interrupt, receive interrupt, and abnormal interrupt.

Step 2 Configure SMHC_FIFOTH to determine the burst size and TX/RX trigger level. For example, if SMHC_FIFOTH is configured as 0x300F00F0, it indicates the burst size is 16, TX_TL is 15, and RX_TL is 240. Configure SMHC_DLBA to determine the start address of the DMA descriptor.

Step 3 To read three blocks of data from sectors begin with sector0, configure SMHC_BYTCNT[BYTE_CNT] to 0x600 and configure the descriptor according to the data size; set the data sector address of CMD18 command (Multiple Data Blocks Read) to 0x0, write 0x80003352 to SMHC_CMD, and send CMD18 command to read data to the device. When the data transfer is completed, CMD12 will be sent automatically.

Step 4 Check whether SMHC_RINTSTS[CC] is 1. If yes, the command is sent successfully; otherwise, continue to wait until timeout, and then exit the process.

Step 5 Check whether SMHC_IDST[RX_INT] is 1. If yes, the data transfer for writing DMA is completed. Write 0x337 to SMHC_IDST to clear the interrupt flag. Otherwise, continue to wait until timeout, and then exit the process.

Step 6 Check whether SMHC_RINTSTS[ACD] and SMHC_RINTSTS[DTC] are both 1. If yes, data transfer, CMD12 transfer, and CMD18 reading operation are completed. Otherwise, abnormity exists. Read SMHC_RINTSTS and SMHC_STATUS to query the existing abnormity.

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8.2.4.6 Writing Pre-Defined Multiple Data Blocks (CMD23 + CMD25)

To write pre-defined multiple data blocks, follow the steps below:

Step 1 Write 0x1 to SMHC_CTRL[DMA_RST] to reset the internal DMA controller; write 0x82 to SMHC_IDMAC to enable the IDMAC interrupt and configure AHB master burst transfers; configure SMHC_IDIE to enable the transfer interrupt, receive interrupt, and abnormal interrupt.

Step 2 Configure SMHC_FIFOTH to determine the burst size and TX/RX trigger level. For example, if SMHC_FIFOTH is configured as 0x300F00F0, it indicates the burst size is 16, TX_TL is 15, and RX_TL is 240. Configure SMHC_DLBA to determine the start address of the DMA descriptor.

Step 3 To write three blocks of data, configure SMHC_CMDARG to 0x3 to specify the number of data blocks as three. Then write 0x80000157 to SMHC_CMD to send the CMD23 command. Check whether SMHC_RINTSTS[CC] is 1. If yes, the command is sent successful; otherwise, continue to wait until timeout, and then exit the process.

Step 4 Configure SMHC_BYTCNT[BYTE_CNT] to 0x600 and configure the descriptor according to the data size; set the data sector address of CMD25 command (Multiple Data Blocks Write) to 0x0, write 0x80002759 to SMHC_CMD, and send CMD25 command to write data to the device.

Step 5 Check whether SMHC_RINTSTS[CC] is 1. If yes, the command is sent successful; otherwise, continue to wait until timeout, and then exit the process.

Step 6 Check whether SMHC_IDST[TX_INT] is 1. If yes, the data transfer for writing DMA is completed. Write 0x337 to SMHC_IDST to clear the interrupt flag. Otherwise, continue to wait until timeout, and then exit the process.

Step 7 Check whether SMHC_RINTSTS[DTC] is 1. If yes, the data transfer and CMD25 writing operations are completed. Otherwise, abnormity exists. Read SMHC_RINTSTS and SMHC_STATUS to query the existing abnormity.

Step 8 Send CMD13 command to query whether the device writing operation is completed and returns to the idle status. For example, device RCA is 0x1234, first set SMHC_CMDARG to 0x12340000, write 0x8000014D to SMHC_CMD, go to step4 to ensure command transfer completed, and then check whether the highest bit of SMHC_RESP0 (CMD13 response) is 1. If yes, the device is in the idle status, and the next command can be sent. Otherwise, the device is in the busy status. Continue to send CMD13 to wait for the device to enter the idle status until timeout.

8.2.4.7 Reading Pre-Defined Multiple Data Blocks (CMD23 + CMD18)

To read pre-defined multiple data blocks, follow the steps below:

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Step 1 Write 0x1 to SMHC_CTRL[DMA_RST] to reset the internal DMA controller; write 0x82 to SMHC_IDMAC to enable the IDMAC interrupt and configure AHB master burst transfers; configure SMHC_IDIE to enable the transfer interrupt, receive interrupt, and abnormal interrupt.

Step 2 Configure SMHC_FIFOTH to determine the burst size and TX/RX trigger level. For example, if SMHC_FIFOTH is configured as 0x300F00F0, it indicates the burst size is 16, TX_TL is 15, and RX_TL is 240. Configure SMHC_DLBA to determine the start address of the DMA descriptor.

Step 3 To read three blocks of data, configure SMHC_CMDARG to 0x3 to specify the number of data blocks as three. Then write 0x80000157 to SMHC_CMD to send the CMD23 command. Check whether SMHC_RINTSTS[CC] is 1. If yes, the command is sent successful; otherwise, continue to wait until timeout, and then exit the process.

Step 4 Configure SMHC_BYTCNT[BYTE_CNT] to 0x600 and configure the descriptor according to the data size; set the data sector address of CMD18 (Multiple Data Blocks Read) to 0x0, write 0x80002352 to SMHC_CMD, and send CMD18 command to read data from device to DRAM/SRAM.

Step 5 Check whether SMHC_RINTSTS[CC] is 1. If yes, the command is sent successful; otherwise, continue to wait until timeout, and then exit the process.

Step 6 Check whether SMHC_IDST[TX_INT] is 1. If yes, the data transfer for writing DMA is completed. Write 0x337 to SMHC_IDST to clear the interrupt flag. Otherwise, continue to wait until timeout, and then exit the process.

Step 7 Check whether SMHC_RINTSTS[DTC] is 1. If yes, the data transfer and CMD18 writing operations are completed. Otherwise, abnormity exists. Read SMHC_RINTSTS and SMHC_STATUS to query the existing abnormity.

8.2.5 Register List

Module Name	Base Address
SMHC0	0x04020000
SMHC1	0x04021000
SMHC2	0x04022000

Register Name	Offset	Description
SMHC_CTRL	0x0000	Control Register
SMHC_CLKDIV	0x0004	Clock Control Register
SMHC_TMOUT	0x0008	Time Out Register
SMHC_CTYPE	0x000C	Bus Width Register

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Register Name	Offset	Description
SMHC_BLKSIZ	0x0010	Block Size Register
SMHC_BYTCNT	0x0014	Byte Count Register
SMHC_CMD	0x0018	Command Register
SMHC_CMDARG	0x001C	Command Argument Register
SMHC_RESP0	0x0020	Response 0 Register
SMHC_RESP1	0x0024	Response 1 Register
SMHC_RESP2	0x0028	Response 2 Register
SMHC_RESP3	0x002C	Response 3 Register
SMHC_INTMASK	0x0030	Interrupt Mask Register
SMHC_MINTSTS	0x0034	Masked Interrupt Status Register
SMHC_RINTSTS	0x0038	Raw Interrupt Status Register
SMHC_STATUS	0x003C	Status Register
SMHC_FIFOTH	0x0040	FIFO Water Level Register
SMHC_FUNS	0x0044	FIFO Function Select Register
SMHC_TCBCNT	0x0048	Transferred Byte Count between Controller and Card
SMHC_TBBCNT	0x004C	Transferred Byte Count between Host Memory and Internal FIFO
SMHC_DBGC	0x0050	Current Debug Control Register
SMHC_CSDC	0x0054	CRC Status Detect Control Registers
SMHC_A12A	0x0058	Auto Command 12 Argument Register
SMHC_NTSR	0x005C	SD New Timing Set Register
SMHC_HWRST	0x0078	Hardware Reset Register
SMHC_IDMAC	0x0080	IDMAC Control Register
SMHC_DLBA	0x0084	Descriptor List Base Address Register
SMHC_IDST	0x0088	IDMAC Status Register
SMHC_IDIE	0x008C	IDMAC Interrupt Enable Register
SMHC_THLD	0x0100	Card Threshold Control Register
SMHC_SFC	0x0104	Sample FIFO Control Register
SMHC_A23A	0x0108	Auto Command 23 Argument Register
EMMC_DDR_SBIT_DET	0x010C	eMMC4.5 DDR Start Bit Detection Control Register
SMHC_EXT_CMD	0x0138	Extended Command Register
SMHC_EXT_RESP	0x013C	Extended Response Register
SMHC_DRV_DL	0x0140	Drive Delay Control Register
SMHC_SMAP_DL	0x0144	Sample Delay Control Register

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Register Name	Offset	Description
SMHC_DS_DL	0x0148	Data Strobe Delay Control Register
SMHC_HS400_DL	0x014C	HS400 Delay Control Register
SMHC_FIFO	0x0200	Read/Write FIFO

8.2.6 Register Description

8.2.6.1 0x0000 SMHC Global Control Register (Default Value: 0x0000_0100)

Offset: 0x0000			Register Name: SMHC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	FIFO_AC_MOD FIFO Access Mode 0: DMA bus 1: AHB bus
30:13	/	/	/
12	R/W	0x0	TIME_UNIT_CMD Time unit for command line The time unit is used to calculate the command line time out value defined in RTO_LMT. 0: 1 card clock period 1: 256 card clock period
11	R/W	0x0	TIME_UNIT_DAT Time unit for data line Time unit is used to calculate the data line time out value defined in DTO_LMT. 0: 1 card clock period 1: 256 card clock period
10	R/W	0x0	DDR_MOD_SEL DDR Mode Select Although the HS400 speed mode of eMMC is 8-bit DDR, this field should be cleared when HS400_MD_EN is set. 0: SDR mode 1: DDR mode
9	/	/	/

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Offset: 0x0000			Register Name: SMHC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
8	R/W	0x1	CD_DBC_ENB Card Detect (Data[3] status) Debounce Enable 0: Disable de-bounce 1: Enable de-bounce
7:6	/	/	/
5	R/W	0x0	DMA_ENB DMA Global Enable 0: Disable DMA to transfer data via AHB bus 1: Enable DMA to transfer data
4	R/W	0x0	INT_ENB Global Interrupt Enable 0: Disable interrupts 1: Enable interrupts
3	/	/	/
2	R/W	0x0	DMA_RST DMA Reset
1	R/W	0x0	FIFO_RST FIFO Reset 0: No effect 1: Reset the FIFO This bit is auto-cleared after the completion of the reset operation.
0	R/W	0x0	SOFT_RST Software Reset 0: No effect 1: Reset SD/MMC controller This bit is auto-cleared after the completion of reset operation.

8.2.6.2 0x0004 SMHC Clock Control Register (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: SMHC_CLKDIV
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	MASK_DATA0 0: Do not mask data0 when update clock 1: Mask data0 when update clock
30:18	/	/	/

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Offset: 0x0004			Register Name: SMHC_CLKDIV
Bit	**Read/Write**	**Default/Hex**	**Description**
17	R/W	0x0	CCLK_CTRL Card Clock Output Control 0: Card clock is always on 1: Turn off card clock when FSM is in IDLE state
16	R/W	0x0	CCLK_ENB Card Clock Enable 0: Card Clock is off 1: Card Clock is on
15:8	/	/	/
7:0	R/W	0x0	CCLK_DIV Card Clock Divider n: Source clock is divided by 2*n. (n = 0 to 255) When HS400_MD_EN is set, this field must be cleared.

8.2.6.3 0x0008 SMHC Timeout Register (Default Value: 0xFFFF_FF40)

Offset: 0x0008			Register Name: SMHC_TMOUT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	R/W	0xffffff	DTO_LMT Data Timeout Limit This field can set the time that the host waits for the data from the device. Ensure to communicate with the device, this field must be set to the maximum that is greater than the time N_{AC}. About the N_{AC}, the explanation is as follows: When Host read data, data transmission from the Device starts after the access time delay N_{AC} beginning from the end bit of the read command (ACMD51, CMD8, CMD17, and CMD18). When the host reads multiple block (CMD18), a next block's data transmission from the Device starts after the access time delay N_{AC} beginning from the end bit of the previous block. When the host writes data, the value is no effect.
7:0	R/W	0x40	RTO_LMT Response Timeout Limit

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8.2.6.4 0x000C SMHC Bus Width Register (Default Value: 0x0000_0000)

Offset: 0x000C			Register Name: SMHC_CTYPE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1:0	R/W	0x0	CARD_WID Card Width 00: 1-bit width 01: 4-bit width 1x: 8-bit width

8.2.6.5 0x0010 SMHC Block Size Register (Default Value: 0x0000_0200)

Offset: 0x0010			Register Name: SMHC_BLKSIZ
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0x200	BLK_SZ Block Size

8.2.6.6 0x0014 SMHC Byte Count Register (Default Value: 0x0000_0200)

Offset: 0x0014			Register Name: SMHC_BYTCNT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x200	BYTE_CNT Byte counter The number of bytes to be transferred. It must be integer multiple of Block Size (BLK_SZ) for block transfers.

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8.2.6.7 0x0018 SMHC Command Register (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: SMHC_CMD
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	CMD_LOAD Start Command This bit is automatically cleared when the current command is sent. If there is no response error happens, a command complete interrupt bit (CMD_OVER) will be set in the interrupt register. Do not write any other commands until this bit is cleared.
30:29	/	/	/
28	R/W	0x0	VOL_SW Voltage Switch 0: Normal command 1: Voltage switch command, set for CMD11 only.
27	R/W	0x0	BOOT_ABT Boot Abort Setting this bit will terminate the boot operation.
26	R/W	0x0	EXP_BOOT_ACK Expect Boot Acknowledge When the software sets this bit along in mandatory boot operation, the controller expects a boot acknowledge start pattern of 0-1-0 from the selected card.
25:24	R/W	0x0	BOOT_MOD Boot Mode 00: Normal command 01: Mandatory Boot operation 10: Alternate Boot operation 11: Reserved
23:22	/	/	/
21	R/W	0x0	PRG_CLK Change Clock 0: Normal command 1: Change Card Clock When this bit is set, the controller will change the clock domain and clock output. No commands will be sent.
20:16	/	/	/

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Offset: 0x0018			Register Name: SMHC_CMD
Bit	**Read/Write**	**Default/Hex**	**Description**
15	R/W	0x0	SEND_INIT_SEQ Send Initialization 0: Normal command sending 1: Send initialization sequence before sending this command.
14	R/W	0x0	STOP_ABT_CMD Stop Abort Command 0: Normal command sending 1: Send *Stop* or *Abort* command to stop the current data transfer in progress. (CMD12, CMD52 for writing "I/O Abort" in SDIO CCCR)
13	R/W	0x0	WAIT_PRE_OVER Wait for Data Transfer Over 0: Send command at once, does not care about data transferring. 1: Wait for data transfer completion before sending the current command.
12	R/W	0x0	STOP_CMD_FLAG Send Stop CMD Automatically (CMD12) 0: Do not send stop command at the end of the data transfer. 1: Send stop command automatically at the end of the data transfer. If set, the SMHC_RESP1 will record the response of auto CMD12.
11	R/W	0x0	TRANS_MODE Transfer Mode 0: Block data transfer command 1: Stream data transfer command
10	R/W	0x0	TRANS_DIR Transfer Direction 0: Read operation 1: Write operation
9	R/W	0x0	DATA_TRANS Data Transfer 0: Without data transfer 1: With data transfer

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Offset: 0x0018			Register Name: SMHC_CMD
Bit	**Read/Write**	**Default/Hex**	**Description**
8	R/W	0x0	CHK_RESP_CRC Check Response CRC 0: Do not check response CRC 1: Check response CRC
7	R/W	0x0	LONG_RESP Response Type 0: Short Response (48 bits) 1: Long Response (136 bits)
6	R/W	0x0	RESP_RCV Response Receive 0: Command without response 1: Command with response
5:0	R/W	0x0	CMD_IDX CMD Index Command index value

8.2.6.8 0x001C SMHC Command Argument Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: SMHC_CMDARG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	CMD_ARG Command argument

8.2.6.9 0x0020 SMHC Response 0 Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: SMHC_RESP0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	CMD_RESP0 Response 0 Bit[31:0] of response

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8.2.6.10 0x0024 SMHC Response 1 Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: SMHC_RESP1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	CMD_RESP1 Response 1 Bit[63:31] of response

8.2.6.11 0x0028 SMHC Response 2 Register (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: SMHC_RESP2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	CMD_RESP2 Response 2 Bit[95:64] of response

8.2.6.12 0x002C SMHC Response 3 Register (Default Value: 0x0000_0000)

Offset: 0x002C			Register Name: SMHC_RESP3
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	CMD_RESP3 Response 3 Bit[127:96] of response

8.2.6.13 0x0030 SMHC Interrupt Mask Register (Default Value: 0x0000_0000)

Offset: 0x0030			Register Name: SMHC_INTMASK
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	CARD_REMOVAL_INT_EN Card Removed Interrupt Enable
30	R/W	0x0	CARD_INSERT_INT_EN Card Inserted Interrupt Enable
29:17	/	/	/
16	R/W	0x0	SDIO_INT_EN SDIO Interrupt Enable

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Offset: 0x0030			Register Name: SMHC_INTMASK
Bit	**Read/Write**	**Default/Hex**	**Description**
15	R/W	0x0	DEE_INT_EN Data End-bit Error Interrupt Enable
14	R/W	0x0	ACD_INT_EN Auto Command Done Interrupt Enable
13	R/W	0x0	DSE_BC_INT_EN Data Start Error Interrupt Enable
12	R/W	0x0	CB_IW_INT_EN Command Busy and Illegal Write Interrupt Enable
11	R/W	0x0	FU_FO_INT_EN FIFO Underrun/Overflow Interrupt Enable
10	R/W	0x0	DSTO_VSD_INT_EN Data Starvation Timeout/V1.8 Switch Done Interrupt Enable
9	R/W	0x0	DTO_BDS_INT_EN Data Timeout/Boot Data Start Interrupt Enable
8	R/W	0x0	RTO_BACK_INT_EN Response Timeout/Boot ACK Received Interrupt Enable
7	R/W	0x0	DCE_INT_EN Data CRC Error Interrupt Enable
6	R/W	0x0	RCE_INT_EN Response CRC Error Interrupt Enable
5	R/W	0x0	DRR_INT_EN Data Receive Request Interrupt Enable
4	R/W	0x0	DTR_INT_EN Data Transmit Request Interrupt Enable
3	R/W	0x0	DTC_INT_EN Data Transfer Complete Interrupt Enable
2	R/W	0x0	CC_INT_EN Command Complete Interrupt Enable
1	R/W	0x0	RE_INT_EN Response Error Interrupt Enable
0	/	/	/

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8.2.6.14 0x0034 SMHC Masked Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0034			Register Name: SMHC_MINTSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R	0x0	M_CARD_REMOVAL_INT Card Removed
30	R	0x0	M_CARD_INSERT Card Inserted
29:17	/	/	/
16	R	0x0	M_SDIO_INT SDIO Interrupt
15	R	0x0	M_DEE_INT Data End-bit Error When the bit is set during receiving data, it means that the host controller does not receive the valid data end bit. When the bit is set during transmitting data, it means that the host controller does not receive the CRC status token. This is a write-1-to-clear bit.
14	R	0x0	M_ACD_INT Auto Command Done When set, it means auto-stop command (CMD12) completed.
13	R	0x0	M_DSE_BC_INT Data Start Error/Busy Clear When set during receiving data, it means that the host controller found an error start bit. When the bit is set during transmitting data, it means that the busy signal is cleared after the last block.
12	R	0x0	M_CB_IW_INT Command Busy and Illegal Write
11	R	0x0	M_FU_FO_INT FIFO Underrun/Overflow
10	R	0x0	M_DSTO_VSD_INT Data Starvation Timeout/V1.8 Switch Done
9	R	0x0	M_DTO_BDS_INT Data Timeout/Boot Data Start
8	R	0x0	M_RTO_BACK_INT Response Timeout/Boot ACK Received

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Offset: 0x0034			Register Name: SMHC_MINTSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
7	R	0x0	M_DCE_INT Data CRC Error When the bit is set during receiving data, it means that the received data have data CRC error. When the bit is set during transmitting data, it means that the received CRC status taken is negative.
6	R	0x0	M_RCE_INT Response CRC Error
5	R	0x0	M_DRR_INT Data Receive Request When set, it means that there are enough data in FIFO during receiving data.
4	R	0x0	M_DTR_INT Data Transmit Request When set, it means that there is enough space in FIFO during transmitting data.
3	R	0x0	M_DTC_INT Data Transfer Complete
2	R	0x0	M_CC_INT Command Complete
1	R	0x0	M_RE_INT Response Error When set, Transmit Bit error or End Bit error or CMD Index error may occurs.
0	/	/	/

8.2.6.15 0x0038 SMHC Raw Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0038			Register Name: SMHC_RINTSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W1C	0x0	CARD_REMOVAL Card Removed Write 1 to clear this bit.

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Offset: 0x0038			Register Name: SMHC_RINTSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
30	R/W1C	0x0	CARD_INSERT Card Inserted Write 1 to clear this bit.
29:17	/	/	/
16	R/W1C	0x0	SDIOI_INT SDIO Interrupt Write 1 to clear this bit.
15	R/W1C	0x0	DEE Data End-bit Error When the bit is set during receiving data, it means that the host controller does not receive the valid data end bit. When the bit is set during transmitting data, it means that the host controller does not receive the CRC status token. Write 1 to clear this bit.
14	R/W1C	0x0	ACD Auto Command Done When set, it means that the auto-stop command (CMD12) is completed. Write 1 to clear this bit.
13	R/W1C	0x0	DSE_BC Data Start Error/Busy Clear When the bit is set during receiving data, it means that the host controller found an error start bit. When the bit is set during transmitting data, it means that the busy signal is cleared after the last block. Write 1 to clear this bit.
12	R/W1C	0x0	CB_IW Command Busy and Illegal Write Write 1 to clear this bit.
11	R/W1C	0x0	FU_FO FIFO Underrun/Overflow Write 1 to clear this bit.
10	R/W1C	0x0	DSTO_VSD Data Starvation Timeout/V1.8 Switch Done Write 1 to clear this bit.

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Offset: 0x0038			Register Name: SMHC_RINTSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
9	R/W1C	0x0	DTO_BDS Data Timeout/Boot Data Start When the bit is set during receiving data, it means that some of the channel of DATA[3:0] lack of the start bit. Write 1 to clear this bit.
8	R/W1C	0x0	RTO_BACK Response Timeout/Boot ACK Received Write 1 to clear this bit.
7	R/W1C	0x0	DCE Data CRC Error When the bit is set during receiving data, it means that the received data have data CRC error. When the bit is set during transmitting data, it means that the received CRC status taken is negative. Write 1 to clear this bit.
6	R/W1C	0x0	RCE Response CRC Error Write 1 to clear this bit.
5	R/W1C	0x0	DRR Data Receive Request When set, it means that there are enough data in FIFO during receiving data. Write 1 to clear this bit.
4	R/W1C	0x0	DTR Data Transmit Request When set, it means that there is enough space in FIFO during transmitting data. Write 1 to clear this bit.
3	R/W1C	0x0	DTC Data Transfer Complete When set, it means that the current command completes even through error occurs. Write 1 to clear this bit.

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Offset: 0x0038			Register Name: SMHC_RINTSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W1C	0x0	CC Command Complete When set, it means that the current command completes even through error occurs. Write 1 to clear this bit.
1	R/W1C	0x0	RE Response Error When set, it means that the transmit bit error, end bit error, or CMD index error may occur. Write 1 to clear this bit.
0	/	/	/

8.2.6.16 0x003C SMHC Status Register (Default Value: 0x0000_0006)

Offset: 0x003C			Register Name: SMHC_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R	0x0	DMA_REQ DMA Request DMA request signal state
30:26	/	/	/
25:17	R	0x0	FIFO_LEVEL FIFO Level Number of filled locations in FIFO
16:11	R	0x0	RESP_IDX Response Index Index of previous response, including any auto-stop sent by the controller.
10	R	0x0	FSM_BUSY Data FSM Busy Data transmit or receive state-machine is busy.
9	R	0x0	CARD_BUSY Card Data Busy Inverted version of DATA[0] 0: Card data is not busy. 1: Card data is busy.

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Offset: 0x003C			Register Name: SMHC_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
8	R	0x0	CARD_PRESENT Data[3] Status The level of DATA[3], checks whether the card is present. 0: The card is not present. 1: The card is present.
7:4	R	0x0	FSM_STA Command FSM States 0000: Idle 0001: Send init sequence 0010: TX CMD start bit 0011: TX CMD TX bit 0100: TX CMD index + argument 0101: TX CMD CRC7 0110: TX CMD end bit 0111: RX response start bit 1000: RX response IRQ response 1001: RX response TX bit 1010: RX response CMD index 1011: RX response data 1100: RX response CRC7 1101: RX response end bit 1110: CMD path wait NCC 1111: Wait; CMD-to-response turn around
3	R	0x0	FIFO_FULL FIFO Full 0: FIFO is not full 1: FIFO is full
2	R	0x1	FIFO_EMPTY FIFO Empty 0: FIFO is not empty 1: FIFO is empty
1	R	0x1	FIFO_TX_LEVEL FIFO TX Water Level Flag 0: FIFO does not reach the transmit trigger level 1: FIFO reaches the transmit trigger level

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Offset: 0x003C			Register Name: SMHC_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R	0x0	FIFO_RX_LEVEL FIFO RX Water Level Flag 0: FIFO does not reach the receive trigger level. 1: FIFO reaches the receive trigger level.

8.2.6.17 0x0040 SMHC FIFO Water Level Register (Default Value: 0x000F_0000)

Offset: 0x0040			Register Name: SMHC_FIFOTH
Bit	**Read/Write**	**Default/Hex**	**Description**
31	/	/	/
30:28	R/W	0x0	BSIZE_OF_TRANS Burst Size of Multiple Transaction 000: 1 transfers 001: 4 010: 8 011: 16 Others: Reserved It should be programmed the same as the DMA controller multiple transaction size. The units for the transfer are the DWORD. A single transfer would be signaled based on this value. The value should be sub-multiple of (RX_TL + 1) and (FIFO_DEPTH - TX_TL) Recommended: FIFO_DEPTH = 256, FIFO_SIZE = 256 * 32 = 1K MSize = 16, TX_TL = 240, RX_TL = 15
27:24	/	/	/

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Offset: 0x0040			Register Name: SMHC_FIFOTH
Bit	**Read/Write**	**Default/Hex**	**Description**
23:16	R/W	0xF	RX_TL RX Trigger Level 0x0 to 0xFE: The RX trigger level is from 0 to 254. 0xFF: Reserved Indicates the FIFO threshold for the FIFO request host to receive data from the FIFO. When the FIFO data level is greater than this value, the DMA request is raised if DMA enabled, or the RX interrupt bit is set if interrupt enabled. At the end of the packet, if the last transfer is less than this level, the value is ignored and the relative request will be raised as usual. Recommended: 15 (means greater than 15)
15:8	/	/	/
7:0	R/W	0x0	TX_TL TX Trigger Level 0x1 to 0xFF: The TX trigger level is 1 to 255. 0x0: No trigger Indicates the FIFO threshold for the FIFO request host to transmit data to the FIFO. When the FIFO data level is less than or equal to this value, the DMA TX request is raised if DMA enabled, or TX request interrupt bit is set if interrupt enabled. At the end of the packet, if the last transfer is less than this level, the value is ignored and the relative request will be raised as usual. Recommended: 240 (means less than or equal to 240)

8.2.6.18 0x0044 SMHC Function Select Register (Default Value: 0x0000_0000)

Offset: 0x0044			Register Name: SMHC_FUNS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/

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Offset: 0x0044			Register Name: SMHC_FUNS
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	ABT_RDATA Abort Read Data 0: Ignored 1: After the suspend command is issued during the read-transfer, the software polls card to find when the suspend happens. Once the suspend occurs, the software sets the bit to reset the data state-machine, which is waiting for the next block of data. This bit is used in the SDIO card suspends sequence and is auto-cleared once the controller resets to the idle state.
1	R/W	0x0	READ_WAIT Read Wait 0: Clear SDIO read wait 1: Assert SDIO read wait
0	R/W	0x0	HOST_SEND_MMC_IRQRESQ Host Send MMC IRQ Response 0: Ignored 1: Send auto IRQ response When the host is waiting for the MMC card interrupt response, setting this bit will make the controller cancel the waiting state and return to the idle state, at which time, the controller will receive the IRQ response sent by itself. This bit is auto-cleared after the response is sent.

8.2.6.19 0x0048 SMHC Transferred Byte Count Register 0 (Default Value: 0x0000_0000)

Offset: 0x0048			Register Name: SMHC_TBC0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	TBC0 Transferred Count 0 The number of bytes transferred between the card and internal FIFO. The register should be accessed in full to avoid read-coherency problems and read only after the data transfer completes.

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8.2.6.20 0x004C SMHC Transferred Byte Count Register 1 (Default Value: 0x0000_0000)

Offset: 0x004C			Register Name: SMHC_TBC1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	TBC1 Transferred Count 1 The number of bytes transferred between the Host/DMA memory and internal FIFO. The register should be accessed in full to avoid read-coherency problems and read only after the data transfer completes.

8.2.6.21 0x0054 SMHC CRC Status Detect Control Register (Default Value: 0x0000_0003)

Offset: 0x0054			Register Name: SMHC_CSDC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3:0	R/W	0x3	CRC_DET_PARA 110: HS400 speed mode 011: Other speed mode Others: Reserved

8.2.6.22 0x0058 SMHC Auto Command 12 Argument Register (Default Value: 0x0000_FFFF)

Offset: 0x0058			Register Name: SMHC_A12A
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0xffff	SD_A12A Auto CMD12 Argument The argument of command 12 automatically sent by the controller.

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8.2.6.23 0x005C SMHC New Timing Set Register (Default Value: 0x8171_0000)

Offset: 0x005C			Register Name: SMHC_NTSR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x1	MODE_SELECT 0: Old mode of Sample/Output Timing 1: New mode of Sample/Output Timing
30:25	/	/	/
24	R/W	0x1	CMD_DAT_RX_PHASE_CLR Clear the input phase of command lines and data lines during the update clock operation. 0: Disabled 1: Enabled
23	/	/	/
22	R/W	0x1	DAT_CRC_STATUS_RX_PHASE_CLR Clear the input phase of data lines before receiving the CRC status. 0: Disabled 1: Enabled
21	R/W	0x1	DAT_TRANS_RX_PHASE_CLR Clear the input phase of data lines before transferring the data. 0: Disabled 1: Enabled
20	R/W	0x1	DAT_RECV_RX_PHASE_CLR Clear the input phase of data lines before receiving the data. 0: Disabled 1: Enabled
19:17	/	/	/
16	R/W	0x1	CMD_SEND_RX_PHASE_CLR Clear command rx phase before sending the command. 0: Disabled 1: Enabled
15:10	/	/	/
9:8	R/W	0x0	DAT_SAMPLE_TIMING_PHASE 00: Sample timing phase offset 90^0 01: Sample timing phase offset 180^0 10: Sample timing phase offset 270^0 11: Sample timing phase offset 0^0 (only for SD2 hs400 mode)

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Offset: 0x005C			Register Name: SMHC_NTSR
Bit	**Read/Write**	**Default/Hex**	**Description**
7:6	/	/	/
5:4	R/W	0x0	CMD_SAMPLE_TIMING_PHASE 00: Sample timing phase offset 90^0 01: Sample timing phase offset 180^0 10: Sample timing phase offset 270^0 11: Ignore
3:1	/	/	/
0	R/W	0x0	HS400_NEW_SAMPLE_EN 0: Disable hs400 new sample method 1: Enable hs400 new sample method

8.2.6.24 0x0078 SMHC Hardware Reset Register (Default Value: 0x0000_0001)

Offset: 0x0078			Register Name: SMHC_HWRST
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x1	HW_RST 1: Active mode 0: Reset These bits cause the cards to enter the pre-idle state, which requires them to be re-initialized.

8.2.6.25 0x0080 SMHC IDMAC Control Register (Default Value: 0x0000_0000)

Offset: 0x0080			Register Name: SMHC_IDMAC
Bit	**Read/Write**	**Default/Hex**	**Description**
31	W	0x0	DES_LOAD_CTRL When IDMAC fetches a descriptor, if the valid bit of a descriptor is not set, IDMAC FSM will go to the suspend state. Setting this bit will make the IDMAC refetch descriptor again and do the transfer normally.
30:11	/	/	/
10:8	R	0x0	Reserved

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Offset: 0x0080			Register Name: SMHC_IDMAC
Bit	**Read/Write**	**Default/Hex**	**Description**
7	R/W	0x0	IDMAC_ENB IDMAC Enable When set, the IDMAC is enabled.
6:2	R/W	0x0	Reserved
1	R/W	0x0	FIX_BUST_CTRL Fixed Burst Controls whether the AHB Master interface performs fixed burst transfers or not. When set, the AHB will use only SINGLE, INCR4, and INCR8 during the start of normal burst transfers. When reset, the AHB will use SINGLE and INCR burst transfer operations.
0	R/W	0x0	IDMAC_RST DMA Reset When set, the DMA Controller resets all its internal registers. It is automatically cleared after 1 clock cycle.

8.2.6.26 0x0084 SMHC Descriptor List Base Address Register (Default Value: 0x0000_0000)

Offset: 0x0084			Register Name: SMHC_DLBA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	DES_BASE_ADDR Start of Descriptor List Contains the base address of the First Descriptor. It is a word (4 Byte) address.

8.2.6.27 0x0088 SMHC IDMAC Status Register (Default Value: 0x0000_0000)

Offset: 0x0088			Register Name: SMHC_IDST_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16:13	R	0x0	Reserved

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Offset: 0x0088			Register Name: SMHC_IDST_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
12:10	R	0x0	IDMAC_ERR_STA Error Bits Indicates the type of error that caused a Bus Error. Valid only with Fatal Bus Error bit (IDST[2]) set. This field does not generate an interrupt. 001: Host Abort received during the transmission. 010: Host Abort received during the reception. Others: Reserved
9	R/W1C	0x0	ABN_INT_SUM (AIS) Abnormal Interrupt Summary Logical OR of the following: IDST[2]: Fatal Bus Interrupt IDST[4]: Descriptor Unavailable Bit Interrupt IDST[5]: Card Error Summary Interrupt Only unmasked bits affect this bit. This is a sticky bit and must be cleared each time a corresponding bit that causes AIS to be set is cleared.
8	R/W1C	0x0	NOR_INT_SUM (NIS) Normal Interrupt Summary Logical OR of the following: IDST[0]: Transmit Interrupt IDST[1]: Receive Interrupt Only unmasked bits affect this bit. This is a sticky bit and must be cleared each time a corresponding bit that causes NIS to be set is cleared.
7:6	/	/	/
5	R/W1C	0x0	ERR_FLAG_SUM Card Error Summary Indicates the status of the transaction to/from the card; also present in RINTSTS. Indicates the logical OR of the following bits: EBE: End Bit Error RTO: Response Timeout RCRC: Response CRC SBE: Start Bit Error DRTO: Data Read Timeout DCRC: Data CRC for Receive RE: Response Error Writing 1 clears this bit.

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Offset: 0x0088			Register Name: SMHC_IDST_REG
Bit	Read/Write	Default/Hex	Description
4	R/W1C	0x0	DES_UNAVL_INT Descriptor Unavailable Interrupt This bit is set when the descriptor is unavailable due to OWN bit = 0 (DES0[31] =0). Writing 1 clears this bit.
3	/	/	/
2	R/W1C	0x0	FATAL_BERR_INT Fatal Bus Error Interrupt Indicates that a Bus Error occurred (IDST[12:10]). When this bit is set, the DMA disables all its bus accesses. Writing 1 clears this bit.
1	R/W1C	0x0	RX_INT Receive Interrupt Indicates the completion of data reception for a descriptor. Writing 1 clears this bit.
0	R/W1C	0x0	TX_INT Transmit Interrupt Indicates that data transmission is finished for a descriptor. Writing 1 clears this bit.

8.2.6.28 0x008C SMHC IDMAC Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x008C			Register Name: SMHC_IDIE_REG
Bit	Read/Write	Default/Hex	Description
31:6	/	/	/
5	R/W	0x0	ERR_SUM_INT_ENB Card Error Summary Interrupt Enable. When set, it enables the Card Interrupt Summary.
4	R/W	0x0	DES_UNAVL_INT_ENB Descriptor Unavailable Interrupt. When set along with Abnormal Interrupt Summary Enable, the Descriptor Unavailable Interrupt is enabled.
3	/	/	/

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Offset: 0x008C			Register Name: SMHC_IDIE_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	FERR_INT_ENB Fatal Bus Error Enable When set with Abnormal Interrupt Summary Enable, the Fatal Bus Error Interrupt is enabled. When reset, the Fatal Bus Error Enable Interrupt is disabled.
1	R/W	0x0	RX_INT_ENB Receive Interrupt Enable. When set with Normal Interrupt Summary Enable, Receive Interrupt is enabled. When reset, the Receive Interrupt is disabled.
0	R/W	0x0	TX_INT_ENB Transmit Interrupt Enable. When set with Normal Interrupt Summary Enable, Transmit Interrupt is enabled. When reset, the Transmit Interrupt is disabled.

8.2.6.29 0x0100 SMHC Card Threshold Control Register (Default Value: 0x0000_0000)

Offset: 0x0100			Register Name: SMHC_THLD
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/
27:16	R/W	0x0	CARD_WR_THLD Card Read/Write Threshold Size
15:3	/	/	/
2	R/W	0x0	CARD_WR_THLD_ENB Card Write Threshold Enable 0: Card write threshold disabled 1: Card write threshold enabled Host controller initiates write transfer only if the card threshold amount of data is available in transmit FIFO.
1	R/W	0x0	BCIG Busy Clear Interrupt Generation 0: Busy clear interrupt disabled 1: Busy clear interrupt enabled The application can disable this feature if it does not want to wait for a Busy Clear Interrupt.

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Offset: 0x0100			Register Name: SMHC_THLD
Bit	Read/Write	Default/Hex	Description
0	R/W	0x0	CARD_RD_THLD_ENB Card Read Threshold Enable 0: Card read threshold disabled 1: Card read threshold enabled Host controller initiates Read Transfer only if the CARD_RD_THLD amount of space is available in receive FIFO.

8.2.6.30 0x0104 SMHC Sample FIFO Control Register (Default Value: 0x0000_0006)

Offset: 0x0104			Register Name: SMHC_SFC
Bit	Read/Write	Default/Hex	Description
31:5	/	/	/
4:1	R/W	0x3	STOP_CLK_CTRL Stop Clock Control When receiving data, if CARD_RD_THLD_ENB is set and CARD_RD_THLD is set the same with BLK_SZ, the device clock may stop at the block gap during data receiving. This field is used to control the position of the stopping clock. The value can be changed between 0x0 and 0xF, but actually, the available value and the position of the stopping clock must be decided by the actual situation. The value increases one in this field is linked to one cycle (two cycles in DDR mode) that the position of the stopping clock moved up.
0	R/W	0x0	BYPASS_EN Bypass enable When set, sample FIFO will be bypassed.

8.2.6.31 0x0108 SMHC Auto Command 23 Argument Register (Default Value: 0x0000_0000)

Offset: 0x0108			Register Name: SMHC_A23A
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	A23A Auto CMD23 Argument The argument of command 23 is automatically sent by controller with this field.

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8.2.6.32 0x010C SMHC eMMC4.5 DDR Start Bit Detection Control Register (Default Value: 0x0000_0000)

Offset: 0x010C			Register Name: EMMC_DDR_SBIT_DET
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	HS400_MD_EN HS400 Mode Enable 0: Disabled 1: Enabled It is required to set this bit to '1' before initiating any data transfer CMD in HS400 mode.
30:1	/	/	/
0	R/W	0x0	HALF_START_BIT Control for start bit detection mechanism inside mstorage based on duration of start bit. For eMMC 4.5, start bit can be: 0: Full cycle 1: Less than one full cycle Set HALF_START_BIT = 1 for eMMC 4.5 and above; set to 0 for SD applications.

8.2.6.33 0x0138 SMHC Extended Command Register (Default Value: 0x0000_0000)

Offset: 0x0138			Register Name: SMHC_EXT_CMD
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	AUTO_CMD23_EN Send CMD23 Automatically When setting this bit, send CMD23 automatically before sending the command specified in the SMHC_CMD register. When SOFT_RST is set, this field will be cleared.

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8.2.6.34 0x013C SMHC Extended Response Register (Default Value: 0x0000_0000)

Offset: 0x013C			Register Name: SMHC_EXT_RESP
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	SMHC_EXT_RESP When AUTO_CMD23_EN is set, this register stores the response of CMD23.

8.2.6.35 0x0140 SMHC Drive Delay Control Register (Default Value: 0x0001_0000)

Offset: 0x0140			Register Name: SMHC_DRV_DL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/W	0x0	DAT_DRV_PH_SEL Data Drive Phase Select **When 0x005C[31]=0:** 0: Data drive phase offset is 90° at SDR mode, 45° at DDR8 mode, and 90° at DDR4 mode. 1: Data drive phase offset is 180° at SDR mode, 90° at DDR8 mode, and 0° at DDR4 mode. **When 0x005C[31]=1:** 0: Data drive phase offset is 90° at SDR mode, and 45° at DDR mode. 1: Data drive phase offset is 180° at SDR mode, and 90° at DDR mode.
16	R/W	0x1	CMD_DRV_PH_SEL Command Drive Phase Select **When 0x005C[31]=0:** 0: Command drive phase offset is 90° at SDR mode, 45° at DDR8 mode, and 90° at DDR4 mode. 1: Command drive phase offset is 180° at SDR mode, 90° at DDR8 mode, and 180° at DDR4 mode. **When 0x005C[31]=1:** 0: Command drive phase offset is 90° at SDR mode and 45° at DDR mode. 1: Command drive phase offset is 180° at SDR mode and 90° at DDR mode.
15:0	/	/	/

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8.2.6.36 0x0144 SMHC Sample Delay Control Register (Default Value: 0x0000_2000)

Offset: 0x0144			Register Name: SMHC_SAMP_DL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15	R/W	0x0	SAMP_DL_CAL_START Sample Delay Calibration Start When set, it means that start sample delay chain calibration.
14	R	0x0	SAMP_DL_CAL_DONE Sample Delay Calibration Done When set, it means that sample delay chain calibration is done and the result of calibration is shown in SAMP_DL.
13:8	R	0x20	SAMP_DL Sample Delay It indicates the number of delay cells corresponding to the current card clock. The delay time generated by these delay cells is equal to the cycle of the card clock nearly. Generally, it is necessary to do drive delay calibration when the card clock is changed. This bit is valid only when SAMP_DL_CAL_DONE is set.
7	R/W	0x0	SAMP_DL_SW_EN Sample Delay Software Enable When set, it means that enable the sample delay specified at SAMP_DL_SW.
6	/	/	/
5:0	R/W	0x0	SAMP_DL_SW Sample Delay Software The relative delay between the clock line and command line, data line. It can be determined according to the value of SAMP_DL, the cycle of the card clock and the input timing requirement of the device.

8.2.6.37 0x0148 SMHC Data Strobe Delay Control Register (Default Value: 0x0000_2000)

Offset: 0x0148			Register Name: SMHC_DS_DL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/

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Offset: 0x0148			Register Name: SMHC_DS_DL
Bit	**Read/Write**	**Default/Hex**	**Description**
15	R/W	0x0	DS_DL_CAL_START Data Strobe Delay Calibration Start When set, it means that start sample delay chain calibration.
14	R	0x0	DS_DL_CAL_DONE Data Strobe Delay Calibration Done When set, it means that sample delay chain calibration is done and the result of calibration is shown in DS_DL.
13:8	R	0x20	DS_DL Data Strobe Delay It indicates the number of delay cells corresponding to the current card clock. The delay time generated by these delay cells is equal to the cycle of SMHC's clock nearly. This bit is valid only when SAMP_DL_CAL_DONE is set.
7	R/W	0x0	DS_DL_SW_EN Sample Delay Software Enable
6	/	/	/
5:0	R/W	0x0	DS_DL_SW Data Strobe Delay Software

8.2.6.38 0x014C SMHC HS400 New Timing Delay Control Register (Default Value: 0x0000_8000)

Offset: 0x014C			Register Name: SMHC_HS400_DL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15	R/W	0x0	HS400_DL_CAL_START HS400 Delay Calibration Start When set, it means that start sample delay chain calibration.
14	R	0x0	HS400_DL_CAL_DONE HS400 Delay Calibration Done When set, it means that sample delay chain calibration is done and the result of calibration is shown in HS400_DL.
13:12	/	/	/

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Offset: 0x014C			Register Name: SMHC_HS400_DL
Bit	**Read/Write**	**Default/Hex**	**Description**
11:8	R	0x8	HS400_DL HS400 Delay It indicates the number of delay cells corresponding to the current card clock. The delay time generated by these delay cells is equal to the cycle of the SMHC clock nearly. This bit is valid only when HS400_DL_CAL_DONE is set.
7	R/W	0x0	HS400_DL_SW_EN Sample Delay Software Enable
6	/	/	/
3:0	R/W	0x0	HS400_DL_SW HS400 Delay Software

8.2.6.39 0x0200 SMHC FIFO Register (Default Value: 0x0000_0000)

Offset: 0x0200			Register Name: SMHC_FIFO
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TX/RX_FIFO Data FIFO

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9 Audio

9.1 I2S/PCM

9.1.1 Overview

The I2S/PCM controller is designed to transfer streaming audio-data between the system memory and the codec chip. The controller supports standard I2S format, Left-justified mode format, Right-justified mode format, PCM mode format, and TDM mode format.

The I2S/PCM controller includes the following features:

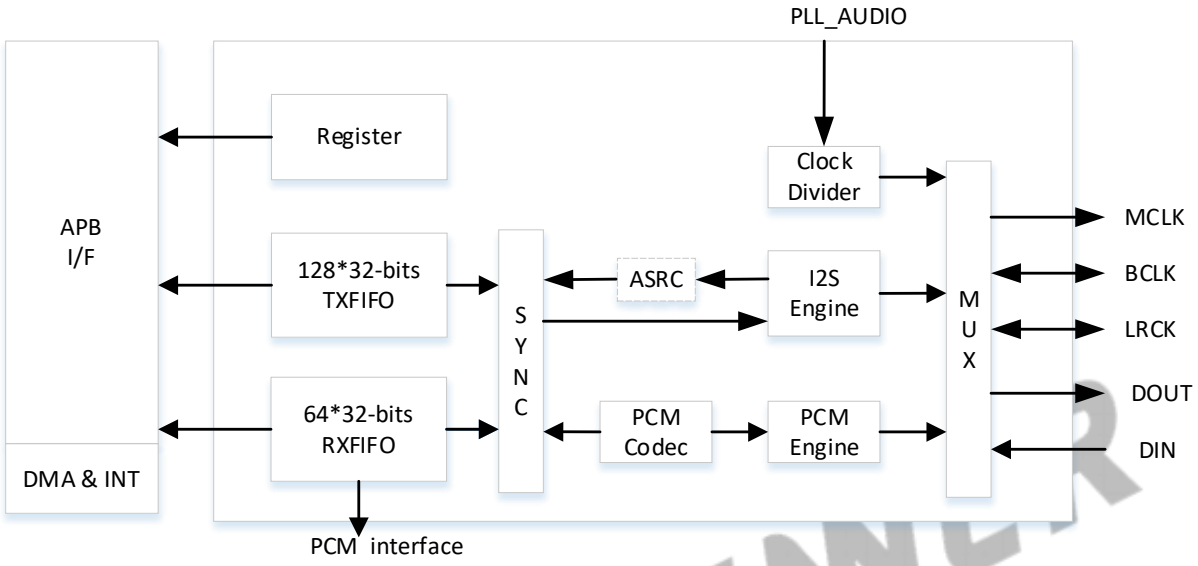
- Three I2S/PCM external interfaces (I2S0, I2S1, I2S2) for connecting external power amplifier and MIC ADC
- Compliant with standard Philips Inter-IC sound (I2S) bus specification
  - Left-justified, Right-justified, PCM mode, and Time Division Multiplexing (TDM) format
  - Programmable PCM frame width: 1 BCLK width (short frame) and 2 BCLKs width (long frame)
- Transmit and Receive data FIFOs
  - Programmable FIFO thresholds
  - 128 depth x 32-bit width TXFIFO and 64 depth x 32-bit width RXFIFO
- Supports multiple function clock
  - Clock up to 24.576 MHz Data Output of I2S/PCM in Master mode (Only if the IO PAD and Peripheral I2S/PCM satisfy Timing Parameters)
  - Clock up to 12.288 MHz Data Input of I2S/PCM in Master mode
- Supports TX/RX DMA Slave interface
- Supports multiple application scenarios
  - Up to 16 channels (fs = 48 kHz) which has adjustable width from 8-bit to 32-bit
  - Sample rate from 8 kHz to 384 kHz (CHAN = 2)
  - 8-bit u-law and 8-bit A-law companded sample
- Supports master/slave mode

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9.1.2 Block Diagram

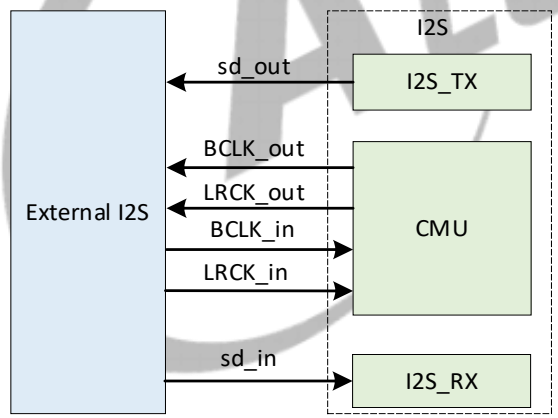
The following figure shows the functional block diagram of the I2S/PCM interface.

Figure 9-1 I2S/PCM Interface System Block Diagram



The following figure shows the typical application of the I2S/PCM interface.

Figure 9-2 Typical Application of I2S/PCM Interface



The I2S/PCM interface system integrates one I2S_TX and one I2S_RX.

- The I2S_TX is for playing music in I2S or PCM format.
- The I2S_RX is for receiving data in I2S or PCM format.
- When the I2S works in the master mode, the external I2S module provides BCLK_in and LRCK_in for the clock management unit (CMU), and the I2S_TX and I2S_RX work with the two external clocks.
- When the I2S works in the slave mode, the CMU provides clocks BCLK_out and LRCK_out for the external I2S module, and the I2S_TX and I2S_RX work with the internal clocks.

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9.1.3 Functional Description

9.1.3.1 External Signals

The following table describes the external signals of the I2S/PCM interface.

LRCK and BCLK are bidirectional I/O. When the I2S/PCM interface works in the Master mode, LRCK and BCLK are output pins. When the I2S/PCM interface works in the Slave mode, LRCK and BCLK are input pins.

MCLK is an output pin for external devices. DOUT are the serial data output pins and DIN are the serial data input pins. For details about General Purpose I/O port, refer to section 9.7 "GPIO".

Table 9-1 I2S/PCM External Signals

Signal Name	Description	Type
I2S0-MCLK	I2S0 Master Clock	O
I2S0-LRCK	I2S0/PCM0 Sample Rate Clock/Sync	I/O
I2S0-BCLK	I2S0/PCM0 Bit Rate Clock	I/O
I2S0-DOUT[3:0]	I2S0/PCM0 Serial Data Output Channel [3:0]	O
I2S0-DIN[3:0]	I2S0/PCM0 Serial Data Input Channel [3:0]	I
I2S1-MCLK	I2S1 Master Clock	O
I2S1-LRCK	I2S1/PCM1 Sample Rate Clock/Sync	I/O
I2S1-BCLK	I2S1/PCM1 Bit Rate Clock	I/O
I2S1-DOUT[1:0]	I2S1/PCM1 Serial Data Output Channel [1:0]	O
I2S1-DIN[1:0]	I2S1/PCM1 Serial Data Input Channel [1:0]	I
I2S2-MCLK	I2S2 Master Clock	O
I2S2-LRCK	I2S2/PCM2 Sample Rate Clock/Sync	I/O
I2S2-BCLK	I2S2/PCM2 Bit Rate Clock	I/O
I2S2-DOUT[3:0]	I2S2/PCM2 Serial Data Output Channel [3:0]	O
I2S2-DIN[3:0]	I2S2/PCM2 Serial Data Input Channel [3:0]	I

9.1.3.2 Clock Sources

The following table describes the clock sources for I2S/PCM. For clock setting, configurations, and gating information, refer to section 3.3 "CCU".

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Table 9-2 I2S/PCM Clock Sources

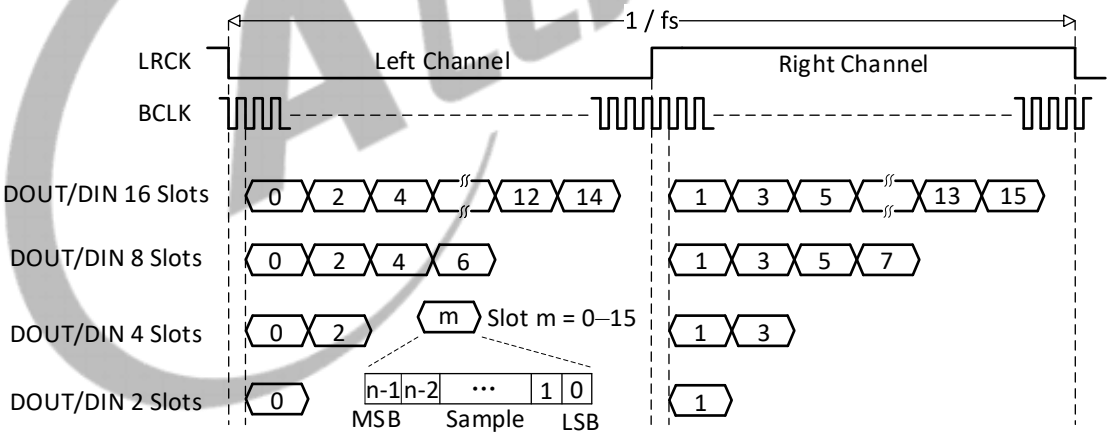
Clock Name	Description
PLL_AUDIO0(1X)	By default, PLL_AUDIO0(1X) is 24.5714 MHz, and PLL_AUDIO0(4X) is 98.2856 MHz.
PLL_AUDIO0(4X)	
PLL_AUDIO1(DIV2)	By default, PLL_AUDIO1 is 3072 MHz, PLL_AUDIO1(DIV2) is 1536 MHz, and PLL_AUDIO1(DIV5) is 614.4 MHz (24.576 MHz*25).
PLL_AUDIO1(DIV5)	

9.1.3.3 Timing Diagram

The I2S/PCM supports standard I2S mode, Left-justified I2S mode, Right-justified I2S mode, PCM mode, and TDM mode. The software can select the modes by setting **I2S/PCM_CTL**. The following figures describe the waveforms for SYNC, BCLK, DOUT, and DIN in different modes.

Each sampling period contains an LRCK. The low level of LRCK is the left channel corresponding to the even slots, and the high level is the right channel corresponding to the odd slots. Each slot is the sampling point of a mono channel. The sampling period can support the transmission of 2/4/8/16 slots. The BCLK corresponds to the serial data bit.

Figure 9-3 I2S Standard Mode Timing



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Figure 9-4 Left-Justified Mode Timing

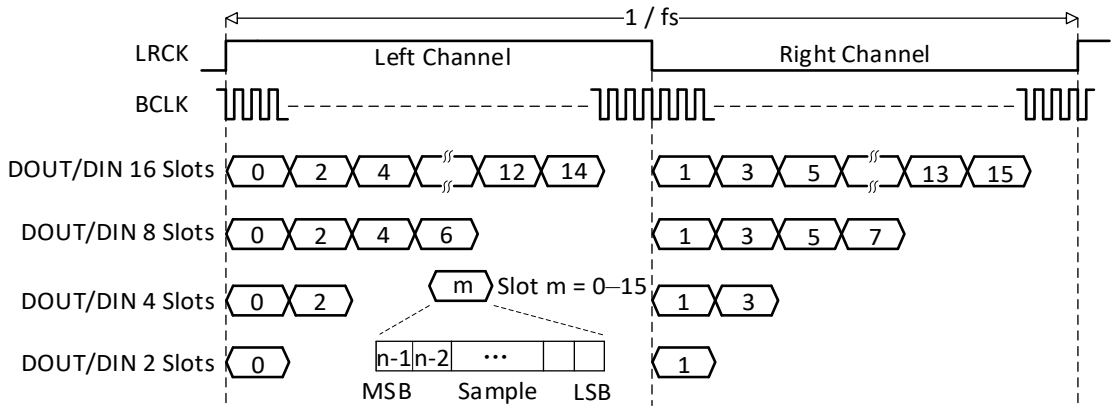


Figure 9-5 Right-Justified Mode Timing

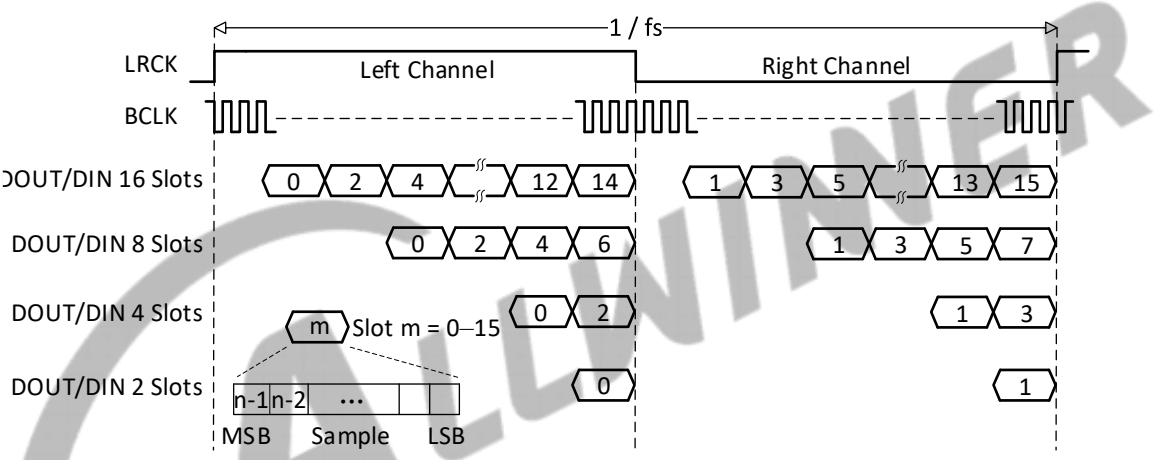
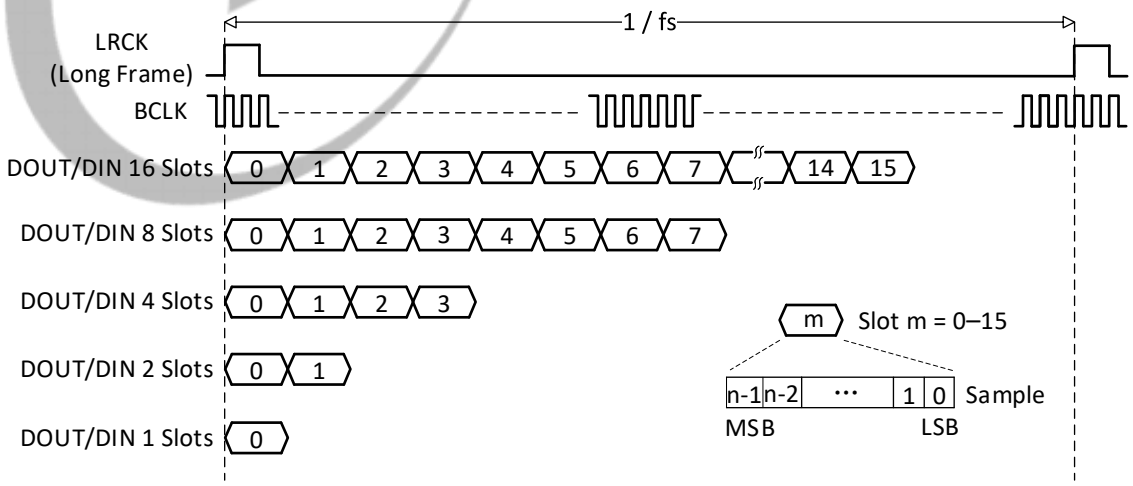
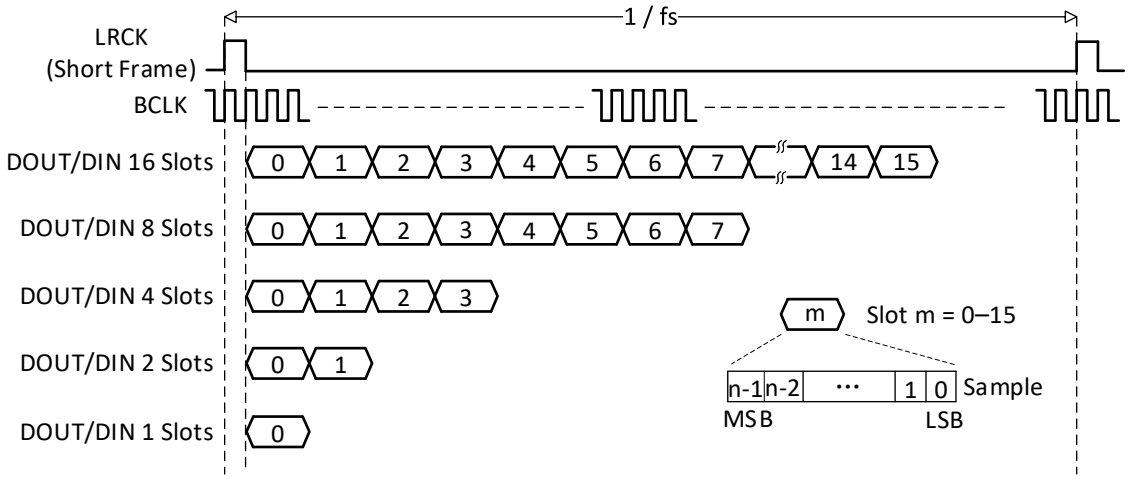


Figure 9-6 PCM Long Frame Mode Timing



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Figure 9-7 PCM Short Frame Mode Timing



9.1.3.4 DIN Slot Mapping

The 4-wire DIN has 64 slots, each wire DIN has 16 slots. However, only 16 slots are valid and act as the RX channels.

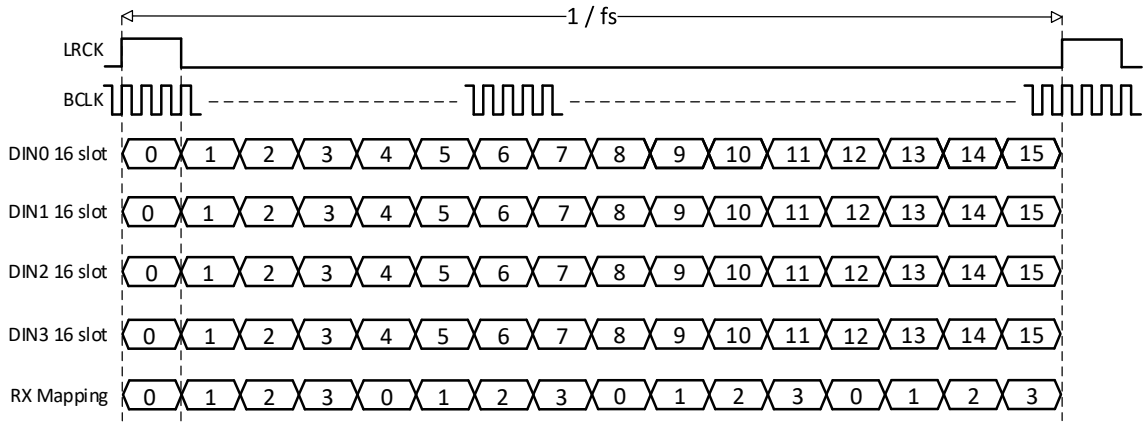
The following table shows the relationship between the slot id and encoder.

Table 9-3 DIN Slot ID and Encoder

DIN0 Slot ID	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
DIN1 Slot ID	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
DIN2 Slot ID	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
DIN3 Slot ID	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

There are 16 channels mapping configuration, each wire selects four slots for RX. The following figure shows the 16-channel mapping configuration.

Figure 9-8 16-Channel Mapping Configuration



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9.1.3.5 ASRC

The ASRC module supports sampling rate conversion between the up-sampling and down-sampling. The ASRC also supports sampling rate conversion between dual-channel audio data, and the size of the sampling data is up to 24 bits.

The ASRC module has the following features:

- Typical THD + N: -130 dB (Range: -125 dB to -139 dB)
- Supports sampling rate conversion between the up-sampling and down-sampling to implement the sampling rate conversion for stereo data
  - The up-sampling ratio ranges from 1 to 7.5x
  - The down-sampling ratio ranges from 8 to 1x
- Supports sampling rate conversion between two identical frequencies
- Sampling rate for both the input and output range is from 8 kHz to 192 kHz and can be decimal
- Sampling rate can be configured manually or via adaptive generation
- The ASRC input is connected to I2S RX_FIFO_WDATA [31:8], and the input data is 24-bit MSB big-endian. For the input data that is less than 24 bits, use zeros to pad out the values at the low bits instead of high bits
- The ASRC needs some time to calculate the result. The output outsamplea/b will keep 0 during the calculation, and then change to the valid value when the result comes out

Calculating the ASRC Latency

Calculate the ASRC up-sampling and down-sampling latency according to the following formulas.

$$\text{Upsampling Latency} = \text{Phase Delay} + \text{FIFO Delay} = 32 + 16 = 48 \text{ Input Sample Periods}$$

$$\text{Downsampling Latency} = \text{Phase Delay} + \text{FIFO Delay} = (32 * f_{sout}/f_{sin}) + 16 \text{ Input Sample Periods}$$

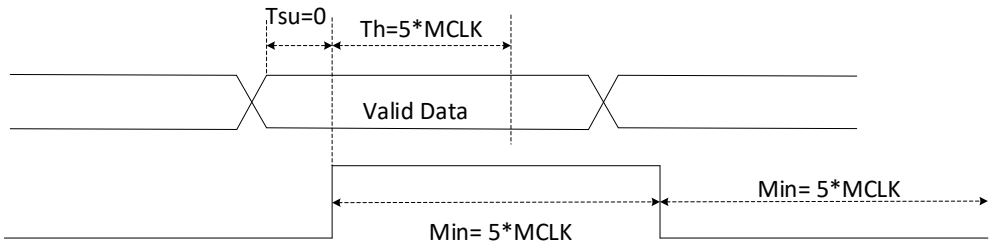
ASRC Timing

The MCLK samples the input clock CLKIN to generate pulse signals.

The following figure shows the timing requirements for the inputs.

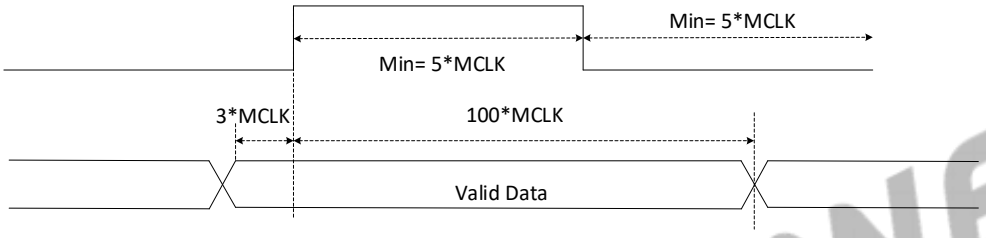
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Figure 9-9 Timing Requirements for Inputs



The following figure shows the timing requirements for the outputs.

Figure 9-10 Timing Requirements for Outputs



For the up-sampling, $F_{MCLK} = F_{sout} * 1350$.

For the down-sampling, $F_{MCLK} = F_{sin} * 0.30 + F_{sout} * 295$.

The following table provides the proper values of MCLK in MHz with different Fsin and Fsout in kHz.

Table 9-4 Proper MCLK Values with Different Fsin and Fsout

Fsin \ Fsout	32	44.1	48	88.2	96	144	192
32	45	60	65	120	130	195	260
44.1	55	60	65	120	130	195	260
48	60	65	65	120	130	195	260
88.2	105	105	110	120	130	195	260
96	110	115	115	125	130	195	260
144	160	165	165	175	180	195	260
192	210	215	215	225	230	245	260

Note: The units for Fsin and Fsout are kHz and MCLK is MHz.

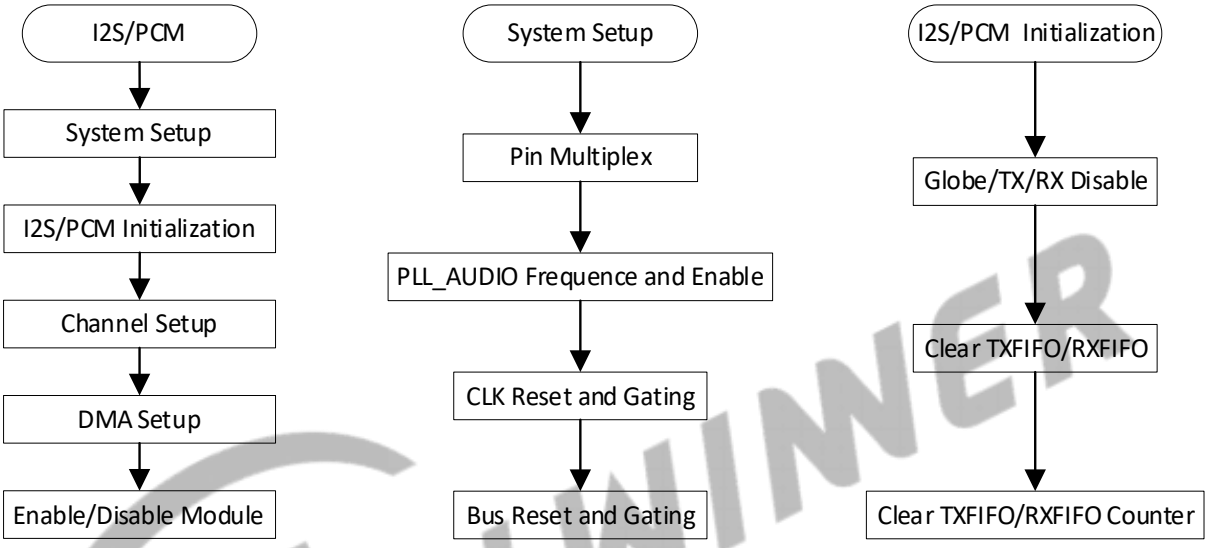
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9.1.3.6 Operation Modes

The software operation of the I2S/PCM is divided into five steps: system setup, I2S/PCM initialization, the channel setup, DMA setup, and Enable/Disable module.

The following figure shows the whole operation flow of I2S/PCM.

Figure 9-11 I2S/PCM Operation Flow



1. System Setup and I2S/PCM Initialization

The clock source for the I2S/PCM should be followed. Firstly, disable the PLL_AUDIO through PLL_AUDIOx Control Register[PLL_ENABLE] in the CCU. Secondly, set up the frequency of the PLL_AUDIO in the PLL_AUDIOx Control Register. After that, enable the I2S/PCM gating through the **I2S/PCMx_CLK_REG** when you checkout that the PLL_AUDIOx Control Register[LOCK] becomes to 1. At last, reset and enable the I2S/PCM bus gating by setting **I2S/PCM_BGR_REG**.

After the system setup, the register of I2S/PCM can be setup. Firstly, initialize the I2S/PCM. You should close the Globe Enable bit (**I2S/PCM_CTL**[0]), Transmitter Block Enable bit (**I2S/PCM_CTL**[2]), and Receiver Block Enable bit (**I2S/PCM_CTL**[1]) by writing 0. After that, clear the TX/RX FIFO by writing 0 to the bit[25:24] of **I2S/PCM_FCTL**. At last, you can clear the TX FIFO and RX FIFO counter by writing 0 to **I2S/PCM_TXCNT** and **I2S/PCM_RXCNT**.

2. Channel Setup and DMA Setup

First, you can set up the I2S/PCM of master and slave. The configuration can be referred to the protocol of I2S/PCM. Then, you can set up the translation mode, the sample resolution, the wide of the slot, the channel slot number, and the trigger level, and so on. The setup of the register can be found in the specification.

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The I2S/PCM supports two methods to transfer the data. The most common way is DMA, the setup of DMA can be found in the **"**DMA**"**. In this module, you just enable the DRQ.

3. Enable and Disable I2S/PCM

To enable the function, you can enable TX/RX by writing **I2S/PCM_CTL**[TXEN]/**I2S/PCM_CTL**[RXEN]. After that, enable I2S/PCM by writing 1 to **I2S/PCM_CTL**[Globe Enable]. Write 0 to the Globe Enable bit to disable I2S/PCM.

9.1.4 Programming Guidelines

9.1.4.1 Application Example of Processing ASRC Input and Output Data

The following example shows a typical application of ASRC: the input data is 24-bit valid, and the output data is a 32-bit data whose highest 24 bits are valid output and the lowest eight bits are padded out with zeros.

To implement the application, configure the sample resolution and slot width as 32 bits. Follow the steps below:

Step 1 For the input register: 0x04 [6:4] sample_res = 3`h7, 0x04 [2:0] slot_width = 3`h7.

The format of the input data: 32'hXXXXXXXX, where, bit[31] is the MSB and X is the valid data bit.

Step 2 For the output register: 0x04 [6:4] sample_res = 3`h7, 0x04 [2:0] slot_width = 3`h7

The format of the output data: 32'hXXXXXX00, where, bit[31] is the MSB, X is the valid data bit, and bit[7:0] are the padded zeros.

9.1.4.2 Converting the Sampling Rate with ASRC

Converting a 48 kHz sampling rate to 16 kHz is the most common scenario in actual applications. Follow the steps below to convert the sampling rate from 48 kHz to 16 kHz for the 32-bit data.

1. Configure the PLL_AUDIO Register

a) Configure **PLL_AUDIO0_CTRL_REG**[31:0] as 0x8814AB01. That is, PLL_AUDIO0 = 24*(171+1)/(1+1)/(1+0)/(1+20) = 98.286 MHz. According to the relationship among the Fsin, Fsout, and MCLK, the MCLK should be greater than 60 MHz. In the simulation phase, the HOSC frequency is 25 MHz, so the output frequency of PLL_AUDIO0 should be 25*(171+1)/(1+1)/(1+0)/(1+20) = 102.381 MHz. In the IC test phase, configure the frequency of PLL_AUDIO0 according to its actual output frequency.

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b) It is suggested that you configure the ASRC MCLK as an equal-duty-cycle signal. You can specify an odd number for bit[21:16] (PLL_POST_DIV_P) of **PLL_AUDIO0_CTRL_REG** to get an equal-duty-cycle output clock of PLL_AUDIO0.

c) Configure bit[25:24] of **I2S/PCM2_ASRC_CLK_REG** as 0x00 to select the PLL_AUDIO0(4X).

2. Configure the I2S Registers

a) Configure bit[7:4] (BCLKDIV) of **I2S/PCM_CLKD** as 4`h9, that is, the frequency of BCLK will be 98.286 MHz/32 = 3.072 MHz.

b) Configure bit[17:8] (LRCK_PERIOD) of **I2S/PCM_FMT0** as 10`h1F. That is, the LRCK_PERIOD width is configured as 32 BLCKs and can generate the ASRC CLKIN with a 48 kHz sampling rate. $(\frac{3.072\text{MHz}}{32*2}=48\text{kHz})$

c) Configure bit[6:4] (Sample Resolution bits) of **I2S/PCM_FMT0** as 3`h7 to specify the sample resolution as 32-bit.

d) Configure bit[2:0] (Slot Width bits) of **I2S/PCM_FMT0** as 3`h7 to specify the slot width as 32-bit.

3. Configure the ASRC Registers

a) Configure bit[16] (clock gate) of **MCLKCFG** as 1`h1 to open the clock gating.

b) Configure bit[3:0] (division factor) of **MCLKCFG** as 1`h1 to specify the division factor as 1.

c) Configure bit[20] (clock gate) of **F_{SOUT}CFG** as 1`h1 to open the clock gating.

d) Configure bit[19:16] (clock select) of **F_{SOUT}CFG** as 4`h0 to select I2S0_ASRC_CLK as the clock source.

e) Configure bit[7:4] (the first division factor) of **F_{SOUT}CFG** as 16`h13 to configure the first division factor as 128.

f) Configure bit[3:0] (the second division factor) of **F_{SOUT}CFG** as 16`h10 to configure the second division factor as 48.

g) Configure the ASRC ratio.

To configure the ASRC ratio manually, configure bit[31] (Manual Configuration of ASRC Ratio Enable) of ASRCMANCFG as 1`h1 to enable the manual configuration of ASRC ratio. Configure bit[25:0] of ASRCMANCFG as 26`h155555 to specify the ratio value as 0x155555. The calculation formula for the ratio value: Dec2Hex (Fsout/Fsin)*2^{22}). In this example, Fsout/Fsin = 16 kHz/48 kHz =1/3, then the ratio is 0x155555.

To configure the ASRC ratio automatically, configure bit[31] (Manual Configuration of ASRC Ratio Enable) of ASRCMANCFG as 1`h0 to enable the automatic configuration of ASRC ratio. Then the system will automatically calculate the ratio value based on the MCLK, Fsout, and Fsin.

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9.1.5 Register List

Module Name	Base Address
I2S/PCM0	0x02032000
I2S/PCM1	0x02033000
I2S/PCM2	0x02034000

Register Name	Offset	Description
I2S/PCM_CTL	0x0000	I2S/PCM Control Register
I2S/PCM_FMT0	0x0004	I2S/PCM Format Register 0
I2S/PCM_FMT1	0x0008	I2S/PCM Format Register 1
I2S/PCM_ISTA	0x000C	I2S/PCM Interrupt Status Register
I2S/PCM_RXFIFO	0x0010	I2S/PCM RXFIFO Register
I2S/PCM_FCTL	0x0014	I2S/PCM FIFO Control Register
I2S/PCM_FSTA	0x0018	I2S/PCM FIFO Status Register
I2S/PCM_INT	0x001C	I2S/PCM DMA & Interrupt Control Register
I2S/PCM_TXFIFO	0x0020	I2S/PCM TXFIFO Register
I2S/PCM_CLKD	0x0024	I2S/PCM Clock Divide Register
I2S/PCM_TXCNT	0x0028	I2S/PCM TX Sample Counter Register
I2S/PCM_RXCNT	0x002C	I2S/PCM RX Sample Counter Register
I2S/PCM_CHCFG	0x0030	I2S/PCM Channel Configuration Register
I2S/PCM_TX0CHSEL	0x0034	I2S/PCM TX0 Channel Select Register
I2S/PCM_TX1CHSEL	0x0038	I2S/PCM TX1 Channel Select Register
I2S/PCM_TX2CHSEL	0x003C	I2S/PCM TX2 Channel Select Register
I2S/PCM_TX3CHSEL	0x0040	I2S/PCM TX3 Channel Select Register
I2S/PCM_TX0CHMAP0	0x0044	I2S/PCM TX0 Channel Mapping Register0
I2S/PCM_TX0CHMAP1	0x0048	I2S/PCM TX0 Channel Mapping Register1
I2S/PCM_TX1CHMAP0	0x004C	I2S/PCM TX1 Channel Mapping Register0
I2S/PCM_TX1CHMAP1	0x0050	I2S/PCM TX1 Channel Mapping Register1
I2S/PCM_TX2CHMAP0	0x0054	I2S/PCM TX2 Channel Mapping Register0
I2S/PCM_TX2CHMAP1	0x0058	I2S/PCM TX2 Channel Mapping Register1
I2S/PCM_TX3CHMAP0	0x005C	I2S/PCM TX3 Channel Mapping Register0
I2S/PCM_TX3CHMAP1	0x0060	I2S/PCM TX3 Channel Mapping Register1

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Register Name	Offset	Description
I2S/PCM_RXCHSEL	0x0064	I2S/PCM RX Channel Select Register
I2S/PCM_RXCHMAP0	0x0068	I2S/PCM RX Channel Mapping Register0
I2S/PCM_RXCHMAP1	0x006C	I2S/PCM RX Channel Mapping Register1
I2S/PCM_RXCHMAP2	0x0070	I2S/PCM RX Channel Mapping Register2
I2S/PCM_RXCHMAP3	0x0074	I2S/PCM RX Channel Mapping Register3
MCLKCFG	0x0080	ASRC MCLK Configuration Register
FsoutCFG	0x0084	ASRC Out Sample Rate Configuration Register
FsinEXTCFG	0x0088	ASRC Input Sample Pulse Extend Configuration Register
ASRCCFG	0x008C	ASRC Enable Register
ASRCMANCFG	0x0090	ASRC Manual Ratio Configuration Register
ASRCRATIOSTAT	0x0094	ASRC Status Register
ASRCFIFOSTAT	0x0098	ASRC FIFO Level Status Register
ASRCMBISTCFG	0x009C	ASRC MBIST Test Configuration Register
ASRCMBISTSTAT	0x00A0	ASRC MBIST Test Status Register

9.1.6 Register Description

9.1.6.1 0x0000 I2S/PCM Control Register (Default Value: 0x0006_0000)

Offset: 0x0000			Register Name: I2S/PCM_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21	R/W	0x0	RX_SYNC_EN_START The bit takes effect only when RX_SYNC_EN is set to 1. I2S0/I2S1/I2S2 Synchronize Enable Start. 0: Disabled 1: Enabled
20	R/W	0x0	RX_SYNC_EN I2S RX Synchronize Enable 0: Disabled 1: Enabled
19	/	/	/

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Offset: 0x0000			Register Name: I2S/PCM_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
18	R/W	0x1	BCLK_OUT Bit Clock Direction Select 0: Input 1: Output
17	R/W	0x1	LRCK_OUT LRCK Direction Select 0: Input 1: Output
16:12	/	/	/
11	R/W	0x0	DOUT3_EN Data3 Output Enable 0: Disabled, Hi-Z State 1: Enabled
10	R/W	0x0	DOUT2_EN Data2 Output Enable 0: Disabled, Hi-Z State 1: Enabled
9	R/W	0x0	DOUT1_EN Data1 Output Enable 0: Disabled, Hi-Z State 1: Enabled
8	R/W	0x0	DOUT0_EN Data0 Output Enable 0: Disabled, Hi-Z State 1: Enabled
7	/	/	/
6	R/W	0x0	OUT_MUTE Data Output Mute Enable 0: Normal Transfer 1: Force DOUT to output 0
5:4	R/W	0x0	MODE_SEL Mode Selection 00: PCM Mode (offset 0: Long Frame; offset 1: Short Frame) 01: Left Mode (offset 0: LJ Mode; offset 1: I2S Mode) 10: Right-Justified Mode 11: Reserved

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Offset: 0x0000			Register Name: I2S/PCM_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W	0x0	LOOP Loopback Test 0: Normal Mode 1: Loopback Test When set to '1', the bit indicates that the DOUT is connected to the DIN.
2	R/W	0x0	TXEN Transmitter Block Enable 0: Disabled 1: Enabled
1	R/W	0x0	RXEN Receiver Block Enable 0: Disabled 1: Enabled
0	R/W	0x0	GEN Globe Enable 0: Disabled 1: Enabled

9.1.6.2 0x0004 I2S/PCM Format Register 0 (Default Value: 0x0000_0033)

Offset: 0x0004			Register Name: I2S/PCM_FMT0
Bit	**Read/Write**	**Default/Hex**	**Description**
31	/	/	/
30	R/W	0x0	LRCK_WIDTH LRCK Width (only applies to the PCM mode) 0: LRCK = 1 BCLK Width (Short Frame) 1: LRCK = 2 BCLK Width (Long Frame)
29:20	/	/	/

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Offset: 0x0004			Register Name: I2S/PCM_FMT0
Bit	**Read/Write**	**Default/Hex**	**Description**
19	R/W	0x0	LRCK_POLARITY In I2S/Left-Justified/Right-Justified mode: 0: Left Channel when LRCK is low. 1: Left channel when LRCK is high. In PCM mode: 0: PCM LRCK asserted at the negative edge. 1: PCM LRCK asserted at the positive edge.
18	/	/	/
17:8	R/W	0x0	LRCK_PERIOD It is used to program the number of BCLKs per channel of the sample frame. This value is interpreted as follows. PCM mode: Number of BCLKs within (Left + Right) channel width. I2S/Left-Justified/Right-Justified mode: Number of BCLKs within each channel width (Left or Right). For example: N = 7: 8 BCLKs width … N = 1023: 1024 BCLKs width
7	R/W	0x0	BCLK_POLARITY 0: Normal mode, DOUT drives data at negative edge 1: Invert mode, DOUT drives data at positive edge
6:4	R/W	0x3	SR Sample Resolution 000: Reserved 001: 8-bit 010: 12-bit 011: 16-bit 100: 20-bit 101: 24-bit 110: 28-bit 111: 32-bit

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Offset: 0x0004			Register Name: I2S/PCM_FMT0
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W	0x0	EDGE_TRANSFER Edge Transfer 0: DOUT drives data and DIN sample data at the different BCLK edge 1: DOUT drives data and DIN sample data at the same BCLK edge BCLK_POLARITY = 0, EDGE_TRANSFER = 0, DIN sample data at positive edge; BCLK_POLARITY = 0, EDGE_TRANSFER = 1, DIN sample data at negative edge; BCLK_POLARITY = 1, EDGE_TRANSFER = 0, DIN sample data at negative edge; BCLK_POLARITY = 1, EDGE_TRANSFER = 1, DIN sample data at positive edge.
2:0	R/W	0x3	SW Slot Width Select 000: Reserved 001: 8-bit 010: 12-bit 011: 16-bit 100: 20-bit 101: 24-bit 110: 28-bit 111: 32-bit

9.1.6.3 0x0008 I2S/PCM Format Register 1 (Default Value: 0x0000_0030)

Offset: 0x0008			Register Name: I2S/PCM_FMT1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	RX MLS MSB/LSB First Select 0: MSB First 1: LSB First

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Offset: 0x0008			Register Name: I2S/PCM_FMT1
Bit	**Read/Write**	**Default/Hex**	**Description**
6	R/W	0x0	TX MLS MSB/LSB First Select 0: MSB First 1: LSB First
5:4	R/W	0x3	SEXT Sign Extend in Slot [Sample Resolution < Slot Width] 00: Zeros or audio gain padding at LSB position 01: Sign extension at MSB position 10: Reserved 11: Transfer 0 after each sample in each Slot
3:2	R/W	0x0	RX_PDM PCM Data Mode 00: Linear PCM 01: Reserved 10: 8-bit u-law 11: 8-bit A-law
1:0	R/W	0x0	TX_PDM PCM Data Mode 00: Linear PCM 01: Reserved 10: 8-bit u-law 11: 8-bit A-law

9.1.6.4 0x000C I2S/PCM Interrupt Status Register (Default Value: 0x0000_0010)

Offset: 0x000C			Register Name: I2S/PCM_ISTA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6	R/W1C	0x0	TXU_INT TXFIFO Underrun Pending Interrupt 0: No pending interrupt 1: TXFIFO underrun pending interrupt Write ‘1’ to clear this interrupt.

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Offset: 0x000C			Register Name: I2S/PCM_ISTA
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R/W1C	0x0	TXO_INT TXFIFO Overrun Pending Interrupt 0: No pending interrupt 1: TXFIFO overrun pending interrupt Write '1' to clear this interrupt.
4	R	0x1	TXE_INT TXFIFO Empty Pending Interrupt 0: No pending IRQ 1: TXFIFO empty pending interrupt when data in TXFIFO are less than TX trigger level
3	/	/	/
2	R/W1C	0x0	RXU_INT RXFIFO Underrun Pending Interrupt 0: No pending interrupt 1: RXFIFO underrun pending interrupt Write '1' to clear this interrupt.
1	R/W1C	0x0	RXO_INT RXFIFO Overrun Pending Interrupt 0: No pending IRQ 1: RXFIFO overrun pending IRQ Write '1' to clear this interrupt.
0	R/W	0x0	RXA_INT RXFIFO Data Available Pending Interrupt 0: No pending IRQ 1: Data available pending IRQ when data in RXFIFO are more than RX trigger level

9.1.6.5 0x0010 I2S/PCM RXFIFO Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: I2S/PCM_RXFIFO
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	RX_DATA RX Sample The host can get one sample by reading this register. The left channel sample data is first and then the right channel sample.

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9.1.6.6 0x0014 I2S/PCM FIFO Control Register (Default Value: 0x0004_00F0)

Offset: 0x0014			Register Name: I2S/PCM_FCTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	HUB_EN Audio Hub Enable The bit takes effect only when TXEN is set to 1. I2S0/I2S1/I2S2/OWA TXFIFO Hub Enable. 0: Disabled 1: Enabled
30:26	/	/	/
25	R/WAC	0x0	FTX Write '1' to flush TXFIFO, self clear to '0'.
24	R/WAC	0x0	FRX Write '1' to flush RXFIFO, self clear to '0'.
23:19	/	/	/
18:12	R/W	0x40	TXTL TXFIFO Empty Trigger Level Interrupt and DMA request trigger level for TXFIFO normal condition. Trigger Level = TXTL
11:10	/	/	/
9:4	R/W	0xF	RXTL RXFIFO Trigger Level Interrupt and DMA request trigger level for RXFIFO normal condition. Trigger Level = RXTL + 1
3	/	/	/
2	R/W	0x0	TXIM TXFIFO Input Mode (Mode 0, 1) 0: Valid data at the MSB of TXFIFO register 1: Valid data at the LSB of TXFIFO register Example for 20-bit transmitted audio sample: Mode 0: TXFIFO[31:0] = {APB_WDATA[31:12], 12'h0} Mode 1: TXFIFO[31:0] = {APB_WDATA[19:0], 12'h0}

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Offset: 0x0014			Register Name: I2S/PCM_FCTL
Bit	**Read/Write**	**Default/Hex**	**Description**
1:0	R/W	0x0	RXOM RXFIFO Output Mode (Mode 0, 1, 2, 3) 00: Expanding '0' at LSB of RXFIFO register 01: Expanding received sample sign bit at MSB of RXFIFO register 10: Truncating received samples at high half-word of RXFIFO register and low half-word of RXFIFO register is filled by '0' 11: Truncating received samples at low half-word of RXFIFO register and high half-word of RXFIFO register is expanded by its sign bit Example for 20-bit received audio sample: Mode 0: APB_RDATA[31:0] = {RXFIFO[31:12], 12'h0} Mode 1: APB_RDATA[31:0] = {12{RXFIFO[31]}, RXFIFO[31:12]} Mode 2: APB_RDATA [31:0] = {RXFIFO[31:16], 16'h0} Mode 3: APB_RDATA[31:0] = {16{RXFIFO[31], RXFIFO[31:16]}

9.1.6.7 0x0018 I2S/PCM FIFO Status Register (Default Value: 0x1080_0080)

Offset: 0x0018			Register Name: I2S/PCM_FSTA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28	R	0x1	TXE TXFIFO Empty 0: No room for new sample in TXFIFO 1: More than one room for new sample in TXFIFO (>= 1 Word)
27:24	/	/	/
23:16	R	0x80	TXE_CNT TXFIFO Empty Space Word Counter
15:9	/	/	/
8	R	0x0	RXA RXFIFO Available 0: No available data in RXFIFO 1: More than one sample in RXFIFO (>= 1 Word)
7	R	0x1	PLACE_HOLDER NO Meaning

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Offset: 0x0018			Register Name: I2S/PCM_FSTA
Bit	**Read/Write**	**Default/Hex**	**Description**
6:0	R	0x0	RXA_CNT RXFIFO available sample word counter

9.1.6.8 0x001C I2S/PCM DMA & Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: I2S/PCM_INT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	TX_DRQ TXFIFO Empty DRQ Enable 0: Disabled 1: Enabled
6	R/W	0x0	TXUI_EN TXFIFO Underrun Interrupt Enable 0: Disabled 1: Enabled
5	R/W	0x0	TXOI_EN TXFIFO Overrun Interrupt Enable 0: Disabled 1: Enabled When set to '1', an interrupt happens when writing new audio data if TXFIFO is full.
4	R/W	0x0	TXEI_EN TXFIFO Empty Interrupt Enable 0: Disabled 1: Enabled
3	R/W	0x0	RX_DRQ RXFIFO Data Available DRQ Enable 0: Disabled 1: Enabled When set to '1', RXFIFO DMA request line is asserted if data is available in RXFIFO.

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Offset: 0x001C			Register Name: I2S/PCM_INT
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	RXUI_EN RXFIFO Underrun Interrupt Enable 0: Disabled 1: Enabled
1	R/W	0x0	RXOI_EN RXFIFO Overrun Interrupt Enable 0: Disabled 1: Enabled
0	R/W	0x0	RXAI_EN RXFIFO Data Available Interrupt Enable 0: Disabled 1: Enabled

9.1.6.9 0x0020 I2S/PCM TXFIFO Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: I2S/PCM_TXFIFO
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	W	0x0	TX_DATA TX Sample Transmitting left, right channel sample data should be written to this register one by one. The left channel sample data is first and then the right channel sample.

9.1.6.10 0x0024 I2S/PCM Clock Divide Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: I2S/PCM_CLKD
Bit	**Read/Write**	**Default/Hex**	**Description**
31:9	/	/	/
8	R/W	0x0	MCLKO_EN 0: Disable MCLK Output 1: Enable MCLK Output **Note: Whether in slave or master mode, when this bit is set to '1', MCLK should be output.**

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Offset: 0x0024			Register Name: I2S/PCM_CLKD
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0x0	BCLKDIV BCLK Divide Ratio from PLL_AUDIO 0000: Reserved 0001: Divide by 1 0010: Divide by 2 0011: Divide by 4 0100: Divide by 6 0101: Divide by 8 0110: Divide by 12 0111: Divide by 16 1000: Divide by 24 1001: Divide by 32 1010: Divide by 48 1011: Divide by 64 1100: Divide by 96 1101: Divide by 128 1110: Divide by 176 1111: Divide by 192
3:0	R/W	0x0	MCLKDIV MCLK Divide Ratio from PLL_AUDIO 0000: Reserved 0001: Divide by 1 0010: Divide by 2 0011: Divide by 4 0100: Divide by 6 0101: Divide by 8 0110: Divide by 12 0111: Divide by 16 1000: Divide by 24 1001: Divide by 32 1010: Divide by 48 1011: Divide by 64 1100: Divide by 96 1101: Divide by 128 1110: Divide by 176 1111: Divide by 192

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9.1.6.11 0x0028 I2S/PCM TX Sample Counter Register (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: I2S/PCM_TXCNT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TX_CNT TX Sample Counter The audio sample number of sending into TXFIFO. When one sample is put into TXFIFO by DMA or by host IO, the TX sample counter register increases by one. The TX sample counter register can be set to any initial value at any time. After being updated by the initial value, the counter register should count on the base of this initial value.

9.1.6.12 0x002C I2S/PCM RX Sample Counter Register (Default Value: 0x0000_0000)

Offset: 0x002C			Register Name: I2S/PCM_RXCNT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	RX_CNT RX Sample Counter The audio sample number of writing into RXFIFO. When one sample is written by Digital Audio Engine, the RX sample counter register increases by one. The RX sample counter register can be set to any initial value at any time. After being updated by the initial value, the counter register should count on the base of this initial value.

9.1.6.13 0x0030 I2S/PCM Channel Configuration Register (Default Value: 0x0000_0000)

Offset: 0x0030			Register Name: I2S/PCM_CHCFG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:10	/	/	/
9	R/W	0x0	TX_SLOT_HIZ 0: Normal mode for the last half-cycle of BCLK in the slot 1: Turn to Hi-Z state for the last half-cycle of BCLK in the slot
8	R/W	0x0	TX_STATE 0: Transfer level 0 in non-transferring slot 1: Turn to Hi-Z State (TDM) in non-transferring slot

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Offset: 0x0030			Register Name: I2S/PCM_CHCFG
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0x0	RX_SLOT_NUM RX Channel/Slot number between CPU/DMA and RXFIFO 0000: 1 channel or slot ... 0111: 8 channels or slots 1000: 9 channels or slots ... 1111: 16 channels or slots
3:0	R/W	0x0	TX_SLOT_NUM TX Channel/Slot number between CPU/DMA and TXFIFO 0000: 1 channel or slot ... 0111: 8 channels or slots 1000: 9 channels or slots ... 1111:16 channels or slots

9.1.6.14 0x0034 I2S/PCM TX0 Channel Select Register (Default Value: 0x0000_0000)

Offset: 0x0034			Register Name: I2S/PCM_TX0CHSEL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21:20	R/W	0x0	TX0_OFFSET TX0 Offset Tune (TX0 Data offset to LRCK) 0: No offset n: Data is offset by n BCLKs to LRCK
19:16	R/W	0x0	TX0_CHSEL TX0 Channel (Slot) Number Select for Each Output 0000: 1 channel or slot ... 0111: 8 channels or slots 1000: 9 channels or slots ... 1111: 16 channels or slots

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Offset: 0x0034			Register Name: I2S/PCM_TX0CHSEL
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R/W	0x0	TX0_CHEN TX0 Channel (Slot) Enable The bit[15:0] refer to Slot [15:0]. When one or more slots are disabled, the affected slots are set to the disable state. 0: Disabled 1: Enabled

9.1.6.15 0x0038 I2S/PCM TX1 Channel Select Register (Default Value: 0x0000_0000)

Offset: 0x0038			Register Name: I2S/PCM_TX1CHSEL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21:20	R/W	0x0	TX1_OFFSET TX1 Offset Tune (TX1 Data offset to LRCK) 0: No offset n: Data is offset by n BCLKs to LRCK
19:16	R/W	0x0	TX1_CHSEL TX1 Channel (Slot) Number Select for Each Output 0000: 1 channel or slot ... 0111: 8 channels or slots 1000: 9 channels or slots ... 1111: 16 channels or slots
15:0	R/W	0x0	TX1_CHEN TX1 Channel (Slot) Enable The bit[15:0] refers to Slot [15:0]. When one or more slots are disabled, the affected slots are set to the disable state. 0: Disabled 1: Enabled

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9.1.6.16 0x003C I2S/PCM TX2 Channel Select Register (Default Value: 0x0000_0000)

Offset: 0x003C			Register Name: I2S/PCM_TX2CHSEL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21:20	R/W	0x0	TX2_OFFSET TX2 Offset Tune (TX2 Data offset to LRCK) 0: No offset n: Data is offset by n BCLKs to LRCK
19:16	R/W	0x0	TX2_CHSEL TX2 Channel (Slot) Number Select for Each Output 0000: 1 channel or slot ... 0111: 8 channels or slots 1000: 9 channels or slots ... 1111: 16 channels or slots
15:0	R/W	0x0	TX2_CHEN TX2 Channel (Slot) Enable The bit[15:0] refers to Slot [15:0]. When one or more slots are disabled, the affected slots are set to the disable state. 0: Disabled 1: Enabled

9.1.6.17 0x0040 I2S/PCM TX3 Channel Select Register (Default Value: 0x0000_0000)

Offset: 0x0040			Register Name: I2S/PCM_TX3CHSEL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21:20	R/W	0x0	TX3_OFFSET TX3 Offset Tune (TX3 Data offset to LRCK) 0: No offset n: Data is offset by n BCLKs to LRCK

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Offset: 0x0040			Register Name: I2S/PCM_TX3CHSEL
Bit	**Read/Write**	**Default/Hex**	**Description**
19:16	R/W	0x0	TX3_CHSEL TX3 Channel (Slot) Number Select for Each Output 0000: 1 channel or slot ... 0111: 8 channels or slots 1000: 9 channels or slots ... 1111: 16 channels or slots
15:0	R/W	0x0	TX3_CHEN TX3 Channel (Slot) Enable The bit[15:0] refers to Slot [15:0]. When one or more slots are disabled, the affected slots are set to the disable state. 0: Disabled 1: Enabled

9.1.6.18 0x0044 I2S/PCM TX0 Channel Mapping0 Register 0 (Default Value: 0x0000_0000)

Offset: 0x0044			Register Name: I2S/PCM_TX0CHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	TX0_CH15_MAP TX0 Channel 15 Mapping 0000: The first sample ... 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
27:24	R/W	0x0	TX0_CH14_MAP TX0 Channel 14 Mapping 0000: The first sample ... 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

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Offset: 0x0044			Register Name: I2S/PCM_TX0CHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	R/W	0x0	TX0_CH13_MAP TX0 Channel 13 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
19:16	R/W	0x0	TX0_CH12_MAP TX0 Channel 12 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
15:12	R/W	0x0	TX0_CH11_MAP TX0 Channel 11 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
11:8	R/W	0x0	TX0_CH10_MAP TX0 Channel 10 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

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Offset: 0x0044			Register Name: I2S/PCM_TX0CHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0x0	TX0_CH9_MAP TX0 Channel 9 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
3:0	R/W	0x0	TX0_CH8_MAP TX0 Channel 8 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

9.1.6.19 0x0048 I2S/PCM TX0 Channel Mapping1 Register 1 (Default Value: 0x0000_0000)

Offset: 0x0048			Register Name: I2S/PCM_TX0CHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	TX0_CH7_MAP TX0 Channel 7 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

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Offset: 0x0048			Register Name: I2S/PCM_TX0CHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
27:24	R/W	0x0	TX0_CH6_MAP TX0 Channel 6 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
23:20	R/W	0x0	TX0_CH5_MAP TX0 Channel 5 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
19:16	R/W	0x0	TX0_CH4_MAP TX0 Channel 4 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
15:12	R/W	0x0	TX0_CH3_MAP TX0 Channel 3 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

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Offset: 0x0048			Register Name: I2S/PCM_TX0CHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
11:8	R/W	0x0	TX0_CH2_MAP TX0 Channel 2 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
7:4	R/W	0x0	TX0_CH1_MAP TX0 Channel 1 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
3:0	R/W	0x0	TX0_CH0_MAP TX0 Channel 0 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

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9.1.6.20 0x004C I2S/PCM TX1 Channel Mapping0 Register 0 (Default Value: 0x0000_0000)

Offset: 0x004C			Register Name: I2S/PCM_TX1CHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	TX1_CH15_MAP TX1 Channel 15 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
27:24	R/W	0x0	TX1_CH14_MAP TX1 Channel 14 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
23:20	R/W	0x0	TX1_CH13_MAP TX1 Channel 13 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
19:16	R/W	0x0	TX1_CH12_MAP TX1 Channel 12 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample

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Offset: 0x004C			Register Name: I2S/PCM_TX1CHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0x0	TX1_CH11_MAP TX1 Channel 11 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
11:8	R/W	0x0	TX1_CH10_MAP TX1 Channel 10 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
7:4	R/W	0x0	TX1_CH9_MAP TX1 Channel 9 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
3:0	R/W	0x0	TX1_CH8_MAP TX1 Channel 8 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample

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9.1.6.21 0x0050 I2S/PCM TX1 Channel Mapping1 Register 1 (Default Value: 0x0000_0000)

Offset: 0x0050			Register Name: I2S/PCM_TX1CHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	TX1_CH7_MAP TX1 Channel 7 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
27:24	R/W	0x0	TX1_CH6_MAP TX1 Channel 6 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
23:20	R/W	0x0	TX1_CH5_MAP TX1 Channel 5 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
19:16	R/W	0x0	TX1_CH4_MAP TX1 Channel 4 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample

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Offset: 0x0050			Register Name: I2S/PCM_TX1CHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0x0	TX1_CH3_MAP TX1 Channel 3 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
11:8	R/W	0x0	TX1_CH2_MAP TX1 Channel 2 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
7:4	R/W	0x0	TX1_CH1_MAP TX1 Channel 1 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
3:0	R/W	0x0	TX1_CH0_MAP TX1 Channel 0 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample

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9.1.6.22 0x0054 I2S/PCM TX2 Channel Mapping0 Register 0 (Default Value: 0x0000_0000)

Offset: 0x0054			Register Name: I2S/PCM_TX2CHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	TX2_CH15_MAP TX2 Channel 15 Mapping 0000: The first sample ... 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
27:24	R/W	0x0	TX2_CH14_MAP TX2 Channel 14 Mapping 0000: The first sample ... 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
23:20	R/W	0x0	TX2_CH13_MAP TX2 Channel 13 Mapping 0000: The first sample ... 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
19:16	R/W	0x0	TX2_CH12_MAP TX2 Channel 12 Mapping 0000: The first sample ... 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

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Offset: 0x0054			Register Name: I2S/PCM_TX2CHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0x0	TX2_CH11_MAP TX2 Channel 11 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
11:8	R/W	0x0	TX2_CH10_MAP TX2 Channel 10 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
7:4	R/W	0x0	TX2_CH9_MAP TX2 Channel 9 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
3:0	R/W	0x0	TX2_CH8_MAP TX2 Channel 8 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

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9.1.6.23 0x0058 I2S/PCM TX2 Channel Mapping1 Register 1 (Default Value: 0x0000_0000)

Offset: 0x0058			Register Name: I2S/PCM_TX2CHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	TX2_CH7_MAP TX2 Channel 7 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
27:24	R/W	0x0	TX2_CH6_MAP TX2 Channel 6 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
23:20	R/W	0x0	TX2_CH5_MAP TX2 Channel 5 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
19:16	R/W	0x0	TX2_CH4_MAP TX2 Channel 4 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample

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Offset: 0x0058			Register Name: I2S/PCM_TX2CHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0x0	TX2_CH3_MAP TX2 Channel 3 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
11:8	R/W	0x0	TX2_CH2_MAP TX2 Channel 2 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
7:4	R/W	0x0	TX2_CH1_MAP TX2 Channel 1 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
3:0	R/W	0x0	TX2_CH0_MAP TX2 Channel 0 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

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9.1.6.24 0x005C I2S/PCM TX3 Channel Mapping0 Register 0 (Default Value: 0x0000_0000)

Offset: 0x005C			Register Name: I2S/PCM_TX3CHMAP0
Bit	Read/Write	Default/Hex	Description
31:28	R/W	0x0	TX3_CH15_MAP TX3 Channel 15 Mapping 0000: The first sample ... 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
27:24	R/W	0x0	TX3_CH14_MAP TX3 Channel 14 Mapping 0000: The first sample ... 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
23:20	R/W	0x0	TX3_CH13_MAP TX3 Channel 13 Mapping 0000: The first sample ... 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
19:16	R/W	0x0	TX3_CH12_MAP TX3 Channel 12 Mapping 0000: The first sample ... 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

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Offset: 0x005C			Register Name: I2S/PCM_TX3CHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0x0	TX3_CH11_MAP TX3 Channel 11 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
11:8	R/W	0x0	TX3_CH10_MAP TX3 Channel 10 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
7:4	R/W	0x0	TX3_CH9_MAP TX3 Channel 9 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
3:0	R/W	0x0	TX3_CH8_MAP TX3 Channel 8 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample

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9.1.6.25 0x0060 I2S/PCM TX3 Channel Mapping1 Register 1 (Default Value: 0x0000_0000)

Offset: 0x0060			Register Name: I2S/PCM_TX3CHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	TX3_CH7_MAP TX3 Channel 7 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
27:24	R/W	0x0	TX3_CH6_MAP TX3 Channel 6 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
23:20	R/W	0x0	TX3_CH5_MAP TX3 Channel 5 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
19:16	R/W	0x0	TX3_CH4_MAP TX3 Channel 4 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample

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Offset: 0x0060			Register Name: I2S/PCM_TX3CHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0x0	TX3_CH3_MAP TX3 Channel 3 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
11:8	R/W	0x0	TX3_CH2_MAP TX3 Channel 2 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
7:4	R/W	0x0	TX3_CH1_MAP TX3 Channel 1 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
3:0	R/W	0x0	TX3_CH0_MAP TX3 Channel 0 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample

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9.1.6.26 0x0064 I2S/PCM RX Channel Select Register (Default Value: 0x0000_0000)

Offset: 0x0064			Register Name: I2S/PCM_RXCHSEL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21:20	R/W	0x0	RX_OFFSET RX Offset Tune (RX Data offset to LRCK) 0: No offset n: Data is offset by n BCLKs to LRCK
19:16	R/W	0x0	RX_CHSEL RX Channel (Slot) Number Select for Input 0000: 1 channel or slot ... 0111: 8 channels or slots 1000: 9 channels or slots ... 1111: 16 channels or slots
15:0	/	/	/

9.1.6.27 0x0068 I2S/PCM RX Channel Mapping Register0 (Default Value: 0x0000_0000)

Offset: 0x0068			Register Name: I2S/PCM_RXCHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x0	RX_CH15_SELECT RX Channel 15 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3

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Offset: 0x0068			Register Name: I2S/PCM_RXCHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
27:24	R/W	0x0	RX_CH15_MAP RX Channel 15 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
23:22	/	/	/
21:20	R/W	0x0	RX_CH14_SELECT RX Channel 14 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3
19:16	R/W	0x0	RX_CH14_MAP RX Channel 14 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
15:14	/	/	/
13:12	R/W	0x0	RX_CH13_SELECT RX Channel 13 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3

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Offset: 0x0068			Register Name: I2S/PCM_RXCHMAP0
Bit	**Read/Write**	**Default/Hex**	**Description**
11:8	R/W	0x0	RX_CH13_MAP RX Channel 13 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
7:6	/	/	/
5:4	R/W	0x0	RX_CH12_SELECT RX Channel 12 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3
3:0	R/W	0x0	RX_CH12_MAP RX Channel 12 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample

9.1.6.28 0x006C I2S/PCM RX Channel Mapping Register1 (Default Value: 0x0000_0000)

Offset: 0x006C			Register Name: I2S/PCM_RXCHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x0	RX_CH11_SELECT RX Channel 11 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3

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Offset: 0x006C			Register Name: I2S/PCM_RXCHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
27:24	R/W	0x0	RX_CH11_MAP RX Channel 11 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
23:22	/	/	/
21:20	R/W	0x0	RX_CH10_SELECT RX Channel 10 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3
19:16	R/W	0x0	RX_CH10_MAP RX Channel 10 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
15:14	/	/	/
13:12	R/W	0x0	RX_CH9_SELECT RX Channel 9 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3

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Offset: 0x006C			Register Name: I2S/PCM_RXCHMAP1
Bit	**Read/Write**	**Default/Hex**	**Description**
11:8	R/W	0x0	RX_CH9_MAP RX Channel 9 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample
7:6	/	/	/
5:4	R/W	0x0	RX_CH8_SELECT RX Channel 8 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3
3:0	R/W	0x0	RX_CH8_MAP RX Channel 8 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample … 1111: The sixteenth sample

9.1.6.29 0x0070 I2S/PCM RX Channel Mapping Register2 (Default Value: 0x0000_0000)

Offset: 0x0070			Register Name: I2S/PCM_RXCHMAP2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x0	RX_CH7_SELECT RX Channel 7 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3

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Offset: 0x0070			Register Name: I2S/PCM_RXCHMAP2
Bit	**Read/Write**	**Default/Hex**	**Description**
27:24	R/W	0x0	RX_CH7_MAP RX Channel 7 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
23:22	/	/	/
21:20	R/W	0x0	RX_CH6_SELECT RX Channel 6 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3
19:16	R/W	0x0	RX_CH6_MAP RX Channel 6 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
15:14	/	/	/
13:12	R/W	0x0	RX_CH5_SELECT RX Channel 5 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3

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Offset: 0x0070			Register Name: I2S/PCM_RXCHMAP2
Bit	**Read/Write**	**Default/Hex**	**Description**
11: 8	R/W	0x0	RX_CH5_MAP RX Channel 5 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
7:6	/	/	/
5:4	R/W	0x0	RX_CH4_SELECT RX Channel 4 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3
3:0	R/W	0x0	RX_CH4_MAP RX Channel 4 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

9.1.6.30 0x0074 I2S/PCM RX Channel Mapping Register3 (Default Value: 0x0000_0000)

Offset: 0x0074			Register Name: I2S/PCM_RXCHMAP3
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x0	RX_CH3_SELECT RX Channel 3 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3

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Offset: 0x0074			Register Name: I2S/PCM_RXCHMAP3
Bit	**Read/Write**	**Default/Hex**	**Description**
27:24	R/W	0x0	RX_CH3_MAP RX Channel 3 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
23:22	/	/	/
21:20	R/W	0x0	RX_CH2_SELECT RX Channel 2 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3
19:16	R/W	0x0	RX_CH2_MAP RX Channel 2 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
15:14	/	/	/
13:12	R/W	0x0	RX_CH1_SELECT RX Channel 1 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3

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Offset: 0x0074			Register Name: I2S/PCM_RXCHMAP3
Bit	**Read/Write**	**Default/Hex**	**Description**
11:8	R/W	0x0	RX_CH1_MAP RX Channel 1 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample
7:6	/	/	/
5:4	R/W	0x0	RX_CH0_SELECT RX Channel 0 Select 00: SDI0 01: SDI1 10: SDI2 11: SDI3
3:0	R/W	0x0	RX_CH0_MAP RX Channel 0 Mapping 0000: The first sample … 0111: The eighth sample 1000: The ninth sample ... 1111: The sixteenth sample

9.1.6.31 0x0080 I2S/PCM ASRC MCLK Configuration Register (Default Value: 0x0000_0000)

Offset: 0x0080			Register Name: MCLKCFG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	R	0x0	/
16	R/W	0x0	ASRC_MCLK_GATE ASRC Clock Gate Enable Control 0: Gated 1: Not gated
15:4	/	/	/

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Offset: 0x0080			Register Name: MCLKCFG
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	ASRC_MCLK_FREQ_DIV_COE Frequency Division Coefficient 4'd0 = Res (no output), 4'd1 = 1x, 4'd2 = 1/2x, 4'd3 = 1/4x, 4'd4 = 1/6x, 4'd5 = 1/8x, 4'd6 = 1/12x, 4'd7 = 1/16x, 4'd8 = 1/24x, 4'd9 = 1/32x, 4'd10 = 1/48, 4'd11 = 1/64x, 4'd12 = 1/96x, 4'd13 = 1/128x, 4'd14 = 1/176x, 4'd15 = 1/192x, others = Res

9.1.6.32 0x0084 I2S/PCM ASRC OUT Sample Configuration Register (Default Value: 0x0000_0000)

Offset: 0x0084			Register Name: F_{SOUT}CFG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:21	R	0x0	/
20	R/W	0x0	FSOUT_GATE fsout Clock Gate Enable Control 0: Gated 1: Not gated

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Offset: 0x0084			Register Name: F_{SOUT}CFG
Bit	**Read/Write**	**Default/Hex**	**Description**
19:16	R/W	0x0	FSOUT_CLK_SRC_SEL fsout Clock Source Select 00: I2S0_ASRC_CLK 01: ACLK 10: ACLKM 11: BCLK Others: Reserved
15:8	/	/	/
7:4	R/W	0x0	FSOUT_CLK_FREQ_DIV_COE1 fsout Frequency Division Coefficient 1 The First Division Factor It has two levels of frequency division, the first level is bit[7:4], the second level is bit[3:0], and the frequency division factors are multiplied by the two division factors, the division relationship of the two divisions are the same. 4'd0 = Res (no output), 4'd1 = 1x, 4'd2 = 1/2x, 4'd3 = 1/4x, 4'd4 = 1/6x, 4'd5 = 1/8x, 4'd6 = 1/12x, 4'd7 = 1/16x, 4'd8 = 1/24x, 4'd9 = 1/32x, 4'd10 = 1/48, 4'd11 = 1/64x, 4'd12 = 1/96x, 4'd13 = 1/128x, 4'd14 = 1/176x, 4'd15 = 1/192x

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Offset: 0x0084			Register Name: F_{SOUT}CFG
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	FSOUT_CLK_FREQ_DIV_COE2 fsout Frequency Division Coefficient 2 The Second Division Factor 4'd0 = Res (no output), 4'd1 = 1x, 4'd2 = 1/2x, 4'd3 = 1/4x, 4'd4 = 1/6x, 4'd5 = 1/8x, 4'd6 = 1/12x, 4'd7 = 1/16x, 4'd8 = 1/24x, 4'd9 = 1/32x, 4'd10 = 1/48, 4'd11 = 1/64x, 4'd12 = 1/96x, 4'd13 = 1/128x, 4'd14 = 1/176x, 4'd15 = 1/192x

9.1.6.33 0x0088 I2S/PCM IN Sample Pulse Extend Configuration Register (Default Value: 0x0000_0000)

Offset: 0x0088			Register Name: FsinEXTCFG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	R	0x0	/
16	R/W	0x0	Extend Enable 0: Disabled 1: Enabled Enable the bit when using ASRC.
15:0	R/W	0x0	The Cycle Number of Pulse Extend The cycle is BCLK clock and is 1 at least.

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9.1.6.34 0x008C I2S/PCM ASRC Enable Register (Default Value: 0x0000_0000)

Offset: 0x008C			Register Name: ASRCEN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	R	0x0	/
0	R/W	0x0	ASRC Function Enable 0: Disabled 1: Enabled

9.1.6.35 0x0090 I2S/PCM ASRC Manual Configuration Register (Default Value: 0x0000_0000)

Offset: 0x0090			Register Name: ASRCMANCFG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	ASRC_RATIO_MANUAL_EN Manual Configuration of ASRC Ratio Enable 0: Disabled 1: Enabled
30:26	R	0x0	/
25:0	R/W	0x0	ASRC_RATIO_VALUE_MANUAL_CFG ASRC Ratio Value Manual Configure The ratio value is an unsigned 26-bit number and uses 4.22 data format, which means there are 4 bits to the left of the decimal point and 22 bits to the right of the decimal point.

9.1.6.36 0x0094 I2S/PCM ASRC Ratio State Register (Default Value: 0x0040_0000)

Offset: 0x0094			Register Name: ASRCRATIOSTAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	R	0x0	/
29	R	0x0	ASRC_BUF_OVERFLOW_STA ASRC Receive Data Buffer Overflow State It can control the mute with lock. 0: No overflow 1: Overflow

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Offset: 0x0094			Register Name: ASRCRATIOSTAT
Bit	Read/Write	Default/Hex	Description
28	R	0x0	ADAPT_COMPUT_LOCK Adaptive Ratio Computational Lock 0: Unlocked 1: Locked
27:26	R	0x0	/
25:0	R	0x400000	ADAPT_COMPUT_VALUE Adaptive Ratio Computational Value

9.1.6.37 0x0098 I2S/PCM ASRC FIFO State Register (Default Value: 0x0000_0000)

Offset: 0x0098			Register Name: ASRCFIFOSTAT
Bit	Read/Write	Default/Hex	Description
31:9	/	/	/
8:0	R	0x0	ASRC_RX_FIFO_FULL_LEVAL ASRC RXFIFO Full Level The manually-configured FIFO fill level for the ratio value of the received data.

9.1.6.38 0x009C I2S/PCM MBIST Test Configuration Register (Default Value: 0x0000_0000)

Offset: 0x009C			Register Name: ASRCMBISTCFG
Bit	Read/Write	Default/Hex	Description
31:9	/	/	/
8	R/W	0x0	ASRC_RAM_BIST_EN ASRC RAM BIST Enable Enable the RAM BIST.
7:1	/	/	/
0	R/W	0x0	ASRC_ROM_BIST_EN ASRC ROM BIST Enable Enable the ROM BIST.

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9.1.6.39 0x00A0 I2S/PCM ASRC MBIST Test State Register (Default Value: 0x0000_0002)

Offset: 0x00A0			Register Name: ASRCMBISTSTA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	/	/	/
18	R	0x0	ROM_BIST_ERROR_XOR ROM BIST error xor
17	R	0x0	ROM_BIST_ERROR_SUM ROM BIST error sum
16	R	0x0	ROM_BUSY_STATUS ROM BUSY STATUS 1: ROM busy 0: ROM idle
15:8	/	/	/
7	R	0x0	RAM_BIST_ERR_STATUS RAM BIST error status 1: Error 0: No effect
6:4	R	0x0	RAM_BIST_ERROR_PATTERN. RAM BIST error pattern
3:2	R	0x0	RAM_BIST_ERROR_CYCLE RAM BIST error cycle
1	R	0x1	RAM_STOP_STATUS RAM stop status 1: Stop 0: Running
0	R	0x0	RAM_BUSY_STATUS RAM busy status 1: RAM busy 0: RAM idle

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9.2 DMIC

9.2.1 Overview

The DMIC controller supports one 8-channel digital microphone interface and can output 128 fs or 64 fs (fs = ADC sample rate).

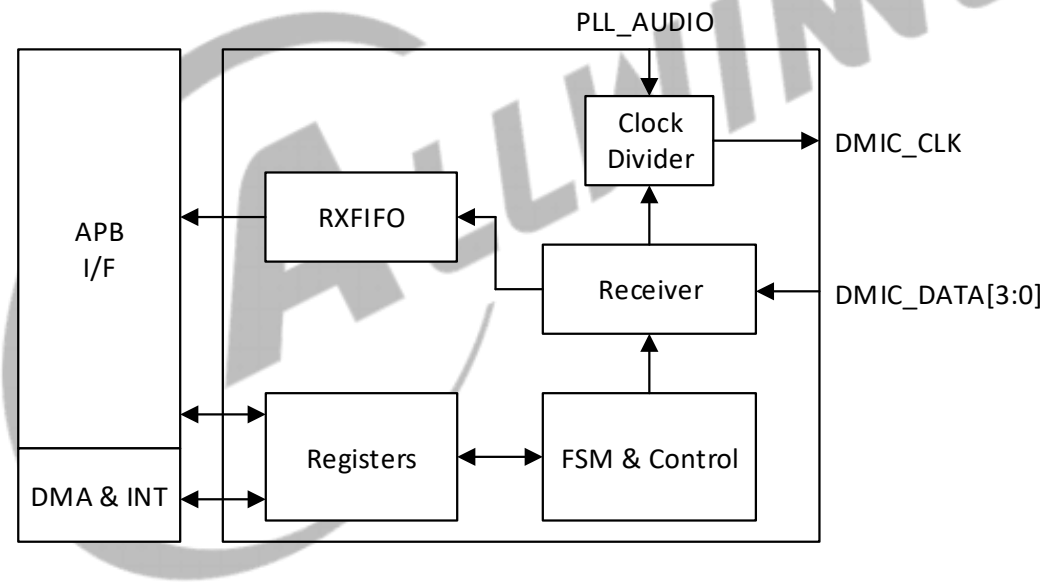
The DMIC controller includes the following features:

- Supports up to 8 channels
- Sample rate from 8 kHz to 48 kHz

9.2.2 Block Diagram

The following figure shows a block diagram of the DMIC.

Figure 9-12 DMIC Block Diagram



9.2.3 Functional Description

9.2.3.1 External Signals

The following table describes the external signals of DMIC.

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Table 9-5 DMIC External Signals

Signal	Description	Type
DMIC-CLK	Digital Microphone Clock Output	O
DMIC-DATA0	Digital Microphone Data Input	I
DMIC-DATA1	Digital Microphone Data Input	I
DMIC-DATA2	Digital Microphone Data Input	I
DMIC-DATA3	Digital Microphone Data Input	I

9.2.3.2 Clock Sources

The following table describes the clock source for DMIC. For clock setting, configurations, and gating information, refer to section 3.3 "CCU".

Table 9-6 DMIC Clock Sources

Clock Sources	Description
PLL_AUDIO0(1X)	By default, PLL_AUDIO0(1X) is 24.5714 MHz.
PLL_AUDIO1(DIV2)	By default, PLL_AUDIO1 is 3072 MHz, PLL_AUDIO1(DIV2) is 1536 MHz, and PLL_AUDIO1(DIV5) is 614.4 MHz (24.576 MHz*25).
PLL_AUDIO1(DIV5)	

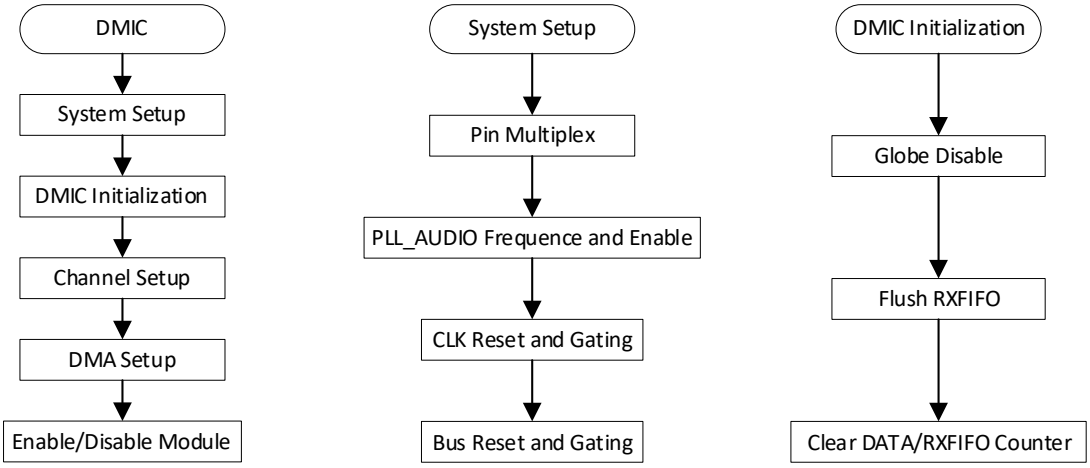
9.2.3.3 Operation Mode

The software operation of the DMIC is divided into five steps: system setup, DMIC initialization, channel setup, DMA setup, and Enable/Disable module.

The following figure shows the flow chart of the whole operation, the system setup, and the DMIC initialization.

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Figure 9-13 DMIC Operation Mode



1. System Setup and DMIC Initialization

The first step in the system setup is properly programming the GPIO because the DMIC port is a multiplex pin. For functions of the multiplex pins, refer to the pin multiplex specification.

Perform the following steps for the clock source. Firstly, disable the PLL_AUDIO through PLL_AUDIOx Control Register[PLL_ENABLE]. Secondly, set up the frequency of the PLL_AUDIO in PLL_AUDIOx Control Register. Then enable PLL_AUDIO. After that, enable the DMIC gating through **DMIC_CLK_REG** when you checkout that the LOCK bit of PLL_AUDIOx Control Register becomes 1. At last, reset and enable the DMIC bus gating by **DMIC_BGR_REG**.

After the system setup, the register of DMIC can be setup. Firstly, initialize the DMIC. You should close the globe enable bit (**DMIC_EN**[8]), data channel enable bit (**DMIC_EN**[7:0]) by writing 0 to it. After that, flush the RXFIFO by writing 1 to **DMIC_RXFIFO_CTR**[31]. At last, you can clear the Data/RXFIFO counter by writing 1 to **DMIC_RXFIFO_STA**, **DMIC_CNT**.

2. Channel Setup and DMA Setup

You can set up the sample rate, the sample resolution, the over-sample rate, the channel number, the RXFIFO output mode, the RXFIFO trigger level, and so on. The setup of the register can be found in the specification.

The DMIC supports two methods to transfer the data. The most common way is DMA, the setup of DMA can be found in section 3.9 “DMAC”. In this module, you just enable the DRQ.

3. Enable and Disable DMIC

To enable the function, you can enable the data channel enable bit (**DMIC_EN**[7:0]) by writing 1 to it. After that, enable DMIC by writing 1 to the Globe Enable bit (**DMIC_EN**[8]). Write 0 to **DMIC_EN**[8] to disable DMIC.

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9.2.4 Register List

Module Name	Base Address
DMIC	0x02031000

Register Name	Offset	Description
DMIC_EN	0x0000	DMIC Enable Control Register
DMIC_SR	0x0004	DMIC Sample Rate Register
DMIC_CTR	0x0008	DMIC Control Register
DMIC_DATA	0x0010	DMIC Data Register
DMIC_INTC	0x0014	DMIC Interrupt Control Register
DMIC_INTS	0x0018	DMIC Interrupt Status Register
DMIC_RXFIFO_CTR	0x001C	DMIC RXFIFO Control Register
DMIC_RXFIFO_STA	0x0020	DMIC RXFIFO Status Register
DMIC_CH_NUM	0x0024	DMIC Channel Numbers Register
DMIC_CH_MAP	0x0028	DMIC Channel Mapping Register
DMIC_CNT	0x002C	DMIC Counter Register
DATA0_DATA1_VOL_CTR	0x0030	Data0 and Data1 Volume Control Register
DATA2_DATA3_VOL_CTR	0x0034	Data2 And Data3 Volume Control Register
HPF_EN_CTR	0x0038	High Pass Filter Enable Control Register
HPF_COEF_REG	0x003C	High Pass Filter Coefficient Register
HPF_GAIN_REG	0x0040	High Pass Filter Gain Register

9.2.5 Register Description

9.2.5.1 0x0000 DMIC Enable Control Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: DMIC_EN
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/

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Offset: 0x0000			Register Name: DMIC_EN
Bit	**Read/Write**	**Default/Hex**	**Description**
29	R/W	0x0	RX_SYNC_EN_START Audio Subsys RX Synchronize Enable Start Includes Audio codec/I2S0/I2S1/I2S2/DMIC. The bit takes effect only when RX_SYNC_EN is set to 1. 0: Disabled 1: Enabled
28	R/W	0x0	RX_SYNC_EN DMIC RX Synchronize Enable 0: Disabled 1: Enabled
27:9	/	/	/
8	R/W	0x0	GLOBE_EN DMIC Globe Enable 0: Disabled 1: Enabled
7	R/W	0x0	DATA3_CHR_EN DATA3 Right Channel Enable 0: Disabled 1: Enabled
6	R/W	0x0	DATA3_CHL_EN DATA3 Left Channel Enable 0: Disabled 1: Enabled
5	R/W	0x0	DATA2_CHR_EN DATA2 Right Channel Enable 0: Disabled 1: Enabled
4	R/W	0x0	DATA2_CHL_EN DATA2 Left Channel Enable 0: Disabled 1: Enabled
3	R/W	0x0	DATA1_CHR_EN DATA1 Right Channel Enable 0: Disabled 1: Enabled

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Offset: 0x0000			Register Name: DMIC_EN
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	DATA1_CHL_EN DATA1 Left Channel Enable 0: Disabled 1: Enabled
1	R/W	0x0	DATA0_CHR_EN DATA0 Right Channel Enable 0: Disabled 1: Enabled
0	R/W	0x0	DATA0_CHL_EN DATA0 Left Channel Enable 0: Disabled 1: Enabled

9.2.5.2 0x0004 DMIC Sample Rate Register (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: DMIC_SR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/
2:0	R/W	0x0	DMIC_SR Sample Rate of DMIC 000: 48 kHz 010: 24 kHz 100: 12 kHz 110: Reserved 001: 32 kHz 011: 16 kHz 101: 8 kHz 111: Reserved 44.1 kHz/22.05 kHz/11.025 kHz can be supported by Audio PLL Configure Bit.

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9.2.5.3 0x0008 DMIC Control Register (Default Value: 0x0000_0000)

Offset: 0x0008			Register Name: DMIC_CTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:11	/	/	/
10:9	R/W	0x0	DMICFDT DMIC RXFIFO Delay Time for Writing Data after GLOBE_EN 00: 5 ms 01: 10 ms 10: 20 ms 11: 30 ms
8	R/W	0x0	DMICDFEN DMIC RXFIFO Delay Function for Writing Data after GLOBE_EN 0: Disabled 1: Enabled
7	R/W	0x0	DATA3 Left Data and Right Data Swap Enable 0: Disabled 1: Enabled
6	R/W	0x0	DATA2 Left Data and Right Data Swap Enable 0: Disabled 1: Enabled
5	R/W	0x0	DATA1 Left Data and Right Data Swap Enable 0: Disabled 1: Enabled
4	R/W	0x0	DATA0 Left Data and Right Data Swap Enable 0: Disabled 1: Enabled
3:1	/	/	/
0	R/W	0x0	DMIC Oversample Rate 0: 128 (Supports 8 kHz to 24 kHz) 1: 64 (Supports 16 kHz to 48 kHz)

9.2.5.4 0x0010 DMIC DATA Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: DMIC_DATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	DMIC_DATA

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9.2.5.5 0x0014 DMIC Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0014			Register Name: DMIC_INTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/
2	R/W	0x0	RXFIFO_DRQ_EN DMIC RXFIFO Data Available DRQ Enable 0: Disabled 1: Enabled
1	R/W	0x0	RXFIFO_OVERRUN_IRQ_EN DMIC RXFIFO Overrun IRQ Enable 0: Disabled 1: Enabled
0	R/W	0x0	DATA_IRQ_EN DMIC RXFIFO Data Available IRQ Enable 0: Disabled 1: Enabled

9.2.5.6 0x0018 DMIC Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: DMIC_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R/W1C	0x0	RXFIFO_OVERRUN_IRQ_PENDING DMIC RXFIFO Overrun Pending Interrupt 0: No pending IRQ 1: RXFIFO overrun pending IRQ Writing '1' to clear this interrupt or automatically clear if the interrupt condition fails.
0	R/ W1C	0x0	RXFIFO_DATA_IRQ_PENDING DMIC RXFIFO Data Available Pending Interrupt 0: No pending IRQ 1: Data available pending IRQ Writing '1' to clear this interrupt or automatically clear if the interrupt condition fails.

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9.2.5.7 0x001C DMIC RXFIFO Control Register (Default Value: 0x0000_0040)

Offset: 0x001C			Register Name: DMIC_RXFIFO_CTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W1C	0x0	DMIC_RXFIFO_FLUSH DMIC RXFIFO Flush Writing '1' to flush RXFIFO, self clear to '0'
30:10	/	/	/
9	R/W	0x0	RXFIFO_MODE RXFIFO Output Mode (Mode 0, 1) 0: Expanding '0' at LSB of RXFIFO register 1: Expanding received sample sign bit at MSB of RXFIFO register For 24-bit received audio sample: Mode 0: RXDATA[31:0] = {RXFIFO_O[20:0], 11'h0} Mode 1: RXDATA[31:0] = {8{RXFIFO_O[20]}, RXFIFO_O[20:0], 3'h0} For 16-bit received audio sample: Mode 0: RXDATA[31:0] = {RXFIFO_O[20:5], 16'h0} Mode 1: RXDATA[31:0] = {16{RXFIFO_O[20]}, RXFIFO_O[20:5]}
8	R/W	0x0	Sample_Resolution 0: 16-bit 1: 24- bit
7:0	R/W	0x40	RXFIFO_TRG_LEVEL RXFIFO Trigger Level (TRLV[7:0]) Interrupt and DMA request trigger level for DMIC RXFIFO normal condition IRQ/DRQ Generated when WLEVEL > TRLV[7:0]) WLEVEL represents the number of valid samples in the DMIC RXFIFO

9.2.5.8 0x0020 DMIC RXFIFO Status Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: DMIC_RXFIFO_STA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:9	/	/	/
8	R	0x1	Reserved

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Offset: 0x0020			Register Name: DMIC_RXFIFO_STA
Bit	Read/Write	Default/Hex	Description
7:0	R/W	0x0	DMIC_DATA_CNT DMIC RXFIFO Available Sample Word Counter

9.2.5.9 0x0024 DMIC Channel Numbers Register (Default Value: 0x0000_0001)

Offset: 0x0024			Register Name: DMIC_CH_NUM
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2:0	R/W	0x1	DMIC_CH_NUM DMIC enable channel numbers are (N + 1).

9.2.5.10 0x0028 DMIC Channel Mapping Register (Default Value: 0x7654_3210)

Offset: 0x0028			Register Name: DMIC_CH_MAP
Bit	Read/Write	Default/Hex	Description
31:28	R/W	0x7	DMIC_CH7_MAP DMIC Channel 7 Mapping 0000: DATA0 Left Channel 0001: DATA0 Right Channel 0010: DATA1 Left Channel 0011: DATA1 Right Channel 0100: DATA2 Left Channel 0101: DATA2 Right Channel 0110: DATA3 Left Channel 0111: DATA3 Right Channel

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Offset: 0x0028			Register Name: DMIC_CH_MAP
Bit	**Read/Write**	**Default/Hex**	**Description**
27:24	R/W	0x6	DMIC_CH6_MAP DMIC Channel 6 Mapping 0000: DATA0 Left Channel 0001: DATA0 Right Channel 0010: DATA1 Left Channel 0011: DATA1 Right Channel 0100: DATA2 Left Channel 0101: DATA2 Right Channel 0110: DATA3 Left Channel 0111: DATA3 Right Channel
23:20	R/W	0x5	DMIC_CH5_MAP DMIC Channel 5 Mapping 0000: DATA0 Left Channel 0001: DATA0 Right Channel 0010: DATA1 Left Channel 0011: DATA1 Right Channel 0100: DATA2 Left Channel 0101: DATA2 Right Channel 0110: DATA3 Left Channel 0111: DATA3 Right Channel
19:16	R/W	0x4	DMIC_CH4_MAP DMIC Channel 4 Mapping 0000: DATA0 Left Channel 0001: DATA0 Right Channel 0010: DATA1 Left Channel 0011: DATA1 Right Channel 0100: DATA2 Left Channel 0101: DATA2 Right Channel 0110: DATA3 Left Channel 0111: DATA3 Right Channel

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Offset: 0x0028			Register Name: DMIC_CH_MAP
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0x3	DMIC_CH3_MAP DMIC Channel 3 Mapping 0000: DATA0 Left Channel 0001: DATA0 Right Channel 0010: DATA1 Left Channel 0011: DATA1 Right Channel 0100: DATA2 Left Channel 0101: DATA2 Right Channel 0110: DATA3 Left Channel 0111: DATA3 Right Channel
11:8	R/W	0x2	DMIC_CH2_MAP DMIC Channel 2 Mapping 0000: DATA0 Left Channel 0001: DATA0 Right Channel 0010: DATA1 Left Channel 0011: DATA1 Right Channel 0100: DATA2 Left Channel 0101: DATA2 Right Channel 0110: DATA3 Left Channel 0111: DATA3 Right Channel
7:4	R/W	0x1	DMIC_CH1_MAP DMIC Channel 1 Mapping 0000: DATA0 Left Channel 0001: DATA0 Right Channel 0010: DATA1 Left Channel 0011: DATA1 Right Channel 0100: DATA2 Left Channel 0101: DATA2 Right Channel 0110: DATA3 Left Channel 0111: DATA3 Right Channel

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Offset: 0x0028			Register Name: DMIC_CH_MAP
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	DMIC_CH0_MAP DMIC Channel0 Mapping 0000: DATA0 Left Channel 0001: DATA0 Right Channel 0010: DATA1 Left Channel 0011: DATA1 Right Channel 0100: DATA2 Left Channel 0101: DATA2 Right Channel 0110: DATA3 Left Channel 0111: DATA3 Right Channel

9.2.5.11 0x002C DMIC Counter Register (Default Value: 0x0000_0000)

Offset: 0x002C			Register Name: DMIC_CNT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	DMIC_CNT RX Sample Counter The audio sample number of writing into RXFIFO. When one sample is read by Digital Audio Engine, the RX sample counter register increases by one. The RX sample counter register can be set to any initial valve at any time. After being updated by the initial value, the counter register should count on the base of this initial value. **Note: It is used for Audio/Video Synchronization.**

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9.2.5.12 0x0030 DATA0 and DATA1 Volume Control Register (Default Value: 0xA0A0_A0A0)

Offset: 0x0030			Register Name: DATA0_DATA1_VOL_CTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	R/W	0xA0	DATA1L_VOL Data1 Left Channel Volume Control (-119.25 dB to 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB
23:16	R/W	0xA0	DATA1R_VOL Data1 Right Channel Volume Control (-119.25 dB to 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB
15:8	R/W	0xA0	DATA0L_VOL Data0 Left Channel Volume Control (-119.25 dB to 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB

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Offset: 0x0030			Register Name: DATA0_DATA1_VOL_CTR
Bit	**Read/Write**	**Default/Hex**	**Description**
7:0	R/W	0xA0	DATA0R_VOL Data0 Right Channel Volume Control (-119.25 dB to 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB

9.2.5.13 0x0034 DATA2 and DATA3 Volume Control Register (Default Value: 0xA0A0_A0A0)

Offset: 0x0034			Register Name: DATA2_DATA3_VOL_CTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	R/W	0xA0	DATA3L_VOL Data3 Light Channel Volume Control (-119.25 dB to 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB

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Offset: 0x0034			Register Name: DATA2_DATA3_VOL_CTR
Bit	**Read/Write**	**Default/Hex**	**Description**
23:16	R/W	0xA0	DATA3R_VOL Data3 Right Channel Volume Control (-119.25 dB to 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB
15:8	R/W	0xA0	DATA2L_VOL Data2 Light Channel Volume Control (-119.25 dB to 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB
7:0	R/W	0xA0	DATA2R_VOL Data2 Right Channel Volume Control (-119.25 dB to 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB

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9.2.5.14 0x0038 High Pass Filter Enable Control Register (Default Value: 0x0000_0000)

Offset: 0x0038			Register Name: HPF_EN_CTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	HPF_DATA3_CHR_EN High Pass Filter DATA3 Right Channel Enable 0: Disabled 1: Enabled
6	R/W	0x0	HPF_DATA3_CHL_EN High Pass Filter DATA3 Left Channel Enable 0: Disabled 1: Enabled
5	R/W	0x0	HPF_DATA2_CHR_EN High Pass Filter DATA2 Right Channel Enable 0: Disabled 1: Enabled
4	R/W	0x0	HPF_DATA2_CHL_EN High Pass Filter DATA2 Left Channel Enable 0: Disabled 1: Enabled
3	R/W	0x0	HPF_DATA1_CHR_EN High Pass Filter DATA1 Right Channel Enable 0: Disabled 1: Enabled
2	R/W	0x0	HPF_DATA1_CHL_EN High Pass Filter DATA1 Left Channel Enable 0: Disabled 1: Enabled
1	R/W	0x0	HPF_DATA0_CHR_EN High Pass Filter DATA0 Right Channel Enable 0: Disabled 1: Enabled
0	R/W	0x0	HPF_DATA0_CHL_EN High Pass Filter DATA0 Left Channel Enable 0: Disabled 1: Enabled

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9.2.5.15 0x003C High Pass Filter Coefficient Register (Default Value: 0x00FF_AA45)

Offset: 0x003C			Register Name: HPF_COEF_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x00FFAA45	HPF_COE High Pass Filter Coefficient

9.2.5.16 0x0040 High Pass Filter Gain Register (Default Value: 0x00FF_D522)

Offset: 0x0040			Register Name: HPF_GAIN_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x00FFD522	HPF_GAIN High Pass Filter Gain

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9.3 OWA

9.3.1 Overview

The One Wire Audio (OWA) provides a serial bus interface for audio data. This interface is widely used for consumer audio.

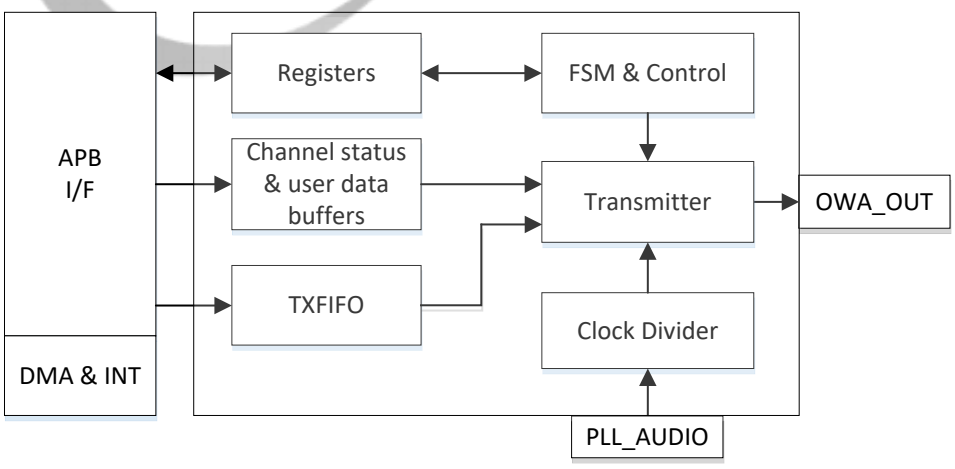
The OWA includes the following features:

- One OWA TX
- Compliance with S/PDIF interface
- IEC-60958 transmitter functionality
- Supports 16-bit, 20-bit, and 24-bit data formats
- One 128×24bits TXFIFO for audio data transfer
- Programmable FIFO thresholds
- Supports TX DMA slave interface
- Function clock includes 24.576 MHz and 22.579 MHz frequency
- Hardware parity generation on the transmitter
- Supports channel status insertion for the transmitter
- Supports interrupts and DMA

9.3.2 Block Diagram

The following figure shows the OWA block diagram.

Figure 9-14 OWA Block Diagram



OWA contains the following sub-blocks:

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Table 9-7 OWA Sub-blocks

Sub-block	Description
Registers	Analyze the configuration parameter, DMA requests, and IRQ feedbacks.
Transmitter	Sends the data
FSM	Finite state machine
Clock Divider	Clock divider circuit

9.3.3 Functional Description

9.3.3.1 External Signals

The OWA is a Biphase-Mark Encoding Digital Audio Transfer protocol. In this protocol, the CLK signal and data signal are transferred in the same line. The following figure describes the external signals of OWA. OWA-OUT is the output pin for the output CLK and DATA.

Table 9-8 OWA External Signals

Signal Name	Description	Type
OWA-OUT	OWA output	O

9.3.3.2 Clock Sources

The following tables describe the clock sources for OWA. For clock setting, configurations and gating information, refer to section 3.3 "CCU".

Table 9-9 OWA_TX Clock Sources

Clock Name	Description
PLL_AUDIO0(1X)	By default, PLL_AUDIO0(1X) is 24.5714 MHz, and PLL_AUDIO0(4X) is 98.2856 MHz.
PLL_AUDIO0(4X)	
PLL_AUDIO1(DIV2)	By default, PLL_AUDIO1 is 3072 MHz, PLL_AUDIO1(DIV2) is 1536 MHz, and PLL_AUDIO1(DIV5) is 614.4 MHz (24.576 MHz*25).
PLL_AUDIO1(DIV5)	

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9.3.3.3 Biphase-Mark Code (BMC)

In the OWA format, the digital signal is coded using the biphase-mark code (BMC). The clock, frame, and data are embedded in only one signal—the data pin. In the BMC system, each data bit is encoded into two logical states (00, 01, 10, or 11) at the pin. The following figure and table show how data is encoded to the BMC format.

The frequency of the clock is twice the data bit rate, as shown in the following figure. Also, the clock is always programmed to 128 x fs, where fs is the sample rate. The device receiving in the OWA format can recover the clock and frame information from the BMC signal.

Figure 9-15 OWA Biphase-Mark Code

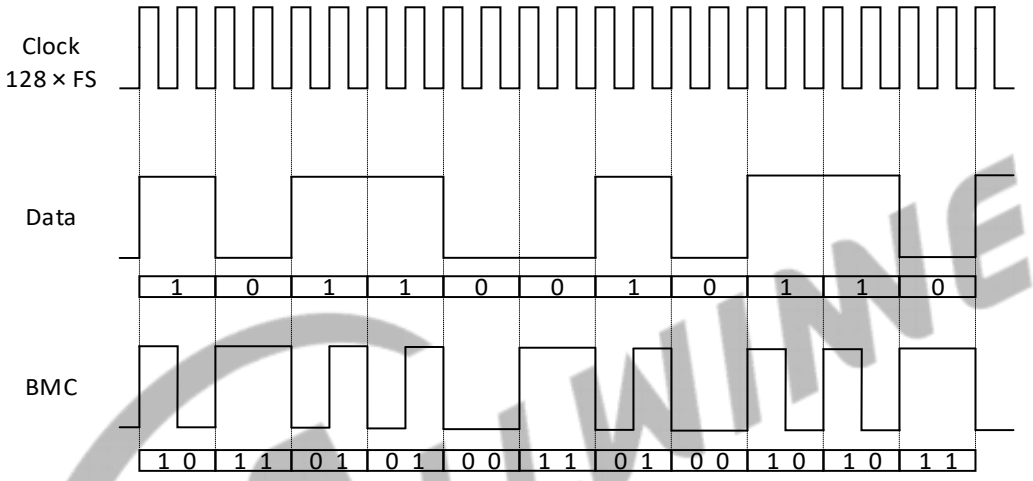


Table 9-10 Biphase-Mark Encoder

Data	Previous State	BMC
0	0	11
0	1	00
1	0	10
1	1	01

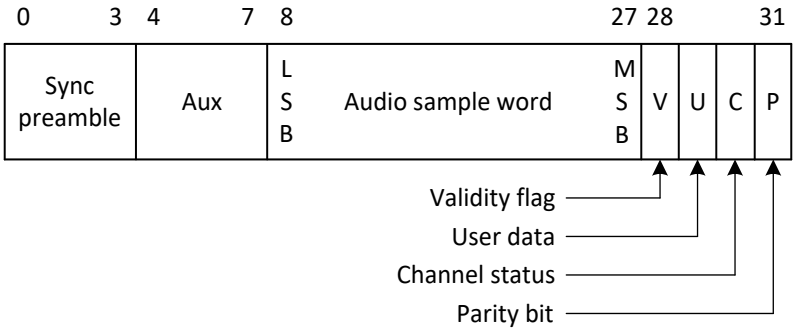
9.3.3.4 IEC60958 Transmit Format

The OWA supports digital audio data transfer.

Every audio sample transmitted in a sub-frame consists of 32-bit, numbered from 0 to 31. The following figure shows a sub-frame.

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Figure 9-16 OWA Sub-Frame Format



Bits 0-3 carry one of the four permitted preambles to signify the type of audio sample in the current sub-frame. The preamble is not encoded in BMC format, and therefore the preamble code can contain more than two consecutive 0 or 1 logical states in a row.

Bits 4-27 carry the audio sample word in linear 2s-complement representation. The most-significant bit (MSB) is carried by bit 27. When a 24-bit coding range is used, the least-significant bit (LSB) is in bit 4. When a 20-bit coding range is used, bit[8:27] carry the audio sample word with the LSB in bit 8. Bit[4:7] may be used for other applications and are designated auxiliary sample bits.

If the source provides fewer bits than the interface allows (either 20 or 24), the unused LSBs are set to logical 0. For a nonlinear PCM audio application or a data application, the main data field may carry any other information.

Bit 28 carries the validity bit (V) associated with the main data field in the sub-frame.

Bit 29 carries the user data channel (U) associated with the main data field in the sub-frame.

Bit 30 carries the channel status information (C) associated with the main data field in the sub-frame. The channel status indicates if the data in the sub-frame is a digital audio or some other type of data.

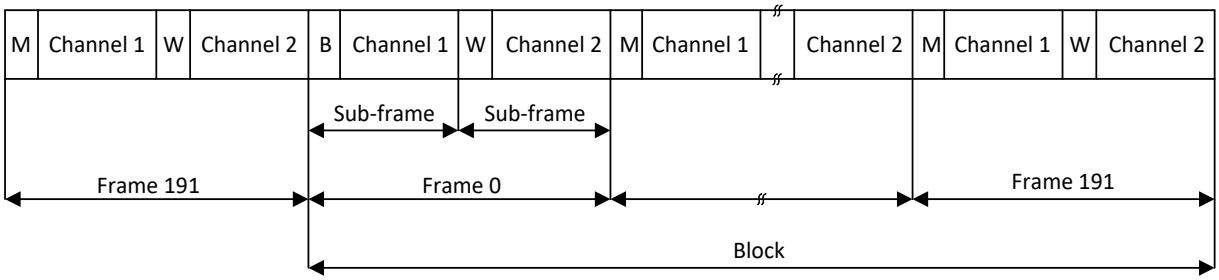
Bit 31 carries a parity bit (P) such that bit 4-31 carry an even number of 1s and an even number of 0s (even parity). As shown in the following table, the preambles (bit 0-3) are also defined with even parity.

Table 9-11 Preamble Codes

Preamble Code	Previous Logical State	Logical State	Description
B (or Z)	0	1110 1000	Start of a block and sub-frame 1
M (or X)	0	1110 0010	Sub-frame 1
W (or Y)	0	1110 0100	Sub-frame 2

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Figure 9-17 OWA Frame/Block Format



9.3.3.5 Audio Sample Ratio Detection

The sampling rate is calculated according to the data pulse back-stepping method. In the first phase lock of the CDR, find 1 Frame period, count by using the high-speed sampling clock, and read the counting value of the pulse, then the sampling rate can be calculated.

Table 9-12 The Corresponding Relation between Different System Clock and Sample Ratio

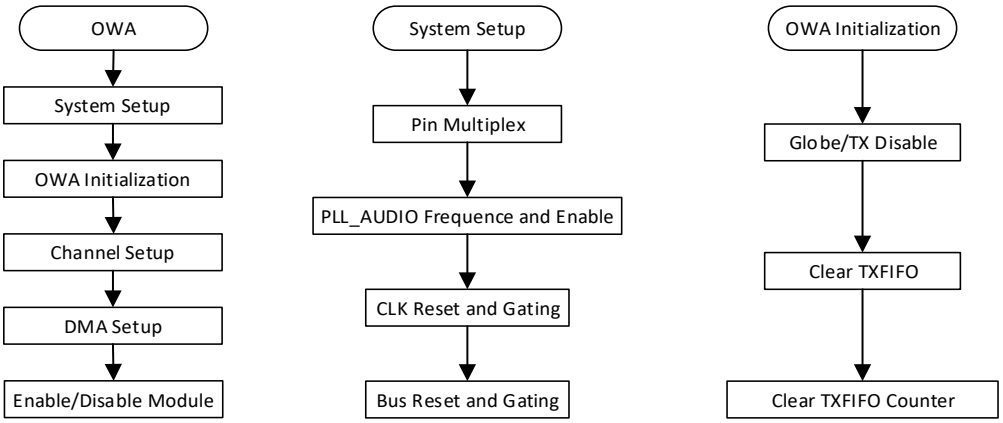
	Sample Clock Cycles	
TX Sample Rate(kHz)	**196.608 MHz-SysClk**	**200 MHz-SysClk**
22.05	8916(±5)	9070(±5)
24	8192(±5)	8333(±5)
32	6144(±5)	6250(±5)
44.1	4458(±5)	4535(±5)
48	4096(±5)	4166(±5)
96	2048(±5)	2083(±5)
176.4	1114(±5)	1133(±5)
192	1024(±5)	1041(±5)

9.3.3.6 Operation Modes

The software operation of the OWA is divided into five steps: system setup, OWA initialization, channel setup, DMA setup and enable/disable module. The following sections describe these five steps.

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Figure 9-18 OWA Operation Flow



1. System Setup and OWA Initialization

The first step in the OWA initialization is properly programming the GPIO because the OWA port is a multiplex pin. You can find the function in section 9.7 "GPIO".

The clock source for the OWA should be followed. Firstly, reset the audio PLL in PLL_AUDIOx Control Register. Secondly, set up the frequency of the Audio PLL in the PLL_AUDIOx Control Register. After that, enable the OWA gating. Lastly, enable the OWA bus gating.

After the system setup, the register of OWA can be set up. Firstly, reset the OWA by writing 1 to **OWA_CTL**[0] and clear the TX FIFO by writing 1 to **OWA_FCTL**[17:16]. After that, enable the globe enable bit by writing 1 to **OWA_CTL**[1] and clear the interrupt and TX counter by setting **OWA_ISTA** and **OWA_TX_CNT**.

2. Channel Setup and DMA Setup

You can set up the audio type, clock divider ratio, the sample format, and the trigger level, and so on. The setup of the register can be found in the specification.

The OWA supports two methods to transfer the data. The most common way is DMA, the configuration of DMA can be found in section 3.9 "DMAC". In this module, you just enable the DRQ in **OWA_INT**[7].

3. Enable and Disable OWA

To enable the function, you can enable TX by writing **OWA_TX_CFIG**[31]. After that, enable OWA by writing 1 to **OWA_CTL**[1]. Writing 0 to **OWA_CTL**[1] to disable process.

9.3.4 Register List

Module Name	Base Address
OWA	0x02036000

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Register Name	Offset	Description
OWA_GEN_CTL	0x0000	OWA General Control Register
OWA_TX_CFIG	0x0004	OWA TX Configuration Register
OWA_ISTA	0x000C	OWA Interrupt Status Register
OWA_FCTL	0x0014	OWA FIFO Control Register
OWA_FSTA	0x0018	OWA FIFO Status Register
OWA_INT	0x001C	OWA Interrupt Control Register
OWA_TX_FIFO	0x0020	OWA TX FIFO Register
OWA_TX_CNT	0x0024	OWA TX Counter Register
OWA_TX_CHSTA0	0x002C	OWA TX Channel Status Register0
OWA_TX_CHSTA1	0x0030	OWA TX Channel Status Register1

9.3.5 Register Description

9.3.5.1 0x0000 OWA General Control Register (Default Value: 0x0000_0080)

Offset: 0x0000			Register Name: OWA_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R	0x1	Reserved
6:2	/	/	/
1	R/W	0x0	GEN Global Enable Disabling this bit overrides the operations of enabling and flushing all FIFOs by any other blocks or channels. 0: Disabled 1: Enabled
0	R/W	0x0	RST_TX Reset TX 0: Normal 1: Reset Self clear to 0.

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9.3.5.2 0x0004 OWA TX Configure Register (Default Value: 0x0000_00F0)

Offset: 0x0004			Register Name: OWA_TX_CFIG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	TX_SINGLE_MODE Tx Single Channel Mode 0: Disabled 1: Enabled
30:18	/	/	/
17	R/W	0x0	ASS Audio Sample Select when TX FIFO Underrun 0: Sending 0 1: Sending the last audio **Note: This bit is only valid in PCM mode.**
16	R/W	0x0	TX_AUDIO TX Data Type 0: Linear PCM (Valid bit of both sub-frame set to 0) 1: Non-audio (Valid bit of both sub-frame set to 1)
15:9	/	/	/
8:4	R/W	0xF	TX_RATIO TX Clock Divide Ratio Clock divide ratio = TX_TATIO + 1 Fs = PLL_AUDIO/[(TX_TATIO + 1)*64*2]
3:2	R/W	0x0	TX_SF TX Sample Format 00: 16 bits 01: 20 bits 10: 24 bits 11: Reserved
1	R/W	0x0	TX_CHM CHSTMODE 0: Channel status A and B set to 0 1: Channel status A and B generated from TX_CHSTA
0	R/W	0x0	TXEN TX Enable 0: Disabled 1: Enabled

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9.3.5.3 0x000C OWA Interrupt Status Register (Default Value: 0x0000_0010)

Offset: 0x000C			Register Name: OWA_ISTA
Bit	Read/Write	Default/Hex	Description
31:7	/	/	/
6	R/W1C	0x0	TXU_INT TX FIFO Underrun Pending Interrupt 0: No Pending IRQ 1: FIFO Underrun Pending Interrupt Writing “1” to clear this interrupt.
5	R/W1C	0x0	TXO_INT TX FIFO Overrun Pending Interrupt 0: No Pending IRQ 1: FIFO Overrun Pending Interrupt Writing “1” to clear this interrupt.
4	R/W1C	0x1	TXE_INT TX FIFO Empty Pending Interrupt 0: No Pending IRQ 1: FIFO Empty Pending Interrupt Writing “1” to clear this interrupt or automatically clear if the interrupt condition fails.
3:0	/	/	/

9.3.5.4 0x0014 OWA FIFO Control Register (Default Value: 0x0004_0200)

Offset: 0x0014			Register Name: OWA_FCTL
Bit	Read/Write	Default/Hex	Description
31	R/W	0x0	HUB_EN Audio Hub Enable The bit takes effect only when the TXEN is set to 1. Audio codec/I2S0/I2S1/I2S2/OWA TXFIFO Hub Enable. 0: Disabled 1: Enabled
30	R/W1C	0x0	FTX Write ‘1’ to flush TXFIFO, self clear to ‘0’.
29:20	/	/	/

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Offset: 0x0014			Register Name: OWA_FCTL
Bit	Read/Write	Default/Hex	Description
19:12	R/W	0x40	TXTL TX FIFO Empty Trigger Level Interrupt and DMA request trigger level for TX FIFO normal condition. Trigger Level = TXTL
11:3	/	/	/
2	R/W	0x0	TXIM TXFIFO Input Mode (Mode0, 1) 0: Valid data at the MSB of TXFIFO Register 1: Valid data at the LSB of TXFIFO Register Example for 20-bit transmitted audio sample: Mode 0: TXFIFO[23:0] = {APB_WDATA[31:12], 4'h0} Mode 1: TXFIFO[23:0] = {APB_WDATA[19:0], 4'h0}
1:0	/	/	/

9.3.5.5 0x0018 OWA FIFO Status Register (Default Value: 0x8080_0000)

Offset: 0x0018			Register Name: OWA_FSTA
Bit	Read/Write	Default/Hex	Description
31	R	0x1	TXE TXFIFO Empty (indicate the TXFIFO is not full) 0: No room for new sample in TXFIFO 1: More than one room for new sample in TXFIFO (>= 1 Word)
30:24	/	/	/
23:16	R	0x80	TXE_CNT TXFIFO Empty Space Word Counter
15:0	/	/	/

9.3.5.6 0x001C OWA Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: OWA_INT
Bit	Read/Write	Default/Hex	Description
31:8	/	/	/

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Offset: 0x001C			Register Name: OWA_INT
Bit	**Read/Write**	**Default/Hex**	**Description**
7	R/W	0x0	TX_DRQ TXFIFO Empty DRQ Enable 0: Disabled 1: Enabled
6	R/W	0x0	TXUI_EN TXFIFO Underrun Interrupt Enable 0: Disabled 1: Enabled
5	R/W	0x0	TXOI_EN TXFIFO Overrun Interrupt Enable 0: Disabled 1: Enabled
4	R/W	0x0	TXEI_EN TXFIFO Empty Interrupt Enable 0: Disabled 1: Enabled
3:0	/	/	/

9.3.5.7 0x0020 OWA TX FIFO Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: OWA_TXFIFO
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	W	0x0	TX_DATA Transmitting A, B channel data should be written this register one by one. A channel data is first, and then the B channel data.

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9.3.5.8 0x0024 OWA TX Counter Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: OWA_TX_CNT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TX_CNT TX Sample Counter The audio sample number of sending into TXFIFO. When one sample is put into TXFIFO by DMA or by host IO, the TX sample counter register increases by one. The TX sample counter register can be set to any initial value at any time. After updated by the initial value, the counter register should count on the base of this initial value.

9.3.5.9 0x002C OWA TX Channel Status Register0 (Default Value: 0x0000_0000)

Offset: 0x002C			Register Name: OWA_TX_CHSTA0
Bit	**Read/Write**	**Default/Hex**	**Description**
31: 30	/	/	/
29:28	R/W	0x0	CA Clock Accuracy 00: Level 2 01: Level 1 10: Level 3 11: Not matched

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Offset: 0x002C			Register Name: OWA_TX_CHSTA0
Bit	**Read/Write**	**Default/Hex**	**Description**
27:24	R/W	0x0	FREQ Sampling Frequency 0000: 44.1 kHz 0001: Not indicated 0010: 48 kHz 0011: 32 kHz 0100: 22.05 kHz 0101: Reserved 0110: 24 kHz 0111: Reserved 1000: Reserved 1001: 768 kHz 1010: 96 kHz 1011: Reserved 1100: 176.4 kHz 1101: Reserved 1110: 192 kHz 1111: Reserved
23:20	R/W	0x0	CN Channel Number
19:16	R/W	0x0	SN Source Number
15:8	R/W	0x0	CC Category Code Indicates the kind of equipment that generates the digital audio interface signal.
7:6	R/W	0x0	MODE Mode 00: Default Mode 01 to 11: Reserved

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Offset: 0x002C			Register Name: OWA_TX_CHSTA0
Bit	**Read/Write**	**Default/Hex**	**Description**
5:3	R/W	0x0	EMP Emphasis Additional format information For bit 1 = “0”, Linear PCM audio mode: 000: 2 audio channels without pre-emphasis 001: 2 audio channels with 50 μs/15 μs pre-emphasis 010: Reserved (for 2 audio channels with pre-emphasis) 011: Reserved (for 2 audio channels with pre-emphasis) 100 to 111: Reserved For bit 1 = “1”, other than Linear PCM applications: 000: Default state 001 to 111: Reserved
2	R/W	0x0	CP Copyright 0: Copyright is asserted 1: No copyright is asserted
1	R/W	0x0	TYPE Audio Data Type 0: Linear PCM samples 1: Non-linear PCM audio
0	R/W	0x0	PRO Application Type 0: Consumer application 1: Professional application This bit must be fixed to “0”.

9.3.5.10 0x0030 OWA TX Channel Status Register1 (Default Value: 0x0000_0000)

Offset: 0x0030			Register Name: OWA_TX_CHSTA1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:10	/	/	/
9:8	R/W	0x0	CGMS_A 00: Copying is permitted without restriction 01: One generation of copies may be made 10: Condition not be used 11: No copying is permitted

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Offset: 0x0030			Register Name: OWA_TX_CHSTA1
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0x0	ORIG_FREQ Original Sampling Frequency 0000: Not indicated 0001: 192 kHz 0010: 12 kHz 0011: 176.4 kHz 0100: Reserved 0101: 96 kHz 0110: 8 kHz 0111: 88.2 kHz 1000: 16 kHz 1001: 24 kHz 1010: 11.025 kHz 1011: 22.05 kHz 1100: 32 kHz 1101: 48 kHz 1110: Reserved 1111: 44.1 kHz
3:1	R/W	0x0	WL Sample Word Length For bit 0 = “0”: 000: Not indicated 001: 16 bits 010: 18 bits 100: 19 bits 101: 20 bits 110: 17 bits 111: Reserved For bit 0 = “1”: 000: Not indicated 001: 20 bits 010: 22 bits 100: 23 bits 101: 24 bits 110: 21 bits 111: Reserved

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Offset: 0x0030			Register Name: OWA_TX_CHSTA1
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	MWL Max Word Length 0: Maximum audio sample word length is 20 bits 1: Maximum audio sample word length is 24 bits

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9.4 Audio Codec

9.4.1 Overview

The Audio Codec is high-performance audio encoder and decoder module which supports DAC/ADC, dynamic range controller (DRC) and dynamic voltage controller (DVC) functions.

The Audio Codec has the following features:

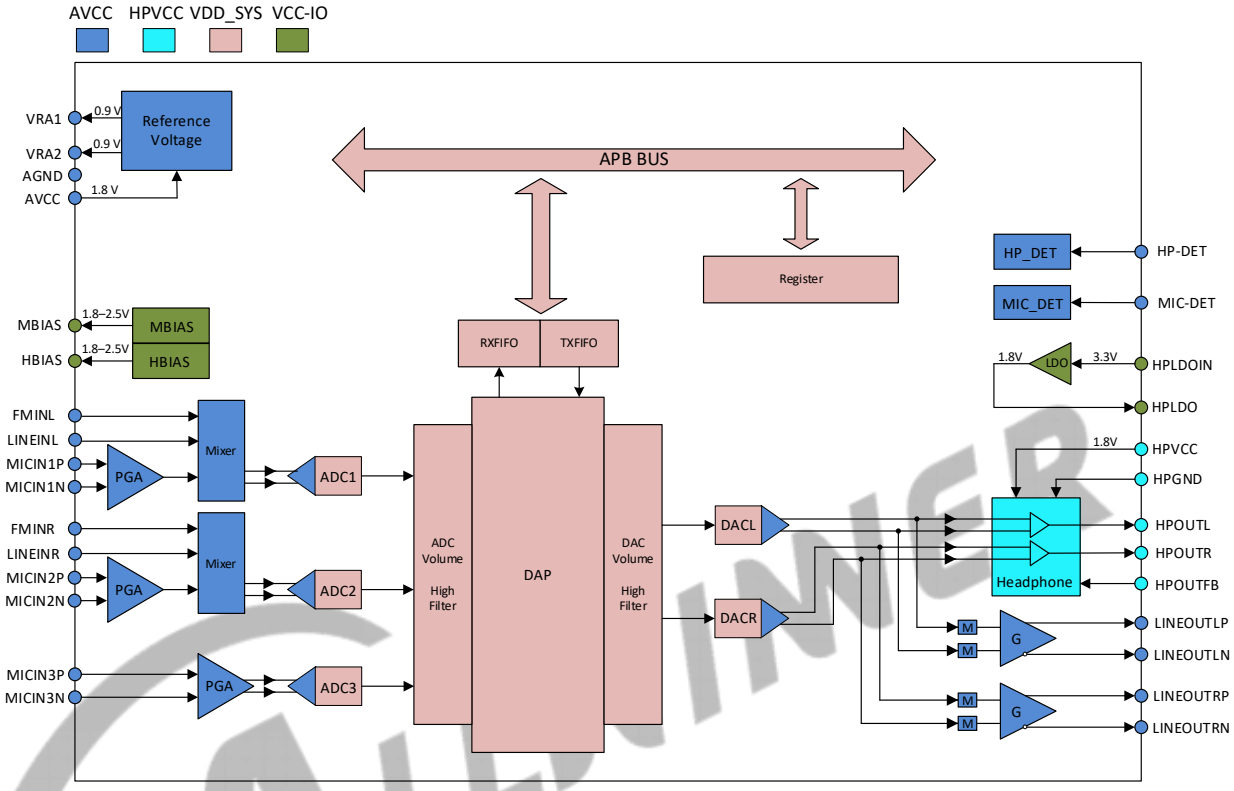
- Two audio digital-to-analog converter (DAC) channels
  - Supports the DAC sample rate from 8 kHz to 192 kHz
  - 100 ± 2 dB SNR@A-weight, -85 ± 3 dB THD + N
  - Supports 16-bit and 20-bit audio sample resolution
- Two audio outputs
  - One stereo headphone output: HPOUTL/R
  - One stereo differential lineout output: LINEOUTLP/N and LINEOUTRP/N
- There audio analog-to-digital converter (ADC) channels
  - Supports the ADC sample rate from 8 kHz to 48 kHz
  - 95 ± 3 dB SNR@A-weight, -80 ± 3 dB THD + N
  - Supports 16-bit and 20-bit audio sample resolution
- Five audio inputs
  - Three differential microphone inputs: MICIN1P/1N, MICIN2P/2N, MICIN3P/3N, or three single-end microphone inputs: MICIN1P, MICIN2P, MICIN3P
  - One stereo LINEIN input: LINEINL/R
  - One stereo FMIN input: FMINL/R
- Supports Dynamic Range Controller (DRC) adjusting the ADC recording and DAC playback
- One 128x20-bit FIFO for DAC data transmit, one 128x20-bit FIFO for ADC data receive
- Programmable FIFO thresholds
- Supports interrupts and DMA
- Internal HPLDO output for HPVCC
- Internal ALDO output for AVCC

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9.4.2 Block Diagram

The following figure shows the block diagram of Audio Codec.

Figure 9-19 Audio Codec Block Diagram



9.4.3 Functional Description

9.4.3.1 External Signals

Table 9-13 Audio Codec External Signals

Signal	Type	Description
MICIN1P	AI	Positive Differential Input for MIC1
MICIN1N	AI	Negative Differential Input for MIC1
MICIN2P	AI	Positive Differential Input for MIC2
MICIN2N	AI	Negative Differential Input for MIC2
MICIN3P	AI	Positive Differential Input for MIC3
MICIN3N	AI	Negative Differential Input for MIC3
FMINL	AI	FMIN Left Input
FMINR	AI	FMIN Right Input
LINEINL	AI	LINEIN Left Single-End Input

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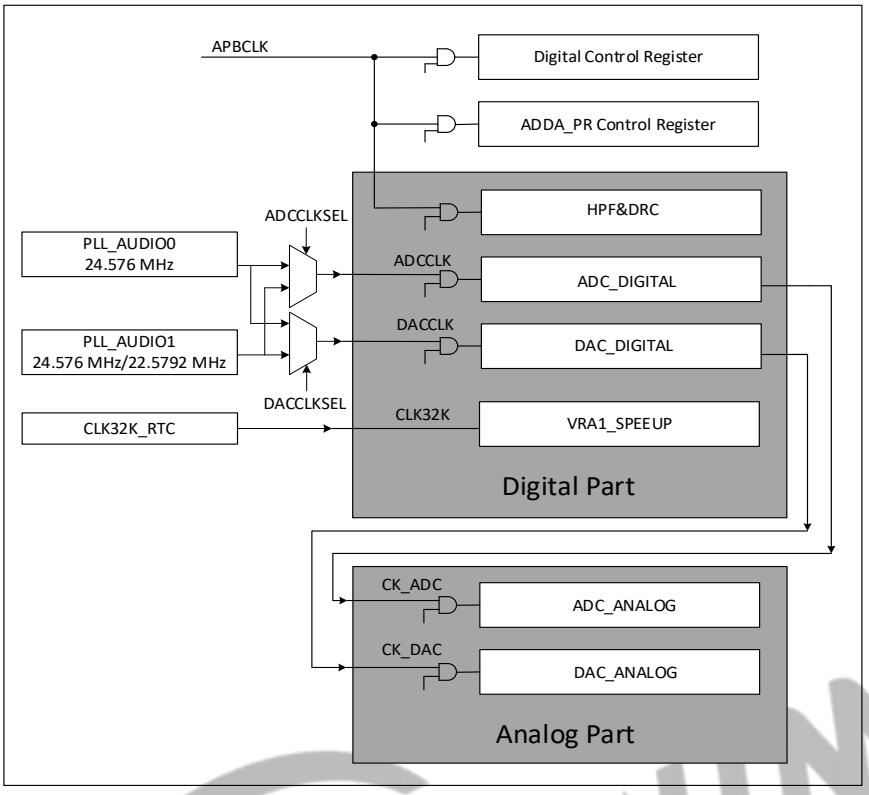
Signal	Type	Description
LINEINR	AI	LINEIN Right Single-End Input
LINEOUTLN	AO	Lineout Left Channel Negative Differential Output
LINEOUTLP	AO	Lineout Left Channel Positive Differential Output
LINEOUTRN	AO	Lineout Right Channel Negative Differential Output
LINEOUTRP	AO	Lineout Right Channel Positive Differential Output
HPOUTL	AO	Headphone Light Output
HPOUTR	AO	Headphone Right Output
HPOUTFB	AI	Pseudo Differential Headphone Ground Reference
HP-DET	AI	Headphone Jack Detect
HBIAS	AO	Second Bias Voltage Output for Headset Microphone
MBIAS	AO	First Bias Voltage Output for Main Microphone
MIC-DET	AI	Headphone MIC Detect
VRA1	AO	Internal Reference Voltage
VRA2	AO	Internal Reference Voltage
HPLDOIN	P	Headphone LDO Input
HPVCC	P	Headphone Power
AVCC	P	Analog Power
AGND	G	Analog Ground

9.4.3.2 Clock Sources

The following figure describes the clock source of Audio Codec. For clock setting, configuration, and gating information, refer to section 3.3 “CCU”.

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Figure 9-20 Audio Codec Clock Diagram



The clock source for the digital part is the PLL_AUDIO0 and PLL_AUDIO1. For the ADC clock, configure **AUDIO_CODEC_ADC_CLK_REG**[25:24] to select the clock source. For the DAC clock, configure **AUDIO_CODEC_DAC_CLK_REG**[25:24] to select the clock source. The PK-PK jitter of PLL_AUDIO0 and PLL_AUDIO1 should be less than 200 ps.

The clock source for the analog part is the CK_ADC and CK_DAC, both of which are divided from the digital part.

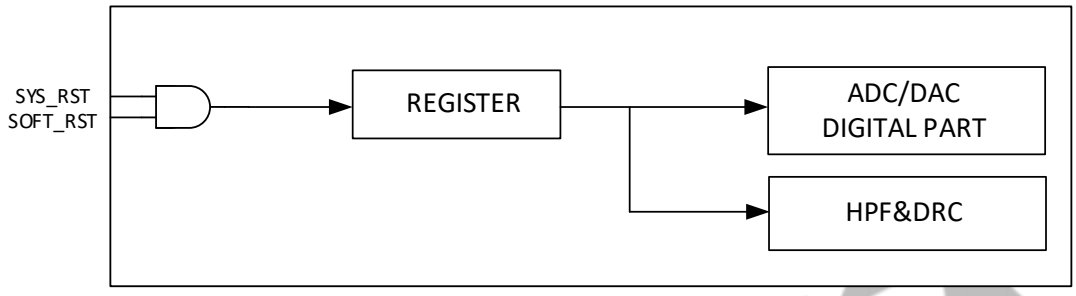
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9.4.3.3 Reset System

Digital Part Reset System

The following figure shows the reset system of the audio codec digital part.

Figure 9-21 Audio Codec Digital Part Reset System

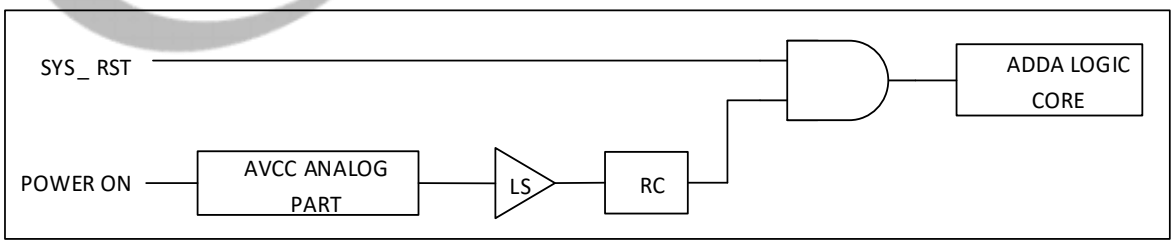


The SYS_RST comes from the VDD-SYS domain and is produced by the RTC domain. Each domain has the de-bounce to confirm the reset system is strong. For the codec register part, MIX can be reset by the SYS_RST when being powered on or the system soft is writing the reset control logic. The other parts can be reset by the soft configuration through writing the register.

Analog Part Reset System

The following figure shows the reset system of the audio codec analog part.

Figure 9-22 Audio Codec Analog Part Reset System



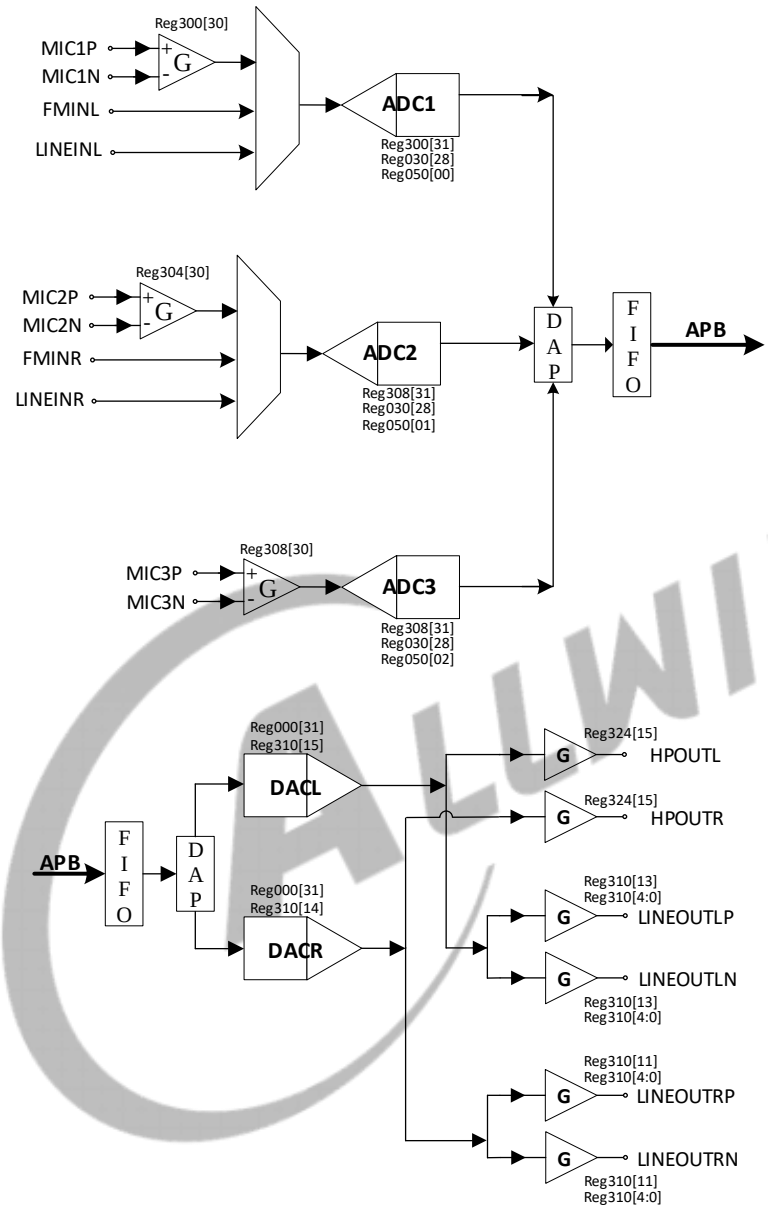
When AVCC is powered on, it sends the AVCC_POR signal. The AVCC_POR signal passes the level shift and RC filter part to the ADDA logic core.

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9.4.3.4 Data Path Diagram

The following figure shows a data path of the Audio Codec.

Figure 9-23 Audio Codec Data Path Diagram



9.4.3.5 Three ADCs

The three ADCs are used for recording stereo sound and a reference signal. The sample rates of the three ADCs are independent of the DAC sample rate. The digital ADC part can be enabled or disabled by the bit[28] of the **AC_ADC_FIFOC** register.

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9.4.3.6 Stereo DACs

The stereo DAC sample rate can be configured by setting the register. To save power, the analog DACL can be enabled or disabled by setting the bit[15] of the **DAC_REG** register, and the analog DACR can be enabled or disabled by setting the bit[14] of the **DAC_REG** register. The digital DAC part can be enabled or disabled by the bit[31] of the **AC_DAC_DPC** register.

9.4.3.7 Analog Audio Input Path

The Audio Codec supports 5 analog audio input paths:

- MICIN1P/N
- MICIN2P/N
- MICIN3P/N
- LINEINL/R
- FMINL/R

MICIN1P/N, LINEINL, FMINL provide differential input that can be mixed into the ADC1 record mixer. MICIN2P/N, LINEINR, FMINR provide differential input that can be mixed into the ADC2 record mixer. MICIN3P/N provides differential input. The MICIN is a high impedance, low capacitance input suitable for connecting to various differential microphones of different dynamics and sensitivity. The gain for each pre-amplifier can be set independently. MBIAS provides the reference voltage for electret condenser type (ECM) microphones.

9.4.3.8 Analog Audio Output Path

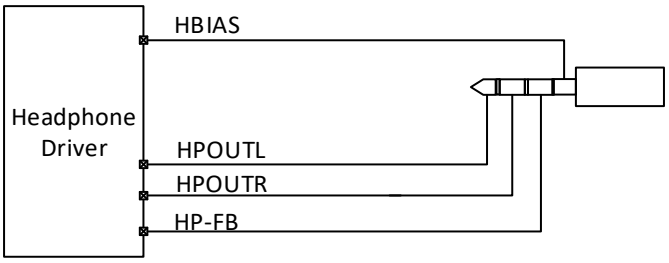
The Audio Codec has 2 analog output paths:

- LINEOUTLP/N, LINEOUTRP/N
- HPOUTL/R

The headphone PA is powered up or down by HP_REG[bit15] (HPPA_EN). HPOUTL/R can drive a 16R or 32R headphone load without DC capacitors by using Charge Pump to generate the negative rails. HP-FB is the ground loop noise rejection feedback. HBIAS provides reference voltage for electret condenser type (ECM) microphones.

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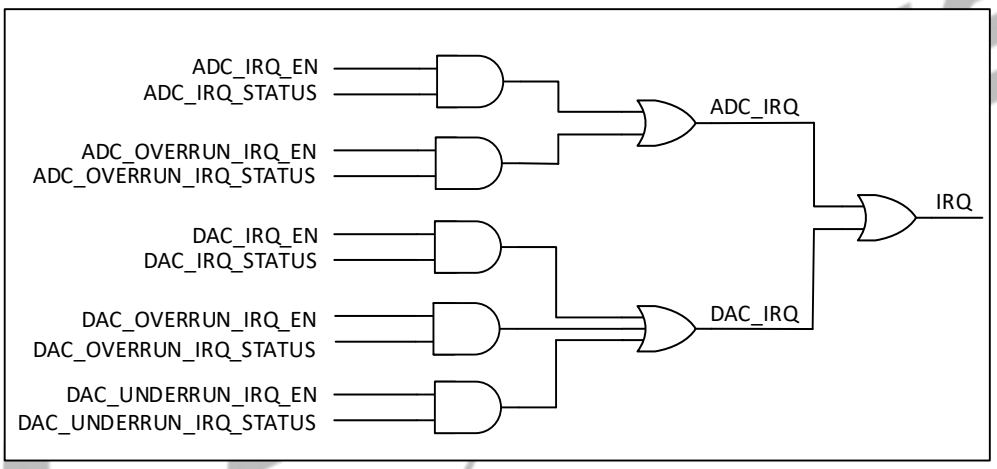
Figure 9-24 Headphone Output Application



9.4.3.9 Interrupts

The Audio Codec has two interrupts. The following figure describes the Audio Codec interrupt system.

Figure 9-25 Audio Codec Interrupt System



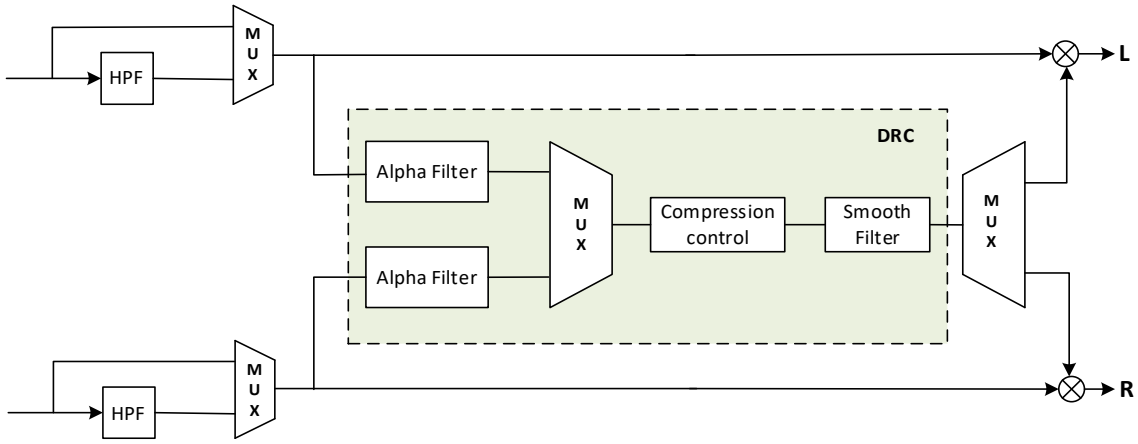
9.4.3.10 Digital Audio Processor (DAP)

The DAP module is used to remove the DC offset and automatically adjusts the volume to a flatten volume level. It mainly consists of two HPF and one DRC.

The following figure shows the DAP data flow.

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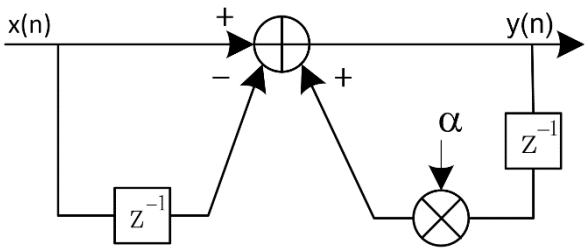
Figure 9-26 DAP Data Flow



HPF Function

The DAP has individual channel high pass filter (HPF, -3 dB cutoff < 1 Hz) that can be enabled and disabled. The filter cutoff frequency is less than 1 Hz that can be removed DC offset from ADC recording. The HPF can also be bypassed.

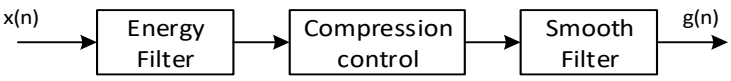
Figure 9-27 HPF Logic Structure



DRC Function

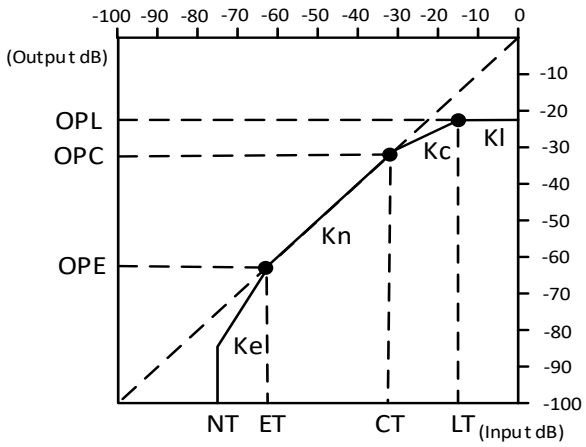
The DRC scheme has three thresholds, three offsets, and four slopes (all programmable). There is one ganged DRC for the left and right channels. The following figure shows the diagram of DRC input/output.

Figure 9-28 DRC Block Diagram



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Figure 9-29 DRC Static Curve Parameters



Professional-quality dynamic range compression automatically adjusts the volume to flatten volume level.

One DRC for left/right and one DRC for the subwoofer.

Each DRC has an adjustable threshold, offset, and compression levels, programmable energy, attack, and decay time constants.

Transparent compression: Compressors can attack fast enough to avoid apparent clipping before engaging, and decay times can be set slow enough to avoid pumping.

Configure the DRC parameters according to the following guidelines:

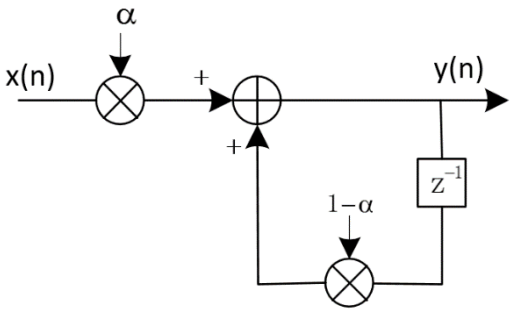
- **Number format**

  The Number format is N.M which means there are N bits to the left of the decimal point including the sign bit and M bits to the right of the decimal point. For example, Numbers formatted 9.23 means that there are 9 bits at the left of the decimal point and 23 bits at the right decimal point.

- **Energy Filter**

  The following figure shows the structure of the energy filter.

Figure 9-30 Energy Filter Structure



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The Energy Filter is to estimate the RMS value of the audio data stream into DRC and has two parameters, which determine the time window over which RMS to be made. The parameter is computed by $\alpha = 1 - e^{-2.2Ts/ta}$.

For the Compression Control, there are ten parameters (ET, CT, LT, Ke, Kn, Kc, Kl, OPL, OPC, and OPE), which are all programmable, and the computation will be explained as follows.

- **Threshold Parameter Computation (T parameter)**

  The threshold is the value that determines the signal to be compressed or not. When the RMS of the signal is larger than the threshold, the signal will be compressed. The value of threshold input to the coefficient register is computed by $Tin = -\frac{T_{dB}}{6.0206}$.

  Where, T_{dB} must less than zero, the positive value is illegal.

  For example, it is desired to set CT = -40 dB, then the Tin require to set CT to -40 dB is CTin = - (-40 dB)/6.0206 = 6.644, CT_{in} is entered as a 32-bit number in 8.24 format.

  Therefore, CT_{in} = 6.644 = 0000 0110.1010 0100 1101 0011 1100 0000 = 0x06A4 D3C0 in 8.24 format.

- **Slope Parameter Computation (K parameter)**

  The K is the slope within the compression region. For example, an n: 1 compression means that an output increase of 1 dB is for n dB RMS input. The k input to the coefficient ram is computed by $K = \frac{1}{n}$

  Where, n is from 1 to 50, and must be an integer.

  For example, it is desired to set to 2:1, then the Kc requires to set to 2:1, is Kc = 1/2 = 0.5, Kc is entered as a 32-bit number in 8.24 format.

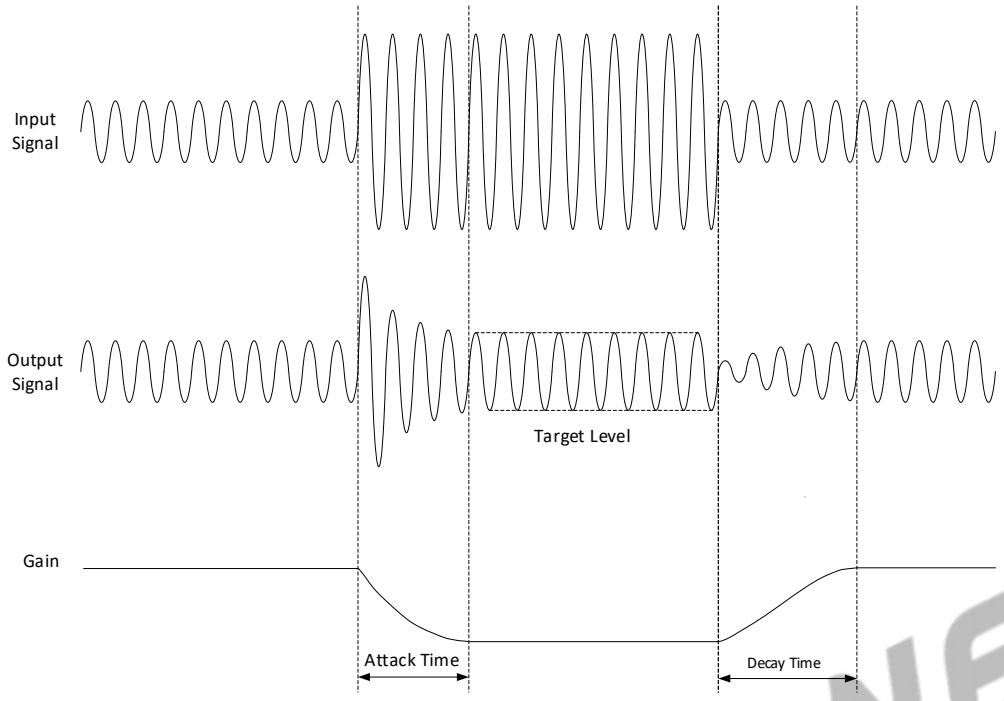
  Therefore, Kc = 0.5 = 0000 0000.1000 0000 0000 0000 0000 0000 = 0x0080 0000 in 8.24 format.

- **Gain Smooth Filter**

  The Gain Smooth Filter is to smooth the gain and control the ratio of gain increase and decrease. The decay time and attack are shown in Figure 9-36. The structure of the Gain Smooth filter is also the Alpha filter, so the rise time computation is the same as the Energy filter which is $\alpha = 1 - e^{-2.2Ts/ta}$.

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Figure 9-31 Gain Smooth Filter



9.4.4 Programming Guidelines

9.4.4.1 Record Process

In recording mode, the analog audio signals are recorded from the microphones at the specified sample rate, processed by the ADC, and then transferred to the DRAM via the DMA.

Step 1 Codec initialization: configure **AUDIO_CODEC_BGR_REG** to open the audio codec bus clock gating and de-assert bus reset; configure **AUDIO_CODEC_ADC_CLK_REG** and **PLL_AUDIO0_CTRL_REG** to configure PLL_Audio0 frequency and enable PLL_Audio0. For details, refer to section 3.3 "CCU".

Step 2 Configure the sample rate and data transfer format, then open the ADC.

Step 3 Configure the DMA and DMA request.

Step 4 Enable the ADC DRQ and DMA.

9.4.4.2 Playback Process

In playback mode, the audio data are transferred from the DRAM via DMA, processed by the DAC, and finally output via the analog interface.

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Step 1 Codec initialization: configure **AUDIO_CODEC_BGR_REG** to open the audio codec bus clock gating and de-assert bus reset; configure **AUDIO_CODEC_DAC_CLK_REG** and **PLL_AUDIO1_CTRL_REG** to configure PLL_Audio1 frequency and enable PLL_Audio1. For details, refer to section 3.3 "CCU".

Step 2 Configure the sample rate and data transfer format, then open the DAC.

Step 3 Configure the DMA and DMA request.

Step 4 Enable the DAC DRQ and DMA.

9.4.5 Register List

Module Name	Base Address
Audio Codec	0x02030000

Register Name	Offset	Description
AC_DAC_DPC	0x0000	DAC Digital Part Control Register
DAC_VOL_CTRL	0x0004	DAC Volume Control Register
AC_DAC_FIFOC	0x0010	DAC FIFO Control Register
AC_DAC_FIFOS	0x0014	DAC FIFO Status Register
AC_DAC_TXDATA	0x0020	DAC TX DATA Register
AC_DAC_CNT	0x0024	DAC TX FIFO Counter Register
AC_DAC_DG	0x0028	DAC Debug Register
AC_ADC_FIFOC	0x0030	ADC FIFO Control Register
ADC_VOL_CTRL1	0x0034	ADC Volume Control1 Register
AC_ADC_FIFOS	0x0038	ADC FIFO Status Register
AC_ADC_RXDATA	0x0040	ADC RX Data Register
AC_ADC_CNT	0x0044	ADC RX Counter Register
AC_ADC_DG	0x004C	ADC Debug Register
ADC_DIG_CTRL	0x0050	ADC Digtial Control Register
VRA1SPEEDUP_DOWN_CTRL	0x0054	VRA1 Speedup Down Control Register
AC_DAC_DAP_CTRL	0x00F0	DAC DAP Control Register
AC_ADC_DAP_CTR	0x00F8	ADC DAP Control Register
AC_DAC_DRC_HHPFC	0x0100	DAC DRC High HPF Coef Register
AC_DAC_DRC_LHPFC	0x0104	DAC DRC Low HPF Coef Register
AC_DAC_DRC_CTRL	0x0108	DAC DRC Control Register

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Register Name	Offset	Description
AC_DAC_DRC_LPFHAT	0x010C	DAC DRC Left Peak Filter High Attack Time Coef Register
AC_DAC_DRC_LPFLAT	0x0110	DAC DRC Left Peak Filter Low Attack Time Coef Register
AC_DAC_DRC_RPFHAT	0x0114	DAC DRC Right Peak Filter High Attack Time Coef Register
AC_DAC_DRC_RPFLAT	0x0118	DAC DRC Peak Filter Low Attack Time Coef Register
AC_DAC_DRC_LPFHRT	0x011C	DAC DRC Left Peak Filter High Release Time Coef Register
AC_DAC_DRC_LPFLRT	0x0120	DAC DRC Left Peak Filter Low Release Time Coef Register
AC_DAC_DRC_RPFHRT	0x0124	DAC DRC Right Peak filter High Release Time Coef Register
AC_DAC_DRC_RPFLRT	0x0128	DAC DRC Right Peak filter Low Release Time Coef Register
AC_DAC_DRC_LRMSHAT	0x012C	DAC DRC Left RMS Filter High Coef Register
AC_DAC_DRC_LRMSLAT	0x0130	DAC DRC Left RMS Filter Low Coef Register
AC_DAC_DRC_RRMSHAT	0x0134	DAC DRC Right RMS Filter High Coef Register
AC_DAC_DRC_RRMSLAT	0x0138	DAC DRC Right RMS Filter Low Coef Register
AC_DAC_DRC_HCT	0x013C	DAC DRC Compressor Threshold High Setting Register
AC_DAC_DRC_LCT	0x0140	DAC DRC Compressor Slope High Setting Register
AC_DAC_DRC_HKC	0x0144	DAC DRC Compressor Slope High Setting Register
AC_DAC_DRC_LKC	0x0148	DAC DRC Compressor Slope Low Setting Register
AC_DAC_DRC_HOPC	0x014C	DAC DRC Compressor High Output at Compressor Threshold Register
AC_DAC_DRC_LOPC	0x0150	DAC DRC Compressor Low Output at Compressor Threshold Register
AC_DAC_DRC_HLT	0x0154	DAC DRC Limiter Threshold High Setting Register
AC_DAC_DRC_LLT	0x0158	DAC DRC Limiter Threshold Low Setting Register
AC_DAC_DRC_HKl	0x015C	DAC DRC Limiter Slope High Setting Register
AC_DAC_DRC_LKl	0x0160	DAC DRC Limiter Slope Low Setting Register
AC_DAC_DRC_HOPL	0x0164	DAC DRC Limiter High Output at Limiter Threshold
AC_DAC_DRC_LOPL	0x0168	DAC DRC Limiter Low Output at Limiter Threshold
AC_DAC_DRC_HET	0x016C	DAC DRC Expander Threshold High Setting Register
AC_DAC_DRC_LET	0x0170	DAC DRC Expander Threshold Low Setting Register
AC_DAC_DRC_HKE	0x0174	DAC DRC Expander Slope High Setting Register

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Register Name	Offset	Description
AC_DAC_DRC_LKE	0x0178	DAC DRC Expander Slope Low Setting Register
AC_DAC_DRC_HOPE	0x017C	DAC DRC Expander High Output at Expander Threshold
AC_DAC_DRC_LOPE	0x0180	DAC DRC Expander Low Output at Expander Threshold
AC_DAC_DRC_HKN	0x0184	DAC DRC Linear Slope High Setting Register
AC_DAC_DRC_LKN	0x0188	DAC DRC Linear Slope Low Setting Register
AC_DAC_DRC_SFHAT	0x018C	DAC DRC Smooth filter Gain High Attack Time Coef Register
AC_DAC_DRC_SFLAT	0x0190	DAC DRC Smooth filter Gain Low Attack Time Coef Register
AC_DAC_DRC_SFHRT	0x0194	DAC DRC Smooth filter Gain High Release Time Coef Register
AC_DAC_DRC_SFLRT	0x0198	DAC DRC Smooth filter Gain Low Release Time Coef Register
AC_DAC_DRC_MXGHS	0x019C	DAC DRC MAX Gain High Setting Register
AC_DAC_DRC_MXGLS	0x01A0	DAC DRC MAX Gain Low Setting Register
AC_DAC_DRC_MNGHS	0x01A4	DAC DRC MIN Gain High Setting Register
AC_DAC_DRC_MNGLS	0x01A8	DAC DRC MIN Gain Low Setting Register
AC_DAC_DRC_EPSHC	0x01AC	DAC DRC Expander Smooth Time High Coef Register
AC_DAC_DRC_EPSLC	0x01B0	DAC DRC Expander Smooth Time Low Coef Register
AC_DAC_DRC_HPFHGAIN	0x01B8	DAC DRC HPF Gain High Coef Register
AC_DAC_DRC_HPFLGAIN	0x01BC	DAC DRC HPF Gain Low Coef Register
AC_ADC_DRC_HHPFC	0x0200	ADC DRC High HPF Coef Register
AC_ADC_DRC_LHPFC	0x0204	ADC DRC Low HPF Coef Register
AC_ADC_DRC_CTRL	0x0208	ADC DRC Control Register
AC_ADC_DRC_LPFHAT	0x020C	ADC DRC Left Peak Filter High Attack Time Coef Register
AC_ADC_DRC_LPFLAT	0x0210	ADC DRC Left Peak Filter Low Attack Time Coef Register
AC_ADC_DRC_RPFHAT	0x0214	ADC DRC Right Peak Filter High Attack Time Coef Register
AC_ADC_DRC_RPFLAT	0x0218	ADC DRC Right Peak Filter Low Attack Time Coef Register
AC_ADC_DRC_LPFHRT	0x021C	ADC DRC Left Peak Filter High Release Time Coef Register
AC_ADC_DRC_LPFLRT	0x0220	ADC DRC Left Peak Filter Low Release Time Coef Register

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Register Name	Offset	Description
AC_ADC_DRC_RPFHRT	0x0224	ADC DRC Right Peak Filter High Release Time Coef Register
AC_ADC_DRC_RPFLRT	0x0228	ADC DRC Right Peak Filter Low Release Time Coef Register
AC_ADC_DRC_LRMSHAT	0x022C	ADC DRC Left RMS Filter High Coef Register
AC_ADC_DRC_LRMSLAT	0x0230	ADC DRC Left RMS Filter Low Coef Register
AC_ADC_DRC_RRMSHAT	0x0234	ADC DRC Right RMS Filter High Coef Register
AC_ADC_DRC_RRMSLAT	0x0238	ADC DRC Right RMS Filter Low Coef Register
AC_ADC_DRC_HCT	0x023C	ADC DRC Compressor Threshold High Setting Register
AC_ADC_DRC_LCT	0x0240	ADC DRC Compressor Slope High Setting Register
AC_ADC_DRC_HKC	0x0244	ADC DRC Compressor Slope High Setting Register
AC_ADC_DRC_LKC	0x0248	ADC DRC Compressor Slope Low Setting Register
AC_ADC_DRC_HOPC	0x024C	ADC DRC Compressor High Output at Compressor Threshold Register
AC_ADC_DRC_LOPC	0x0250	ADC DRC Compressor Low Output at Compressor Threshold Register
AC_ADC_DRC_HLT	0x0254	ADC DRC Limiter Threshold High Setting Register
AC_ADC_DRC_LLT	0x0258	ADC DRC Limiter Threshold Low Setting Register
AC_ADC_DRC_HKl	0x025C	ADC DRC Limiter Slope High Setting Register
AC_ADC_DRC_LKl	0x0260	ADC DRC Limiter Slope Low Setting Register
AC_ADC_DRC_HOPL	0x0264	ADC DRC Limiter High Output at Limiter Threshold
AC_ADC_DRC_LOPL	0x0268	ADC DRC Limiter Low Output at Limiter Threshold
AC_ADC_DRC_HET	0x026C	ADC DRC Expander Threshold High Setting Register
AC_ADC_DRC_LET	0x0270	ADC DRC Expander Threshold Low Setting Register
AC_ADC_DRC_HKE	0x0274	ADC DRC Expander Slope High Setting Register
AC_ADC_DRC_LKE	0x0278	ADC DRC Expander Slope Low Setting Register
AC_ADC_DRC_HOPE	0x027C	ADC DRC Expander High Output at Expander Threshold
AC_ADC_DRC_LOPE	0x0280	ADC DRC Expander Low Output at Expander Threshold
AC_ADC_DRC_HKN	0x0284	ADC DRC Linear Slope High Setting Register
AC_ADC_DRC_LKN	0x0288	ADC DRC Linear Slope Low Setting Register
AC_ADC_DRC_SFHAT	0x028C	ADC DRC Smooth filter Gain High Attack Time Coef Register
AC_ADC_DRC_SFLAT	0x0290	ADC DRC Smooth filter Gain Low Attack Time Coef Register

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Register Name	Offset	Description
AC_ADC_DRC_SFHRT	0x0294	ADC DRC Smooth filter Gain High Release Time Coef Register
AC_ADC_DRC_SFLRT	0x0298	ADC DRC Smooth filter Gain Low Release Time Coef Register
AC_ADC_DRC_MXGHS	0x029C	ADC DRC MAX Gain High Setting Register
AC_ADC_DRC_MXGLS	0x02A0	ADC DRC MAX Gain Low Setting Register
AC_ADC_DRC_MNGLS	0x02A4	ADC DRC MIN Gain High Setting Register
AC_ADC_DRC_MXGLS	0x02A8	ADC DRC MIN Gain Low Setting Register
AC_ADC_DRC_EPSHC	0x02AC	ADC DRC Expander Smooth Time High Coef Register
AC_ADC_DRC_EPSLC	0x02B0	ADC DRC Expander Smooth Time Low Coef Register
AC_ADC_DRC_HPFHGAIN	0x02B8	ADC DRC HPF Gain High Coef Register
AC_ADC_DRC_HPFLGAIN	0x02BC	ADC DRC HPF Gain Low Coef Register
Analog Domain Register		
ADC1_REG	0x0300	ADC1 Analog Control Register
ADC2_REG	0x0304	ADC2 Analog Control Register
ADC3_REG	0x0308	ADC3 Analog Control Register
DAC_REG	0x0310	DAC Analog Control Register
MICBIAS_REG	0x0318	MICBIAS Analog Control Register
RAMP_REG	0x031C	BIAS Analog Control Register
BIAS_REG	0x0320	BIAS Analog Control Register
ADC5_REG	0x0330	ADC5 Analog Control Register

9.4.6 Register Description

9.4.6.1 0x0000 DAC Digital Part Control Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: AC_DAC_DPC
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	EN_DA DAC Digital Part Enable 0: Disabled 1: Enabled
30:29	/	/	/

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Offset: 0x0000			Register Name: AC_DAC_DPC
Bit	**Read/Write**	**Default/Hex**	**Description**
28:25	R/W	0x0	MODQU Internal DAC Quantization Levels Levels = [7*(21 + MODQU[3:0])]/128 Default levels = 7*21/128 = 1.15
24	R/W	0x0	DWA DWA Function Disable 0: Enabled 1: Disabled
23:19	/	/	/
18	R/W	0x0	HPF_EN High Pass Filter Enable 0: Disabled 1: Enabled
17:12	R/W	0x0	DVOL Digital volume control: DVC, ATT = DVC[5:0]*(-1.16 dB) 64 steps, -1.16 dB/step
11:1	/	/	/
0	R/W	0x0	HUB_EN Audio Hub Enable The bit takes effect only when the EN_DA is set to 1. System Domain: Audio Codec/I2S0/I2S1/I2S2/OWA TXFIFO Hub Enable. 0: Disabled 1: Enabled

9.4.6.2 0x0004 DAC Volume Control Register (Default Value: 0x0000_A0A0)

Offset: 0x0004			Register Name: DAC_VOL_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0x0	DAC_VOL_SEL DAC Volume Control Selection Enable 0: Disabled 1: Enabled

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Offset: 0x0004			Register Name: DAC_VOL_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
15:8	R/W	0xA0	DAC_VOL_L DAC left channel volume (-119.25 dB to 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F = -0.75 dB 0xA0 = 0 dB 0xA1 = 0.75 dB ... 0xFF = 71.25 dB
7:0	R/W	0xA0	DAC_VOL_R DAC right channel volume (-119.25 dB To 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F = -0.75 dB 0xA0 = 0 dB 0xA1 = 0.75 dB ... 0xFF = 71.25 dB

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9.4.6.3 0x0010 DAC FIFO Control Register (Default Value: 0x0000_4000)

Offset: 0x0010			Register Name: AC_DAC_FIFOC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	R/W	0x0	DAC_FS Sample Rate of DAC 000: 48 kHz 010: 24 kHz 100: 12 kHz 110: 192 kHz 001: 32 kHz 011: 16 kHz 101: 8 kHz 111: 96 kHz 44.1 kHz/22.05 kHz/11.025 kHz can be supported by Audio PLL Configure Bit
28	R/W	0x0	FIR_VER FIR Version 0: 64-Tap FIR 1: 32-Tap FIR
27	/	/	/
26	R/W	0x0	SEND_LASAT Audio sample select when TX FIFO underrun 0: Sending zero 1: Sending the last audio sample
25:24	R/W	0x0	FIFO_MODE For 20-bit transmitted audio sample: 00/10: FIFO_I[19:0] = {TXDATA[31:12]} 01/11: FIFO_I[19:0] = {TXDATA[19:0]} For 16-bit transmitted audio sample: 00/10: FIFO_I[19:0] = {TXDATA[31:16], 4'b0} 01/11: FIFO_I[19:0] = {TXDATA[15:0], 4'b0}
23	/	/	/

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Offset: 0x0010			Register Name: AC_DAC_FIFOC
Bit	**Read/Write**	**Default/Hex**	**Description**
22:21	R/W	0x0	DAC_DRQ_CLR_CNT When TX FIFO available room is less than or equal N, the DRQ request will be de-asserted. N is defined here: 00: IRQ/DRQ de-asserted when WLEVEL > TXTL 01: 4 10: 8 11: 16
20:15	/	/	/
14:8	R/W	0x40	TX_TRIG_LEVEL TX FIFO Empty Trigger Level (TXTL[12:0]) Interrupt and DMA request trigger level for TX FIFO normal condition. IRQ/DRQ generated when WLEVEL ≤ TXTL **Note: WLEVEL represents the number of valid samples in the TX FIFO. Only TXTL[6:0] valid when TXMODE = 0**
7	/	/	/
6	R/W	0x0	DAC_MONO_EN DAC Mono Enable 0: Stereo, 64 levels FIFO 1: Mono, 128 levels FIFO When enabled, L & R channel send the same data.
5	R/W	0x0	TX_SAMPLE_BITS Transmitting Audio Sample Resolution 0: 16 bits 1: 20 bits
4	R/W	0x0	DAC_DRQ_EN DAC FIFO Empty DRQ Enable 0: Disabled 1: Enabled
3	R/W	0x0	DAC_IRQ_EN DAC FIFO Empty IRQ Enable 0: Disabled 1: Enabled

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Offset: 0x0010			Register Name: AC_DAC_FIFOC
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	FIFO_UNDERRUN_IRQ_EN DAC FIFO Underrun IRQ Enable 0: Disabled 1: Enabled
1	R/W	0x0	FIFO_OVERRUN_IRQ_EN DAC FIFO Overrun IRQ Enable 0: Disabled 1: Enabled
0	R/WC	0x0	FIFO_FLUSH DAC FIFO Flush Write '1' to flush TX FIFO, self clear to '0'

9.4.6.4 0x0014 DAC FIFO Status Register (Default Value: 0x0080_8008)

Offset: 0x0014			Register Name: AC_DAC_FIFOS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23	R	0x1	TX_EMPTY TX FIFO Empty 0: No room for new sample in TX FIFO 1: More than one room for new sample in TX FIFO (>= 1 word)
22:8	R	0x80	TXE_CNT TX FIFO Empty Space Word Counter
7:4	/	/	/
3	R/W1C	0x1	TXE_INT TX FIFO Empty Pending Interrupt 0: No Pending IRQ 1: FIFO Empty Pending Interrupt Write '1' to clear this interrupt or automatically clear if the interrupt condition fails.
2	R/W1C	0x0	TXU_INT TX FIFO Underrun Pending Interrupt 0: No Pending Interrupt 1: FIFO Underrun Pending Interrupt Write '1' to clear this interrupt

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Offset: 0x0014			Register Name: AC_DAC_FIFOS
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W1C	0x0	TXO_INT TX FIFO Overrun Pending Interrupt 0: No Pending Interrupt 1: FIFO Overrun Pending Interrupt Write '1' to clear this interrupt
0	/	/	/

9.4.6.5 0x0020 DAC TX DATA Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: AC_DAC_TXDATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	W	0x0	TX_DATA Write the transmitting left and right channel sample data to this register one by one. Write the left channel sample data first and then the right channel sample.

9.4.6.6 0x0024 DAC TX Counter Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: AC_DAC_CNT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TX_CNT TX Sample Counter The audio sample number of sending into TXFIFO. When one sample is put into TXFIFO by DMA or by host IO, the TX sample counter register increases by one. The TX sample counter register can be set to any initial valve at any time. After being updated by the initial value, the counter register should count from this initial value. **Note: It is used for Audio/Video Synchronization.**

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9.4.6.7 0x0028 DAC Debug Register (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: AC_DAC_DG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11	R/W	0x0	DAC_MODU_SELECT DAC Modulator Debug 0: DAC Modulator Normal Mode 1: DAC Modulator Debug Mode
10:9	R/W	0x0	DAC_PATTERN_SELECT DAC Pattern Select 00: Normal (Audio sample from TX FIFO) 01: -6 dB Sin wave 10: -60 dB Sin wave 11: Silent wave
8	R/W	0x0	CODEC_CLK_SELECT CODEC Clock Source Select 0: CODEC clock from PLL 1: CODEC clock from OSC (for Debug)
7	/	/	/
6	R/W	0x0	DA_SWP DAC Output Channel Swap Enable 0: Disabled 1: Enabled
5:3	/	/	/
2:0	R/W	0x0	ADDA_LOOP_MODE ADDA Loop Mode Select 000: Disabled 001: ADDA LOOP MODE DACL/DACR is connected to ADC1/ADC2 010: ADDA LOOP MODE DACL/DACR is connected to ADC3 Others: Reserved

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9.4.6.8 0x0030 ADC FIFO Control Register (Default Value: 0x0000_0400)

Offset: 0x0030			Register Name: AC_ADC_FIFOC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	R/W	0x0	ADFS Sample Rate of ADC 000: 48 kHz 010: 24 kHz 100: 12 kHz 110: Reserved 001: 32 kHz 011: 16 kHz 101: 8 kHz 111: Reserved 44.1 kHz/22.05 kHz/11.025 kHz can be supported by Audio PLL Configure Bit.
28	R/W	0x0	EN_AD ADC Digital Part Enable 0: Disabled 1: Enabled
27:26	R/W	0x0	ADCFDT ADC FIFO delay time for writing data after EN_AD 00: 5 ms 01: 10 ms 10: 20 ms 11: 30 ms
25	R/W	0x0	ADCDFEN ADC FIFO delay function for writing data after EN_AD 0: Disabled 1: Enabled

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Offset: 0x0030			Register Name: AC_ADC_FIFOC
Bit	**Read/Write**	**Default/Hex**	**Description**
24	R/W	0x0	RX_FIFO_MODE RX FIFO Output Mode (Mode 0, 1) 0: Expanding '0' at LSB of TX FIFO register 1: Expanding received sample sign bit at MSB of TX FIFO register For 20-bit received audio sample: Mode 0: RXDATA[31:0] = {FIFO_O[19:0], 12'h0} Mode 1: RXDATA[31:0] = {12{FIFO_O[19]}, FIFO_O[19:0]} For 16-bit received audio sample: Mode 0: RXDATA[31:0] = {FIFO_O[19:4], 16'h0} Mode 1: RXDATA[31:0] = {16{FIFO_O[19]}, FIFO_O[19:4]}
23:22	/	/	/
21	R/W	0x0	RX_SYNC_EN_START The bit takes effect only when RX_SYNC_EN is set to 1. System Domain: Audio codec/I2S0/I2S1/I2S2/DMIC Synchronize Enable Start. 0: Disabled 1: Enabled
20	R/W	0x0	RX_SYNC_EN Audiocodec RX Synchronize Enable 0: Disabled 1: Enabled
19:17	/	/	/
16	R/W	0x0	RX_SAMPLE_BITS Receiving Audio Sample Resolution 0: 16 bits 1: 20 bits
15:12	/	/	/
11:4	R/W	0x40	RX_FIFO_TRG_LEVEL RX FIFO Trigger Level (RXTL[5:0]) Interrupt and DMA request trigger level for RX FIFO normal condition IRQ/DRQ generated when WLEVEL > RXTL[5:0] **Note: WLEVEL represents the number of valid samples in the RX FIFO.**

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Offset: 0x0030			Register Name: AC_ADC_FIFOC
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W	0x0	ADC_DRQ_EN ADC FIFO Data Available DRQ Enable 0: Disabled 1: Enabled
2	R/W	0x0	ADC_IRQ_EN ADC FIFO Data Available IRQ Enable 0: Disabled 1: Enabled
1	R/W	0x0	ADC_OVERRUN_IRQ_EN ADC FIFO Overrun IRQ Enable 0: Disabled 1: Enabled
0	R/WC	0x0	ADC_FIFO_FLUSH ADC FIFO Flush Write '1' to flush TX FIFO, self clear to '0'.

9.4.6.9 0x0034 ADC Volume Control1 Register (Default Value: 0xA0A0_A0A0)

Offset: 0x0034			Register Name: ADC_VOL_CTRL1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	R/W	0xA0	Reserved
23:16	R/W	0xA0	ADC3_VOL ADC3 channel volume (-119.25 dB To 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB

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Offset: 0x0034			Register Name: ADC_VOL_CTRL1
Bit	**Read/Write**	**Default/Hex**	**Description**
15:8	R/W	0xA0	ADC2_VOL ADC2 channel volume (-119.25 dB To 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB
7:0	R/W	0xA0	ADC1_VOL ADC1 channel volume (-119.25 dB To 71.25 dB, 0.75 dB/Step) 0x00: Mute 0x01: -119.25 dB ... 0x9F: -0.75 dB 0xA0: 0 dB 0xA1: 0.75 dB ... 0xFF: 71.25 dB

9.4.6.10 0x0038 ADC FIFO Status Register (Default Value: 0x0000_0001)

Offset: 0x0038			Register Name: AC_ADC_FIFOS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23	R	0x0	RXA RX FIFO Available 0: No available data in RX FIFO 1: More than one sample in RX FIFO (>= 1 word)
22:17	/	/	/
16:8	R	0x0	RXA_CNT RX FIFO Available Sample Word Counter

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Offset: 0x0038			Register Name: AC_ADC_FIFOS
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	/	/	/
3	R/W1C	0x0	RXA_INT RX FIFO Data Available Pending Interrupt 0: No Pending IRQ 1: Data Available Pending IRQ Write '1' to clear this interrupt or automatic clear if the interrupt condition fails.
2	/	/	/
1	R/W1C	0x0	RXO_INT RX FIFO Overrun Pending Interrupt 0: No Pending IRQ 1: FIFO Overrun Pending IRQ Write '1' to clear this interrupt.
0	R	0x1	Reserved

9.4.6.11 0x0040 ADC RX DATA Register (Default Value: 0x0000_0000)

Offset: 0x0040			Register Name: AC_ADC_RXDATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	RX_DATA RX Sample The host can get one sample by reading this register. The left channel sample data comes first and then the right channel sample.

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9.4.6.12 0x0044 ADC RX Counter Register (Default Value: 0x0000_0000)

Offset: 0x0044			Register Name: AC_ADC_CNT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	RX_CNT RX Sample Counter The audio sample number of writing into RXFIFO. When one sample is written by Digital Audio Engine, the RX sample counter register increases by one. The RX sample counter register can be set to any initial valve at any time. After being updated by the initial value, the counter register should count from this initial value. **Note: It is used for Audio/Video Synchronization.**

9.4.6.13 0x004C ADC Debug Register (Default Value: 0x0000_0000)

Offset: 0x004C			Register Name: AC_ADC_DG_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/
25	R/W	0x0	AD_SWP2 ADC output channel swap enable (for digital filter) 0: Disabled 1: Enabled **Note: ADC3 and ADC4 swap data.**
24	R/W	0x0	AD_SWP1 ADC output channel swap enable (for digital filter) 0: Disabled 1: Enabled **Note: ADC1 and ADC2 swap data.**
23:0	/	/	/

9.4.6.14 0x0050 ADC Digtial Control Register (Default Value: 0x0000_0000)

Offset: 0x0050			Register Name: ADC_DIG_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/

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Offset: 0x0050			Register Name: ADC_DIG_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
17	R/W	0x0	ADC3_VOL_EN ADC3 Volume Control Enable 0: Disabled 1: Enabled
16	R/W	0x0	ADC1_2_VOL_EN ADC1/2 Volume Control Enable 0: Disabled 1: Enabled
15:3	/	/	/
2:0	R/W	0x0	ADC_CHANNEL_EN Bit 3: ADC4 enabled Bit 2: ADC3 enabled Bit 1: ADC2 enabled Bit 0: ADC1 enabled

9.4.6.15 0x0054 VRA1 Speedup Down Control Register (Default Value: 0x0000_0000)

Offset: 0x0054			Register Name: VRA1SPEEDUP_DOWN_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:5	/	/	/
4	R	0x0	VRA1SPEEDUP_DOWN_STATE Only if VAR1SPEEDUP_DOWN_Further_CTRL (0x310[22]) is set 0, VAR1Speedup Down State is valid. 0: VAR1Speedup_Down does not work. 1: VAR1Speedup_Down works.
3:2	/	/	/
1	R/W	0x0	VRA1SPEEDUP_DOWN_CTRL VAR1Speedup Down Manual Control Enable 0: Disabled. VAR1Speedup Down converts to 1 after the bus rst releases 32 ms. 1: Enabled. VAR1Speedup Down converts to 1 immediately.

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Offset: 0x0054			Register Name: VRA1SPEEDUP_DOWN_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	VRA1SPEEDUP_DOWN_RST_CTRL VAR1Speedup Down RST Manual Control Enable 0: Disabled. VAR1Speedup Down converts to 1 after the bus rst releases 32 ms. 1: Enabled. VAR1Speedup Down reset 0 immediately.

9.4.6.16 0x00F0 DAC DAP Control Register (Default Value: 0x0000_0000)

Offset: 0x00F0			Register Name: AC_DAC_DAP_CTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	DDAP_EN DAP for DRC enable 0: Bypassed 1: Enabled
30	/	/	/
29	R/W	0x0	DDAP_DRC_EN DRC enable control 0: Disabled 1: Enabled
28	R/W	0x0	DDAP_HPF_EN HPF enable control 0: Disabled 1: Enabled
27:0	/	/	/

9.4.6.17 0x00F8 ADC DAP Control Register (Default Value: 0x0000_0000)

Offset: 0x00F8			Register Name: AC_ADC_DAP_CTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	ADC_DAP0_EN (control the DAP of ADC1/2) DAP for ADC enable 0: Bypassed 1: Enabled
30	/	/	/

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Offset: 0x00F8			Register Name: AC_ADC_DAP_CTR
Bit	**Read/Write**	**Default/Hex**	**Description**
29	R/W	0x0	ADC_DRC0_EN ADC DRC0 enable control 0: Disabled 1: Enabled
28	R/W	0x0	ADC_HPF0_EN ADC HPF0 enable control 0: Disabled 1: Enabled
27	R/W	0x0	ADC_DAP1_EN (control the DAP of ADC3) ADC DAP1 enable control
26	/	/	/
25	R/W	0x0	ADC_DRC1_EN ADC DRC1 enable control 0: Disabled 1: Enabled
24	R/W	0x0	ADC_HPF1_EN ADC HPF1 enable control 0: Disabled 1: Enabled
23:0	/	/	/

9.4.6.18 0x0100 DAC DRC High HPF Coef Register (Default Value: 0x0000_00FF)

Offset: 0x0100			Register Name: AC_DAC_DRC_HHPFC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:11	/	/	/
10:0	R/W	0xFF	HPF coefficient setting and the data is 3.24 format.

9.4.6.19 0x0104 DAC DRC Low HPF Coef Register (Default Value: 0x0000_FAC1)

Offset: 0x0104			Register Name: AC_DAC_DRC_LHPFC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/

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Offset: 0x0104			Register Name: AC_DAC_DRC_LHPFC
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0xFAC1	HPF coefficient setting and the data is 3.24 format.

9.4.6.20 0x0108 DAC DRC Control Register (Default Value: 0x0000_0080)

Offset: 0x0108			Register Name: AC_DAC_DRC_CTRL
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15	R	0x0	DRC delay buffer data output state when The DRC delay function is enabled and the DRC function is disabled. After disabling the DRC function and this bit goes to 0, write the DRC delay function bit to 0. 0: Not completed 1: Completed
14:10	/	/	/
13:8	R/W	0x0	Signal delay time setting 6'h00: (8x1) fs 6'h01: (8x2) fs 6'h02: (8x3) fs ---------- 6'h2e: (8*47) fs 6'h2f: (8*48) fs 6'h30 -- 6'h3f: (8*48) fs Delay time = 8*(n + 1) fs, n<6'h30; When the delay function is disabled, the signal delay time is unused.
7	R/W	0x1	DAC_DRC_DELAY_BUF_EN The delay buffer use or not when the DRC is disabled and the DRC buffer data output completely. 0: Do not use the buffer. 1: Use the buffer.
6	R/W	0x0	DAC_DRC_GAIN_MAX_LIMIT_EN DRC gain max limit enable 0: Disabled 1: Enabled

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Offset: 0x0108			Register Name: AC_DAC_DRC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R/W	0x0	DAC_DRC_GAIN_MIN_LIMIT_EN DRC gain min limit enable When this function is enabled, it will overwrite the noise detect function. 0: Disabled 1: Enabled
4	R/W	0x0	DAC_DRC_DETECT_NOISE_EN Control the DRC to detect noise when ET is enabled. 0: Disabled 1: Enabled
3	R/W	0x0	DAC_DRC_SIGNAL_FUNC_SEL Signal function select 0: RMS filter 1: Peak filter When the signal function selects the Peak filter, the RMS parameter is unused. (AC_DRC_LRMSHAT, AC_DRC_LRMSLAT, AC_DRC_LRMSHAT, AC_DRC_LRMSLAT) When the signal function selects the RMS filter, the Peak filter parameter is unused. (AC_DRC_LPFHAT, AC_DRC_LPFLAT, AC_DRC_RPFHAT, AC_DRC_RPFLAT, AC_DRC_LPFHRT, AC_DRC_LPFLRT, AC_DRC_RPFHRT, and AC_DRC_RPFLRT)
2	R/W	0x0	DAC_DRC_DELAY_FUNC_EN Delay function enable 0: Disabled 1: Enabled When the bit is disabled, the signal delay time is unused.
1	R/W	0x0	DAC_DRC_LT_EN DRC LT enable 0: Disabled 1: Enabled When the bit is disabled, Kl and OPL parameter is unused.
0	R/W	0x0	DAC_DRC_ET_EN DRC ET enable 0: Disabled 1: Enabled When the bit is disabled, Ke and OPE parameter is unused.

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9.4.6.21 0x010C DAC DRC Left Peak Filter High Attack Time Coef Register (Default Value: 0x0000_000B)

Offset: 0x010C			Register Name: AC_DAC_DRC_LPFHAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:11	/	/	/
10:0	R/W	0x000B	DAC_DRC_LPFHAT The left peak filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/ta). The format is 3.24. (The default value is 1 ms)

9.4.6.22 0x0110 DAC DRC Left Peak Filter Low Attack Time Coef Register (Default Value: 0x0000_77BF)

Offset: 0x0110			Register Name: AC_DAC_DRC_LPFLAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0x77BF	DAC_DRC_LPFLAT The left peak filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/ta). The format is 3.24. (The default value is 1 ms)

9.4.6.23 0x0114 DAC DRC Right Peak Filter High Attack Time Coef Register (Default Value: 0x0000_000B)

Offset: 0x0114			Register Name: AC_DAC_DRC_RPFHAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0xB	DAC_DRC_RPFHAT The right peak filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/ta). The format is 3.24. (The default value is 1 ms)

9.4.6.24 0x0118 DAC DRC Left Peak Filter Low Attack Time Coef Register (Default Value: 0x0000_77BF)

Offset: 0x0118			Register Name: AC_DAC_DRC_RPFLAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/

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Offset: 0x0118			Register Name: AC_DAC_DRC_RPFLAT
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0x77BF	DAC_DRC_RPFLAT The left peak filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/ta). The format is 3.24. (The default value is 1 ms)

9.4.6.25 0x011C DAC DRC Left Peak Filter High Release Time Coef Register (Default Value: 0x0000_00FF)

Offset: 0x011C			Register Name: AC_DAC_DRC_LPFHRT
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R/W	0x00FF	DAC_DRC_LPFHRT The left peak filter release time parameter setting, which is determined by the equation that RT = exp (-2.2Ts/tr). The format is 3.24. (The default value is 100 ms)

9.4.6.26 0x0120 DAC DRC Left Peak Filter Low Release Time Coef Register (Default Value: 0x0000_E1F8)

Offset: 0x0120			Register Name: AC_DAC_DRC_LPFLRT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xE1F8	DAC_DRC_LPFLRT The left peak filter release time parameter setting, which is determined by the equation that RT = exp (-2.2Ts/tr). The format is 3.24. (The default value is 100 ms)

9.4.6.27 0x0124 DAC DRC Right Peak Filter High Release Time Coef Register (Default Value: 0x0000_00FF)

Offset: 0x0124			Register Name: AC_DAC_DRC_RPFHRT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/

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Offset: 0x0124			Register Name: AC_DAC_DRC_RPFHRT
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0xFF	DAC_DRC_RPFHRT The right peak filter release time parameter setting, which is determined by the equation that RT = exp (-2.2Ts/tr). The format is 3.24. (The default value is 100 ms)

9.4.6.28 0x0128 DAC DRC Right Peak filter Low Release Time Coef Register(Default Value: 0x0000_E1F8)

Offset: 0x0128			Register Name: AC_DAC_DRC_RPFLRT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xE1F8	DAC_DRC_RPFLRT The right peak filter release time parameter setting, which is determined by the equation that AT = exp(-2.2Ts/tr). The format is 3.24. (The default value is 100 ms)

9.4.6.29 0x012C DAC DRC Left RMS Filter High Coef Register (Default Value: 0x0000_0001)

Offset: 0x012C			Register Name: AC_DAC_DRC_LRMSHAT
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R/W	0x0001	DAC_DRC_LRMSHAT The left RMS filter average time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tav). The format is 3.24. (The default value is 10 ms)

9.4.6.30 0x0130 DAC DRC Left RMS Filter Low Coef Register (Default Value: 0x0000_2BAF)

Offset: 0x0130			Register Name: AC_DAC_DRC_LRMSLAT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/

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Offset: 0x0130			Register Name: AC_DAC_DRC_LRMSLAT
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0x2BAF	DAC_DRC_LRMSLAT The left RMS filter average time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tav). The format is 3.24. (The default value is 10 ms)

9.4.6.31 0x0134 DAC DRC Right RMS Filter High Coef Register (Default Value: 0x0000_0001)

Offset: 0x0134			Register Name: AC_DAC_DRC_RRMSHAT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x2BAF	DAC_DRC_RRMSHAT The right RMS filter average time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tav). The format is 3.24. (The default value is 10 ms)

9.4.6.32 0x0138 DAC DRC Right RMS Filter Low Coef Register (Default Value: 0x0000_2BAF)

Offset: 0x0138			Register Name: AC_DAC_DRC_RRMSLAT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x2BAF	DAC_DRC_RRMSLAT The right RMS filter average time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tav). The format is 3.24. (The default value is 10 ms)

9.4.6.33 0x013C DAC DRC Compressor Theshold High Setting Register (Default Value: 0x0000_06A4)

Offset: 0x013C			Register Name: AC_DAC_DRC_HCT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/

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Offset: 0x013C			Register Name: AC_DAC_DRC_HCT
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R/W	0x06A4	DAC_DRC_HCT The compressor threshold setting, which is set by the equation that CTin = -CT/6.0206. The format is 8.24. (The default value is -40 dB)

9.4.6.34 0x0140 DAC DRC Compressor Slope High Setting Register (Default Value: 0x0000_D3C0)

Offset: 0x0140			Register Name: AC_DAC_DRC_LCT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0xD3C0	DAC_DRC_LCT The compressor threshold setting, which is set by the equation that CTin = -CT/6.0206. The format is 8.24. (The default value is -40 dB)

9.4.6.35 0x0144 DAC DRC Compressor Slope High Setting Register (Default Value: 0x0000_0080)

Offset: 0x0144			Register Name: AC_DAC_DRC_HKC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0x0080	DAC_DRC_HKC The slope of the compressor, which is determined by the equation that Kc = 1/R. R is the ratio of the compressor, which is always an integer. The format is 8.24. (The default value is 2:1)

9.4.6.36 0x0148 DAC DRC Compressor Slope Low Setting Register (Default Value: 0x0000_0000)

Offset: 0x0148			Register Name: AC_DAC_DRC_LKC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/

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Offset: 0x0148			Register Name: AC_DAC_DRC_LKC
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0x0000	DAC_DRC_LKC The slope of the compressor, which is determined by the equation that Kc = 1/R. R is the ratio of the compressor, which is always an integer. The format is 8.24. (The default value is 2:1)

9.4.6.37 0x014C DAC DRC Compressor High Output at Compressor Threshold Register (Default Value: 0x0000_F95B)

Offset: 0x014C			Register Name: AC_DAC_DRC_HOPC
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xF95B	DAC_DRC_HOPC The output of the compressor, which is determined by the equation -OPC/6.0206. The format is 8.24 (The default value is -40 dB)

9.4.6.38 0x0150 DAC DRC Compressor Low Output at Compressor Threshold Register (Default Value: 0x0000_2C3F)

Offset: 0x0150			Register Name: AC_DAC_DRC_LOPC
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x2C3F	DAC_DRC_LOPC The output of the compressor, which is determined by the equation OPC/6.0206. The format is 8.24. (The default value is -40 dB)

9.4.6.39 0x0154 DAC DRC Limiter Theshold High Setting Register (Default Value: 0x0000_01A9)

Offset: 0x0154			Register Name: AC_DAC_DRC_HLT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x01A9	DAC_DRC_HLT The limiter threshold setting, which is set by the equation that LTin = -LT/6.0206, The format is 8.24. (The default value is -10 dB)

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9.4.6.40 0x0158 DAC DRC Limiter Theshold Low Setting Register (Default Value: 0x0000_34F0)

Offset: 0x0158			Register Name: AC_DAC_DRC_LLT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x34F0	DAC_DRC_LLT The limiter threshold setting, which is set by the equation that LTin = -LT/6.0206. The format is 8.24. (The default value is -10 dB)

9.4.6.41 0x015C DAC DRC Limiter Slope High Setting Register (Default Value: 0x0000_0005)

Offset: 0x015C			Register Name: AC_DAC_DRC_HKl
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0005	DAC_DRC_HKl The slope of the limiter which is determined by the equation that Kl = 1/R. R is the ratio of the limiter, which is always an integer. The format is 8.24. (The default value is <50:1>)

9.4.6.42 0x0160 DAC DRC Limiter Slope Low Setting Register (Default Value: 0x0000_1EB8)

Offset: 0x0160			Register Name: AC_DAC_DRC_LKl
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x1EB8	DAC_DRC_LKl The slope of the limiter, which is determined by the equation that Kl = 1/R. R is the ratio of the limiter, which is always an integer. The format is 8.24. (The default value is <50:1>)

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9.4.6.43 0x0164 DAC DRC Limiter High Output at Limiter Threshold Register (Default Value: 0x0000_FBD8)

Offset: 0x0164			Register Name: AC_DAC_DRC_HOPL
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xFBD8	DAC_DRC_HOPL The output of the limiter, which is determined by equation OPT/6.0206. The format is 8.24. (The default value is -25 dB)

9.4.6.44 0x0168 DAC DRC Limiter Low Output at Limiter Threshold Register (Default Value: 0x0000_FBA7)

Offset: 0x0168			Register Name: AC_DAC_DRC_LOPL
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xFBA7	DAC_DRC_LOPL The output of the limiter, which is determined by equation OPT/6.0206. The format is 8.24. (The default value is -25 dB)

9.4.6.45 0x016C DAC DRC Expander Theshold High Setting Register (Default Value: 0x0000_0BA0)

Offset: 0x016C			Register Name: AC_DAC_DRC_HET
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0BA0	DAC_DRC_HET The expander threshold setting, which is set by the equation that ETin = -ET/6.0206. The format is 8.24. (The default value is -70 dB)

9.4.6.46 0x0170 DAC DRC Expander Theshold Low Setting Register (Default Value: 0x0000_7291)

Offset: 0x0170			Register Name: AC_DAC_DRC_LET
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x7291	DAC_DRC_LET The expander threshold setting, which is set by the equation that ETin = -ET/6.0206. The format is 8.24. (The default value is -70 dB)

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9.4.6.47 0x0174 DAC DRC Expander Slope High Setting Register (Default Value: 0x0000_0500)

Offset: 0x0174			Register Name: AC_DAC_DRC_HKE
Bit	Read/Write	Default/Hex	Description
31:14	/	/	/
13:0	R/W	0x0500	DAC_DRC_HKE The slope of the expander, which is determined by the equation that Ke = 1/R. R is the ratio of the expander, which is always an integer and the ke must larger than 50. The format is 8.24. (The default value is <1:5>)

9.4.6.48 0x0178 DAC DRC Expander Slope Low Setting Register (Default Value: 0x0000_0000)

Offset: 0x0178			Register Name: AC_DAC_DRC_LKE
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0000	DAC_DRC_LKE The slope of the expander, which is determined by the equation that Ke = 1/R. R is the ratio of the expander, which is always an integer and the ke must larger than 50. The format is 8.24. (The default value is <1:5>)

9.4.6.49 0x017C DAC DRC Expander High Output at Expander Threshold Register (Default Value: 0x0000_F45F)

Offset: 0x017C			Register Name: AC_DAC_DRC_HOPE
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xF45F	DAC_DRC_HOPE The output of the expander, which is determined by equation OPE/6.0206. The format is 8.24. (The default value is -70 dB)

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9.4.6.50 0x0180 DAC DRC Expander Low Output at Expander Threshold Register (Default Value: 0x0000_8D6E)

Offset: 0x0180			Register Name: AC_DAC_DRC_LOPE
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x8D6E	DAC_DRC_LOPE The output of the expander which is determined by equation OPE/6.0206. The format is 8.24. (The default value is -70 dB)

9.4.6.51 0x0184 DAC DRC Linear Slope High Setting Register (Default Value: 0x0000_0100)

Offset: 0x0184			Register Name: AC_DAC_DRC_HKN
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0100	DAC_DRC_HKN The slope of the linear, which is determined by the equation that Kn = 1/R. R is the ratio of the linear, which is always an integer. The format is 8.24. (The default value is <1:1>)

9.4.6.52 0x0188 DAC DRC Linear Slope Low Setting Register (Default Value: 0x0000_0000)

Offset: 0x0188			Register Name: AC_DAC_DRC_LKN
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0000	DAC_DRC_LKN The slope of the linear, which is determined by the equation that Kn = 1/R. R is the ratio of the linear, which is always an integer. The format is 8.24. (The default value is <1:1>)

9.4.6.53 0x018C DAC DRC Smooth Filter Gain High Attack Time Coef Register (Default Value: 0x0000_0002)

Offset: 0x018C			Register Name: AC_DAC_DRC_SFHAT
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/

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Offset: 0x018C			Register Name: AC_DAC_DRC_SFHAT
Bit	Read/Write	Default/Hex	Description
10:0	R/W	0x0002	DAC_DRC_SFHAT The smooth filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 5 ms)

9.4.6.54 0x0190 DAC DRC Smooth Filter Gain Low Attack Time Coef Register (Default Value: 0x0000_5600)

Offset: 0x0190			Register Name: AC_DAC_DRC_SFLAT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x5600	DAC_DRC_SFLAT The smooth filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 5 ms)

9.4.6.55 0x0194 DAC DRC Smooth Filter Gain High Release Time Coef Register (Default Value: 0x0000_0000)

Offset: 0x0194			Register Name: AC_DAC_DRC_SFHRT
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R/W	0x0000	DAC_DRC_SFHRT The gain smooth filter release time parameter setting, which is determined by the equation that RT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 200 ms)

9.4.6.56 0x0198 DAC DRC Smooth Filter Gain Low Release Time Coef Register (Default Value: 0x0000_0F04)

Offset: 0x0198			Register Name: AC_DAC_DRC_SFLRT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/

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Offset: 0x0198			Register Name: AC_DAC_DRC_SFLRT
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R/W	0x0F04	DAC_DRC_SFLRT The gain smooth filter release time parameter setting, which is determined by the equation that RT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 200 ms)

9.4.6.57 0x019C DAC DRC MAX Gain High Setting Register (Default Value: 0x0000_FE56)

Offset: 0x019C			Register Name: AC_DAC_DRC_MXGHS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0xFE56	DAC_DRC_MXGHS The max gain setting, which is determined by equation MXG_{in}=MXG/6.0206. The format is 8.24 and must -20 dB < MXG < 30 dB (The default value is -10 dB)

9.4.6.58 0x01A0 DAC DRC MAX Gain Low Setting Register (Default Value: 0x0000_CB0F)

Offset: 0x01A0			Register Name: AC_DAC_DRC_MXGLS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0xCB0F	DAC_DRC_MXGLS The max gain setting, which is determined by equation MXG_{in}=MXG/6.0206. The format is 8.24 and must -20 dB < MXG < 30 dB (The default value is -10 dB)

9.4.6.59 0x01A4 DAC DRC MIN Gain High Setting Register (Default Value: 0x0000_F95B)

Offset: 0x01A4			Register Name: AC_DAC_DRC_MNGHS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/

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Offset: 0x01A4			Register Name: AC_DAC_DRC_MNGHS
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0xF95B	DAC_DRC_MNGHS The min gain setting, which is determined by equation MXG_{in}=MXG/6.0206. The format is 8.24 and must -60 dB ≤ MNG ≤ -40 dB (The default value is -40 dB)

9.4.6.60 0x01A8 DAC DRC MIN Gain Low Setting Register (Default Value: 0x0000_2C3F)

Offset: 0x01A8			Register Name: AC_DAC_DRC_MNGLS
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x2C3F	DAC_DRC_MNGLS The min gain setting, which is determined by equation MXG_{in}=MNG/6.0206. The format is 8.24 and must -60 dB ≤ MNG ≤ -40 dB (The default value is -40 dB)

9.4.6.61 0x01AC DAC DRC Expander Smooth Time High Coef Register (Default Value: 0x0000_0000)

Offset: 0x01AC			Register Name: AC_DAC_DRC_EPSHC
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R/W	0x0000	DAC_DRC_EPSHC The gain smooth filter release and attack time parameter setting in expander region, which are determined by the equation that RT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 30 ms)

9.4.6.62 0x01B0 DAC DRC Expander Smooth Time Low Coef Register (Default Value: 0x0000_640C)

Offset: 0x01B0			Register Name: AC_DAC_DRC_EPSLC
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/

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Offset: 0x01B0			Register Name: AC_DAC_DRC_EPSLC
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0x640C	DAC_DRC_EPSLC The gain smooth filter release and attack time parameter setting in expander region, which are determined by the equation that RT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 30 ms)

9.4.6.63 0x01B8 DAC DRC HPF Gain High Coef Register (Default Value: 0x0000_0100)

Offset: 0x01B8			Register Name: AC_DAC_DRC_HPFHGAIN
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R/W	0x100	DAC_DRC_HPFHGAIN The gain of HPF coefficient. The format is 3.24. (gain = 1)

9.4.6.64 0x01BC DAC DRC HPF Gain Low Coef Register (Default Value: 0x0000_0000)

Offset: 0x01BC			Register Name: AC_DAC_DRC_HPFLGAIN
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0000	DAC_DRC_HPFLGAIN The gain of HPF coefficient. The format is 3.24. (gain = 1)

9.4.6.65 0x0200 ADC DRC High HPF Coef Register (Default Value: 0x0000_00FF)

Offset: 0x0200			Register Name: AC_ADC_DRC_HHPFC
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R/W	0xFF	ADC_DRC_HHPFC HPF coefficient setting and the data is 3.24 format.

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9.4.6.66 0x0204 ADC DRC Low HPF Coef Register (Default Value: 0x0000_FAC1)

Offset: 0x0204			Register Name: AC_ADC_DRC_LHPFC
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xFAC1	HPF coefficient setting and the data is 3.24 format.

9.4.6.67 0x0208 ADC DRC Control Register (Default Value: 0x0000_0080)

Offset: 0x0208			Register Name: AC_ADC_DRC_CTRL
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15	R	0x0	ADC_DRC_DELAY_BUF_OUTPUT_STATE DRC delay buffer data output state when The DRC delay function is enabled and the DRC function is disabled. After disabled DRC function and this bit goes to 0, the user should write the DRC delay function bit to 0. 0: Not completed 1: Completed
14:10	/	/	/
13:8	R/W	0x0	ADC_DRC_SIGNAL_DELAY_TIME_SET Signal delay time setting 6'h00: (8x1) fs 6'h01: (8x2) fs 6'h02: (8x3) fs ---------- 6'h2e: (8*47) fs 6'h2f: (8*48) fs 6'h30 -- 6'h3f: (8*48) fs Delay time = 8*(n + 1) fs, n < 6'h30; When the delay function is disabled, the signal delay time is unused.
7	R/W	0x1	ADC_DRC_DELAY_BUF_EN The delay buffer use or not when the DRC is disabled and the DRC buffer data output completely. 0: Do not use the buffer 1: Use the buffer

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Offset: 0x0208			Register Name: AC_ADC_DRC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
6	R/W	0x0	ADC_DRC_GAIN_MAX_LIMIT_EN DRC gain max limit enable 0: Disabled 1: Enabled
5	R/W	0x0	ADC_DRC_GAIN_MIN_LIMIT_EN DRC gain min limit enable When this fuction is enabled, it will overwrite the noise detect function. 0: Disabled 1: Enabled
4	R/W	0x0	ADC_DRC_DETECT_NOISE_EN Control the DRC to detect noise when ET is enabled 0: Disabled 1: Enabled
3	R/W	0x0	ADC_DRC_SIGNAL_FUNC_SEL Signal function select 0: RMS filter 1: Peak filter When the signal function selects the Peak filter, the RMS parameter is unused. (AC_DRC_LRMSHAT, AC_DRC_LRMSLAT, AC_DRC_LRMSHAT, and AC_DRC_LRMSLAT) When the signal function selects the RMS filter, the Peak filter parameter is unused. (AC_DRC_LPFHAT, AC_DRC_LPFLAT, AC_DRC_RPFHAT, AC_DRC_RPFLAT, AC_DRC_LPFHRT, AC_DRC_LPFLRT, AC_DRC_RPFHRT, and AC_DRC_RPFLRT)
2	R/W	0x0	ADC_DRC_DELAY_FUNC_EN Delay function enable 0: Disabled 1: Enabled When the bit is disabled, the signal delay time is unused.
1	R/W	0x0	ADC_DRC_LT_EN DRC LT enable 0: Disabled 1: Enabled When the bit is disabled, Kl and OPL parameter is unused.

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Offset: 0x0208			Register Name: AC_ADC_DRC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	ADC_DRC_ET_EN DRC ET enable 0: Disabled 1: Enabled When the bit is disabled, Ke and OPE parameter is unused.

9.4.6.68 0x020C ADC DRC Left Peak Filter High Attack Time Coef Register (Default Value: 0x0000_000B)

Offset: 0x020C			Register Name: AC_ADC_DRC_LPFHAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:11	/	/	/
10:0	R/W	0x000B	ADC_DRC_LPFHAT The left peak filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/ta). The format is 3.24. (The default value is 1 ms)

9.4.6.69 0x0210 ADC DRC Left Peak Filter Low Attack Time Coef Register (Default Value: 0x0000_77BF)

Offset: 0x0210			Register Name: AC_ADC_DRC_LPFLAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0x77BF	ADC_DRC_LPFLAT The left peak filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/ta). The format is 3.24. (The default value is 1 ms)

9.4.6.70 0x0214 ADC DRC Right Peak Filter High Attack Time Coef Register (Default Value: 0x0000_000B)

Offset: 0x0214			Register Name: AC_ADC_DRC_RPFHAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/

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Offset: 0x0214			Register Name: AC_ADC_DRC_RPFHAT
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0x000B	ADC_DRC_RPFHAT The right peak filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/ta). The format is 3.24. (The default value is 1 ms)

9.4.6.71 0x0218 ADC DRC Right Peak Filter Low Attack Time Coef Register (Default Value: 0x0000_77BF)

Offset: 0x0218			Register Name: AC_ADC_DRC_RPFLAT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x77BF	ADC_DRC_RPFLAT The right peak filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/ta). The format is 3.24. (The default value is 1 ms)

9.4.6.72 0x021C ADC DRC Left Peak Filter High Release Time Coef Register (Default Value: 0x0000_00FF)

Offset: 0x021C			Register Name: AC_ADC_DRC_LPFHRT
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R/W	0x00FF	ADC_DRC_LPFHRT The left peak filter release time parameter setting, which is determined by the equation that RT = exp (-2.2Ts/tr). The format is 3.24. (The default value is 100 ms)

9.4.6.73 0x0220 ADC DRC Left Peak Filter Low Release Time Coef Register (Default Value: 0x0000_E1F8)

Offset: 0x0220			Register Name: AC_ADC_DRC_LPFLRT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/

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Offset: 0x0220			Register Name: AC_ADC_DRC_LPFLRT
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0xE1F8	ADC_DRC_LPFLRT The left peak filter release time parameter setting, which is determined by the equation that RT = exp (-2.2Ts/tr). The format is 3.24. (The default value is 100 ms)

9.4.6.74 0x0224 ADC DRC Right Peak Filter High Release Time Coef Register (Default Value: 0x0000_00FF)

Offset: 0x0224			Register Name: AC_ADC_DRC_RPFHRT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x00FF	ADC_DRC_RPFHRT The right peak filter release time parameter setting, which is determined by the equation that RT = exp (-2.2Ts/tr). The format is 3.24. (The default value is 100 ms)

9.4.6.75 0x0228 ADC DRC Right Peak Filter Low Release Time Coef Register (Default Value: 0x0000_E1F8)

Offset: 0x0228			Register Name: AC_ADC_DRC_RPFLRT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xE1F8	ADC_DRC_RPFLRT The right peak filter release time parameter setting, which is determined by the equation that RT = exp (-2.2Ts/tr). The format is 3.24. (The default value is 100 ms)

9.4.6.76 0x022C ADC DRC Left RMS Filter High Coef Register (Default Value: 0x0000_0001)

Offset: 0x022C			Register Name: AC_ADC_DRC_LRMSHAT
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/

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Offset: 0x022C			Register Name: AC_ADC_DRC_LRMSHAT
Bit	**Read/Write**	**Default/Hex**	**Description**
10:0	R/W	0x0001	ADC_DRC_LRMSHAT The left RMS filter average time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tav). The format is 3.24. (The default value is 10 ms)

9.4.6.77 0x0230 ADC DRC Left RMS Filter Low Coef Register (Default Value: 0x0000_2BAF)

Offset: 0x0230			Register Name: AC_ADC_DRC_LRMSLAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0x2BAF	ADC_DRC_LRMSLAT The left RMS filter average time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tav). The format is 3.24. (The default value is 10 ms)

9.4.6.78 0x0234 ADC DRC Right RMS Filter High Coef Register (Default Value: 0x0000_0001)

Offset: 0x0234			Register Name: AC_ADC_DRC_RRMSHAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:11	/	/	/
10:0	R/W	0x0001	ADC_DRC_RRMSHAT The right RMS filter average time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tav). The format is 3.24. (The default value is 10 ms)

9.4.6.79 0x0238 ADC DRC Right RMS Filter Low Coef Register (Default Value: 0x0000_2BAF)

Offset: 0x0238			Register Name: AC_ADC_DRC_RRMSLAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/

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Offset: 0x0238			Register Name: AC_ADC_DRC_RRMSLAT
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0x2BAF	ADC_DRC_RRMSLAT The right RMS filter average time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tav). The format is 3.24. (The default value is 10 ms)

9.4.6.80 0x023C ADC DRC Compressor Theshold High Setting Register (Default Value: 0x0000_06A4)

Offset: 0x023C			Register Name: AC_ADC_DRC_HCT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x06A4	ADC_DRC_HCT The compressor threshold setting, which is set by the equation that CTin = -CT/6.0206. The format is 8.24. (The default value is -40 dB)

9.4.6.81 0x0240 ADC DRC Compressor Slope High Setting Register (Default Value: 0x0000_D3C0)

Offset: 0x0240			Register Name: AC_ADC_DRC_LCT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xD3C0	ADC_DRC_LCT The compressor threshold setting, which is set by the equation that CTin = -CT/6.0206. The format is 8.24. (The default value is -40 dB)

9.4.6.82 0x0244 ADC DRC Compressor Slope High Setting Register (Default Value: 0x0000_0080)

Offset: 0x0244			Register Name: AC_ADC_DRC_HKC
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/

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Offset: 0x0244			Register Name: AC_ADC_DRC_HKC
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0x0080	ADC_DRC_HKC The slope of the compressor which is determined by the equation that Kc = 1/R. R is the ratio of the compressor, which is always an integer. The format is 8.24. (The default value is <2:1>)

9.4.6.83 0x0248 ADC DRC Compressor Slope Low Setting Register (Default Value: 0x0000_0000)

Offset: 0x0248			Register Name: AC_ADC_DRC_LKC
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0000	ADC_DRC_LKC The slope of the compressor, which is determined by the equation that Kc = 1/R. R is the ratio of the compressor, which is always an integer. The format is 8.24. (The default value is <2:1>)

9.4.6.84 0x024C ADC DRC Compressor High Output at Compressor Threshold Register (Default Value: 0x0000_F95B)

Offset: 0x024C			Register Name: AC_ADC_DRC_HOPC
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xF95B	ADC_DRC_HOPC The output of the compressor, which is determined by the equation -OPC/6.0206. The format is 8.24. (The default value is -40 dB)

9.4.6.85 0x0250 ADC DRC Compressor Low Output at Compressor Threshold Register (Default Value: 0x0000_2C3F)

Offset: 0x0250			Register Name: AC_ADC_DRC_LOPC
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/

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Offset: 0x0250			Register Name: AC_ADC_DRC_LOPC
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0x2C3F	ADC_DRC_LOPC The output of the compressor, which is determined by the equation OPC/6.0206. The format is 8.24. (The default value is -40 dB)

9.4.6.86 0x0254 ADC DRC Limiter Theshold High Setting Register (Default Value: 0x0000_01A9)

Offset: 0x0254			Register Name: AC_ADC_DRC_HLT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x01A9	ADC_DRC_HLT The limiter threshold setting, which is set by the equation that LTin = -LT/6.0206. The format is 8.24. (The default value is -10 dB)

9.4.6.87 0x0258 ADC DRC Limiter Theshold Low Setting Register (Default Value: 0x0000_34F0)

Offset: 0x0258			Register Name: AC_ADC_DRC_LLT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x34F0	ADC_DRC_LLT The limiter threshold setting, which is set by the equation that LTin = -LT/6.0206. The format is 8.24. (The default value is -10 dB)

9.4.6.88 0x025C ADC DRC Limiter Slope High Setting Register (Default Value: 0x0000_0005)

Offset: 0x025C			Register Name: AC_ADC_DRC_HKl
Bit	Read/Write	Default/Hex	Description
31:14	/	/	/
13:0	R/W	0x0005	ADC_DRC_HKl The slope of the limiter, which is determined by the equation that Kl = 1/R. R is the ratio of the limiter, which is always an integer. The format is 8.24. (The default value is <50:1>)

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9.4.6.89 0x0260 ADC DRC Limiter Slope Low Setting Register (Default Value: 0x0000_1EB8)

Offset: 0x0260			Register Name: AC_ADC_DRC_LKl
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0x1EB8	ADC_DRC_LKl The slope of the limiter, which is determined by the equation that Kl = 1/R. R is the ratio of the limiter, which is always an integer. The format is 8.24. (The default value is <50:1>)

9.4.6.90 0x0264 ADC DRC Limiter High Output at Limiter Threshold Register (Default Value: 0x0000_FBD8)

Offset: 0x0264			Register Name: AC_ADC_DRC_HOPL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0xFBD8	ADC_DRC_HOPL The output of the limiter, which is determined by equation OPT/6.0206. The format is 8.24. (The default value is -25 dB)

9.4.6.91 0x0268 ADC DRC Limiter Low Output at Limiter Threshold Register (Default Value: 0x0000_FBA7)

Offset: 0x0268			Register Name: AC_ADC_DRC_LOPL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0xFBA7	ADC_DRC_LOPL The output of the limiter which is determined by equation OPT/6.0206. The format is 8.24. (The default value is -25 dB)

9.4.6.92 0x026C ADC DRC Expander Theshold High Setting Register (Default Value: 0x0000_0BA0)

Offset: 0x026C			Register Name: AC_ADC_DRC_HET
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/

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Offset: 0x026C			Register Name: AC_ADC_DRC_HET
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0x0BA0	ADC_DRC_HET The expander threshold setting, which is set by the equation that ETin = -ET/6.0206, The format is 8.24. (The default value is -70 dB)

9.4.6.93 0x0270 ADC DRC Expander Theshold Low Setting Register (Default Value: 0x0000_7291)

Offset: 0x0270			Register Name: AC_ADC_DRC_LET
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x7291	ADC_DRC_LET The expander threshold setting, which is set by the equation that ETin = -ET/6.0206, The format is 8.24. (The default value is -70 dB)

9.4.6.94 0x0274 ADC DRC Expander Slope High Setting Register (Default Value: 0x0000_0500)

Offset: 0x0274			Register Name: AC_ADC_DRC_HKE
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0500	ADC_DRC_HKE The slope of the expander, which is determined by the equation that Ke = 1/R. R is the ratio of the expander, which is always an integer and the ke must larger than 50. The format is 8.24. (The default value is <1:5>)

9.4.6.95 0x0278 ADC DRC Expander Slope Low Setting Register (Default Value: 0x0000_0000)

Offset: 0x0278			Register Name: AC_ADC_DRC_LKE
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/

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Offset: 0x0278			Register Name: AC_ADC_DRC_LKE
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0x0000	ADC_DRC_LKE The slope of the expander, which is determined by the equation that Ke = 1/R. R is the ratio of the expander, which is always an integer and the ke must be larger than 50. The format is 8.24. (The default value is <1:5>)

9.4.6.96 0x027C ADC DRC Expander High Output at Expander Threshold Register (Default Value: 0x0000_F45F)

Offset: 0x027C			Register Name: AC_ADC_DRC_HOPE
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xF45F	ADC_DRC_HOPE The output of the expander, which is determined by equation OPE/6.0206. The format is 8.24. (The default value is -70 dB)

9.4.6.97 0x0280 ADC DRC Expander Low Output at Expander Threshold Register (Default Value: 0x0000_8D6E)

Offset: 0x0280			Register Name: AC_ADC_DRC_LOPE
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x8D6E	ADC_DRC_LOPE The output of the expander, which is determined by equation OPE/6.0206. The format is 8.24. (The default value is -70 dB)

9.4.6.98 0x0284 ADC DRC Linear Slope High Setting Register (Default Value: 0x0000_0100)

Offset: 0x0284			Register Name: AC_ADC_DRC_HKN
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0100	ADC_DRC_HKN The slope of the linear, which is determined by the equation that Kn = 1/R. R is the ratio of the linear, which is always an integer. The format is 8.24. (The default value is <1:1>)

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9.4.6.99 0x0288 ADC DRC Linear Slope Low Setting Register (Default Value: 0x0000_0000)

Offset: 0x0288			Register Name: AC_ADC_DRC_LKN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0x0000	ADC_DRC_LKN The slope of the linear, which is determined by the equation that Kn = 1/R. R is the ratio of the linear, which is always an integer. The format is 8.24. (The default value is <1:1>)

9.4.6.100 0x028C ADC DRC Smooth Filter Gain High Attack Time Coef Register (Default Value: 0x0000_0002)

Offset: 0x028C			Register Name: AC_ADC_DRC_SFHAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:11	/	/	/
10:0	R/W	0x0002	ADC_DRC_SFHAT The smooth filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 5 ms)

9.4.6.101 0x0290 ADC DRC Smooth Filter Gain Low Attack Time Coef Register (Default Value: 0x0000_5600)

Offset: 0x0290			Register Name: AC_ADC_DRC_SFLAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0x5600	ADC_DRC_SFLAT The smooth filter attack time parameter setting, which is determined by the equation that AT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 5 ms)

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9.4.6.102 0x0294 ADC DRC Smooth Filter Gain High Release Time Coef Register (Default Value: 0x0000_0000)

Offset: 0x0294			Register Name: AC_ADC_DRC_SFHRT
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R/W	0x0000	ADC_DRC_SFHRT The gain smooth filter release time parameter setting, which is determined by the equation that RT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 200 ms)

9.4.6.103 0x0298 ADC DRC Smooth Filter Gain Low Release Time Coef Register (Default Value: 0x0000_0F04)

Offset: 0x0298			Register Name: AC_ADC_DRC_SFLRT
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0F04	ADC_DRC_SFLRT The gain smooth filter release time parameter setting, which is determined by the equation that RT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 200 ms)

9.4.6.104 0x029C ADC DRC MAX Gain High Setting Register (Default Value: 0x0000_FE56)

Offset: 0x029C			Register Name: AC_ADC_DRC_MXGHS
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xFE56	ADC_DRC_MXGHS The max gain setting, which is determined by equation MXG_{in}=MXG/6.0206. The format is 8.24 and must -20 dB < MXG < 30 dB (The default value is -10 dB)

9.4.6.105 0x02A0 ADC DRC MAX Gain Low Setting Register (Default Value: 0x0000_CB0F)

Offset: 0x02A0			Register Name: AC_ADC_DRC_MXGLS
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/

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Offset: 0x02A0			Register Name: AC_ADC_DRC_MXGLS
Bit	Read/Write	Default/Hex	Description
15:0	R/W	0xCB0F	ADC_DRC_MXGLS The max gain setting, which is determined by equation MXG_{in}=MXG/6.0206. The format is 8.24 and must -20 dB < MXG < 30 dB (The default value is -10 dB)

9.4.6.106 0x02A4 ADC DRC MIN Gain High Setting Register (Default Value: 0x0000_F95B)

Offset: 0x02A4			Register Name: AC_ADC_DRC_MNGHS
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xF95B	ADC_DRC_MNGHS The min gain setting, which is determined by equation MXG_{in}=MXG/6.0206. The format is 8.24 and must -60 dB ≤ MNG ≤ -40 dB (The default value is -40 dB)

9.4.6.107 0x02A8 ADC DRC MIN Gain Low Setting Register (Default Value: 0x0000_2C3F)

Offset: 0x02A8			Register Name: AC_ADC_DRC_MNGLS
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x2C3F	ADC_DRC_MNGLS The min gain setting, which is determined by equation MXG_{in}=MNG/6.0206. The format is 8.24 and must -60 dB ≤ MNG ≤ -40 dB (The default value is -40 dB)

9.4.6.108 0x02AC ADC DAP Expander Smooth Time High Coef Register (Default Value: 0x0000_0000)

Offset: 0x02AC			Register Name: AC_ADC_DRC_EPSHC
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/

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Offset: 0x02AC			Register Name: AC_ADC_DRC_EPSHC
Bit	Read/Write	Default/Hex	Description
10:0	R/W	0x0000	ADC_DRC_EPSHC The gain smooth filter release and attack time parameter setting in expander region, which is determined by the equation that RT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 30 ms)

9.4.6.109 0x02B0 ADC DRC Expander Smooth Time Low Coef Register (Default Value: 0x0000_640C)

Offset: 0x02B0			Register Name: AC_ADC_DRC_EPSLC
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x640C	ADC_DRC_EPSLC The gain smooth filter release and attack time parameter setting in expander region, which is determined by the equation that RT = 1-exp (-2.2Ts/tr). The format is 3.24. (The default value is 30 ms)

9.4.6.110 0x02B8 ADC DRC HPF Gain High Coef Register (Default Value: 0x0000_0100)

Offset: 0x02B8			Register Name: AC_ADC_DRC_HPFHGAIN
Bit	Read/Write	Default/Hex	Description
31:11	/	/	/
10:0	R/W	0x100	ADC_DRC_HPFHGAIN The gain of HPF coefficient setting, which format is 3.24. (gain = 1)

9.4.6.111 0x02BC ADC DRC HPF Gain Low Coef Register (Default Value: 0x0000_0000)

Offset: 0x02BC			Register Name: AC_ADC_DRC_HPFLGAIN
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0000	ADC_DRC_HPFLGAIN The gain of HPF coefficient setting, which format is 3.24. (gain = 1)

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9.4.6.112 0x0300 ADC1 Analog Control Register (Default Value: 0x001C_C055)

Offset: 0x0300			Register Name: ADC1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	ADC1_EN ADC1 Channel Enable 0: Disabled 1: Enabled
30	R/W	0x0	MIC1_PGA_EN MIC1 PGA Enable 0: Disabled 1: Enabled
29	R/W	0x0	ADC1 Dither Control 0: New Dither Off 1: New Dither On
28	R/W	0x0	MIC1_SIN_EN MIC1 Single Input Enable 0: Disable 1: Enable
27	R/W	0x0	FMINLEN FMINL Enable 0: Disable 1: Enable
26	R/W	0x0	FMINLG FMINL Gain Control 0: 0 dB 1: 6 dB
25:24	R/W	0x0	DSM_DITHER_LVL Dither Level Control (Dither level is positive ralated to the ctrl bits) 00: No Level 01: Min Level 10: Middle Level 11: Max Level
23	R/W	0x0	LINEINLEN LINEINL Enable 0: Disable 1: Enable

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Offset: 0x0300			Register Name: ADC1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
22	R/W	0x0	LINEINLG LINEINL Gain Control 0: 0 dB 1: 6 dB
21:20	R/W	0x1	IOPBUFFER PGA Vcm Buffer OP Bias Current Select 00: 6 uA 01: 7 uA 10: 8 uA 11: 9 uA
19:18	R/W	0x3	ADC1_PGA_CTRL_RCM ADC1 PGA Common Mode Input Impedance Control for MICIN 00: 100 kΩ 01: 75 kΩ 10: 50 kΩ 11: 25 kΩ
17:16	R/W	0x0	ADC1_PGA_IN_VCM_CTRL ADC1 PGA Common-Mode Voltage Control 00: 900 mV 01: 800 mV 10: 750 mV 11: 700 mV
15:14	R/W	0x3	IOPADC ADC1-ADC3 Bias Current Select 00: 1 uA 01: 2 uA 10: 3 uA 11: 4 uA
13	/	/	/

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Offset: 0x0300			Register Name: ADC1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
12:8	R/W	0x0	ADC1_PGA_GAIN_CTRL ADC1 PGA gain settings: 0x0: 0 dB 0x10: 21 dB 0x1: 6 dB 0x11: 22 dB 0x2: 6 dB 0x12: 23 dB 0x3: 6 dB 0x13: 24 dB 0x4: 9 dB 0x14: 25 dB 0x5: 10 dB 0x15: 26 dB 0x6: 11 dB 0x16: 27 dB 0x7: 12 dB 0x17: 28 dB 0x8: 13 dB 0x18: 29 dB 0x9: 14 dB 0x19: 30 dB 0xA: 15 dB 0x1A: 31 dB 0xB: 16 dB 0x1B: 32 dB 0xC: 17 dB 0x1C: 33 dB 0xD: 18 dB 0x1D: 34 dB 0xE: 19 dB 0x1E: 35 dB 0xF: 20 dB 0x1F: 36 dB
7:6	R/W	0x1	ADC1_IOPAAF ADC1 OP AAF Bias Current Select 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA. For example: ADC1_REG<15:14> = 11, IOPADC = 4 uA 00: 1.50*4 uA = 6 uA 01: 1.75*4 uA = 7 uA 10: 2.00*4 uA = 8 uA 11: 2.25*4 uA = 9 uA

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Offset: 0x0300			Register Name: ADC1_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
5:4	R/W	0x1	ADC1_IOPSDM1 ADC1 OP SDM Bias Current Select 1 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA.
3:2	R/W	0x1	ADC1_IOPSDM2 ADC1 OP SDM Bias Current Select 2 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA.
1:0	R/W	0x1	ADC1_IOPMIC ADC1 OP MIC Bias Current Select 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA.

9.4.6.113 0x0304 ADC2 Analog Control Register (Default Value: 0x001C_0055)

Offset: 0x0304			Register Name: ADC2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	ADC2_EN ADC2 Channel Enable 0: Disabled 1: Enabled
30	R/W	0x0	MIC2_PGA_EN MIC2 PGA Enable 0: Disabled 1: Enabled

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Offset: 0x0304			Register Name: ADC2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
29	R/W	0x0	ADC2 Dither Control 0: New Dither Off 1: New Dither On
28	R/W	0x0	MIC2_SIN_EN MIC2 Single Input Enable 0: Disable 1: Enable
27	R/W	0x0	FMINREN FMINR Enable 0: Disable 1: Enable
26	R/W	0x0	FMINRG FMINR Gain Control 0: 0 dB 1: 6 dB
25:24	R/W	0x0	DSM_DITHER_LVL Dither Level Control (Dither level is positive ralated to the ctrl bits) 00: No Level 01: Min Level 10: Middle Level 11: Max Level
23	R/W	0x0	LINEINREN LINEINR Enable 0: Disable 1: Enable
22	R/W	0x0	LINEINRG LINEINR Gain Control 0: 0 dB 1: 6 dB
21:20	R/W	0x1	IOPBUFFER PGA Vcm Buffer OP Bias Current Select 00: 6 uA 01: 7 uA 10: 8 uA 11: 9 uA

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Offset: 0x0304			Register Name: ADC2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
19:18	R/W	0x3	ADC2_PGA_CTRL_RCM ADC2 PGA Common Mode Input Impedance Control for MICIN 00: 100 kΩ 01: 75 kΩ 10: 50 kΩ 11: 25 kΩ
17:16	R/W	0x0	ADC2_PGA_IN_VCM_CTRL ADC2 PGA Common-Mode Voltage Control 00: 900 mV 01: 800 mV 10: 750 mV 11: 700 mV
15:13	/	/	/
12:8	R/W	0x0	ADC2_PGA_GAIN_CTRL ADC2 PGA Gain Settings 0x0: 0 dB 0x10: 21 dB 0x1: 6 dB 0x11: 22 dB 0x2: 6 dB 0x12: 23 dB 0x3: 6 dB 0x13: 24 dB 0x4: 9 dB 0x14: 25 dB 0x5: 10 dB 0x15: 26 dB 0x6: 11 dB 0x16: 27 dB 0x7: 12 dB 0x17: 28 dB 0x8: 13 dB 0x18: 29 dB 0x9: 14 dB 0x19: 30 dB 0xA: 15 dB 0x1A: 31 dB 0xB: 16 dB 0x1B: 32 dB 0xC: 17 dB 0x1C: 33 dB 0xD: 18 dB 0x1D: 34 dB 0xE: 19 dB 0x1E: 35 dB 0xF: 20 dB 0x1F: 36 dB

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Offset: 0x0304			Register Name: ADC2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
7:6	R/W	0x1	ADC2_IOPAAF ADC2 OP AAF Bias Current Select 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA.
5:4	R/W	0x1	ADC2_IOPSDM1 ADC2 OP SDM Bias Current Select 1 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA.
3:2	R/W	0x1	ADC2_IOPSDM2 ADC2 OP SDM Bias Current Select 2 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA.
1:0	R/W	0x1	ADC2_IOPMIC ADC2 OP MIC Bias Current Select 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA.

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9.4.6.114 0x0308 ADC3 Analog Control Register (Default Value: 0x001C_0055)

Offset: 0x0308			Register Name: ADC3_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	ADC3_EN ADC3 Channel Enable 0: Disabled 1: Enabled
30	R/W	0x0	MIC3_PGA_EN MIC3 PGA Enable 0: Disabled 1: Enabled
29	R/W	0x0	ADC3 Dither Control 0: New Dither Off 1: New Dither On
28	R/W	0x0	MIC3_SIN_EN MIC3 Single Input Enable 0: Disabled 1: Enabled
27:26	/	/	/
25:24	R/W	0x0	DSM_DITHER_LVL Dither Level Control (Dither level is positive ralated to the ctrl bits) 00: No Level 01: Min Level 10: Middle Level 11: Max Level
23:22	/	/	/
21:20	R/W	0x1	IOPBUFFER PGA Vcm Buffer OP Bias Current Select 00: 6 uA 01: 7 uA 10: 8 uA 11: 9 uA

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Offset: 0x0308			Register Name: ADC3_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
19:18	R/W	0x3	ADC3_PGA_CTRL_RCM ADC3 PGA Common Mode Input Impedance Control for MICIN 00: 100 kΩ 01: 75 kΩ 10: 50 kΩ 11: 25 kΩ
17:16	R/W	0x0	ADC3_PGA_IN_VCM_CTRL ADC3 PGA Common-Mode Voltage Control 00: 900 mV 01: 800 mV 10: 750 mV 11: 700 mV
15:13	/	/	/
12:8	R/W	0x0	ADC3_PGA_GAIN_CTRL ADC3 PGA Gain Settings 0x0: 0 dB 0x10: 21 dB 0x1: 6 dB 0x11: 22 dB 0x2: 6 dB 0x12: 23 dB 0x3: 6 dB 0x13: 24 dB 0x4: 9 dB 0x14: 25 dB 0x5: 10 dB 0x15: 26 dB 0x6: 11 dB 0x16: 27 dB 0x7: 12 dB 0x17: 28 dB 0x8: 13 dB 0x18: 29 dB 0x9: 14 dB 0x19: 30 dB 0xA: 15 dB 0x1A: 31 dB 0xB: 16 dB 0x1B: 32 dB 0xC: 17 dB 0x1C: 33 dB 0xD: 18 dB 0x1D: 34 dB 0xE: 19 dB 0x1E: 35 dB 0xF: 20 dB 0x1F: 36 dB

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Offset: 0x0308			Register Name: ADC3_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
7:6	R/W	0x1	ADC3_IOPAAF ADC3 OP AAF Bias Current Select 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA
5:4	R/W	0x1	ADC3_IOPSDM1 ADC3 OP SDM Bias Current Select 1 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA
3:2	R/W	0x1	ADC3_IOPSDM2 ADC3 OP SDM Bias Current Select 2 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA
1:0	R/W	0x1	ADC3_IOPMIC ADC3 OP MIC Bias Current Select 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA

9.4.6.115 0x0310 DAC Analog Control Register (Default Value: 0x0015_0000)

Offset: 0x0310			Register Name: DAC_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/

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Offset: 0x0310			Register Name: DAC_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
23	R/W	0x0	CURRENT_TEST_SELECT Internal Current Sink Test Enable (from MICIN3P pin) 0: Normal 1: For Debug
22	/	/	/
21:20	R/W	0x1	IOPVRS VRA2 Buffer OP and Headphone Feedback Buffer OP Bias Current Select 00: 6 uA 01: 7 uA 10: 8 uA 11: 9 uA
19:18	R/W	0x1	ILINEOUTAMPS LINEOUTLL/R AMP Bias Current Select 00: 6 uA 01: 7 uA 10: 8 uA 11: 9 uA
17:16	R/W	0x1	IOPDACS OPDACL/R Bias Current Select 00: 6 uA 01: 7 uA 10: 8 uA 11: 9 uA
15	R/W	0x0	DACL_EN DACL Enable 0: Disabled 1: Enabled
14	R/W	0x0	DACR_EN DACR Enable 0: Disabled 1: Enabled
13	R/W	0x0	LINEOUTLEN Left Channel LINEOUT Enable 0: Disable 1: Enable

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Offset: 0x0310			Register Name: DAC_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
12	R/W	0x0	LMUTE DACL to Left Channel LINEOUT Mute Control 0: Mute 1: Not mute
11	R/W	0x0	LINEOUTREN Right Channel LINEOUT Enable 0: Disable 1: Enable
10	R/W	0x0	RMUTE DACR to Right Channel LINEOUT Mute Control 0: Mute 1: Not mute
9:7	/	/	/
6	R/W	0x0	LINEOUTL_DIFFEN Left Channel LINEOUT Output Control 0: Single-End 1: Differential
5	R/W	0x0	LINEOUTR_DIFFEN Right Channel LINEOUT Output Control 0: Single-End 1: Differential
4:0	R/W	0x0	LINEOUT_VOL_CTRL LINEOUT Volume Control. Total 30 level from 0x1F to 0x02 with the volume 0 dB to -43.5 dB, -1.5 dB/step, mute when 00000 & 00001.

9.4.6.116 0x0318 MICBIAS Analog Control Register (Default Value: 0x4000_3030)

Offset: 0x0318			Register Name: MICBIAS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	/	/	/

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Offset: 0x0318			Register Name: MICBIAS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
30:28	R/W	0x4	SELDETADCFS Select sample interval of the ADC sample 000: 2 ms … 100: 32 ms … 111: 256 ms
27:26	R/W	0x0	SELDETADCDB Select debounce time when jack removal 00: 128 ms 01: 256 ms 10: 512 ms 11: 1024 ms
25:24	R/W	0x0	SELDETADCBF Select the time to enable HBIAS before MICADC work 00: 2 ms 01: 4 ms 10: 8 ms 11: 16 ms
23	R/W	0x0	JACKDETEN Jack detect enable 0: Disable 1: Enable
22:21	R/W	0x0	SELDETADCDY Select the delay time to pull low the micdet when jack removal 00: 0.5 ms 01: 1 ms 10: 1.5 ms 11: 2 ms
20	R/W	0x0	MICADCEN Microphone detect ADC enable 0: Disabled 1: Enabled
19	R/W	0x0	POPFREE When this bit is 0, HBIAS MICADC is controlled by registor

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Offset: 0x0318			Register Name: MICBIAS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
18	R/W	0x0	DET_MODE MIC Detect Mode 0: Jack in pull low 1: Jack in pull high
17	R/W	0x0	AUTOPLEN Enable the function to auto pull low MICDET when jack removal 0: Disabled 1: Enabled
16	R/W	0x0	MICDETPL When this bit is 1and AUTOPLEN is 0, the MICDET is pulled down to GND.
15	R/W	0x0	HMICBIASEN Headphone Microphone Bias Enable 0: Disabled 1: Enabled
14:13	R/W	0x1	HBIASSEL HMICBIAS Voltage Level Select 00: 1.88 V 01: 2.09 V 10: 2.33 V 11: 2.55 V
12	R/W	0x1	HMIC_BIAS_CHOPPER_EN HMIC BIAS Chopper Enable 0: Disabled 1: Enabled
11:10	R/W	0x0	HMIC_BIAS_CHOPPER_CLK_SEL HMIC BIAS Chopper Clock Select 00: 250 kHz 01: 500 kHz 10: 1 MHz 11: 2 MHz
9:8	/	/	/
7	R/W	0x0	MMICBIASEN Master Microphone Bias Enable 0: Disabled 1: Enabled

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Offset: 0x0318			Register Name: MICBIAS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
6:5	R/W	0x1	MBIASSEL MMICBIAS Voltage Level Select 00: 1.88 V 01: 2.09 V 10: 2.33 V 11: 2.50 V
4	R/W	0x1	MMIC_BIAS_CHOPPER_EN MMIC BIAS Chopper Enable 0: Disabled 1: Enabled
3:2	R/W	0x0	MMIC_BIAS_CHOPPER_CLK_SEL MMIC BIAS Chopper Clock Select 00: 250 kHz 01: 500 kHz 10: 1 MHz 11: 2 MHz
1:0	/	/	/

9.4.6.117 0x031C Ramp Control Register (Default Value: 0x0018_0000)

Offset: 0x031C			Register Name: RAMP_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	RAMP_RISE_INT_EN RAMP Rise Interrupt Enable 0: Enabled 1: Disabled
30	R/W1C	0x0	RAMP_RISE_INT RK Increase Upward Finish and Rampen Pull Down Instruction 0: No Pending IRQ 1: Ramp Rise Finish Pending Interrupt Write '1' to clear this interrupt.
29	R/W	0x0	RAMP_FALL_INT_EN RAMP Fall Int Enable 0: Enabled 1: Disabled

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Offset: 0x031C			Register Name: RAMP_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
28	R/W1C	0x0	RAMP_FALL_INT RK Downward Decrease Finish and Rampen Pull Down Instruction 0: No Pending IRQ 1: Ramp Fall Finish Pending Interrupt Write '1' to clear this interrupt.
27:25	/	/	/
24	R/W	0x0	RAMP_SRST Ramp Soft Reset 0: Disabled 1: Enabled
23:21	/	/	/
20:16	R/W	0x18	RAMP_CLK_DIV_M Analog Ramp Clk Div Freq Value : M (from 0 to 31, Default: 24). Ana_Ramp_Clk= 24MHz/(M+1) Default Ramp Clk Freq: 24MHz/(24+1)=960 kHz
15	R/W	0x0	HP_PULL_OUT_EN Heanphone Pullout Enable 0: Disabled 1: Enabled

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Offset: 0x031C			Register Name: RAMP_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
14:12	R/W	0x0	RAMP_HOLD_STEP RAMP HOLD STEP 000: 9600 001: 19200 010: 38400 011: 76800 100: 96000 101: 115200 110: 153600 111: 192000 Ramp Hold Time = Ramp Hold Step/Ramp Clk Freq When Ramp Clk Freq is equal to 960 kHz, the corresponding Ramp Hold time of each gear is: 000: 9600/960 kHz=10 ms 001: 19200/960 kHz=20 ms 010: 38400/960 kHz=40 ms 011: 76800/960 kHz=80 ms 100: 96000/960 kHz=100 ms 101: 115200/960 kHz=120 ms 110: 153600/960 kHz=160 ms 111: 192000/960 kHz=200 ms
11:10	/	/	/
9:8	R/W	0x0	GAP_STEP Gap Step 00: ramp step 01: ramp step*2 10: ramp step*3 11: ramp step*4
7	/	/	/

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Offset: 0x031C			Register Name: RAMP_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
6:4	R/W	0x0	RAMP_STEP RK Frequency Gear, Control Ramp Rise/Fall Total Time 000: 20 001: 30 010: 40 011: 60 100: 80 101: 120 110: 160 111: 240 Ramp Rise/Fall Total Time =(Ramp Step/Ramp Clk Freq)*4096 When Default Ramp Clk Freq is equal to 960 kHz, the corresponding time of each gear is: 000: (20/960kHz)*4096=85.3 ms 001: (30/960kHz)*4096=128 ms 010: (40/960kHz)*4096=170.6 ms 011: (60/960kHz)*4096=256 ms 100: (80/960kHz)*4096=341.3 ms 101: (120/960kHz)*4096=512 ms 110: (160/960kHz)*4096=682.6 ms 111: (240/960kHz)*4096=1024 ms
3	R/W	0x0	RMD_EN Ramp Manual Down Enable 0: Disabled 1: Enabled
2	R/W	0x0	RMU_EN Ramp Manual Up Enable 0: Disabled 1: Enabled
1	R/W	0x0	RMC_EN Ramp Manual Control Enable 0: Disabled 1: Enabled

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Offset: 0x031C			Register Name: RAMP_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	RD_EN Ramp Digital Enable 0: Disabled 1: Enabled

9.4.6.118 0x0320 BIAS Analog Control Register (Default Value: 0x0000_0080)

The register is not controlled by the clock and reset of Audio Codec, only controlled by the clock and reset of system bus.

Offset: 0x0320			Register Name: BIAS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x80	BIASDATA Bias Current Register Setting Data

9.4.6.119 0x0328 HMIC Control Register (Default Value: 0x0000_0008)

Offset: 0x0328			Register Name: HMIC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:23	/	/	/
22:21	R/W	0x0	HMIC_SAMPLE_SELECT Down Sample Setting Select 00: Down by 1, 128 Hz 01: Down by 2, 64 Hz 10: Down by 4, 32 Hz 11: Down by 8, 16 Hz
20:16	R/W	0x0	MDATA_THRESHOLD MIC DET EN Threshold Value

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Offset: 0x0328			Register Name: HMIC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
15:14	R/W	0x0	HMIC_SF HMIC Smooth Filter setting 00: by pass 01: (x1+x2)/2 10: (x1+x2+x3+x4)/4 11: (x1+x2+x3+x4+ x5+x6+x7+x8)/8
13:10	R/W	0x0	HMIC_M Debounce when the MIC Key down or up. 0000:1 samlpe data 0001:2 samlpe data ... 1111:16 samlpe data
9:6	R/W	0X0	HMIC_N Debounce when earphone plug in or pull out 125 ms to 2 s 0000: 125 ms 0001: 250 ms ... 1111: 2 s
5:3	R/W	0x1	MDATA_THRESHOLD_DEBOUNCE MDATA Threshold Debounce 000: 0 001: 1 010: 2 011: 3 100: 4 101: 5 110: 6 111: 7
2	R/W	0x0	JACK_OUT_IRQ_EN MIC Detect Interrupt Set 0: Disabled 1: Enabled

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Offset: 0x0328			Register Name: HMIC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	JACK_IN_IRQ_EN MIC Detect Interrupt Set 0: Disabled 1: Enabled
0	R/W	0x0	MIC_DET_IRQ_EN MIC Detect Interrupt Set 0: Disabled 1: Enabled

9.4.6.120 0x032C HMIC Status Register (Default Value: 0x0000_6000)

Offset: 0x032C			Register Name: HMIC_STS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:15	/	/	/
14:13	R/W	0x3	MDATA_DISCARD After MIC DATA data is received, the first N-data will be discarded. N defined as follows: 00: None discarded 01: 1-data discarded 10: 2-data discarded 11: 4-data discarded
12:8	R	0x0	HMIC_DATA HMIC Average Data
7:5	/	/	/
4	R/W1C	0x0	JACK_DET_OIRQ Jack output detect pending interrupt 0: No Pending IRQ 1: Pending IRQ Writing 1 clear pending.
3	R/W1C	0x0	JACK_DET_IIRQ Jack input detect pending interrupt 0: No Pending IRQ 1: Pending IRQ Writing 1 clear pending.
2:1	/	/	/

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Offset: 0x032C			Register Name: HMIC_STS
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W1C	0x0	MIC_DET_ST MIC detect pending interrupt 0: No pending IRQ 1: Pending IRQ Writing 1 clear pending.

9.4.6.121 0x0340 Headphone2 Analog Control Register (Default Value: 0x0640_4000)

Offset: 0x0340			Register Name: HP2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	HPFB_BUF_EN Headphone Feedback Buffer OP Enable 0: Disable 1: Enable
30:28	R/W	0x0	HEADPHONE_GAIN HeadPhone Gain 000: 0 dB 001: -6 dB 010: -12 dB 011: -18 dB 100: -24 dB 101: -30 dB 110: -36 dB 111: -42 dB
27:26	R/W	0x1	HPFB_RES Headphone Feedback Big Resistor Control 00: 0.88 MΩ 01: 1.00 MΩ 10: 1.08 MΩ 11: 1.20 MΩ
25:24	R/W	0x2	OPDRV_CUR Headphone OP Output Stage Current Setting 00: Min 11: Max

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Offset: 0x0340			Register Name: HP2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
23:22	R/W	0x1	IOPHP Headphone L/R OP Bias Current Select 00: 6 uA 01: 7 uA 10: 8 uA 11: 9 uA
21	R/W	0x0	HP_DRVEN Headphone Driver Enable 0: Disable 1: Enable
20	R/W	0x0	HP_DRVOUTEN Headphone Driver Output Enable 0: Disabled 1: Enabled
19	R/W	0x0	RSWITCH RSwitch 0: HPOUT OUTPUT VCM of RAMP_DAC 1: VRA1
18	R/W	0x0	RAMPEN Ramp DAC Enable 0: Disabled 1: Enabled
17	R/W	0x0	HPFB_IN_EN Headphone Feedback PAD IN Switch Enable 0: Disabled 1: Enabled
16	R/W	0x0	RAMP_FINAL_CONTROL Headphone Ramp Final Step Control 0: Ramp Output Select Ramp 1: Ramp Output Select HPFB buffer Output
15	R/W	0x0	RAMP_OUT_EN Ramp Output Switch Enable 0: Disable 1: Enable

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Offset: 0x0340			Register Name: HP2_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
14:13	R/W	0x2	RAMP_FINAL_STATE_RES Ramp Final State Resistor 00: 2.5k 01: 5.0k 10: 10k 11: 20k
9:8	R/W	0x0	HPFB_BUF_OUTPUT_CURRENT Headphone Feedback Buffer Output Current Select 00: 35I 01: 28I 10: 45I 11: 38I I=7 uA
7:0	/	/	/

9.4.6.122 0x0348 POWER Analog Control Register (Default Value: 0x8000_3325)

The register is not controlled by the clock and reset of Audio Codec, only controlled by the clock and reset of system bus.

Offset: 0x0348			Register Name: POWER_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x1	ALDO_EN ALDO Enable 0: Disabled 1: Enabled
30	R/W	0x0	HPLDO_EN HPLDO Enable 0: Disabled 1: Enabled
29	R/W	0x0	VAR1SPEEDUP_DOWN_Further_CTRL VAR1 Speedup Down Further Control In Adda Analog 0: The digital logic signal input by the digital-analog interface pin controls the var1_speedup_down function (that is, the var1 signal is rapidly pulled up/down) 1: Writing 1 can finish the var1_speedup_down function (ignore the control of the digital-analog interface pin)

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Offset: 0x0348			Register Name: POWER_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
28:17	/	/	/
16	R	0x0	AVCCPOR Avccpor Monitor
15	/	/	/
14:12	R/W	0x3	ALDO_OUTPUT_VOLTAGE ALDO Output Voltage Control 000: 2.03 V 001: 1.95 V 010: 1.87 V 011: 1.80 V 100: 1.73 V 101: 1.67 V 110: 1.61 V 111: 1.56 V
11	/	/	/
10:8	R/W	0x3	HPLDO_OUTPUT_VOLTAGE HPLDO Output Voltage Control 000: 2.03 V 001: 1.95 V 010: 1.87 V 011: 1.80 V 100: 1.73 V 101: 1.67 V 110: 1.61 V 111: 1.56 V
7:0	R/W	0x25	BG_TRIM BG Output Voltage Trimming Only low 6-bit is used. The BG output voltage range is from 0.7 V to 1.208 V.

9.4.6.123 0x034C ADC Current Analog Control Register (Default Value: 0x0015_1515)

Offset: 0x034C			Register Name: ADC_CUR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/

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Offset: 0x034C			Register Name: ADC_CUR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
21:20	R/W	0x1	ADC3_IOPMIC2 ADC3 OP MIC2 Bias Current Select 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA
19:18	R/W	0x1	ADC3_OUTPUT_CURRENT ADC3 OP MIC1 Output Current Select 00: 15I 01: 20I 10: 35I 11: 40I I=7 uA
17:16	R/W	0x1	ADC3_OUTPUT_CURRENT ADC3 OP MIC2 Output Current Select 00: 15I 01: 20I 10: 35I 11: 40I I=7 uA
15:14	/	/	/
13:12	R/W	0x1	ADC2_IOPMIC2 ADC2 OP MIC2 Bias Current Select 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA.
11:10	R/W	0x1	ADC2_OUTPUT_CURRENT ADC2 OP MIC1 Output Current Select 00: 15I 01: 20I 10: 35I 11: 40I I=7 uA

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Offset: 0x034C			Register Name: ADC_CUR_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
9:8	R/W	0x1	ADC2_OUTPUT_CURRENT ADC2 OP MIC2 Output Current Select 00: 15I 01: 20I 10: 35I 11: 40I I=7 uA
7:6	/	/	/
5:4	R/W	0x1	ADC1_IOPMIC2 ADC1 OP MIC2 Bias Current Select 00: 1.50*IOPADC 01: 1.75*IOPADC 10: 2.00*IOPADC 11: 2.25*IOPADC IOPADC is defined by ADC1_REG<15:14> from 1 uA to 4 uA.
3:2	R/W	0x1	ADC1_OUTPUT_CURRENT ADC1 OP MIC1 Output Current Select 00: 15I 01: 20I 10: 35I 11: 40I I=7 uA
1:0	R/W	0x1	ADC1_OUTPUT_CURRENT ADC1 OP MIC2 Output Current Select 00: 15I 01: 20I 10: 35I 11: 40I I=7 uA

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10 Interfaces

10.1 TWI

10.1.1 Overview

The Two Wire Interface (TWI) provides an interface between a CPU and any TWI-bus-compatible device that connects via the TWI bus. The TWI is designed to be compatible with the standard I2C bus protocol. The communication of the TWI is carried out by a byte-wise mode based on interrupt polled handshaking. Each device on the TWI bus is recognized by a unique address and can operate as either transmitter or receiver, a device connected to the TWI bus can be considered as master or slave when performing data transfers. Note that a master device is a device that initiates a data transfer on the bus and generates the clock signals to permit the transfer. During this transfer, any device addressed by this master is considered a slave.

The TWI has the following features:

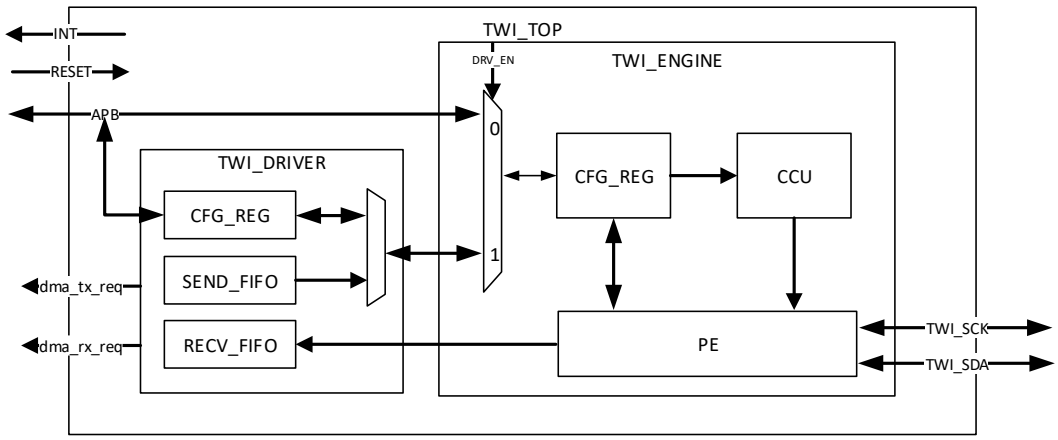
- Compliant with I2C bus standard
- Supports standard mode (up to 100 kbit/s) and fast mode (up to 400 kbit/s)
- Supports 7-bit and 10-bit device addressing modes
- Supports master mode or slave mode
- Master mode features:
  - Supports the bus arbitration in the case of multiple master devices
  - Supports clock synchronization and bit and byte waiting
  - Supports packet transmission and DMA
- Slave mode features:
  - Interrupt on address detection
- The TWI controller includes one TWI engine and one TWI driver. And the TWI driver supports packet transmission and DMA mode when TWI works in master mode

10.1.2 Block Diagram

Figure 10-1 shows the block diagram of TWI.

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Figure 10-1 TWI Block Diagram



TWI contains the following sub-blocks:

Table 10-1 TWI Sub-blocks

Sub-block	Description
RESET	Module reset signal
INT	Module output interrupt signal
CFG_REG	Module configuration register in TWI
PE	Packet encoding/decoding
CCU	Module clock controller unit
SEND_FIFO	The register address bytes and the written data bytes are buffered in SEND_FIFO
RECV_FIFO	The read data bytes are buffered in RECV_FIFO

The controller includes TWI engine and TWI driver. Each time the TWI engine sends a START signal, a STOP signal, or a BYTE data, or a corresponding ACK, the TWI engine will generate an interrupt, and wait for the CPU to process and clear the interrupt before the next START, STOP, or BYTE, ACK transmission can be performed. Therefore, when a device communication is completed, many interrupts will be generated, and the CPU needs to wait for the previous interrupt before it can configure the next one. The TWI driver defines each communication with the device as a packet transmission. The CPU can directly configure the slave address, register address and data transmission for one or more package transmissions without waiting for interruption, then start the TWI driver, and the TWI driver can control the TWI engine to complete a pre-configured communication, and report an interrupt to the CPU after completion.

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10.1.3 Functional Description

10.1.3.1 External Signals

The TWI controller has 4 TWI modules called TWI0, TWI1, TWI2, and TWI3. The following table describes the external signals of the TWI. The TWIn-SCK and TWIn-SDA are bidirectional I/O, when the TWI is configured as a master device, the TWIn-SCK is an output pin; when the TWI is configurable as a slave device, the TWIn-SCK is an input pin. When using TWI, the corresponding PADs are selected as TWI function via section 9.7 "GPIO".

Table 10-2 TWI External Signals

Signal	Description	Type
TWI0-SCK	TWI0 Clock Signal	I/O, OD
TWI0-SDA	TWI0 Serial Data	I/O, OD
TWI1-SCK	TWI1 Clock Signal	I/O, OD
TWI1-SDA	TWI1 Serial Data	I/O, OD
TWI2-SCK	TWI2 Clock Signal	I/O, OD
TWI2-SDA	TWI2 Serial Data	I/O, OD
TWI3-SCK	TWI3 Clock Signal	I/O, OD
TWI3-SDA	TWI3 Serial Data	I/O, OD

10.1.3.2 Clock Sources

Each TWI controller has an input clock source. The following table describes the clock sources for TWI. After selecting a proper clock, users must open the gating of TWI and release the corresponding reset bit.

For more details on the clock setting, configuration, and gating information, see section 3.3 "CCU".

Table 10-3 TWI Clock Sources

Clock Sources	Description
APB1 Bus	TWI clock source. Refer to CCU for details on APB1.

10.1.3.3 Write/Read Timing in Standard and Extended Addressing Mode

This section is the 7-bit/10-bit addressing mode of the entire TWI protocol to read and write device registers. It can be achieved by directly using the TWI engine or using the TWI driver to control the TWI engine.

Figure 10-2 describes the write timing in 7-bit standard addressing mode.

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Figure 10-2 Write Timing in 7-bit Standard Addressing Mode

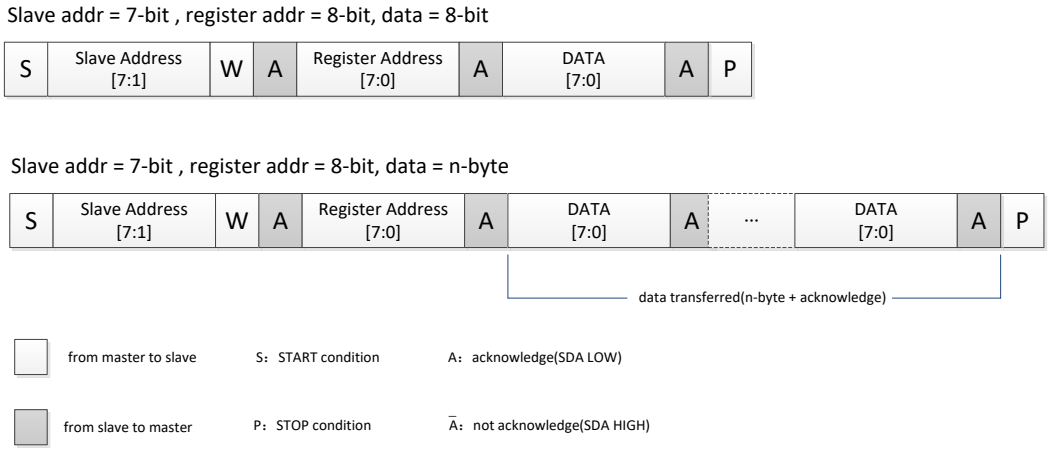


Figure 10-3 describes the read timing in 7-bit standard address mode.

Figure 10-3 Read Timing in 7-bit Standard Addressing Mode

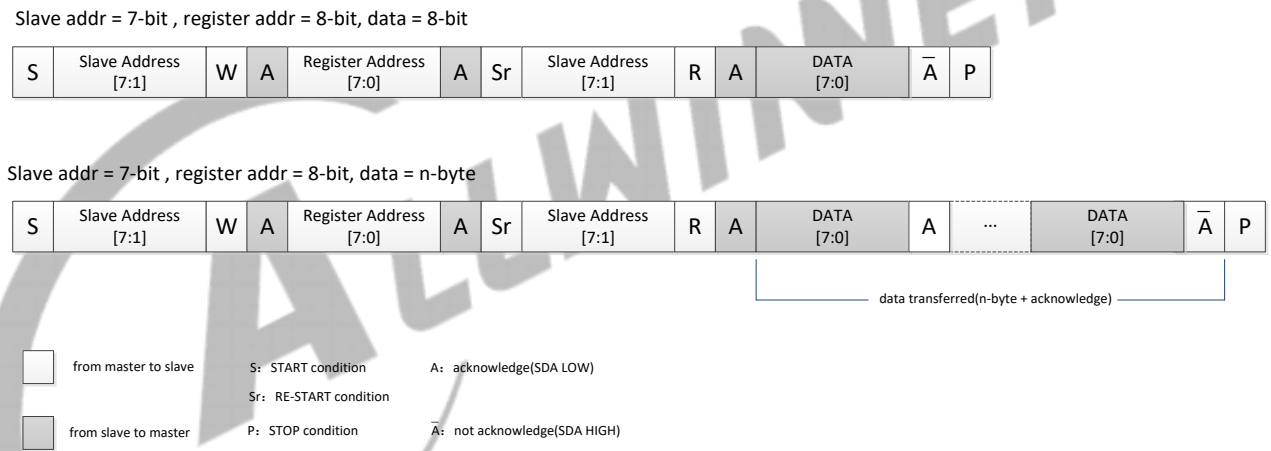
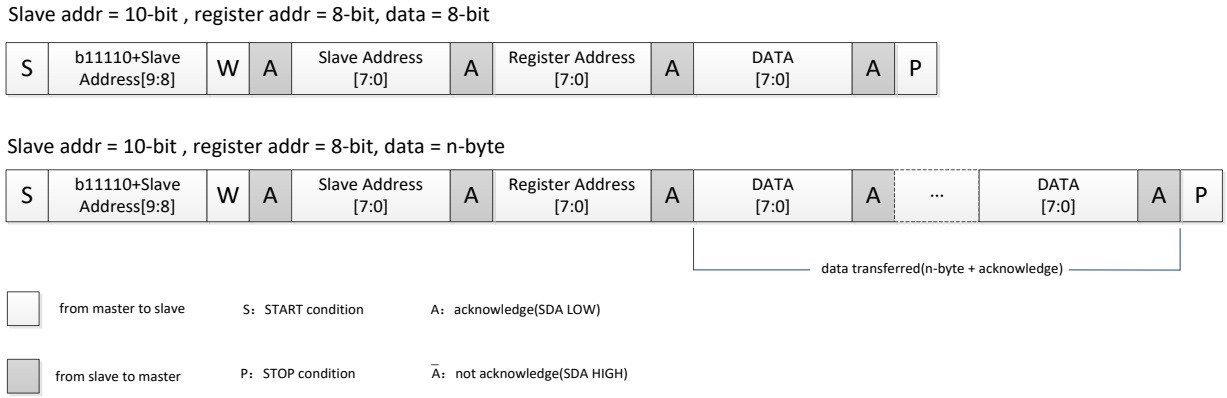


Figure 10-4 describes the write timing in 10-bit extended address mode.

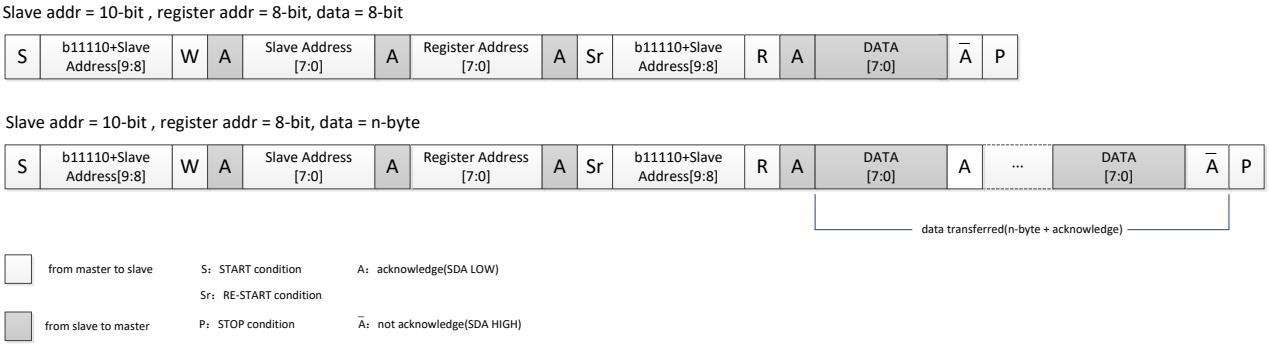
Figure 10-4 Write Timing in 10-bit Extended Addressing Mode



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Figure 10-5 describes the read timing in 10-bit extended address mode.

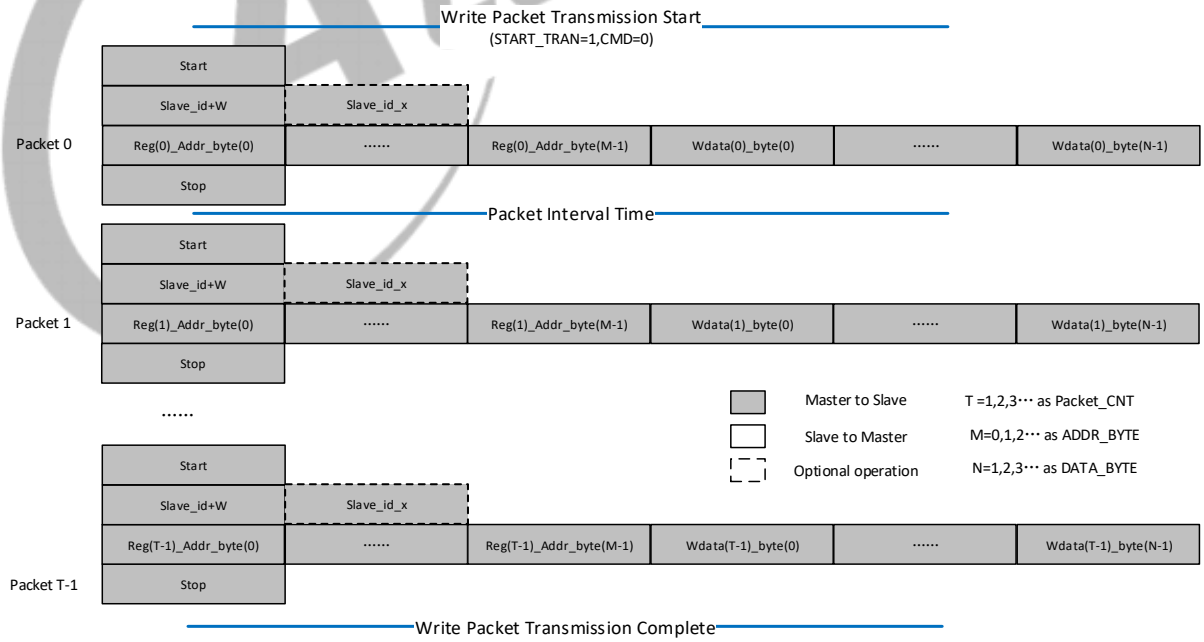
Figure 10-5 Read Timing in 10-bit Extended Addressing Mode



10.1.3.4 Write/Read Packet Transmission of TWI Driver

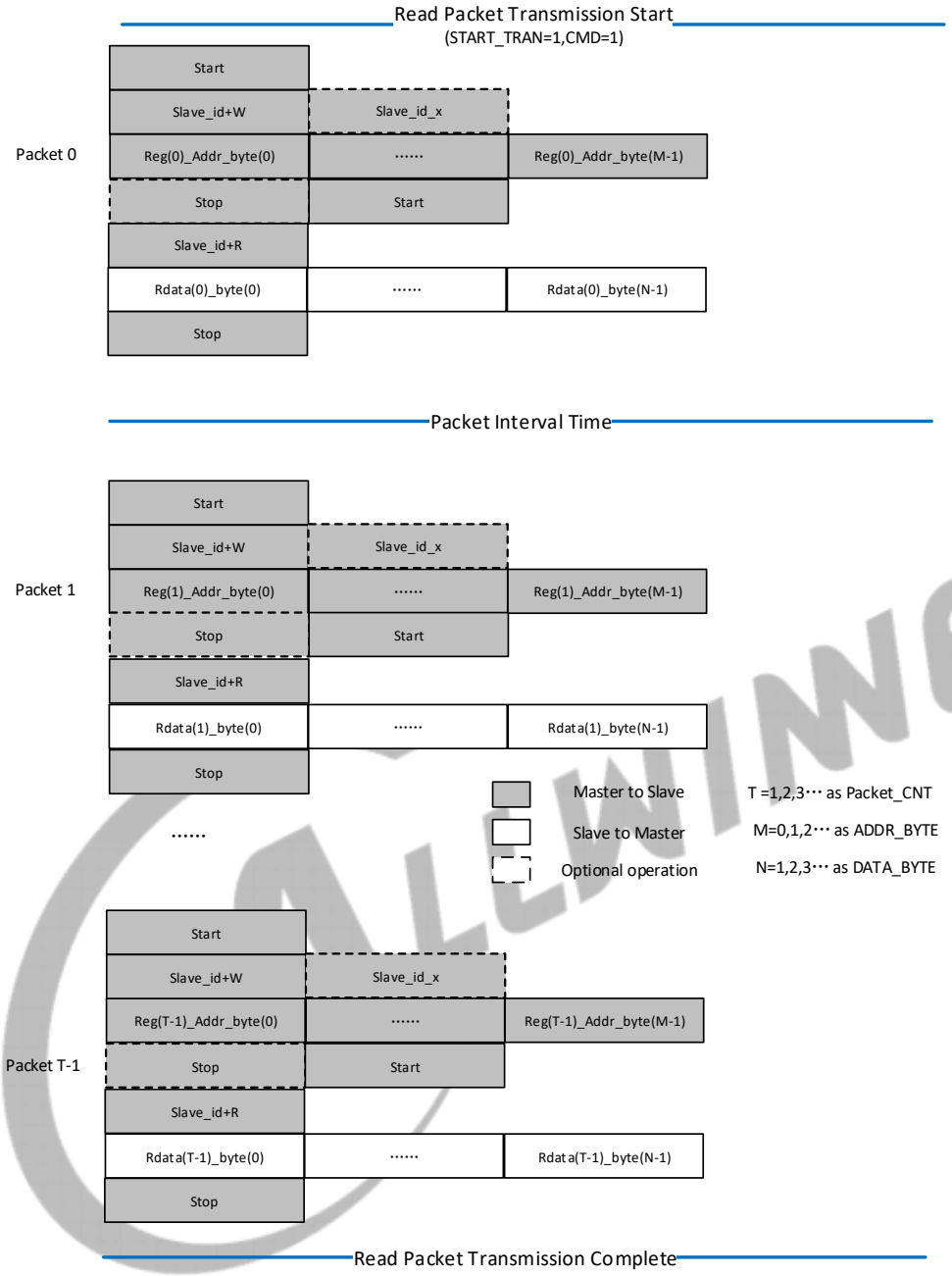
The TWI driver is only supported for master mode. When the TWI works in master mode, the TWI driver drives the TWI engine for one or more packet transmission instead of the CPU host. Packet transmission is defined in the following figures. The register address bytes and the written data bytes are buffered in SEND_FIFO, the read data bytes are buffered in RECV_FIFO.

Figure 10-6 TWI Driver Write Packet Transmission



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Figure 10-7 TWI Driver Read Packet Transmission



10.1.3.5 Master and Slave Mode of TWI Engine

In Master mode, the CPU host controls the TWI engine by writing command and data to its registers. The TWI engine transmits an interrupt to CPU when each time a byte transfer is done or a START/STOP command is detected. The CPU host can poll the status register if the interrupt mechanism is not disabled by the CPU host.

When the CPU host wants to start a bus transfer, it initiates a bus START to enter the master mode by setting **TWI_CNTR**[M_STA] to high. The TWI engine will assert the INT line and **TWI_CNTR**[INT_FLAG] to indicate a completion for the START command and each consequent byte transfer. At each interrupt, the CPU host needs

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to check the current state by the TWI_STAT register. A transfer must conclude with the STOP command by setting TWI_CNTR[M_STP] to high.

In Slave mode, the TWI engine also constantly samples the bus and look for its own slave address during addressing cycles. Once a match is found, it is addressed, and the TWI engine interrupts the CPU host with the corresponding status. Upon request, the CPU host should read the status, read/write the TWI_DATA register, and set the TWI_CNTR register. After each byte transfer, a slave device always stops the operation of the remote master by holding the next low pulse on the SCL line until the CPU host responds to the status of the previous byte transfer or START command.

10.1.3.6 Generation of Repeated Start

After the data transfer, if the master still requires the bus, it can signal another Start followed by another slave address without signaling a Stop.

10.1.3.7 Programming State Diagram

Figure 10-8 shows the TWI programming state diagram. For the value between two states, see the TWI_STAT register in section 9.1.6.5.

M_SEND_S: master sends START signal;

M_SEND_ADDR: master sends slave address;

M_SEND_XADD: master sends slave extended address;

M_SEND_SR: master repeated start;

M_SEND_DATA: master sends data;

M_SEND_P: master sends STOP signal;

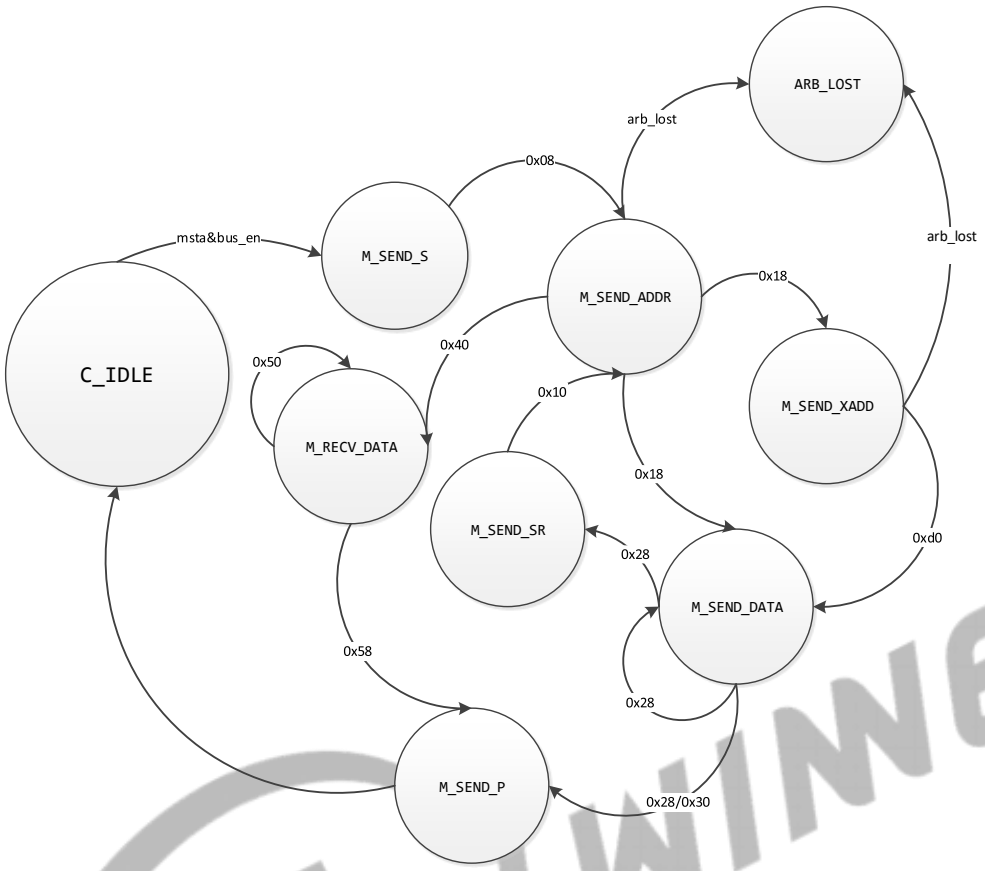
M_RECV_DATA: master receives data;

ARB_LOST: Arbitration lost;

C_IDLE: Idle.

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Figure 10-8 TWI Programming State Diagram



10.1.4 Programming Guidelines

The TWI controller operates in an 8-bit data format. The data on the TWI_SDA line is always 8 bits long. At first, the TWI controller sends a start condition. When in the addressing formats of 7-bit, the TWI sends out an 8-bit message which includes 7 MSB slave address and 1 LSB read/write flag. The least significant of the salve address indicates the direction of transmission. When the TWI works in 10-bit slave address mode, the operation will be divided into two steps, for details on the operation, refer to register description in Section 10.1.6.1 and 10.1.6.2.

The following takes the TWI module in the CPUX domain as an example.

10.1.4.1 Initialization for TWI Engine

To initialize the TWI engine, perform the following steps:

Step 1 Configure corresponding GPIO multiplex function as TWI mode.

Step 2 For TWIn, set **TWI_BGR_REG**[TWIn_GATING] in CCU module to 0 to close TWIn clock.

Step 3 For TWIn, set **TWI_BGR_REG**[TWIn_RST] in CCU module to 0, then set to 1 to reset TWIn.

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Step 4 For TWIn, set **TWI_BGR_REG**[TWIn_GATING] in CCU module to 1 to open TWIn clock.

Step 5 Configure **TWI_CCR**[CLK_M] and **TWI_CCR**[CLK_N] to get the needed rate (The clock source of TWI is from APB1).

Step 6 Configure **TWI_CNTR**[BUS_EN] and **TWI_CNTR**[A_ACK], when using interrupt mode, set **TWI_CNTR**[INT_EN] to 1, and register the system interrupt through GIC module. In slave mode, configure **TWI_ADDR** and **TWI_XADDR** registers to finish TWI initialization configuration.

10.1.4.2 Writing Data Operation for TWI Engine

To write data to the device, perform the following steps:

Step 1 Clear **TWI_EFR** register, and configure **TWI_CNTR**[M_STA] to 1 to transmit the START signal.

Step 2 After the START signal is transmitted, the first interrupt is triggered, then write device ID to **TWI_DATA** (For a 10-bit device ID, firstly write the first byte ID, secondly write the second byte ID in the next interrupt).

Step 3 The Interrupt is triggered again after device ID transmission completes, write device data address to be read to **TWI_DATA** (For a 16-bit address, firstly write the first-byte address, secondly write the second-byte address).

Step 4 Interrupt is triggered after data address transmission completes, write data to be transmitted to **TWI_DATA** (For consecutive write data operation, every byte transmission completion triggers interrupt, during interrupt write the next byte data to **TWI_DATA**).

Step 5 After transmission completes, write **TWI_CNTR**[M_STP] to 1 to transmit the STOP signal and end this write-operation.

10.1.4.3 Reading Data Operation for TWI Engine

To read data from the device, perform the following steps:

Step 1 Clear **TWI_EFR** register, and set **TWI_CNTR**[A_ACK] to 1, and configure **TWI_CNTR**[M_STA] to 1 to transmit the START signal.

Step 2 After the START signal is transmitted, the first interrupt is triggered, then write device ID to **TWI_DATA** (For a 10-bit device ID, firstly write the first-byte ID, secondly write the second-byte ID in the next interrupt).

Step 3 The Interrupt is triggered again after device ID transmission completes, write device data address to be read to **TWI_DATA** (For a 16-bit address, firstly write the first-byte address, secondly write the second-byte address).

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Step 4 The Interrupt is triggered after data address transmission completes, write **TWI_CNTR**[M_STA] to 1 to transmit new START signal, and after interrupt triggers, write device ID to **TWI_DATA** to start read-operation.

Step 5 After device address transmission completes, each receive completion will trigger an interrupt, in turn, read **TWI_DATA** to get data, when receiving the previous interrupt of the last byte data, clear [A_ACK] to stop acknowledge signal of the last byte.

Step 6 Write **TWI_CNTR**[M_STP] to 1 to transmit the STOP signal and end this read-operation.

10.1.4.4 Initialization for TWI Driver

To initialize the TWI driver, perform the following steps:

Step 1 Configure corresponding GPIO multiplex function as TWI mode.

Step 2 For TWIn, set **TWI_BGR_REG**[TWIn_GATING] in CCU module to 0 to close TWIn clock.

Step 3 For TWIn, set **TWI_BGR_REG**[TWIn_RST] in CCU module to 0, then set to 1 to reset TWIn.

Step 4 For TWIn, set **TWI_BGR_REG**[TWIn_GATING] in CCU module to 1 to open TWIn clock.

Step 5 Set **TWI_DRV_CTRL**[TWI_DRV_EN] to 1 to enable the TWI driver.

Step 6 Configure **TWI_DRV_BUS_CTRL**[CLK_M] and **TWI_DRV_BUS_CTRL**[CLK_N] to get the needed rate (The clock source of TWI is from APB1).

Step 7 Set **TWI_DRV_CTRL**[RESTART_MODE] to 0 and [READ_TRAN_MODE] to 1, set **TWI_DRV_INT_CTRL**[TRAN_COM_INT_EN] to 1.

Step 8 When using DMA for data transmission, set **TWI_DRV_DMA_CFG**[DMA_RX_EN] and **TWI_DRV_DMA_CFG**[DMA_TX_EN] to 1, and configure **TWI_DRV_DMA_CFG**[RX_TRIG] and **TWI_DRV_DMA_CFG**[TX_TRIG] to set the thresholds of RXFIFO and TXFIFO.

10.1.4.5 Writing Packet Transmission for TWI Driver

To write package to the device, perform the following steps:

Step 1 Configure **TWI_DRV_SLV**[SLV_ID] to set the device ID, and configure **TWI_DRV_SLV**[CMD] to 0 to set the write operation.

Step 2 Configure **TWI_DRV_FMT**[ADDR_BYTE] according to the address width of the device register, and **TWI_DRV_FMT**[DATA_BYTE] according to the written data count in a packet.

Step 3 Configure **TWI_DRV_CFG**[PACKET_CNT] to set the written packet number.

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Step 4 Configure DMA channel, including TWI TXFIFO, device register address, and the written data.

Step 5 Set [START_TRAN] to 1 to start TWI Driver transmission.

Step 6 When TWI driver transmission completes, the interrupt is triggered, it indicates that the write packet transmission ends.

10.1.4.6 Reading Packet Transmission for TWI Driver

To read package from the device, perform the following steps:

Step 1 Configure **TWI_DRV_SLV**[SLV_ID] to set the device ID, and configure **TWI_DRV_SLV**[CMD] to 1 to set the read operation.

Step 2 Configure **TWI_DRV_FMT**[ADDR_BYTE] according to the address width of the device register, and **TWI_DRV_FMT**[DATA_BYTE] according to the read data count in a packet.

Step 3 Configure **TWI_DRV_CFG**[PACKET_CNT] to set the read packet number.

Step 4 Configure DMA channel, including TWI TXFIFO, TWI RXFIFO, device register address and the read data.

Step 5 Set [START_TRAN] to 1 to start TWI Driver transmission.

Step 6 When TWI driver transmission completes, the interrupt is triggered, it indicates that the read packet transmission ends.

10.1.5 Register List

Module Name	Base Address
TWI0	0x02502000
TWI1	0x02502400
TWI2	0x02502800
TWI3	0x02502C00

Register Name	Offset	Description
TWI_ADDR	0x0000	TWI Slave Address Register
TWI_XADDR	0x0004	TWI Extended Slave Address Register
TWI_DATA	0x0008	TWI Data Byte Register
TWI_CNTR	0x000C	TWI Control Register
TWI_STAT	0x0010	TWI Status Register
TWI_CCR	0x0014	TWI Clock Control Register

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Register Name	Offset	Description
TWI_SRST	0x0018	TWI Software Reset Register
TWI_EFR	0x001C	TWI Enhance Feature Register
TWI_LCR	0x0020	TWI Line Control Register
TWI_DRV_CTRL	0x0200	TWI_DRV Control Register
TWI_DRV_CFG	0x0204	TWI_DRV Transmission Configuration Register
TWI_DRV_SLV	0x0208	TWI_DRV Slave ID Register
TWI_DRV_FMT	0x020C	TWI_DRV Packet Format Register
TWI_DRV_BUS_CTRL	0x0210	TWI_DRV Bus Control Register
TWI_DRV_INT_CTRL	0x0214	TWI_DRV Interrupt Control Register
TWI_DRV_DMA_CFG	0x0218	TWI_DRV DMA Configure Register
TWI_DRV_FIFO_CON	0x021C	TWI_DRV FIFO Content Register
TWI_DRV_SEND_FIFO_ACC	0x0300	TWI_DRV Send Data FIFO Access Register
TWI_DRV_RECV_FIFO_ACC	0x0304	TWI_DRV Receive Data FIFO Access Register

10.1.6 Register Description

10.1.6.1 0x0000 TWI Slave Address Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: TWI_ADDR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:1	R/W	0x0	SLA Slave Address For 7-bit addressing, the bit[7:1] indicates: SLA6, SLA5, SLA4, SLA3, SLA2, SLA1, SLA0 For 10-bit addressing, the bit[7:1] indicates: 1, 1, 1, 1, 0, SLAX[9:8]
0	R/W	0x0	GCE General Call Address Enable 0: Disable 1: Enable

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NOTE

For 7-bit addressing:

SLA6 – SLA0 is the 7-bit address of the TWI in slave mode. When the TWI receives this address after a START condition, it will generate an interrupt and enter slave mode. (SLA6 corresponds to the first bit received from the TWI bus.) If GCE is set to '1', the TWI will also recognize the general call address (00h).

For 10-bit addressing:

When the address received starts with b'11110, the TWI recognizes b'11110 as the first part of a 10-bit address and if the next two bits match ADDR[2:1] (For example, SLAX9 and SLAX8 for the extended address of the device), it sends an ACK. (The device does not generate an interrupt at this point.) If the next byte of the address matches the XADDR register (SLAX7 – SLAX0), the TWI generates an interrupt and goes into slave mode.

10.1.6.2 0x0004 TWI Extend Address Register (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: TWI_XADDR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x0	SLAX Extend Slave Address SLAX[7:0]

10.1.6.3 0x0008 TWI Data Register (Default Value: 0x0000_0000)

Offset: 0x0008			Register Name: TWI_DATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x0	TWI_DATA Data byte transmitted or received

10.1.6.4 0x000C TWI Control Register (Default Value: 0x0000_0000)

Offset: 0x000C			Register Name: TWI_CNTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/

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Offset: 0x000C			Register Name: TWI_CNTR
Bit	**Read/Write**	**Default/Hex**	**Description**
7	R/W	0x0	INT_EN Interrupt Enable 0: The interrupt line always low 1: The interrupt line will go high when INT_FLAG is set.
6	R/W	0x0	BUS_EN TWI Bus Enable 0: The TWI bus SDA/SCL is ignored and the TWI controller will not respond to any address on the bus. 1: The TWI will respond to call to its slave address – and to the general call address if the GCE bit in the ADDR register is set. **Note: In master operation mode, this bit should be set to '1'.**
5	R/WAC	0x0	M_STA Master Mode Start When the M_STA is set to '1', the TWI controller enters master mode and will transmit a START condition on the bus when the bus is free. If the M_STA bit is set to '1' when the TWI controller is already in master mode and one or more bytes have been transmitted, then a repeated START condition will be sent. If the M_STA bit is set to '1' when the TWI is accessed in slave mode, the TWI will complete the data transfer in slave mode then enter master mode when the bus has been released. The M_STA bit is cleared automatically after a START condition has been sent. Writing a '0' to this bit has no effect.
4	R/W1C	0x0	M_STP Master Mode Stop If the M_STP is set to '1' in master mode, a STOP condition is transmitted on the TWI bus. If the M_STP bit is set to '1' in slave mode, the TWI will indicate if a STOP condition has been received, but no STOP condition will be transmitted on the TWI bus. If both M_STA and M_STP bits are set, the TWI will first transmit the STOP condition (if in master mode), then transmit the START condition. The M_STP bit is cleared automatically. Writing a '0' to this bit has no effect.

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Offset: 0x000C			Register Name: TWI_CNTR
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W1C	0x0	INT_FLAG Interrupt Flag The INT_FLAG is automatically set to '1' when any of the 28 (out of the possible 29) states is entered (see 'STAT Register' below). The state that does not set INT_FLAG is state F8h. If the INT_EN bit is set, the interrupt line goes high when INT_FLAG is set to '1'. If the TWI is operating in slave mode, the data transfer is suspended when INT_FLAG is set and the low period of the TWI bus clock line (SCL) is stretched until '1' is written to INT_FLAG. The TWI clock line is then released and the interrupt line goes low.
2	R/W	0x0	A_ACK Assert Acknowledge When A_ACK is set to '1', an Acknowledge (low level on SDA) will be sent during the acknowledge clock pulse on the TWI bus if: (1). Either the whole of a matching 7-bit slave address or the first or the second byte of a matching 10-bit slave address has been received. (2). The general call address has been received and the GCE bit in the ADDR register is set to '1'. (3). A data byte has been received in master or slave mode. When A_ACK is '0', a Not Acknowledge (high level on SDA) will be sent when a data byte is received in master or slave mode. If A_ACK is cleared to '0' in slave transmitter mode, the byte in the DATA register is assumed to be the 'last byte'. After this byte has been transmitted, the TWI will enter state C8h then return to the idle state (status code F8h) when INT_FLAG is cleared. The TWI will not respond as a slave unless A_ACK is set.
1	/	/	/
0	R/W	0x0	CLK_COUNT_MODE 0: scl clock high period count on oscl 1: scl clock high period count on iscl

10.1.6.5 0x0010 TWI Status Register (Default Value: 0x0000_00F8)

Offset: 0x0010			Register Name: TWI_STAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/

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Offset: 0x0010			Register Name: TWI_STAT
Bit	**Read/Write**	**Default/Hex**	**Description**
7:0	R	0xF8	STA Status Information Byte Code Status 0x00: Bus error 0x08: START condition transmitted 0x10: Repeated START condition transmitted 0x18: Address + Write bit transmitted, ACK received 0x20: Address + Write bit transmitted, ACK not received 0x28: Data byte transmitted in master mode, ACK received 0x30: Data byte transmitted in master mode, ACK not received 0x38: Arbitration lost in address or data byte 0x40: Address + Read bit transmitted, ACK received 0x48: Address + Read bit transmitted, ACK not received 0x50: Data byte received in master mode, ACK transmitted 0x58: Data byte received in master mode, not ACK transmitted 0x60: Slave address + Write bit received, ACK transmitted 0x68: Arbitration lost in the address as master, slave address + Write bit received, ACK transmitted 0x70: General Call address received, ACK transmitted 0x78: Arbitration lost in the address as master, General Call address received, ACK transmitted 0x80: Data byte received after slave address received, ACK transmitted 0x88: Data byte received after slave address received, not ACK transmitted 0x90: Data byte received after General Call received, ACK transmitted 0x98: Data byte received after General Call received, not ACK transmitted 0xA0: STOP or repeated START condition received in slave mode 0xA8: Slave address + Read bit received, ACK transmitted 0xB0: Arbitration lost in the address as master, slave address + Read bit received, ACK transmitted 0xB8: Data byte transmitted in slave mode, ACK received 0xC0: Data byte transmitted in slave mode, ACK not received 0xC8: The Last byte transmitted in slave mode, ACK received 0xD0: Second Address byte + Write bit transmitted, ACK received

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Offset: 0x0010			Register Name: TWI_STAT
Bit	Read/Write	Default/Hex	Description
			0xD8: Second Address byte + Write bit transmitted, ACK not received 0xF8: No relevant status information, INT_FLAG=0 Others: Reserved

10.1.6.6 0x0014 TWI Clock Register (Default Value: 0x0000_0080)

Offset: 0x0014			Register Name: TWI_CCR
Bit	Read/Write	Default/Hex	Description
31:8	/	/	/
7	R/W	0x1	CLK_DUTY Setting duty cycle of clock as master 0: 50% 1: 40%
6:3	R/W	0x0	CLK_M The TWI SCL output frequency, in master mode, is F1/10: F1 = F0/(CLK_M + 1) Fscl = F1/10 = Fin/(2^CLK_N * (CLK_M + 1)*10) Specially, Fscl = F1/11 when CLK_M=0 and CLK_DUTY=40% due to the delay of SCL sample debounce.
2:0	R/W	0x0	CLK_N The TWI bus is sampled by the TWI at the frequency defined by F0: Fsamp = F0 = Fin/2^CLK_N The TWI SCL output frequency, in master mode, is F1/10: F1 = F0/(CLK_M + 1) Fscl = F1/10 = Fin/(2^CLK_N * (CLK_M + 1)*10) Specially, Fscl = F1/11 when CLK_M=0 and CLK_DUTY=40% due to the delay of SCL sample debounce. For Example: Fin = 24 MHz (APB clock input) For 400 kHz full speed 2-wire, CLK_N = 1, CLK_M = 2 F0 = 24 MHz/2^1 = 12 MHz, F1 = F0/(10*(2+1)) = 0.4 MHz For 100 kHz standard speed 2-wire, CLK_N = 1, CLK_M = 11 F0 = 24 MHz/2^1 = 12 MHz, F1 = F0/(10*(11+1)) = 0.1 MHz

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10.1.6.7 0x0018 TWI Soft Reset Register (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: TWI_SRST
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/WAC	0x0	SOFT_RST Soft Reset Write '1' to this bit to reset the TWI and clear to '0' when completing Soft Reset operation.

10.1.6.8 0x001C TWI Enhance Feature Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: TWI_EFR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1:0	R/W	0x0	DBN Data Byte Number Follow Read Command Control 00: No data byte can be written after the read command 01: Only 1-byte data can be written after the read command 10: 2-bytes data can be written after the read command 11: 3-bytes data can be written after the read command

10.1.6.9 0x0020 TWI Line Control Register (Default Value: 0x0000_003A)

Offset: 0x0020			Register Name: TWI_LCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:6	/	/	/
5	R	0x1	SCL_STATE Current State of TWI_SCL 0: Low 1: High
4	R	0x1	SDA_STATE Current State of TWI_SDA 0: Low 1: High

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Offset: 0x0020			Register Name: TWI_LCR
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W	0x1	SCL_CTL TWI_SCL Line State Control Bit When the line control mode is enabled (bit[2] is set), this bit decides the output level of TWI_SCL. 0: Output low level 1: Output high level
2	R/W	0x0	SCL_CTL_EN TWI_SCL Line State Control Enable When this bit is set, the state of TWI_SCL is controlled by the value of bit[3]. 0: Disable TWI_SCL line control mode 1: Enable TWI_SCL line control mode
1	R/W	0x1	SDA_CTL TWI_SDA Line State Control Bit When the line control mode is enabled (bit[0] is set), this bit decides the output level of TWI_SDA. 0: Output low level 1: Output high level
0	R/W	0x0	SDA_CTL_EN TWI_SDA Line State Control Enable When this bit is set, the state of TWI_SDA is controlled by the value of bit[1]. 0: Disable TWI_SDA line control mode 1: Enable TWI_SDA line control mode

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10.1.6.10 0x0200 TWI_DRV Control Register (Default Value: 0x00F8_1000)

Offset: 0x0200			Register Name: TWI_DRV_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/WAC	0x0	START_TRAN Start transmission 0: Transmission idle 1: Start transmission Automatically cleared to '0' when finished. If the slave is not responding for the expected status over the time defined by TIMEOUT, the current transmission will stop. All setting formats and data will be loaded from registers and FIFO when the transmission starts.
30	/	/	/
29	R/W	0x0	RESTART_MODE Restart mode 0: RESTART 1: STOP+START Define the TWI_DRV action after sending the register address.
28	R/W	0x0	READ_TRAN_MODE Read transition mode 0: Send slave_id+W 1: Not send slave_id+W Setting this bit to 1 if reading from a slave in which the register width is equal to 0.
27:24	R	0x0	TRAN_RESULT Transition result 000: OK 001: FAIL Other: Reserved

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Offset: 0x0200			Register Name: TWI_DRV_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
23:16	R	0xf8	TWI_STA TWI status 0x00: bus error 0x08: START condition transmitted 0x10: Repeated START condition transmitted 0x18: Address + Write bit transmitted, ACK received 0x20: Address + Write bit transmitted, ACK not received 0x28: Data byte transmitted in master mode, ACK received 0x30: Data byte transmitted in master mode, ACK not received 0x38: Arbitration lost in address or data byte 0x40: Address + Read bit transmitted, ACK received 0x48: Address + Read bit transmitted, ACK not received 0x50: Data byte received in master mode, ACK received 0x58: Data byte received in master mode, ACK not received 0x01: Timeout when sending the 9th SCL clock Other: Reserved
15:8	R/W	0x10	TIMEOUT_N Timeout number When sending the 9th clock, assert fail signal when the slave device does not respond after N*F_{SCL} cycles. And the software must do a reset to the TWI_DRV module and send a stop condition to slave.
7:2	/	/	/
1	R/W	0x0	SOFT_RESET Software reset 0: Normal 1: Reset
0	R/W	0x0	TWI_DRV_EN TWI driver enable 0: Module disable 1: Module enable (only use in TWI Master Mode)

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10.1.6.11 0x0204 TWI_DRV Transmission Configuration Register (Default Value: 0x0000_0001)

Offset: 0x0204			Register Name: TWI_DRV_CFG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0	PKT_INTERVAL Define the interval between each packet for PKT_INTERVAL F_{SCL} cycles.
15:0	R/W	0x1	PACKET_CNT The FIFO data is transmitted as PACKET_CNT packets in current format.

10.1.6.12 0x0208 TWI_DRV Slave ID Register (Default Value: 0x0000_0000)

Offset: 0x0208			Register Name: TWI_DRV_SLV
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:9	R/W	0x0	SLV_ID Slave device ID For 7-bit addressing, the bit[7:1] indicates: SLA6, SLA5, SLA4, SLA3, SLA2, SLA1, SLA0 For 10-bit addressing, the bit[7:1] indicates: 1, 1, 1, 1, 0, SLAX[9:8]
8	R/W	0x0	CMD R/W operation to slave device 0: Write 1: Read
7:0	R/W	0x0	SLV_ID_X SLAX[7:0] The low 8 bits for slave device ID with 10-bit addressing.

10.1.6.13 0x020C TWI_DRV Packet Format Register (Default Value: 0x0001_0001)

Offset: 0x020C			Register Name: TWI_DRV_FMT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/

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Offset: 0x020C			Register Name: TWI_DRV_FMT
Bit	**Read/Write**	**Default/Hex**	**Description**
23:16	R/W	0x1	ADDR_BYTE How many bytes be sent as slave device reg address 0~255
15:0	R/W	0x1	DATA_BYTE How many bytes be sent/received as data 1~65535

10.1.6.14 0x0210 TWI_DRV Bus Control Register (Default Value: 0x0000_80C0)

Offset: 0x0210			Register Name: TWI_DRV_BUS_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	W	0x0	CLK_COUNT_MODE Clock count mode 0: scl clock high period count on oscl 1: scl clock high period count on iscl
15	R/W	0x1	CLK_DUTY Setting duty cycle of clock as Master 0: 50% 1: 40%
14:12	R/W	0x0	CLK_N TWI_DRV bus sampling clock F0=24MHz/2^CLK_N
11:8	R/W	0x0	CLK_M TWI_DRV output SCL frequency is F_{SCL}=F1/10=(F0/(CLK_M+1))/10 Specially, Foscl = F1/11 when CLK_M=0 and CLK_DUTY=40% due to the delay of SCL sample debounce.
7	R	0x1	SCL_STA SCL current status
6	R	0x1	SDA_STA SDA current status
5:4	/	/	/
3	R/W	0x0	SCL_MOV SCL manual output value

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Offset: 0x0210			Register Name: TWI_DRV_BUS_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	SDA_MOV SDA manual output value
1	R/W	0x0	SCL_MOE SCL manual output enable
0	R/W	0x0	SDA_MOE SDA manual output enable

10.1.6.15 0x0214 TWI_DRV Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0214			Register Name: TWI_DRV_INT_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
19	R/W	0x0	RX_REQ_INT_EN If set, an interrupt is sent when RX_REQ_PD sets.
18	R/W	0x0	TX_REQ_INT_EN If set, an interrupt is sent when TX_REQ_PD sets.
17	R/W	0x0	TRAN_ERR_INT_EN If set, an interrupt is sent when TRAN_ERR_PD sets.
16	R/W	0x0	TRAN_COM_INT_EN If set, an interrupt is sent when TRAN_COM_PD sets.
15:4	/	/	/
3	R/W1C	0x0	RX_REQ_PD Set when the data byte number in RECV_FIFO reaches RX_TRIG.
2	R/W1C	0x0	TX_REQ_PD Set when there is no less than DMA_TX_TRIG empty byte number in SEND_FIFO.
1	R/W1C	0x0	TRAN_ERR_PD Packet transmission failure pending
0	R/W1C	0x0	TRAN_COM_PD Packet transmission completion pending

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10.1.6.16 0x0218 TWI_DRV DMA Configure Register (Default Value: 0x0010_0010)

Offset: 0x0218			Register Name: TWI_DRV_DMA_CFG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	DMA_RX_EN DMA RX Enable
23:22	/	/	/
21:16	R/W	0x10	RX_TRIG RX trigger When DMA_RX_EN is set, send DMA RX Req when the data byte number in RECV_FIFO reaches RX_TRIG, or the read transmission is completed, the data of RECV_FIFO does not reach RX_TRIG but as long as the RECV_FIFO is not empty.
15:9	/	/	/
8	R/W	0x0	DMA_TX_EN DMA TX Enable
7:6	/	/	/
5:0	R/W	0x10	TX_TRIG TX trigger When DMA_TX_EN is set, send DMA TX Req when the space of SEND_FIFO (FIFO Level – data volume) reaches TX_TRIG.

10.1.6.17 0x021C TWI_DRV FIFO Content Register (Default Value: 0x0000_0000)

Offset: 0x021C			Register Name: TWI_DRV_FIFO_CON
Bit	**Read/Write**	**Default/Hex**	**Description**
31:23	/	/	/
22	R/WAC	0x0	RECV_FIFO_CLEAR Set this bit to clear RECV_FIFO pointer, and this bit is cleared automatically.
21:16	R	0x0	RECV_FIFO_CONTENT The number of data in RECV_FIFO
15:7	/	/	/
6	R/WAC	0x0	SEND_FIFO_CLEAR Set this bit to clear SEND_FIFO pointer, and this bit is cleared automatically.

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Offset: 0x021C			Register Name: TWI_DRV_FIFO_CON
Bit	**Read/Write**	**Default/Hex**	**Description**
5:0	R	0x0	SEND_FIFO_CONTENT The number of data in SEND_FIFO

10.1.6.18 0x0300 TWI_DRV Send Data FIFO Access Register (Default Value: 0x0000_0000)

Offset: 0x0300			Register Name: TWI_DRV_SEND_FIFO_ACC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	W	0x0	SEND_DATA_FIFO Address of a 32x8 SEND_FIFO, which stores reg address and data sending to the slave device.

10.1.6.19 0x0304 TWI_DRV Receive Data FIFO Access Register (Default Value: 0x0000_0000)

Offset: 0x0304			Register Name: TWI_DRV_RECV_FIFO_ACC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R	0x0	RECV_DATA_FIFO Address of a 32x8 RECV_FIFO, which stores data received from the slave device.

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10.2 UART

10.2.1 Overview

The universal asynchronous receiver transmitter (UART) provides an asynchronous serial communication with external devices, modem (data carrier equipment, DCE). It performs serial-to-parallel conversion on the data received from peripherals and transmits the converted data to the internal bus. It also performs parallel-to-serial conversion on the data that is transmitted to peripherals.

The UART has the following features:

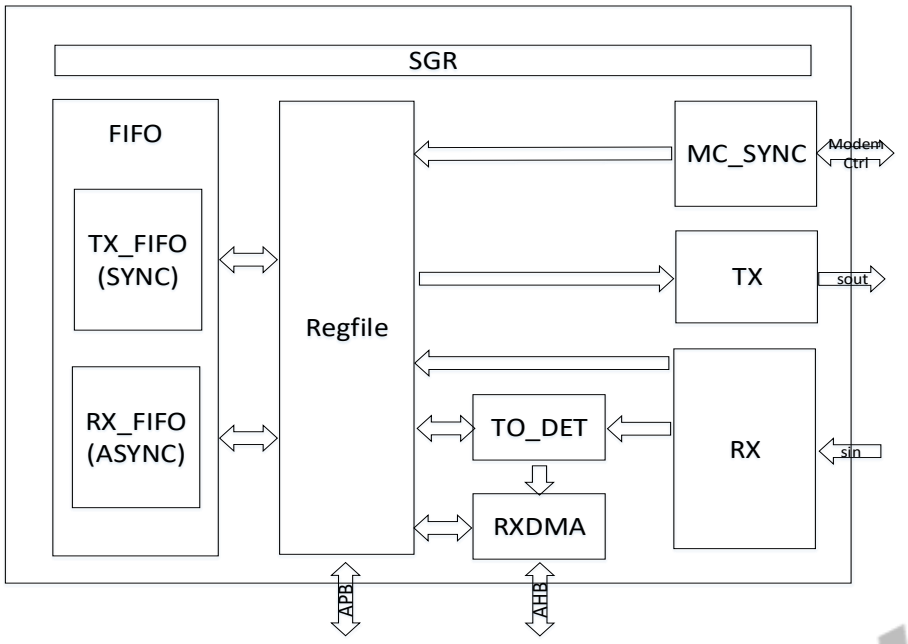
- Compatible with industry-standard 16450/16550 UARTs
- Supports IrDA-compatible slow infrared (SIR) format
- Two separate FIFOs: one is RX FIFO, and the other is TX FIFO
  - Each of them is 64 bytes (For UART0)
  - Each of them is 256 bytes (For UART1, UART2, UART3, UART4, and UART5)
- The working reference clock is from the APB bus clock
  - Speed up to 4 Mbit/s with 64 MHz APB clock
  - Speed up to 1.5 Mbit/s with 24 MHz APB clock
- 5 to 8 data bits for RS-232 characters, or 9 bits RS-485 format
- 1, 1.5 or 2 stop bits
- Programmable parity (even, odd, or no parity)
- Supports TX/RX DMA slave controller interface
- Supports software/hardware flow control
- Supports RX DMA Master interface (Only for UART1)
- Supports auto-flow by using CTS & RTS (Only for UART1/2/3)

10.2.2 Block Diagram

Figure 10-9 shows a block diagram of the UART.

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Figure 10-9 UART Block Diagram



10.2.3 Functional Description

10.2.3.1 External Signals

The following table describes the external signals of UART.

Table 10-4 UART External Signals

Signal	Description	Type
UART0-TX	UART0 Data Transmit	O
UART0-RX	UART0 Data Receive	I
UART1-TX	UART1 Data Transmit	O
UART1-RX	UART1 Data Receive	I
UART1-CTS	UART1 Data Clear to Send	I
UART1-RTS	UART1 Data Request to Send	O
UART2-TX	UART2 Data Transmit	O
UART2-RX	UART2 Data Receive	I
UART2-CTS	UART2 Data Clear to Send	I
UART2-RTS	UART2 Data Request to Send	O
UART3-TX	UART3 Data Transmit	O
UART3-RX	UART3 Data Receive	I

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Signal	Description	Type
UART3-CTS	UART3 Data Clear to Send	I
UART3-RTS	UART3 Data Request to Send	O
UART4-TX	UART4 Data Transmit	O
UART4-RX	UART4 Data Receive	I
UART5-TX	UART5 Data Transmit	O
UART5-RX	UART5 Data Receive	I

10.2.3.2 Clock Sources

The following table describes the clock sources of UART.

Table 10-5 UART Clock Sources

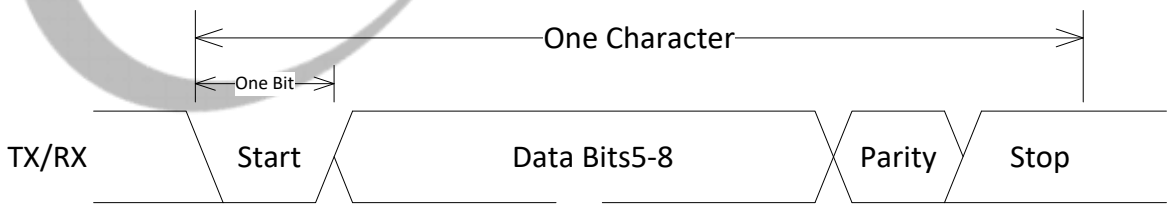
Clock Sources	Description
APB1 Bus	UART clock source. Refer to CCU for details on APB1.

10.2.3.3 Typical Applications and Timing Diagram

UART Serial Data Format

The following figure shows the UART serial data format. The start bit, data bit, parity bit, and stop bit can be configured.

Figure 10-10 UART Serial Data Format



Using UART for RTS/CTS Autoflow Control

Figure 10-11 shows the typical application diagram for RTS/CTS autoflow control. Figure 10-12 shows the data format of the RTS/CTS autoflow control.

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Figure 10-11 Application Diagram for RTS/CTS Autoflow Control

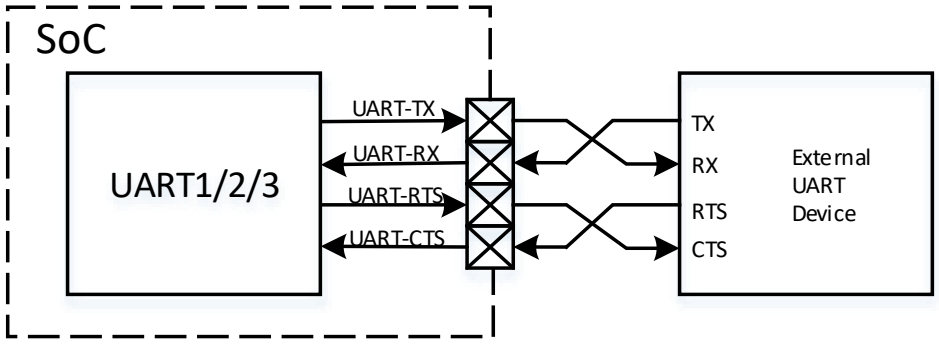
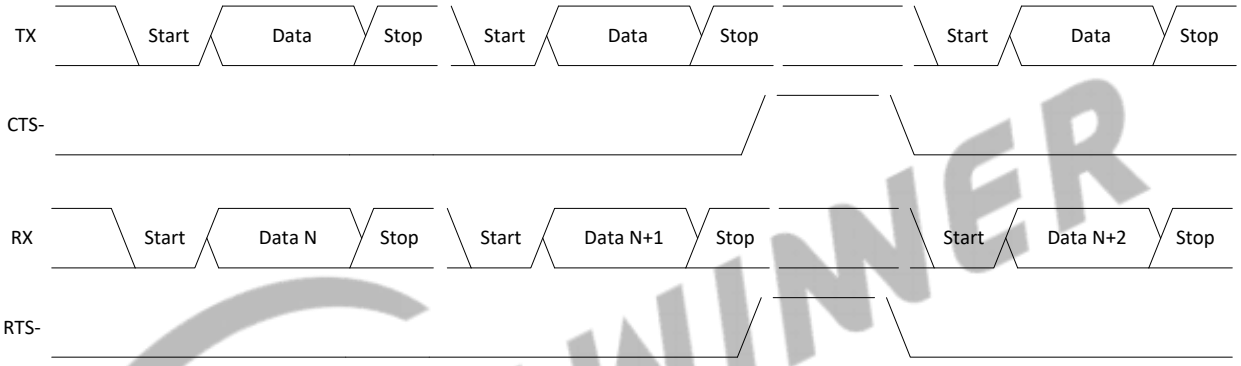


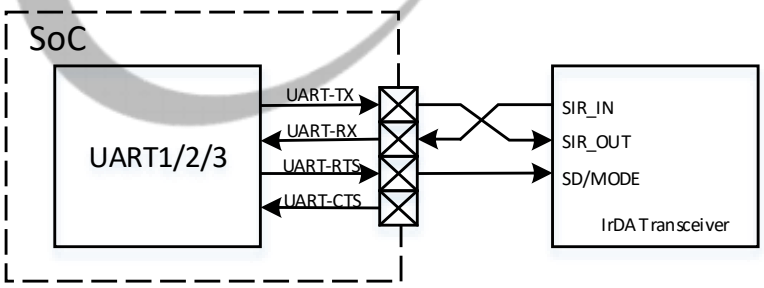
Figure 10-12 RTS/CTS Autoflow Control Data Format



Using UART for Serial IrDA

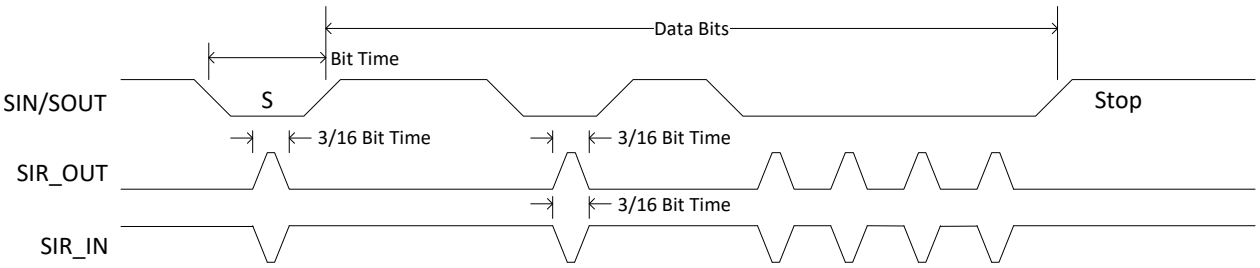
Figure 10-13 shows the application diagram for the IrDA transceiver. Figure 10-14 shows the data format of the serial IrDA.

Figure 10-13 Application Diagram for IrDA Transceiver



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Figure 10-14 Serial IrDA Data Format



Using UART for RS-485

Figure 10-15 shows the application diagram for the RS-485 transceiver. Figure 10-16 shows the data format of the RS-485.

Figure 10-15 Application Diagram for RS-485 Transceiver

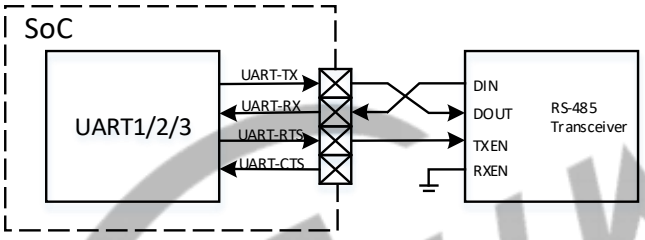
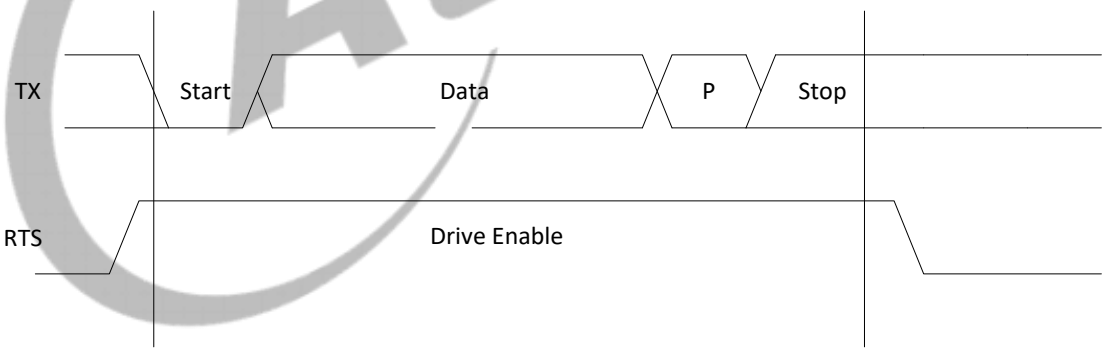


Figure 10-16 RS-485 Data Format



10.2.3.4 UART Operating Mode

Data Frame Format

The UART_LCR register can set the basic parameter of a data frame: data width (5 to 8 bits), stop bit number (1/1.5/2), parity type.

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A frame transfer of the UART includes the start signal, data signal, parity bit, and stop signal. The LSB is transmitted first.

- Start signal (start bit): It is the start flag of a data frame. According to the UART protocol, the low level of the TXD signal indicates the start of a data frame. When the UART transmits data, the level needs to hold high.
- Data signal (data bit): The data bit width can be configured as 5-bit, 6-bit, 7-bit, and 8-bit through different applications.
- Parity bit: It is a 1-bit error correction signal. Parity bit includes odd parity, even parity. The UART can enable and disable the parity bit by setting the **UART_LCR** register.
- Stop Signal (stop bit): It is the stop bit of a data frame. The stop bit can be set to 1-bit, 1.5-bit, and 2-bit by the **UART_LCR** register. The high level of the TXD signal indicates the end of a data frame.

Baud and Error Rates

The baud rate is calculated as follows: Baud rate = SCLK/(16 * divisor).

The SCLK is usually APB1 and can be set in section 3.3 "CCU".

The divisor is frequency divider of UART. The frequency divider has 16-bit, the low 8-bit is in the **UART_DLL** register, the high 8-bit is in the **UART_DLH** register.

The relationship between the different UART mode and the error rate is as follows.

Figure 10-17 UART Mode Baud and Error Rates

Clock source	Divisor	Baud rate	Over sampling	Error (%)
24000000	5000	300	16	0
24000000	2500	600	16	0
24000000	1250	1200	16	0
24000000	625	2400	16	0
24000000	313	4800	16	-0.16
24000000	156	9600	16	0.16
24000000	78	19200	16	0.16
24000000	39	38400	16	0.16
24000000	26	57600	16	0.16
24000000	13	115200	16	0.16
48000000	13	230400	16	0.16
64000000	7	576000	16	-0.794
75000000	5	921600	16	1.725

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Clock source	Divisor	Baud rate	Over sampling	Error (%)
48000000	3	1000000	16	0
24000000	1	1500000	16	0
48000000	1	3000000	16	0
64000000	1	4000000	16	0

Figure 10-18 IrDA Mode Baud and Error Rates

Clock source	Divisor	Baud rate	Encoding	Error (%)
24000000	5000	300	3/16	0
24000000	2500	600	3/16	0
24000000	1250	1200	3/16	0
24000000	625	2400	3/16	0
24000000	313	4800	3/16	-0.16
24000000	156	9600	3/16	0.16
24000000	78	19200	3/16	0.16
24000000	39	38400	3/16	0.16
24000000	26	57600	3/16	0.16
24000000	13	115200	3/16	0.16

Figure 10-19 RS485 Mode Baud and Error Rates

Clock source	Divisor	Baud rate	Encoding	Error (%)
24000000	5000	300	16	0
24000000	2500	600	16	0
24000000	1250	1200	16	0
24000000	625	2400	16	0
24000000	313	4800	16	-0.16
24000000	156	9600	16	0.16
24000000	78	19200	16	0.16
24000000	39	38400	16	0.16
24000000	26	57600	16	0.16
24000000	13	115200	16	0.16

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DLAB Definition

The DLAB control bit (UART_LCR[7]) is the access control bit of the divisor Latch register.

If DLAB is 0, then the 0x00 offset address is the UART_RBR/UART_THR (RX/TX FIFO) register, and the 0x04 offset address is the UART_IER register.

If DLAB is 1, then the 0x00 offset address is the UART_DLL register, and the 0x04 offset address is the UART_DLH register.

When the UART initials, the divisor needs to be set. That is, writing 1 to DLAB can access the UART_DLL and UART_DLH register, after finished the configuration, writing 0 to DLAB can access the UART_RBR/UART_THR register.

CHCFG_AT_BUSY Definition

The function of the CHCFG_AT_BUSY (UART_HALT[1]) and CHANGE_UPDATE (UART_HALT[2]) are as follows.

CHCFG_AT_BUSY: Enable the bit, the software can also set the UART controller when UART is busy, such as the UART_LCR, UART_DLH, UART_DLL register.

CHANGE_UPDATE: If CHCFG_AT_BUSY is enabled, and CHANGE_UPDATE is written to 1, the configuration of the UART controller can be updated. After completed the update, the bit is cleared to 0 automatically.

Setting divisor performs the following steps:

Step 1 Write 1 to CHCFG_AT_BUSY to enable “configure at busy”.

Step 2 Write 1 to DLAB (UART_LCR[7]) and set the UART_DLH and UART_DLL registers.

Step 3 Write 1 to CHANGE_UPDATE to update the configuration. The bit is cleared to 0 automatically after completing the update.

UART Busy Flag

The UART_USR[0] is a busy flag of the UART controller.

When the TX transmits data, or the RX receives data, or the TX FIFO is not empty, or the RX FIFO is not empty, then the busy flag bit can be set to 1 by hardware, which indicates the UART controller is busy.

10.2.4 Programming Guidelines

The following takes the UART module in the CPUX domain as an example.

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10.2.4.1 Initialization

Step 1 System Initialization

- Configure **APB1_CFG_REG** in the CCU module to set the APB1 bus clock (The clock is 24MHz by default).
- Set **UART_BGR_REG**[UARTx_GATING] to 1 to enable the module clock, and set **UART_BGR_REG**[UARTx_RST] to 1 to de-assert the module.

Step 2 UART Controller Initialization

- IO configuration: Configure GPIO multiplex as UART function, and set UART pins to internal pull-up mode (For detail, see the description in section 9.7 "GPIO").
- Baud-rate configuration:
  - Set UART baud-rate (refer to section 9.2.3.4);
  - Write **UART_FCR**[FIFOE] to 1 to enable TX/RX FIFO;
  - Write **UART_HALT**[HALT_TX] to 1 to disable TX transfer;
  - Set **UART_LCR**[DLAB] to 1, remain default configuration for other bits; set 0x00 offset address to the **UART_DLL** register, set 0x04 offset address to the **UART_DLH** register;
  - Write the high 8-bit of divisor to the **UART_DLH** register, and write the low 8-bit of divisor to the **UART_DLL** register;
  - Set **UART_LCR**[DLAB] to 0, remain default configuration for other bits; set 0x00 offset address to the **UART_RBR**/**UART_THR** register, set 0x04 offset address to the **UART_IER** register;
  - Set **UART_HALT**[HALT_TX] to 0 to enable TX transfer.

Step 3 Controller Parameter Configuration

- Set data width, stop bits, and even/odd parity type by writing the **UART_LCR** register.
- Reset, enable FIFO and set FIFO trigger condition by writing the **UART_FCR** register.
- Set the flow control parameter by writing the **UART_MCR** register.

Step 4 Interrupt Configuration

- Configure UART interrupt vector number to request UART interrupt (Refer to section 3.8 "GIC" module for interrupt vector number).
- In DMA mode, write **UART_IER** to 0 to disable interrupt; write **UART_HSK**[Handshake configuration] to 0xE5 to set DMA handshake mode; write **UART_FCR**[DMAM] to 1 to set DMA transmission/reception mode; set DMA parameter and request DMA interrupt according to DMA configuration process.

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- In Interrupt mode, configure **UART_IER** to enable the corresponding interrupt according to requirements: such as transmit (TX) interrupt, receive (RX) interrupt, receive line status interrupt, RS48 interrupt, etc. (Here TX/RX interrupt is usually used).

10.2.4.2 Transferring/Receiving Data in Query Mode

Data transfer

Step 1 Write data to **UART_THR** to start data transfer.

Step 2 Check TX_FIFO status by reading **UART_USR**[TFNF]. If the bit is 1, data can continue to be written; if the bit is 0, wait for data transfer, and data cannot continue to write until FIFO is not full.

Data receive

Step 1 Check RX_FIFO status by reading **UART_USR**[RFNE].

Step 2 Read data from **UART_RBR** if RX_FIFO is not empty.

Step 3 If **UART_USR**[RFNE] is 0, data is received completely.

10.2.4.3 Transferring/Receiving Data in Interrupt Mode

Data transfer

Step 1 Set **UART_IER**[ETBEI] to 1 to enable the *UART transmission interrupt*.

Step 2 Write the data to be transmitted to **UART_THR**.

Step 3 When the data of TX_FIFO meets trigger condition (such as FIFO/2, FIFO/4), the UART transfer interrupt is generated.

Step 4 Check **UART_USR**[TFE] and determine whether TX_FIFO is empty. If **UART_USR**[TFE] is 1, it indicates that the data in TX_FIFO is transmitted completely.

Step 5 Clear **UART_IER**[ETBEI] to 0 to disable transfer interrupt.

Data receive

Step 1 Set **UART_IER**[ERBFI] to 1 to enable the *UART reception interrupt*.

Step 2 When the received data from RX_FIFO meets trigger condition (such as FIFO/2, FIFO/4), the UART receive interrupt is generated.

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Step 3 Read data from **UART_RBR**.

Step 4 Check RX_FIFO status by reading **UART_USR**[RFNE] and determine whether to read data. If the bit is 1, continue to read data from **UART_RBR** until **UART_USR**[RFNE] is cleared to 0, which indicates data is received completely.

10.2.4.4 Transferring/Receiving Data in DMA Mode

Data transfer

Step 1 Configure the UART DMA interrupt according to the initialization process.

Step 2 Configure DMA data channel, including the transfer source address, the transfer destination address, the number of data to be transferred, and the transfer type, and so on. (For details, see section 3.9 "DMAC").

Step 3 Enable the DMA transfer function of the UART by setting the register of the DMA module.

Step 4 Determine whether UART data is transferred completely based on the DMA status. If all data is transferred completely, disable the DMA transfer function of the UART.

Data receive

Step 1 Configure DMA data channel, including the transfer source address, the transfer destination address, the number of data to be transferred, and the transfer type, and so on. (For details, see section 3.9 "DMAC").

Step 2 Enable the DMA receive function of the UART by setting the register of the DMA module.

Step 3 Determine whether UART data is received completely based on the DMA status. If all data is received completely, disable the DMA receive function of the UART.

10.2.5 Register List

Module Name	Base Address
UART0	0x02500000
UART1	0x02500400
UART2	0x02500800
UART3	0x02500C00
UART4	0x02501000
UART5	0x02501400

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Register Name	Offset	Description
UART_RBR	0x0000	UART Receive Buffer Register
UART_THR	0x0000	UART Transmit Holding Register
UART_DLL	0x0000	UART Divisor Latch Low Register
UART_DLH	0x0004	UART Divisor Latch High Register
UART_IER	0x0004	UART Interrupt Enable Register
UART_IIR	0x0008	UART Interrupt Identity Register
UART_FCR	0x0008	UART FIFO Control Register
UART_LCR	0x000C	UART Line Control Register
UART_MCR	0x0010	UART Modem Control Register
UART_LSR	0x0014	UART Line Status Register
UART_MSR	0x0018	UART Modem Status Register
UART_SCH	0x001C	UART Scratch Register
UART_USR	0x007C	UART Status Register
UART_TFL	0x0080	UART Transmit FIFO Level Register
UART_RFL	0x0084	UART Receive FIFO Level Register
UART_HSK	0x0088	UART DMA Handshake Configuration Register
UART_DMA_REQ_EN	0x008C	UART DMA Request Enable Register
UART_HALT	0x00A4	UART Halt TX Register
UART_DBG_DLL	0x00B0	UART Debug DLL Register
UART_DBG_DLH	0x00B4	UART Debug DLH Register
UART_A_FCC	0x00F0	UART FIFO Clock Control Register
UART_A_RXDMA_CTRL	0x0100	UART RXDMA Control Register
UART_A_RXDMA_STR	0x0104	UART RXDMA Start Register
UART_A_RXDMA_STA	0x0108	UART RXDMA Status Register
UART_A_RXDMA_LMT	0x010C	UART RXDMA Limit Register
UART_A_RXDMA_SADDRL	0x0110	UART RXDMA Buffer Start Address Low Register
UART_A_RXDMA_SADDRH	0x0114	UART RXDMA Buffer Start Address High Register
UART_A_RXDMA_BL	0x0118	UART RXDMA Buffer Length Register
UART_A_RXDMA_IE	0x0120	UART RXDMA Interrupt Enable Register
UART_A_RXDMA_IS	0x0124	UART RXDMA Interrupt Status Register
UART_A_RXDMA_WADDRL	0x0128	UART RXDMA Write Address Low Register
UART_A_RXDMA_WADDRH	0x012C	UART RXDMA Write Address high Register

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Register Name	Offset	Description
UART_A_RXDMA_RADDRL	0x0130	UART RXDMA Read Address Low Register
UART_A_RXDMA_RADDRH	0x0134	UART RXDMA Read Address high Register
UART_A_RXDMA_DCNT	0x0138	UART RADMA Data Count Register

10.2.6 Register Description

10.2.6.1 0x0000 UART Receiver Buffer Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: UART_RBR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R	0x0	RBR Receiver Buffer Register Data byte received on the serial input port (sin) in UART mode, or the serial infrared input (sir_in) in infrared mode. The data in this register is valid only if the Data Ready (DR) bit in *UART_LCR* is set. If in FIFO mode and FIFOs are enabled (The *UART_FCR*[0] is set to 1), this register accesses the head of the receive FIFO. If the receive FIFO is full and this register can not read before the next data character arrives, then the data already in the FIFO are preserved, but any incoming data are lost and an overrun error occurs.

10.2.6.2 0x0000 UART Transmit Holding Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: UART_THR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/

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Offset: 0x0000			Register Name: UART_THR
Bit	**Read/Write**	**Default/Hex**	**Description**
7:0	W	0x0	THR Transmit Holding Register Data is transmitted on the serial output port (SOUT) in UART mode or the serial infrared output (sir_out_n) in infrared mode. Data should only be written to the *UART_THR* when the THRE bit (*UART_LSR*[5]) is set. If in FIFO mode and FIFOs are enabled (*UART_FCR*[0] = 1) and THRE is set, the 16 number of characters data may be written to the *UART_THR* before the FIFO is full. When the FIFO is full, any written data results in the written data being lost.

10.2.6.3 0x0000 UART Divisor Latch Low Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: UART_DLL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x0	DLL Divisor Latch Low Lower 8 bits of 16 bits, read/write, Divisor Latch Register contains the baud rate divisor for the UART. This register may only be accessed when the DLAB bit (*UART_LCR*[7]) is set and the UART is not busy (*UART_USR*[0] is 0). The output baud rate is equal to the serial clock (SCLK) frequency divided by sixteen times the value of the baud rate divisor, as follows: **baud rate = (serial clock freq)/(16 * divisor)**. Note that when the Divisor Latch Registers (*UART_DLL* and *UART_DLH*) are set to 0, the baud clock is disabled and no serial communications occur. Also, once the DLL is set, at least 8 clock cycles of the slowest UART clock should be allowed to pass before transmitting or receiving data.

10.2.6.4 0x0004 UART Divisor Latch High Register (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: UART_DLH
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/

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Offset: 0x0004			Register Name: UART_DLH
Bit	**Read/Write**	**Default/Hex**	**Description**
7:0	R/W	0x0	DLH Divisor Latch High Upper 8 bits of 16 bits, read/write, Divisor Latch Register contains the baud rate divisor for the UART. This register may only be accessed when the DLAB bit (*UART_LCR*[7]) is set and the UART is not busy (*UART_USR*[0] is 0). The output baud rate is equal to the serial clock (SCLK) frequency divided by sixteen times the value of the baud rate divisor, as follows: **baud rate = (serial clock freq)/(16 * divisor)**. Note that when the Divisor Latch Registers (*UART_DLL* and *UART_DLH*) is set to 0, the baud clock is disabled and no serial communications occur. Also, once the DLH is set, at least 8 clock cycles of the slowest UART clock should be allowed to pass before transmitting or receiving data.

10.2.6.5 0x0004 UART Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: UART_IER
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	PTIME Programmable THRE Interrupt Mode Enable This is used to enable/disable the generation of THRE Interrupt. 0: Disable 1: Enable
6:5	/	/	/
4	R/W	0x0	RS485_INT_EN RS485 Interrupt Enable 0: Disable 1: Enable
3	R/W	0x0	EDSSI Enable Modem Status Interrupt This is used to enable/disable the generation of Modem Status Interrupt. This is the fourth highest priority interrupt. 0: Disable 1: Enable

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Offset: 0x0004			Register Name: UART_IER
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	ELSI Enable Receiver Line Status Interrupt This is used to enable/disable the generation of Receiver Line Status Interrupt. This is the highest priority interrupt. 0: Disable 1: Enable
1	R/W	0x0	ETBEI Enable Transmit Holding Register Empty Interrupt This is used to enable/disable the generation of Transmitter Holding Register Empty Interrupt. This is the third-highest priority interrupt. 0: Disable 1: Enable
0	R/W	0x0	ERBFI Enable Received Data Available Interrupt This is used to enable/disable the generation of Received Data Available Interrupt and the Character Timeout Interrupt (if in FIFO mode and FIFOs enabled). These are the second-highest priority interrupt. 0: Disable 1: Enable

10.2.6.6 0x0008 UART Interrupt Identity Register (Default Value: 0x0000_0001)

Offset: 0x0008			Register Name: UART_IIR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:6	R	0x0	FEFLAG FIFOs Enable Flag This is used to indicate whether the FIFOs are enabled or disabled. 00: Disable 11: Enable
5:4	/	/	/

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Offset: 0x0008			Register Name: UART_IIR
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R	0x1	IID Interrupt ID This indicates the highest priority pending interrupt which can be one of the following types. 0000: modem status 0001: no interrupt pending 0010: THR empty 0011: RS485 Interrupt 0100: received data available 0110: receiver line status 0111: busy detect 1100: character timeout The bit 3 indicates an interrupt can only occur when the FIFOs are enabled and used to distinguish a Character Timeout condition interrupt.

Interrupt ID	Priority Level	Interrupt Type	Interrupt Source	Interrupt Reset
0001	-	None	None	-
0110	Highest	Receiver line status	Overrun/parity/framing errors or break interrupt	Reading the line status register
0011	Second	RS485 Interrupt	In RS485 mode, receives address data and match setting address	Writes 1 to addr flag to reset
0100	Third	Received data available	Receiver data available (non-FIFO mode or FIFOs disabled) or RCVR FIFO trigger level reached (FIFO mode and FIFOs enabled)	Reading the receiver buffer register (non-FIFO mode or FIFOs disabled) or the FIFO drops below the trigger level (FIFO mode and FIFOs enabled)
1100	Fourth	Character timeout indication	No characters in or out of the RCVR FIFO during the last 4 character times and there is at least 1character in it during This time	Reading the receiver buffer register

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Interrupt ID	Priority Level	Interrupt Type	Interrupt Source	Interrupt Reset
0010	Fifth	Transmit holding register empty	Transmitter holding register empty (Program THRE mode disabled) or XMIT FIFO at or below threshold (Program THRE mode enabled)	Reading the IIR register (if the source of interrupt); or, writing into THR (FIFOs or THRE mode not selected or disabled) or XMIT FIFO above threshold (FIFOs and THRE mode selected and enabled).
0000	Sixth	Modem status	Clear to send or data set ready or ring indicator or data carrier detect. Note that if the autoflow control mode is enabled, a change in CTS (that is, DCTS set) does not cause an interrupt.	Reading the Modem status register
0111	Seventh	Busy detect indication	UART_16550_COMPATIBLE = NO and master has tried to write to the Line Control Register while the UART is busy (USR[0] is set to one).	Reading the UART status register

10.2.6.7 0x0008 UART FIFO Control Register (Default Value: 0x0000_0000)

Offset: 0x0008			Register Name: UART_FCR
Bit	Read/Write	Default/Hex	Description
31:8	/	/	/
7:6	W	0x0	RT RCVR Trigger This is used to select the trigger level in the receiver FIFO when the Received Data Available Interrupt is generated. In the autoflow control mode, it is used to determine when the rts_n signal is de-asserted. It also determines when the dma_rx_req_n signal is asserted in certain modes of operation. 00: 1 character in the FIFO 01: FIFO ¼ full 10: FIFO ½ full 11: FIFO-2 less than full

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Offset: 0x0008			Register Name: UART_FCR
Bit	**Read/Write**	**Default/Hex**	**Description**
5:4	W	0x0	TFT TX Empty Trigger This is used to select the empty threshold level when the THRE Interrupts are generated and the mode is active. It also determines when the dma_tx_req_n signal is asserted in certain modes of operation. 00: FIFO empty 01: 2 characters in the FIFO 10: FIFO ¼ full 11: FIFO ½ full
3	W	0x0	DMAM DMA Mode 0: Mode 0 In this mode, when the PTE in UART_HALT is high and TX FIFO is enabled, the TX DMA request will be set when the TFL in UART_TFL is less than or equal to FIFO Trigger Level (otherwise it will be cleared). When the PTE is high and TX FIFO is disabled, the TX DMA request will be set only if the THR in UART_THR is empty. If the PTE is low, the TX DMA request will be set only if the TX FIFO (TX FIFO enabled) or THR (TX FIFO disabled) is empty. When the DMA_PTE_RX in UART_HALT is high and RX FIFO is enabled, the RX DRQ will be set only if the RFL in UART_RFL is equal to or more than FIFO Trigger Level, otherwise, it will be cleared. 1: Mode 1 In this mode, TX FIFO should be enabled. If the PTE in *UART_HALT* is high, the TX DMA request will be set when the TFL in *UART_TFL* is less than or equal to FIFO Trigger Level; If the PTE is low, the TX DMA request will be set when TX FIFO is empty. Once the request is set, it is cleared only when TX FIFO is full. If the RFL in UART_RFL is equal to or more than FIFO Trigger Level or there is a character timeout, the RX DRQ will be set; Once the RX DRQ is set, it is cleared only when RX FIFO (RX FIFO enabled) or RBR (RX FIFO disabled) is empty.
2	W	0x0	XFIFOR XMIT FIFO Reset The bit resets the control part of the transfer FIFO and treats the FIFO as empty. This also de-asserts the DMA TX request. It is 'self-cleared'. It is not necessary to clear this bit.

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Offset: 0x0008			Register Name: UART_FCR
Bit	**Read/Write**	**Default/Hex**	**Description**
1	W	0x0	RFIFOR RCVR FIFO Reset The bit resets the control part of the receive FIFO and treats the FIFO as empty. This also de-asserts the DMA RX request. It is 'self-cleared'. It is not necessary to clear this bit.
0	W	0x0	FIFOE Enable FIFOs The bit enables/disables the transmitting (XMIT) and receiving (RCVR) FIFOs. Whenever the value of this bit is changed, both the XMIT and RCVR controller part of FIFOs is reset.

10.2.6.8 0x000C UART Line Control Register (Default Value: 0x0000_0000)

Offset: 0x000C			Register Name: UART_LCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	DLAB Divisor Latch Access Bit It is writable only when UART is not busy (UART_USR[0] is 0) and always readable. This bit is used to enable the reading and writing of the Divisor Latch register (UART_DLL and UART_DLH) to set the baud rate of the UART. This bit must be cleared after the initial baud rate setup in order to access other registers. 0: Select RX Buffer Register (UART_RBR)/TX Holding Register (UART_THR) and Interrupt Enable Register (UART_IER) 1: Select Divisor Latch LS Register (UART_DLL) and Divisor Latch MS Register (UART_DLM)
6	R/W	0x0	BC Break Control Bit This is used to cause a break condition to be transmitted to the receiving device. If set to 0, the serial output is forced to the spacing (logic 0) state. When not in Loopback mode, as determined by UART_MCR[4], the SOUT line is forced low until the Break bit is cleared. If SIR_MODE is enabled and active (UART_MCR[6] is set to 1), the sir_out_n line is continuously pulsed. When in Loopback mode, the break condition is internally looped back to the receiver and the sir_out_n line is forced low.

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Offset: 0x000C			Register Name: UART_LCR
Bit	**Read/Write**	**Default/Hex**	**Description**
5:4	R/W	0x0	EPS Even Parity Select It is writable only when UART is not busy (UART_USR[0] is 0). This is used to select the even and odd parity when the PEN is enabled (the UART_LCR[3] is set to 1). Setting the UART_LCR[5] is unset to reverse the LCR[4]. 00: Odd Parity 01: Even Parity 1X: Reverse LCR[4] In RS485 mode, it is the 9th bit--address bit. 11: 9th bit = 0, indicates that this is a data byte. 10: 9th bit = 1, indicates that this is an address byte. **Note: When using this function, the PEN(UART_LCR[3]) must set to 1.**
3	R/W	0x0	PEN Parity Enable It is writable only when UART is not busy (UART_USR[0] is 0) and always readable. This bit is used to enable and disable parity generation and detection in transmitted and received serial characters respectively. 0: Parity disabled 1: Parity enabled
2	R/W	0x0	STOP Number of stop bits It is writable only when UART is not busy (UART_USR[0] is 0) and always readable. This is used to select the number of stop bits per character that the peripheral transmits and receives. If set to 0, one stop bit is transmitted in the serial data. If set to 1 and the data bits are set to 5 (UART_LCR[1:0] is 0), one and a half stop bit is transmitted. Otherwise, two stop bits are transmitted. Note that regardless of the number of stop bits selected, the receiver checks only the first stop bit. 0: 1 stop bit 1: 1.5 stop bits when DLS (LCR[1:0]) is zero, else 2 stop bit

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Offset: 0x000C			Register Name: UART_LCR
Bit	**Read/Write**	**Default/Hex**	**Description**
1:0	R/W	0x0	DLS Data Length Select It is writable only when UART is not busy (UART_USR[0] is 0) and always readable. This is used to select the count of bits in a transmitted or received frame. 00: 5 bits 01: 6 bits 10: 7 bits 11: 8 bits

10.2.6.9 0x0010 UART Modem Control Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: UART_MCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:6	R/W	0x0	UART_FUNCTION Select IrDA or RS485 00: UART Mode 01: IrDA SIR Mode 10: RS485 Mode 11: Reserved
5	R/W	0x0	AFCE Auto Flow Control Enable When FIFOs are enabled and the AFCE bit is set, the AutoFlow Control is enabled. 0: Auto Flow Control mode disabled 1: Auto Flow Control mode enabled

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Offset: 0x0010			Register Name: UART_MCR
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W	0x0	LOOP Loop Back Mode 0: Normal Mode 1: Loop Back Mode This is used to put the UART into a diagnostic mode for test purposes. If operating in UART mode (SIR_MODE != Enabled or not active, UART_MCR[6] is set to 0), the data on the SOUT line is held high, while serial data output is looped back to the sin line, internally. In this mode, all the interrupts are fully functional. Also, in loopback mode, the modem control inputs (dsr_n, cts_n, ri_n, dcd_n) are disconnected and the modem control outputs (dtr_n, rts_n, out1_n, out2_n) are looped back to the inputs, internally. If operating in infrared mode (SIR_MODE == Enabled AND active, UART_MCR[6] is set to 1), the data on the sir_out_n line is held low, while serial data output is inverted and looped back to the sir_in line.
3:2	/	/	/
1	R/W	0x0	RTS Request to Send This is used to directly control the Request to Send (rts_n) output. The RTS (rts_n) output is used to inform the modem or data set that the UART is ready to exchange data. When Auto RTS Flow Control is not enabled (*UART_MCR[5]* is set to 0), the rts_n signal is set low by programming UART_MCR[1] (RTS) to a high. In Auto Flow Control, AFCE_MODE == Enabled and active (*UART_MCR[5]* is set to 1) and FIFOs enable (UART_FCR[0] is set to 1), the rts_n output is controlled in the same way, but is also gated with the receiver FIFO threshold trigger (rts_n is inactive high when above the threshold). The rts_n signal is de-asserted when UART_MCR[1] is set low. 0: rts_n de-asserted (logic 1) 1: rts_n asserted (logic 0) Note that in Loopback mode (UART_MCR[4] is set to 1), the rts_n output is held inactive high while the value of this location is internally looped back to an input.

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Offset: 0x0010			Register Name: UART_MCR
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	DTR Data Terminal Ready This is used to directly control the Data Terminal Ready (dtr_n) output. The value written to this location is inverted and driven out on dtr_n. 0: dtr_n de-asserted (logic 1) 1: dtr_n asserted (logic 0) The DTR output is used to inform the modem or data set that the UART is ready to establish communications. Note that in Loopback mode (UART_MCR[4] is set to 1), the dtr_n output is held inactive high while the value of this location is internally looped back to an input.

10.2.6.10 0x0014 UART Line Status Register (Default Value: 0x0000_0060)

Offset:0x0014			Register Name: UART_LSR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R	0x0	FIFOERR RX Data Error in FIFO When FIFOs are disabled, this bit is always 0. When FIFOs are enabled, this bit is set to “1” when there is at least one PE, FE, or BI in the RX FIFO. It is cleared by reading from the UART_LSR register, there are no subsequent errors in the FIFO.
6	R	0x1	TEMT Transmitter Empty If the FIFOs are disabled, this bit is set to "1" whenever the TX Holding Register (UART_THR) and the TX Shift Register are empty. If the FIFOs are enabled, this bit is set whenever the TX FIFO and the TX Shift Register are empty. In both cases, this bit is cleared when a byte is written to the TX data channel.

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Offset:0x0014			Register Name: UART_LSR
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R	0x1	THRE TX Holding Register Empty If the FIFOs are disabled, this bit is set to "1" when the TX Holding Register (UART_THR) is empty and ready to accept new data and it is cleared when the CPU writes to the TX Holding Register. If the FIFOs are enabled, this bit is set to "1" whenever the TX FIFO is empty and it is cleared when at least one byte is written to the TX FIFO.
4	R	0x0	BI Break Interrupt This is used to indicate the detection of a break sequence on the serial input data. If in UART mode (SIR_MODE == Disabled), it is set when the serial input, sir_in, is held in a logic '0' state for longer than the sum of *start time* + *data bits* + *parity* + *stop bits*. If in infrared mode (SIR_MODE == Enabled), it is set when the serial input, sir_in, is continuously pulsed to logic '0' for longer than the sum of *start time* + *data bits* + *parity* + *stop bits*. A break condition on serial input causes one and only one character, consisting of all zeros, to be received by the UART. In the FIFO mode, the character associated with the break condition is carried through the FIFO and is revealed when the character is at the top of the FIFO. Reading the UART_LSR clears the BI bit. In the non-FIFO mode, the BI indication occurs immediately and persists until the UART_LSR is read.

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Offset:0x0014			Register Name: UART_LSR
Bit	**Read/Write**	**Default/Hex**	**Description**
3	RC	0x0	FE Framing Error This is used to indicate the occurrence of a framing error in the receiver. A framing error occurs when the receiver does not detect a valid STOP bit in the received data. In the FIFO mode, since the framing error is associated with a character received, it is revealed when the character with the framing error is at the top of the FIFO. When a framing error occurs, the UART tries to resynchronize. It does this by assuming that the error was due to the start bit of the next character and then continues receiving the other bit i.e. data, and/or parity and stop. It should be noted that the Framing Error (FE) bit (UART_LSR[3]) is set if a break interrupt has occurred, as indicated by Break Interrupt (BI) bit (UART_LSR[4]). 0: no framing error 1: framing error Reading the UART_LSR clears the FE bit.
2	RC	0x0	PE Parity Error This is used to indicate the occurrence of a parity error in the receiver if the Parity Enable (PEN) bit (UART_LCR[3]) is set. In the FIFO mode, since the parity error is associated with a character received, it is revealed when the character with the parity error arrives at the top of the FIFO. It should be noted that the Parity Error (PE) bit (UART_LSR[2]) is set if a break interrupt has occurred, as indicated by Break Interrupt (BI) bit (UART_LSR[4]). 0: no parity error 1: parity error Reading the UART_LSR clears the PE bit.

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Offset:0x0014			Register Name: UART_LSR
Bit	**Read/Write**	**Default/Hex**	**Description**
1	RC	0x0	OE Overrun Error This occurs if a new data character was received before the previous data was read. In the non-FIFO mode, the OE bit is set when a new character arrives in the receiver before the previous character was read from the UART_RBR. When this happens, the data in the UART_RBR is overwritten. In the FIFO mode, an overrun error occurs when the FIFO is full and a new character arrives at the receiver. The data in the FIFO is retained and the data in the receive shift register is lost. 0: no overrun error 1: overrun error Reading the UART_LSR clears the OE bit.
0	R	0x0	DR Data Ready This is used to indicate that the receiver contains at least one character in the UART_RBR or the receiver FIFO. 0: no data ready 1: data ready This bit is cleared when the UART_RBR is read in non-FIFO mode, or when the receiver FIFO is empty, in FIFO mode. **Note: Not use when the RXDMA master is enabled (rxdma_ctrl[0] is set to 1).**

10.2.6.11 0x0018 UART Modem Status Register (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: UART_MSR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R	0x0	DCD Line State of Data Carrier Detect This is used to indicate the current state of the modem control line dcd_n. This bit is the complement of dcd_n. When the Data Carrier Detect input (dcd_n) is asserted it is an indication that the carrier has been detected by the modem or data set. 0: dcd_n input is de-asserted (logic 1) 1: dcd_n input is asserted (logic 0)

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Offset: 0x0018			Register Name: UART_MSR
Bit	**Read/Write**	**Default/Hex**	**Description**
6	R	0x0	RI Line State of Ring Indicator This is used to indicate the current state of the modem control line ri_n. This bit is the complement of ri_n. When the Ring Indicator input (ri_n) is asserted it is an indication that a telephone ringing signal has been received by setting the modem or data. 0: ri_n input is de-asserted (logic 1) 1: ri_n input is asserted (logic 0)
5	R	0x0	DSR Line State of Data Set Ready This is used to indicate the current state of the modem control line dsr_n. This bit is the complement of the dsr_n. When the Data Set Ready input (dsr_n) is asserted, it is an indication that the modem or data set is ready to establish communication with UART. 0: dsr_n input is de-asserted (logic 1) 1: dsr_n input is asserted (logic 0) In Loopback Mode (UART_MCR[4] is set to 1), the DSR is the same as the DTR (UART_MCR[0]).
4	R	0x0	CTS Line State of Clear To Send This is used to indicate the current state of the modem control line cts_n. This bit is the complement of cts_n. When the Clear to Send input (cts_n) is asserted, it is an indication that the modem or data set is ready to exchange data with UART. 0: cts_n input is de-asserted (logic 1) 1: cts_n input is asserted (logic 0) In Loopback Mode (UART_MCR[4] = 1), the CTS is the same as the RTS (UART_MCR[1]).

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Offset: 0x0018			Register Name: UART_MSR
Bit	**Read/Write**	**Default/Hex**	**Description**
3	RC	0x0	DDCD Delta Data Carrier Detect This is used to indicate that the modem control line dcd_n has changed since the last time the UART_MSR was read. 0: no change on dcd_n since the last read of UART_MSR 1: change on dcd_n since the last read of UART_MSR Reading the UART_MSR clears the DDCD bit. **Note: If the DDCD bit is not set and the dcd_n signal is asserted (low) and a reset occurs, then the DDCD bit is set when the reset is removed if the dcd_n signal remains asserted.**
2	RC	0x0	TERI Trailing Edge Ring Indicator This is used to indicate that a change in the input ri_n (from an active-low to an inactive-high state) has occurred since the last time the UART_MSR was read. 0: no change on ri_n since the last read of UART_MSR 1: change on ri_n since the last read of UART_MSR Reading the UART_MSR clears the TERI bit.
1	RC	0x0	DDSR Delta Data Set Ready This is used to indicate that the modem control line dsr_n has changed since the last time the UART_MSR was read. 0: no change on dsr_n since the last read of UART_MSR 1: change on dsr_n since the last read of UART_MSR Reading the UART_MSR clears the DDSR bit. In Loopback Mode (UART_MCR[4] = 1), the DDSR reflects changes on the DTR (UART_MCR[0]*)*. **Note: If the DDSR bit is not set and the dsr_n signal is asserted (low) and a reset occurs, then the DDSR bit is set when the reset is removed if the dsr_n signal remains asserted.**

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Offset: 0x0018			Register Name: UART_MSR
Bit	**Read/Write**	**Default/Hex**	**Description**
0	RC	0x0	DCTS Delta Clear to Send This is used to indicate that the modem control line cts_n has changed since the last time the UART_MSR was read. 0: no change on ctsdsr_n since the last read of UART_MSR 1: change on ctsdsr_n since the last read of UART_MSR Reading the UART_MSR clears the DCTS bit. In Loopback Mode (UART_MCR[4] = 1), the DCTS reflects changes on the RTS (UART_MCR[1]). **Note: If the DCTS bit is not set and the cts_n signal is asserted (low) and a reset occurs, then the DCTS bit is set when the reset is removed if the cts_n signal remains asserted.**

10.2.6.12 0x001C UART Scratch Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: UART_SCH
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x0	SCRATCH_REG Scratch Register This register is for programmers to use as a temporary storage space. It has no defined purpose in the UART.

10.2.6.13 0x007C UART Status Register (Default Value: 0x0000_0006)

Offset: 0x007C			Register Name: UART_USR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:5	/	/	/
4	R	0x0	RFF RX FIFO Full This is used to indicate that the RX FIFO is completely full. 0: RX FIFO not full 1: RX FIFO Full This bit is cleared when the RX FIFO is no longer full.

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Offset: 0x007C			Register Name: UART_USR
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R	0x0	RFNE RX FIFO Not Empty This is used to indicate that the RX FIFO contains one or more entries. 0: RX FIFO is empty 1: RX FIFO is not empty This bit is cleared when the RX FIFO is empty.
2	R	0x1	TFE TX FIFO Empty This is used to indicate that the TX FIFO is completely empty. 0: TX FIFO is not empty 1: TX FIFO is empty This bit is cleared when the TX FIFO is no longer empty.
1	R	0x1	TFNF TX FIFO Not Full This is used to indicate that the TX FIFO is not full. 0: TX FIFO is full 1: TX FIFO is not full This bit is cleared when the TX FIFO is full.
0	R	0x0	BUSY UART Busy Bit 0: Idle or inactive 1: Busy

10.2.6.14 0x0080 UART Transmit FIFO Level Register (Default Value: 0x0000_0000)

Offset: 0x0080			Register Name: UART_TFL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:9	/	/	/
8:0	R	0x0	TFL TX FIFO Level The bit indicates the number of data entries in the TX FIFO.

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10.2.6.15 0x0084 UART Receive FIFO Level Register (Default Value: 0x0000_0000)

Offset: 0x0084			Register Name: UART_RFL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:9	/	/	/
8:0	R	0x0	RFL RX FIFO Level The bit indicates the number of data entries in the RX FIFO. **Note: Not use when the RXDMA master is enabled (**UART_RXDMA_CTRL**[0] is set to 1).**

10.2.6.16 0x0088 UART DMA Handshake Configuration Register (Default Value: 0x0000_00A5)

Offset: 0x0088			Register Name: UART_HSK
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0xA5	Handshake configuration 0xA5: DMA wait cycle mode 0xE5: DMA handshake mode

10.2.6.17 0x008C UART DMA Request Enable Register(Default Value: 0x0000_0003)

Offset: 0x008C			Register Name: UART_DMA_REQ_EN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/
2	R/W	0x0	DMA Timeout Enable 0: Disable 1: Enable
1	R/W	0x1	DMA TX REQ Enable 0: Disable 1: Enable
0	R/W	0x1	DMA RX REQ Enable 0: Disable 1: Enable

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10.2.6.18 0x00A4 UART Halt TX Register (Default Value: 0x0000_0000)

Offset: 0x00A4			Register Name: UART_HALT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	PTE The sending of TX_REQ In DMA1 mode (FIFO on), if the PTE is set to 1 when the TFL in UART_TFL is less than or equal to the trigger value, the controller sends the DMA request. If the PTE is set to 0, when FIFO is empty, the controller sends the DMA request. The DMA request will stop when FIFO is full. In DMA0 mode, if the PTE is set to 1 and FIFO is on, when the TFL in UART_TFL is less than or equal to the trigger value, the controller sends DMA request. If the PTE is set to 1 and FIFO off, when the THR in UART_THR is empty, the controller sends DMA request. If the PTE is set to 0, when FIFO(FIFO Enable) or THR(FIFO Enable) is empty, the controller sends DMA request. Otherwise, the DMA request is cleared.
6	R/W	0x0	DMA_PTE_RX The Transmission of RX_DRQ In DMA1 mode, when RFL is more than or equal to the trigger value, or a receive timeout has occurred, the controller sends DRQ. In DMA0 mode, when DMA_PTE_RX = 1 and FIFO is on, if RFL is more than or equal to trig, the controller sends DRQ, else DRQ is cleared. In other cases, once the received data is valid, the controller sends DRQ.
5	R/W	0x0	SIR_RX_INVERT SIR RX Pulse Polarity Invert 0: Not invert receiver signal 1: Invert receiver signal
4	R/W	0x0	SIR_TX_INVERT SIR TX Pulse Polarity Invert 0: Not invert transmit pulse 1: Invert transmit pulse
3	/	/	/

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Offset: 0x00A4			Register Name: UART_HALT
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/WAC	0x0	CHANGE_UPDATE After the user uses UART_HALT[1] to change the baud rate or LCR configuration, write 1 to update the configuration and wait this bit to self-clear to 0 to finish update process. Writing 0 to this bit has no effect. 1: Update trigger, self-clear to 0 when finish update.
1	R/W	0x0	CHCFG_AT_BUSY This is an enable bit for the user to change LCR register configuration and baud rate register (UART_DLH and UART_DLL) when the UART is busy. 1: Enable change when busy
0	R/W	0x0	HALT_TX Halt TX This register is used to halt transmissions for testing, so that the transmit FIFO can be filled by the master when FIFOs are implemented and enabled. 0 : Halt TX disabled 1 : Halt TX enabled **Note: If FIFOs are not enabled, the setting has no effect on operation.**

10.2.6.19 0x00B0 UART DBG DLL Register (Default Value: 0x0000_0000)

Offset: 0x00B0			Register Name: UART_DBG_DLL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R	0x0	DEBUG DLL

10.2.6.20 0x00B4 UART DBG DLH Register (Default Value: 0x0000_0000)

Offset: 0x00B4			Register Name: UART_DBG_DLH
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R	0x0	DEBUG DLH

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10.2.6.21 0x00F0 UART FIFO Clock Control Register (Default Value: 0x0000_0003)

Offset: 0x00F0			Register Name: UART_FCC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	R	0x0	FIFO Depth Indicates the depth of TX/RX FIFO
7:3	/	/	/
2	R/W	0x0	RXFIFO Clock Mode 0: Sync mode, writing/reading clocks use apb clock 1: Sync mode, writing clock uses apb clock, reading clock uses ahb clock
1	R/W	0x1	TX FIFO Clock Enable 0: Clock disable 1: Clock enable
0	R/W	0x1	RX FIFO Clock Enable 0: Clock disable 1: Clock enable

10.2.6.22 0x0100 UART RXDMA Control Register (Default Value: 0x0000_0000)

Offset: 0x0100			Register Name: UART_RXDMA_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:8	R/W	0x0	RXDMA Timeout Threshold Unit is 1 UART bit time Note that this field is only configurable when RXDMA Busy is 0.
7	/	/	/
6	R/W	0x0	RXDMA Timeout Enable Once enable, the DMA starts a transfer even the data entries in RX FIFO do not reach BLK_SIZE. Note that this field is only configurable when RXDMA Busy is 0.

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Offset: 0x0100			Register Name: UART_RXDMA_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
5:4	R/W	0x0	RXDMA AHB Burst Mode Set for AHB port burst supported INCR8 is recommended, while INCR16 may be unsupported due to the system bus. 00: SIGNLE 01: INCR4 10: INCR8 11: INCR16 Note that this field is only configurable while RXDMA Busy is 0.
3:2	R/W	0x0	RXDMA BLK SIZE Every time when data entries in RX FIFO reach BLK_SIZE, start a DMA block transfer. It is recommended that the block size no more than RX FIFO Depth. 00: 8 bytes 01: 16 bytes 10: 32 bytes 11: 64 bytes Note that this field is only configurable while RXDMA Busy is 0.
1	R/W	0x0	RXDMA Mode 0: Continous 1: Limited When data transferred reaches the limited count set in RXDMA LIMIT, the DMA stops and the RXDMA Start bit is cleared automatically. Note that this field is only configurable while RXDMA Busy is 0.
0	R/W	0x0	RXDMA Enable 0: RXDMA Disable 1: RXDMA Enable Note that if the software turns off this bit, the RXDMA will stop after the current block transfer completes, then the software should do a reset to the RX FIFO before re-enable.

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10.2.6.23 0x0104 UART RXDMA Start Register (Default Value: 0x0000_0000)

Offset: 0x0104			Register Name: UART_RXDMA_STR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
0	R/WAC	0x0	RXDMA Start Only valid when RXDMA mode is set to 1, it is auto cleared when data transferred reaches the RXDMA Limit Size.

10.2.6.24 0x0108 UART RXDMA Status Register (Default Value: 0x0000_0000)

Offset: 0x0108			Register Name: UART_RXDMA_STA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
1	R	0x0	Buffer Read Address Updating 0: Buffer Read Address Register is ready for updating 1: Buffer Read Address Register is busy for updating The software should not update Buffer Read Address Register until this bit is 0.
0	R	0x0	RXDMA BUSY 0: RXDMA is idle 1: RXDMA is busy

10.2.6.25 0x010C UART RXDMA Limit Register (Default Value: 0x0000_0000)

Offset: 0x010C			Register Name: UART_RXDMA_LMT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0x0	RXDMA Limit Size Only valid when RXDMA Mode is set to 1, and the unit is byte. Note that this field is only configurable while RXDMA Busy is 0.

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10.2.6.26 0x0110 UART RXDMA Buffer Start Address Low Register (Default Value: 0x0000_0000)

Offset: 0x0110			Register Name: UART_RXDMA_SADDRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	RXDMA Buffer Start Address [31:0] Byte address Note that this field is only configurable while RXDMA Busy is 0.

10.2.6.27 0x0114 UART RXDMA Buffer Start Address High Register (Default Value: 0x0000_0000)

Offset: 0x0114			Register Name: UART_RXDMA_SADDRH
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1:0	R/W	0x0	RXDMA Buffer Start Address [33:32] Byte address Note that this field is only configurable while RXDMA Busy is 0.

10.2.6.28 0x0118 UART RXDMA Buffer Length Register (Default Value: 0x0000_0000)

Offset: 0x0118			Register Name: UART_RXDMA_BL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R/W	0x0	RXDMA Buffer Length Unit is byte Note that this field is only configurable while RXDMA Busy is 0.

10.2.6.29 0x0120 UART RXDMA Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x0120			Register Name: UART_RXDMA_IE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3	R/W	0x0	RXDMA Buffer Overrun RXDMA Buffer Overrun Interrupt Enable

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Offset: 0x0120			Register Name: UART_RXDMA_IE
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	RXDMA Timeout Done RXDMA Timeout Done Interrupt Enable
1	R/W	0x0	RXDMA BLK Done RXDMA BLK Done Interrupt Enable
0	R/W	0x0	RXDMA Limit Done RXDMA Limit Done Interrupt Enable

10.2.6.30 0x0124 UART RXDMA Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0124			Register Name: UART_RXDMA_IS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3	R/W1C	0x0	RXDMA Buffer Overrun Asserted when the RXDMA buffer is overflow.
2	R/W1C	0x0	RXDMA Timeout Done Asserted when a DMA transfer caused by timeout is done.
1	R/W1C	0x0	RXDMA BLK Done Asserted when a DMA block transfer is done.
0	R/W1C	0x0	RXDMA Limit Done Asserted when data transferred reaches limit size in RXDMA Limit Mode.

10.2.6.31 0x0128 UART RXDMA Write Address Low Register (Default Value: 0x0000_0000)

Offset: 0x0128			Register Name: UART_RXDMA_WADDRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	RXDMA Current Write Address[31:0] Updated when every DMA transfer is done It is byte address.

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10.2.6.32 0x012C UART RXDMA Write Address High Register (Default Value: 0x0000_0000)

Offset: 0x012C			Register Name: UART_RXDMA_WADDRH
Bit	Read/Write	Default/Hex	Description
31:2	/	/	/
1:0	R	0x0	RXDMA Current Write Address[33:32] Updated when every DMA transfer is done It is byte address.

10.2.6.33 0x0130 UART RXDMA Read Address Low Register (Default Value: 0x0000_0000)

Offset: 0x0130			Register Name: UART_RXDMA_RADDRL
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	RXDMA Current Read Address[31:0] Software should update this register after reading data in RXDMA Buffer in time It is byte address. The software should not update Buffer Read Address Register until UART_RXDMA_STA[1] is 0. The software should update Read Address High Register first, and then Read Address Low Register, even there is no change on Read Address High Register.

10.2.6.34 0x0134 UART RXDMA Read Address High Register (Default Value: 0x0000_0000)

Offset: 0x0134			Register Name: UART_RXDMA_RADDRH
Bit	Read/Write	Default/Hex	Description
31:2	/	/	/
1:0	R/W	0x0	RXDMA Current Read Address[33:32] Software should update this register after reading data in RXDMA Buffer in time. It is byte address. The software should not update Buffer Read Address Register until until UART_RXDMA_STA[1] is 0. The software should update Read Address High Register first and then Read Address Low Register , even there is no change on Read Address High Register.

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10.2.6.35 0x0138 UART RXDMA Data Count Register (Default Value: 0x0000_0000)

Offset: 0x0138			Register Name: UART_RXDMA_DCNT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R	0x0	RXDMA Data Count Only valid while RXDMA Mode is set to 1, it is used for counting the data transferred by RXDMA, and is cleared when reaches RXDMA Limit Size. Its unit is byte.

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10.3 SPI

10.3.1 Overview

The Serial Peripheral Interface (SPI) is a full-duplex, synchronous, four-wire serial communication interface between a CPU and SPI-compliant external devices. The SPI controller contains a 64 x 8 bits receiver buffer (RXFIFO) and a 64 x 8 bits transmit buffer (TXFIFO). It can work in master mode and slave mode.

The SPI has the following features:

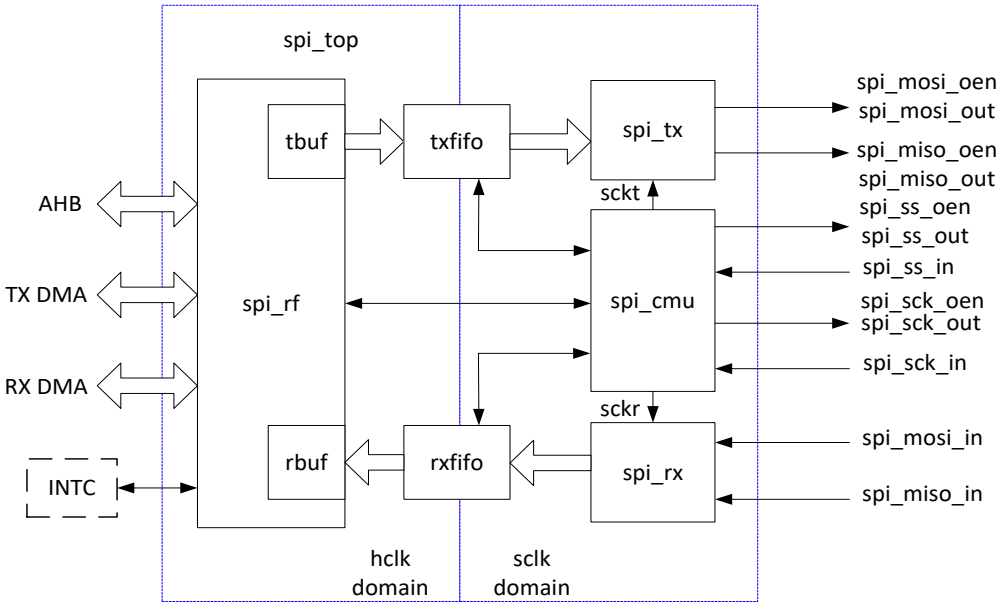
- Full-duplex synchronous serial interface
- Master/slave configurable
- 8-bit wide by 64-entry FIFO for both transmit and receive data
- Polarity and phase of the Chip Select (SPI_SS) and SPI Clock (SPI_SCLK) are configurable
- Supports interrupts and DMA
- Supports mode0, mode1, mode2, and mode3
- Supports 3-wire/4-wire SPI
- Supports programmable serial data frame length: 1 bit to 32 bits
- Supports standard SPI, dual-output/dual-input SPI, dual I/O SPI, quad-output/quad-input SPI
- Supports maximum IO rate of the mass production: 100 MHz

10.3.2 Block Diagram

Figure 10-20 shows a block diagram of the SPI.

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Figure 10-20 SPI Block Diagram



SPI contains the following sub-blocks:

Table 10-6 SPI Sub-blocks

Sub-block	Description
spi_rf	Responsible for implementing the internal register, interrupt, and DMA Request.
spi_tbuf	The data length transmitted from AHB to TXFIFO is converted into 8 bits, then the data is written into the RXFIFO.
spi_rbuf	The block is used to convert the RXFIFO data into the reading data length of AHB.
txfifo, rxfifo	The data transmitted from the SPI to the external serial device is written into the TXFIFO; the data received from the external serial device into SPI is pushed into the RXFIFO.
spi_cmu	Responsible for implementing SPI bus clock, chip select, internal sample, and the generation of transfer clock.
spi_tx	Responsible for implementing SPI data transfer, the interface of the internal TXFIFO, and status register.
spi_rx	Responsible for implementing SPI data receive, the interface of the internal RXFIFO, and status register.

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10.3.3 Functional Description

10.3.3.1 External Signals

The following table describes the external signals of SPI. The MOSI and MISO are bidirectional I/O, when SPI is as a master device, the CLK and CS are the output pin; when SPI is as a slave device, the CLK and CS are the input pin. When using SPI, the corresponding PADs are selected as SPI function via section 9.7 "GPIO".

Table 10-7 SPI External Signals

Signal	Description	Type
SPI0-CS	SPI0 chip select signal, low active When the device is not selected, data will not be accepted via the SI pin, and the SO pin will stop transmission.	I/O
SPI0-CLK	SPI0 clock signal This pin is used to provide a clock to the device and is used to control the flow of data to and from the device.	I/O
SPI0-MOSI	SPI0 master data out, slave data in	I/O
SPI0-MISO	SPI0 master data in, slave data out	I/O
SPI0-WP	Write protection and low active It also can be used for serial data input and output for SPI Quad Input or Quad Output mode.	I/O
SPI0-HOLD	When the device is selected and a serial sequence is underway, the HOLD pin can be used to temporarily pause the serial communication with the master device without deselecting or resetting the serial sequence. While the HOLD pin is asserted, the SO pin is at high impedance, and all transitions on the SCK pin and data on the SI pin are ignored. It also can be used for serial data input and output for SPI Quad Input or Quad Output mode.	I/O

10.3.3.2 Clock Sources

The SPI controller gets 5 different clock sources, users can select one of them to make SPI clock source. The following table describes the clock sources for SPI. For more details on the clock setting, configuration, and gating information, see section 3.3 "CCU".

Table 10-8 SPI Clock Sources

Clock Sources	Description
HOSC	24 MHz Crystal

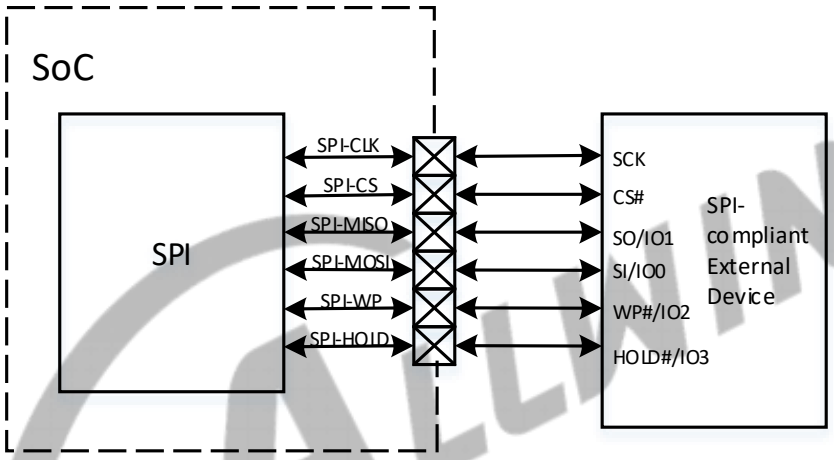
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Clock Sources	Description
PLL_PERI(1X)	Peripheral Clock, default value is 600 MHz
PLL_PERI(2X)	Peripheral Clock, default value is 1200 MHz
PLL_AUDIO0(DIV2)	Audio Clock, the default value is 1536 MHz
PLL_AUDIO0(DIV5)	Audio Clock, the default value is 614.4 MHz

10.3.3.3 Typical Application

Figure 10-21 shows the application block diagram when the SPI master device is connected to a slave device.

Figure 10-21 SPI Application Block Diagram



10.3.3.4 SPI Transmit Format

The SPI supports 4 different formats for data transfer. The software can select one of the four modes in which the SPI works by setting the bit1 (Polarity) and bit0 (Phase) of SPI_TCR. The SPI controller master uses the SPI_SCLK signal to transfer data in and out of the shift register. Data is clocked using any one of four programmable clock phase and polarity combinations.

The CPOL (SPI_TCR[1]) defines the polarity of the clock signal (SPI_SCLK). The SPI_SCLK is a high level when CPOL is '1' and it is a low level when CPOL is '0'. The CPHA (SPI_TCR[0]) decides whether the leading edge of SPI_SCLK is used to setup or sample data. The leading edge is used to setup data when CPHA is '1', and sample data when CPHA is '0'. The following table lists the four modes.

Table 10-9 SPI Transmit Format

Mode	Polarity (CPOL)	Phase (CPHA)	Leading Edge	Trailing Edge
Mode0	0	0	Sample on the rising edge	Setup on the falling edge

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Mode	Polarity (CPOL)	Phase (CPHA)	Leading Edge	Trailing Edge
Mode1	0	1	Setup on the rising edge	Sample on the falling edge
Mode2	1	0	Sample on the falling edge	Setup on the rising edge
Mode3	1	1	Setup on the falling edge	Sample on the rising edge

Figure 10-22 and Figure 10-23 describe four waveforms for SPI_SCLK.

Figure 10-22 SPI Phase 0 Timing Diagram

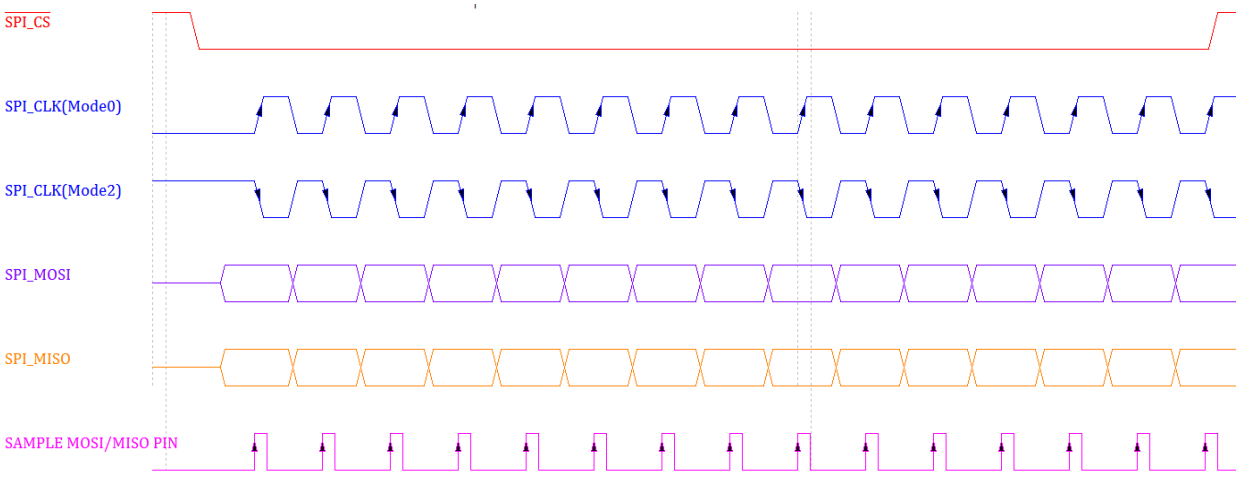
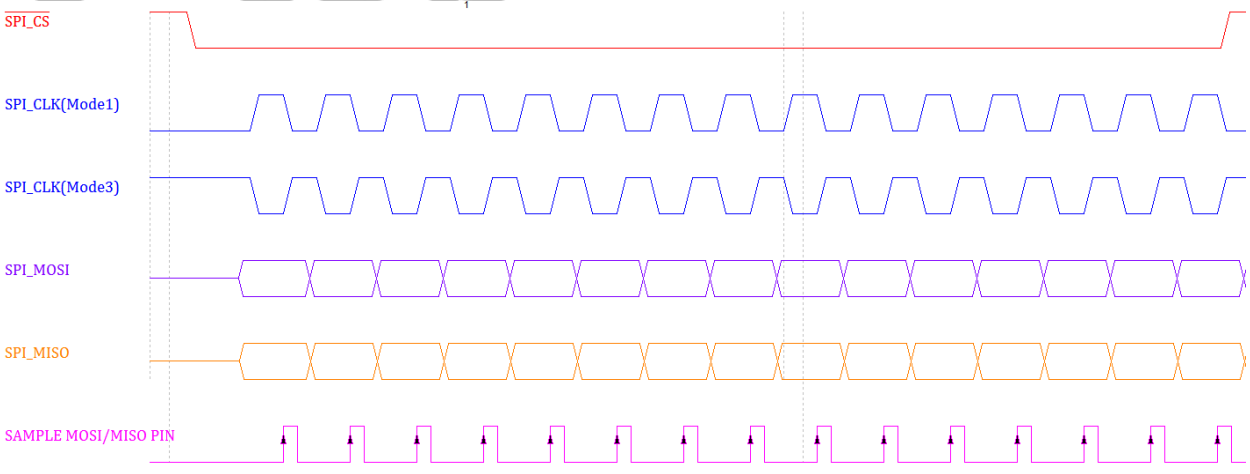


Figure 10-23 SPI Phase 1 Timing Diagram



10.3.3.5 SPI Master and Slave Mode

The SPI controller can be configured to a master or slave device. The master mode is selected by setting the MODE bit (**SPI_GCR**[1]); the slave mode is selected by clearing the MODE bit.

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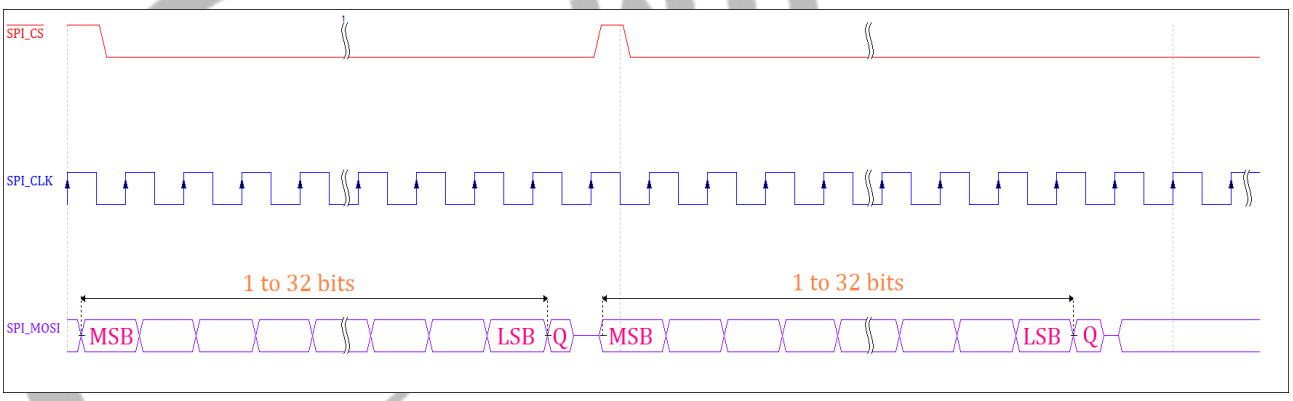
In master mode, the SPI_CLK is generated and transmitted to the external device, and the data from the TX FIFO is transmitted on the MOSI pin, the data from the slave device is received on the MISO pin and sent to RX FIFO. The Chip Select (SPI_SS) is an active low signal, and it must be set low before the data are transmitted or received. The SPI_SS can be selected the auto control mode or software manual control mode. When using the auto control, the SS_OWNER (SPI_TCR[6]) must be cleared (default value is 0); when using the manual control, the SS_OWNER must be set. And the level of SPI_SS is controlled by SS_LEVEL (SPI_TCR[7]).

In slave mode, after the software selects the MODE bit (SPI_GCR[1]) to '0', it waits for master initiate a transaction. When the master asserts SPI_SS, then SPI_CLK is transmitted to the slave device, the slave data is transmitted from TX FIFO on the MISO pin and the data from the MOSI pin is received in RX FIFO.

10.3.3.6 SPI 3-Wire Mode

The SPI 3-wire mode is only valid when the SPI controller work in master mode, and is selected when the Work Mode Select bit (SPI_BATC[1:0]) is equal to 0x2. And in the 3-wire mode, the input data and the output data use the same single data line. The following figure describes the 3-wire mode.

Figure 10-24 SPI 3-Wire Mode

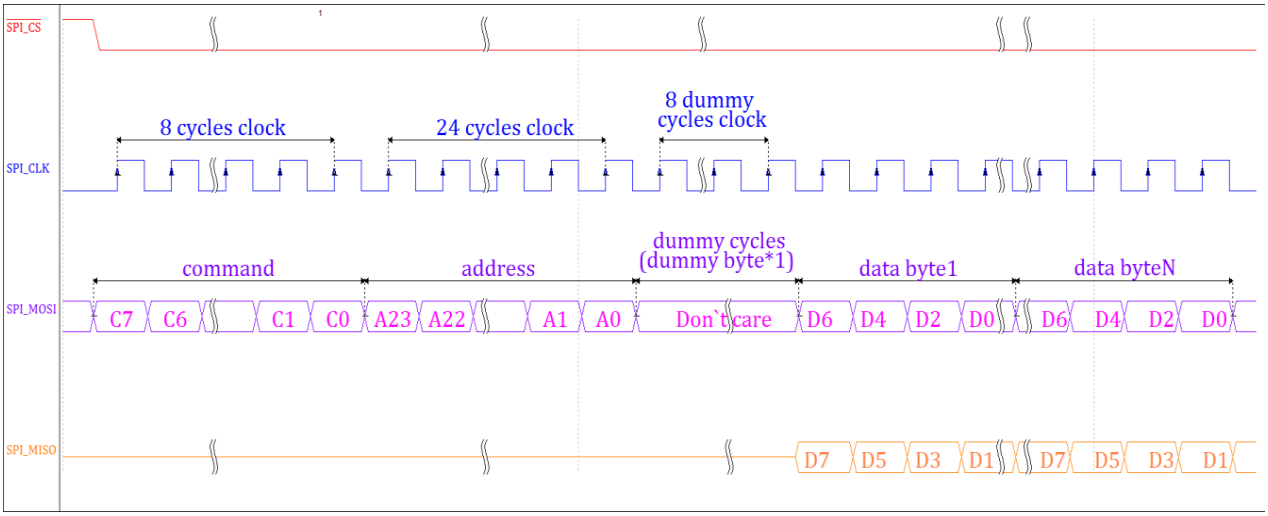


10.3.3.7 SPI Dual-Input/Dual-Output and Dual I/O Mode

The dual read mode (SPI x2) is selected when the DRM is set in SPI_BCC[28]. Using the dual mode allows data to be transferred to or from the device at double the rate of standard single mode, the data can be read at fast speed using two data bits (MOSI and MISO) at a time. The following figure describes the dual-input/dual-output SPI (Figure 10-25) and the dual I/O SPI (Figure 10-26).

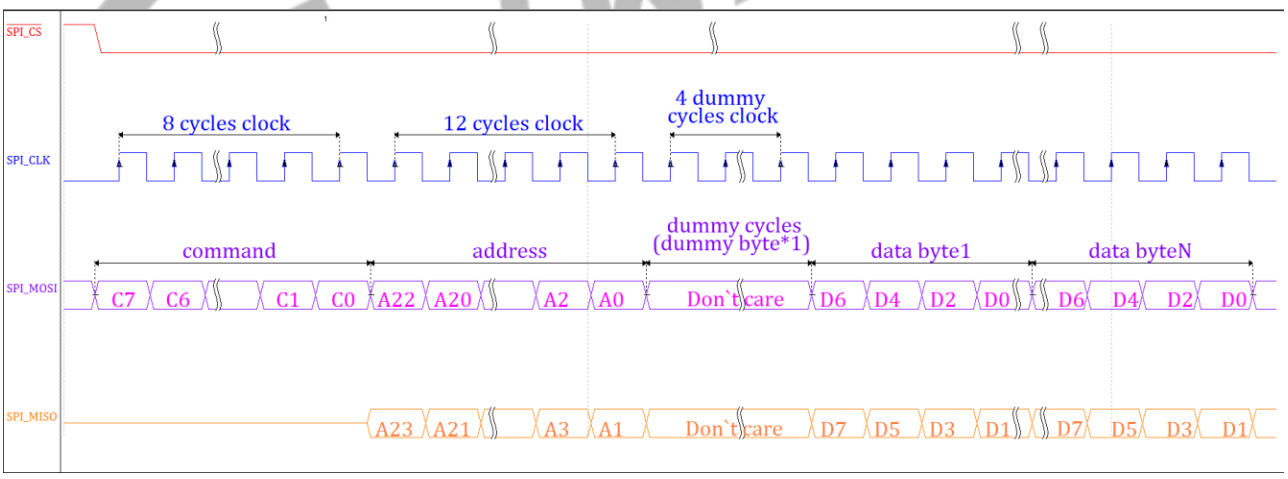
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Figure 10-25 SPI Dual-Input/Dual-Output Mode



In the dual-input/dual-output SPI mode, the command, address, and the dummy bytes output in a unit of a single bit in serial mode through the SPI_MOSI line, only the data bytes are output (write) and input (read) in a unit of dual bits through the SPI_MOSI and SPI_MISO.

Figure 10-26 SPI Dual I/O Mode



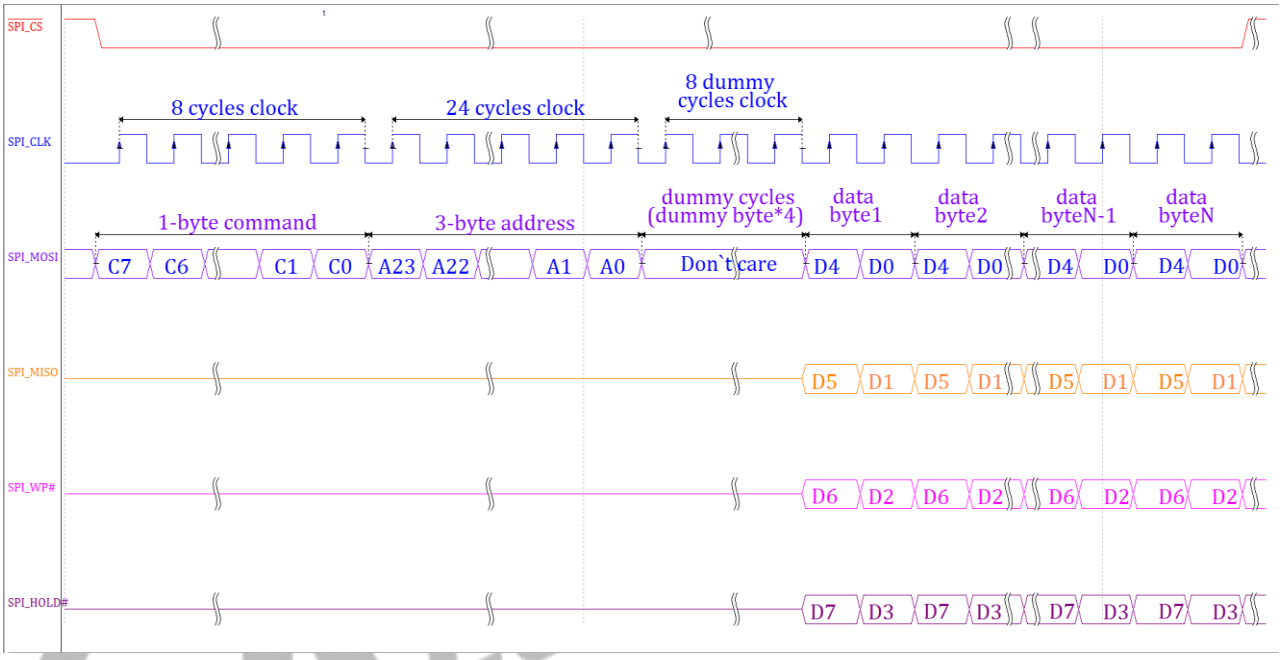
In the dual I/O SPI mode, only the command bytes output in a unit of a single bit in serial mode through the SPI_MOSI line. The address bytes and the dummy bytes output in a unit of dual bits through the SPI_MOSI and SPI_MISO. And the data bytes output (write) and input (read) in a unit of dual bits through the SPI_MOSI and SPI_MISO.

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10.3.3.8 SPI Quad-Input/Quad-Output Mode

The quad read mode (SPI x4) is selected when the Quad_EN is set in **SPI_BCC**[29]. Using the quad mode allows data to be transferred to or from the device at 4 times the rate of standard single mode, the data can be read at fast speed using four data bits (MOSI, MISO, IO2 (WP#) and IO3 (HOLD#)) at the same time. The following figure describes the quad-input/quad-output SPI.

Figure 10-27 SPI Quad-Input/Quad-Output Mode



In the quad-input/quad-output SPI mode, the command, address, and the dummy bytes output in a unit of a single bit in serial mode through SPI_MOSI line. Only the data bytes output (write) and input (read) in a unit of quad bits through the SPI_MOSI, SPI_MISO, SPI_WP#, and SPI_HOLD#.

10.3.3.9 Transmission/Reception Bursts in Master Mode

In SPI master mode, the transmission and reception bursts (byte in unit) are configured before the SPI transfers the serial data between the processor and external device. The transmission bursts are written in MWTC (bit[23:0]) of the SPI Master Transmit Counter Register. The transmission bursts in single mode before automatically sending dummy bursts are written in STC (bit[23:0]) of the SPI Master Transmit Counter Register**.** For dummy data, the SPI controller can automatically send before receiving by writing DBC (bit[27:24]) in the SPI Master Transmit Counter Register. If users do not use the SPI controller to send dummy data automatically, then the dummy bursts are used as the transmission counters to write together in MWTC (bit[23:0]) of the SPI Master Transmit Counter Register. In master mode, the total burst numbers are written in MBC (bit[23:0]) of the SPI Master Transmit Counter Register. When all transmission and reception bursts are transferred, the SPI controller will send a completed interrupt, at the same time, the SPI controller will clear DBC, MWTC, and MBC.

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10.3.3.10 SPI Sample Mode and Run Clock Configuration

The SPI controller runs at 3 kHz–100 MHz at its interface to external SPI devices. The internal SPI clock should run at the same frequency as the outgoing clock in the master mode. The SPI clock is selected from different clock sources, the SPI must configure different work mode. There are three work modes: normal sample mode, delay half-cycle sample mode, delay one-cycle sample mode. The Delay half-cycle sample mode is the default mode of the SPI controller. When the SPI runs at 40 MHz or below 40 MHz, the SPI can work at normal sample mode or delay half-cycle sample mode. When the SPI runs over 80 MHz, setting the SDC bit in the SPI Transfer Control Register to '1' makes the internal read sample point with a half-cycle delay of SPI_CLK, which is used in high speed read operation to reduce the error caused by the time delay of SPI_CLK between master and slave. Table 10-10 and Table 10-11 show the different configurations of the SPI sample mode.

Table 10-10 SPI Old Sample Mode and Run Clock

SPI Sample Mode	SDM(bit13)	SDC(bit11)	Run Clock
normal sample	1	0	<=24 MHz
delay half cycle sample	0	0	<=40 MHz
delay one cycle sample	0	1	>=80 MHz

CAUTION

The remaining spectrum is not recommended. Because when the output delay of SPI flash (refer to the datasheet of the manufactures for the specific delay time) is the same with the half-cycle time of SPI working clock, the variable edge of the output data for the device bumps into the clock sampling edge of the controller, so setting 1 cycle of sampling delay would cause stability problem.

Table 10-11 SPI New Sample Mode

SPI Sample Mode	SDM (bit13)	SDC (bit11)	SDC1 (bit15)
normal sample	1	0	0
delay half cycle sample	0	0	0
delay one cycle sample	0	1	0
delay 1.5 cycle sample	1	1	0
delay 2 cycle sample	1	0	1
delay 2.5 cycle sample	0	0	1
delay 3 cycle sample	0	1	1

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10.3.3.11 SPI Error Conditions

If any error conditions occur, the hardware will set the corresponding status bits in the SPI Interrupt Status Register and stop the transfer. For the SPI controller, the following error scenarios can happen.

1. **TX_FIFO Underrun**

   The TX_FIFO underrun happens when the CPU/DMA reads data from TX FIFO when it is empty. In the case, the SPI controller will end the transaction and flag the error bit along with the TF_UDF bit in the SPI Interrupt Status Register. The SPI controller will generate an interrupt if interrupts are enabled. The software has to clear the error bit and the TF_UDF bit. To start a new transaction, the software has to reset the FIFO by writing to the SRST (soft reset) bit in the SPI Global Control Register.

2. **TX_FIFO Overflow**

   The TX_FIFO overflow happens when the CPU/DMA writes data into the TX FIFO when it is full. In the case, the SPI controller will end the transaction and flag the error bit along with the TF_OVF bit in the SPI Interrupt Status Register. The SPI controller will generate an interrupt if interrupts are enabled. The software has to clear the error bit and the TF_OVF bit. To start a new transaction, the software has to reset the FIFO by writing to the SRST (soft reset) bit in the SPI Global Control Register.

3. **RX_FIFO Underrun**

   The RX_FIFO underrun happens when the CPU/DMA reads data from RX FIFO when it is empty. In the case, the SPI controller will end the transaction and flag the error bit along with the RF_UDF bit in the SPI Interrupt Status Register. The SPI controller will generate an interrupt if interrupts are enabled. The software has to clear the error bit and the RF_UDF bit. To start a new transaction, the software has to reset the fifo by writing to the SRST (soft reset) bit in the SPI Global Control Register.

4. **RX_FIFO Overflow**

   The RX_FIFO overflow happens when the CPU/DMA writes data into the RX FIFO when it is full. In the case, the SPI controller will end the transaction and flag the error bit along with the RF_OVF bit in the SPI Interrupt Status Register. The SPI controller will generate an interrupt if interrupts are enabled. The software has to clear the error bit and the RF_OVF bit. To start a new transaction, the software has to reset the FIFO by writing to the SRST (soft reset) bit in the SPI Global Control Register.

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10.3.4 Programming Guidelines

10.3.4.1 Writing/Reading Data Process

The SPI transfers serial data between the processor and the external device. The CPU mode and DMA mode are the two main operational modes for SPI. For each SPI, the data is simultaneously transmitted (shifted out serially) and received (shifted in serially). The SPI has 2 channels, including the TX channel and RX channel. The TX channel has the path from TX FIFO to the external device. The RX channel has the path from the external device to RX FIFO.

Write Data: The CPU or DMA must write data on the **SPI_TXD** register, the data on the register are automatically moved to TX FIFO.

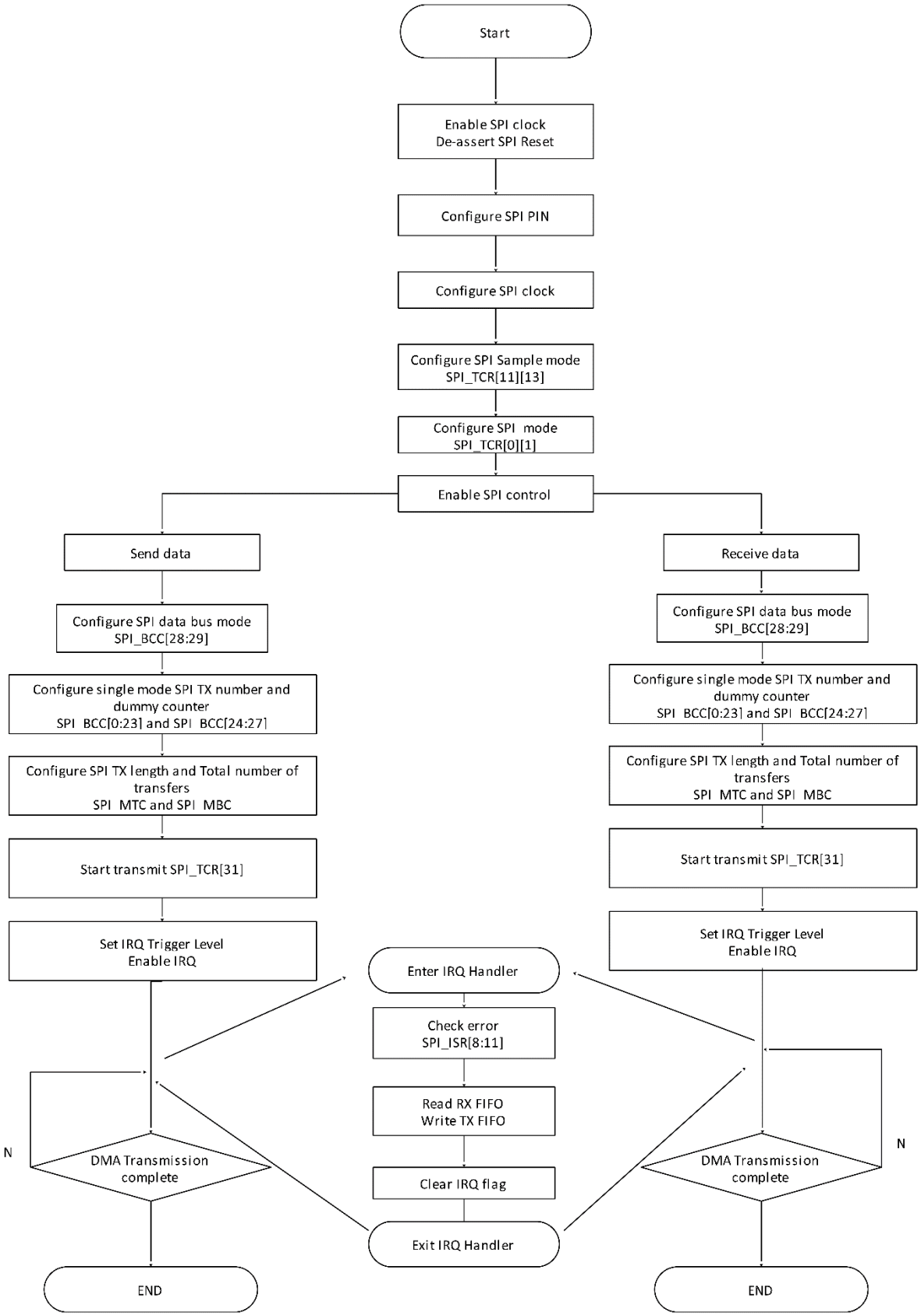
Read Data: To read data from RX FIFO, the CPU or DMA must access the **SPI_RXD** register and the data are automatically sent to the **SPI_RXD** register.

In CPU or DMA mode, the SPI sends a completed interrupt (**SPI_ISR**[TC]) to the processor after each transmission is complete.

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CPU Mode

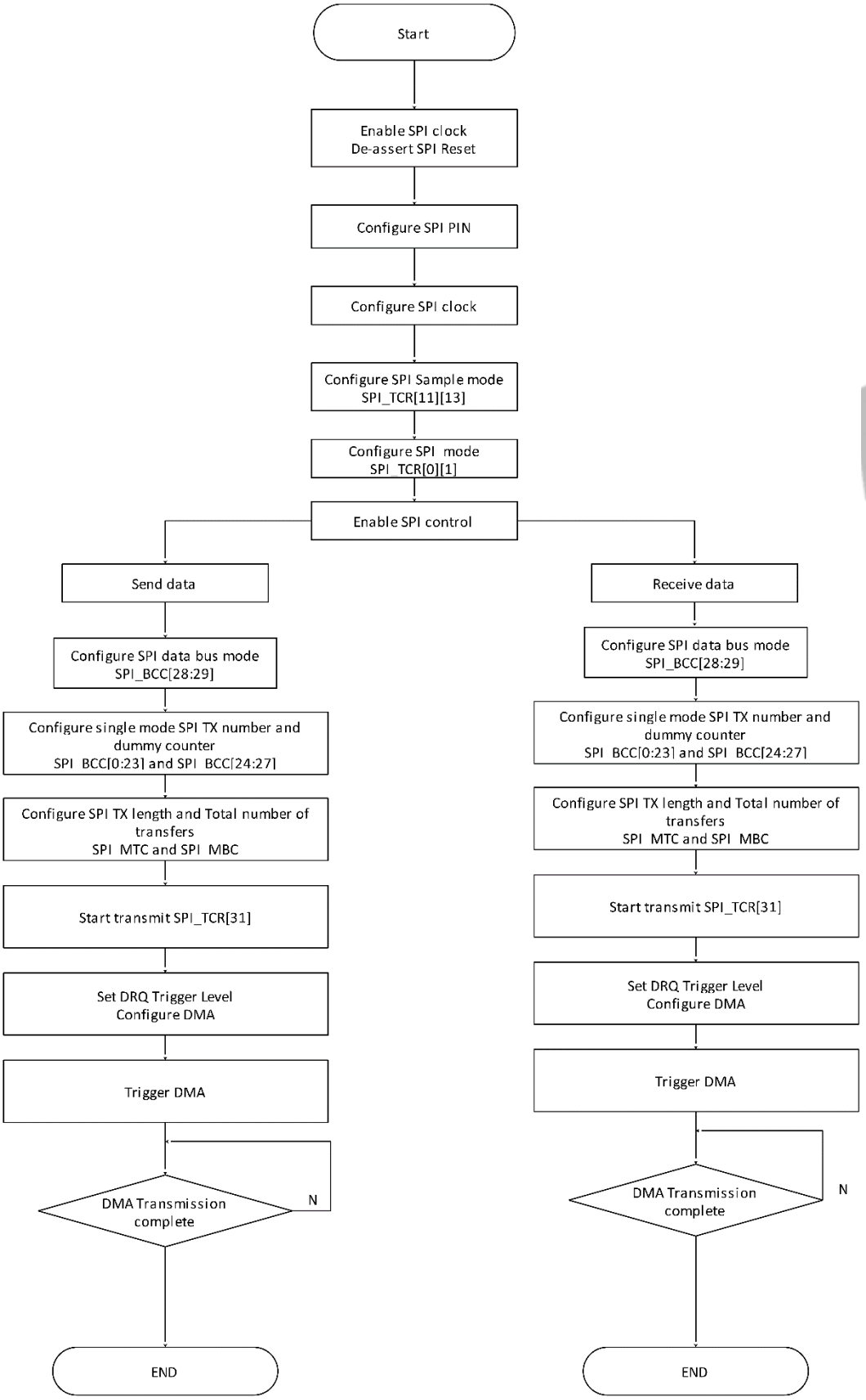
Figure 10-28 SPI Write/Read Data in CPU Mode



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DMA Mode

Figure 10-29 SPI Write/Read Data in DMA Mode



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10.3.4.2 Calibrate Delay Chain

The SPI has one delay chain which is used to generate delay to make proper timing between the internal SPI clock signal and data signals. Delay chain is made up of 64 delay cells. The delay time of one delay cell can be estimated through delay chain calibration.

The steps to calibrate delay chain are as follows:

Step 1 Enable SPI. To calibrate the delay chain by the operation registers in SPI, the SPI must be enabled through AHB reset and AHB clock gating control registers.

Step 2 Configure a proper clock for SPI. The calibration delay chain is based on the clock for SPI from CCU.

Step 3 Set proper initial delay value. Write 0xA0 to the SPI Sample Delay Control Register to set initial delay value 0x20 to delay chain. Then write 0x0 to the SPI Sample Delay Control Register to clear this value.

Step 4 Write 0x8000 to the SPI Sample Delay Control Register to start to calibrate the delay chain.

Step 5 Wait until the flag (bit14 in the SPI Sample Delay Control Register) of calibration done is set. The number of delay cells is shown at the bit[13:8] of the SPI Sample Delay Control Register. The delay time generated by these delay cells is equal to the cycle of the SPI clock nearly. This value is the result of calibration.

Step 6 Calculate the delay time of one delay cell according to the cycle of the SPI clock and the result of calibration.

10.3.5 Register List

Module Name	Base Address
SPI0	0x04025000

Register Name	Offset	Description
SPI_GCR	0x0004	SPI Global Control Register
SPI_TCR	0x0008	SPI Transfer Control Register
SPI_IER	0x0010	SPI Interrupt Control Register
SPI_ISR	0x0014	SPI Interrupt Status Register
SPI_FCR	0x0018	SPI FIFO Control Register
SPI_FSR	0x001C	SPI FIFO Status Register
SPI_WCR	0x0020	SPI Wait Clock Register
SPI_SAMP_DL	0x0028	SPI Sample Delay Control Register
SPI_MBC	0x0030	SPI Master Burst Counter Register

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Register Name	Offset	Description
SPI_MTC	0x0034	SPI Master Transmit Counter Register
SPI_BCC	0x0038	SPI Master Burst Control Register
SPI_BATCR	0x0040	SPI Bit-Aligned Transfer Configure Register
SPI_BA_CCR	0x0044	SPI Bit-Aligned Clock Configuration Register
SPI_TBR	0x0048	SPI TX Bit Register
SPI_RBR	0x004C	SPI RX Bit Register
SPI_NDMA_MODE_CTL	0x0088	SPI Normal DMA Mode Control Register
SPI_TXD	0x0200	SPI TX Data Register
SPI_RXD	0x0300	SPI RX Data Register

10.3.6 Register Description

10.3.6.1 0x0004 SPI Global Control Register (Default Value: 0x0000_0080)

Offset:0x0004			Register Name: SPI_GCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/WAC	0x0	SRST Soft reset Writing '1' to this bit will clear the SPI controller, and auto clear to '0' when reset operation completes. Writing '0' to this bit has no effect.
30:8	/	/	/
7	R/W	0x1	TP_EN Transmit Pause Enable In master mode, it is used to control the transmit state machine to stop smart burst sending when RX FIFO is full. 0: Normal operation, ignore RXFIFO status 1: Stop transmit data when RXFIFO full Cannot be written when XCH=1.
6:3	/	/	/
2	R/W	0x0	MODE_SELEC Sample Timing Mode Select 0: Old mode of Sample Timing 1: New mode of Sample Timing Cannot be written when XCH=1.

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Offset:0x0004			Register Name: SPI_GCR
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	MODE SPI Function Mode Select 0: Slave mode 1: Master mode Cannot be written when XCH=1.
0	R/W	0x0	EN SPI Module Enable Control 0: Disable 1: Enable After transforming from bit_mode to byte_mode, it must enable the SPI module again.

10.3.6.2 0x0008 SPI Transfer Control Register (Default Value: 0x0000_0087)

Offset: 0x0008			Register Name: SPI_TCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/WAC	0x0	XCH Exchange Burst In master mode, it is used to start SPI burst. 0: Idle 1: Initiates exchange. Writing “1” to this bit will start the SPI burst, and will auto-clear after finishing the bursts transfer specified by SPI_MBC. Writing “1” to SRST (SPI_GCR[31]) will also clear this bit. Writing ‘0’ to this bit has no effect. Cannot be written when XCH=1.
30:16	/	/	/
15	R/W	0x0	SDC1 Master Sample Data Control register1 Set this bit to ‘1’ to make the internal read sample point with a delay of half-cycle of SPI_CLK. It is used in high speed read operation to reduce the error caused by the time delay of SPI_CLK between master and slave. 0: normal operation, do not delay the internal read sample point 1: delay the internal read sample point Cannot be written when XCH=1.

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Offset: 0x0008			Register Name: SPI_TCR
Bit	**Read/Write**	**Default/Hex**	**Description**
14	R/W	0x0	SDDM Sending Data Delay Mode 0: Normal sending 1: Delay sending Set the bit to "1" to make the data that should be sent with a delay of half-cycle for SPI_CLK in dual IO mode of SPI mode0. Cannot be written when XCH=1.
13	R/W	0x0	SDM Master Sample Data Mode 0: Delay sample mode 1: Normal sample mode In normal sample mode, the SPI master samples the data at the correct edge for each SPI mode; In delay sample mode, the SPI master samples data at the edge that is half cycle delayed by the correct edge defined in respective SPI mode. Cannot be written when XCH=1.
12	R/W	0x0	FBS First Transmit Bit Select 0: MSB first 1: LSB first Cannot be written when XCH=1.
11	R/W	0x0	SDC Master Sample Data Control Set this bit to '1' to make the internal read sample point with a delay of half-cycle for SPI_CLK. It is used in high speed read operation to reduce the error caused by the time delay of SPI_CLK between master and slave. 0: Normal operation, do not delay the internal read sample point 1: Delay the internal read sample point Cannot be written when XCH=1.
10	R/W	0x0	RPSM Rapids Mode Select Select rapid mode for high speed write. 0: Normal write mode 1: Rapid write mode Cannot be written when XCH=1.

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Offset: 0x0008			Register Name: SPI_TCR
Bit	**Read/Write**	**Default/Hex**	**Description**
9	R/W	0x0	DDB Dummy Burst Type 0: The bit value of dummy SPI burst is zero 1: The bit value of dummy SPI burst is one Cannot be written when XCH=1.
8	R/W	0x0	DHB Discard Hash Burst In master mode, it controls whether discarding unused SPI bursts 0: Receiving all SPI bursts in the BC period 1: Discard unused SPI bursts, only fetching the SPI bursts during the dummy burst period. The burst number is specified by TC. Cannot be written when XCH=1.
7	R/W	0x1	SS_LEVEL When control SS signal manually (SS_OWNER (SPI_TCR[6])==1), set this bit to '1' or '0' to control the level of SS signal. 0: Set SS to low 1: Set SS to high Cannot be written when XCH=1.
6	R/W	0x0	SS_OWNER SS Output Owner Select Usually, the controller sends the SS signal automatically with data together. When this bit is set to 1, the software must manually write SS_LEVEL (SPI_TCR[7]) to 1 or 0 to control the level of the SS signal. 0: SPI controller 1: Software Cannot be written when XCH=1.
5:4	R/W	0x0	SS_SEL SPI Chip Select Select one of four external SPI Master/Slave Devices 00: SPI_SS0 will be asserted 01: SPI_SS1 will be asserted 10: SPI_SS2 will be asserted 11: SPI_SS3 will be asserted Cannot be written when XCH=1.

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Offset: 0x0008			Register Name: SPI_TCR
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W	0x0	SSCTL In master mode, this bit selects the output waveform for the SPI_SSx signal. Only valid when SS_OWNER (SPI_TCR[6])= 0. 0: SPI_SSx remains asserted between SPI bursts 1: Negate SPI_SSx between SPI bursts Cannot be written when XCH=1.
2	R/W	0x1	SPOL SPI Chip Select Signal Polarity Control 0: Active high polarity (0 = Idle) 1: Active low polarity (1 = Idle) Cannot be written when XCH=1.
1	R/W	0x1	CPOL SPI Clock Polarity Control 0: Active high polarity (0 = Idle) 1: Active low polarity (1 = Idle) Cannot be written when XCH=1.
0	R/W	0x1	CPHA SPI Clock/Data Phase Control 0: Phase 0 (Leading edge for sample data) 1: Phase 1 (Leading edge for setup data) Cannot be written when XCH=1.

10.3.6.3 0x0010 SPI Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: SPI_IER
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	/	/	/
13	R/W	0x0	SS_INT_EN SSI Interrupt Enable Chip select signal (SSx) from the valid state to the invalid state 0: Disable 1: Enable

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Offset: 0x0010			Register Name: SPI_IER
Bit	**Read/Write**	**Default/Hex**	**Description**
12	R/W	0x0	TC_INT_EN Transfer Completed Interrupt Enable 0: Disable 1: Enable
11	R/W	0x0	TF_UDR_INT_EN TXFIFO Underrun Interrupt Enable 0: Disable 1: Enable
10	R/W	0x0	TF_OVF_INT_EN TX FIFO Overflow Interrupt Enable 0: Disable 1: Enable
9	R/W	0x0	RF_UDR_INT_EN RXFIFO Underrun Interrupt Enable 0: Disable 1: Enable
8	R/W	0x0	RF_OVF_INT_EN RX FIFO Overflow Interrupt Enable 0: Disable 1: Enable
7	/	/	/
6	R/W	0x0	TF_FUL_INT_EN TX FIFO Full Interrupt Enable 0: Disable 1: Enable
5	R/W	0x0	TX_EMP_INT_EN TX FIFO Empty Interrupt Enable 0: Disable 1: Enable
4	R/W	0x0	TX_ERQ_INT_EN TX FIFO Empty Request Interrupt Enable 0: Disable 1: Enable
3	/	/	/

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Offset: 0x0010			Register Name: SPI_IER
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	RF_FUL_INT_EN RX FIFO Full Interrupt Enable 0: Disable 1: Enable
1	R/W	0x0	RX_EMP_INT_EN RX FIFO Empty Interrupt Enable 0: Disable 1: Enable
0	R/W	0x0	RF_RDY_INT_EN RX FIFO Ready Request Interrupt Enable 0: Disable 1: Enable

10.3.6.4 0x0014 SPI Interrupt Status Register (Default Value: 0x0000_0032)

Offset: 0x0014			Register Name: SPI_ISR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	/	/	/
13	R/W1C	0x0	SSI SS Invalid Interrupt When SSI is 1, it indicates that SPI_SS has changed from valid state to invalid state. Writing 1 to this bit clears it.
12	R/W1C	0x0	TC Transfer Completed In master mode, it indicates that all bursts specified by SPI_MBC have been exchanged. In other conditions, when setting, this bit indicates that all the data in TXFIFO has been loaded in the Shift register, and the Shift register has shifted out all the bits. Writing 1 to this bit clears it. 0: Busy 1: Transfer completed

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Offset: 0x0014			Register Name: SPI_ISR
Bit	**Read/Write**	**Default/Hex**	**Description**
11	R/W1C	0x0	TF_UDF TXFIFO Underrun This bit is set when the TXFIFO is underrun. Writing 1 to this bit clears it. 0: TXFIFO is not underrun 1: TXFIFO is underrun
10	R/W1C	0x0	TF_OVF TXFIFO Overflow This bit is set when the TXFIFO is overflowed. Writing 1 to this bit clears it. 0: TXFIFO is not overflowed 1: TXFIFO is overflowed
9	R/W1C	0x0	RX_UDF RXFIFO Underrun When set, this bit indicates that RXFIFO is underrun. Writing 1 to this bit clears it. 0: RXFIFO is not underrun 1: RXFIFO is underrun
8	R/W1C	0x0	RX_OVF RXFIFO Overflow When set, this bit indicates that RXFIFO has overflowed. Writing 1 to this bit clears it. 0: RXFIFO is not overflowed 1: RXFIFO is overflowed
7	/	/	/
6	R/W1C	0x0	TX_FULL TXFIFO Full This bit is set when the TXFIFO is full. Writing 1 to this bit clears it. 0: TXFIFO is not Full 1: TXFIFO is Full
5	R/W1C	0x1	TX_EMP TXFIFO Empty This bit is set when the TXFIFO is empty. Writing 1 to this bit clears it. 0: TXFIFO contains one or more words 1: TXFIFO is empty

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Offset: 0x0014			Register Name: SPI_ISR
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W1C	0x1	TX_READY TXFIFO Ready 0: TX_WL > TX_TRIG_LEVEL 1: TX_WL <= TX_TRIG_LEVEL This bit will be immediately set to 1 if TX_WL <= TX_TRIG_LEVEL. Writing "1" to this bit clears it. The TX_WL is the water level of TXFIFO.
3	/	/	/
2	R/W1C	0x0	RX_FULL RXFIFO Full This bit is set when the RXFIFO is full. Writing 1 to this bit clears it. 0: Not Full 1: Full
1	R/W1C	0x1	RX_EMP RXFIFO Empty This bit is set when the RXFIFO is empty. Writing 1 to this bit clears it. 0: Not empty 1: empty
0	R/W1C	0x0	RX_RDY RXFIFO Ready 0: RX_WL < RX_TRIG_LEVEL 1: RX_WL >= RX_TRIG_LEVEL This bit is will be immediately set to 1 if RX_WL >= RX_TRIG_LEVEL. Writing "1" to this bit clears it. The RX_WL is the water level of RXFIFO.

10.3.6.5 0x0018 SPI FIFO Control Register (Default Value: 0x0040_0001)

Offset: 0x0018			Register Name: SPI_FCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/WAC	0x0	TX_FIFO_RST TX FIFO Reset Writing '1' to this bit will reset the control portion of the TX FIFO and auto clear to '0' when completing reset operation, writing to '0' has no effect.

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Offset: 0x0018			Register Name: SPI_FCR
Bit	**Read/Write**	**Default/Hex**	**Description**
30	R/W	0x0	TF_TEST_ENB TX Test Mode Enable 0: Disable 1: Enable In normal mode, the TXFIFO can only be read by the SPI controller, writing '1' to this bit will switch the read and write function of the TXFIFO to AHB bus. This bit is used to test the TXFIFO, do not set in normal operation, and do not set RF_TEST and TF_TEST at the same time.
29:25	/	/	/
24	R/W	0x0	TF_DRQ_EN TXFIFO DMA Request Enable 0: Disable 1: Enable
23:16	R/W	0x40	TX_TRIG_LEVEL TXFIFO Empty Request Trigger Level
15	R/WAC	0x0	RF_RST RXFIFO Reset Writing '1' to this bit will reset the control portion of the receiver FIFO, and auto clear to '0' when completing reset operation, writing '0' to this bit has no effect.
14	R/W	0x0	RF_TEST RX Test Mode Enable 0: Disable 1: Enable In normal mode, the RXFIFO can only be written by the SPI controller, writing '1' to this bit will switch the read and write function of RXFIFO to AHB bus. This bit is used to test the RXFIFO, do not set in normal operation, and do not set RF_TEST and TF_TEST at the same time.
13:9	/	/	/
8	R/W	0x0	RF_DRQ_EN RX FIFO DMA Request Enable 0: Disable 1: Enable
7:0	R/W	0x1	RX_TRIG_LEVEL RX FIFO Ready Request Trigger Level

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10.3.6.6 0x001C SPI FIFO Status Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: SPI_FSR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R	0x0	TB_WR TX FIFO Write Buffer Write Enable
30:28	R	0x0	TB_CNT TX FIFO Write Buffer Counter These bits indicate the number of words in TX FIFO Write Buffer
27:24	/	/	/
23:16	R	0x0	TF_CNT TX FIFO Counter These bits indicate the number of words in TX FIFO 0: 0 byte in TX FIFO 1: 1 byte in TX FIFO … 64: 64 bytes in TX FIFO other: Reserved
15	R	0x0	RB_WR RX FIFO Read Buffer Write Enable
14:12	R	0x0	RB_CNT RX FIFO Read Buffer Counter These bits indicate the number of words in RX FIFO Read Buffer
11:8	/	/	/
7:0	R	0x0	RF_CNT RX FIFO Counter These bits indicate the number of words in RX FIFO 0: 0 byte in RX FIFO 1: 1 byte in RX FIFO … 64: 64 bytes in RX FIFO other: Reserved

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10.3.6.7 0x0020 SPI Wait Clock Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: SPI_WCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:20	/	/	/
19:16	R/W	0x0	SWC Dual mode direction switch wait clock counter (for master mode only). These bits control the number of wait states to be inserted before starting dual data transfer in dual SPI mode. The SPI module counts SPI_SCLK by SWC for delaying the next word data transfer. 0: No wait states inserted n: n SPI_SCLK wait states inserted Cannot be written when XCH=1.
15:0	R/W	0x0	WCC Wait Clock Counter (In master mode) These bits control the number of wait states to be inserted in data transfers. The SPI module counts SPI_SCLK by WCC for delaying the next word data transfer. 0: No wait states inserted n: n SPI_SCLK wait states inserted Cannot be written when XCH=1.

10.3.6.8 0x0028 SPI Sample Delay Control Register (Default Value: 0x0000_2000)

Offset: 0x0028			Register Name: SPI_SAMP_DL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15	R/W	0x0	SAMP_DL_CAL_START Sample Delay Calibration Start When set, the sample delay chain calibration is started. Cannot be written when XCH=1.
14	R	0x0	SAMP_DL_CAL_DONE Sample Delay Calibration Done When set, it means that sample delay chain calibration is done and the result of calibration is shown in SAMP_DL. Cannot be written when XCH=1.

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Offset: 0x0028			Register Name: SPI_SAMP_DL
Bit	**Read/Write**	**Default/Hex**	**Description**
13:8	R	0x20	SAMP_DL Sample Delay It indicates the number of delay cells corresponding to the current card clock. The delay time generated by these delay cells is equal to the cycle of the card clock nearly. Generally, it is necessary to do drive delay calibration when the card clock is changed. This bit is valid only when SAMP_DL_CAL_DONE is set. Cannot be written when XCH=1.
7	R/W	0x0	SAMP_DL_SW_EN Sample Delay Software Enable When set, it indicates that enable sample delay specified at SAMP_DL_SW. Cannot be written when XCH=1.
6	/	/	/
5:0	R/W	0x0	SAMP_DL_SW Sample Delay Software The relative delay between the clock line and command line, data lines. It can be determined according to the value of SAMP_DL, the cycle of the card clock, and the input timing requirement of the device. Cannot be written when XCH=1.

10.3.6.9 0x0030 SPI Master Burst Counter Register (Default Value: 0x0000_0000)

Offset: 0x0030			Register Name: SPI_MBC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/

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Offset: 0x0030			Register Name: SPI_MBC
Bit	**Read/Write**	**Default/Hex**	**Description**
23:0	R/W	0x0	MBC Master Burst Counter In master mode, this field specifies the total burst number. The total transfer data include the TXD, RXD, and dummy burst. 0: 0 burst 1: 1 burst … N: N bursts Cannot be written when XCH=1.

10.3.6.10 0x0034 SPI Master Transmit Counter Register (Default Value: 0x0000_0000)

Offset: 0x0034			Register Name: SPI_MTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:0	R/W	0x0	MWTC Master Write Transmit Counter In master mode, this field specifies the burst number that should be sent to TXFIFO before automatically sending dummy bursts. For saving bus bandwidth, the dummy bursts (all zero bits or all one bits) are sent by SPI Controller automatically. 0: 0 burst 1: 1 burst … N: N bursts Cannot be written when XCH=1.

10.3.6.11 0x0038 SPI Master Burst Control Counter Register (Default Value: 0x0000_0000)

Offset: 0x0038			Register Name: SPI_BCC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/

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Offset: 0x0038			Register Name: SPI_BCC
Bit	**Read/Write**	**Default/Hex**	**Description**
29	R/W	0x0	Quad_EN Quad Mode Enable The quad mode includes Quad-Input and Quad-Output. 0: Quad mode disable 1: Quad mode enable Cannot be written when XCH=1.
28	R/W	0x0	DRM Master Dual Mode RX Enable It is only valid when Quad_Mode_EN=0. 0: RX uses the single-bit mode 1: RX uses the dual-bit mode Cannot be written when XCH=1.
27:24	R/W	0x0	DBC Master Dummy Burst Counter In master mode, this field specifies the burst number that should be sent before receiving in dual SPI mode. The data does not care by the device. 0: 0 burst 1: 1 burst … N: N bursts Cannot be written when XCH=1.
23:0	R/W	0x0	STC Master Single Mode Transmit Counter In master mode, this field specifies the burst number that should be sent in the single mode before automatically sending dummy bursts. This is the first transmit counter in all bursts. 0: 0 burst 1: 1 burst … N: N bursts Cannot be written when XCH=1.

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10.3.6.12 0x0040 SPI Bit-Aligned Transfer Configure Register (Default Value: 0x0000_00A0)

Offset: 0x0040			Register Name: SPI_BATC
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/WAC	0x0	TCE Transfer Control Enable In master mode, it is used to start to transfer the serial bit frame, it is only valid when Work Mode Select==0x10/0x11. 0: Idle 1: Initiates transfer Writing "1" to this bit will start to transfer serial bit frame (the value comes from the SPI TX Bit Register or SPI RX Bit Register), and will auto-clear after the bursts transfer completely. Writing '0' to this bit has no effect.
30	R/W	0x0	MSMS Master Sample Standard 0: Delay Sample Mode 1: Standard Sample Mode In Standard Sample Mode, the SPI master samples the data at the standard rising edge of SCLK for each SPI mode; In Delay Sample Mode, the SPI master samples data at the edge that is half cycle delayed by the standard rising edge of SCLK defined in respective SPI mode.
29:26	/	/	/
25	R/W1C	0x0	TBC Transfer Bits Completed When set, this bit indicates that the last bit of the serial data frame in SPI TX Bit Register (or SPI RX Bit Register) has been transferred completely. Writing 1 to this bit clears it. 0: Busy 1: Transfer Completed It is only valid when Work Mode Select==0x10/0x11.
24	R/W	0x0	TBC_INT_EN Transfer Bits Completed Interrupt Enable 0: Disable 1: Enable It is only valid when Work Mode Select==0x10/0x11.
23:22	/	/	/

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Offset: 0x0040			Register Name: SPI_BATC
Bit	**Read/Write**	**Default/Hex**	**Description**
21:16	R/W	0x00	Configure the length of serial data frame (burst) of RX 000000: 0 bit 000001: 1 bit … 100000: 32 bits Other values: reserved It is only valid when Work Mode Select==0x10/0x11, and cannot be written when TCE (bit31) is 1.
15:14	/	/	/
13:8	R/W	0x00	TX_FRM_LEN Configure the length of serial data frame (burst) of TX 000000: 0 bit 000001: 1 bit … 100000: 32 bits Other values: reserved It is only valid when Work Mode Select==0x10/0x11, and cannot be written when TCE (bit31) is 1.
7	R/W	0x1	SS_LEVEL When control the SS signal manually, set this bit to ‘1’ or ‘0’ to control the level of SS signal. 0: Set SS to low 1: Set SS to high It is only valid when Work Mode Select==0x10/0x11, and only work in Mode0, cannot be written when TCE (bit31) is 1.
6	R/W	0x0	SS_OWNER SS Output Owner Select Usually, the controller sends the SS signal automatically with data together. When this bit is set to 1, the software must manually write SS_LEVEL to 1 or 0 to control the level of the SS signal. 0: SPI controller 1: Software It is only valid when Work Mode Select==0x10/0x11, and only work in Mode0, cannot be written when TCE (bit31) is 1.

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Offset: 0x0040			Register Name: SPI_BATC
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R/W	0x1	SPOL SPI Chip Select Signal Polarity Control 0: Active high polarity (0 = Idle) 1: Active low polarity (1 = Idle) It is only valid when Work Mode Select==0x10/0x11, and only work in Mode0, cannot be written when TCE (bit31) is 1.
4	/	/	/
3:2	R/W	0x0	SS_SEL SPI Chip Select Select one of four external SPI Master/Slave Devices 00: SPI_SS0 will be asserted 01: SPI_SS1 will be asserted 10: SPI_SS2 will be asserted 11: SPI_SS3 will be asserted It is only valid when Work Mode Select= =0x10/0x11, and only work in Mode0, cannot be written when TCE (bit31) is 1.
1:0	R/W	0x0	Work Mode Select 00: Data frame is byte aligned in standard SPI, dual-output/dual input SPI, dual IO SPI, and quad-output/quad-input SPI 01: Reserved 10: Data frame is bit aligned in 3-wire SPI 11: Data frame is bit aligned in standard SPI

10.3.6.13 0x0044 SPI Bit-Aligned CLOCK Configuration Register (Default Value: 0x0000_0000)

Offset: 0x0044			Register Name: SPI_BA_CCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x0	CDR_N Clock Divide Rate (Master Mode Only) The SPI_SCLK is determined according to the following equation: SPI_CLK = Source_CLK / (2*(CDR_N + 1)). This register is only valid when Work Mode Select==0x10/0x11.

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10.3.6.14 0x0048 SPI TX Bit Register (Default Value: 0x0000_0000)

Offset: 0x0048			Register Name: SPI_TBR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	VTB The Value of the Transmit Bits This register is used to store the value of the transmitted serial data frame. In the process of transmission, the LSB is transmitted first. This register is only valid when Work Mode Select==0x10/0x11.

10.3.6.15 0x004C SPI RX Bit Register (Default Value: 0x0000_0000)

Offset: 0x004C			Register Name: SPI_RBR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	VRB The Value of the Receive Bits This register is used to store the value of the received serial data frame. In the process of transmission, the LSB is transmitted first. This register is only valid when Work Mode Select==0x10/0x11.

10.3.6.16 0x0088 SPI Normal DMA Mode Control Register (Default Value: 0x0000_00E5)

Offset: 0x0088			Register Name: SPI_NDMA_MODE_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:6	R/W	0x11	SPI_ACT_M SPI NDMA Active Mode 00: dma_active is low 01: dma_active is high 10: dma_active is controlled by dma_request (DRQ) 11: dma_active is controlled by controller
5	R/W	0x1	SPI_ACK_M SPI NDMA Acknowledge Mode 0: active fall do not care ack 1: active fall must after detect ack is high

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Offset: 0x0088			Register Name: SPI_NDMA_MODE_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
4:0	R/W	0x05	SPI_DMA_WAIT The counts of hold cycles from DMA last signal high to dma_active high

10.3.6.17 0x0200 SPI TX Data Register (Default Value: 0x0000_0000)

Offset: 0x0200			Register Name: SPI_TXD
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TDATA Transmit Data This register can be accessed in the byte, half-word, or word unit by AHB. In the byte accessing method, if there are rooms in TXFIFO, one burst data is written to TXFIFO and the depth is increased by 1. In the half-word accessing method, two SPI burst data are written and the TXFIFO depth is increased by 2. In the word accessing method, four SPI burst data are written and the TXFIFO depth is increased by 4. **Note: This address is writable-only if TF_TEST is '0', and if TF_TEST is set to '1', this address is readable and writable to test the TXFIFO through the AHB bus.**

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10.3.6.18 0x0300 SPI RX Data Register (Default Value: 0x0000_0000)

Offset: 0x0300			Register Name: SPI_RXD
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	RDATA Receive Data This register can be accessed in the byte, half-word, or word unit by AHB. In the byte accessing method, if there are data in RXFIFO, the top word is returned and the RXFIFO depth is decreased by 1. In the half-word accessing method, two SPI bursts are returned and the RXFIFO depth is decreased by 2. In the word accessing method, the four SPI bursts are returned and the RXFIFO depth is decreased by 4. **Note: This address is readable-only if RF_TEST is '0', and if RF_TEST is set to '1', this address is readable and writable to test the RXFIFO through the AHB bus.**

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10.4 SPI_DBI

10.4.1 Overview

The R528 provides a 3/4 line SPI display bus interface (SPI_DBI) for video data transmission. It supports DBI mode or SPI mode. The DBI mode is compatible with multiple video data formats at the same time. The SPI mode is used for low-cost display schemes.

The SPI mode has the following features:

- Full-duplex synchronous serial interface
- Master/slave configurable
- 8-bit wide by 64-entry FIFO for both transmit and receive data
- Polarity and phase of the Chip Select (SPI_SS) and SPI Clock (SPI_SCLK) are configurable
- Supports interrupts and DMA
- Supports mode0, mode1, mode2, and mode3
- Supports 3-wire/4-wire SPI
- Supports programmable serial data frame length: 1 bit to 32 bits
- Supports standard SPI, dual-output/dual-input SPI, dual I/O SPI, quad-output/quad-input SPI
- Supports maximum IO rate of the mass production: 100 MHz

The DBI mode has the following features:

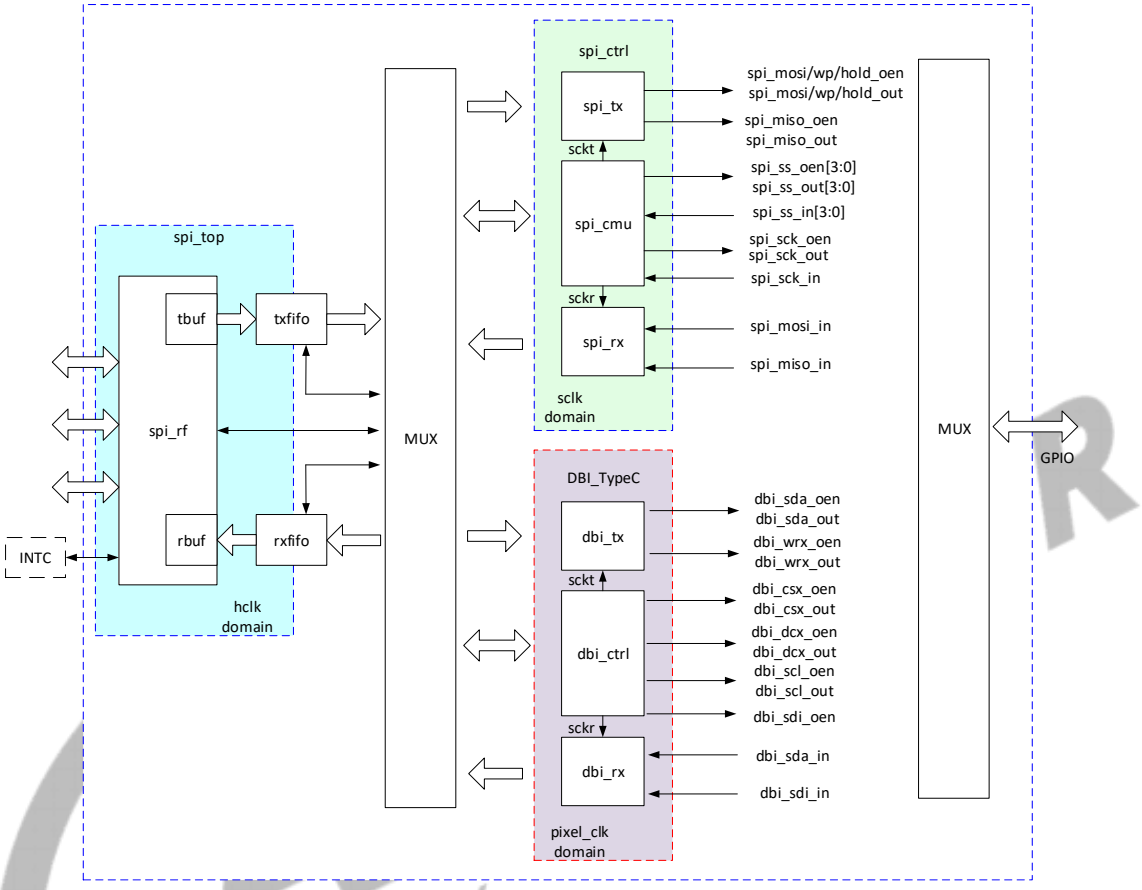
- Supports DBI Type C 3 Line/4 Line Interface Mode
- Supports 2 Data Lane Interface Mode
- Supports data source from CPU or DMA
- Supports RGB111/444/565/666/888 video format
- Maximum resolution of RGB666 240 x 320@30Hz with single data lane
- Maximum resolution of RGB888 240 x 320@60Hz or 320 x 480@30Hz with dual data lane
- Supports Tearing effect
- Supports software flexible control video frame rate

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10.4.2 Block Diagram

Figure 10-30 shows a block diagram of the SPI_DBI.

Figure 10-30 SPI_DBI Block Diagram



SPI_DBI contains the following sub-blocks:

Table 10-12 SPI_DBI Sub-blocks

Sub-block	Description
spi_rf	Responsible for implementing the internal register, interrupt, and DMA Request.
spi_tbuf	The data length transmitted from AHB to TXFIFO is converted into 8 bits, then the data is written into the RXFIFO.
spi_rbuf	The block is used to convert the RXFIFO data into the reading data length of AHB.
txfifo, rxfifo	The data transmitted from the SPI to the external serial device is written into the TXFIFO; the data received from the external serial device into SPI is pushed into the RXFIFO.
spi_cmu	Responsible for implementing SPI bus clock, chip select, internal sample, and the generation of transfer clock.

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Sub-block	Description
spi_tx	Responsible for implementing SPI data transfer, the interface of the internal TXFIFO, and status register.
spi_rx	Responsible for implementing SPI data receive, the interface of the internal RXFIFO, and status register.
dbi_ctrl	Responsible for implementing DBI bus clock, chip select, data command select, RGB format reshape.
dbi_tx	Responsible for implementing DBI data transfer, the interface of the internal TXFIFO, and status register.
dbi_rx	Responsible for implementing DBI data receive, the interface of the internal RXFIFO, and status register.

10.4.3 Functional Description

10.4.3.1 External Signals

The following table describes the external signals of SPI_DBI. When using SPI_DBI, the corresponding PADs are selected as SPI_DBI function via section 9.7 "GPIO".

Table 10-13 SPI_DBI External Signals

External Signal		Description	Type
DBI Mode	DBI-CSX	Chip select signal, low active	I/O
	DBI-SCLK	Serial clock signal	I/O
	DBI-SDO	Data output signal	I/O
	DBI-SDI	Data input signal, the data is sampled on the rising edge and the falling edge	I/O
	DBI-TE	Tearing effect input, it is used to capture the external TE signal edge.	I/O
	DBI-DCX	DCX pin is the select output signal of data and command. DCX = 0: register command; DCX = 1: data or parameter.	I/O
	DBI-WRX	When DBI operates in dual data lane format, the RGB666 format 2 can use WRX to transfer data	I/O
SPI Mode	SPI1-CS	SPI1 chip select signal, low active When the device is not selected, data will not be accepted via the SI pin, and the SO pin will stop transmission.	I/O

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External Signal		Description	Type
	SPI1-CLK	SPI1 clock signal This pin is used to provide a clock to the device and is used to control the flow of data to and from the device.	I/O
	SPI1-MOSI	SPI1 master data out, slave data in	I/O
	SPI1-MISO	SPI1 master data in, slave data out	I/O
	SPI1-WP	Write protection and active low It also can be used for serial data input and output for SPI Quad Input or Quad Output mode.	I/O
	SPI1-HOLD	When the device is selected and a serial sequence is underway, the HOLD pin is can be used to temporarily pause the serial communication with the master device without deselecting or resetting the device serial sequence. While the HOLD pin is asserted, the SO pin is at high impedance, and all transitions on the SCK pin and data on the SI pin are ignored. It also can be used for serial data input and output for SPI Quad Input or Quad Output mode.	I/O

10.4.3.2 Clock Sources

The SPI_DBI controller gets 5 different clock sources, users can select one of them to make SPI_DBI clock source. The following table describes the clock sources for SPI_DBI. For more details on the clock setting, configuration, and gating information, see section 3.3 "CCU".

Table 10-14 SPI_DBI Clock Sources

Clock Sources	Description
HOSC	24 MHz Crystal
PLL_PERI(1X)	Peripheral Clock, the default value is 600 MHz
PLL_PERI(2X)	Peripheral Clock, the default value is 1200 MHz
PLL_AUDIO0(DIV2)	Audio Clock, the default value is 1536 MHz
PLL_AUDIO0(DIV5)	Audio Clock, the default value is 614.4 MHz

10.4.3.3 Typical Application

Figure 10-31 shows the application block diagram when the SPI master device is connected to a slave device.

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Figure 10-31 SPI Application Block Diagram

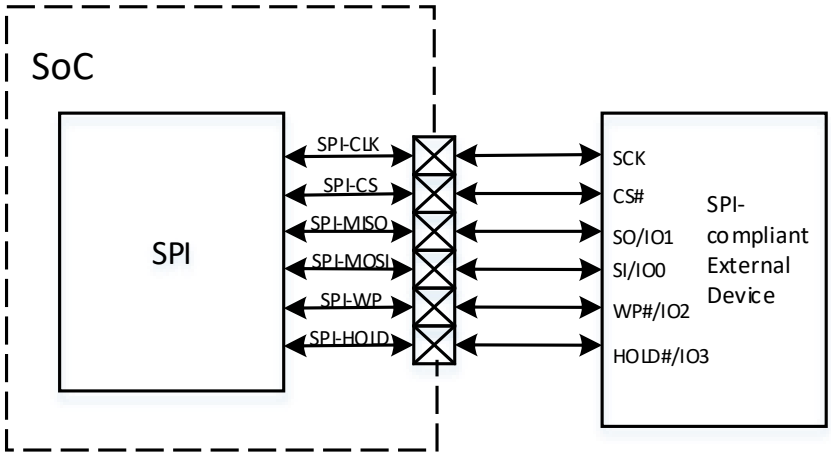
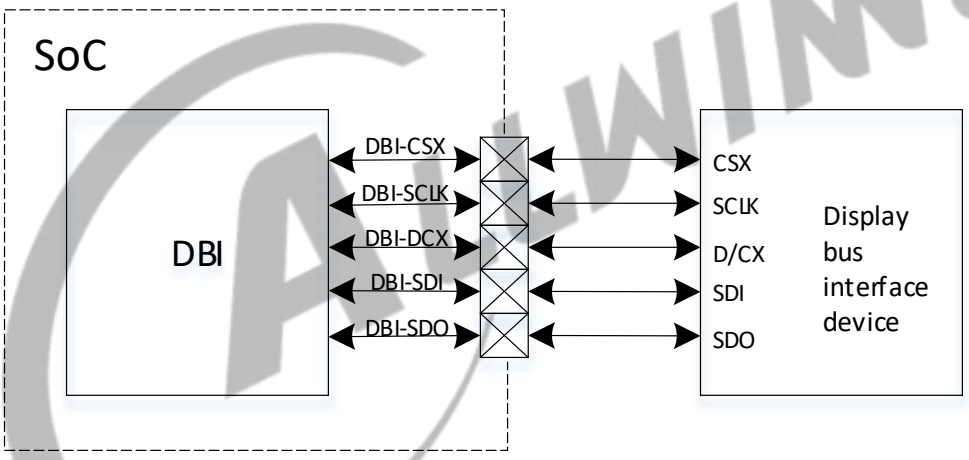


Figure 10-32 shows the application block diagram when the DBI master device is connected to a display bus interface device.

Figure 10-32 DBI Application Block Diagram



10.4.3.4 SPI Transmission Format

The SPI supports 4 different formats for data transmission. The software can select one of the four modes in which the SPI works by setting the bit1 (Polarity) and bit0 (Phase) of SPI_TCR. The SPI controller master uses the SPI_SCLK signal to transfer data in and out of the shift register. Data is clocked using any one of four programmable clock phase and polarity combinations.

The CPOL (SPI_TCR[1]) defines the polarity of the clock signal (SPI_SCLK). The SPI_SCLK is a high level when CPOL is '1' and it is a low level when CPOL is '0'. The CPHA (SPI_TCR[0]) decides whether the leading edge of SPI_SCLK is used to setup or sample data. The leading edge is used to setup data when CPHA is '1', and sample data when CPHA is '0'. The following table lists the four modes.

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Table 10-15 SPI Transmit Format

SPI Mode	Polarity (CPOL)	Phase (CPHA)	Leading Edge	Trailing Edge
mode0	0	0	Sample on the rising edge	Setup on the falling edge
mode1	0	1	Setup on the rising edge	Sample on the falling edge
mode2	1	0	Sample on the falling edge	Setup on the rising edge
mode3	1	1	Setup on the falling edge	Sample on the rising edge

Figure 10-33 and Figure 10-34 describe four waveforms for SPI_SCLK.

Figure 10-33 SPI Phase 0 Timing Diagram

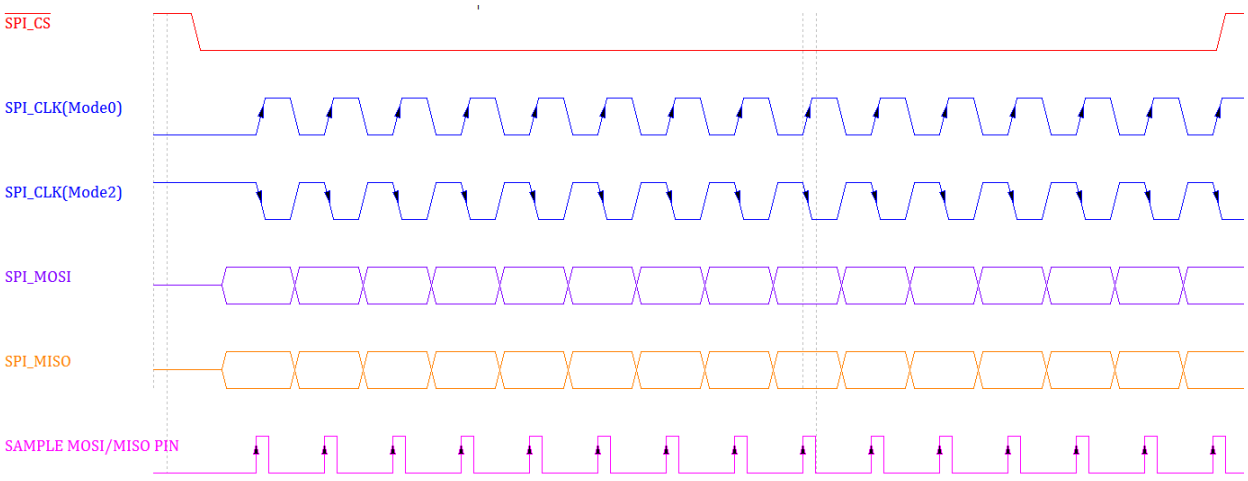
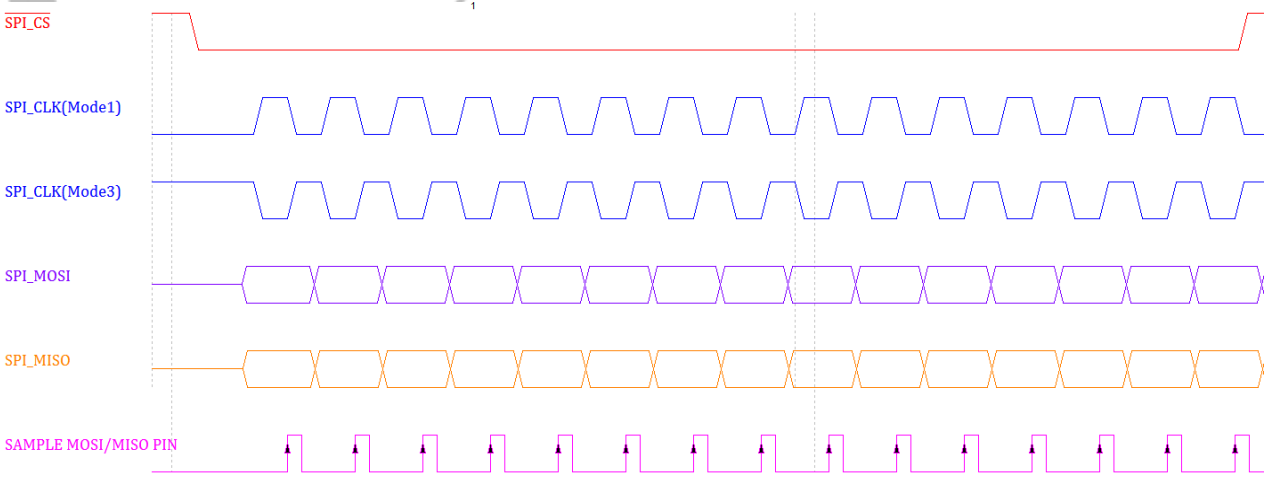


Figure 10-34 SPI Phase 1 Timing Diagram



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10.4.3.5 SPI Master and Slave Mode

The SPI controller can be configured to a master or slave device. The master mode is selected by setting the MODE bit (SPI_GCR[1]); the slave mode is selected by clearing the MODE bit.

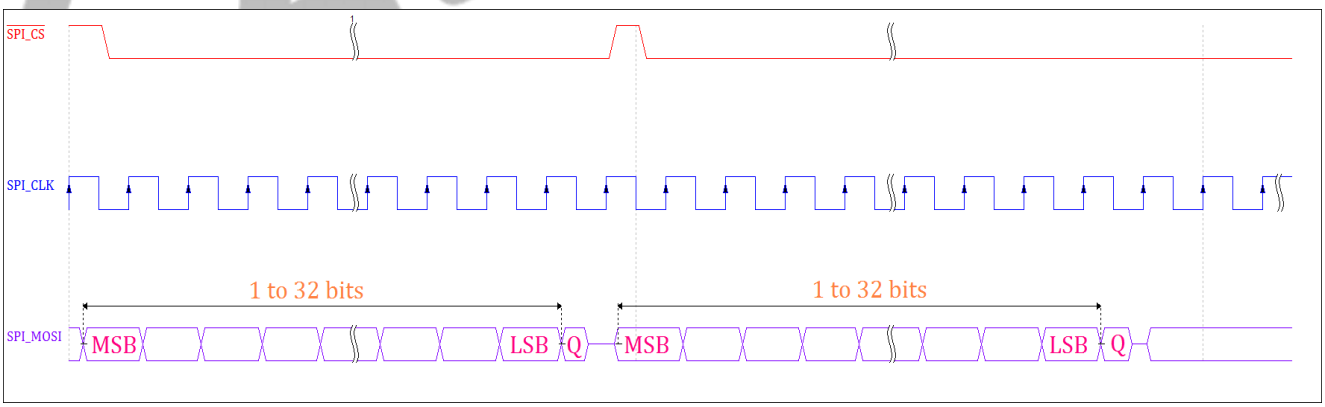
In master mode, the SPI_CLK is generated and transmitted to the external device, and the data from the TX FIFO is transmitted on the MOSI pin, the data from the slave is received on the MISO pin and sent to RX FIFO. The Chip Select (SPI_SS) is an active low signal, and it must be set low before the data are transmitted or received. The SPI_SS can be selected the auto control mode or the software manual control mode. When using auto control, the SS_OWNER (SPI_TCR[6]) must be cleared (default value is 0); when using manual control, the SS_OWNER must be set. And the level of SPI_SS is controlled by SS_LEVEL (SPI_TCR[7]).

In slave mode, after the software selects the MODE bit (SPI_GCR[1]) to '0', it waits for master initiate a transaction. When the master asserts SPI_SS, and SPI_CLK is transmitted to the slave, the slave data is transmitted from TX FIFO on the MISO pin, and the data from the MOSI pin is received in RX FIFO.

10.4.3.6 SPI 3-Wire Mode

The SPI 3-wire mode is only valid when the SPI controller work in master mode, and is selected when the Work Mode Select bit (SPI_BATC[1:0]) is equal to 0x2. And in the 3-wire mode, the input data and the output data use the same single data line. The following figure describes the 3-wire mode.

Figure 10-35 SPI 3-Wire Mode

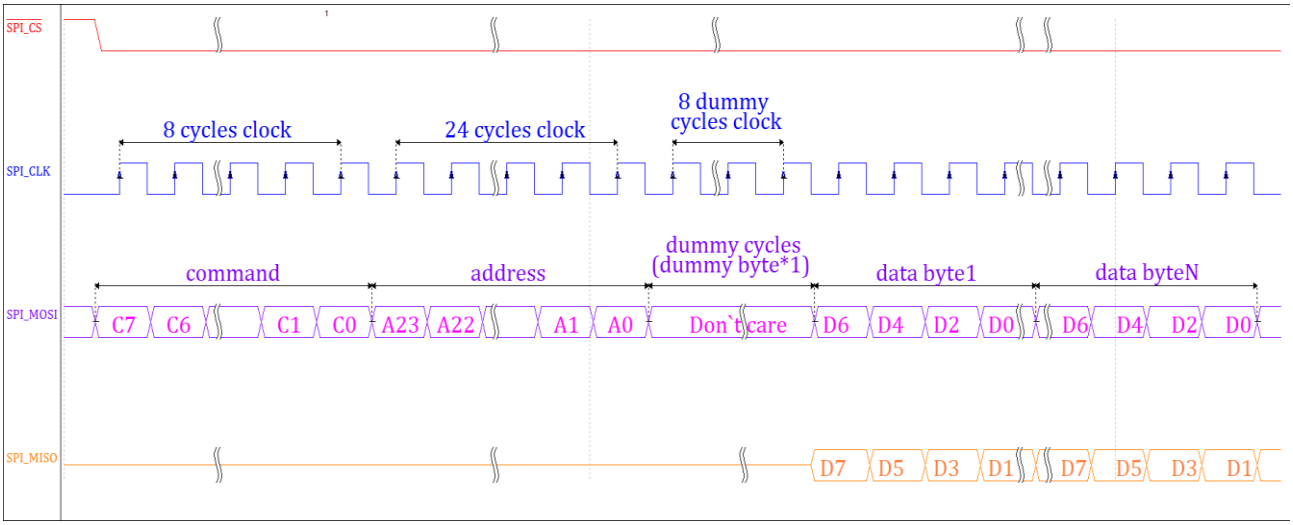


10.4.3.7 SPI Dual-Input/Dual-Output and Dual I/O Mode

The dual read mode (SPI x2) is selected when the DRM is set in SPI_BCC[28]. Using the dual mode allows data to be transferred to or from the device at double the rate of standard single mode SPI devices, the data can be read at fast speed using two data bits (MOSI and MISO) at a time. The following figure describes the dual-input/dual-output SPI (Figure 10-36) and the dual I/O SPI (Figure 10-37).

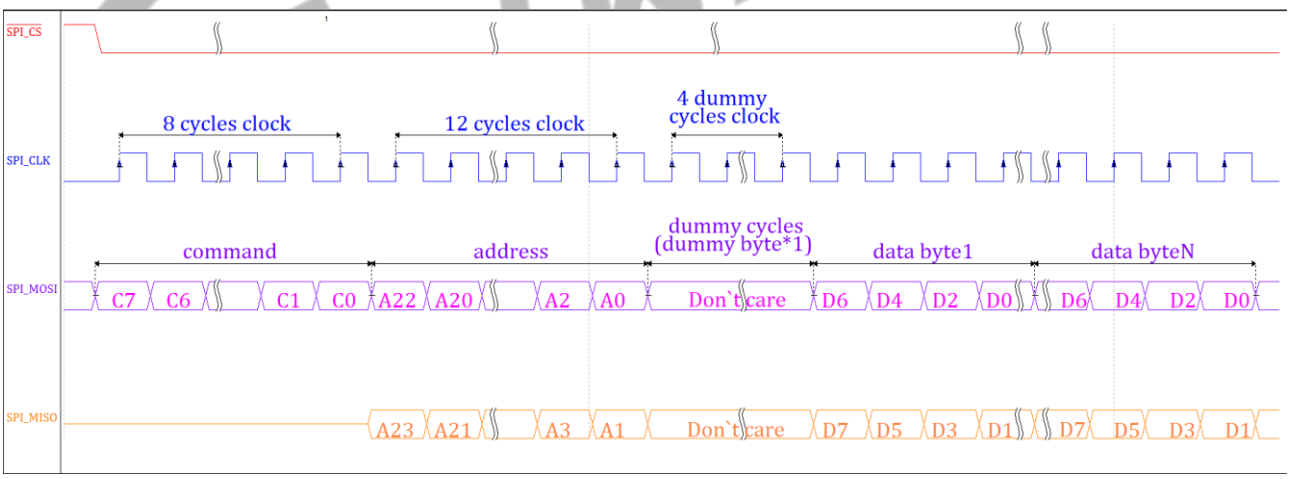
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Figure 10-36 SPI Dual-Input/Dual-Output Mode



In the dual-input/dual-output SPI mode, the command, address, and the dummy bytes output in a unit of a single bit in serial mode through the SPI_MOSI line, only the data bytes are output (write) and input (read) in a unit of dual bits through the SPI_MOSI and SPI_MISO.

Figure 10-37 SPI Dual I/O Mode



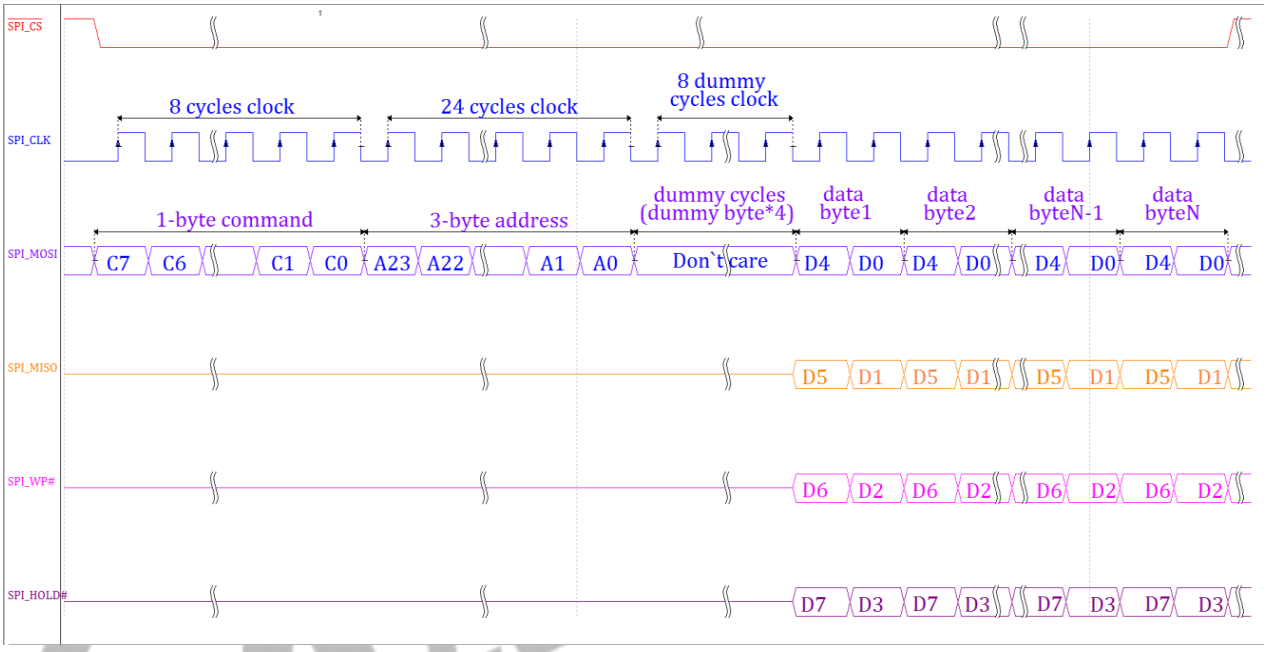
In the dual I/O SPI mode, only the command bytes output in a unit of a single bit in serial mode through the SPI_MOSI line. The address bytes and the dummy bytes output in a unit of dual bits through the SPI_MOSI and SPI_MISO. And the data bytes output (write) and input (read) in a unit of dual bits through the SPI_MOSI and SPI_MISO.

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10.4.3.8 SPI Quad-Input/Quad-Output Mode

The quad read mode (SPI x4) is selected when the Quad_EN is set in **SPI_BCC**[29]. Using the quad mode allows data to be transferred to or from the device at 4 times the rate of standard single mode SPI devices, the data can be read at fast speed using four data bits (MOSI, MISO, IO2 (WP#) and IO3 (HOLD#)) at the same time. The following figure describes the quad-input/quad-output SPI.

Figure 10-38 SPI Quad-Input/Quad-Output Mode



In the quad-input/quad-output SPI mode, the command, address, and the dummy bytes output in a unit of a single bit in serial mode through the SPI_MOSI line. Only the data bytes output (write) and input (read) in a unit of quad bits through the SPI_MOSI, SPI_MISO, SPI_WP#, and SPI_HOLD#.

10.4.3.9 Transmission/Reception Bursts in Master Mode

In SPI master mode, the transmission and reception bursts (byte in unit) are configured before the SPI transfers serial data between the processor and external device. The transmission bursts are written in MWTC (bit[23:0]) of the SPI Master Transmit Counter Register**.** The transmission bursts in single mode before automatically sending dummy bursts are written in STC (bit[23:0]) of the SPI Master Transmit Counter Register**.** For dummy data, the SPI controller can automatically send before receiving by writing DBC (bit[27:24]) in the SPI Master Transmit Counter Register. If users do not use the SPI controller to send dummy data automatically, then the dummy bursts are used as the transmission counters to write together in MWTC (bit[23:0]) of the SPI Master Transmit Counter Register**.** In master mode, the total burst numbers are written in MBC (bit[23:0]) of the SPI Master Transmit Counter Register**.** When all transmission and reception bursts are transferred, the SPI controller will send a completed interrupt, at the same time, the SPI controller will clear DBC, MWTC, and MBC.

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10.4.3.10 SPI Sample Mode and Run Clock Configuration

The SPI controller runs at 3 kHz–100 MHz at its interface to external SPI devices. The internal SPI clock should run at the same frequency as the outgoing clock in the master mode. The SPI clock is selected from different clock sources, the SPI must configure different work mode. There are three work modes: normal sample mode, delay half-cycle sample mode, delay one-cycle sample mode. Delay half-cycle sample mode is the default mode of the SPI controller. When the SPI runs at 40 MHz or below 40 MHz, the SPI can work at normal sample mode or delay half-cycle sample mode. When the SPI runs over 80 MHz, setting the SDC bit in the SPI Transfer Control Register to '1' makes the internal read sample point with a half-cycle delay of SPI_CLK, which is used in high speed read operation to reduce the error caused by the time delay of SPI_CLK between master and slave. Table 10-16 and Table 10-17 show the different configurations of the SPI sample mode.

Table 10-16 SPI Old Sample Mode and Run Clock

SPI Sample Mode	SDM(bit13)	SDC(bit11)	Run Clock
normal sample	1	0	<=24 MHz
delay half cycle sample	0	0	<=40 MHz
delay one cycle sample	0	1	>=80 MHz

CAUTION

The remaining spectrum is not recommended. Because when the output delay of SPI flash (refer to the datasheet of the manufactures for the specific delay time) is the same with the half-cycle time of SPI working clock, the variable edge of the output data for the device bumps into the clock sampling edge of the controller, so setting 1 cycle of sampling delay would cause stability problem.

Table 10-17 SPI New Sample Mode

SPI Sample Mode	SDM (bit13)	SDC (bit11)	SDC1 (bit15)
normal sample	1	0	0
delay half cycle sample	0	0	0
delay one cycle sample	0	1	0
delay 1.5 cycle sample	1	1	0
delay 2 cycle sample	1	0	1
delay 2.5 cycle sample	0	0	1
delay 3 cycle sample	0	1	1

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10.4.3.11 DBI 3-Line Interface Writing and Reading Timing

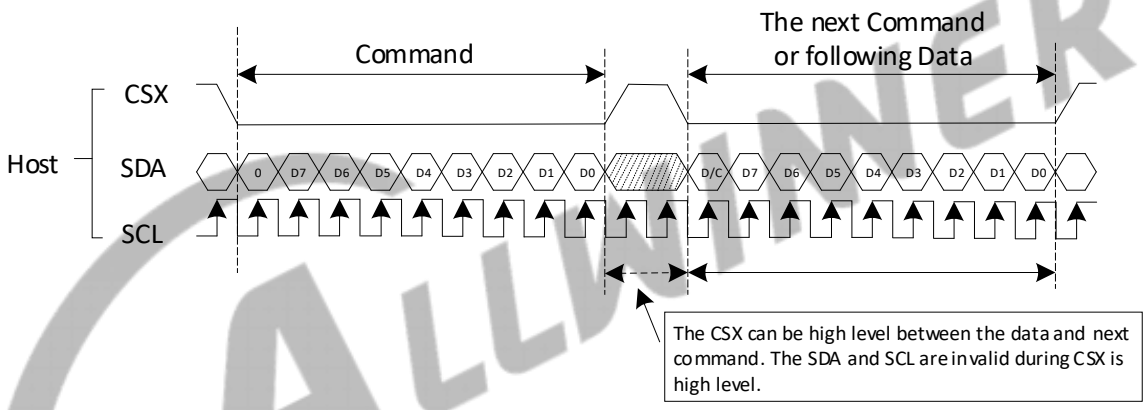
The 3-line DBI Interface I contains CSX, SDA, and SCL, where SDA shares this port for bidirectional port data input and output.

The 3-line DBI Interface II contains CSX, SDA, SCL, and SDI; Data input and output ports are independent of each other.

Since the 3-line display bus mode has no Data/Command data line indicating whether Data or Command is currently being transmitted, an extra bit is added to the data-stream before MSB to indicate whether Data or Command is currently being transmitted. (0: Command, 1: Data)

The following figure shows the writing operation format of 3-line DBI Interface I and Interface II.

Figure 10-39 DBI 3-Line Display Bus Serial Interface Writing Operation Format

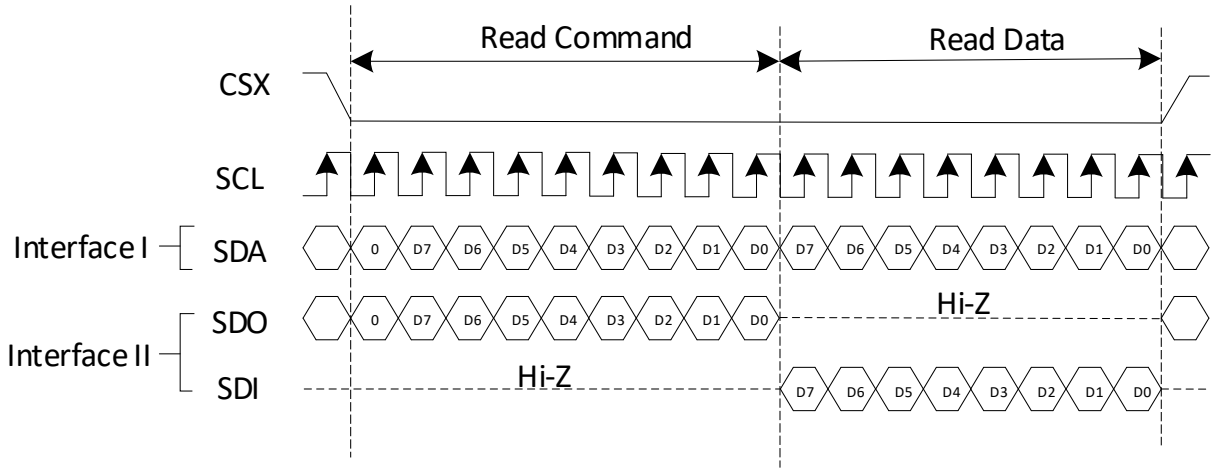


The 3-line DBI Interface I uses the SDA port as bidirectional data input and output port. There are only three cases of data reading volume, 8bits/24bits/32bits, and the first data sampled is high.

The following figure shows the 8 bits reading operation format of 3-line DBI Interface I and Interface II. After the read command is transmitted, the data is read immediately with on dummy period.

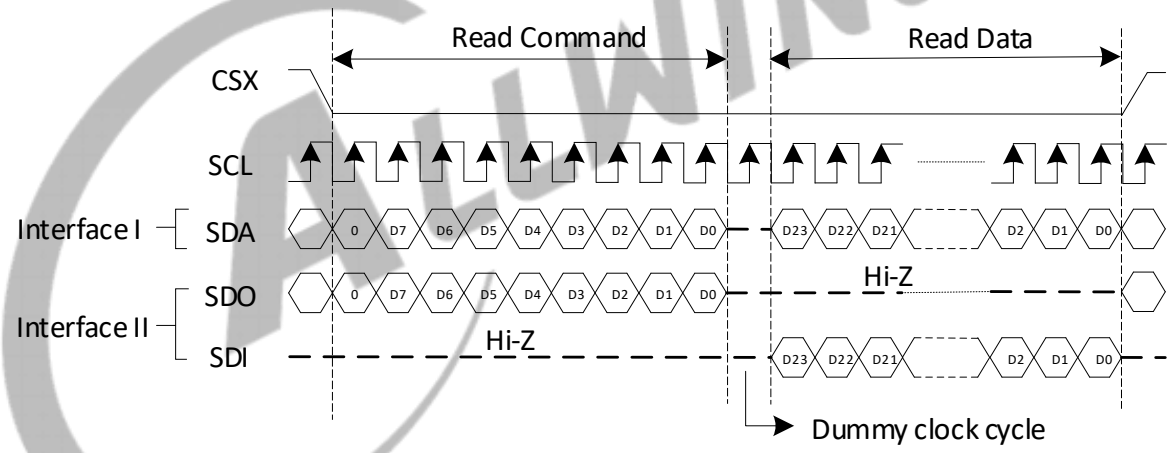
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Figure 10-40 DBI 3-Line Display Bus Serial Interface 8-bit Reading Operation Format



The following figure shows the 24 bits reading operation format of 3-line DBI Interface I and Interface II. After the read command is transmitted, the data is read after waiting for the dummy clock cycle.

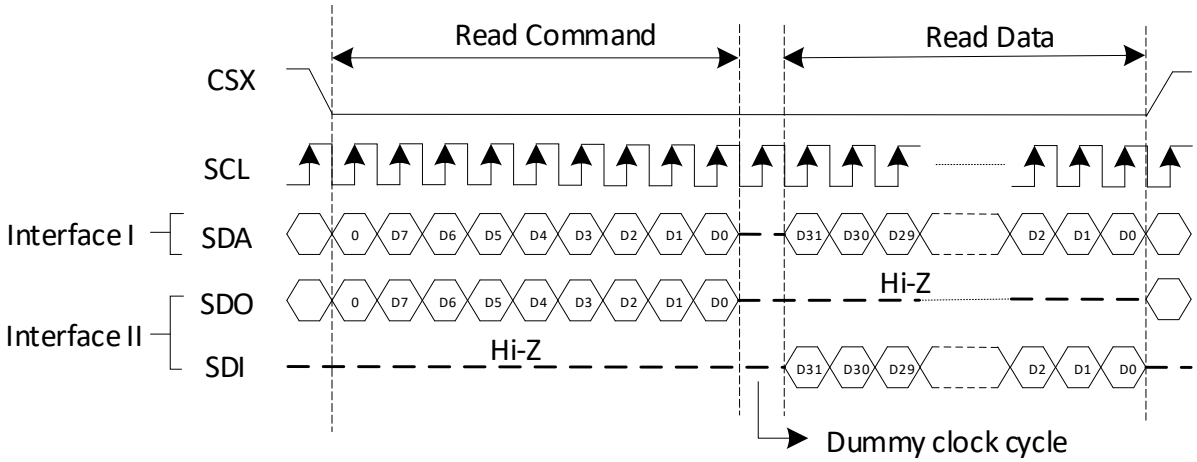
Figure 10-41 DBI 3-Line Display Bus Serial Interface 24-bit Reading Operation Format



The following figure shows the 32 bits reading operation format of 3-line DBI Interface I and Interface II. After the read command is transmitted, the data is read after waiting for the dummy clock cycle.

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Figure 10-42 DBI 3-Line Display Bus Serial Interface 32-bit Reading Operation Format



10.4.3.12 DBI 4-Line Interface Writing and Reading Timing

The 4-line DBI Interface I contains CSX, D/CX, SDA, and SCL, where SDA shares this port for bidirectional port data input and output.

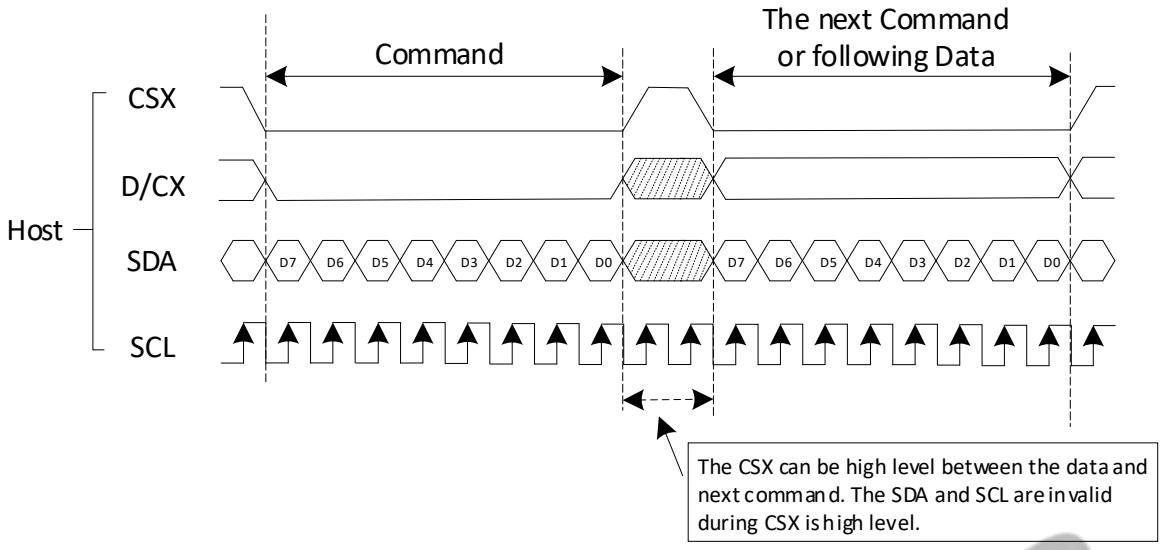
The 4-line DBI Interface II contains CSX, D/CX, SDA, SCL, and SDI; Data input and output ports are independent of each other.

Since the 4-line display bus mode has a Data/Command data line indicating whether Data or Command is currently being transmitted (0: Command, 1: Data). So there is no need to add an extra bit to data-stream before MSB like the 3-line DBI.

The following figure shows the writing operation format of 4-line DBI Interface I and Interface II.

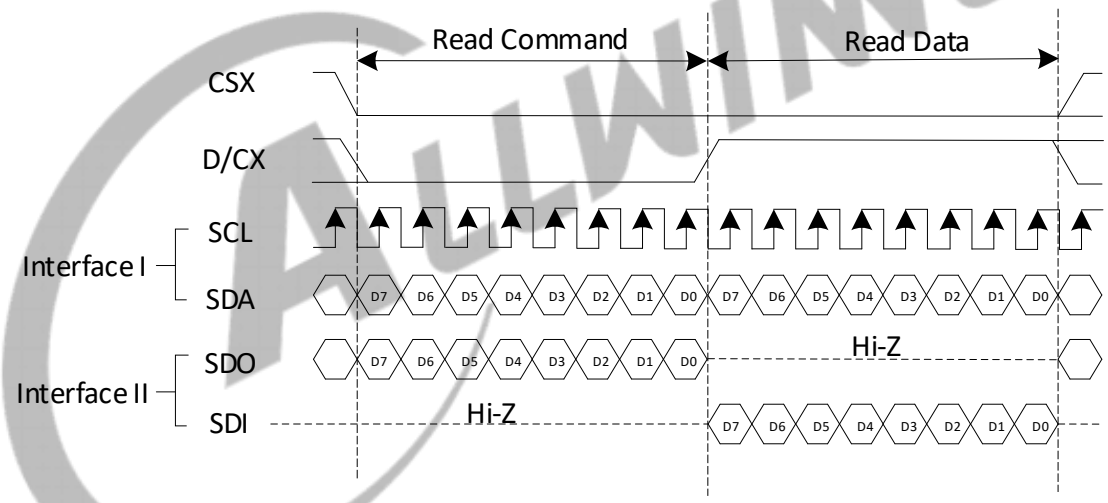
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Figure 10-43 DBI 4-Line Display Bus Serial Interface Writing Operation Format



The following figure shows the 8 bits reading operation format of 4-line DBI Interface I and Interface II.

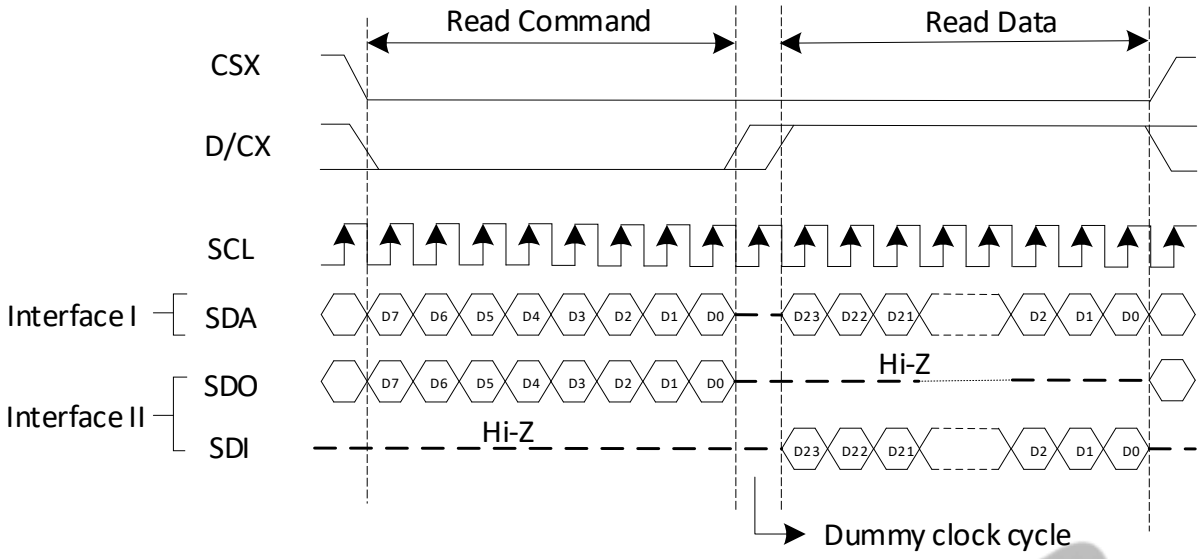
Figure 10-44 DBI 4-Line Display Bus Serial Interface 8-bit Reading Operation Format



The following figure shows the 24 bits reading operation format of 4-line DBI Interface I and Interface II.

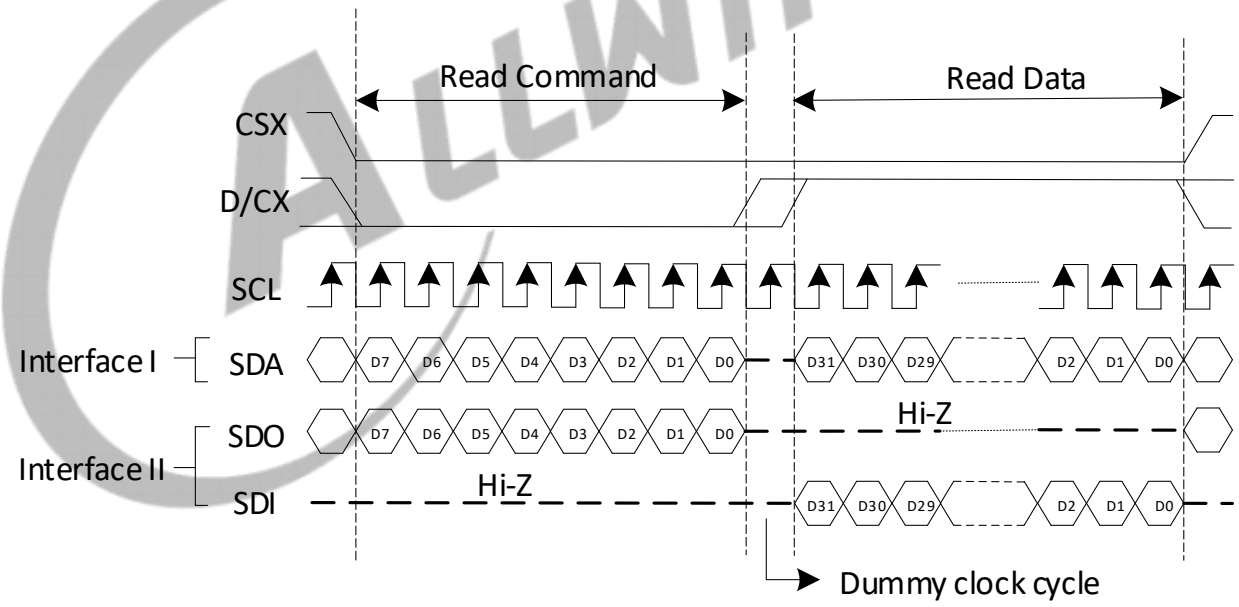
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Figure 10-45 DBI 4-Line Display Bus Serial Interface 24-bit Reading Operation Format



The following figure shows the 32 bits reading operation format of 4-line DBI Interface I and Interface II.

Figure 10-46 DBI 4-Line Display Bus Serial Interface 32-bit Reading Operation Format



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10.4.3.13 DBI 3-Line Interface Transmit Video Format

Figure 10-47 RGB111 3-Line Interface Transmit Video Format

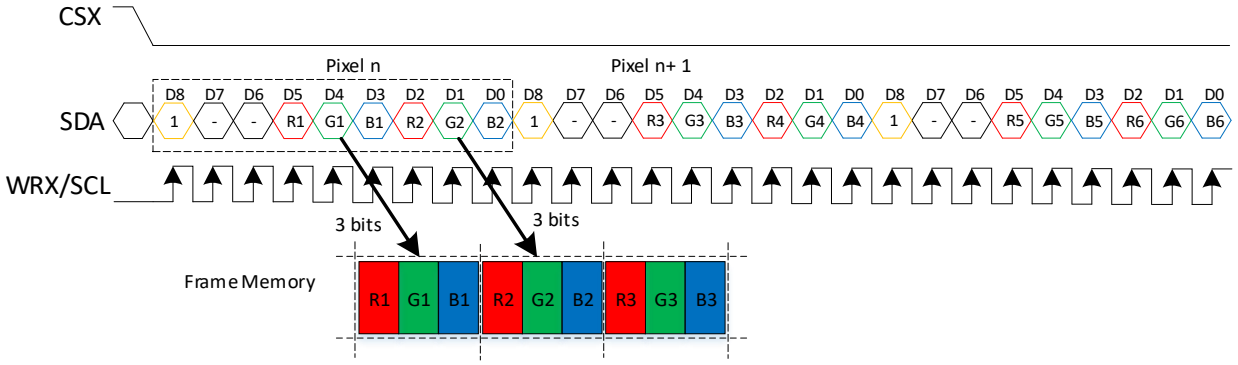
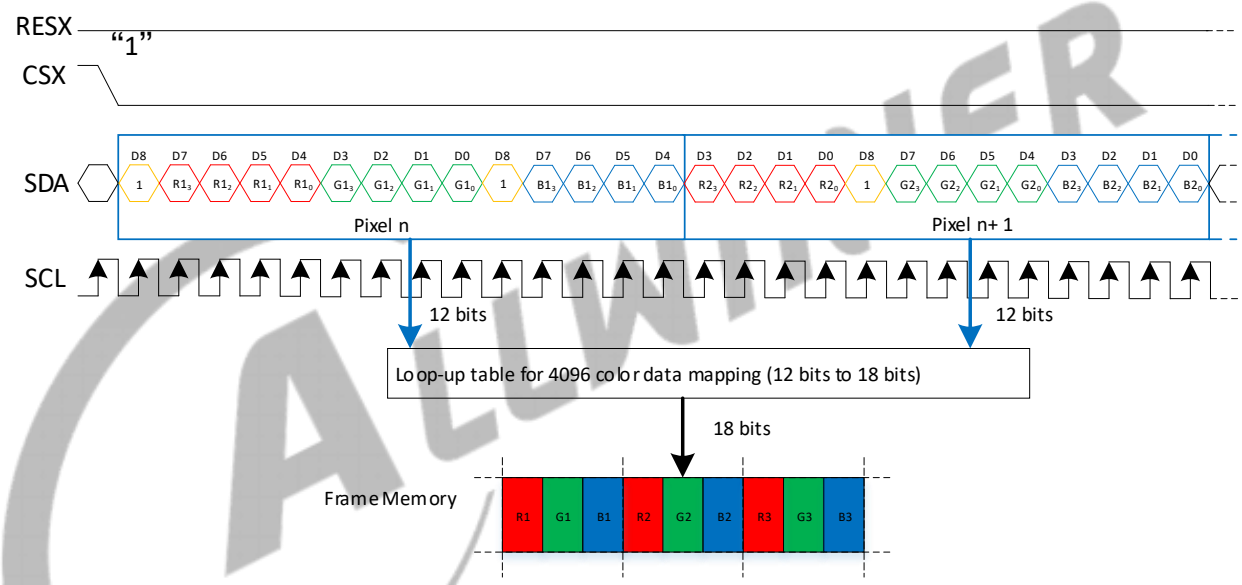


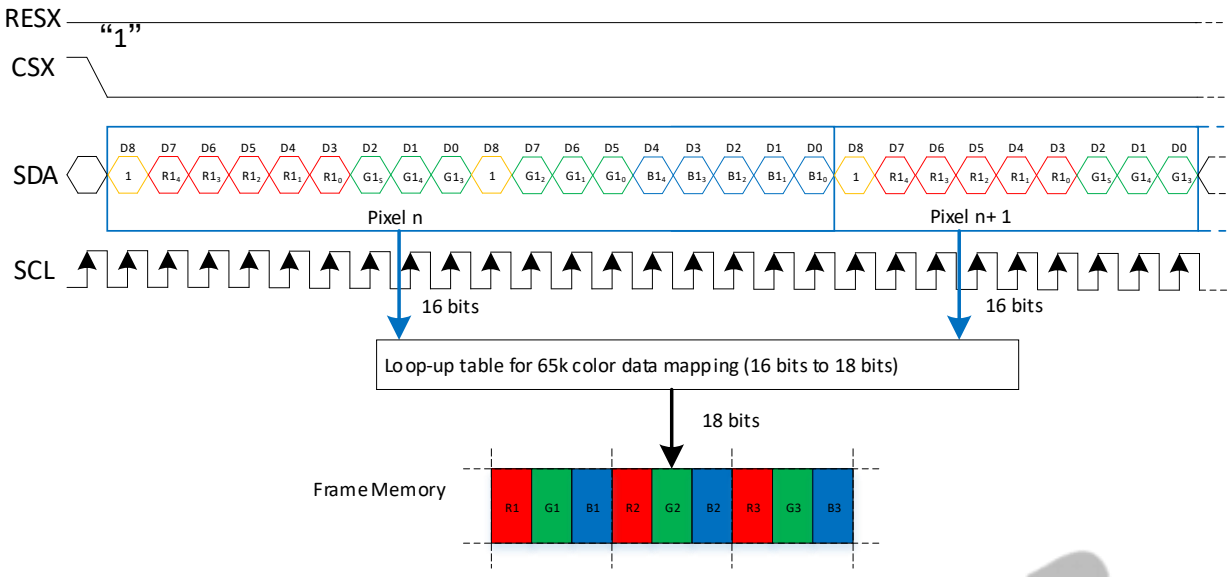
Figure 10-48 RGB444 3-Line Interface Transmit Video Format



Note 1. Pixel data with 12-bit color depth information
Note 2. The most significant bits are: Rx3, Gx3 and Bx3
Note 3. The least significant bits are: Rx0, Gx0 and Bx0

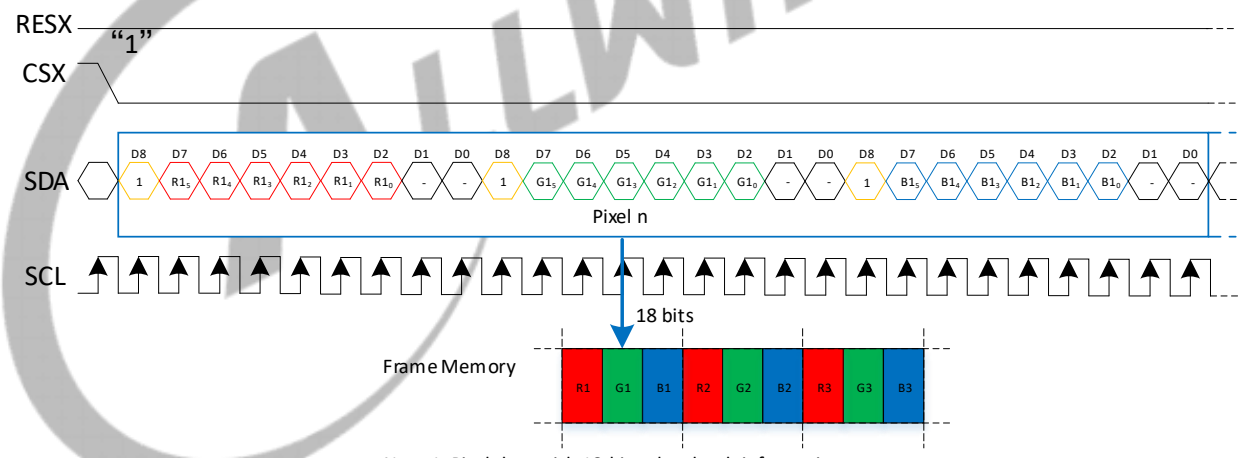
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Figure 10-49 RGB565 3-Line Interface Transmit Video Format



Note 1. Pixel data with 16-bit color depth information
Note 2. The most significant bits are: Rx4, Gx5 and Bx4
Note 3. The least significant bits are: Rx0, Gx0 and Bx0

Figure 10-50 RGB666 3-Line Interface Transmit Video Format



Note 1. Pixel data with 18-bit color depth information
Note 2. The most significant bits are: Rx5, Gx5 and Bx5
Note 3. The least significant bits are: Rx0, Gx0 and Bx0

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10.4.3.14 DBI 4-Line Interface Transmit Video Format

Figure 10-51 RGB111 4-Line Interface Transmit Video Format

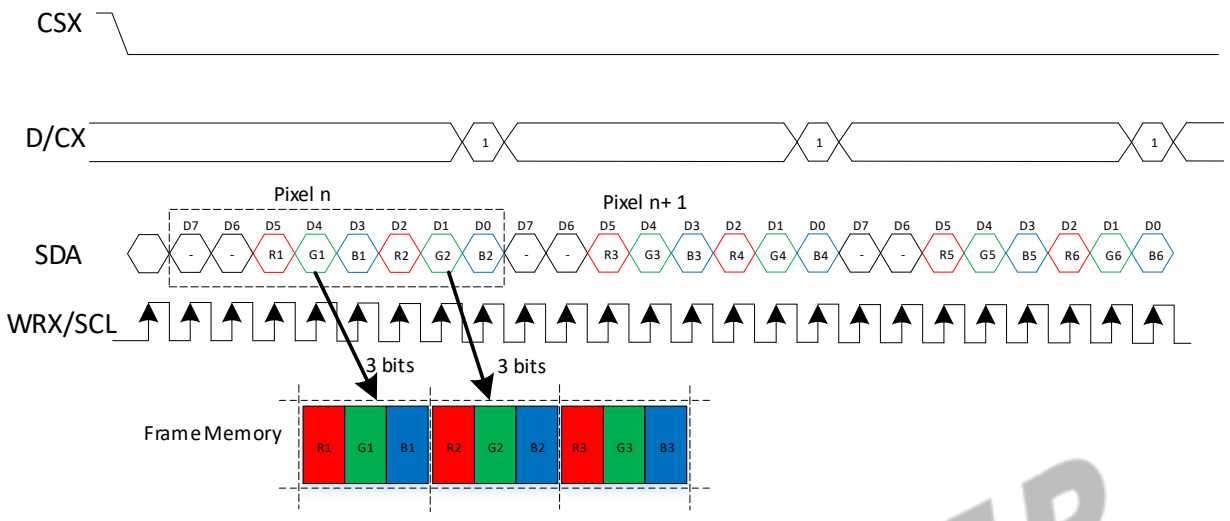
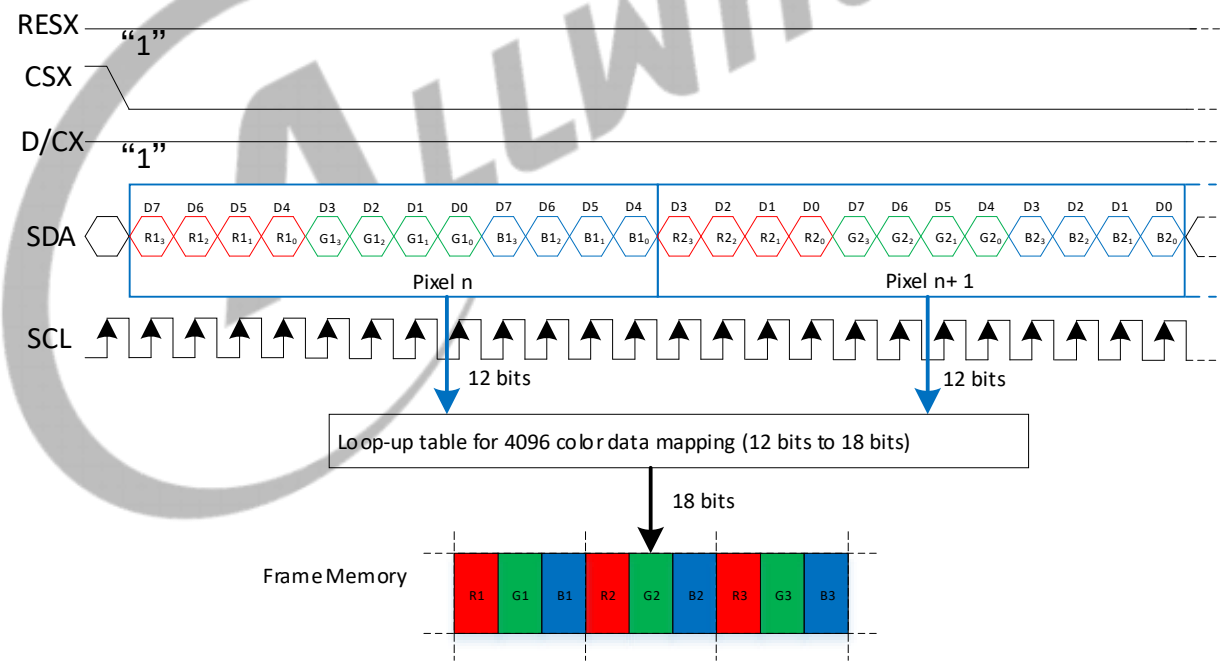


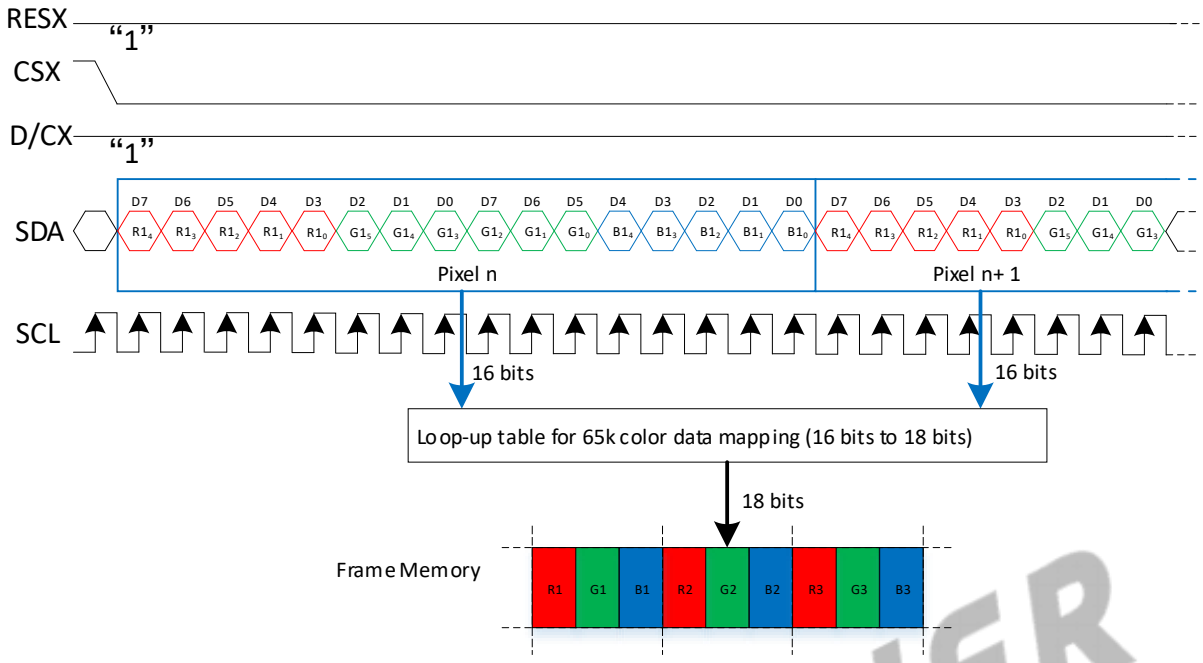
Figure 10-52 RGB444 4-Line Interface Transmit Video Format



Note 1. Pixel data with 12-bit color depth information
Note 2. The most significant bits are: Rx3, Gx3 and Bx3
Note 3. The least significant bits are: Rx0, Gx0 and Bx0

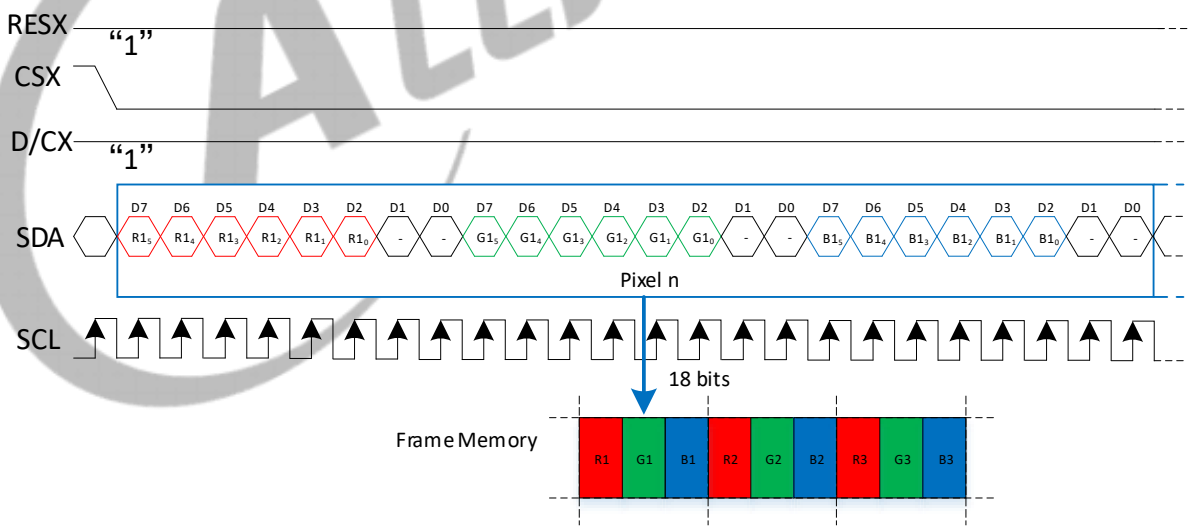
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Figure 10-53 RGB565 4-Line Interface Transmit Video Format



Note 1. Pixel data with 16-bit color depth information
Note 2. The most significant bits are: Rx4, Gx5 and Bx4
Note 3. The least significant bits are: Rx0, Gx0 and Bx0

Figure 10-54 RGB666 4-Line Interface Transmit Video Format



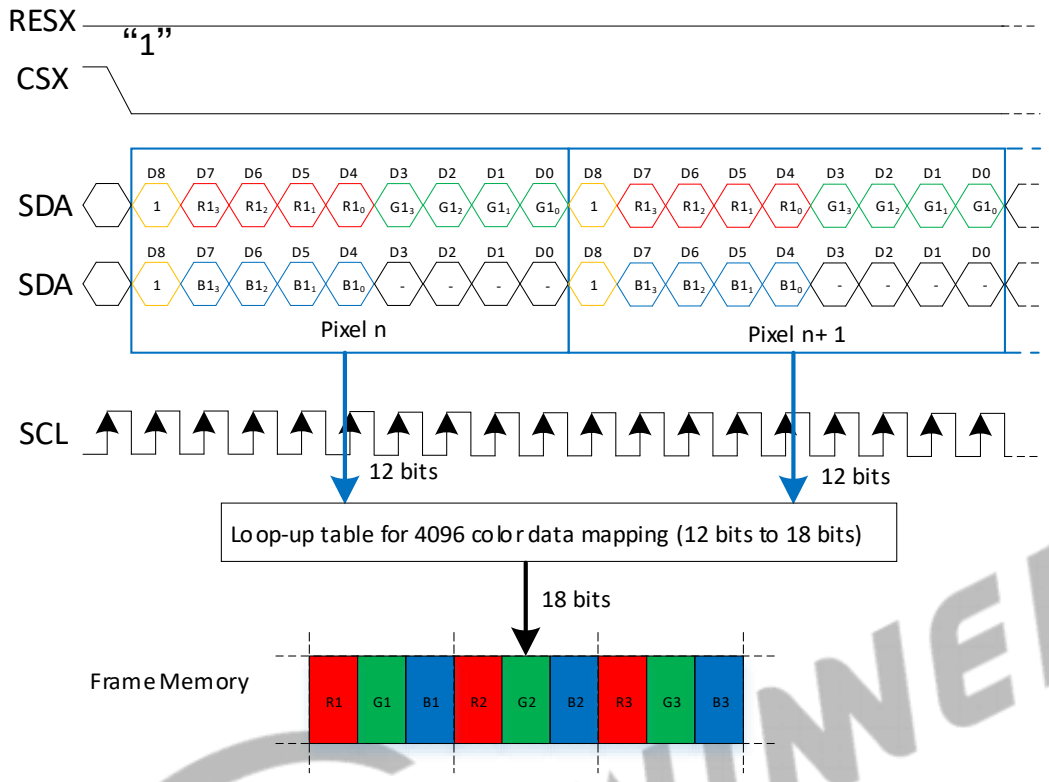
Note 1. Pixel data with 18-bit color depth information
Note 2. The most significant bits are: Rx5, Gx5 and Bx5
Note 3. The least significant bits are: Rx0, Gx0 and Bx0

10.4.3.15 DBI 2 Data Lane Interface Transmit Video Format

For RGB444:

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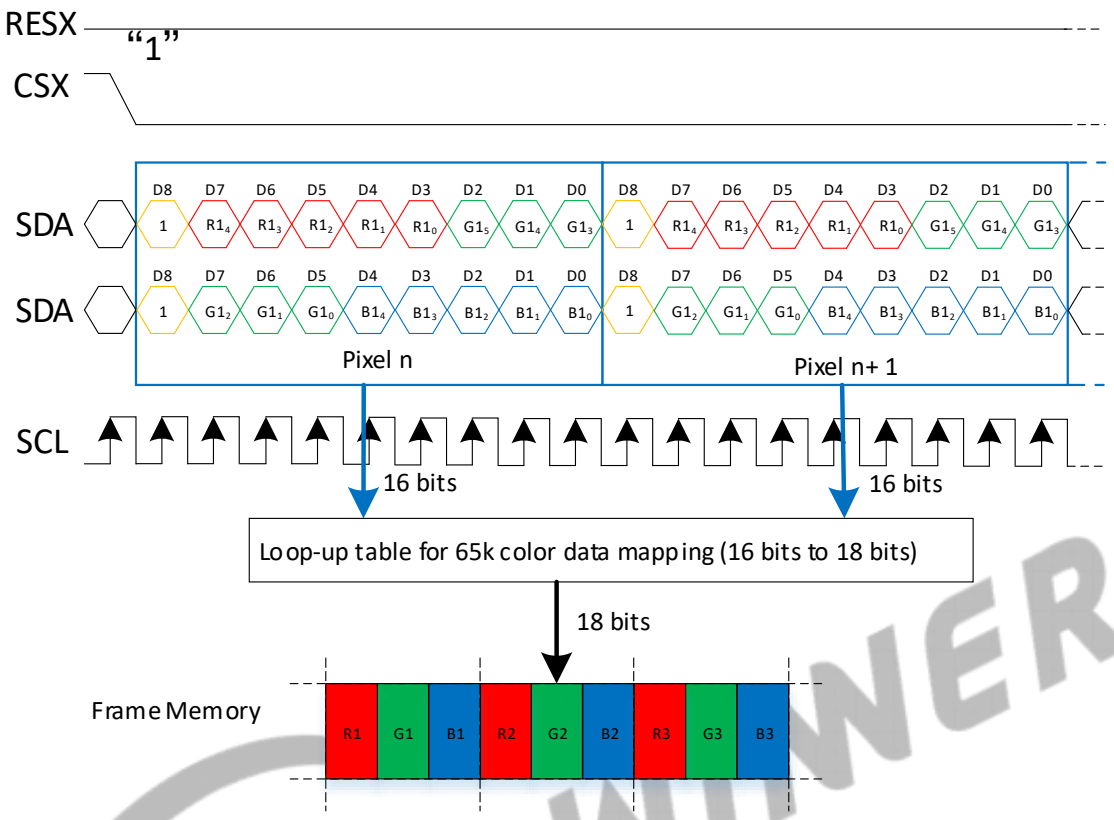
Figure 10-55 RGB444 2 Data Lane Interface Transmit Video Format



Note 1. Pixel data with 12-bit color information
Note 2. The most significant bits are: Rx3, Gx3 and Bx3
Note 3. The least significant bits are: Rx0, Gx0 and Bx0

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Figure 10-56 RGB565 2 Data Lane Interface Transmit Video Format



Note 1. Pixel data with 16-bit color information
Note 2. The most significant bits are: Rx4, Gx5 and Bx4
Note 3. The least significant bits are: Rx0, Gx0 and Bx0

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Figure 10-57 RGB666 2 Data Lane Interface Transmit Video Format 0

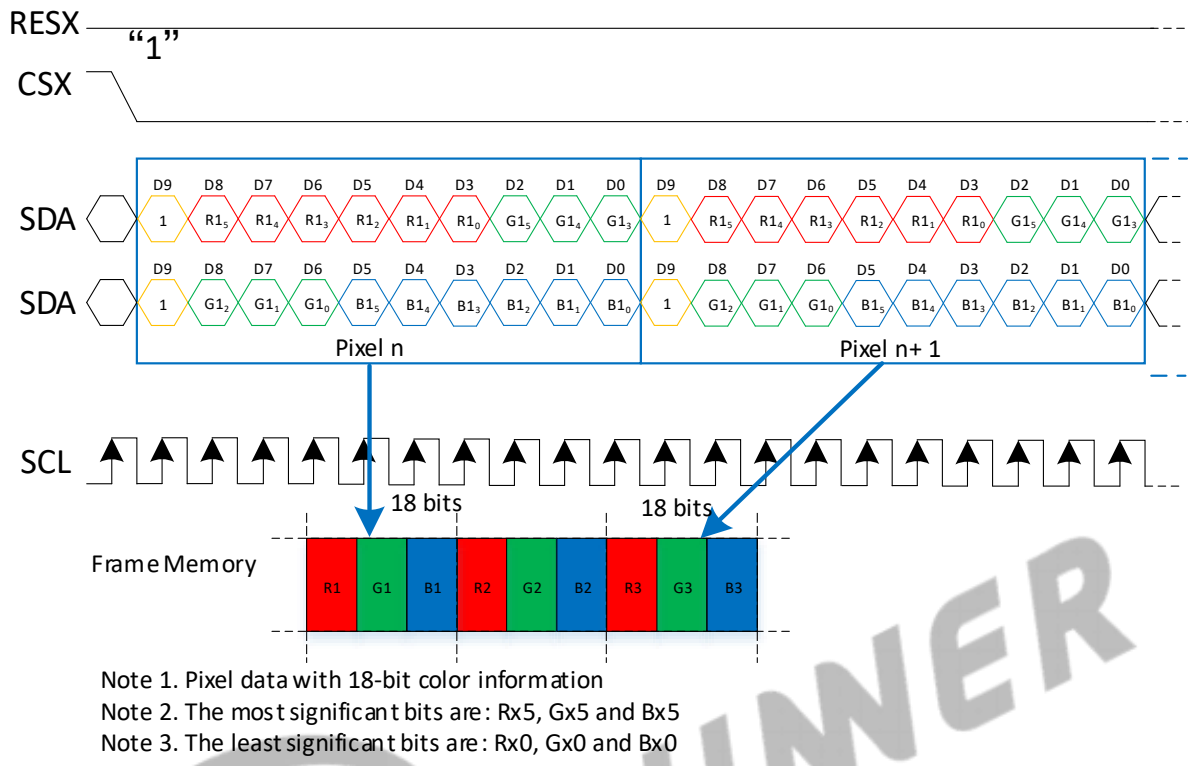


Figure 10-58 RGB666 2 Data Lane Interface Transmit Video Format 1 (ilitek)

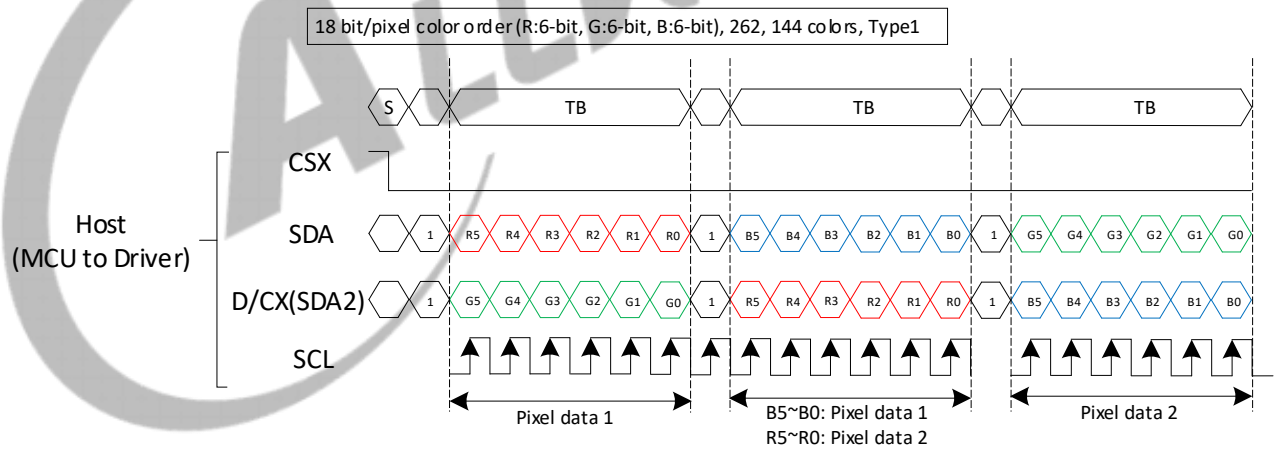
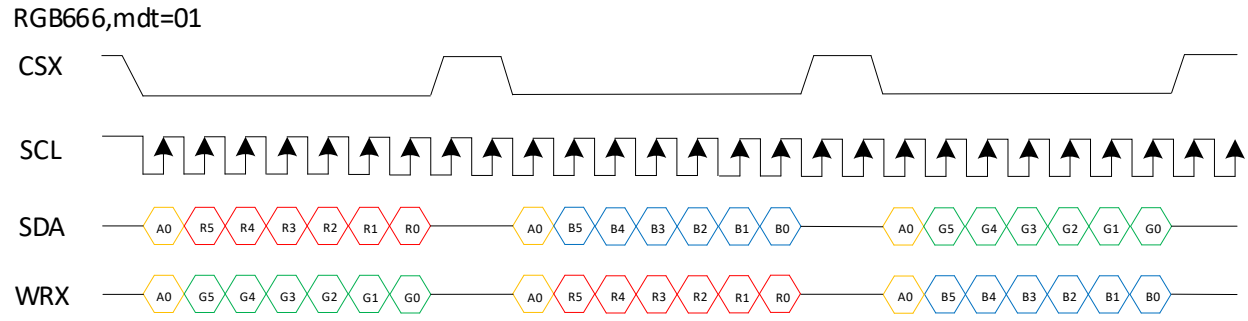
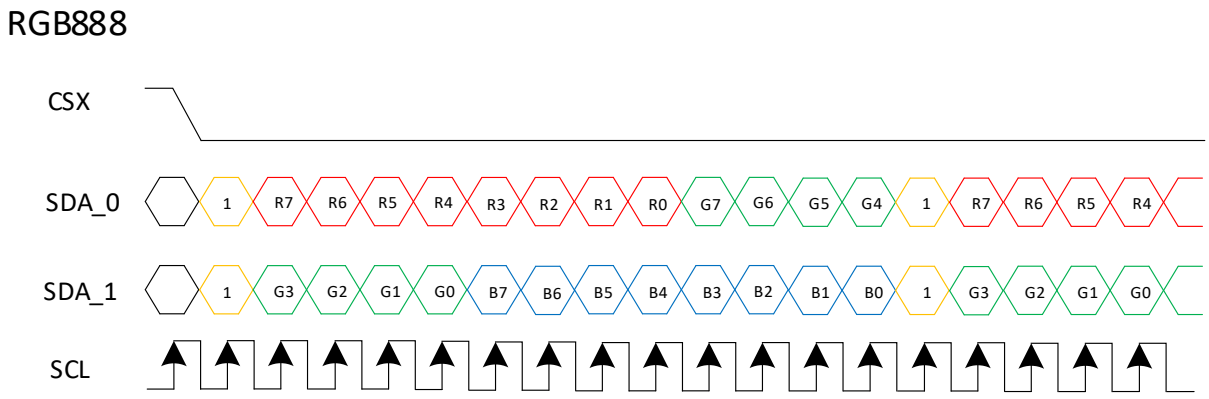


Figure 10-59 RGB666 2 Data Lane Interface Transmit Video Format 2 (New vision)



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Figure 10-60 RGB888 2 Data Lane Interface Transmit Video Format



Note 1. Pixel data with 24-bit color information
Note 2. The most significant bits are: R7, G7 and B7
Note 3. The least significant bits are: R0, G0 and B0

10.4.4 Programming Guidelines

10.4.4.1 Writing/Reading Data Process Using SPI Mode

The SPI transfers serial data between the processor and the external device. CPU and DMA are the two main operational modes for SPI. For each SPI, the data is simultaneously transmitted (shifted out serially) and received (shifted in serially). The SPI has 2 channels, including the TX channel and RX channel. The TX channel has the path from TX FIFO to the external device. The RX channel has the path from the external device to RX FIFO.

Write Data: CPU or DMA must write data on the **SPI_TXD** register, the data on the register are automatically moved to TX FIFO.

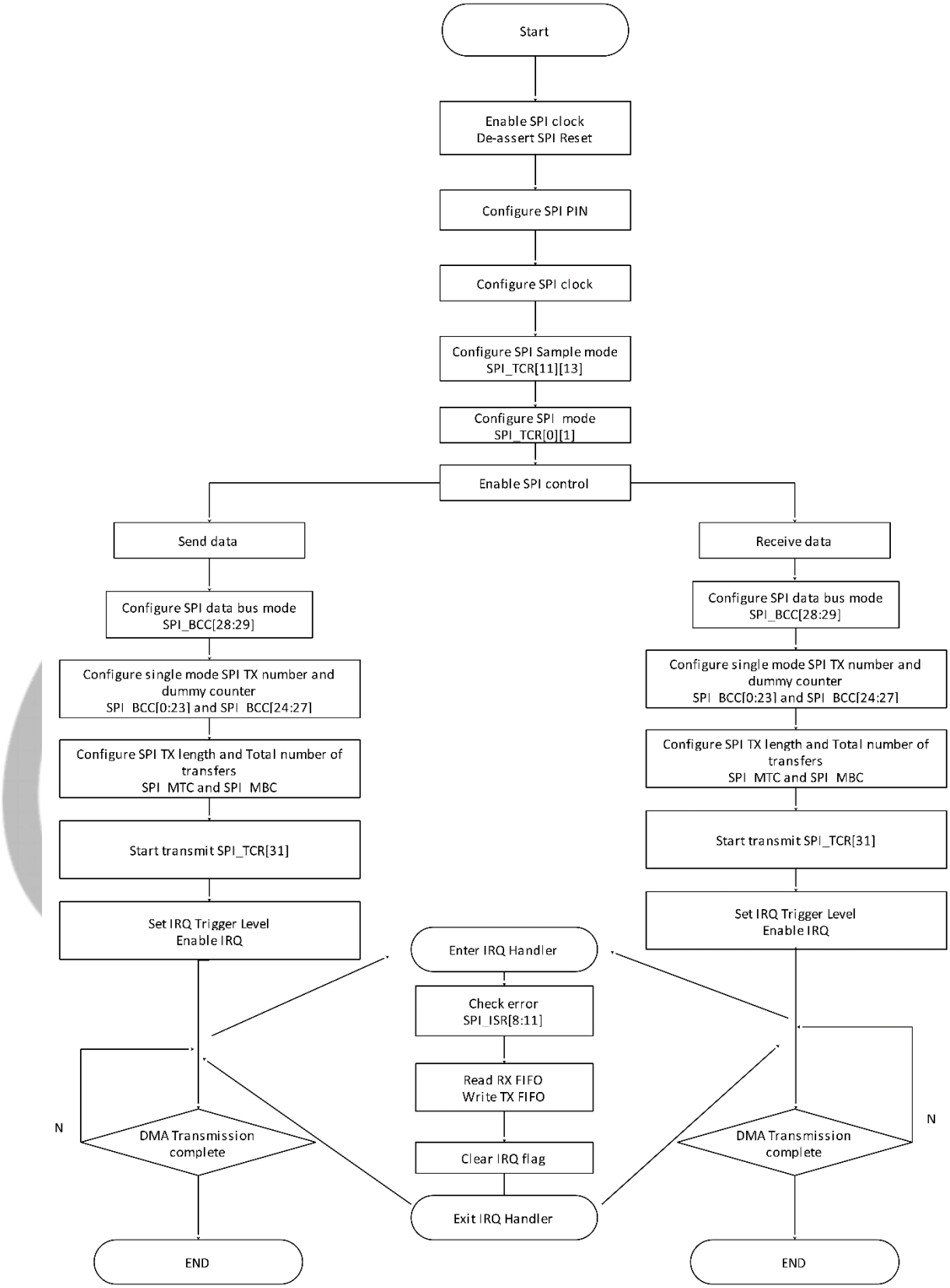
Read Data: To read data from RX FIFO, CPU or DMA must access the register **SPI_RXD** and data are automatically sent to the register **SPI_RXD**.

In CPU or DMA mode, the SPI sends a completed interrupt (**SPI_ISR**[TC]) to the processor at the end of each transfer.

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CPU Mode

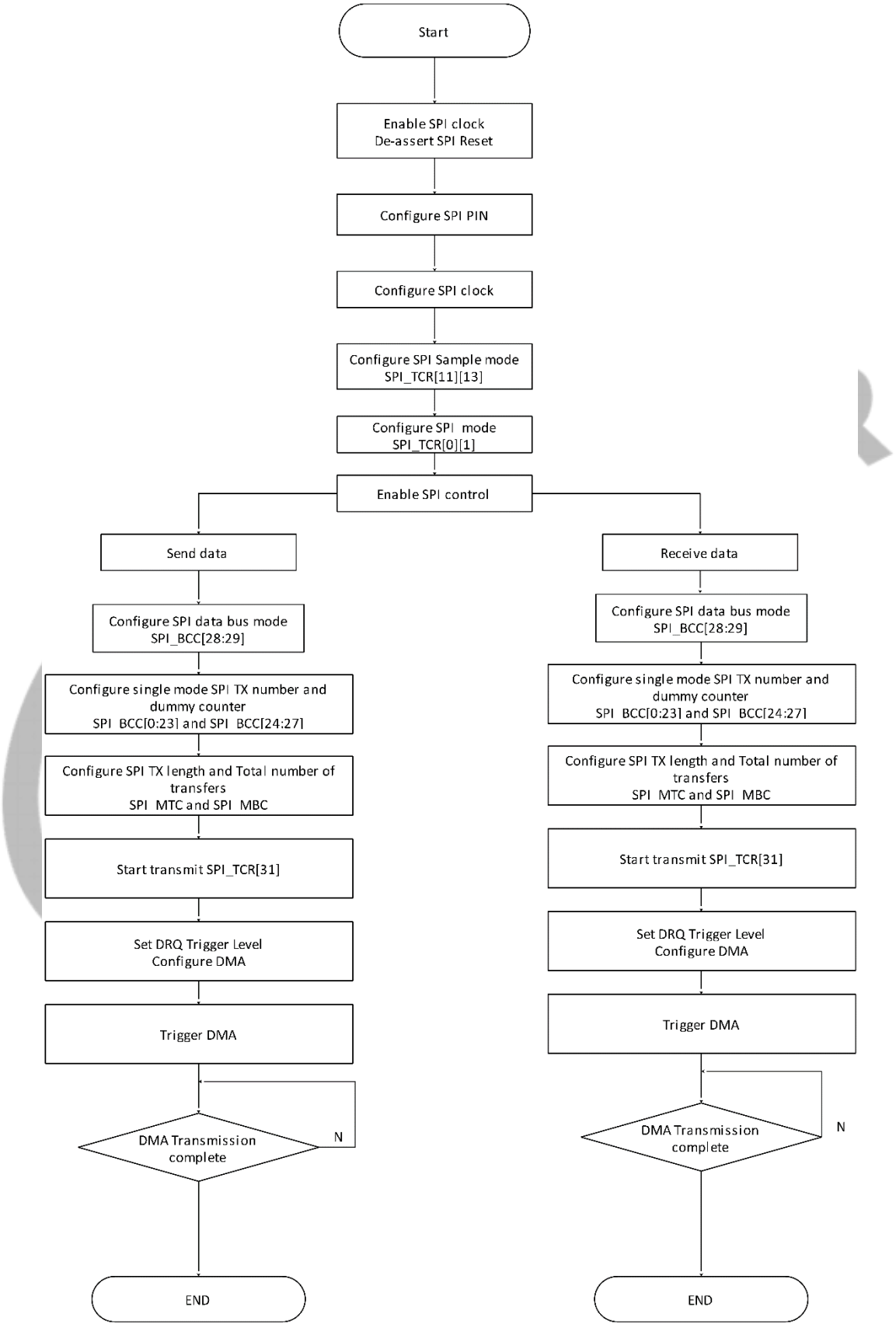
Figure 10-61 SPI Write/Read Data in CPU Mode



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DMA Mode

Figure 10-62 SPI Write/Read Data in DMA Mode



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10.4.4.2 Calibrate Delay Chain Using SPI Mode

The SPI has one delay chain which is used to generate delay to make proper timing between the internal SPI clock signal and data signals. Delay chain is made up of 64 delay cells. The delay time of one delay cell can be estimated through delay chain calibration.

The steps to calibrate delay chain are as follows:

Step 1 Enable SPI. To calibrate the delay chain by operation registers in SPI, the SPI must be enabled through AHB reset and AHB clock gating control registers.

Step 2 Configure a proper clock for SPI. The calibration delay chain is based on the clock for SPI from CCU.

Step 3 Set proper initial delay value. Write 0xA0 to the SPI Sample Delay Control Register to set initial delay value 0x20 to delay chain. Then write 0x0 to the SPI Sample Delay Control Register to clear this value.

Step 4 Write 0x8000 to the SPI Sample Delay Control Register to start to calibrate the delay chain.

Step 5 Wait until the flag (Bit14 in the SPI Sample Delay Control Register) of calibration done is set. The number of delay cells is shown at Bit[13:8] in SPI Sample Delay Control Register. The delay time generated by these delay cells is equal to the cycle of SPI's clock nearly. This value is the result of calibration.

Step 6 Calculate the delay time of one delay cell according to the cycle of the SPI clock and the result of calibration.

10.4.4.3 Transmitting Write Command Using DBI Mode

Step 1 Set the SPI_DBI_MODE_SEL (bit3) of **SPI_GCR** (0x0004) to 1 to select DBI mode.

Step 2 Set the DBI EN MODE SEL (bit[30:29]) of **DBI_CTL_1** (0x0104) to 0 to select the trigger mode of DBI.

Step 3 Configure the **DBI_CTL_0** (0x0100).

- Set **DBI_CTL_0**[Command Type] (bit31) to 0 to configure the writing command.
- Set **DBI_CTL_0**[Write Command Dummy Cycles] (bit[30:20]) to configure the number of dummy cycles between commands.
- Set **DBI_CTL_0**[Output Data Sequence] (bit19) to select the MSB or LSB.
- Set **DBI_CTL_0**[Transmit Mode] (bit15) to 0 to select the command path.
- Set **DBI_CTL_0**[Output Data Format] (bit[14:12]) to 0 to transmit the command.
- Set **DBI_CTL_0**[DBI interface Select] (bit[10:8]) to select the DBI interface type.
- The remaining values of the **DBI_CTL_0** register remain the default value.

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Step 4 Set **DBI_CTL_1**[DCX_DATA] (bit22) to 0 to send the command.

Step 5 DMA Path: Configure the **SPI_FCR** register (0x0018).

- Set **SPI_FCR**[TF_DRQ_EN] (bit24) to 1 to enable TXFIFO DMA.
- Set **SPI_FCR**[TX_TRIG_LEVEL] (bit[23:16]) to 255. It indicates the controller requests data from DMA if the remaining space of TX FIFO is greater than 255.

CPU Path: Write the command to be sent to the 0x200 address.

Step 6 Set **SPI_GCR**[DBI_EN] (bit4) to 1 to start transmitting the command.

Step 7 Wait until the TX FIFO underrun interrupt (**SPI_ISR**[TF_UDF]) is 1. It indicates that the command written to the TX FIFO is transmitted completely.

10.4.4.4 Transmitting Parameter Using DBI Mode

Step 1 Set the SPI_DBI_MODE_SEL (bit3) of **SPI_GCR** (0x0004) to 1 to select DBI mode.

Step 2 Set the DBI_EN_MODE_SEL (bit[30:29]) of **DBI_CTL_1** (0x0104) to 0 to select the trigger mode of DBI.

Step 3 Configure the **DBI_CTL_0** register (0x0100).

- Set **DBI_CTL_0**[Command Type] (bit31) to 0 to configure the writing command.
- Set **DBI_CTL_0**[Write Command Dummy Cycles] (bit[30:20]) to configure the number of dummy cycles between commands.
- Set **DBI_CTL_0**[Output Data Sequence] (bit19) to select the MSB or LSB.
- Set **DBI_CTL_0**[Transmit Mode] (bit15) to 0 to select the command path.
- Set **DBI_CTL_0**[Output Data Format] (bit[14:12]) to 0 to transmit the command.
- Set **DBI_CTL_0**[DBI interface Select] (bit[10:8]) to select the DBI interface type.
- The remaining values of the **DBI_CTL_0** register remain the default value.

Step 4 Set **DBI_CTL_1**[DCX_DATA] (bit22) to 1 to send the parameter.

Step 5 DMA Path: Configure the register (0x0018).

- Set **SPI_FCR**[TF_DRQ_EN] (bit24) to 1 to enable TXFIFO DMA.
- Set **SPI_FCR**[TX_TRIG_LEVEL] (bit[23:16]) to 255. It indicates the controller requests data from DMA if the remaining space of TX FIFO is greater than 255.

CPU Path: Write the command to be sent to the 0x0200 address.

Step 6 Set **SPI_GCR**[DBI_EN] (bit4) to 1 to start transmitting the command.

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Step 7 Wait until the TX FIFO underrun interrupt (**SPI_ISR**[TF_UDF]) is 1. It indicates that the command written to the TX FIFO is transmitted completely.

10.4.4.5 Transmitting Video Using DBI Mode

Set the SPI_DBI_MODE_SEL (bit3) of **SPI_GCR** (0x0004) to 1 to select DBI mode.

If the data is from the CPU path, the controller writes the command to be sent to the 0x0200 address by the AHB bus.

If the data is from the DMA path, configure **DBI_CTL_1**[DBI_FIFO_DRQ_EN] (bit15) to 1 and **DBI_CTL_1**[TX_TRIG_LEVEL] (bit[14:8]) to 64, which indicates the controller requests data from DMA if the remaining space of TX FIFO is greater than 64.

Software Trigger Mode

The software enables DBI_en_trigger when the edge interrupt of TE is detected.

After transmitting each frame image, the controller clears automatically the line_cnt, pixel_cnt and stops transmitting data.

Wait for the edge interrupt of TE, the software needs to enable DBI_en_trigger, in circulation.

The operation process is as follows.

Step 1 Set the SPI_DBI_MODE_SEL (bit3) of **SPI_GCR** (0x0004) to 1 to select DBI mode.

Step 2 Set the DBI EN MODE SEL (bit[30:29]) of **DBI_CTL_1** (0x0104) to 1 to select the software trigger mode.

Step 3 Configure the **DBI_CTL_0** register (0x0100).

- Set **DBI_CTL_0**[Command Type] (bit31) to 0 to set the writing command.
- Set **DBI_CTL_0**[Write Command Dummy Cycles] (bit[30:20]) to configure the number of dummy cycles between commands.
- Set **DBI_CTL_0**[Output Data Sequence] (bit19) to select the MSB or LSB.
- Set **DBI_CTL_0**[Transmit Mode] (bit15) to 1 to select the image path.
- Set **DBI_CTL_0**[Output Data Format] (bit[14:12]) to select RGB111//444/565/666/888.
- Set **DBI_CTL_0**[DBI interface Select] (bit[10:8]) to select the DBI interface type.
- The remaining values of the **DBI_CTL_0** register remain the default value.

Step 4 Set **DBI_CTL_1**[DCX_DATA] (bit22) to 0 to send the image data.

Step 5 Configure **DBI_Video_Size** (0x110) according to the sent image size.

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Step 6 Configure **DBI_CTL_2** (0x0108) to set the TE-related parameter.

Step 7 Detect the TE interrupt of the **DBI_INT** (0x0120) register.

Step 8 Configure **DBI_CTL_1**[DBI_soft_trigger] to 1.

Timer Trigger Mode

The software configures timer_en to enable timer counting, and when the counter reaches the specified value, the DBI_EN automatically can be enabled to start transmitting data.

After transmitting each frame image, the controller clears automatically the line_cnt, pixel_cnt, and stops transmitting data.

The timer starts counting again. When the counter reaches the specified value, the controller automatically enables DBI_EN, and in circulation until the software turns off the timer_en.

The operation process is as follows.

Step 1 Set the SPI_DBI_MODE_SEL (bit3) of **SPI_GCR** (0x0004) to 1 to select DBI mode.

Step 2 Set the DBI EN MODE SEL (bit30:29) of **DBI_CTL_1** (0x0104) to 2 to select the timer trigger mode.

Step 3 Configure the **DBI_CTL_0** register (0x0100).

- Set **DBI_CTL_0**[Command Type] (bit31) to 0 to set the writing command.
- Set **DBI_CTL_0**[Write Command Dummy Cycles] (bit[30:20]) to configure the number of dummy cycles between commands.
- Set **DBI_CTL_0**[Output Data Sequence] (bit19) to select the MSB or LSB.
- Set **DBI_CTL_0**[Transmit Mode] (bit15) to 1 to select the image path.
- Set **DBI_CTL_0**[Output Data Format] (bit[14:12]) to select RGB111/444/565/666/888.
- Set **DBI_CTL_0**[DBI interface Select] (bit[10:8]) to select the DBI interface type.
- The remaining values of the **DBI_CTL_0** register remain the default value.

Step 4 Set **DBI_CTL_1**[DCX_DATA] (bit22) to 0 to send the image data.

Step 5 Configure **DBI_Video_Size** (0x110) to transmit the image size.

Step 6 Configure the related parameter of **DBI_Timer** (0x10C).

TE Trigger Mode

When the edge changes of the TE are detected (The rising and falling edges are optional), the DBI_EN automatically can be enabled to start transmitting data.

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After transmitting each frame image, the controller clears automatically the line_cnt, pixel_cnt, and stops transmitting data.

When the edge changes of the TE are detected (The rising and falling edges are optional), the DBI_EN automatically can be enabled to start transmitting data until the software shuts down TE_EN or the screen no longer sends TE signals.

The operation process is as follows.

Step 1 Set the SPI_DBI_MODE_SEL (bit3) of **SPI_GCR** (0x0004) to 1 to select DBI mode.

Step 2 Set the DBI EN MODE SEL (bit30:29) of **DBI_CTL_1** (0x0104) to 3 to select the TE trigger mode.

Step 3 Configure the **DBI_CTL_0** register (0x0100).

- Set **DBI_CTL_0**[Command Type] (bit31) to 0 to set the writing command.
- Set **DBI_CTL_0**[Write Command Dummy Cycles] (bit[30:20]) to configure the number of dummy cycles between commands.
- Set **DBI_CTL_0**[Output Data Sequence] (bit19) to select the MSB or LSB.
- Set **DBI_CTL_0**[Transmit Mode] (bit15) to 1 to select the image path.
- Set **DBI_CTL_0**[Output Data Format] (bit[14:12]) to select RGB111/444/565/666/888.
- Set **DBI_CTL_0**[DBI interface Select] (bit[10:8]) to select the DBI interface type.
- The remaining values of the **DBI_CTL_0** register remain the default value.

Step 4 Configure **DBI_CTL_1**[DCX_DATA] (bit22) to 0 to send the image data.

Step 5 Configure **DBI_Video_Size** (0x0110) to transmit the image size.

Step 6 Configure **DBI_CTL_2** (0x0108) to set the TE-related parameter.

10.4.4.6 Transmitting Read Command and Read Data Using DBI Mode

Step 1 Set the SPI_DBI_MODE_SEL (bit3) of **SPI_GCR** (0x0004) to 1 to select DBI mode.

Step 2 Set the DBI EN MODE SEL (bit[30:29]) of **DBI_CTL_1** (0x0104) to 0.

Step 3 Configure the **DBI_CTL_0** register (0x0100).

- Set **DBI_CTL_0**[Command Type] (bit31) to 0 to set the reading command.
- Set **DBI_CTL_0**[Output Data Sequence] (bit19) to select the MSB or LSB.
- Set **DBI_CTL_0**[Transmit Mode] (bit15) to 0 to select the command path.
- Set **DBI_CTL_0**[Output Data Format] (bit[14:12]) to 0.
- Set **DBI_CTL_0**[DBI interface Select] (bit[10:8]) to select the DBI interface type.

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- The remaining values of the DBI_CTL_0 register remain the default value.

Step 4 Configure the DBI_CTL_1 register (0x0104).

- Configure DBI_CTL_1[DCX_DATA] (bit22) to 0 to send the command.
- Configure DBI_CTL_1[Read_MSB_First] (bit20) to select whether the first bit of the read data is the highest or lowest bit of data.
- Configure DBI_CTL_1[Read Data Number of Bytes] to set the byte number to be read.
- Configure DBI_CTL_1[Read Command Dummy Cycles] to set the dummy cycle between the read command and the read data, when the dummy cycle is complete, the data starts to be sampled.

Step 5 DMA Path: Configure the SPI_FCR register (0x0018).

- Set SPI_FCR[RF_DRQ_EN] (bit8) to 1 to enable RXFIFO DMA.
- Set SPI_FCR[RX_TRIG_LEVEL] (bit[7:0]) to 32, which indicates the controller requests receiving data from DMA if the data of the RX FIFO is greater than 64.

CPU Path: Read data in RX FIFO from the 0x0300 address.

Step 6 Set SPI_GCR[DBI_EN] (bit4) to 1 to start transmitting command.

Step 7 Wait until DBI_INT[RD_DONE_INT] is 1. It indicates that the data is read completely.

10.4.5 Register List

Module Name	Base Address
SPI_DBI	0x04026000

Register Name	Offset	Description
SPI_GCR	0x0004	SPI Global Control Register
SPI_TCR	0x0008	SPI Transfer Control Register
SPI_IER	0x0010	SPI Interrupt Control Register
SPI_ISR	0x0014	SPI Interrupt Status Register
SPI_FCR	0x0018	SPI FIFO Control Register
SPI_FSR	0x001C	SPI FIFO Status Register
SPI_WCR	0x0020	SPI Wait Clock Register
SPI_SAMP_DL	0x0028	SPI Sample Delay Control Register
SPI_MBC	0x0030	SPI Master Burst Counter Register
SPI_MTC	0x0034	SPI Master Transmit Counter Register

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Register Name	Offset	Description
SPI_BCC	0x0038	SPI Master Burst Control Register
SPI_BATCR	0x0040	SPI Bit-Aligned Transfer Configure Register
SPI_BA_CCR	0x0044	SPI Bit-Aligned Clock Configuration Register
SPI_TBR	0x0048	SPI TX Bit Register
SPI_RBR	0x004C	SPI RX Bit Register
SPI_NDMA_MODE_CTL	0x0088	SPI Normal DMA Mode Control Register
DBI_CTL_0	0x0100	DBI Control Register 0
DBI_CTL_1	0x0104	DBI Control Register 1
DBI_CTL_2	0x0108	DBI Control Register 2
DBI_TIMER	0x010C	DBI Timer Control Register
DBI_VIDEO_SZIE	0x0110	DBI Video Size Configuration Register
DBI_INT	0x0120	DBI Interrupt Register
DBI_DEBUG_0	0x0124	DBI BEBUG 0 Register
DBI_DEBUG_1	0x0128	DBI BEBUG 1 Register
SPI_TXD	0x0200	SPI TX Data register
SPI_RXD	0x0300	SPI RX Data register

10.4.6 Register Description

10.4.6.1 0x0004 SPI Global Control Register (Default Value: 0x0000_0080)

Offset:0x0004			Register Name: SPI_GCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/WAC	0x0	SRST Soft reset Writing ‘1’ to this bit will clear the SPI controller, and auto clear to ‘0’ when reset operation completes. Writing ‘0’ to this bit has no effect.
30:8	/	/	/

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Offset:0x0004			Register Name: SPI_GCR
Bit	**Read/Write**	**Default/Hex**	**Description**
7	R/W	0x1	TP_EN Transmit Pause Enable In master mode, it is used to control transmit state machine to stop smart burst sending when RX FIFO is full. 0: Normal operation, ignore RXFIFO status 1: Stop transmit data when RXFIFO full Cannot be written when XCH=1.
6:5	/	/	/
4	R/W	0x0	DBI EN DBI Module Enable Control 0: Disable 1: Enable
3	R/W	0x0	SPI_DBI_MODE_SEL DBI Working Mode Select 0: SPI MODE 1: DBI MODE
2	R/W	0x0	MODE_SELEC Sample Timing Mode Select 0: Old mode of Sample Timing 1: New mode of Sample Timing Cannot be written when XCH=1.
1	R/W	0x0	MODE SPI Function Mode Select 0: Slave mode 1: Master mode Cannot be written when XCH=1.
0	R/W	0x0	EN SPI Module Enable Control 0: Disable 1: Enable After transforming from bit_mode to byte_mode, it must enable the SPI module again.

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10.4.6.2 0x0008 SPI Transfer Control Register (Default Value: 0x0000_0087)

Offset: 0x0008			Register Name: SPI_TCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/WAC	0x0	XCH Exchange Burst In master mode, it is used to start SPI burst 0: Idle 1: Initiates exchange. Writing “1” to this bit will start the SPI burst, and will auto-clear after finishing the bursts transfer specified by BC. Writing “1” to SRST will also clear this bit. Writing ‘0’ to this bit has no effect. Cannot be written when XCH=1.
30:16	/	/	/
15	R/W	0x0	SDC1 Master Sample Data Control register1 Set this bit to ‘1’ to make the internal read sample point with a delay of half-cycle of SPI_CLK. It is used in high speed read operation to reduce the error caused by the time delay of SPI_CLK between master and slave. 0: Normal operation, do not delay the internal read sample point 1: Delay the internal read sample point Cannot be written when XCH=1.
14	R/W	0x0	SDDM Sending Data Delay Mode 0: Normal sending 1: Delay sending Set the bit to "1" to make the data that should be sent with a delay of half-cycle of SPI_CLK in dual IO mode for SPI mode 0. Cannot be written when XCH=1.
13	R/W	0x0	SDM Master Sample Data Mode 0: Delay sample mode 1: Normal sample mode In normal sample mode, the SPI master samples the data at the correct edge for each SPI mode; In delay sample mode, the SPI master samples data at the edge that is half cycle delayed by the correct edge defined in respective SPI mode. Cannot be written when XCH=1.

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Offset: 0x0008			Register Name: SPI_TCR
Bit	**Read/Write**	**Default/Hex**	**Description**
12	R/W	0x0	FBS First Transmit Bit Select 0: MSB first. The upper bits are transmitted first. 1: LSB first. The lower bits are transmitted first. Cannot be written when XCH=1.
11	R/W	0x0	SDC Master Sample Data Control Set this bit to '1' to make the internal read sample point with a delay of half-cycle of SPI_CLK. It is used in high speed read operation to reduce the error caused by the time delay of SPI_CLK between master and slave. 0: Normal operation, do not delay the internal read sample point 1: Delay the internal read sample point Cannot be written when XCH=1.
10	R/W	0x0	RPSM Rapids Mode Select Select rapid mode for high speed write. 0: Normal write mode 1: Rapid write mode Cannot be written when XCH=1.
9	R/W	0x0	DDB Dummy Burst Type 0: The bit value of dummy SPI burst is zero 1: The bit value of dummy SPI burst is one Cannot be written when XCH=1.
8	R/W	0x0	DHB Discard Hash Burst In master mode, it controls whether discarding unused SPI bursts 0: Receiving all SPI bursts in the BC period 1: Discard unused SPI bursts, only fetching the SPI bursts during the dummy burst period. The burst number is specified by TC. Cannot be written when XCH=1.

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Offset: 0x0008			Register Name: SPI_TCR
Bit	**Read/Write**	**Default/Hex**	**Description**
7	R/W	0x1	SS_LEVEL SPI Chip Select Level When control SS signal manually (SS_OWNER (SPI_TCR[6])==1), set this bit to '1' or '0' to control the level of SS signal. 0: Set SS to low 1: Set SS to high Cannot be written when XCH=1.
6	R/W	0x0	SS_OWNER SS Output Owner Select Usually, the controller sends the SS signal automatically with data together. When this bit is set to 1, the software must manually write SS_LEVEL (SPI_TCR[7]) to 1 or 0 to control the level of the SS signal. 0: SPI controller 1: Software Cannot be written when XCH=1.
5:4	R/W	0x0	SS_SEL SPI Chip Select Select one of four external SPI Master/Slave Devices 00: SPI_SS0 will be asserted 01: SPI_SS1 will be asserted 10: SPI_SS2 will be asserted 11: SPI_SS3 will be asserted Cannot be written when XCH=1.
3	R/W	0x0	SSCTL In master mode, this bit selects the output waveform for the SPI_SSx signal. Only valid when SS_OWNER (SPI_TCR[6])= 0. 0: SPI_SSx remains asserted between SPI bursts 1: Negate SPI_SSx between SPI bursts Cannot be written when XCH=1.
2	R/W	0x1	SPOL SPI Chip Select Signal Polarity Control 0: Active high polarity (0 = Idle) 1: Active low polarity (1 = Idle) Cannot be written when XCH=1.

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Offset: 0x0008			Register Name: SPI_TCR
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x1	CPOL SPI Clock Polarity Control 0: Active high polarity (0 = Idle) 1: Active low polarity (1 = Idle) Cannot be written when XCH=1.
0	R/W	0x1	CPHA SPI Clock/Data Phase Control 0: Phase 0 (Leading edge for sample data) 1: Phase 1 (Leading edge for setup data) Cannot be written when XCH=1.

10.4.6.3 0x0010 SPI Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: SPI_IER
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	/	/	/
13	R/W	0x0	SS_INT_EN SSI Interrupt Enable Chip select signal (SSx) from the valid state to the invalid state 0: Disable 1: Enable
12	R/W	0x0	TC_INT_EN Transfer Completed Interrupt Enable 0: Disable 1: Enable
11	R/W	0x0	TF_UDR_INT_EN TXFIFO Underrun Interrupt Enable 0: Disable 1: Enable
10	R/W	0x0	TF_OVF_INT_EN TX FIFO Overflow Interrupt Enable 0: Disable 1: Enable

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Offset: 0x0010			Register Name: SPI_IER
Bit	**Read/Write**	**Default/Hex**	**Description**
9	R/W	0x0	RF_UDR_INT_EN RXFIFO Underrun Interrupt Enable 0: Disable 1: Enable
8	R/W	0x0	RF_OVF_INT_EN RX FIFO Overflow Interrupt Enable 0: Disable 1: Enable
7	/	/	/
6	R/W	0x0	TF_FUL_INT_EN TX FIFO Full Interrupt Enable 0: Disable 1: Enable
5	R/W	0x0	TX_EMP_INT_EN TX FIFO Empty Interrupt Enable 0: Disable 1: Enable
4	R/W	0x0	TX_ERQ_INT_EN TX FIFO Empty Request Interrupt Enable 0: Disable 1: Enable
3	/	/	/
2	R/W	0x0	RF_FUL_INT_EN RX FIFO Full Interrupt Enable 0: Disable 1: Enable
1	R/W	0x0	RX_EMP_INT_EN RX FIFO Empty Interrupt Enable 0: Disable 1: Enable
0	R/W	0x0	RF_RDY_INT_EN RX FIFO Ready Request Interrupt Enable 0: Disable 1: Enable

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10.4.6.4 0x0014 SPI Interrupt Status Register (Default Value: 0x0000_0032)

Offset: 0x0014			Register Name: SPI_ISR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	/	/	/
13	R/W1C	0x0	SSI SS Invalid Interrupt When SSI is 1, it indicates that SS has changed from the valid state to the invalid state. Writing 1 to this bit clears it.
12	R/W1C	0x0	TC Transfer Completed In master mode, it indicates that all bursts specified by BC have been exchanged. In other conditions, when set, this bit indicates that all the data in TXFIFO has been loaded in the Shift register, and the Shift register has shifted out all the bits. Writing 1 to this bit clears it. 0: Busy 1: Transfer completed
11	R/W1C	0x0	TF_UDF TXFIFO Underrun This bit is set when the TXFIFO is underrun. Writing 1 to this bit clears it. 0: TXFIFO is not underrun 1: TXFIFO is underrun
10	R/W1C	0x0	TF_OVF TXFIFO Overflow This bit is set when the TXFIFO is overflowed. Writing 1 to this bit clears it. 0: TXFIFO is not overflowed 1: TXFIFO is overflowed
9	R/W1C	0x0	RX_UDF RXFIFO Underrun When set, this bit indicates that RXFIFO is underrun. Writing 1 to this bit clears it. 0: RXFIFO is not underrun 1: RXFIFO is underrun

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Offset: 0x0014			Register Name: SPI_ISR
Bit	**Read/Write**	**Default/Hex**	**Description**
8	R/W1C	0x0	RX_OVF RXFIFO Overflow When set, this bit indicates that RXFIFO is overflowed. Writing 1 to this bit clears it. 0: RXFIFO is not overflowed 1: RXFIFO is overflowed
7	/	/	/
6	R/W1C	0x0	TX_FULL TXFIFO Full This bit is set when the TXFIFO is full. Writing 1 to this bit clears it. 0: TXFIFO is not Full 1: TXFIFO is Full
5	R/W1C	0x1	TX_EMP TXFIFO Empty This bit is set when the TXFIFO is empty. Writing 1 to this bit clears it. 0: TXFIFO contains one or more words. 1: TXFIFO is empty
4	R/W1C	0x1	TX_READY TXFIFO Ready 0: TX_WL > TX_TRIG_LEVEL 1: TX_WL <= TX_TRIG_LEVEL This bit will be immediately set to 1 if TX_WL <= TX_TRIG_LEVEL. Writing “1” to this bit clears it. The TX_WL is the water level of TXFIFO.
3	/	/	/
2	R/W1C	0x0	RX_FULL RXFIFO Full This bit is set when the RXFIFO is full. Writing 1 to this bit clears it. 0: Not Full 1: Full
1	R/W1C	0x1	RX_EMP RXFIFO Empty This bit is set when the RXFIFO is empty. Writing 1 to this bit clears it. 0: Not empty 1: empty

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Offset: 0x0014			Register Name: SPI_ISR
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W1C	0x0	RX_RDY RXFIFO Ready 0: RX_WL < RX_TRIG_LEVEL 1: RX_WL >= RX_TRIG_LEVEL This bit will be immediately set to 1 if RX_WL >= RX_TRIG_LEVEL. Writing "1" to this bit clears it. The RX_WL is the water level of RXFIFO.

10.4.6.5 0x0018 SPI FIFO Control Register (Default Value: 0x0040_0001)

Offset: 0x0018			Register Name: SPI_FCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/WAC	0x0	TX_FIFO_RST TX FIFO Reset Writing '1' to this bit will reset the control portion of the TXFIFO and auto clear to '0' when completing the reset operation, writing '0' to this bit has no effect.
30	R/W	0x0	TF_TEST_ENB TX Test Mode Enable 0: Disable 1: Enable In normal mode, the TXFIFO can only be read by the SPI controller, writing '1' to this bit will switch the read and write function of TXFIFO to AHB bus. This bit is used to test the TXFIFO, do not set in normal operation, and do not set RF_TEST and TF_TEST at the same time.
29:25	/	/	/
24	R/W	0x0	TF_DRQ_EN TX FIFO DMA Request Enable 0: Disable 1: Enable
23:16	R/W	0x40	TX_TRIG_LEVEL TX FIFO Empty Request Trigger Level

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Offset: 0x0018			Register Name: SPI_FCR
Bit	**Read/Write**	**Default/Hex**	**Description**
15	R/WAC	0x0	RF_RST RXFIFO Reset Writing '1' to this bit will reset the control portion of the receiver FIFO, and auto clear to '0' when completing the reset operation, writing '0' to this bit has no effect.
14	R/W	0x0	RF_TEST RX Test Mode Enable 0: Disable 1: Enable In normal mode, the RXFIFO can only be written by the SPI controller, writing '1' to this bit will switch the read and write function of RXFIFO to AHB bus. This bit is used to test the RXFIFO, do not set in normal operation, and do not set RF_TEST and TF_TEST at the same time.
13:9	/	/	/
8	R/W	0x0	RF_DRQ_EN RXFIFO DMA Request Enable 0: Disable 1: Enable
7:0	R/W	0x1	RX_TRIG_LEVEL RXFIFO Ready Request Trigger Level

10.4.6.6 0x001C SPI FIFO Status Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: SPI_FSR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R	0x0	TB_WR TXFIFO Write Buffer Write Enable
30:28	R	0x0	TB_CNT TXFIFO Write Buffer Counter These bits indicate the number of words in TXFIFO Write Buffer
27:24	/	/	/

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Offset: 0x001C			Register Name: SPI_FSR
Bit	**Read/Write**	**Default/Hex**	**Description**
23:16	R	0x0	TF_CNT TXFIFO Counter These bits indicate the number of words in TXFIFO 0: 0 byte in TXFIFO 1: 1 byte in TXFIFO … 64: 64 bytes in TXFIFO other: Reserved
15	R	0x0	RB_WR RXFIFO Read Buffer Write Enable
14:12	R	0x0	RB_CNT RXFIFO Read Buffer Counter These bits indicate the number of words in RXFIFO Read Buffer
11:8	/	/	/
7:0	R	0x0	RF_CNT RXFIFO Counter These bits indicate the number of words in RXFIFO 0: 0 byte in RXFIFO 1: 1 byte in RXFIFO … 64: 64 bytes in RXFIFO other: Reserved

10.4.6.7 0x0020 SPI Wait Clock Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: SPI_WCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:20	/	/	/

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Offset: 0x0020			Register Name: SPI_WCR
Bit	**Read/Write**	**Default/Hex**	**Description**
19:16	R/W	0x0	SWC Dual mode direction switch wait clock counter (for master mode only). These bits control the number of wait states to be inserted before starting dual data transfer in dual SPI mode. The SPI module counts SPI_SCLK by SWC for delaying the next word data transfer. 0: No wait states inserted n: n SPI_SCLK wait states inserted Cannot be written when XCH=1.
15:0	R/W	0x0	WCC Wait Clock Counter (In master mode) These bits control the number of wait states to be inserted in data transfers. The SPI module counts SPI_SCLK by WCC for delaying the next word data transfer. 0: No wait states inserted n: n SPI_SCLK wait states inserted Cannot be written when XCH=1.

10.4.6.8 0x0028 SPI Sample Delay Control Register (Default Value: 0x0000_2000)

Offset: 0x0028			Register Name: SPI_SAMP_DL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15	R/W	0x0	SAMP_DL_CAL_START Sample Delay Calibration Start When set, it indicates that start sample delay chain calibration. Cannot be written when XCH=1.
14	R	0x0	SAMP_DL_CAL_DONE Sample Delay Calibration Done When set, it indicates that the sample delay chain calibration is done and the result of calibration is shown in SAMP_DL. Cannot be written when XCH=1.

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Offset: 0x0028			Register Name: SPI_SAMP_DL
Bit	**Read/Write**	**Default/Hex**	**Description**
13:8	R	0x20	SAMP_DL Sample Delay It indicates the number of delay cells corresponding to the current card clock. The delay time generated by these delay cells is equal to the cycle of the card clock nearly. Generally, it is necessary to do drive delay calibration when the card clock is changed. This bit is valid only when SAMP_DL_CAL_DONE is set. Cannot be written when XCH=1.
7	R/W	0x0	SAMP_DL_SW_EN Sample Delay Software Enable When set, it indicates that enable sample delay specified at SAMP_DL_SW. Cannot be written when XCH=1.
6	/	/	/
5:0	R/W	0x0	SAMP_DL_SW Sample Delay Software The relative delay between the clock line and command line, data lines. It can be determined according to the value of SAMP_DL, the cycle of the card clock, and the input timing requirement of the device. Cannot be written when XCH=1.

10.4.6.9 0x0030 SPI Master Burst Counter Register (Default Value: 0x0000_0000)

Offset: 0x0030			Register Name: SPI_MBC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/

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Offset: 0x0030			Register Name: SPI_MBC
Bit	Read/Write	Default/Hex	Description
23:0	R/W	0x0	MBC Master Burst Counter In master mode, this field specifies the total burst number which includes the TXD, RXD, and dummy burst. 0: 0 burst 1: 1 burst … N: N bursts Cannot be written when XCH=1.

10.4.6.10 0x0034 SPI Master Transmit Counter Register (Default Value: 0x0000_0000)

Offset: 0x0034			Register Name: SPI_MTC
Bit	Read/Write	Default/Hex	Description
31:24	/	/	/
23:0	R/W	0x0	MWTC Master Write Transmit Counter In master mode, this field specifies the burst number that should be sent to TXFIFO before automatically sending dummy bursts. For saving bus bandwidth, the dummy bursts (all zero bits or all one bits) are sent by SPI Controller automatically. 0: 0 burst 1: 1 burst … N: N bursts Cannot be written when XCH=1.

10.4.6.11 0x0038 SPI Master Burst Control Counter Register (Default Value: 0x0000_0000)

Offset: 0x0038			Register Name: SPI_BCC
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/

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Offset: 0x0038			Register Name: SPI_BCC
Bit	**Read/Write**	**Default/Hex**	**Description**
29	R/W	0x0	Quad_EN Quad_Mode_EN The Quad mode includes Quad-Input and Quad-Output. 0: Quad mode disable 1: Quad mode enable Cannot be written when XCH=1.
28	R/W	0x0	DRM Master Dual Mode RX Enable It is only valid when Quad_Mode_EN=0. 0: RX uses the single-bit mode 1: RX uses the dual mode Cannot be written when XCH=1.
27:24	R/W	0x0	DBC Master Dummy Burst Counter In master mode, this field specifies the burst number that should be sent before receiving in dual SPI mode. The data does not care by the device. 0: 0 burst 1: 1 burst … N: N bursts Cannot be written when XCH=1
23:0	R/W	0x0	STC Master Single Mode Transmit Counter In master mode, this field specifies the burst number that should be sent in the single mode before automatically sending dummy bursts. This is the first transmit counter in all bursts. 0: 0 burst 1: 1 burst … N: N bursts Cannot be written when XCH=1

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10.4.6.12 0x0040 SPI Bit-Aligned Transfer Configure Register (Default Value: 0x0000_00A0)

Offset: 0x0040			Register Name: SPI_BATC
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/WAC	0x0	TCE Transfer Control Enable In master mode, it is used to start to transfer the serial bits frame, it is only valid when Work Mode Select==0x10/0x11. 0: Idle 1: Initiates transfer Writing "1" to this bit will start to transfer serial bits frame (the value comes from the SPI TX Bit Register or SPI RX Bit Register), and will auto-clear after the bursts transfer completely. Writing '0' to this bit has no effect.
30	R/W	0x0	MSMS Master Sample Standard 0: Delay Sample Mode 1: Standard Sample Mode In Standard Sample Mode, the SPI master samples the data at the standard rising edge of SCLK for each SPI mode; In Delay Sample Mode, the SPI master samples data at the edge that is half cycle delayed by the standard rising edge of SCLK defined in respective SPI mode.
29:26	/	/	/
25	R/W1C	0x0	TBC Transfer Bits Completed When set, this bit indicates that the last bit of the serial data frame in SPI TX Bit Register (or SPI RX Bit Register) has been transferred completely. Writing 1 to this bit clears it. 0: Busy 1: Transfer Completed It is only valid when Work Mode Select==0x10/0x11.
24	R/W	0x0	TBC_INT_EN Transfer Bits Completed Interrupt Enable 0: Disable 1: Enable It is only valid when Work Mode Select==0x10/0x11.
23:22	/	/	/

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Offset: 0x0040			Register Name: SPI_BATC
Bit	**Read/Write**	**Default/Hex**	**Description**
21:16	R/W	0x00	RX_FEM_LEN Configure the length of serial data frame (burst) of RX 000000: 0 bit 000001: 1 bit … 100000: 32 bits Other values: reserved It is only valid when Work Mode Select==0x10/0x11, and cannot be written when TCE (SPI_BATC[31])=1.
15:14	/	/	/
13:8	R/W	0x00	TX_FEM_LEN Configure the length of serial data frame (burst) of TX 000000: 0 bit 000001: 1 bit … 100000: 32 bits Other values: reserved It is only valid when Work Mode Select==0x10/0x11, and cannot be written when TCE=1.
7	R/W	0x1	SS_LEVEL When control SS signal manually, set this bit to '1' or '0' to control the level of SS signal. 0: Set SS to low 1: Set SS to high It is only valid when Work Mode Select==0x10/0x11, and only work in Mode0, cannot be written when TCE=1.
6	R/W	0x0	SS_OWNER SS Output Owner Select Usually, the controller sends the SS signal automatically with data together. When this bit is set to 1, the software must manually write SS_LEVEL (SPI_BATC[7]) to 1 or 0 to control the level of the SS signal. 0: SPI controller 1: Software It is only valid when Work Mode Select==0x10/0x11, and only work in Mode0, cannot be written when TCE=1.

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Offset: 0x0040			Register Name: SPI_BATC
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R/W	0x1	SPOL SPI Chip Select Signal Polarity Control 0: Active high polarity (0 = Idle) 1: Active low polarity (1 = Idle) It is only valid when Work Mode Select==0x10/0x11, and only work in Mode0, cannot be written when TCE=1.
4	/	/	/
3:2	R/W	0x0	SS_SEL SPI Chip Select Select one of four external SPI Master/Slave Devices 00: SPI_SS0 will be asserted 01: SPI_SS1 will be asserted 10: SPI_SS2 will be asserted 11: SPI_SS3 will be asserted It is only valid when Work Mode Select==0x10/0x11, and only work in Mode0, cannot be written when TCE=1.
1:0	R/W	0x0	WMS Work Mode Select 00: Data frame is byte aligned in standard SPI, dual-output/dual input SPI, dual IO SPI, and quad-output/quad-input SPI 01: Reserved 10: Data frame is bit aligned in 3-wire SPI 11: Data frame is bit aligned in standard SPI

10.4.6.13 0x0044 SPI Bit-Aligned Clock Configuration Register (Default Value: 0x0000_0000)

Offset: 0x0044			Register Name: SPI_BA_CCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x0	CDR_N Clock Divide Rate (Master Mode Only) The SPI_SCLK is determined according to the following equation: SPI_CLK = Source_CLK / (2*(CDR_N + 1)). This register is only valid when Work Mode Select==0x10/0x11.

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10.4.6.14 0x0048 SPI TX Bit Register (Default Value: 0x0000_0000)

Offset: 0x0048			Register Name: SPI_TBR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	VTB The Value of the Transmit Bits This register is used to store the value of the transmitted serial data frame. In the process of transmission, the LSB is transmitted first. This register is only valid when Work Mode Select==0x10/0x11.

10.4.6.15 0x004C SPI RX Bit Register (Default Value: 0x0000_0000)

Offset: 0x004C			Register Name: SPI_RBR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	VRB The Value of the Receive Bits This register is used to store the value of the received serial data frame. In the process of transmission, the LSB is transmitted first. This register is only valid when Work Mode Select==0x10/0x11.

10.4.6.16 0x0088 SPI Normal DMA Mode Control Register (Default Value: 0x0000_00E5)

Offset: 0x0088			Register Name: SPI_NDMA_MODE_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:6	R/W	0x11	SPI_ACT_M SPI NDMA Active Mode 00: dma_active is low 01: dma_active is high 10: dma_active is controlled by dma_request (DRQ) 11: dma_active is controlled by controller
5	R/W	0x1	SPI_ACK_M SPI NDMA Acknowledge Mode 0: active fall do not care ack 1: active fall must after detect ack is high

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Offset: 0x0088			Register Name: SPI_NDMA_MODE_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
4:0	R/W	0x05	SPI_DMA_WAIT Delay Cycles The counts of hold cycles from DMA last signal high to dma_active high

10.4.6.17 0x0100 DBI Control Register 0 (Default Value: 0x0010_0000)

Offset: 0x0100			Register Name: DBI_CTL_0
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	CMDT Command Type 0: Write Command 1: Read Command
30:20	R/W	0x1	WCDC Write Command Dummy Cycles Controls dummy cycles between two write commands Range 1~255 Default Condition: there is a dbi_clk cycle between each command or parameter.
19	R/W	0x0	DAT_SEQ Output Data Sequence 0: MSB First 1: LSB First
18:16	R/W	0x0	RGB_SEQ Output RGB Sequence 000: RGB 001: RBG 010: GRB 011: GBR 100: BRG 101: BGR 110, 111: Reserved

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Offset: 0x0100			Register Name: DBI_CTL_0
Bit	**Read/Write**	**Default/Hex**	**Description**
15	R/W	0x0	TRAN_MOD Transmit Mode 0: Command/Parameter 1: Video
14:12	R/W	0x0	DAT_FMT Output Data Format 000: RGB111 001: RGB444 010: RGB565 011: RGB666 100: RGB888 (only for 2 Data Lane Interface) 101~111: Reserved
11	/	/	/
10:8	R/W	0x0	DBI Interface 000: 3 Line Interface I 001: 3 Line Interface II 010: 4 Line Interface I 011: 4 Line Interface II 100: 2 Data Lane Interface

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Offset: 0x0100			Register Name: DBI_CTL_0
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0x0	RGB_Source_Format When video_source_type is RGB32 (DBI_CTL_0[bit0] = 0) 0000: RGB 0001: RBG 0010: GRB 0011: GBR 0100: BRG 0101: BGR Others: Reserved When video_source_type is RGB16 (DBI_CTL_0[bit0] = 1) 0000: RGB 0001~0100: Reserved 0101: BGR 0110: GRBG_0 {G[5:3]R[4:0]B[4:0]G[2:0]} 0111: GBRG_0 {G[5:3]B[4:0]R[4:0]G[2:0]} 1000: GRBG_1 {G[2:0]R[4:0]B[4:0]G[5:3]} 1001: GBRG_1 {G[2:0]B[4:0]R[4:0]G[5:3]} Others: Reserved
3	R/W	0x0	DUM_VAL Dummy Cycle Value Output Value During Dummy Cycle
2	R/W	0x0	RGB_BO RGB Bit Order 0: Remain the sequence of RGB data 1: Swap the higher bit and the lower bit for each component of DRAM RGB
1	R/W	0x0	ELEMENT_A_POS Element A Position Only for RGB32 Data Format 0: A component is in the bit[31:24] of data source 1: A component is in the bit[7:0] of data source
0	R/W	0x0	VI_SRC_TYPE Video Source Type 0: RGB32 1: RGB16

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10.4.6.18 0x0104 DBI Control Register 1 (Default Value: 0x0000_0001)

Offset: 0x0104			Register Name: DBI_CTL_1
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/WAC	0x0	DBI_SOFT_TRG DBI soft trigger It is only available for software trigger mode. Writing '1' to this bit will start DBI TX module and auto clear to '0' when completing start operation, writing '0' to this bit has no effect.
30:29	R/W	0x0	DBI EN MODE SEL DBI Enable Mode Select 00: Always on DBI mode 01: Software trigger mode 10: Timer trigger mode 11: TE trigger mode
28	/	/	/
27:26	R/W	0x0	RGB666_FMT 2 Data Lane RGB666 Format 00: Normal Format 01: Special Format for ILITEK 10: Special Format for New Vision
25	R/W	0x0	DBI_RXCLK_INV DBI rx clock inverse 0: Sample data by using the positive edge of the output clock 1: Sample data by using the negative edge of the output clock
24	R/W	0x0	DBI_CLKO_MOD DBI output clock mode 0: DBI clock always on (DCX Setup/hold equals one clock cycle) 1: DBI clock auto gating (DCX Setup/hold equals to a half clock cycle)

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Offset: 0x0104			Register Name: DBI_CTL_1
Bit	**Read/Write**	**Default/Hex**	**Description**
23	R/W	0x0	DBI_CLKO_INV DBI clock output inverse **When the bit24 (DBI output clock mode) is 0.** 0: The falling edge releases the CSX signal, and the falling edge releases data 1: The rising edge releases the CSX signal, and the rising edge releases data **When the bit24 (DBI output clock mode) is 1.** 0: The rising edge releases the CSX signal, and the falling edge releases data 1: The falling edge releases the CSX signal, and the rising edge releases data
22	R/W	0x0	DCX_DATA DCX Data Value 0: DCX Value equal to 0 1: DCX Value equal to 1
21	R/W	0x0	RGB 16 Data Source Select RGB 16 Data Source Select 0: Pixel1 is stored in the higher bit of address, and Pixel0 is stored in the lower bit of address 1: Pixel0 is stored in the higher bit of address, and Pixel1 is stored in the lower bit of address
20	R/W	0x0	RDAT_LSB Bit Order of Read Data 0: A reading data is the higher bit 1: A reading data is the lower bit
19:16	/	/	/
15:8	R/W	0x0	RCDC Read Command Dummy Cycles The dummy cycle between the read command and read data Reading 1-byte (8 bits) data has not dummy cycle.
7:0	R/W	0x1	RDBN Read Data Number of Bytes Sample Bytes data based on configuration.

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10.4.6.19 0x0108 DBI Control Register 2 (Default Value: 0x0000_4000)

Offset: 0x0108			Register Name: DBI_CTL_2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/
15	R/W	0x0	DBI_FIFO_DRQ_EN DBI FIFO DMA Request Enable 0: Disable 1: Enable
14:8	R/W	0x40	DBI_TRIG_LEVEL DBI FIFO Empty Request Trigger Level
7	/	/	/
6	R/W	0x0	DBI_SDI_OUT_SEL DBI SDI PIN Output Select The signal is used with the DBI SDI PIN Function Sel bit. 0: Output WRX (When DBI DCX PIN Function Sel = 0, the SDI pin outputs data) 1: Output DCX
5	R/W	0x0	DBI_DCX_SEL DBI DCX PIN Function Select 0: DBI DCX Function 1: WRX (2 Data Lane Interface)
4:3	R/W	0x0	DBI_SDI_SEL DBI SDI PIN Function Select 00: DBI_SDI (Interface II) 01: DBI_TE 10: DBI_DCX 11: Reserved
2	R/W	0x0	TE_DBC_SEL TE debounce function select 0: debounce 1: no-debounce
1	R/W	0x0	TE_TRIG_SEL TE edge trigger select 0: TE rising edge 1: TE falling edge
0	R/W	0x0	TE_EN TE enable 0: TE Disable 1: TE Enable

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10.4.6.20 0x010C DBI Timer Control Register (Default Value: 0x0000_0000)

Offset: 0x010C			Register Name: DBI_Timer
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	DBI_TM_EN DBI Timer Enable 0: Enable 1: Disable
30:0	R/W	0x0	DBI Timer Value It sets the time interval between sending data twice, which is frame blanking. It is used to set the time at which the interrupt of the DBI Timer is triggered. When the Timer_EN is 1, the timer starts to count (the clock of the counting is SCLK), and the counter reaches the target value to trigger the Timer_INT of DBI, the data will start to send in series. **Note: Do not count when sending the series data.**

10.4.6.21 0x0110 DBI Video Size Register (Default Value: 0x01E0_0140)

Offset: 0x0110			Register Name: DBI_Video_Size
Bit	**Read/Write**	**Default/Hex**	**Description**
31:27	/	/	/
26:16	R/W	0x1E0	V_SIZE It is used to generate the Frame int.
15:11	/	/	/
10:0	R/W	0x140	H_SIZE It is used to generate the Line int.

10.4.6.22 0x0120 DBI Interrupt Register (Default Value: 0x0000_4000)

Offset: 0x0120			Register Name: DBI_INT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:15	/	/	/

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Offset: 0x0120			Register Name: DBI_INT
Bit	**Read/Write**	**Default/Hex**	**Description**
14	R/W1C	0x1	DBI_FIFO_EMPTY_INT DBI FIFO Empty Interrupt Status 0: DBI_FIFO is not empty 1: DBI_FIFO is empty
13	R/W1C	0x0	DBI_FIFO_FULL_INT DBI FIFO Full Interrupt Status 0: DBI_FIFO is not full 1: DBI_FIFO is full
12	R/W1C	0x0	TIMER_INT It indicates that the timer has been count sclk cycles to the value of DBI_Timer Register[30:0]. Writing 1 to this bit clears it. 0: Timer has not been achieved the objective 1: Timer has been achieved the objective
11	R/W1C	0x0	RD_DONE_INT It indicates that the number of byte setting in DBI_Control Register 1[19:8] has been read. Writing 1 to this bit clears it. 0: All data has not been read 1: All data has been read
10	R/W1C	0x0	TE_INT It indicates that the TE signal has been changed. Writing 1 to this bit clears it. 0: TE signal has not been changed 1: TE signal has been changed
9	R/W1C	0x0	FRAM_DONE_INT It indicates that a frame video data has been sent. Writing 1 to this bit clears it. 0: A frame video has not been sent 1: A frame video has been sent
8	R/W1C	0x0	LINE_DONE_INT It indicates that a line of video data has been sent. Writing 1 to this bit clears it. 0: A line of video data has not been sent 1: A line of video data has been sent
7	/	/	/

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Offset: 0x0120			Register Name: DBI_INT
Bit	**Read/Write**	**Default/Hex**	**Description**
6	R/W	0x0	DBI_FIFO_EMPTY_INT_EN DBI FIFO Empty Interrupt Enable 0: Disable 1: Enable
5	R/W	0x0	DBI_FIFO_FULL_INT_EN DBI FIFO Full Interrupt Enable 0: Disable 1: Enable
4	R/W	0x0	TIMER_INT_EN Timer Interrupt Enable 0: Disable 1: Enable
3	R/W	0x0	RD_DONE_INT_EN Read Done Interrupt Enable 0: Disable 1: Enable
2	R/W	0x0	TE_INT_EN TE Interrupt Enable 0: Disable 1: Enable
1	R/W	0x0	FRAM_DONE_INT_EN Frame Done Interrupt Enable 0: Disable 1: Enable
0	R/W	0x0	LINE_DONE_INT_EN Line Done Interrupt Enable 0: Disable 1: Enable

10.4.6.23 0x0124 DBI Debug Register 0 (Default Value: 0x007F_0000)

Offset: 0x0124			Register Name: DBI_Debug_0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:23	/	/	/

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Offset: 0x0124			Register Name: DBI_Debug_0
Bit	**Read/Write**	**Default/Hex**	**Description**
22:16	R	0x7F	DBI_FIFO_AVAIL DBI_FIFO ROOM VALID 0~127 Words
15:13	/	/	/
12	R	0x0	TE_VAL TE input value 0: TE not Trigger 1: TE Trigger
11:8	R	0x0	DBI_RXCS FSM for DBI Receive RX_BS0 ~ RX_BS6 , Gray - Code
7:4	R	0x0	SH_CS FSM for shifter 0~11 : SH0~SH11
3:2	/	/	DBI_TXCS FSM for DBI Transmit 00: IDLE 01: SHIF 10: DUMY 11: READ
1:0	R	0x0	MEM_CS FSM for DBI Memory 00: IDLE_FRM 01: FRM_POS 10: FRM_RDY

10.4.6.24 0x0128 DBI Debug Register 1 (Default Value: 0x0000_0000)

Offset: 0x0128			Register Name: DBI_Debug_1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/
25:16	R	0x0	LCNT Line counter The number of pixel lines that are currently sent
15:12	/	/	/

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Offset: 0x0128			Register Name: DBI_Debug_1
Bit	**Read/Write**	**Default/Hex**	**Description**
11:0	R	0x0	CCNT Component counter The number of RGB components that are currently sent The field is equal to pixel_cnt *3.

10.4.6.25 0x0200 SPI TX Data Register (Default Value: 0x0000_0000)

Offset: 0x0200			Register Name: SPI_TXD
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TDATA Transmit Data This register can be accessed in the byte, half-word, or word unit by AHB. In the byte accessing method, if there are rooms in TXFIFO, one burst data is written to TXFIFO and the depth is increased by 1. In the half-word accessing method, two SPI burst data are written and the TXFIFO depth is increased by 2. In the word accessing method, four SPI burst data are written and the TXFIFO depth is increased by 4. **Note: This address is writable-only if TF_TEST is '0', and if TF_TEST is set to '1', this address is readable and writable to test the TX FIFO through the AHB bus.**

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10.4.6.26 0x0300 SPI RX Data Register (Default Value: 0x0000_0000)

Offset: 0x0300			Register Name: SPI_RXD
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	RDATA Receive Data This register can be accessed in the byte, half-word, or word unit by AHB. In the byte accessing method, if there are data in RXFIFO, the top word is returned and the RXFIFO depth is decreased by 1. In the half-word accessing method, two SPI bursts are returned and the RXFIFO depth is decreased by 2. In the word accessing method, the four SPI bursts are returned and the RXFIFO depth is decreased by 4. **Note: This address is readable-only if RF_TEST is '0', and if RF_TEST is set to '1', this address is readable and writable to test the RX FIFO through the AHB bus.**

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10.5 USB2.0 DRD

10.5.1 Overview

The USB2.0 dual-role device (USB2.0 DRD) supports both device and host functions which can also be configured as a Host-only or Device-only controller. It complies with the USB2.0 Specification.

For saving CPU bandwidth, the DMA interface of the DRD module can also support the external DMA controller to do the data transfer between the memory and the DRD FIFO. The DRD core also supports USB power saving functions.

The USB2.0 DRD has the following features:

- Complies with USB2.0 Specification
- Supports USB Host function
  - Compatible with Enhanced Host Controller Interface (EHCI) Specification, Version 1.0
  - Compatible with Open Host Controller Interface (OHCI) Specification, Version 1.0a
  - Supports High-Speed (HS, 480 Mbit/s), Full-Speed (FS, 12 Mbit/s), and Low-Speed (LS, 1.5 Mbit/s)
  - Supports only 1 USB Root port shared between EHCI and OHCI
- Supports USB Device function
  - Supports High-Speed (HS, 480 Mbit/s), Full-Speed (FS, 12 Mbit/s)
  - Supports bi-directional endpoint0 (EP0) for Control transfer
  - Up to 10 user-configurable endpoints (EP1+, EP1-, EP2+, EP2-, EP3+, EP3-, EP4+, EP4-, EP5+, EP5-) for Bulk transfer, Isochronous transfer and Interrupt transfer
  - Up to (8 KB + 64 Bytes) FIFO for all EPs (including EP0)
  - Supports interface to an external Normal DMA controller for every EP
- Supports an internal DMA controller for data transfer with memory
- Supports High-Bandwidth Isochronous & Interrupt transfers
- Automated splitting/combining of packets for Bulk transfers
- Supports point-to-point and point-to-multipoint transfer in both Host and Peripheral modes
- Includes automatic ping capabilities
- Soft connect/disconnect function
- Performs all transaction scheduling in hardware

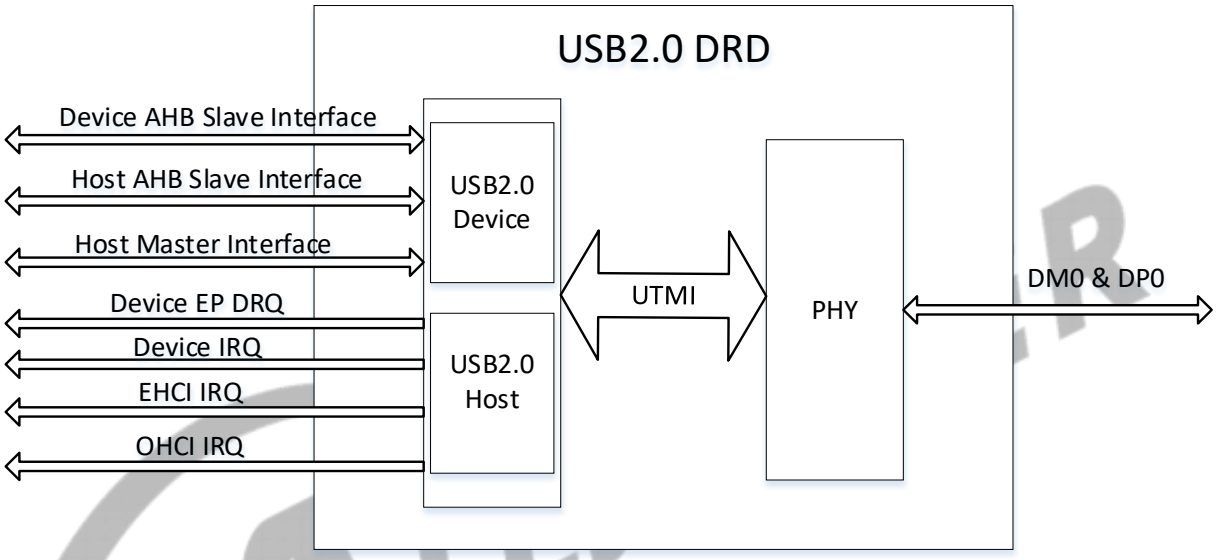
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- Power optimization and power management capabilities
- Device and host controller share a 8K SRAM and a physical PHY

10.5.2 Block Diagram

The following figure shows the block diagram of USB2.0 DRD Controller.

Figure 10-63 USB2.0 DRD Controller Block Diagram



10.5.3 Functional Description

10.5.3.1 External Signals

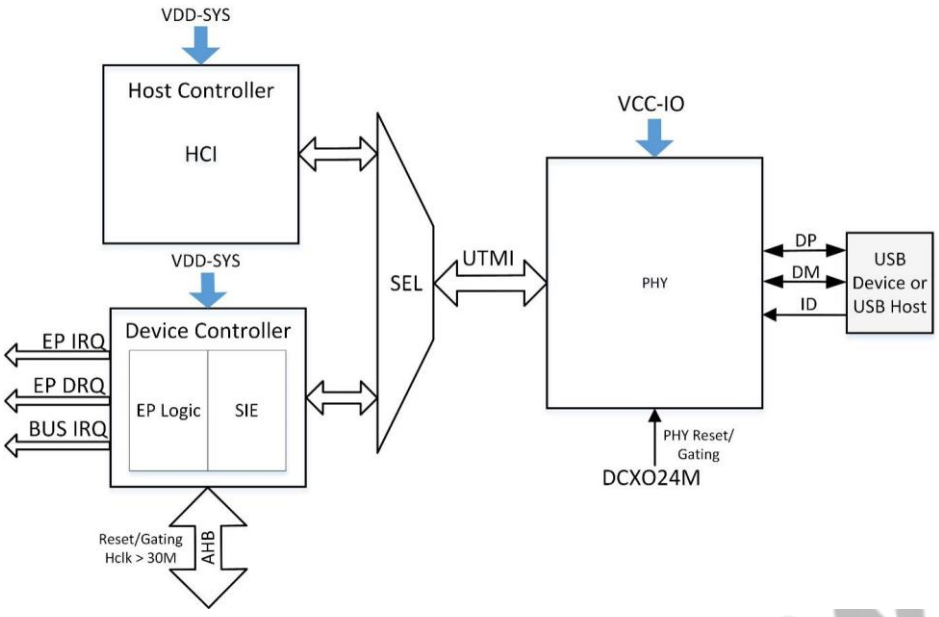
Table 10-18 USB2.0 DRD External Signals

Signal	Description	Type
USB0-DP	USB2.0 DRD differential signal positive	AI/O
USB0-DM	USB2.0 DRD differential signal negative	AI/O

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10.5.3.2 Controller and PHY Connection Diagram

Figure 10-64 USB2.0 DRD Controller and PHY Connection Diagram



10.5.4 Register List

Module Name	Base Address	Comments
USB_DRD_DEVICE	0x04100000	USB Device Controller
USB_DRD_HOST	0x04101000	USB Host Controller

Register Name	Offset	Description
USB_DRD_DEVICE		
USB_EPFIFOn	0x0000+N*0x0004 (N=0,1,2,3,4,5)	USB FIFO Entry for Endpoint N
USB_GCS	0x0040	USB Global Control and Status Register
USB_EPINTF	0x0044	USB Endpoint Interrupt Flag Register
USB_EPINTE	0x0048	USB Endpoint Interrupt Enable Register
USB_BUSINTF	0x004C	USB Bus Interrupt Flag Register
USB_BUSINTE	0x0050	USB Bus Interrupt Enable Register
USB_FNUM	0x0054	USB Frame Number Register
USB_TESTC	0x007C	USB Test Control Register
USB_CSR0	0x0080	USB EP0 Control and Status Register
USB_TXCSR	0x0080	USB EP1~5 Tx Control and Status Register

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Register Name	Offset	Description
USB_RXCSR	0x0084	USB EP1~5 Rx Control and Status Register
USB_COUNT0	0x0088	USB EP0 Rx Counter Register
USB_RXCOUNT	0x0088	USB EP1~5 Rx Counter Register
USB_ATTR0	0x008C	USB EP0 Attribute Register
USB_EPATTR	0x008C	USB EP1~5 Attribute Register
USB_TXFIFO	0x0090	USB EP1~5 TxFIFO Setting Register
USB_RXFIFO	0x0094	USB EP1~5 RxFIFO Setting Register
USB_FADDR	0x0098	USB Function Address Register
USB_ISCR	0x0400	USB Interface Status and Control Register
USB_PHY_CTL	0x0404	USB PHY Control Register
USB_PHY_TEST	0x0414	USB PHY Test Register
USB_PHY_TUNE	0x0418	USB PHY Tune Register
USB_PHY_SEL	0x0420	USB PHY Select Register
USB_PHY_STA	0x0424	USB PHY Status Register
USB_DMA_INTE	0x0500	USB DMA Interrupt Enable Register
USB_DMA_INTS	0x0504	USB DMA Interrupt Status Register
USB_DMA_CHAN_CFG	0x0540 + N*0x0010 (N = 0 to 7)	USB DMA Channel Configuration Register
USB_DMA_SDRAM_ADD	0x0544 + N*0x0010 (N = 0 to 7)	USB DMA SDRAM Start Address Register
USB_DMA_BC	0x0548 + N*0x0010 (N = 0 to 7)	USB DMA Byte Counter Register
USB_DMA_RESIDUAL_BC	0x0548 + N*0x0010 (N = 0 to 7)	USB DMA RESIDUAL Byte Counter Register
USB_DRD_HOST		
E_CAPLENGTH	0x0000	EHCI Identification Register
E_HCIVERSION	0x0002	EHCI Host Interface Version Number Register
E_HCSPARAMS	0x0004	EHCI Host Control Structural Parameter Register
E_HCCPARAMS	0x0008	EHCI Host Control Capability Parameter Register
E_HCSPPORTROUTE	0x000C	EHCI Companion Port Route Description
E_USBCMD	0x0010	EHCI USB Command Register

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Register Name	Offset	Description
E_USBSTS	0x0014	EHCI USB Status Register
E_USBINTR	0x0018	EHCI USB Interrupt Enable Register
E_FRINDEX	0x001C	EHCI USB Frame Index Register
E_PERIODICLISTBASE	0x0024	EHCI Periodic Frame List Base Address Register
E_ASYNCLISTADDR	0x0028	EHCI Current Asynchronous List Address Register
E_CONFIGFLAG	0x0050	EHCI Configured Flag Register
E_PORTSC	0x0054	EHCI Port Status and Control Register
O_HcRevision	0x0400	OHCI Revision Register
O_HcControl	0x0404	OHCI Control Register
O_HcCommandStatus	0x0408	OHCI Command Status Register
O_HcInterruptStatus	0x040C	OHCI Interrupt Status Register
O_HcInterruptEnable	0x0410	OHCI Interrupt Enable Register
O_HcInterruptDisable	0x0414	OHCI Interrupt Disable Register
O_HcHCCA	0x0418	OHCI HCCA Register
O_HcPeriodCurrentED	0x041C	OHCI Period Current ED Register
O_HcControlHeadED	0x0420	OHCI Control Head ED Register
O_HcControlCurrentED	0x0424	OHCI Control Current ED Register
O_HcBulkHeadED	0x0428	OHCI Bulk Head ED Register
O_HcBulkCurrentED	0x042C	OHCI Bulk Current ED Register
O_HcDoneHead	0x0430	OHCI Done Head Register
O_HcFmInterval	0x0434	OHCI Frame Interval Register
O_HcFmRemaining	0x0438	OHCI Frame Remaining Register
O_HcFmNumber	0x043C	OHCI Frame Number Register
O_HcPerioddicStart	0x0440	OHCI Periodic Start Register
O_HcLSThreshold	0x0444	OHCI LS Threshold Register
O_HcRhDescriptorA	0x0448	OHCI Root Hub DescriptorA Register
O_HcRhDesriptorB	0x044C	OHCI Root Hub DescriptorB Register
O_HcRhStatus	0x0450	OHCI Root Hub Status Register
O_HcRhPortStatus	0x0454	OHCI Root Hub Port Status Register
USB_CTRL	0x0800	HCI Interface Register
HCI_CTRL3	0x0808	HCI Control 3 Register
PHY_CTRL	0x0810	PHY Control Register
PHY_STA	0x0824	PHY Status Register
USB_SPDCR	0x0828	HCI SIE Port Disable Control Register

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Register Name	Offset	Description
USB_HCIVER	0x0830	USB Version Number Register

10.5.5 USB_DRD_Device Register Description

10.5.5.1 0x0000 + N*0x0004 (N = 0 to 5) USB FIFO Entry for Endpoint N (Default Value: 0x0000_0000)

Offset: 0x0000 + N*0x0004 (N = 0 to 5)			Register Name: USB_EPFIFOn
Bit	Read/Write	Default/Hex	Description
31:0	R/W	UDF	EPnFIFO FIFO Entry for Endpoint n

10.5.5.2 0x0040 USB Global Control and Status Register (Default Value: 0x0000_0020)

Offset: 0x0040			Register Name: USB_GCS
Bit	Read/Write	Default/Hex	Description
31	R/W	0	TX_EDMA 1'b0: DMA_REQ signal for all IN Endpoints will be de-asserted when MAXP bytes have been written to and endpoint. This is late mode. 1'b1: DMA_REQ signal for all IN Endpoints will be de-asserted when MAXP-8 bytes have been written to an endpoint. This is early mode.
30	R/W	0	RX_EDMA 1'b0: DMA_REQ signal for all OUT Endpoints will be de-asserted when MAXP bytes have been read to an endpoint. This is late mode. 1'b1: DMA_REQ signal for all OUT Endpoints will be de-asserted when MAXP-8 bytes have been read to and endpoint. This is early mode.
29	/	/	/
28:25	R/W	0	Reserved
24	R/W	0	FIFO_BUS_SEL 0: CPU bus for FIFO Access, 1: DMA bus for FIFO operation.
23:20	/	/	/
19:16	R/W	0x0	EPIND Endpoint Index

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<table>
<tr><td colspan="3">Offset: 0x0040</td><td>Register Name: USB_GCS</td></tr>
<tr><td>Bit</td><td>Read/Write</td><td>Default/Hex</td><td>Description</td></tr>
<tr><td></td><td></td><td></td><td>Index is a 4-bit register that determines which endpoint control/status registers are accessed. Before accessing an endpoint’s control/status registers at 0x0080~0x00BF, the endpoint number should be written to the Index register to ensure that correct control/status registers in the memory map.
Note: The valid value for Index register is 0-4.</td></tr>
<tr><td>15</td><td>R</td><td>0</td><td>BDev
B-Device
0 => ‘A’ device;
1 => ‘B’ device;
Only valid while a session is in progress.
Note: If the core is in Force_Host mode (i.e. a session has been started with USB_TMCTL.7=1), this bit will indicate the state of the HOSTDISCON input signal from the PHY.</td></tr>
<tr><td>14:13</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>12:11</td><td>R</td><td>0x0</td><td>VBus
These bits encode the current VBus level as follows:
<table>
<tr><td>D4</td><td>D3</td><td>Meaning</td></tr>
<tr><td>0</td><td>0</td><td>Below SessionEnd</td></tr>
<tr><td>0</td><td>1</td><td>Above SessionEnd, below AValid</td></tr>
<tr><td>1</td><td>0</td><td>Above AValid, below VBusValid</td></tr>
<tr><td>1</td><td>1</td><td>Above VBusValid</td></tr>
</table></td></tr>
<tr><td>10</td><td>R</td><td>0</td><td>HostMode
Host Mode
This bit is set when the USB/DRD is acting as a Host.</td></tr>
<tr><td>9</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>8</td><td>R/W</td><td>0</td><td>Session
When operating as an ‘A’ device, this bit is set or cleared by the CPU to start or end a session.
When operating as an ‘B’ device, this bit is set/cleared by the USB/DRD when a session starts/ends. It is also set by the CPU to initiate the Session Request Protocol.
When the USB/DRD is in Suspend mode, the bit may be cleared by the CPU to perform a software disconnect. Note: Clearing this bit when the core is not suspending will result in undefined behavior.</td></tr>
<tr><td>7</td><td>R/W</td><td>0</td><td>IsoUpdateEn
Isochronous Update Enable</td></tr>
</table>

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Offset: 0x0040			Register Name: USB_GCS
Bit	**Read/Write**	**Default/Hex**	**Description**
			When set by the CPU, the USB/DRD will wait for an SOF token from the Tx packet ready before sending the packet. If an IN token is received before an SOF token, then a zero length data packet will be send. **Note: This bit only affects endpoints performing Isochronous transfer.**
6	R/W	0	SoftConn Soft Connect The USB D+/D- line is enabled when this bit is set by CPU and tri-stated when this bit is cleared by CPU. **Note: Only valid in Peripheral Mode (but not means 'B' Device).**
5	R/W	1	HSEN High-speed Mode Enable When set by CPU , the USB/DRD will negotiate for High-speed mode when the device is reset by host. If not set, the device will only operate in Full-speed mode.
4	R	0	HSFLAG High-speed Mode Flag When set, this read-only bit indicates High-speed mode successfully negotiated during USB reset. And this bit becomes valid when USB Reset completes (as indicated by USB reset interrupt).
3	R	0	Reset This bit is set when Reset Signaling is present on the bus.
2	R/W	0	Resume Set by the CPU to generate Resume signaling when the function is in Suspend mode. The CPU should clear this bit after 10 ms (a maximum of 15 ms) to end Resume signaling.
1	R	0	SuspendM Suspend Mode This bit is set on entry into Suspend mode.
0	R/W	0	SuspendMEn Enable SuspendM Set by the CPU to enable the SUSPENDM output of UTMI+ bus.

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10.5.5.3 0x0044 USB Endpoint Interrupt Flag Register (Default Value: 0x0000_0000)

Offset: 0x0044			Register Name: USB_EPINTF
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21	R	0	EP5Rx Rx Endpoint 5 interrupt flag
20	R	0	EP4Rx Rx Endpoint 4 interrupt flag
19	R	0	EP3Rx Rx Endpoint 3 interrupt flag
18	R	0	EP2Rx Rx Endpoint 2 interrupt flag
17	R	0	EP1Rx Rx Endpoint 1 interrupt flag
16:6	/	/	/
5	R	0	EP5Tx Tx Endpoint 5 interrupt flag
4	R	0	EP4Tx Tx Endpoint 4 interrupt flag
3	R	0	EP3Tx Tx Endpoint 3 interrupt flag
2	R	0	EP2Tx Tx Endpoint 2 interrupt flag
1	R	0	EP1Tx Tx Endpoint 1 interrupt flag
0	R	0	EP0 Endpoint 0 interrupt flag

10.5.5.4 0x0048 USB Endpoint Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x0048			Register Name: USB_EPINTE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:22	/	/	/
21	R/W	0	EP5Rx Rx Endpoint 5 interrupt enable
20	R/W	0	EP4Rx

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			Rx Endpoint 4 interrupt enable
19	R/W	0	EP3Rx Rx Endpoint 3 interrupt enable
18	R/W	0	EP2Rx Rx Endpoint 2 interrupt enable
17	R/W	0	EP1Rx Rx Endpoint 1 interrupt enable
16:6	/	/	/
5	R/W	0	EP5Tx Tx Endpoint 5 interrupt enable
4	R/W	0	EP4Tx Tx Endpoint 4 interrupt enable
3	R/W	0	EP3Tx Tx Endpoint 3 interrupt enable
2	R/W	0	EP2Tx Tx Endpoint 2 interrupt enable
1	R/W	0	EP1Tx Tx Endpoint 1 interrupt enable
0	R/W	0	EP0 Endpoint 0 interrupt enable

10.5.5.5 0x004C USB Bus Interrupt Flag Register (Default Value: 0x0000_0000)

Offset: 0x004C			Register Name: USB_BUSINTF
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R	0	VBusError Set when VBus drops below the VBus Valid threshold during a session. **Note: Only valid when USB/DRD is 'A' device.**
6	R	0	SessionRequest Set when Session Request signaling has been detected. **Note: Only valid when USB/DRD is 'A' device.**
5	R	0	Disconnect Set in Host mode when a device disconnect is detected. Set in Peripheral mode when a session ends. **Note: Valid at all transaction speeds.**
4	R	0	Connect

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Offset: 0x004C			Register Name: USB_BUSINTF
Bit	**Read/Write**	**Default/Hex**	**Description**
			Set in host mode when a device connection is detected. **Note: Only valid in Host mode. Valid at all transaction speeds.**
3	R	0	SOF Set when a new frame starts.
2	R	0	ResetBabble Reset Set in Peripheral mode when Reset signaling is detected on the bus. Babble Set in Host mode when babble is detected. Note: Only active after first SOF has been sent.
1	R	0	Resume Set when Resume signaling is detected on the bus while the USB/DRD is in Suspend mode.
0	R	0	Suspend Set when Suspend signaling is detected on the bus. Note: Only valid in Peripheral mode.

10.5.5.6 0x0050 USB Bus Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x0050			Register Name: USB_BUSINTE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0	VBusError VBusError interrupt enable
6	R/W	0	Session Request Session Request interrupt enable
5	R/W	0	Disconnect Disconnect interrupt enable
4	R/W	0	Connect Connect interrupt enable
3	R/W	0	SOF SOF interrupt enable
2	R/W	0	ResetBabble Reset Reset interrupt enable Babble

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Offset: 0x0050			Register Name: USB_BUSINTE
Bit	**Read/Write**	**Default/Hex**	**Description**
			Babble interrupt enable
1	R/W	0	Resume Resume interrupt enable
0	R/W	0	Suspend Suspend interrupt enable

10.5.5.7 0x0054 USB Frame Number Register (Default Value: 0x0000_0000)

Offset: 0x0054			Register Name: USB_FNUM
Bit	**Read/Write**	**Default/Hex**	**Description**
31:11	/	/	/
10:0	R	0x000	FRNUM Frame Number Hold the last received frame number.

10.5.5.8 0x007C USB Test Control Register (Default Value: 0x0000_0000)

Offset: 0x007C			Register Name: USB_TESTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	0	/
23:16	R	/	FSM USB Operation Finite State Machine for Debug
15:11	/	/	/
10	R/W	0	EXTRXACT Extend Rx Active Signal for safe
9	R/W	0	RESUME_SE0 Resume from SE0 Enable
8	R/W	0	TM1 Test Mode Enable for Simulation.
7	R/W	0	Force_Host The CPU sets this bit to instruct the core to enter Host mode when the Session bit (Bit 0 of USB_DEVCTL) is set, regardless of whether it is connected to any peripheral. The state of the CID input, HostDisconnect and Linestate signals are ignored. The core will then

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<table>
<tr><th colspan="3">Offset: 0x007C</th><th>Register Name: USB_TESTC</th></tr>
<tr><th>Bit</th><th>Read/Write</th><th>Default/Hex</th><th>Description</th></tr>
<tr><td></td><td></td><td></td><td>remain in Host mode until the Session bit is cleared, even if a device is disconnected, and if the Force_Host bit remains set, will re-enter Host mode the next time the Session bit is set.
While in this mode, the status if the HOSTDISCON signal from the PHY may be read from bit 7 of the USB_DEVCTL (in 0x0060) register.
The operating speed is determined from the Force_HS and Force_FS bits as follows:
<table>
<tr><td>Force_HS</td><td>Force_FS</td><td>Operating Speed</td></tr>
<tr><td>0</td><td>0</td><td>Low Speed</td></tr>
<tr><td>0</td><td>1</td><td>Full Speed</td></tr>
<tr><td>1</td><td>0</td><td>High Speed</td></tr>
<tr><td>1</td><td>1</td><td>Undefined</td></tr>
</table></td></tr>
<tr><td>6</td><td>W</td><td>0</td><td>FIFO_Access
The CPU sets this bit to transfer the packet in the Endpoint 0 Tx FIFO to the Endpoint 0 Rx FIFO. It is cleared automatically.
Note: Writing ‘0’ to this bit will be ignored.</td></tr>
<tr><td>5</td><td>R/W</td><td>0</td><td>Force_FS
The CPU sets this bit either in conjunction with bit 7 above or to force the USB/DRD into Full-speed mode when it receive a USB reset.</td></tr>
<tr><td>4</td><td>R/W</td><td>0</td><td>Force_HS
The CPU sets this bit either in conjunction with bit 7 above or to force the USB/DRD into High-speed mode when it receive a USB reset.</td></tr>
<tr><td>3</td><td>R/W</td><td>0</td><td>Test_Packet
(High-speed mode) The CPU sets this bit to enter Test_Packet test mode. In the mode, the USB/DRD repetitively transmits on the bus a 53-byte test packet, the form of which is defined in the Universal Serial Bus Specification Revision 2.0, Section 7.1.20.
Note: The text packet has a fixed format and must be loaded into the Endpoint 0 FIFO before the test mode is entered.</td></tr>
<tr><td>2</td><td>R/W</td><td>0</td><td>Test_K
(High-speed mode) The CPU sets this bit to enter the Test_K test mode. In this mode, the USB/DRD transmits a continuous K on the bus.</td></tr>
<tr><td>1</td><td>R/W</td><td>0</td><td>Test_J
(High-speed mode) The CPU sets this bit to enter the Test_J est mode. In this mode, the USB/DRD transmits a continuous J on the bus.</td></tr>
<tr><td>0</td><td>R/W</td><td>0</td><td>Test_SE0_NAK</td></tr>
</table>

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Offset: 0x007C			Register Name: USB_TESTC
Bit	**Read/Write**	**Default/Hex**	**Description**
			(High-speed mode) The CPU sets this bit to enter the Test_SE0_NAK test mode. In this mode, the USB/DRD remains in High-speed mode but responds to any valid IN token with a NAK.

NOTE

Note: Only one of Bits 0-6 should be set at any time.

10.5.5.9 0x0080 USB EP0 Control and Status Register (Default Value: 0x0000_0000)

Offset: 0x0080			Register Name: USB_CSR0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	W	0	FlushFIFO The CPU writes a '1' to this bit to flush the next packet to be transmitted/read from the Endpoint 0 FIFO. The FIFO pointer is reset, and the TxPktRdy/RxPktRdy bit (below) is cleared. **Note: (ⅰ)Writing '0' to this bit is ignored. (ⅱ)Flush FIFO should only be used when TxPktRdy/RxPktRdy is set, at other times, it may cause data to be corrupted.**
23	W	0	ServicedSetupEnd The CPU writes a '1' to this bit to clear the SetupEnd bit. It is cleared automatically.
22	W	0	ServicedRxPktRdy The CPU writes a 1 to this bit to clear the RxPktRdy bit. It is cleared automatically.
21	W	0	SendStall The CPU writes a '1' to this bit to terminate the current transaction. The STALL handshake will be transmitted and then this bit will be cleared automatically. Note: The FIFO should be flushed before SendStall is set.
20	R	0	SetupEnd This bit will be set when a control transaction ends before the DataEnd bit has been set. An interrupt will be generated and the FIFO flushed at this time. The bit is cleared by the CPU writing a '1' to the ServicedSetupEnd bit.

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Offset: 0x0080			Register Name: USB_CSR0
Bit	**Read/Write**	**Default/Hex**	**Description**
19	W	0	DataEnd The CPU sets this bit: When setting TxPktRdy for the last data packet. When clearing RxPktRdy after unloading the last data packet. When setting TxPktRdy for a zero length data packet. It is cleared automatically.
18	R/W	0	SentStall This bit is set when a STALL handshake is transmitted. The CPU should clear this bit.
17	R/W	0	TxPktRdy The CPU sets this bit after loading a data packet into the FIFO. It is cleared automatically when a data packet has been transmitted. An interrupt is also generated at this point (if enabled).
16	R	0	RxPktRdy This bit is set when a data packet has been received. An interrupt is generated (if enabled) when this bit is set. The CPU clears this bit by setting the ServicedRxPktRdy bit.
15:0	/	/	/

10.5.5.10 0x0080 USB EP1 to 5 Tx Control and Status Register (Default Value: 0x0000_0000)

Offset: 0x0080			Register Name: USB_TXCSR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0	AutoSet If CPU sets this bit, TxPktRdy will be automatically set when data of maximum packet size (value in the USB_TXMAXP) is loaded into the Tx FIFO. If a packet of less than the maximum packet size is loaded, then TxPktRdy will have to be set manually. **Note: Should not be set for high-bandwidth Isochronous/Interrupt endpoints.**
30	R/W	0	ISO The CPU sets this bit to enable the Tx endpoint for Isochronous transfers, and clears it to enable the Tx endpoint for Bulk or Interrupt transfers. **Note: This is only has any effect in Peripheral mode. In Host mode, it always returns zero.**
29	R/W	0	Mode

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Offset: 0x0080			Register Name: USB_TXCSR
Bit	**Read/Write**	**Default/Hex**	**Description**
			The CPU sets this bit to enable the endpoint direction as Tx, and clears the bit to enable it as Rx. **Note: This bit only has any affect where the same endpoint FIFO is used for Tx and Rx transactions.**
28	R/W	0	DMAReqEnab The CPU sets this bit to enable the DMA request for the Tx endpoint.
27	R/W	0	FrcDataTog The CPU sets this bit to force the endpoint data toggle to switch and the data packet to be cleared from the FIFO, regardless of whether an ACK was received. This can be used by Interrupt Tx endpoints that are used to communicate rate feedback for Isochronous endpoints.
26	R/W	0	DMAReqMode The CPU sets this bit to select DMA Request Mode 1 and clears it to select DMA Request Mode 0. **Note: This bit must not be cleared either before or in the same cycle as the above DMAReqEnab bit is cleared.**
25:24	/	/	/
23	R/W	0	IncompTx When the endpoint is being used for high-bandwidth Isochronous/Interrupt transfers, this bit is set to indicate where a large packet has been split into 2 or 3 packets for transmission but insufficient IN tokens have been received to send all the parts. **Note: In anything other than a high-bandwidth transfer, this bit will always return 0. And writing '1' to this bit is ignored.**
22	W	0	ClrDataTog The CPU writes a 1 to this bit to reset the endpoint data toggle to 0. It is cleared automatically. **Note: Writing '0' to this bit is ignored.**
21	R/W	0	SentStall This bit is set when a STALL handshake is transmitted. The FIFO is flushed and the TxPktRdy bit is cleared. The CPU should clear this bit. **Note: Writing '1' to this bit is ignored.**
20	R/W	0	SendStall The CPU writes a 1 to this to issue a STALL handshake to an IN token. The CPU clears this bit to terminate the stall condition. **Note: (ⅰ)The FIFO should be flushed before SendStall is set.(ⅱ)This bit has no effect where the endpoint is being used for Isochronous transfers.**

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Offset: 0x0080			Register Name: USB_TXCSR
Bit	**Read/Write**	**Default/Hex**	**Description**
19	W	0	FlushFIFO The CPU writes a 1 to this bit to flush the latest packet from the endpoint Tx FIFO. The FIFO pointer is reset, the TxPktRdy bit (below) is cleared and an interrupt is generated. May be set simultaneously with TxPktRdy to abort the packet that is currently being loaded into the FIFO. **Note: (ⅰ)Writing '0' to this bit is ignored. (ⅱ)Flush FIFO should only be used when TxPktRdy is set, at other times, it may cause data to be corrupted. Also note that, if the FIFO is double-buffered, FlushFIFO may need to be set twice to completely clear the FIFO.**
18	R/W	0	UnderRun The USB sets this bit if an IN token is received when the TxPktRdy bit not set. The CPU should clear this bit. **Note: Writing '1' to this bit is ignored.**
17	R/W	0	FIFONotEmpty The USB sets this bit when there is at least 1 packet in the Tx FIFO. **Note: Writing '1' to this bit is ignored.**
16	R/W	0	TxPktRdy The CPU sets this bit after loading a data packet into the FIFO. It is cleared automatically when a data packet has been transmitted. An interrupt is also generated at this point (if enabled). TxPktRdy is also automatically cleared prior to loading a second packet to a double buffered FIFO. **Note: Writing '0' to this bit is ignored.**
15:11	R/W	0x00	PacketCount In the case of Bulk endpoints with the packet splitting option enabled, the Packet Count can be up to 32 and defines the maximum number of USB packets of specified payload into which a single data packet placed in the FIFO should be split, prior to transfer. If the packet splitting option is not enabled, Packet Count is not implemented. For Isochronous/Interrupt endpoints operating in High-speed mode and with the High-bandwidth option enabled, Packet Count may only either 2 or 3 (corresponding to bit 11 or bit 12 set, respectively) and it specifies the maximum number of such transactions that can be take place in a single microframe. If either bit 11 or bit 12 is non-zero, the USB/DRD will automatically split any data packet written to the FIFO into up to 2 or 3 USB packet, each containing the specified payload (or less). For Isochronous/Interrupt transfers in

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Offset: 0x0080			Register Name: USB_TXCSR
Bit	**Read/Write**	**Default/Hex**	**Description**
			Full-speed mode or if High-bandwidth is not enabled, bit 11 and 12 are ignored. **Note: Value for this bits is (Packet Count - 1), but not Packet Count.**
10:0	R/W	0x000	MaximumPayload These bits define the maximum payload (in bytes) transmitted in a single transaction. The value set can be up to 1024 bytes but is subject to the constraints placed by the USB Specification on packet sizes for Bulk, Interrupt and Isochronous transfers in Full-speed and High-speed operations. **Note: (i) The value written to Maximum Payload (multiplied by Packet Count in the case of high-bandwidth Isochronous/Interrupt transfer) must match the value given in the wMaxPacketSize field of the Standard Endpoint Descriptor for the associated endpoint, a mismatch could cause unexpected result. (ii) The total amount of data represented by the value written to this register (Maximum payload × Packet Count) must not exceed the FIFO size for Tx endpoint, and should not exceed half the FIFO size if double-buffering is required.**

10.5.5.11 0x0084 USB EP1 to 5 Rx Control and Status Register (Default Value: 0x0000_0000)

Offset: 0x0084			Register Name: USB_RXCSR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0	AutoClear If CPU sets this bit then the RxPktRdy will be automatically cleared when data of maximum packet size (value in the USB_TXMAXP) is unloaded from the Rx FIFO. If a packet of less than the maximum packet size is unloaded, then RxPktRdy will have to be cleared manually. **Note: Should not be set for high-bandwidth Isochronous endpoints.**
30	R/W	0	ISO The CPU sets this bit to enable the Rx endpoint for Isochronous transfers, and clears it to enable the Rx endpoint for Bulk or Interrupt transfers.
29	R/W	0	DMAReqEnab The CPU sets this bit to enable the DMA request for the Rx endpoint.

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Offset: 0x0084			Register Name: USB_RXCSR
Bit	**Read/Write**	**Default/Hex**	**Description**
28	R/W	0	DisNyet_PIDError DisNyet *Bulk/Interrupt Transactions:* The CPU sets this bit to disable the sending of NYET handshakes. When set, all successfully received Rx packets are ACK'd including at the point at which the FIFO becomes full. **Note: This bit only has any affect in High-speed mode, in which mode it should be set for all Interrupt endpoints.** PIDError ISO Transactions: The core sets this bit to indicate a PID error in the received packet.
27	R/W	0	DMAReqMode The CPU sets this bit to select DMA Request Mode 1 and clears it to select DMA Request Mode 0. **Note: This bit must not be cleared in the same cycle as the above RxPktRdy(or DMAReqEnab) bit is cleared.**
26:25	/	/	/
24	R/W	0	IncompRx This bit will be set in a high-bandwidth Isochronous/Interrupt transfer if the packet received is incomplete. It will be cleared when RxPktRdy is cleared. **Note:** **Writing '1' to this bit is forbidden.** **In anything other than a high-bandwidth transfer, this bit will always return 0.**
23	W	0	ClrDataTog The CPU writes a '1' to this bit to reset the endpoint data toggle to 0. It is cleared automatically. **Note: Writing '0' to this bit is ignored.**
22	R/W	0	SentStall This bit is set when a STALL handshake is transmitted. The CPU should clear this bit. **Note: Writing '1' to this bit is ignored.**
21	R/W	0	SendStall The CPU writes a '1' to this to issue a STALL handshake. The CPU clears this bit to terminate the stall condition. **Note:** **The FIFO should be flushed before SendStall is set.**

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Offset: 0x0084			Register Name: USB_RXCSR
Bit	**Read/Write**	**Default/Hex**	**Description**
			This bit has no effect where the endpoint is being used for Isochronous transfers.
20	W	0	FlushFIFO The CPU writes a '1' to this bit to flush the next packet to be read from the endpoint Rx FIFO. The FIFO pointer is reset and the RxPktRdy bit (below) is cleared. **Note:** **Writing '0' to this bit is ignored.** **Flush FIFO should only be used when RxPktRdy is set, at other times, it may cause data to be corrupted. Also note that, if the FIFO is double-buffered, FlushFIFO may need to be set twice to completely clear the FIFO.**
19	R	0	DataError This bit is set when RxPktRdy is set if the data packet has a CRC or bit-stuff error. It is cleared when RxPktRdy is cleared. **Note: This bit is only valid when the endpoint is operating in ISO mode. In bulk mode, it always returns zero.**
18	R/W	0	OverRun The USB sets this bit if an OUT token can not be loaded into the Rx FIFO. The CPU should clear this bit. **Note:** **Writing '1' to this bit is ignored.** **This bit is only valid when the endpoint is operating in ISO mode. In bulk mode, it always returns zero.**
17	R	0	FIFOFull The USB sets this bit when no more packets can be loaded into the Rx FIFO.
16	R/W	0	RxPktRdy This bit is set when a data packet has been received. The CPU should clear this bit when the packet has been unloaded from the Rx FIFO. An interrupt is generated when the bit is set. **Note: Writing '1' to this bit is ignored.**
15:11	R/W	0x00	PacketCount In the case of Bulk endpoints with the packet combining option enabled, the Packet Count can be up to 32 and defines the maximum number of USB packets of specified payload which are to be combined into a single data packet within the FIFO. For Isochronous/Interrupt endpoints operating in High-speed mode and with the High-bandwidth option enabled, Packet Count may

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Offset: 0x0084			Register Name: USB_RXCSR
Bit	**Read/Write**	**Default/Hex**	**Description**
			only either 2 or 3 (corresponding to bit 11 or bit 12 set, respectively) and it specifies the maximum number of such transactions that can be take place in a single microframe. If either bit 11 or bit 12 is non-zero, the USB/DRD will automatically combine the separate USB packets received in any microframe into a single packet within the Rx FIFO. For Isochronous/Interrupt transfers in Full-speed mode or if High-bandwidth is not enabled, bit 11 and 12 are ignored. **Note: Value for this bits is (Packet Count - 1), but not Packet Count.**
10:0	R/W	0x000	MaximumPayload These bits define the maximum payload (in bytes) transmitted in a single transaction. The value set can be up to 1024 bytes but is subject to the constraints placed by the USB Specification on packet sizes for Bulk, Interrupt and Isochronous transfers in Full-speed and High-speed operations. **Note:** **The value written to Maximum Payload (multiplied by Packet Count in the case of high-bandwidth Isochronous/Interrupt transfer) must match the value given in the wMaxPacketSize field of the Standard Endpoint Descriptor for the associated endpoint, a mismatch could cause unexpected result.** **The total amount of data represented by the value written to this register (Maximum payload × Packet Count) must not exceed the FIFO size for OUT endpoint, and should not exceed half the FIFO size if double-buffering is required.**

10.5.5.12 0x0088 USB EP0 Rx Counter Register (Default Value: 0x0000_0000)

Offset: 0x0088			Register Name: USB_COUNT0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6:0	R	0x00	RxCount0 Endpoint 0 Rx Count These bits indicate the number of received data bytes in the Endpoint 0 FIFO. **Note: The value returned changes as the FIFO is unloaded and is only valid while RxPktRdy (of USB_CSR0) is set.**

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10.5.5.13 0x0088 USB EP1 to 5 Rx Counter Register (Default Value: 0x0000_0000)

Offset: 0x0088			Register Name: USB_RXCOUNT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0000	RqPktCount Sets the number of packets of size MaxP that are to be transferred in a block transfer. **Note: Only used in Host mode when AutoReq (of USB_RXCSR) is set. Has no effect in Peripheral mode or AutoReq is not set.**
15:13	/	/	/
12:0	R	0x0000	RxCount Endpoint Rx Count These bits hold the number of data bytes in the packet currently in line to be read from the Rx FIFO. If the packet was transmitted as multiple bulk packets, the number given will be for the combined packet. **Note: The value returned changes as the FIFO is unloaded and is only valid while RxPktRdy (of USB_RXCSR) is set.**

10.5.5.14 0x0090 USB EP1 to 5 TxFIFO Setting Register (Default Value: 0x0000_0000)

Offset: 0x0090			Register Name: USB_TXFIFO
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x0000	AD AD[12:0] Start address of the endpoint FIFO is in units of 8 bytes, and it equals (AD[12:0]*8).
15:5	/	/	/
4	R/W	0	DPB Defines whether double-packet buffering supported. When '1', double-packet buffering is supported. When '0', only single-packet buffering is supported.
3:0	R/W	0x0	SZ SZ[3:0] Maximum packet size to be allowed for (*before any splitting within the FIFO of Bulk/High-Bandwidth packets prior to transmission*) is $2^{(SZ[3:0]+3)}$ bytes, and the valid values for SZ[3:0] are 0x0–0x09. If DPB=0, the FIFO will also this size; if DPB=1, the FIFO will be twice this size.

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10.5.5.15 0x0094 USB EP1 to 5 RxFIFO Setting Register (Default Value: 0x0000_0000)

Offset: 0x0094			Register Name: USB_RXFIFO
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x0000	AD AD[12:0] Start address of the endpoint FIFO is in units of 8 bytes, and it equals (AD[12:0]*8).
15:5	/	/	/
4	R/W	0	DPB Defines whether double-packet buffering supported. When '1', double-packet buffering is supported. When '0', only single-packet buffering is supported.
3:0	R/W	0x0	SZ SZ[3:0] Maximum packet size to be allowed for (*before any splitting within the FIFO of Bulk/High-Bandwidth packets prior to transmission*) is $2^{(SZ[3:0]+3)}$ bytes, and the valid values for SZ[3:0] are 0x0–0x09. If DPB=0, the FIFO will also this size; if DPB=1, the FIFO will be twice this size.

10.5.5.16 0x0098 USB Function Address Register (Default Value: 0x0000_0000)

Offset: 0x0098			Register Name: USB_FADDR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6:0	RW	0x00	FADDR The function address in peripheral mode. This field is reset to zero after a USB bus reset, and should be updated by software after Set_Address Command during USB enumeration.

10.5.5.17 0x0400 USB Interface Status and Control Register (Default Value: 0x0000_0000)

Offset: 0x0400			Register Name: USB_ISCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31	/	0	/
30	R	-	VBUSLS USB VBUS Valid Status detected from Line State

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Offset: 0x0400			Register Name: USB_ISCR
Bit	**Read/Write**	**Default/Hex**	**Description**
29	R	-	VBUSEX USB VBUS Valid Status detected from external VBUS input
28	R	-	IDEX USB ID Status detected from external ID input
27:26	R	-	LS USB Line Status [27]—DM [26]—DP
25	R	-	VBUS USB VBUS Status merged from both internal and external
24	R	-	ID USB ID Status merged from both internal and external
23:18	/	0	/
17	R/W	0	IDPullupEn ID pull up enable 0: disable 1: enable ID pull up
16	R/W	0	DataPullupEn DP/DM pull up enable 0: DP/DM pull up diable 1: DP/DM pull up enable
15:14	R/W	0	ForceID Force ID 0x: use external ID Status 10: force ID to LOW 11: force ID to HIGH
13:12	R/W	0	ForceVBUS Force VBUS Valid 0x: use external VBUS Valid Status from VBUS Input or Line State 10: Force VBUS Valid to LOW 11: Force VBUS Valid to HIGH
11:10	R/W	0	VBUSSEL External VBUS Valid Source Select 0x: External VBUS Valid detected from VBUS Input 10: External VBUS Valid detected from DP/DM Input 11: External VBUS Valid detected from either VBUS or DP/DM input

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Offset: 0x0400			Register Name: USB_ISCR
Bit	**Read/Write**	**Default/Hex**	**Description**
9:8	/	0	/
7	R/W	0	WakeupEn USB Wakeup Enable 0: Disable 1: Enable
6	R/W	0	VBUSCDS VBUS Input Change Detect Status This bit is set by hardware after VBUS input changed when VBUS change detect is enable. Writing '1' will clear this bit.
5	R/W	0	IDCDS ID Input Change Detect Status This bit is set by hardware after ID input changed when ID change detect is enable. Writing '1' will clear this bit.
4	R/W	0	DATACDS DP/DM Input Change Detect Status This bit is set by hardware after DP/DM input changed when DP/DM change detect is enable. Writing '1' will clear this bit.
3	R/W	0	WakeupIE USB Wakeup IRQ Enable 1: Enable USB Wakeup IRQ 0: Disable USB Wakeup IRQ If this bit is set to zero, an USB wakeup event (VBUS/ID/DP/DM change) will generate an USB wakeup request to wakeup the system, but not generate an USB wakeup IRQ to CPU.
2	R/W	0	VBUSCDE VBUS Input Change Detect enable 0: Disable 1: Enable
1	RW	0	IDCDE ID Input Change Detect enable 0: Disable 1: Enable
0	R/W	0	DATACDE DP/DM Input Change Detect enable 0: Disable 1: Enable

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10.5.5.18 0x0410 USB PHY Control Register (Default Value: 0x0000_0008)

Offset: 0x0410			Register Name: USB_PHY_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0	bist_en_a
15:8	R/W	0	vc_addr
7	R/W	0	vc_di
6:4	/	/	/
3	R/W	1	SIDDQ 1: Write 1 to disable phy. 0: Write 0 to enable phy.
2	/	/	/
1	R/W	0	vc_en 0: Write 0 to disable phy vc bus 1: Write 1 to enable phy vc bus. **Note: only 1 VC bus of all the usb controllers could be enabled at the same time.**
0	R/W	0	vc_clk

10.5.5.19 0x0414 USB PHY Test Register (Default Value: 0x0000_0000)

Offset: 0x0414			Register Name: USB_PHY_TEST
Bit	**Read/Write**	**Default/Hex**	**Description**
31:15	/	/	/
14	R/W	0x0	TESTBURNIN
13	R/W	0x0	TESTDATAOUTSEL
12	R/W	0x0	TESTCLK
11:8	R/W	0x0	TESTADDR
7:0	R/W	0x0	TESTDATAIN

10.5.5.20 0x0418 USB PHY Tune Register (Default Value: 0x0234_38E4)

Offset: 0x0418			Register Name: USB_PHY_TUNE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/
25:23	R/W	0x04	COMPDISTUNE

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Offset: 0x0418			Register Name: USB_PHY_TUNE
Bit	Read/Write	Default/Hex	Description
22:20	R/W	0x03	SQRXTUNE
19	R/W	0x0	TXPREEMPPULSETUNE
18:16	R/W	0x04	DRDTUNE
15:12	R/W	0x03	TXFSLSTUNE
11:8	R/W	0x08	TXVREFTUNE
7:6	R/W	0x03	TXHSXVTUNE
5:4	R/W	0x02	TXRISETUNE
3:2	R/W	0x01	TXRESTUNE
1:0	R/W	0x0	TXPREEMPAMPTUNE

10.5.5.21 0x0420 USB PHY Select Register (Default Value: 0x0000_0001)

Offset: 0x0420			Register Name: USB_PHY_SEL
Bit	Read/Write	Default/Hex	Description
31:1	/	/	Reserved
0	R/W	0x1	OTG_SEL 1: Phy is connected to OTG SIE 0: Phy is connected to HCI SIE

10.5.5.22 0x0424 USB PHY Status Register (Default Value: 0x0000_0000)

Offset: 0x0424			Register Name: USB_PHY_STA
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17	R	0	Bist_error
16	R	0	bist_done
15:1	/	/	/
0	R	0	vc_do

10.5.5.23 0x0500 USB DMA Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x0500			Register Name: USB_DMA_INTE
Bit	Read/Write	Default/Hex	Description
31:8	/	/	Reserved
7	R/W	0x0	USB_DMA7_PKG_INT_EN

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Offset: 0x0500			Register Name: USB_DMA_INTE
Bit	**Read/Write**	**Default/Hex**	**Description**
			DMA7 Package End Transfer Interrupt Enable 0: Disable 1: Enable.
6	R/W	0x0	USB_DMA6_PKG_INT_EN DMA6 Package End Transfer Interrupt Enable 0: Disable 1: Enable.
5	R/W	0x0	USB_DMA5_PKG_INT_EN DMA5 Package End Transfer Interrupt Enable 0: Disable 1: Enable.
4	R/W	0x0	USB_DMA4_PKG_INT_EN DMA4 Package End Transfer Interrupt Enable 0: Disable 1: Enable.
3	R/W	0x0	USB_DMA3_PKG_INT_EN DMA3 Package End Transfer Interrupt Enable 0: Disable 1: Enable.
2	R/W	0x0	USB_DMA2_PKG_INT_EN DMA2 Package End Transfer Interrupt Enable 0: Disable 1: Enable.
1	R/W	0x0	USB_DMA1_PKG_INT_EN DMA1 Package End Transfer Interrupt Enable 0: Disable 1: Enable.
0	R/W	0x0	USB_DMA0_PKG_INT_EN DMA0 Package End Transfer Interrupt Enable 0: Disable 1: Enable.

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10.5.5.24 0x0504 USB DMA Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0504			Register Name: USB_DMA_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	Reserved
7	R/W	0x0	USB_DMA7_PKG_INT_STA DMA7 Package End Transfer Interrupt Status. Set 1 to the bit will clean it. 0: No effect 1: Pending.
6	R/W	0x0	USB_DMA6_PKG_INT_STA DMA6 Package End Transfer Interrupt Status. Set 1 to the bit will clean it. 0: No effect 1: Pending.
5	R/W	0x0	USB_DMA5_PKG_INT_STA DMA5 Package End Transfer Interrupt Status. Set 1 to the bit will clean it. 0: No effect 1: Pending.
4	R/W	0x0	USB_DMA4_PKG_INT_STA DMA4 Package End Transfer Interrupt Status. Set 1 to the bit will clean it. 0: No effect 1: Pending.
3	R/W	0x0	USB_DMA3_PKG_INT_STA DMA3 Package End Transfer Interrupt Status. Set 1 to the bit will clean it. 0: No effect 1: Pending.
2	R/W	0x0	USB_DMA2_PKG_INT_STA DMA2 Package End Transfer Interrupt Status. Set 1 to the bit will clean it. 0: No effect 1: Pending.
1	R/W	0x0	USB_DMA1_PKG_INT_STA DMA1 Package End Transfer Interrupt Status. Set 1 to the bit will clean it. 0: No effect

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Offset: 0x0504			Register Name: USB_DMA_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: Pending.
0	R/W	0x0	USB_DMA0_PKG_INT_STA DMA0 Package End Transfer Interrupt Status. Set 1 to the bit will clean it. 0: No effect 1: Pending.

10.5.5.25 0x0540 + N*0x0010 (N = 0 to 7) USB DMA Channel Configuration Register (Default Value: 0x0000_0000)

Offset: 0x0540 + N*0x0010 (N = 0 to 7)			Register Name: USB_DMA_CHAN_CFG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	DMA_EN DMA Channel Enable If set to 1, DMA will start the data transfer between the source and the destination. The bit will hold on until the DMA finished. It will be cleared automatically. Set 0 to this bit will stop the corresponding DMA channel and reset its state machine.
30:27	/	/	/
26:16	R/W	0x0	DMA_BST_LEN DMA Burst Length The value setting on this field should be equated to the usb max packet length of the corresponding endpoint.
15:5	/	/	/
4	R/W	0x0	DMA_DIR DMA Transfer Direction 0: SDRAM to USB FIFO 1: USB FIFO to SDRAM
3:0	R/W	0x0	DMA_FOR_EP DMA Channel for Endpoint The Endpoint number setting on this field selects the dma channel for the corresponding endpoint.

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10.5.5.26 0x0544 + N*0x0010 (N = 0 to 7) USB DMA SDRAM Start Address Register (Default Value: 0x0000_0000)

Offset: 0x0544 + N*0x0010 (N = 0 to 7)			Register Name: USB_DMA_SDRAM_ADD
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	DMA_SDRAM_STR_ADDR DMA SDRAM Start Address The sdram start address for the dma channel transfer between the sdram and usb fifo.

10.5.5.27 0x0548 + N*0x0010 (N = 0 to 7) USB DMA Byte Counter Register (Default Value: 0x0000_0000)

Offset: 0x0548 + N*0x0010 (N = 0 to 7)			Register Name: USB_DMA_BC
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17:0	R/W	0x0	DMA_BC DMA Byte Counter

10.5.5.28 0x0548 + N*0x0010 (N = 0 to 7) USB DMA RESIDUAL Byte Counter Register (Default Value: 0x0000_0000)

Offset: 0x0548 + N*0x0010 (N = 0 to 7)			Register Name: USB_DMA_RESIDUAL_BC
Bit	Read/Write	Default/Hex	Description
31:18	/	/	/
17:0	R/W	0x0	DMA_RESIDUAL_BC DMA Residual Byte Counter This field contains the residual byte count in current transfer.

10.5.6 EHCI Register Description

10.5.6.1 0x0000 EHCI Identification Register (Default Value: 0x0010)

Offset: 0x0000			Register Name: E_CAPLENGTH
Bit	Read/Write	Default/Hex	Description
7:0	R	0x10	CAPLENGTH The value in these bits indicates an offset to add to register base to find the beginning of the Operational Register Space.

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10.5.6.2 0x0002 EHCI Host Interface Version Number Register (Default Value: 0x0100)

Offset: 0x0002			Register Name: E_HCIVERSION
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R	0x0100	HCIVERSION This is a 16-bit register containing a BCD encoding of the EHCI revision number supported by this host controller. The most significant byte of this register represents a major revision and the least significant byte is the minor revision.

10.5.6.3 0x0004 EHCI Host Control Structural Parameter Register (Default Value: 0x0000_1101)

Offset: 0x0004			Register Name: E_HCSPARAMS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:20	R	0	Debug Port Number This register identifies which of the host controller ports is the debug port. The value is the port number (one based) of the debug port. This field will always be '0'.
19:16	/	/	/
15:12	R	1	Number of Companion Controller (N_CC) This field indicates the number of companion controllers associated with this USB2.0 host controller. A zero in this field indicates there are no companion host controllers. And a value larger than zero in this field indicates there are companion USB1.1 host controller(s). This field will always be '0'.
11:8	R	1	Number of Port per Companion Controller(N_PCC) This field indicates the number of ports supported per companion host controller. It is used to indicate the port routing configuration to system software. This field will always fix with '0'.
7	R	0	Port Routing Rules This field indicates the method used by this implementation for how all ports are mapped to companion controllers. The value of this field has the following interpretation: Value: 0 — Meaning: The first N_PCC ports are routed to the lowest numbered function companion host controller, the next N_PCC port are routed to the next

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Offset: 0x0004			Register Name: E_HCSPARAMS
Bit	Read/Write	Default/Hex	Description
			<table><tr><td></td><td>lowest function companion controller, and so on.</td></tr><tr><td>1</td><td>The port routing is explicitly enumerated by the first N_PORTS elements of the HCSP-PORTTOUTE array.</td></tr></table> This field will always be '0'.
6:4	/	/	/
3:0	R	1	N_PORTS This field specifies the number of physical downstream ports implemented on this host controller. The value of this field determines how many port registers are addressable in the Operational Register Space. Valid values are in the range of 0x1 to 0x0f. This field is always 1.

10.5.6.4 0x0008 EHCI Host Control Capability Parameter Register (Default Value: 0x0000_a026)

Offset: 0x0008			Register Name: E_HCCPARAMS
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:8	R	0xa0	EHCI Extended Capabilities Pointer (EECP) This optional field indicates the existence of a capabilities list. A value of 00b indicates no extended capabilities are implemented. A non-zero value in this register indicates the offset in PCI configuration space of the first EHCI extended capabiliby. The pointer value must be 40h or greater if implemented to maintain to consistency of the PCI header defined for this calss of device. The value of this field is always '00b'.
7:4	R	0x2	Isochronous Scheduling Threshold This field indicates, relative to the current position of the executing host controller, where software can reliably update the isochronous schedule. When bit[7] is zero, the value of the least significant 3 bits indicates the number of micro-frames a host controller can hold a set of isochronous data structures(one or more) before flushing the state. When bit[7] is a one, then host software assumes the host controller may cache an isochronous data structure for an entire frame.

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Offset: 0x0008			Register Name: E_HCCPARAMS
Bit	**Read/Write**	**Default/Hex**	**Description**
3	/	/	/
2	R	1	Asynchronous Schedule Park Capability If this bit is set to a one, then the host controller supports the park feature for high-speed queue heads in the Asynchronous Schedule. The feature can be disabled or enabled and set to a specific level by using the Asynchronous Schedule Park Mode Enable and Asynchronous Schedule Park Mode Count fields in the USBCMD register.
1	R	1	Programmable Frame List Flag If this bit is set to a zero, then system software must use a frame list length of 1024 elements with this host controller.The USBCMD register Frame List Size field is a read-only register and should be set to zero. If set to 1,then system software can specify and use the frame list in the USBCMD register Frame List Size field to cofigure the host controller. The frame list must always aligned on a 4K page boundary.This requirement ensures that the frame list is always physically contiguous.
0	/	/	/

10.5.6.5 0x000C EHCI Companion Port Route Description (Default Value: 0x0000_0000)

Offset: 0x000C			Register Name: E_HCSPPORTROUTE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R		HCSP-PORTROUTE This optional field is valid only if Port Routing Rules field in HCSPARAMS register is set to a one. This field is used to allow a host controller implementation to explicitly describe to which companion host controller each implemented port is mapped. This field is a 15-element nibble array (each 4 bit is one array element). Each array location corresponds one-to-one with a physical port provided by the host controller (e.g. PORTROUTE [0] corresponds to the first PORTSC port, PORTROUTE [1] to the second PORTSC port, etc.). The value of each element indicates to which of the companion host controllers this port is routed. Only the first N_PORTS elements have valid information. A value of zero indicates that the port is routed to the lowest

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Offset: 0x000C			Register Name: E_HCSPPORTROUTE
Bit	Read/Write	Default/Hex	Description
			numbered function companion host controller. A value of one indicates that the port is routed to the next lowest numbered function companion host controller, and so on.

10.5.6.6 0x0010 EHCI USB Command Register (Default Value: 0x0008_0b00)

Offset: 0x0010			Register Name: USBCMD
Bit	Read/Write	Default/Hex	Description
31:24	/	/	/
23:16	R/W	0x08	Interrupt Threshold Control The value in this field is used by system software to select the maximum rate at which the host controller will issue interrupts. The only valid values are defined below: Value | Minimum Interrupt Interval 0x00 | Reserved 0x01 | 1 micro-frame 0x02 | 2 micro-frame 0x04 | 4 micro-frame 0x08 | 8 micro-frame(default, equates to 1 ms) 0x10 | 16 micro-frame(2ms) 0x20 | 32 micro-frame(4ms) 0x40 | 64 micro-frame(8ms) Any other value in this register yields undefined results. The default value in this field is 0x08 . Software modifications to this bit while HC Halted bit is equal to zero results in undefined behavior.
15:12	/	/	/
11	R	1	Asynchronous Schedule Park Mode Enable(OPTIONAL) If the Asynchronous Park Capability bit in the HCCPARAMS register is a one, then this bit defaults to a 1 and is R/W. Otherwise the bit must be a zero and is Read Only. Software uses this bit to enable or disable Park mode. When this bit is one, Park mode is enabled. When this bit is zero, Park mode is disabled.
10	/	/	/
9:8	R	0x3	Asynchronous Schedule Park Mode Count(OPTIONAL)

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Offset: 0x0010			Register Name: USBCMD
Bit	**Read/Write**	**Default/Hex**	**Description**
			Asynchronous Park Capability bit in the HCCPARAMS register is a one, Then this field defaults to 0x3 and is W/R. Otherwise it defaults to zero and is R. It contains a count of the number of successive transactions the host controller is allowed to execute from a high-speed queue head on the Asynchronous schedule before continuing traversal of the Asynchronous schedule. Valid value are 0x1 to 0x3.Software must not write a zero to this bit when Park Mode Enable is a one as it will result in undefined behavior.
7	R/W	0	Light Host Controller Reset(OPTIONAL) This control bit is not required. If implemented, it allows the driver to reset the EHCI controller without affecting the state of the ports or relationship to the companion host controllers. For example, the PORSTC registers should not be reset to their default values and the CF bit setting should not go to zero (retaining port ownership relationships). A host software read of this bit as zero indicates the Light Host Controller Reset has completed and it si safe for software to re-initialize the host controller. A host software read of this bit as a one indicates the Light Host
6	R/W	0	Interrupt on Async Advance Doorbell This bit is used as a doorbell by software to tell the host controller to issue an interrupt the next time it advances asynchronous schedule. Soft- Ware must write a 1 to this bit to ring the doorbell. When the host controller has evicted all appropriate cached schedule state, it sets the Interrupt on Async Advance status bit in the USBSTS. if the Interrupt on Async Advance Enable bit in the USBINTR register is a one then the host controller will assert an interrupt at the next interrupt threshold. The host controller sets this bit to a zero after it has set the Interrupt on Async Advance status bit in the USBSTS register to a one. Software should not write a one to this bit when the asynchronous schedule is disabled. Doing so will yield undefined results.
5	R/W	0	Asynchronous Schedule Enable This bit controls whether the host controller skips processing the Asynchronous Schedule. Values mean:

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<table>
<tr><td colspan="3">Offset: 0x0010</td><td>Register Name: USBCMD</td></tr>
<tr><td>Bit</td><td>Read/Write</td><td>Default/Hex</td><td>Description</td></tr>
<tr><td></td><td></td><td></td><td>
<table>
<tr><td>Bit Value</td><td>Meaning</td></tr>
<tr><td>0</td><td>Do not process the Asynchronous Schedule.</td></tr>
<tr><td>1</td><td>Use the ASYNLISTADDR register to access the Asynchronous Schedule.</td></tr>
</table>
The default value of this field is ‘0b’.
</td></tr>
<tr><td>4</td><td>R/W</td><td>0</td><td>
Periodic Schedule Enable
This bit controls whether the host controller skips processing the Periodic Schedule. Values mean:
<table>
<tr><td>Bit Value</td><td>Meaning</td></tr>
<tr><td>0</td><td>Do not process the Periodic Schedule.</td></tr>
<tr><td>1</td><td>Use the PERIODICLISTBASE register to access the Periodic Schedule.</td></tr>
</table>
The default value of this field is ‘0b’.
</td></tr>
<tr><td>3:2</td><td>R/W</td><td>0</td><td>
Frame List Size
This field is R/W only if Programmable Frame List Flag in the HCCPARAMS registers is set to a one. This field specifies the size of the
Frame list. The size the frame list controls which bits in the Frame Index
Register should be used for the Frame List Current index. Values mean:
<table>
<tr><td>Bits</td><td>Meaning</td></tr>
<tr><td>00b</td><td>1024 elements(4096bytes)Default value</td></tr>
<tr><td>01b</td><td>512 elements(2048byts)</td></tr>
<tr><td>10b</td><td>256 elements(1024bytes)For resource-constrained condition</td></tr>
<tr><td>11b</td><td>reserved</td></tr>
</table>
The default value is ‘00b’.
</td></tr>
<tr><td>1</td><td>R/W</td><td>0</td><td>
Host Controller Reset
This control bit is used by software to reset the host controller. The effects of this on Root Hub registers are similar to a Chip Hardware Reset.
When software writes a one to this bit, the Host Controller resets its internal pipelines, timers, counters, state machines, etc. to their initial value. Any transaction currently in progress on USB is
</td></tr>
</table>

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Offset: 0x0010			Register Name: USBCMD
Bit	**Read/Write**	**Default/Hex**	**Description**
			immediately terminated. A USB reset is not driven on downstream ports. All operational registers, including port registers and port state machines are set to their initial values. Port ownership reverts to the companion host controller(s). Software must reinitialize the host controller as described in Section 4.1 of the CHEI Specification in order to return the host controller to an operational state. This bit is set to zero by the Host Controller when the reset process is complete. Software cannot terminate the reset process early by writing a zero to this register. Software should not set this bit to a one when the HC Halted bit in the USBSTS register is a zero. Attempting to reset an actively running host controller will result in undefined behavior.
0	R/W	0	Run/Stop When set to a 1, the Host Controller proceeds with execution of the schedule. When set to 0, the Host Controller completes the current and any actively pipelined transactions on the USB and then halts. The Host Controller must halt within 16 micro-frames after software clears this bit. The HC Halted bit indicates when the Host Controller has finished its pending pipelined transactions and has entered the stopped state. Software must not write a one to this field unless the Host Controller is in the Halt State. The default value is 0x0.

10.5.6.7 0x0014 EHCI USB Status Register (Default Value: 0x0000_1000)

Offset: 0x0014			Register Name: E_USBSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15	R	0	Asynchronous Schedule Status The bit reports the current real status of Asynchronous Schedule. If this bit is a zero then the status of the Asynchronous Schedule is disabled. If this bit is a one then the status of the Asynchronous Schedule is enabled. The Host Controller is not required to immediately disable or enable the Asynchronous Schedule when software transitions the Asynchronous Schedule Enable bit in the USBCMD register. When this bit and the Asynchronous Schedule

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Offset: 0x0014			Register Name: E_USBSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
			Enable bit are the same value, the Asynchronous Schedule is either enabled (1) or disabled (0).
14	R	0	Periodic Schedule Status The bit reports the current real status of the Periodic Schedule. If this bit is a zero then the status of the Periodic Schedule is disabled. If this bit is a one then the status of the Periodic Schedule is enabled. The Host Controller is not required to *immediately* disable or enable the Periodic Schedule when software transitions the *Periodic Schedule Enable* bit in the USBCMD register. When this bit and the *Periodic Schedule Enable* bit are the same value, the Periodic Schedule is either enabled (1) or disabled (0).
13	R	0	Reclamation This is a read-only status bit, which is used to detect an empty asynchronous schedule.
12	R	1	HC Halted This bit is a zero whenever the Run/Stop bit is a one. The Host Controller Sets this bit to one after it has stopped executing as a result of the Run/Stop bit being set to 0, either by software or by the Host Controller Hardware (e.g. internal error). The default value is '1'.
11:6	/	/	/
5	R/WC	0	Interrupt on Async Advance System software can force the host controller to issue an interrupt the next time the host controller advances the asynchronous schedule by writing a one to the Interrupt on Async Advance Doorbell bit in the USBCMD register. This status bit indicates the assertion of that interrupt source.
4	R/WC	0	Host System Error The Host Controller set this bit to 1 when a serious error occurs during a host system access involving the Host Controller module. When this error occurs, the Host Controller clears the Run/Stop bit in the Command register to prevent further execution of the scheduled TDs.
3	R/WC	0	Frame List Rollover The Host Controller sets this bit to a one when the Frame List Index rolls over from its maximum value to zero. The exact value at which the rollover occurs depends on the frame list size. For example, if the frame list size is 1024, the Frame Index Register rolls over every

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Offset: 0x0014			Register Name: E_USBSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
			time FRINDEX [13] toggles. Similarly, if the size is 512, the Host Controller sets this bit to a one every time FRINDEX [12] toggles.
2	R/WC	0	Port Change Detect The Host Controller sets this bit to a one when any port for which the Port Owner bit is set to zero has a change bit transition from a zero to a one or a Force Port Resume bit transition from a zero to a one as a result of a J-K transition detected on a suspended port. This bit will also be set as a result of the Connect Status Chang being set to a one after system software has relinquished ownership of a connected port by writing a one to a port's Port Owner bit.
1	R/WC	0	USB Error Interrupt(USBERRINT) The Host Controller sets this bit to 1 when completion of USB transaction results in an error condition(e.g. error counter underflow).If the TD on which the error interrupt occurred also had its IOC bit set, both. This bit and USBINT bit are set.
0	R/WC	0	USB Interrupt(USBINT) The Host Controller sets this bit to a one on the completion of a USB transaction, which results in the retirement of a Transfer Descriptor that had its IOC bit set. The Host Controller also sets this bit to 1 when a short packet is detected (actual number of bytes received was less than the expected number of bytes)

10.5.6.8 0x0018 EHCI USB Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: E_USBINTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:6	/	/	/
5	R/W	0	Interrupt on Async Advance Enable When this bit is 1, and the Interrupt on Async Advance bit in the USBSTS register is 1, the host controller will issue an interrupt at the next interrupt threshold. The interrupt is acknowledged by software clearing the Interrupt on Async Advance bit.
4	R/W	0	Host System Error Enable When this bit is 1, and the Host System Error Status bit in the USBSTS register is 1, the host controller will issue an interrupt. The

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Offset: 0x0018			Register Name: E_USBINTR
Bit	**Read/Write**	**Default/Hex**	**Description**
			interrupt is acknowledged by software clearing the Host System Error bit.
3	R/W	0	Frame List Rollover Enable When this bit is 1, and the Frame List Rollover bit in the USBSTS register is 1, the host controller will issue an interrupt. The interrupt is acknowledged by software clearing the Frame List Rollover bit.
2	R/W	0	Port Change Interrupt Enable When this bit is 1, and the Port Chang Detect bit in the USBSTS register is 1, the host controller will issue an interrupt. The interrupt is acknowledged by software clearing the Port Chang Detect bit.
1	R/W	0	USB Error Interrupt Enable When this bit is 1, and the USBERRINT bit in the USBSTS register is 1,the host controller will issue an interrupt at the next interrupt threshold. The interrupt is acknowledged by software clearing the USBERRINT bit.
0	R/W	0	USB Interrupt Enable When this bit is 1, and the USBINT bit in the USBSTS register is 1,the host controller will issue an interrupt at the next interrupt threshold. The interrupt is acknowledged by software clearing the USBINT bit

10.5.6.9 0x001C EHCI Frame Index Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: E_FRINDEX
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	/	/	/
13:0	R/W	0	Frame Index The value in this register increment at the end of each time frame (e.g. micro-frame).Bits[N:3] are used for the Frame List current index. It Means that each location of the frame list is accessed 8 times(frames or Micro-frames) before moving to the next index. The following illustrates Values of N based on the value of the Frame List Size field in the USBCMD register. USBCMD[Frame List Size] | Number Elements | N

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Offset: 0x001C			Register Name: E_FRINDEX		
Bit	Read/Write	Default/Hex	Description		
			00b	1024	12
			01b	512	11
			10b	256	10
			11b	Reserved	

NOTE

This register must be written as a DWord. Byte writes produce undefined results.

10.5.6.10 0x0024 EHCI Periodic Frame List Base Address Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: E_PERIODICLISTBASE
Bit	Read/Write	Default/Hex	Description
31:12	R/W		Base Address These bits correspond to memory address signals [31:12], respectively. This register contains the beginning address of the Periodic Frame List in the system memory. System software loads this register prior to starting the schedule execution by the Host Controller. The memory structure referenced by this physical memory pointer is assumed to be 4-K byte aligned. The contents of this register are combined with the Frame Index Register (FRINDEX) to enable the Host Controller to step through the Periodic Frame List in sequence.
11:0	/	/	/

NOTE

Writes must be Dword Writes.

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10.5.6.11 0x0028 EHCI Current Asynchronous List Address Register (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: E_ASYNCLISTADDR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:5	R/W		Link Pointer (LP) This field contains the address of the next asynchronous queue head to be executed. These bits correspond to memory address signals [31:5], respectively.
4:0	/	/	/

NOTE

Writes must be Dword Writes.

10.5.6.12 0x0050E HCI Configure Flag Register (Default Value: 0x0000_0000)

Offset: 0x0050			Register Name: E_CONFIGFLAG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0	Configure Flag(CF) Host software sets this bit as the last action in its process of configuring the Host Controller. This bit controls the default port-routing control logic as follow: Value: 0 — Port routing control logic default-routs each port to an implementation dependent classic host controller. Value: 1 — Port routing control logic default-routs all ports to this host controller. The default value of this field is '0'.

NOTE

This register is not use in the normal implementation.

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10.5.6.13 0x0054 EHCI Port Status and Control Register (Default Value: 0x0000_2000)

<table>
<tr><th colspan="3">Offset: 0x0054</th><th>Register Name: E_PORTSC</th></tr>
<tr><th>Bit</th><th>Read/Write</th><th>Default/Hex</th><th>Description</th></tr>
<tr><td>31:22</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>21</td><td>R/W</td><td>0</td><td>Wake on Disconnect Enable(WKDSCNNT_E)
Writing this bit to a one enables the port to be sensitive to device disconnects as wake-up events.
This field is zero if Port Power is zero.
The default value in this field is ‘0’.</td></tr>
<tr><td>20</td><td>R/W</td><td>0</td><td>Wake on Connect Enable(WKCNNT_E)
Writing this bit to a one enable the port to be sensitive to device connects as wake-up events.
This field is zero if Port Power is zero.
The default value in this field is ‘0’.</td></tr>
<tr><td>19:16</td><td>R/W</td><td>0</td><td>Port Test Control
The value in this field specifies the test mode of the port. The encoding of the test mode bits are as follow:
<table><tr><td>Bits</td><td>Test Mode</td></tr><tr><td>0000b</td><td>The port is NOT operating in a test mode.</td></tr><tr><td>0001b</td><td>Test J_STATE</td></tr><tr><td>0010b</td><td>Test K_STATE</td></tr><tr><td>0011b</td><td>Test SE0_NAK</td></tr><tr><td>0100b</td><td>Test Packet</td></tr><tr><td>0101b</td><td>Test FORCE_ENABLE</td></tr><tr><td>0110b-1111b</td><td>Reserved</td></tr></table>The default value in this field is ‘0000b’.</td></tr>
<tr><td>15:14</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>13</td><td>R/W</td><td>1</td><td>Port Owner
This bit unconditionally goes to a 0b when the Configured bit in the CONFIGFLAG register makes a 0b to 1b transition. This bit unconditionally goes to 1b whenever the Configured bit is zero.
System software uses this field to release ownership of the port to selected host controller (in the event that the attached device is not a high-speed device).Software writes a one to this bit when the attached device is not a high-speed device. A one in this bit means that a companion host controller owns and controls the port.</td></tr>
</table>

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<table>
<tr><th colspan="3">Offset: 0x0054</th><th>Register Name: E_PORTSC</th></tr>
<tr><th>Bit</th><th>Read/Write</th><th>Default/Hex</th><th>Description</th></tr>
<tr><td></td><td></td><td></td><td>Default Value = 1b.</td></tr>
<tr><td>12</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>11:10</td><td>R</td><td>0</td><td>Line Status
These bits reflect the current logical levels of the D+ (bit11) and D- (bit10) signal lines. These bits are used for detection of low-speed USB devices prior to port reset and enable sequence. This read only field is valid only when the port enable bit is zero and the current connect status bit is set to a one.
The encoding of the bits are:
<table>
<tr><td>Bit[11:10]</td><td>USB State</td><td>Interpretation</td></tr>
<tr><td>00b</td><td>SE0</td><td>Not Low-speed device, perform EHCI reset.</td></tr>
<tr><td>10b</td><td>J-state</td><td>Not Low-speed device, perform EHCI reset.</td></tr>
<tr><td>01b</td><td>K-state</td><td>Low-speed device, release ownership of port.</td></tr>
<tr><td>11b</td><td>Undefined</td><td>Not Low-speed device, perform EHCI reset.</td></tr>
</table>
This value of this field is undefined if Port Power is zero.</td></tr>
<tr><td>9</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>8</td><td>R/W</td><td>0</td><td>Port Reset
1=Port is in Reset. 0=Port is not in Reset. Default value = 0.
When software writes a one to this bit (from a zero), the bus reset sequence as defined in the USB Specification Revision 2.0 is started. Software writes a zero to this bit to terminate the bus reset sequence. Software must keep this bit at a one long enough to ensure the reset sequence, as specified in the USB Specification Revision 2.0, completes. Notes: when software writes this bit to a one , it must also write a zero to the Port Enable bit.
Note that when software writes a zero to this bit there may be a delay before the bit status changes to a zero. The bit status will not read as a zero until after the reset has completed. If the port is in high-speed mode after reset is complete, the host controller will automatically enable this port (e.g. set the Port Enable bit to a one). A host controller must terminate the reset and stabilize the state of the port within 2 milliseconds of software transitioning this bit from a one to a zero. For example: if the port detects that the attached device is high-speed during reset, then the host controller must have</td></tr>
</table>

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<table>
<tr><th colspan="3">Offset: 0x0054</th><th>Register Name: E_PORTSC</th></tr>
<tr><th>Bit</th><th>Read/Write</th><th>Default/Hex</th><th>Description</th></tr>
<tr><td></td><td></td><td></td><td>the port in the enabled state with 2ms of software writing this bit to a zero.
The HC Halted bit in the USBSTS register should be a zero before software attempts to use this bit. The host controller may hold Port Reset asserted to a one when the HC Halted bit is a one.
This field is zero if Port Power is zero.</td></tr>
<tr><td>7</td><td>R/W</td><td>0</td><td>Suspend
Port Enabled Bit and Suspend bit of this register define the port states as follows:
<table><tr><td>Bits[Port Enables, Suspend]</td><td>Port State</td></tr><tr><td>0x</td><td>Disable</td></tr><tr><td>10</td><td>Enable</td></tr><tr><td>11</td><td>Suspend</td></tr></table>When in suspend state, downstream propagation of data is blocked on this port, except for port reset. The blocking occurs at the end of the current transaction, if a transaction was in progress when this bit was written to 1. In the suspend state, the port is sensitive to resume detection. Not that the bit status does not change until the port is suspend and that there may be a delay in suspending a port if there is a transaction currently in progress on the USB.
A write of zero to this bit is ignored by the host controller. The host controller will unconditionally set this bit to a zero when:
① Software sets the Force Port Resume bit to a zero(from a one).
② Software sets the Port Reset bit to a one(from a zero).
If host software sets this bit to a one when the port is not enabled(i.e. Port enabled bit is a zero), the results are undefined.
This field is zero if Port Power is zero.
The default value in this field is ‘0’.</td></tr>
<tr><td>6</td><td>R/W</td><td>0</td><td>Force Port Resume
1 = Resume detected/driven on port. 0 = No resume (K-state) detected/ driven on port. Default value = 0.
This functionality defined for manipulating this bit depends on the value of the Suspend bit. For example, if the port is not suspend and software transitions this bit to a one, then the effects on the bus are undefined.
Software sets this bit to a 1 drive resume signaling. The Host Controller sets this bit to a 1 if a J-to-K transition is detected while the port is in the Suspend state. When this bit transitions to a one because a J-to-K transition is detected, the Port Change Detect bit in</td></tr>
</table>

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Offset: 0x0054			Register Name: E_PORTSC
Bit	**Read/Write**	**Default/Hex**	**Description**
			the USBSTS register is also set to a one. If software sets this bit to a one, the host controller must not set the Port Change Detect bit. Note that when the EHCI controller owns the port, the resume sequence follows the defined sequence documented in the USB Specification Revision 2.0. The resume signaling (Full-speed 'K') is driven on the port as long as this remains a one. Software must appropriately time the Resume and set this bit to a zero when the appropriate amount of time has elapsed. Writing a zero (from one) causes the port to return high-speed mode (forcing the bus below the port into a high-speed idle). This bit will remain a one until the port has switched to high-speed idle. The host controller must complete this transition within 2 milliseconds of software setting this bit to a zero. This field is zero if Port Power is zero.
5	R/WC	0	Over-current Change Default = 0. This bit gets set to a one when there is a change to Over-current Active. Software clears this bit by writing a one to this bit position.
4	R	0	Over-current Active 0 = This port does not have an over-current condition. 1 = This port currently has an over-current condition. This bit will automatically transition from a one to a zero when the over current condition is removed. The default value of this bit is '0'.
3	R/WC	0	Port Enable/Disable Change Default = 0. 1 = Port enabled/disabled status has changed. 0 = No change. For the root hub, this bit gets set to a one only when a port is disabled due to the appropriate conditions existing at the EOF2 point (See Chapter 11 of the USB Specification for the definition of a Port Error). Software clears this bit by writing a 1 to it. This field is zero if Port Power is zero.
2	R/W	0	Port Enabled/Disabled 1=Enable, 0=Disable. Ports can only be enabled by the host controller as a part of the reset and enable. Software cannot enable a port by writing a one to this field. The host controller will only set this bit to a one when the reset sequence determines that the attached device is a high-speed device. Ports can be disabled by either a fault condition(disconnect event or other fault condition) or by host software. Note that the bit status

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Offset: 0x0054			Register Name: E_PORTSC
Bit	**Read/Write**	**Default/Hex**	**Description**
			does not change until the port state actually changes. There may be a delay in disabling or enabling a port due to other host controller and bus events. When the port is disabled, downstream propagation of data is blocked on this port except for reset. The default value of this field is '0'. This field is zero if Port Power is zero.
1	R/WC	0	Connect Status Change 1=Change in Current Connect Status, 0=No change, Default=0. Indicates a change has occurred in the port's Current Connect Status. The host controller sets this bit for all changes to the port device connect status, even if system software has not cleared an existing connect status change. For example, the insertion status changes twice before system software has cleared the changed condition, hub hardware will be "setting" an already-set bit. Software sets this bit to 0 by writing a 1 to it. This field is zero if Port Power is zero.
0	R	0	Current Connect Status Device is present on port when the value of this field is a one, and no device is present on port when the value of this field is a zero. This value reflects the current state of the port, and may not correspond directly to the event that caused the Connect Status Change(Bit 1) to be set. This field is zero if Port Power zero.

NOTE

This register is only reset by hardware or in response to a host controller reset.

10.5.7 OHCI Register Description

10.5.7.1 0x0400 OHCI Revision Register (Default Value: 0x0010)

Offset: 0x0400				Register Name: O_HcRevision
Bit	**Read/Write**		**Default/Hex**	**Description**
	HCD	**HC**		
31:8	/	/	/	/

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Offset: 0x0400				Register Name: O_HcRevision
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
7:0	R	R	0x10	Revision This read-only field contains the BCD representation of the version of the HCI specification that is implemented by this HC. For example, a value of 0x11 corresponds to version 1.1. All of the HC implementations that are compliant with this specification will have a value of 0x10.

10.5.7.2 0x0404 OHCI Control Register (Default Value: 0x0000_0000)

Offset: 0x0404				Register Name: O_HcControl
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:11	/	/	/	/
10	R/W	R	0x0	RemoteWakeupEnable This bit is used by HCD to enable or disable the remote wakeup feature upon the detection of upstream resume signaling. When this bit is set and the ResumeDetected bit in *HcInterruptStatus* is set, a remote wakeup is signaled to the host system. Setting this bit has no impact on the generation of hardware interrupt.
9	R/W	R/W	0x0	RemoteWakeupConnected This bit indicates whether HC supports remote wakeup signaling. If remote wakeup is supported and used by the system, it is the responsibility of system firmware to set this bit during POST. HC clear the bit upon a hardware reset but does not alter it upon a software reset. Remote wakeup signaling of the host system is host-bus-specific and is not described in this specification.
8	R/W	R	0x0	InterruptRouting This bit determines the routing of interrupts generated by events registered in HcInterruptStatus. If clear, all interrupt are routed to the normal host bus interrupt mechanism. If set interrupts are routed to the System Management Interrupt. HCD clears this bit upon a hardware reset, but it does not alter this bit upon a software reset. HCD uses this bit as a tag to indicate the ownership of HC.
7:6	R/W	R/W	0x0	HostControllerFunctionalState for USB 00b USBReset 01b USBResume

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<table>
<tr><td colspan="3">Offset: 0x0404</td><td colspan="2">Register Name: O_HcControl</td></tr>
<tr><td rowspan="2">Bit</td><td colspan="2">Read/Write</td><td rowspan="2">Default/Hex</td><td rowspan="2">Description</td></tr>
<tr><td>HCD</td><td>HC</td></tr>
<tr><td></td><td></td><td></td><td></td><td>
<table>
<tr><td>10b</td><td>USBOperational</td></tr>
<tr><td>11b</td><td>USBSuspend</td></tr>
</table>
A transition to USBOperational from another state causes SOF generation to begin 1 ms later. HCD may determine whether HC has begun sending SOFs by reading the StartoFrame field of HcInterruptStatus.
This field may be changed by HC only when in the USBSUSPEND state. HC may move from the USBSUSPEND state to the USBRESUME state after detecting the resume signaling from a downstream port.
HC enters USBSUSPEND after a software reset, whereas it enters USBRESET after a hardware reset. The latter also resets the Root Hub and asserts subsequent reset signaling to downstream ports.</td></tr>
<tr><td>5</td><td>R/W</td><td>R</td><td>0x0</td><td>BulkListEnable
This bit is set to enable the processing of the Bulk list in the next Frame. If cleared by HCD, processing of the Bulk list does not occur after the next SOF. HC checks this bit whenever it determines to process the list. When disabled, HCD may modify the list. If HcBulkCurrentED is pointing to an ED to be removed, HCD must advance the pointer by updating HcBulkCurrentED before re-enabling processing of the list.</td></tr>
<tr><td>4</td><td>R/W</td><td>R</td><td>0x0</td><td>ControlListEnable
This bit is set to enable the processing of the Control list in the next Frame. If cleared by HCD, processing of the Control list does not occur after the next SOF. HC must check this bit whenever it determines to process the list. When disabled, HCD may modify the list. If HcControlCurrentED is pointing to an ED to be removed, HCD must advance the pointer by updating HcControlCurrentED before re-enabling processing of the list.</td></tr>
<tr><td>3</td><td>R/W</td><td>R</td><td>0x0</td><td>IsochronousEnable
This bit is used by HCD to enable/disable processing of isochronous EDs. While processing the periodic list in a Frame, HC checks the status of this bit when it finds an Isochronous ED (F=1). If set (enabled), HC continues processing the EDs. If cleared (disabled), HC halts processing of the periodic list (which now contains only isochronous EDs) and begins processing the Bulk/Control lists.
Setting this bit is guaranteed to take effect in the next Frame (not the current Frame).</td></tr>
</table>

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Offset: 0x0404				Register Name: O_HcControl
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
2	R/W	R	0x0	PeriodicListEnable This bit is set to enable the processing of periodic list in the next Frame. If cleared by HCD, processing of the periodic list does not occur after the next SOF. HC must check this bit before it starts processing the list.
1:0	R/W	R	0x0	ControlBulkServiceRatio This specifies the service ratio between Control and Bulk EDs. Before processing any of the nonperiodic lists, HC must compare the ratio specified with its internal count on how many nonempty Control EDs have been processed, in determining whether to continue serving another Control ED or switching to Bulk EDs. The internal count will be retained when crossing the frame boundary. In case of reset, HCD is responsible for restoring this value. CBSR: 0 → No. of Control EDs Over Bulk EDs Served: 1:1; 1 → 2:1; 2 → 3:1; 3 → 4:1 The default value is 0x0.

10.5.7.3 0x0408 OHCI Command Status Register (Default Value: 0x0000_0000)

Offset: 0x0408				Register Name: O_HcCommandStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:18	/	/	0x0	Reserved
17:16	R	R/W	0x0	SchedulingOverrunCount These bits are incremented on each scheduling overrun error. It is initialized to 00b and wraps around at 11b. This will be incremented when a scheduling overrun is detected even if SchedulingOverrun in *HcInterruptStatus* has already been set. This is used by HCD to monitor any persistent scheduling problem.
15:4	/	/	/	/
3	R/W	R/W	0x0	OwershipChangeRequest This bit is set by an OS HCD to request a change of control of the HC. When set HC will set the OwnershipChange field in

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Offset: 0x0408				Register Name: O_HcCommandStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				HcInterruptStatus. After the changeover, this bit is cleared and remains so until the next request from OS HCD.
2	R/W	R/W	0x0	BulklListFilled This bit is used to indicate whether there are any TDs on the Bulk list. It is set by HCD whenever it adds a TD to an ED in the Bulk list. When HC begins to process the head of the Bulk list, it checks BLF. As long as BulkListFilled is 0, HC will not start processing the Bulk list. If BulkListFilled is 1, HC will start processing the Bulk list and will set BF to 0. If HC finds a TD on the list, then HC will set BulkListFilled to 1 causing the Bulk list processing to continue. If no TD is found on the Bulk list, and if HCD does not set BulkListFilled, then BulkListFilled will still be 0 when HC completes processing the Bulk list and Bulk list processing will stop.
1	R/W	R/W	0x0	ControlListFilled This bit is used to indicate whether there are any TDs on the Control list. It is set by HCD whenever it adds a TD to an ED in the Control list. When HC begins to process the head of the Control list, it checks CLF. As long as ControlListFilled is 0, HC will not start processing the Control list. If CF is 1, HC will start processing the Control list and will set ControlListFilled to 0. If HC finds a TD on the list, then HC will set ControlListFilled to 1 causing the Control list processing to continue. If no TD is found on the Control list, and if the HCD does not set ControlListFilled, then ControlListFilled will still be 0 when HC completes processing the Control list and Control list processing will stop.
0	R/W	R/E	0x0	HostControllerReset This bit is by HCD to initiate a software reset of HC. Regardless of the functional state of HC, it moves to the USBSuspend state in which most of the operational registers are reset except those stated otherwise; e.g, the InteruptRouting field of HcControl, and no Host bus accesses are allowed. This bit is cleared by HC upon the completion of the reset operation. The reset operation must be completed within 10 ms. This bit, when set, should not cause a reset to the Root Hub and no subsequent reset signaling should be asserted to its downstream ports.

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10.5.7.4 0x040C OHCI Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x040C				Register Name: O_HcInterruptStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:7	/	/	/	/
6	R/W	R/W	0x0	RootHubStatusChange This bit is set when the content of HcRhStatus or the content of any of HcRhPortStatus[NumberofDownstreamPort] has changed.
5	R/W	R/W	0x0	FrameNumberOverflow This bit is set when the MSb of HcFmNumber (bit 15) changes value, from 0 to 1 or from 1 to 0, and after HccaFrameNumber has been updated.
4	R/W	R/W	0x0	UnrecoverableError This bit is set when HC detects a system error not related to USB. HC should not proceed with any processing nor signaling before the system error has been corrected. HCD clears this bit after HC has been reset.
3	R/W	R/W	0x0	ResumeDetected This bit is set when HC detects that a device on the USB is asserting resume signaling. It is the transition from no resume signaling to resume signaling causing this bit to be set. This bit is not set when HCD sets the USBRseume state.
2	R/W	R/W	0x0	StartofFrame This bit is set by HC at each start of frame and after the update of HccaFrameNumber. HC also generates a SOF token at the same time.
1	R/W	R/W	0x0	WritebackDoneHead This bit is set immediately after HC has written HcDoneHead to HccaDoneHead. Further updates of the HccaDoneHead will not occur until this bit has been cleared. HCD should only clear this bit after it has saved the content of HccaDoneHead.
0	R/W	R/W	0x0	SchedulingOverrun This bit is set when the USB schedule for the current Frame overruns and after the update of HccaFrameNumber. A scheduling overrun will also cause the SchedulingOverrunCount of HcCommandStatus to be Incremented.

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10.5.7.5 0x0410 OHCI Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x0410				Register Name: O_HcInterruptEnable
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31	R/W	R	0x0	MasterInterruptEnable A '0' writtern to this field is ignored by HC. A '1' written to this field enables interrupt generation due to events specified in the other bits of this register. This is used by HCD as Master Interrupt Enable.
30:7	/	/	/	/
6	R/W	R	0x0	RootHubStatusChange Interrupt Enable 0 Ignore; 1 Enable interrupt generation due to Root Hub Status Change;
5	R/W	R	0x0	FrameNumberOverflow Interrupt Enable 0 Ignore; 1 Enable interrupt generation due to Frame Number Over Flow;
4	R/W	R	0x0	UnrecoverableError Interrupt Enable 0 Ignore; 1 Enable interrupt generation due to Unrecoverable Error;
3	R/W	R	0x0	ResumeDetected Interrupt Enable 0 Ignore; 1 Enable interrupt generation due to Resume Detected;
2	R/W	R	0x0	StartofFrame Interrupt Enable 0 Ignore; 1 Enable interrupt generation due to Start of Flame;
1	R/W	R	0x0	WritebackDoneHead Interrupt Enable 0 Ignore; 1 Enable interrupt generation due to Write back Done Head;
0	R/W	R	0x0	SchedulingOverrun Interrupt Enable 0 Ignore; 1 Enable interrupt generation due to Scheduling Overrun;

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10.5.7.6 0x0414 OHCI Interrupt Disable Register (Default Value: 0x0000_0000)

Offset: 0x0414				Register Name: O_HcInterruptDisable
Bit	Read/Write		Default	Description
	HCD	HC		
31	R/W	R	0x0	MasterInterruptEnable A written '0' to this field is ignored by HC. A '1' written to this field disables interrupt generation due events specified in the other bits of this register. This field is set after a hardware or software reset.
30:7	/	/	/	/
6	R/W	R	0x0	RootHubStatusChange Interrupt Disable 0 Ignore; 1 Disable interrupt generation due to Root Hub Status Change;
5	R/W	R	0x0	FrameNumberOverflow Interrupt Disable 0 Ignore; 1 Disable interrupt generation due to Frame Number Over Flow;
4	R/W	R	0x0	UnrecoverableError Interrupt Disable 0 Ignore; 1 Disable interrupt generation due to Unrecoverable Error;
3	R/W	R	0x0	ResumeDetected Interrupt Disable 0 Ignore; 1 Disable interrupt generation due to Resume Detected;
2	R/W	R	0x0	StartofFrame Interrupt Disable 0 Ignore; 1 Disable interrupt generation due to Start of Flame;
1	R/W	R	0x0	WritebackDoneHead Interrupt Disable 0 Ignore; 1 Disable interrupt generation due to Write back Done Head;
0	R/w	R	0x0	SchedulingOverrun Interrupt Disable 0 Ignore; 1 Disable interrupt generation due to Scheduling Overrun;

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10.5.7.7 0x0418 OHCI HCCA Register (Default Value: 0x0000_0000)

Offset: 0x0418				Register Name: O_HcHCCA
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:8	R/W	R	0x0	HCCA[31:8] This is the base address of the Host Controller Communication Area. This area is used to hold the control structures and the Interrupt table that are accessed by both the Host Controller and the Host Controller Driver.
7:0	R	R	0x0	HCCA[7:0] The alignment restriction in HcHCCA register is evaluated by examining the number of zeros in the lower order bits. The minimum alignment is 256 bytes, therefore, bits 0 through 7 must always return 0 when read.

10.5.7.8 0x041C OHCI Period Current ED Register (Default Value: 0x0000_0000)

Offset: 0x041C				Register Name: O_HcPeriodCurrentED
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R	R/W	0x0	PCED[31:4] This is used by HC to point to the head of one of the Periodec list which will be processed in the current Frame. The content of this register is updated by HC after a periodic ED has been processed. HCD may read the content in determining which ED is currently being processed at the time of reading.
3:0	R	R	0x0	PCED[3:0] Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

10.5.7.9 0x0420 OHCI Control Head ED Register (Default Value: 0x0000_0000)

Offset: 0x0420				Register Name: O_HcControlHeadED
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R/W	R	0x0	EHCD[31:4] The HcControlHeadED register contains the physical address of the first

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Offset: 0x0420				Register Name: O_HcControlHeadED
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				Endpoint Descriptor of the Control list. HC traverse the Control list starting with the HcControlHeadED pointer. The content is loaded from HCCA during the initialization of HC.
3:0	R	R	0x0	EHCD[3:0] Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

10.5.7.10 0x0424 OHCI Control Current ED Register (Default Value: 0x0000_0000)

Offset: 0x0424				Register Name: HcControlCurrentED
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R/W	R/W	0x0	CCED[31:4] The pointer is advanced to the next ED after serving the present one. HC will continue processing the list from where it left off in the last Frame. When it reaches the end of the Control list, HC checks the ControlListFilled of in HcCommandStatus. If set, it copies the content of HcControlHeadED to HcControlCurrentED and clears the bit. If not set, it does nothing. HCD is allowed to modify this register only when the ControlListEnable of HcControl is cleared. When set, HCD only reads the instantaneous value of this register. Initially, this is set to zero to indicate the end of the Control list.
3:0	R	R	0x0	CCED[3:0] Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

10.5.7.11 0x0428 OHCI Bulk Head ED Register (Default Value: 0x0000_0000)

Offset: 0x0428				Register Name: O_HcBulkHeadED
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R/W	R	0x0	BHED[31:4] The HcBulkHeadED register contains the physical address of the first Endpoint Descriptor of the Bulk list. HC traverses the Bulk list

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Offset: 0x0428				Register Name: O_HcBulkHeadED
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				starting with the HcBulkHeadED pointer. The content is loaded from HCCA during the initialization of HC.
3:0	R	R	0x0	BHED[3:0] Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

10.5.7.12 0x042C OHCI Bulk Current ED Register (Default Value: 0x0000_0000)

Offset: 0x042C				Register Name: O_HcBulkCurrentED
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R/W	R/W	0x0	BulkCurrentED[31:4] This is advanced to the next ED after the HC has served the present one. HC continues processing the list from where it left off in the last Frame. When it reaches the end of the Bulk list, HC checks the ControlListFilled of HcControl. If set, it copies the content of HcBulkHeadED to HcBulkCurrentED and clears the bit. If it is not set, it does nothing. HCD is only allowed to modify this register when the BulkListEnable of *HcControl* is cleared. When set, the HCD only reads the instantaneous value of this register. This is initially set to zero to indicate the end of the Bulk list.
3:0	R	R	0x0	BulkCurrentED [3:0] Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

10.5.7.13 0x0430 OHCI Done Head Register (Default Value: 0x0000_0000)

Offset: 0x0430				Register Name: O_HcDoneHead
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R	R/W	0x0	HcDoneHead[31:4] When a TD is completed, HC writes the content of HcDoneHead to the NextTD field of the TD. HC then overwrites the content of HcDoneHead with the address of this TD. This is set to zero

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Offset: 0x0430				Register Name: O_HcDoneHead
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				whenever HC writes the content of this register to HCCA. It also sets the WritebackDoneHead of HcInterruptStatus.
3:0	R	R	0x0	HcDoneHead[3:0] Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

10.5.7.14 0x0434 OHCI Frame Interval Register (Default Value: 0x0000_2EDF)

Offset: 0x0434				Register Name: O_HcFmInterval
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31	R/W	R	0x0	FrameIntervalToggler HCD toggles this bit whenever it loads a new value to FrameInterval.
30:16	R/W	R	0x0	FSLargestDataPacket This field specifies a value which is loaded into the Largest Data Packet Counter at the beginning of each frame. The counter value represents the largest amount of data in bits which can be sent or received by the HC in a single transaction at any given time without causing scheduling overrun. The field value is calculated by the HCD.
15:14	/	/	/	/
13:0	R/W	R	0x2edf	FrameInterval This specifies the interval between two consecutive SOFs in bit times. The nominal value is set to be 11,999. HCD should store the current value of this field before resetting HC. By setting the HostControllerReset field of *HcCommandStatus* as this will cause the HC to reset this field to its nominal value. HCD may choose to restore the stored value upon the completion of the Reset sequence.

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10.5.7.15 0x0438 OHCI Frame Remaining Register (Default Value: 0x0000_0000)

Offset: 0x0438				Register Name: O_HcFmRemaining
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31	R	R/W	0x0	FrameRemaining Toggle This bit is loaded from the FrameIntervalToggle field of HcFmInterval whenever FrameRemaining reaches 0. This bit is used by HCD for the synchronization between FrameInterval and FrameRemaining.
30:14	/	/	/	/
13:0	R	RW	0x0	FramRemaining This counter is decremented at each bit time. When it reaches zero, it is reset by loading the FrameInterval value specified in HcFmInterval at the next bit time boundary. When entering the USBOPERATIONAL state, HC re-loads the content with the FrameInterval of HcFmInterval and uses the updated value from the next SOF.

10.5.7.16 0x043C OHCI Frame Number Register (Default Value: 0x0000_0000)

Offset: 0x043C				Register Name: O_HcFmNumber
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:16	/	/	/	/
15:0	R	R/W	0x0	FrameNumber This is incremented when HcFmRemaining is re-loaded. It will be rolled over to 0x0 after 0x0ffff. When entering the USBOPERATIONAL state, this will be incremented automatically. The content will be written to HCCA after HC has incremented the FrameNumber at each frame boundary and sent a SOF but before HC reads the first ED in that Frame. After writing to HCCA, HC will set the StartofFrame in HcInterruptStatus.

10.5.7.17 0x0440 OHCI Periodic Start Register (Default Value: 0x0000_0000)

Offset: 0x0440				Register Name: O_HcPeriodicStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:14	/	/	/	/

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Offset: 0x0440				Register Name: O_HcPeriodicStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
13:0	R/W	R	0x0	PeriodicStart After a hardware reset, this field is cleared. This is then set by HCD during the HC initialization. The value is calculated roughly as 10% off from HcFmInterval. A typical value will be 0x2A3F (or 0x3e67). When HcFmRemaining reaches the value specified, processing of the periodic lists will have priority over Control/Bulk processing. HC will therefore start processing the Interrupt list after completing the current Control or Bulk transaction that is in progress.

10.5.7.18 0x0444 OHCI LS Threshold Register (Default Value: 0x0000_0628)

Offset: 0x0444				Register Name: O_HcLSThreshold
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:12				Reserved
11:0	R/W	R	0x0628	LSThreshold This field contains a value which is compared to the FrameRemaining field prior to initiating a Low Speed transaction. The transaction is started only if FrameRemaining this field. The value is calculated by HCD with the consideration of transmission and setup overhead.

10.5.7.19 0x0448 OHCI Root Hub DescriptorA Register (Default Value: 0x0200_1201)

Offset: 0x0448				Register Name: O_HcRhDescriptorA
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:24	R/W	R	0x2	PowerOnToPowerGoodTime[POTPGT] This byte specifies the duration HCD has to wait before accessing a powered-on port of the Root Hub. It is implementation-specific. The unit of time is 2 ms. The duration is calculated as POTPGT * 2ms.
23:13	/	/	/	/
12	R/W	R	1	NoOverCurrentProtection This bit describes how the overcurrent status for the Root Hub ports are reported. When this bit is cleared, the

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<table>
<tr><td colspan="4">Offset: 0x0448</td><td>Register Name: O_HcRhDescriptorA</td></tr>
<tr><td rowspan="2">Bit</td><td colspan="2">Read/Write</td><td rowspan="2">Default/Hex</td><td rowspan="2">Description</td></tr>
<tr><td>HCD</td><td>HC</td></tr>
<tr><td></td><td></td><td></td><td></td><td>OverCurrentProtectionMode field specifies global or per-port reporting.<table><tr><td>0</td><td>Over-current status is reported collectively for all downstream ports.</td></tr><tr><td>1</td><td>No overcurrent protection supported.</td></tr></table></td></tr>
<tr><td>11</td><td>R/W</td><td>R</td><td>0</td><td>OverCurrentProtectionMode
This bit describes how the overcurrent status for the Root Hub ports are reported. At reset, these fields should reflect the same mode as PowerSwitchingMode. This field is valid only if the NoOverCurrentProtection field is cleared.<table><tr><td>0</td><td>Over-current status is reported collectively for all downstream ports.</td></tr><tr><td>1</td><td>Over-current status is reported on per-port basis.</td></tr></table></td></tr>
<tr><td>10</td><td>R</td><td>R</td><td>0x0</td><td>Device Type
This bit specifies that the Root Hub is not a compound device. The Root Hub is not permitted to be a compound device. This field should always read/write 0.</td></tr>
<tr><td>9</td><td>R/W</td><td>R</td><td>1</td><td>PowerSwitchingMode
This bit is used to specify how the power switching of the Root Hub ports is controlled. It is implementation-specific. This field is only valid if the NoPowerSwitching field is cleared.<table><tr><td>0</td><td>All ports are powered at the same time.</td></tr><tr><td>1</td><td>Each port is powered individually. This mode allows port power to be controlled by either the global switch or per-port
switching. If the PortPowerControlMask bit is set, the port responds only to port power commands (Set/ClearPortPower). If the port mask is cleared, then the port is controlled only by the global power switch (Set/ClearGlobalPower).</td></tr></table></td></tr>
<tr><td>8</td><td>R/W</td><td>R</td><td>0</td><td>NoPowerSwithcing
These bits are used to specify whether power switching is supported or ports are always powered. It is implementation-specific. When this bit is cleared, the PowerSwitchingMode specifies global or per-port switching.<table><tr><td>0</td><td>Ports are power switched.</td></tr></table></td></tr>
</table>

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Offset: 0x0448				Register Name: O_HcRhDescriptorA
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				1 Ports are always powered on when the HC is powered on.
7:0	R	R	0x01	NumberDownstreamPorts These bits specify the number of downstream ports supported by the Root Hub. It is implementation-specific. The minimum number of ports is 1. The maximum number of ports supported.

10.5.7.20 0x044C OHCI Root Hub DescriptorB Register (Default Value: 0x0000_0000)

Offset: 0x044C				Register Name: O_HcRhDescriptorB
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:16	R/W	R	0x0	PortPowerControlMask Each bit indicates if a port is affected by a global power control command when PowerSwitchingMode is set. When set, the port's power state is only affected by per-port power control (Set/ClearPortPower). When cleared, the port is controlled by the global power switch (Set/ClearGlobalPower). If the device is configured to global switching mode (PowerSwitchingMode = 0), this field is not valid. Bit0 Reserved Bit1 Ganged-power mask on Port #1. Bit2 Ganged-power mask on Port #2. … Bit15 Ganged-power mask on Port #15.
15:0	R/W	R	0x0	DeviceRemovable Each bit is dedicated to a port of the Root Hub. When cleared, the attached device is removable. When set, the attached device is not removable. Bit0 Reserved Bit1 Device attached to Port #1. Bit2 Device attached to Port #2. … Bit15 Device attached to Port #15.

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10.5.7.21 0x0450 OHCI Root Hub Status Register (Default Value: 0x0000_0000)

Offset: 0x0450				Register Name: O_HcRhStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31	W	R	0	(write) ClearRemoteWakeupEnable Write a '1' clears DeviceRemoteWakeupEnable. Write a '0' has no effect.
30:18	/	/	/	/
17	R/W	R	0	OverCurrentIndicatorChang This bit is set by hardware when a change has occurred to the OverCurrentIndicator field of this register. The HCD clears this bit by writing a '1'. Writing a '0' has no effect.
16	R/W	R	0x0	(read) LocalPowerStartusChange The Root Hub does not support the local power status features, thus, this bit is always read as '0'. (write) SetGlobalPower In global power mode (PowerSwitchingMode=0), This bit is written to '1' to turn on power to all ports (clear PortPowerStatus). In per-port power mode, it sets PortPowerStatus only on ports whose PortPowerControlMask bit is not set. Writing a '0' has no effect.
15	R/W	R	0x0	(read) DeviceRemoteWakeupEnable This bit enables a ConnectStatusChange bit as a resume event, causing a USBSUSPEND to USBRESUME state transition and setting the ResumeDetected interrupt. 0 ConnectStatusChange is not a remote wakeup event. 1 ConnectStatusChange is a remote wakeup event. (write) SetRemoteWakeupEnable Writing a '1' sets DeviceRemoveWakeupEnable. Writing a '0' has no effect.
14:2	/	/	/	/
1	R	R/W	0x0	OverCurrentIndicator This bit reports overcurrent conditions when the global reporting is implemented. When set, an overcurrent condition exists. When cleared, all power operations are normal. If per-port overcurrent protection is implemented this bit is always '0'

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Offset: 0x0450				Register Name: O_HcRhStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
0	R/W	R	0x0	(Read) LocalPowerStatus When read, this bit returns the LocalPowerStatus of the Root Hub. The Root Hub does not support the local power status feature; thus, this bit is always read as '0'. (Write) ClearGlobalPower When write, this bit is operated as the ClearGlobalPower. In global power mode (PowerSwitchingMode=0), This bit is written to '1' to turn off power to all ports (clear PortPowerStatus). In per-port power mode, it clears PortPowerStatus only on ports whose PortPowerControlMask bit is not set. Writing a '0' has no effect.

10.5.7.22 0x0454 OHCI Root Hub Port Status Register (Default Value: 0x0000_0100)

Offset: 0x0454				Register Name: O_HcRhPortStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:21	/	/	0x0	Reserved
20	R/W	R/W	0x0	PortResetStatusChange This bit is set at the end of the 10-ms port reset signal. The HCD writes a '1' to clear this bit. Writing a '0' has no effect. 0 port reset is not complete 1 port reset is complete
19	R/W	R/W	0x0	PortOverCurrentIndicatorChange This bit is valid only if overcurrent conditions are reported on a per-port basis. This bit is set when Root Hub changes the PortOverCurrentIndicator bit. The HCD writes a '1' to clear this bit. Writing a '0' has no effect. 0 no change in PortOverCurrentIndicator 1 PortOverCurrentIndicator has changed
18	R/W	R/W	0x0	PortSuspendStatusChange This bit is set when the full resume sequence has been completed. This sequence includes the 20-s resume pulse, LS EOP, and 3-ms resychronization delay. The HCD writes a '1' to clear this bit. Writing a '0' has no effect. This bit is also cleared when ResetStatusChange is set.

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Offset: 0x0454				Register Name: O_HcRhPortStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				0 resume is not completed 1 resume completed
17	R/W	R/W	0x0	PortEnableStatusChange This bit is set when hardware events cause the PortEnableStatus bit to be cleared. Changes from HCD writes do not set this bit. The HCD writes a '1' to clear this bit. Writing a '0' has no effect. 0 no change in PortEnableStatus 1 change in PortEnableStatus
16	R/W	R/W	0x0	ConnectStatusChange This bit is set whenever a connect or disconnect event occurs. The HCD writes a '1' to clear this bit. Writing a '0' has no effect. If CurrentConnectStatus is cleared when a SetPortReset,SetPortEnable, or SetPortSuspend write occurs, this bit is set to force the driver to re-evaluate the connection status since these writes should not occur if the port is disconnected. 0 no change in PortEnableStatus 1 change in PortEnableStatus **Note: If the DeviceRemovable[NDP] bit is set, this bit is set only after a Root Hub reset to inform the system that the device is attached.**
15:10	/	/	/	/
9	R/W	R/W	-	(read) LowSpeedDeviceAttached This bit indicates the speed of the device attached to this port. When set, a Low Speed device is attached to this port. When clear, a Full Speed device is attached to this port. This field is valid only when the CurrentConnectStatus is set. 0 full speed device attached 1 low speed device attached (write) ClearPortPower The HCD clears the PortPowerStatus bit by writing a '1' to this bit. Writing a '0' has no effect.
8	R/W	R/W	0x1	(read) PortPowerStatus This bit reflects the port's power status, regardless of the type of power switching implemented. This bit is cleared if an overcurrent condition is detected. HCD sets this bit by writing SetPortPower or

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<table>
<tr><td colspan="4">Offset: 0x0454</td><td>Register Name: O_HcRhPortStatus</td></tr>
<tr><td rowspan="2">Bit</td><td colspan="2">Read/Write</td><td rowspan="2">Default/Hex</td><td rowspan="2">Description</td></tr>
<tr><td>HCD</td><td>HC</td></tr>
<tr><td></td><td></td><td></td><td></td><td>SetGlobalPower. HCD clears this bit by writing ClearPortPower or ClearGlobalPower. Which power control switches are enabled is determined by PowerSwitchingMode and PortPortControlMask[NumberDownstreamPort]. In global switching mode(PowerSwitchingMode=0), only Set/ClearGlobalPower controls
this bit. In per-port power switching (PowerSwitchingMode=1), if the PortPowerControlMask[NDP] bit for the port is set, only
Set/ClearPortPower commands are enabled. If the mask is not set, only Set/ClearGlobalPower commands are enabled. When port power is disabled, CurrentConnectStatus, PortEnableStatus, PortSuspendStatus, and PortResetStatus should be reset.
<table><tr><td>0</td><td>port power is off</td></tr><tr><td>1</td><td>port power is on</td></tr></table>
(write) SetPortPower
The HCD writes a ‘1’ to set the PortPowerStatus bit. Writing a ‘0’ has no effect.
Note: This bit is always reads ‘1b’ if power switching is not supported.</td></tr>
<tr><td>7:5</td><td>/</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>4</td><td>R/W</td><td>R/W</td><td>0x0</td><td>(read) PortResetStatus
When this bit is set by a write to SetPortReset, port reset signaling is asserted. When reset is completed, this bit is cleared when PortResetStatusChange is set. This bit cannot be set if
CurrentConnectStatus is cleared.
<table><tr><td>0</td><td>port reset signal is not active</td></tr><tr><td>1</td><td>port reset signal is active</td></tr></table>
(write) SetPortReset
The HCD sets the port reset signaling by writing a ‘1’ to this bit. Writing a ‘0’ has no effect. If CurrentConnectStatus is cleared, this write does not set PortResetStatus, but instead sets ConnectStatusChange. This informs the driver that it attempted to reset a disconnected port.</td></tr>
<tr><td>3</td><td>R/W</td><td>R/W</td><td>0x0</td><td>(read) PortOverCurrentIndicator</td></tr>
</table>

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<table>
<tr><td colspan="3">Offset: 0x0454</td><td colspan="2">Register Name: O_HcRhPortStatus</td></tr>
<tr><td rowspan="2">Bit</td><td colspan="2">Read/Write</td><td rowspan="2">Default/Hex</td><td rowspan="2">Description</td></tr>
<tr><td>HCD</td><td>HC</td></tr>
<tr><td></td><td></td><td></td><td></td><td>This bit is only valid when the Root Hub is configured in such a way that overcurrent conditions are reported on a per-port basis. If per-port overcurrent reporting is not supported, this bit is set to 0. If cleared, all power operations are normal for this port. If set, an overcurrent condition exists on this port. This bit always reflects the overcurrent input signal.
<table><tr><td>0</td><td>no overcurrent condition.</td></tr><tr><td>1</td><td>overcurrent condition detected.</td></tr></table>
(write) ClearSuspendStatus
The HCD writes a ‘1’ to initiate a resume. Writing a ‘0’ has no effect. A resume is initiated only if PortSuspendStatus is set.</td></tr>
<tr><td>2</td><td>R/W</td><td>R/W</td><td>0x0</td><td>(read) PortSuspendStatus
This bit indicates the port is suspended or in the resume sequence. It is set by a SetSuspendState write and cleared when PortSuspendStatusChange is set at the end of the resume interval. This bit cannot be set if CurrentConnectStatus is cleared. This bit is also cleared when PortResetStatusChange is set at the end of the port reset or when the HC is placed in the USBRESUME state. If an upstream resume is in progress, it should propagate to the HC.
<table><tr><td>0</td><td>port is not suspended</td></tr><tr><td>1</td><td>port is suspended</td></tr></table>
(write) SetPortSuspend
The HCD sets the PortSuspendStatus bit by writing a ‘1’ to this bit. Writing a ‘0’ has no effect. If CurrentConnectStatus is cleared, this write does not set PortSuspendStatus; instead it sets ConnectStatusChange. This informs the driver that it attempted to suspend a disconnected port.</td></tr>
<tr><td>1</td><td>R/W</td><td>R/W</td><td>0x0</td><td>(read) PortEnableStatus
This bit indicates whether the port is enabled or disabled. The Root Hub may clear this bit when an overcurrent condition, disconnect event, switched-off power, or operational bus error such as babble is detected. This change also causes PortEnabledStatusChange to be set. HCD sets this bit by writing SetPortEnable and clears it by writing ClearPortEnable. This bit cannot be set when CurrentConnectStatus is cleared. This bit is</td></tr>
</table>

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Offset: 0x0454				Register Name: O_HcRhPortStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				also set, if not already, at the completion of a port reset when ResetStatusChange is set or port suspend when SuspendStatusChange is set. 0 port is disabled 1 port is enabled (write) SetPortEnable The HCD sets PortEnableStatus by writing a '1'. Writing a '0' has no effect. If CurrentConnectStatus is cleared, this write does not set PortEnableStatus, but instead sets ConnectStatusChange. This informs the driver that it attempted to enable a disconnected Port.
0	R/W	R/W	0x0	(read) CurrentConnectStatus This bit reflects the current state of the downstream port. 0 No device connected 1 Device connected (write) ClearPortEnable The HCD writes a '1' to clear the PortEnableStatus bit. Writing '0' has no effect. The CurrentConnectStatus is not affected by any write. **Note: This bit is always read '1' when the attached device is nonremovalble(DviceRemoveable[NumberDownstreamPort]).**

10.5.8 HCI Contgroller and PHY Interface Description

10.5.8.1 0x0800 HCI Interface Register (Default Value: 0x0000_0000)

Offset: 0x0800			Register Name: USB_CTRL
Bit	Read/Write	Default/Hex	Description
31	R/W	0x0	USB Standby Clock Sel 0x0: normal mode usb clock as usual 0x1: standby mode usb clock switch to RC 16M clock
30:29	/	/	Reserved.
			DMA Transfer Status Enable

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Offset: 0x0800			Register Name: USB_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
28	R	1	0: Disable 1: Enable
27:26	/	/	/
25	R/W	0	OHCI count select 1: Simulation mode, the counters will be much shorter then real time 0: Normal mode, the counters will count full time
24	R/W	0	Simulation mode 1: Set PHY in a non-driving mode so the EHCI can detect device connection, this is used only for simulation 0: No effect
23:21	/	/	/
20	R/W	0	EHCI HS force Set 1 to this field force the ehci enter the high speed mode during bus reset. This field only valid when the bit 1 is set.
19	/	/	/
18	R/W	0	1: within 2us of the resume-K to SE0 transition 0: random time value of the resume-K to SE0 transition
17:13	/	/	/
12	R/W	0	PP2VBUS 1: ULPI wrapper interface will automatically set or clear DrvVbus register in ULPI PHY according to the port power status form the root hub 0: ULPI wrapper will ignore the difference between power status of root hub and ULPI PHY
11	R/W	0	AHB Master interface INCR16 enable 1: Use INCR16 when appropriate 0: do not use INCR16,use other enabled INCRX or unspecified length burst INCR
10	R/W	0	AHB Master interface INCR8 enable 1: Use INCR8 when appropriate 0: do not use INCR8,use other enabled INCRX or unspecified length burst INCR
9	R/W	0	AHB Master interface burst type INCR4 enable 1: Use INCR4 when appropriate

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Offset: 0x0800			Register Name: USB_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
			0: do not use INCR4,use other enabled INCRX or unspecified length burst INCR
8	R/W	0	AHB Master interface INCRX align enable 1: start INCRx burst only on burst x-align address 0: Start burst on any double word boundary Note: This bit must enable if any bit of 11:9 is enabled
7:4	/	/	/
3	R/W	0x0	RC Clock Gating 0x0: clock gated 0x1: clock ungated
2	R/W	0x0	RC Generation Enable 0x0: disable 0x1: enable
1	/	/	/
0	R/W	0	ULPI bypass enable 1: Enable UTMI interface, disable ULPI interface 0: Enable ULPI interface, disable UTMI interface

10.5.8.2 0x0808 HCI Control 3 Register (Default Value: 0x0000_0000)

Offset: 0x0808			Register Name: HCI_CTRL3
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	Reserved.
16	R/W1C	1	Linestate Change Detect 0: Linestate change not dected. 1: Linestate change dected. Write '1' to clear.
15:4	/	/	Reserved.
3	R/W	0	Remote Wakeup Enable 1: Enable 0: Disable
2	/	/	Reserved.
1	R/W	0	Linestate Change Interrupt Enable 1: Enable 0: Disable
0	R/W	0	Linestate Change Detect Enable

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Offset: 0x0808			Register Name: HCI_CTRL3
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: Enable 0: Disable

10.5.8.3 0x0810 PHY Control Register (Default Value: 0x0000_0008)

Offset: 0x0810			Register Name: PHY_CTRL(Default Value: 0x0000_0008)
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0	bist_en_a
15:8	R/W	0	vc_addr
7	R/W	0	vc_di
6:4	/	/	/
3	R/W	1	SIDDQ 1: Write 1 to disable phy. 0: Write 0 to enable phy.
2	/	/	/
1	R/W	0	vc_en 0: Write 0 to disable phy vc bus 1: Write 1 to enable phy vc bus. Note:only 1 VC bus of all the usb controllers could be enabled at the same time
0	R/W	0	vc_clk

10.5.8.4 0x0824 PHY Status Register (USB1) (Default Value: 0x0000_0000)

Offset: 0x0824			Register Name: PHY_STA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R	0	Bist_error
16	R	0	bist_done
15:1	/	/	/
0	R	0	vc_do

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10.5.8.5 0x0828 HCI SIE Port Disable Control Register (Default Value: 0x0000_0003)

Offset: 0x0828			Register Name: USB_SPDCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0	SE0 Status This bit is set when no-se0 is detected before SOF when bit[1:0] is 10b or 11b
15:5	/	/	/
4	R/W	0	resume_sel When set k-se0 transition 2us, setting this bit to 1, which is cooperated with ss_utmi_backward_enb_i.
3:2	/	/	/
1:0	R/W	0x3	Port Disable Control 00: Port Disable when no-se0 detect before SOF 01: Port Disable when no-se0 detect before SOF 10: No Port Disable when no-se0 detect before SOF 11:Port Disable when no-se0 3 time detect before SOF during 8 Frames

10.5.8.6 0x0830 USB Version Number Register (Default Value: 0x0010_0001)

Offset: 0x0830			Register Name: USB_HCIVER
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:16	R	0x10	USB2_PHY Version Number
15:8	R	0x00	DRD Version Number
7:0	R	0x01	HCI Version Number

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10.6 USB2.0 HOST

10.6.1 Overview

The USB Host Controller is fully compliant with USB 2.0 Specification, Enhanced Host Controller Interface (EHCI) Specification Revision 1.0 and Open Host Controller Interface (OHCI) Specification Release 1.0a.

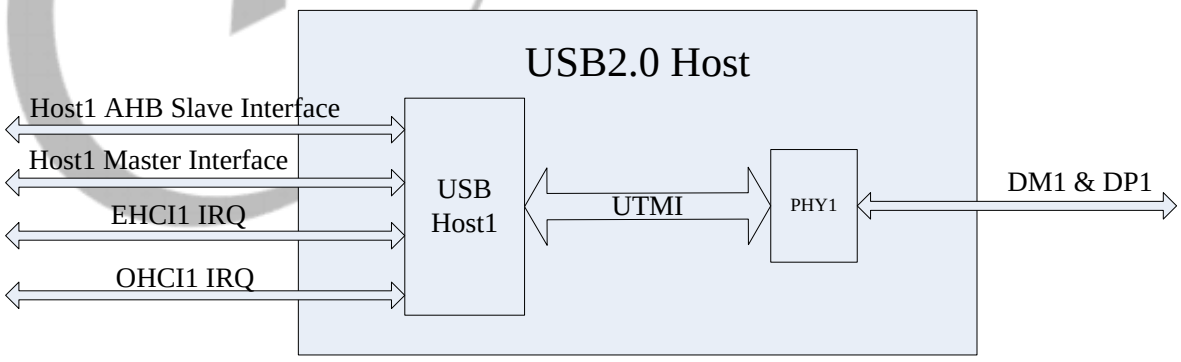
The USB2.0 host controller includes the following features:

- Complies with USB2.0 Specification
- Supports USB2.0 Host function
  - Compatible with Enhanced Host Controller Interface (EHCI) Specification, Version 1.0
  - Compatible with Open Host Controller Interface (OHCI) Specification, Version 1.0a
  - Supports High-Speed (HS, 480 Mbit/s), Full-Speed (FS, 12 Mbit/s) and Low-Speed (LS, 1.5 Mbit/s) Device
  - Supports only 1 USB Root port shared between EHCI and OHCI
- An internal DMA Controller for data transfer with memory

10.6.2 Block Diagram

The following figure shows the block diagram of USB2.0 Host Controller.

Figure 10-65 USB2.0 Host Controller Block Diagram



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10.6.3 Functional Description

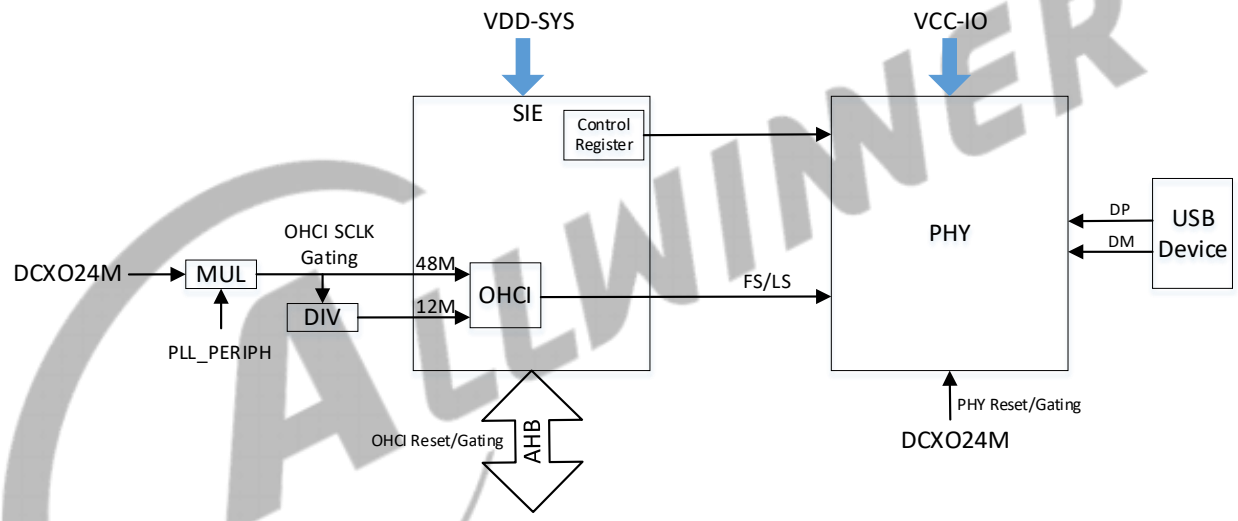
10.6.3.1 External Signals

Table 10-19 USB2.0 Host External Signals

Signal	Description	Type
USB1-DP	USB2.0 Host differential signal positive	AI/O
USB1-DM	USB2.0 Host differential signal negative	AI/O

10.6.3.2 Controller and PHY Connection Diagram

Figure 10-66 USB2.0 Host Controller and PHY Connection Diagram



10.6.4 Register List

Module Name	Base Address
USB1	0x04200000

Register Name	Offset	Description
EHCI Capability Register		
E_CAPLENGTH	0x0000	EHCI Capability Register Length Register
E_HCIVERSION	0x0002	EHCI Host Interface Version Number Register
E_HCSPARAMS	0x0004	EHCI Host Control Structural Parameter Register
E_HCCPARAMS	0x0008	EHCI Host Control Capability Parameter Register

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Register Name	Offset	Description
E_HCSPPORTROUTE	0x000C	EHCI Companion Port Route Description
EHCI Operational Register		
E_USBCMD	0x0010	EHCI USB Command Register
E_USBSTS	0x0014	EHCI USB Status Register
E_USBINTR	0x0018	EHCI USB Interrupt Enable Register
E_FRINDEX	0x001C	EHCI USB Frame Index Register
E_CTRLDSSEGMENT	0x0020	EHCI 4G Segment Selector Register
E_PERIODICLISTBASE	0x0024	EHCI Frame List Base Address Register
E_ASYNCLISTADDR	0x0028	EHCI Next Asynchronous List Address Register
E_CONFIGFLAG	0x0050	EHCI Configured Flag Register
E_PORTSC	0x0054	EHCI Port Status/Control Register
OHCI Control and Status Partition Register		
O_HcControl	0x0404	OHCI Control Register
O_HcCommandStatus	0x0408	OHCI Command Status Register
O_HcInterruptStatus	0x040C	OHCI Interrupt Status Register
O_HcInterruptEnable	0x0410	OHCI Interrupt Enable Register
O_HcInterruptDisable	0x0414	OHCI Interrupt Disable Register
OHCI Memory Pointer Partition Register		
O_HcHCCA	0x0418	OHCI HCCA Base
O_HcPeriodCurrentED	0x041C	OHCI Period Current ED Base
O_HcControlHeadED	0x0420	OHCI Control Head ED Base
O_HcControlCurrentED	0x0424	OHCI Control Current ED Base
O_HcBulkHeadED	0x0428	OHCI Bulk Head ED Base
O_HcBulkCurrentED	0x042C	OHCI Bulk Current ED Base
O_HcDoneHead	0x0430	OHCI Done Head Base
OHCI Frame Counter Partition Register		
O_HcFmInterval	0x0434	OHCI Frame Interval Register
O_HcFmRemaining	0x0438	OHCI Frame Remaining Register
O_HcFmNumber	0x043C	OHCI Frame Number Register
O_HcPerioddicStart	0x0440	OHCI Periodic Start Register
O_HcLSThreshold	0x0444	OHCI LS Threshold Register
OHCI Root Hub Partition Register		
O_HcRhDescriptorA	0x0448	OHCI Root Hub Descriptor Register A
O_HcRhDesriptorB	0x044C	OHCI Root Hub Descriptor Register B

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Register Name	Offset	Description
O_HcRhStatus	0x0450	OHCI Root Hub Status Register
O_HcRhPortStatus	0x0454	OHCI Root Hub Port Status Register
HCI Controller and PHY Interface Register		
HCI_Interface	0x0800	HCI Interface Register
HCI_CTRL3	0x0808	HCI Control Register
PHY_Control	0x0810	PHY Control Register
PHY_STATUS	0x0824	PHY Status Register
HCI SIE Port Disable Control	0x0828	HCI SIE Port Disable Control Register

10.6.5 EHCI Register Description

10.6.5.1 0x0000 EHCI Identification Register (Default Value:0x10)

Offset:0x0000			Register Name: CAPLENGTH
Bit	**Read/Write**	**Default/Hex**	**Description**
7:0	R	0x10	CAPLENGTH The value in these bits indicates an offset to add to register base to find the beginning of the Operational Register Space.

10.6.5.2 0x0002 EHCI Host Interface Version Number Register (Default Value:0x0100)

Offset: 0x0002			Register Name: HCIVERSION
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R	0x0100	HCIVERSION This is a 16-bit register containing a BCD encoding of the EHCI revision number supported by this host controller. The most significant byte of this register represents a major revision and the least significant byte is the minor revision.

10.6.5.3 0x0004 EHCI Host Control Structural Parameter Register (Default Value:0x0000_1101)

Offset: 0x0004			Register Name: HCSPARAMS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:20	R	0x0	Debug Port Number

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<table>
<tr><th colspan="3">Offset: 0x0004</th><th>Register Name: HCSPARAMS</th></tr>
<tr><th>Bit</th><th>Read/Write</th><th>Default/Hex</th><th>Description</th></tr>
<tr><td></td><td></td><td></td><td>This register identifies which of the host controller ports is the debug port. The value is the port number (one based) of the debug port.
This field will always be ‘0’.</td></tr>
<tr><td>19:16</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>15:12</td><td>R</td><td>0x1</td><td>Number of Companion Controller (N_CC)
This field indicates the number of companion controllers associated with this USB2.0 host controller. A zero in this field indicates there are no companion host controllers. And a value larger than zero in this field indicates there are companion USB1.1 host controller(s).
This field will always be ‘0’.</td></tr>
<tr><td>11:8</td><td>R</td><td>0x1</td><td>Number of Port per Companion Controller (N_PCC)
This field indicates the number of ports supported per companion host controller host controller. It is used to indicate the port routing configuration to system software.
This field will always fix with ‘0’.</td></tr>
<tr><td>7</td><td>R</td><td>0x0</td><td>Port Routing Rules
This field indicates the method used by this implementation for how all ports are mapped to companion controllers. The value of this field has the following interpretation:
<table>
<tr><th>Value</th><th>Meaning</th></tr>
<tr><td>0</td><td>The first N_PCC ports are routed to the lowest numbered function companion host controller, the next N_PCC port are routed to the next lowest function companion controller, and so on.</td></tr>
<tr><td>1</td><td>The port routing is explicitly enumerated by the first N_PORTS elements of the HCSP-PORTTOUTE array.</td></tr>
</table>
This field will always be ‘0’.</td></tr>
<tr><td>6:4</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>3:0</td><td>R</td><td>0x1</td><td>N_PORTS
This field specifies the number of physical downstream ports implemented on this host controller. The value of this field determines how many port registers are addressable in the Operational Register Space. Valid values are in the range of 0x1 to 0x0f.
This field is always 1.</td></tr>
</table>

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10.6.5.4 0x0008 EHCI Host Control Capability Parameter Register (Default Value:0x0000_A026)

Offset: 0x0008			Register Name: HCCPARAMS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:8	R	0xA0	EHCI Extended Capabilities Pointer (EECP) This optional field indicates the existence of a capabilities list. A value of 00b indicates no extended capabilities are implemented. A non-zero value in this register indicates the offset in PCI configuration space of the first EHCI extended capabiliby. The pointer value must be 40h or greater if implemented to maintain to consistency of the PCI header defined for this calss of device. The value of this field is always '00b'.
7:4	R	0x2	Isochronous Scheduling Threshold This field indicates, relative to the current position of the executing host controller, where software can reliably update the isochronous schedule. When bit[7] is zero, the value of the least significant 3 bits indicates the number of micro-frames a host controller can hold a set of isochronous data structures(one or more) before flushing the state. When bit[7] is a one, then host software assumes the host controller may cache an isochronous data structure for an entire frame.
3	/	/	/
2	R	0x1	Asynchronous Schedule Park Capability If this bit is set to a one, then the host controller supports the park feature for high-speed queue heads in the Asynchronous Schedule. The feature can be disabled or enabled and set to a specific level by using the Asynchronous Schedule Park Mode Enable and Asynchronous Schedule Park Mode Count fields in the USBCMD register.
1	R	0x1	Programmable Frame List Flag If this bit is set to a zero, then system software must use a frame list length of 1024 elements with this host controller. The USBCMD register Frame List Size field is a read-only register and should be set to zero. If set to 1, then system software can specify and use the frame list in the USBCMD register Frame List Size field to cofigure the host controller. The frame list must always aligned on a 4K page boundary. This requirement ensures that the frame list is always physically contiguous.
0	/	/	/

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10.6.5.5 0x000C EHCI Companion Port Route Description (Default Value:0x0000_0000)

Offset: 0x000C			Register Name: HCSP-PORTROUTE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	HCSP-PORTROUTE This optional field is valid only if Port Routing Rules field in HCSPARAMS register is set to a one. This field is used to allow a host controller implementation to explicitly describe to which companion host controller each implemented port is mapped. This field is a 15-element nibble array (each 4 bit is one array element). Each array location corresponds one-to-one with a physical port provided by the host controller (e.g. PORTROUTE [0] corresponds to the first PORTSC port, PORTROUTE [1] to the second PORTSC port, etc.). The value of each element indicates to which the companion host controllers this port is routed. Only the first N_PORTS elements have valid information. A value of zero indicates that the port is routed to the lowest numbered function companion host controller. A value of one indicates that the port is routed to the next lowest numbered function companion host controller, and so on.

10.6.5.6 0x0010 EHCI USB Command Register (Default Value:0x0008_0B00)

Offset: 0x0010			Register Name: USBCMD
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23:16	R/W	0x08	Interrupt Threshold Control The value in this field is used by system software to select the maximum rate at which the host controller will issue interrupts. The only valid values are defined below:

Value	Minimum Interrupt Interval
0x00	Reserved
0x01	1 micro-frame
0x02	2 micro-frame
0x04	4 micro-frame
0x08	8 micro-frame(default, equates to 1 ms)
0x10	16 micro-frame(2ms)
0x20	32 micro-frame(4ms)
0x40	64 micro-frame(8ms)

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Offset: 0x0010			Register Name: USBCMD
Bit	**Read/Write**	**Default/Hex**	**Description**
			Any other value in this register yields undefined results. The default value in this field is 0x08 . Software modifications to this bit while HC Halted bit is equal to zero results in undefined behavior.
15:12	/	/	/
11	R	0x1	Asynchronous Schedule Park Mode Enable (OPTIONAL) If the Asynchronous Park Capability bit in the HCCPARAMS register is a one, then this bit defaults to a 1 and is R/W. Otherwise the bit must be a zero and is Read Only. Software uses this bit to enable or disable Park mode. When this bit is one, Park mode is enabled. When this bit is zero, Park mode is disabled.
10	/	/	/
9:8	R	0x3	Asynchronous Schedule Park Mode Count (OPTIONAL) Asynchronous Park Capability bit in the HCCPARAMS register is a one, then this field defaults to 0x3 and is W/R. Otherwise it defaults to zero and is R. It contains a count of the number of successive transactions the host controller is allowed to execute from a high-speed queue head on the Asynchronous schedule before continuing traversal of the Asynchronous schedule. Valid value are 0x1 to 0x3.Software must not write a zero to this bit when Park Mode Enable is a one as it will result in undefined behavior.
7	R/W	0x0	Light Host Controller Reset (OPTIONAL) This control bit is not required. If implemented, it allows the driver to reset the EHCI controller without affecting the state of the ports or relationship to the companion host controllers. For example, the PORSTC registers should not be reset to their default values and the CF bit setting should not go to zero (retaining port ownership relationships). A host software read of this bit as zero indicates the Light Host Controller Reset has completed and it si safe for software to re-initialize the host controller. A host software read of this bit as a one indicates the Light Host
6	R/W	0x0	Interrupt on Async Advance Doorbell This bit is used as a doorbell by software to tell the host controller to issue an interrupt the next time it advances asynchronous schedule. Software must write a 1 to this bit to ring the doorbell. When the host controller has evicted all appropriate cached schedule state, it sets the Interrupt on Async Advance status bit in the USBSTS. if the Interrupt on Async Advance Enable bit in the

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<table>
<tr><td colspan="3">Offset: 0x0010</td><td>Register Name: USBCMD</td></tr>
<tr><td>Bit</td><td>Read/Write</td><td>Default/Hex</td><td>Description</td></tr>
<tr><td></td><td></td><td></td><td>USBINTR register is a one then the host controller will assert an interrupt at the next interrupt threshold.
The host controller sets this bit to a zero after it has set the Interrupt on Async Advance status bit in the USBSTS register to a one.
Software should not write a one to this bit when the asynchronous schedule is disabled. Doing so will yield undefined results.</td></tr>
<tr><td>5</td><td>R/W</td><td>0x0</td><td>Asynchronous Schedule Enable
This bit controls whether the host controller skips processing the Asynchronous Schedule. Values mean:<table><tr><td>Bit Value</td><td>Meaning</td></tr><tr><td>0</td><td>Do not process the Asynchronous Schedule.</td></tr><tr><td>1</td><td>Use the ASYNLISTADDR register to access the Asynchronous Schedule.</td></tr></table>The default value of this field is ‘0b’.</td></tr>
<tr><td>4</td><td>R/W</td><td>0x0</td><td>Periodic Schedule Enable
This bit controls whether the host controller skips processing the Periodic Schedule. Values mean:<table><tr><td>Bit Value</td><td>Meaning</td></tr><tr><td>0</td><td>Do not process the Periodic Schedule.</td></tr><tr><td>1</td><td>Use the PERIODICLISTBASE register to access the Periodic Schedule.</td></tr></table>The default value of this field is ‘0b’.</td></tr>
<tr><td>3:2</td><td>R/W</td><td>0x0</td><td>Frame List Size
This field is R/W only if Programmable Frame List Flag in the HCCPARAMS registers is set to a one. This field specifies the size of the
Frame list. The size the frame list controls which bits in the Frame Index
Register should be used for the Frame List Current index. Values mean:<table><tr><td>Bits</td><td>Meaning</td></tr><tr><td>00b</td><td>1024 elements(4096bytes)Default value</td></tr><tr><td>01b</td><td>512 elements(2048byts)</td></tr><tr><td>10b</td><td>256 elements(1024bytes)For resource-constrained condition</td></tr><tr><td>11b</td><td>reserved</td></tr></table>The default value is ‘00b’.</td></tr>
</table>

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Offset: 0x0010			Register Name: USBCMD
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	Host Controller Reset This control bit is used by software to reset the host controller. The effects of this on Root Hub registers are similar to a Chip Hardware Reset. When software writes a one to this bit, the Host Controller resets its internal pipelines, timers, counters, state machines, etc. to their initial value. Any transaction currently in progress on USB is immediately terminated. A USB reset is not driven on downstream ports. All operational registers, including port registers and port state machines are set to their initial values. Port ownership reverts to the companion host controller(s). Software must reinitialize the host controller as described in Section 4.1 of the CHEI Specification in order to return the host controller to an operational state. This bit is set to zero by the Host Controller when the reset process is complete. Software cannot terminate the reset process early by writing a zero to this register. Software should not set this bit to a one when the HC Halted bit in the USBSTS register is a zero. Attempting to reset an actively running host controller will result in undefined behavior.
0	R/W	0x0	Run/Stop When set to a 1, the Host Controller proceeds with execution of the schedule. When set to 0, the Host Controller completes the current and any actively pipelined transactions on the USB and then halts. The Host Controller must halt within 16 micro-frames after software clears this bit. The HC Halted bit indicates when the Host Controller has finished its pending pipelined transactions and has entered the stopped state. Software must not write a one to this field unless the Host Controller is in the Halt State. The default value is 0x0.

10.6.5.7 0x0014 EHCI USB Status Register (Default Value:0x0000_1000)

Offset: 0x0014			Register Name: USBSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15	R	0x0	Asynchronous Schedule Status

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Offset: 0x0014			Register Name: USBSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
			The bit reports the current real status of Asynchronous Schedule. If this bit is a zero then the status of the Asynchronous Schedule is disabled. If this bit is a one then the status of the Asynchronous Schedule is enabled. The Host Controller is not required to immediately disable or enable the Asynchronous Schedule when software transitions the Asynchronous Schedule Enable bit in the USBCMD register. When this bit and the Asynchronous Schedule Enable bit are the same value, the Asynchronous Schedule is either enabled (1) or disabled (0).
14	R	0x0	Periodic Schedule Status The bit reports the current real status of the Periodic Schedule. If this bit is a zero then the status of the Periodic Schedule is disabled. If this bit is a one then the status of the Periodic Schedule is enabled. The Host Controller is not required to *immediately* disable or enable the Periodic Schedule when software transitions the *Periodic Schedule Enable* bit in the USBCMD register. When this bit and the *Periodic Schedule Enable* bit are the same value, the Periodic Schedule is either enabled (1) or disabled (0).
13	R	0x0	Reclamation This is a read-only status bit, which is used to detect an empty asynchronous schedule.
12	R	0x1	HC Halted This bit is a zero whenever the Run/Stop bit is a one. The Host Controller Sets this bit to one after it has stopped executing as a result of the Run/Stop bit being set to 0, either by software or by the Host Controller Hardware (e.g. internal error). The default value is '1'.
11:6	/	/	/
5	R/WC	0x0	Interrupt on Async Advance System software can force the host controller to issue an interrupt the next time the host controller advances the asynchronous schedule by writing a one to the Interrupt on Async Advance Doorbell bit in the USBCMD register. This status bit indicates the assertion of that interrupt source.
4	R/WC	0x0	Host System Error The Host Controller set this bit to 1 when a serious error occurs during a host system access involving the Host Controller module. When this error occurs, the Host Controller clears the Run/Stop bit in the Command register to prevent further execution of the scheduled TDs.
3	R/WC	0x0	Frame List Rollover

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Offset: 0x0014			Register Name: USBSTS
Bit	**Read/Write**	**Default/Hex**	**Description**
			The Host Controller sets this bit to a one when the Frame List Index rolls over from its maximum value to zero. The exact value at which the rollover occurs depends on the frame list size. For example, if the frame list size is 1024, the Frame Index Register rolls over every time FRINDEX [13] toggles. Similarly, if the size is 512, the Host Controller sets this bit to a one every time FRINDEX [12] toggles.
2	R/WC	0x0	Port Change Detect The Host Controller sets this bit to a one when any port for which the Port Owner bit is set to zero has a change bit transition from a zero to a one or a Force Port Resume bit transition from a zero to a one as a result of a J-K transition detected on a suspended port. This bit will also be set as a result of the Connect Status Chang being set to a one after system software has relinquished ownership of a connected port by writing a one to a port's Port Owner bit.
1	R/WC	0x0	USB Error Interrupt(USBERRINT) The Host Controller sets this bit to 1 when completion of USB transaction results in an error condition(e.g. error counter underflow).If the TD on which the error interrupt occurred also had its IOC bit set, both. This bit and USBINT bit are set.
0	R/WC	0x0	USB Interrupt(USBINT) The Host Controller sets this bit to a one on the completion of a USB transaction, which results in the retirement of a Transfer Descriptor that had its IOC bit set. The Host Controller also sets this bit to 1 when a short packet is detected (actual number of bytes received was less than the expected number of bytes)

10.6.5.8 0x0018 EHCI USB Interrupt Enable Register (Default Value:0x0000_0000)

Offset: 0x0018			Register Name: USBINTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:6	/	/	/
5	R/W	0x0	Interrupt on Async Advance Enable When this bit is 1, and the Interrupt on Async Advance bit in the USBSTS register is 1, the host controller will issue an interrupt at the next interrupt threshold. The interrupt is acknowledged by software clearing the Interrupt on Async Advance bit.

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Offset: 0x0018			Register Name: USBINTR
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W	0x0	Host System Error Enable When this bit is 1, and the Host System Error Status bit in the USBSTS register is 1, the host controller will issue an interrupt. The interrupt is acknowledged by software clearing the Host System Error bit.
3	R/W	0x0	Frame List Rollover Enable When this bit is 1, and the Frame List Rollover bit in the USBSTS register is 1, the host controller will issue an interrupt. The interrupt is acknowledged by software clearing the Frame List Rollover bit.
2	R/W	0x0	Port Change Interrupt Enable When this bit is 1, and the Port Chang Detect bit in the USBSTS register is 1, the host controller will issue an interrupt. The interrupt is acknowledged by software clearing the Port Chang Detect bit.
1	R/W	0x0	USB Error Interrupt Enable When this bit is 1, and the USBERRINT bit in the USBSTS register is 1,the host controller will issue an interrupt at the next interrupt threshold. The interrupt is acknowledged by software clearing the USBERRINT bit.
0	R/W	0x0	USB Interrupt Enable When this bit is 1, and the USBINT bit in the USBSTS register is 1,the host controller will issue an interrupt at the next interrupt threshold. The interrupt is acknowledged by software clearing the USBINT bit

10.6.5.9 0x001C EHCI Frame Index Register (Default Value:0x0000_0000)

Offset: 0x001C			Register Name: FRINDEX
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	/	/	/
13:0	R/W	0	Frame Index The value in this register increment at the end of each time frame (e.g. micro-frame). Bits[N:3] are used for the Frame List current index. It means that each location of the frame list is accessed 8 times (frames or Micro-frames) before moving to the next index. The following illustrates values of N based on the value of the Frame List Size field in the USBCMD register.

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Offset: 0x001C			Register Name: FRINDEX
Bit	Read/Write	Default/Hex	Description
			USBCMD[Frame List Size] / Number Elements / N 00b / 1024 / 12 01b / 512 / 11 10b / 256 / 10 11b / Reserved /

NOTE

This register must be written as a DWord. Byte writes produce undefined results.

10.6.5.10 0x0024 EHCI Periodic Frame List Base Address Register (Default Value:0x0000_0000)

Offset: 0x0024			Register Name: PERIODICLISTBASE
Bit	Read/Write	Default/Hex	Description
31:12	R/W	0x0	Base Address These bits correspond to memory address signals [31:12], respectively. This register contains the beginning address of the Periodic Frame List in the system memory. System software loads this register prior to starting the schedule execution by the Host Controller. The memory structure referenced by this physical memory pointer is assumed to be 4 Kbyte aligned. The contents of this register are combined with the Frame Index Register (FRINDEX) to enable the Host Controller to step through the Periodic Frame List in sequence.
11:0	/	/	/

NOTE

Writes must be Dword Writes.

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10.6.5.11 0x0028 EHCI Current Asynchronous List Address Register (Default Value:0x0000_0000)

Offset: 0x0028			Register Name: ASYNCLISTADDR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:5	R/W	0x0	Link Pointer (LP) This field contains the address of the next asynchronous queue head to be executed. These bits correspond to memory address signals [31:5], respectively.
4:0	/	/	/

NOTE

Write must be DWord Writes.

10.6.5.12 0x0050 EHCI Configure Flag Register (Default Value:0x0000_0000)

Offset: 0x0050			Register Name: CONFIGFLAG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	Configure Flag (CF) Host software sets this bit as the last action in its process of configuring the Host Controller. This bit controls the default port-routing control logic as follow: Value: 0 — Port routing control logic default-routs each port to an implementation dependent classic host controller. Value: 1 — Port routing control logic default-routs all ports to this host controller. The default value of this field is '0'.

NOTE

This register is not used in the normal implementation.

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10.6.5.13 0x0054 EHCI Port Status and Control Register (Default Value:0x0000_2000)

<table>
<tr><th colspan="3">Offset: 0x0054</th><th>Register Name: PORTSC</th></tr>
<tr><th>Bit</th><th>Read/Write</th><th>Default/Hex</th><th>Description</th></tr>
<tr><td>31:22</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>21</td><td>R/W</td><td>0x0</td><td>Wake on Disconnect Enable (WKDSCNNT_E)
Writing this bit to a one enables the port to be sensitive to device disconnects as wake-up events.
This field is zero if Port Power is zero.
The default value in this field is ‘0’.</td></tr>
<tr><td>20</td><td>R/W</td><td>0x0</td><td>Wake on Connect Enable (WKCNNT_E)
Writing this bit to a one enable the port to be sensitive to device connects as wake-up events.
This field is zero if Port Power is zero.
The default value in this field is ‘0’.</td></tr>
<tr><td>19:16</td><td>R/W</td><td>0x0</td><td>Port Test Control
The value in this field specifies the test mode of the port. The encoding of the test mode bits are as follows:
<table>
<tr><td>Bits</td><td>Test Mode</td></tr>
<tr><td>0000b</td><td>The port is NOT operating in a test mode.</td></tr>
<tr><td>0001b</td><td>Test J_STATE</td></tr>
<tr><td>0010b</td><td>Test K_STATE</td></tr>
<tr><td>0011b</td><td>Test SE0_NAK</td></tr>
<tr><td>0100b</td><td>Test Packet</td></tr>
<tr><td>0101b</td><td>Test FORCE_ENABLE</td></tr>
<tr><td>0110b-1111b</td><td>Reserved</td></tr>
</table>
The default value in this field is ‘0000b’.</td></tr>
<tr><td>15:14</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>13</td><td>R/W</td><td>0x1</td><td>Port Owner
This bit unconditionally goes to a 0b when the Configured bit in the CONFIGFLAG register makes a 0b to 1b transition. This bit unconditionally goes to 1b whenever the Configured bit is zero.
System software uses this field to release ownership of the port to selected host controller (in the event that the attached device is not a high-speed device).Software writes a one to this bit when the attached device is not a high-speed device. A one in this bit means that a companion host controller owns and controls the port.
Default Value = 1b.</td></tr>
<tr><td>12</td><td>/</td><td>/</td><td>/</td></tr>
</table>

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<table>
<tr><th colspan="3">Offset: 0x0054</th><th>Register Name: PORTSC</th></tr>
<tr><th>Bit</th><th>Read/Write</th><th>Default/Hex</th><th>Description</th></tr>
<tr><td>11:10</td><td>R</td><td>0x0</td><td>Line Status
These bits reflect the current logical levels of the D+ (bit11) and D- (bit10) signal lines. These bits are used for detection of low-speed USB devices prior to port reset and enable sequence. This read only field is valid only when the port enable bit is zero and the current connect status bit is set to a one.
The encoding of the bits are:
<table>
<tr><td>Bit[11:10]</td><td>USB State</td><td>Interpretation</td></tr>
<tr><td>00b</td><td>SE0</td><td>Not Low-speed device, perform EHCI reset.</td></tr>
<tr><td>10b</td><td>J-state</td><td>Not Low-speed device, perform EHCI reset.</td></tr>
<tr><td>01b</td><td>K-state</td><td>Low-speed device, release ownership of port.</td></tr>
<tr><td>11b</td><td>Undefined</td><td>Not Low-speed device, perform EHCI reset.</td></tr>
</table>
This value of this field is undefined if Port Power is zero.</td></tr>
<tr><td>9</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>8</td><td>R/W</td><td>0x0</td><td>Port Reset
1=Port is in Reset. 0=Port is not in Reset. Default value = 0.
When software writes a one to this bit (from a zero), the bus reset sequence as defined in the USB Specification Revision 2.0 is started. Software writes a zero to this bit to terminate the bus reset sequence. Software must keep this bit at a one long enough to ensure the reset sequence, as specified in the USB Specification Revision 2.0, completes.
Note: When software writes this bit to a one , it must also write a zero to the Port Enable bit.

Note that when software writes a zero to this bit there may be a delay before the bit status changes to a zero. The bit status will not read as a zero until after the reset has completed. If the port is in high-speed mode after reset is complete, the host controller will automatically enable this port (e.g. set the Port Enable bit to a one). A host controller must terminate the reset and stabilize the state of the port within 2 milliseconds of software transitioning this bit from a one to a zero. For example: if the port detects that the attached device is high-speed during reset, then the host controller must have the port in the enabled state with 2ms of software writing this bit to a zero.</td></tr>
</table>

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<table>
<tr><th colspan="3">Offset: 0x0054</th><th>Register Name: PORTSC</th></tr>
<tr><th>Bit</th><th>Read/Write</th><th>Default/Hex</th><th>Description</th></tr>
<tr><td></td><td></td><td></td><td>The HC Halted bit in the USBSTS register should be a zero before software attempts to use this bit. The host controller may hold Port Reset asserted to a one when the HC Halted bit is a one.
This field is zero if Port Power is zero.</td></tr>
<tr><td>7</td><td>R/W</td><td>0x0</td><td>Suspend
Port Enabled Bit and Suspend bit of this register define the port states as follows:
<table><tr><th>Bits[Port Enables, Suspend]</th><th>Port State</th></tr><tr><td>0x</td><td>Disable</td></tr><tr><td>10</td><td>Enable</td></tr><tr><td>11</td><td>Suspend</td></tr></table>When in suspend state, downstream propagation of data is blocked on this port, except for port reset. The blocking occurs at the end of the current transaction, if a transaction was in progress when this bit was written to 1. In the suspend state, the port is sensitive to resume detection. Not that the bit status does not change until the port is suspend and that there may be a delay in suspending a port if there is a transaction currently in progress on the USB.
A write of zero to this bit is ignored by the host controller. The host controller will unconditionally set this bit to a zero when:
① Software sets the Force Port Resume bit to a zero(from a one).
② Software sets the Port Reset bit to a one(from a zero).
If host software sets this bit to a one when the port is not enabled(i.e. Port enabled bit is a zero), the results are undefined.
This field is zero if Port Power is zero.
The default value in this field is ‘0’.</td></tr>
<tr><td>6</td><td>R/W</td><td>0x0</td><td>Force Port Resume
1 = Resume detected/driven on port. 0 = No resume (K-state) detected/driven on port. Default value = 0.
This functionality defined for manipulating this bit depends on the value of the Suspend bit. For example, if the port is not suspend and software transitions this bit to a one, then the effects on the bus are undefined.
Software sets this bit to 1 to drive resume signaling. The Host Controller sets this bit to a 1 if a J-to-K transition is detected while the port is in the Suspend state. When this bit transitions to a one because a J-to-K transition is detected, the Port Change Detect bit in the USBSTS register is also set to a one. If software sets this bit</td></tr>
</table>

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Offset: 0x0054			Register Name: PORTSC
Bit	**Read/Write**	**Default/Hex**	**Description**
			to a one, the host controller must not set the Port Change Detect bit. Note that when the EHCI controller owns the port, the resume sequence follows the defined sequence documented in the USB Specification Revision 2.0. The resume signaling (Full-speed 'K') is driven on the port as long as this remains a one. Software must appropriately time the Resume and set this bit to a zero when the appropriate amount of time has elapsed. Writing a zero (from one) causes the port to return high-speed mode (forcing the bus below the port into a high-speed idle). This bit will remain a one until the port has switched to high-speed idle. The host controller must complete this transition within 2 milliseconds of software setting this bit to a zero. This field is zero if Port Power is zero.
5	R/WC	0x0	Over-current Change This bit gets set to a one when there is a change to Over-current Active. Software clears this bit by writing a one to this bit position.
4	R	0x0	Over-current Active 0 = This port does not have an over-current condition 1 = This port currently has an over-current condition This bit will automatically transition from a one to a zero when the over current condition is removed. The default value of this bit is '0'.
3	R/WC	0x0	Port Enable/Disable Change 1 = Port enabled/disabled status has changed 0 = No change For the root hub, this bit gets set to a one only when a port is disabled due to the appropriate conditions existing at the EOF2 point (See Chapter 11 of the USB Specification for the definition of a Port Error). Software clears this bit by writing a 1 to it. This field is zero if Port Power is zero.
2	R/W	0x0	Port Enabled/Disabled 1=Enable 0=Disable Ports can only be enabled by the host controller as a part of the reset and enable. Software cannot enable a port by writing a one to this field. The host controller will only set this bit to a one when the reset sequence determines that the attached device is a high-speed device.

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Offset: 0x0054			Register Name: PORTSC
Bit	**Read/Write**	**Default/Hex**	**Description**
			Ports can be disabled by either a fault condition(disconnect event or other fault condition) or by host software. Note that the bit status does not change until the port state actually changes. There may be a delay in disabling or enabling a port due to other host controller and bus events. When the port is disabled, downstream propagation of data is blocked on this port except for reset. The default value of this field is '0'. This field is zero if Port Power is zero.
1	R/WC	0x0	Connect Status Change 1=Change in Current Connect Status 0=No change Indicates a change has occurred in the current connect status of the port. The host controller sets this bit for all changes to the port device connect status, even if system software has not cleared an existing connect status change. For example, the insertion status changes twice before system software has cleared the changed condition, hub hardware will be "setting" an already-set bit. Software sets this bit to 0 by writing a 1 to it. This field is zero if Port Power is zero.
0	R	0x0	Current Connect Status Device is present on port when the value of this field is a one, and no device is present on port when the value of this field is a zero. This value reflects the current state of the port, and may not correspond directly to the event that caused the Connect Status Change(Bit 1) to be set. This field is zero if Port Power zero.

NOTE

This register is only reset by hardware or in response to a host controller reset.

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10.6.6 OHCI Register Description

10.6.6.1 0x0404 OHCI Control Register (Default Value: 0x0000_0000)

Offset: 0x0404				Register Name: HcRevision
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:11	/	/	/	/
10	R/W	R	0x0	**RemoteWakeupEnable** This bit is used by HCD to enable or disable the remote wakeup feature upon the detection of upstream resume signaling. When this bit is set and the **ResumeDetected** bit in ***HcInterruptStatus*** is set, a remote wakeup is signaled to the host system. Setting this bit has no impact on the generation of hardware interrupt.
9	R/W	R/W	0x0	**RemoteWakeupConnected** This bit indicates whether HC supports remote wakeup signaling. If remote wakeup is supported and used by the system, it is the responsibility of system firmware to set this bit during POST. HC clear the bit upon a hardware reset but does not alter it upon a software reset. Remote wakeup signaling of the host system is host-bus-specific and is not described in this specification.
8	R/W	R	0x0	**InterruptRouting** This bit determines the routing of interrupts generated by events registered in HcInterruptStatus. If clear, all interrupt are routed to the normal host bus interrupt mechanism. If set interrupts are routed to the System Management Interrupt. HCD clears this bit upon a hardware reset, but it does not alter this bit upon a software reset. HCD uses this bit as a tag to indicate the ownership of HC.
7:6	R/W	R/W	0x0	HostControllerFunctionalState for USB 00b USBReset 01b USBResume 10b USBOperational 11b USBSuspend A transition to USBOperational from another state causes SOF generation to begin 1 ms later. HCD may determine whether HC has begun sending SOFs by reading the StartoFrame field of HcInterruptStatus. This field may be changed by HC only when in the USBSUSPEND state. HC may move from the USBSUSPEND state to the USBRESUME state after detecting the resume signaling from a downstream port. HC enters USBSUSPEND after a software reset, whereas it enters USBRESET after a hardware reset. The latter also resets the Root

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<table>
<tr><th colspan="4">Offset: 0x0404</th><th colspan="2">Register Name: HcRevision</th></tr>
<tr><th rowspan="2">Bit</th><th colspan="2">Read/Write</th><th rowspan="2">Default/Hex</th><th rowspan="2">Description</th></tr>
<tr><th>HCD</th><th>HC</th></tr>
<tr><td></td><td></td><td></td><td></td><td>Hub and asserts subsequent reset signaling to downstream ports.</td></tr>
<tr><td>5</td><td>R/W</td><td>R</td><td>0x0</td><td>BulkListEnable
This bit is set to enable the processing of the Bulk list in the next Frame. If cleared by HCD, the processing of the Bulk list does not occur after the next SOF. HC checks this bit whenever it determines to process the list. When disabled, HCD may modify the list. If HcBulkCurrentED is pointing to an ED to be removed, HCD must advance the pointer by updating HcBulkCurrentED before re-enabling processing of the list.</td></tr>
<tr><td>4</td><td>R/W</td><td>R</td><td>0x0</td><td>ControlListEnable
This bit is set to enable the processing of the Control list in the next Frame. If cleared by HCD, the processing of the Control list does not occur after the next SOF. HC must check this bit whenever it determines to process the list. When disabled, HCD may modify the list. If HcControlCurrentED is pointing to an ED to be removed, HCD must advance the pointer by updating HcControlCurrentED before re-enabling processing of the list.</td></tr>
<tr><td>3</td><td>R/W</td><td>R</td><td>0x0</td><td>IsochronousEnable
This bit is used by HCD to enable/disable processing of isochronous EDs. While processing the periodic list in a Frame, HC checks the status of this bit when it finds an Isochronous ED (F=1). If set (enabled), HC continues processing the EDs. If cleared (disabled), HC halts processing of the periodic list (which now contains only isochronous EDs) and begins processing the Bulk/Control lists.
Setting this bit is guaranteed to take effect in the next Frame (not the current Frame).</td></tr>
<tr><td>2</td><td>R/W</td><td>R</td><td>0x0</td><td>PeriodicListEnable
This bit is set to enable the processing of periodic list in the next Frame. If cleared by HCD, processing of the periodic list does not occur after the next SOF. HC must check this bit before it starts processing the list.</td></tr>
<tr><td>1:0</td><td>R/W</td><td>R</td><td>0x0</td><td>ControlBulkServiceRatio
This specifies the service ratio between Control and Bulk EDs. Before processing any of the nonperiodic lists, HC must compare the ratio specified with its internal count on how many nonempty Control EDs have been processed, in determining whether to continue serving another Control ED or switching to Bulk EDs. The internal count will be retained when crossing the frame boundary. In case of reset, HCD is responsible for restoring this value.
<table>
<tr><td>CBSR</td><td>No. of Control EDs Over Bulk EDs Served</td></tr>
<tr><td>0</td><td>1:1</td></tr>
</table>
</td></tr>
</table>

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Offset: 0x0404				Register Name: HcRevision
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				1 2:1 2 3:1 3 4:1 The default value is 0x0.

10.6.6.2 0x0408 OHCI Command Status Register (Default Value: 0x0000_0000)

Offset: 0x0408				Register Name: HcCommandStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:18	/	/	0x0	**Reserved**
17:16	R	R/W	0x0	**SchedulingOverrunCount** These bits are incremented on each scheduling overrun error. It is initialized to 00b and wraps around at 11b. This will be incremented when a scheduling overrun is detected even if **SchedulingOverrun** in *HcInterruptStatus* has already been set. This is used by HCD to monitor any persistent scheduling problem.
15:4	/	/	/	/
3	R/W	R/W	0x0	**OwershipChangeRequest** This bit is set by an OS HCD to request a change of control of the HC. When set HC will set the **OwnershipChange** field in *HcInterruptStatus*. After the changeover, this bit is cleared and remains so until the next request from OS HCD.
2	R/W	R/W	0x0	**BulklListFilled** This bit is used to indicate whether there are any TDs on the Bulk list. It is set by HCD whenever it adds a TD to an ED in the Bulk list. When HC begins to process the head of the Bulk list, it checks BLF. As long as **BulkListFilled** is 0, HC will not start processing the Bulk list. If **BulkListFilled** is 1, HC will start processing the Bulk list and will set BF to 0. If HC finds a TD on the list, then HC will set **BulkListFilled** to 1 causing the Bulk list processing to continue. If no TD is found on the Bulk list, and if HCD does not set **BulkListFilled**, then **BulkListFilled** will still be 0 when HC completes processing the Bulk list and Bulk list processing will stop.
1	R/W	R/W	0x0	**ControlListFilled** This bit is used to indicate whether there are any TDs on the Control list. It is set by HCD whenever it adds a TD to an ED in the Control list. When HC begins to process the head of the Control list, it checks

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Offset: 0x0408				Register Name: HcCommandStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				CLF. As long as **ControlListFilled** is 0, HC will not start processing the Control list. If CF is 1, HC will start processing the Control list and will set **ControlListFilled** to 0. If HC finds a TD on the list, then HC will set **ControlListFilled** to 1 causing the Control list processing to continue. If no TD is found on the Control list, and if the HCD does not set **ControlListFilled**, then **ControlListFilled** will still be 0 when HC completes processing the Control list and Control list processing will stop.
0	R/W	R/E	0x0	**HostControllerReset** This bit is by HCD to initiate a software reset of HC. Regardless of the functional state of HC, it moves to the USBSuspend state in which most of the operational registers are reset except those stated otherwise; e.g, the InteruptRouting field of HcControl, and no Host bus accesses are allowed. This bit is cleared by HC upon the completion of the reset operation. The reset operation must be completed within 10 ms. This bit, when set, should not cause a reset to the Root Hub and no subsequent reset signaling should be asserted to its downstream ports.

10.6.6.3 0x040C OHCI Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x040C				Register Name: HcInterruptStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:7	/	/	/	/
6	R/W	R/W	0x0	**RootHubStatusChange** This bit is set when the content of *HcRhStatus* or the content of any of *HcRhPortStatus*[**NumberofDownstreamPort**] has changed.
5	R/W	R/W	0x0	**FrameNumberOverflow** This bit is set when the MSb of *HcFmNumber* (bit 15) changes value, from 0 to 1 or from 1 to 0, and after *HccaFrameNumber* has been updated.
4	R/W	R/W	0x0	**UnrecoverableError** This bit is set when HC detects a system error not related to USB. HC should not proceed with any processing nor signaling before the system error has been corrected. HCD clears this bit after HC has been reset.
3	R/W	R/W	0x0	**ResumeDetected** This bit is set when HC detects that a device on the USB is asserting resume signaling. It is the transition from no resume signaling to

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Offset: 0x040C				Register Name: HcInterruptStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				resume signaling causing this bit to be set. This bit is not set when HCD sets the USBRseume state.
2	R/W	R/W	0x0	**StartofFrame** This bit is set by HC at each start of frame and after the update of HccaFrameNumber. HC also generates a SOF token at the same time.
1	R/W	R/W	0x0	**WritebackDoneHead** This bit is set immediately after HC has written *HcDoneHead* to *HccaDoneHead*. Further updates of the *HccaDoneHead* will not occur until this bit has been cleared. HCD should only clear this bit after it has saved the content of *HccaDoneHead*.
0	R/W	R/W	0x0	**SchedulingOverrun** This bit is set when the USB schedule for the current Frame overruns and after the update of *HccaFrameNumber*. A scheduling overrun will also cause the **SchedulingOverrunCount** of *HcCommandStatus* to be incremented.

10.6.6.4 0x0410 OHCI Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x0410				Register Name: HcInterruptEnable Register
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31	R/W	R	0x0	**MasterInterruptEnable** A '0' writtern to this field is ignored by HC. A '1' written to this field enables interrupt generation due to events specified in the other bits of this register. This is used by HCD as Master Interrupt Enable.
30:7	/	/	/	/
6	R/W	R	0x0	**RootHubStatusChange Interrupt Enable** 0 Ignore; 1 Enable interrupt generation due to Root Hub Status Change;
5	R/W	R	0x0	**FrameNumberOverflow Interrupt Enable** 0 Ignore; 1 Enable interrupt generation due to Frame Number Over Flow;
4	R/W	R	0x0	**UnrecoverableError Interrupt Enable** 0 Ignore; 1 Enable interrupt generation due to Unrecoverable Error;
3	R/W	R	0x0	**ResumeDetected Interrupt Enable**

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Offset: 0x0410				Register Name: HcInterruptEnable Register
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				0 Ignore; 1 Enable interrupt generation due to Resume Detected;
2	R/W	R	0x0	**StartofFrame Interrupt Enable** 0 Ignore; 1 Enable interrupt generation due to Start of Flame;
1	R/W	R	0x0	**WritebackDoneHead Interrupt Enable** 0 Ignore; 1 Enable interrupt generation due to Write back Done Head;
0	R/W	R	0x0	**SchedulingOverrun Interrupt Enable** 0 Ignore; 1 Enable interrupt generation due to Scheduling Overrun;

10.6.6.5 0x0414 OHCI Interrupt Disable Register (Default Value: 0x0000_0000)

Offset: 0x0414				Register Name: HcInterruptDisable Register
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31	R/W	R	0x0	**MasterInterruptEnable** A written '0' to this field is ignored by HC. A '1' written to this field disables interrupt generation due events specified in the other bits of this register. This field is set after a hardware or software reset.
30:7	/	/	/	/
6	R/W	R	0x0	**RootHubStatusChange Interrupt Disable** 0 Ignore; 1 Disable interrupt generation due to Root Hub Status Change;
5	R/W	R	0x0	**FrameNumberOverflow Interrupt Disable** 0 Ignore; 1 Disable interrupt generation due to Frame Number Over Flow;
4	R/W	R	0x0	**UnrecoverableError Interrupt Disable** 0 Ignore; 1 Disable interrupt generation due to Unrecoverable Error;
3	R/W	R	0x0	**ResumeDetected Interrupt Disable** 0 Ignore; 1 Disable interrupt generation due to Resume Detected;
2	R/W	R	0x0	**StartofFrame Interrupt Disable** 0 Ignore; 1 Disable interrupt generation due to Start of Flame;

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Offset: 0x0414				Register Name: HcInterruptDisable Register
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
1	R/W	R	0x0	**WritebackDoneHead Interrupt Disable** 0: Ignore; 1: Disable interrupt generation due to Write back Done Head;
0	R/w	R	0x0	**SchedulingOverrun Interrupt Disable** 0: Ignore; 1: Disable interrupt generation due to Scheduling Overrun;

10.6.6.6 0x0418 OHCI HCCA Register (Default Value: 0x0000_0000)

Offset: 0x0418				Register Name: HcHCCA
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:8	R/W	R	0x0	**HCCA[31:8]** This is the base address of the Host Controller Communication Area. This area is used to hold the control structures and the Interrupt table that are accessed by both the Host Controller and the Host Controller Driver.
7:0	R	R	0x0	**HCCA[7:0]** The alignment restriction in HcHCCA register is evaluated by examining the number of zeros in the lower order bits. The minimum alignment is 256 bytes, therefore, bits 0 through 7 must always return 0 when read.

10.6.6.7 0x041C OHCI Period Current ED Register (Default Value: 0x0000_0000)

Offset: 0x041C				Register Name: HcPeriodCurrentED[PCED]
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R	R/W	0x0	**PCED[31:4]** This is used by HC to point to the head of one of the Periodec list which will be processed in the current Frame. The content of this register is updated by HC after a periodic ED has been processed. HCD may read the content in determining which ED is currently being processed at the time of reading.
3:0	R	R	0x0	**PCED[3:0]** Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

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10.6.6.8 0x0420 OHCI Control Head ED Register (Default Value: 0x0000_0000)

Offset: 0x0420				Register Name: HcControlHeadED[CHED]
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R/W	R	0x0	**EHCD[31:4]** The HcControlHeadED register contains the physical address of the first Endpoint Descriptor of the Control list. HC traverse the Control list starting with the HcControlHeadED pointer. The content is loaded from HCCA during the initialization of HC.
3:0	R	R	0x0	**EHCD[3:0]** Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

10.6.6.9 0x0424 OHCI Control Current ED Register (Default Value: 0x0000_0000)

Offset: 0x0424				Register Name: HcControlCurrentED[CCED]
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R/W	R/W	0x0	**CCED[31:4]** The pointer is advanced to the next ED after serving the present one. HC will continue processing the list from where it left off in the last Frame. When it reaches the end of the Control list, HC checks the ControlListFilled of in HcCommandStatus. If set, it copies the content of HcControlHeadED to HcControlCurrentED and clears the bit. If not set, it does nothing. HCD is allowed to modify this register only when the ControlListEnable of HcControl is cleared. When set, HCD only reads the instantaneous value of this register. Initially, this is set to zero to indicate the end of the Control list.
3:0	R	R	0x0	**CCED[3:0]** Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

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10.6.6.10 0x0428 OHCI Bulk Head ED Register (Default Value: 0x0000_0000)

Offset: 0x0428				Register Name: HcBulkHeadED[BHED]
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R/W	R	0x0	**BHED[31:4]** The HcBulkHeadED register contains the physical address of the first Endpoint Descriptor of the Bulk list. HC traverses the Bulk list starting with the HcBulkHeadED pointer. The content is loaded from HCCA during the initialization of HC.
3:0	R	R	0x0	**BHED[3:0]** Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

10.6.6.11 0x042C OHCI Bulk Current ED Register (Default Value: 0x0000_0000)

Offset: 0x042C				Register Name: HcBulkCurrentED[BCED]
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R/W	R/W	0x0	**BulkCurrentED[31:4]** This is advanced to the next ED after the HC has served the present one. HC continues processing the list from where it left off in the last Frame. When it reaches the end of the Bulk list, HC checks the **ControlListFilled** of HcControl. If set, it copies the content of *HcBulkHeadED* to *HcBulkCurrentED* and clears the bit. If it is not set, it does nothing. HCD is only allowed to modify this register when the **BulkListEnable** of *HcControl* is cleared. When set, the HCD only reads the instantaneous value of this register. This is initially set to zero to indicate the end of the Bulk list.
3:0	R	R	0x0	**BulkCurrentED [3:0]** Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

10.6.6.12 0x0430 OHCI Done Head Register (Default Value: 0x0000_0000)

Offset: 0x0430				Register Name: HcDoneHead
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:4	R	R/W	0x0	**HcDoneHead[31:4]** When a TD is completed, HC writes the content of *HcDoneHead* to

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Offset: 0x0430				Register Name: HcDoneHead
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				the NextTD field of the TD. HC then overwrites the content of *HcDoneHead* with the address of this TD. This is set to zero whenever HC writes the content of this register to HCCA. It also sets the **WritebackDoneHead** of *HcInterruptStatus*.
3:0	R	R	0x0	**HcDoneHead[3:0]** Because the general TD length is 16 bytes, the memory structure for the TD must be aligned to a 16-byte boundary. So the lower bits in the PCED, through bit 0 to bit 3 must be zero in this field.

10.6.6.13 0x0434 OHCI Frame Interval Register (Default Value: 0x0000_2EDF)

Offset: 0x0434				Register Name: HcFmInterval Register
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31	R/W	R	0x0	**FrameIntervalToggler** HCD toggles this bit whenever it loads a new value to **FrameInterval**.
30:16	R/W	R	0x0	**FSLargestDataPacket** This field specifies a value which is loaded into the Largest Data Packet Counter at the beginning of each frame. The counter value represents the largest amount of data in bits which can be sent or received by the HC in a single transaction at any given time without causing scheduling overrun. The field value is calculated by the HCD.
15:14	/	/	/	/
13:0	R/W	R	0x2edf	**FrameInterval** This specifies the interval between two consecutive SOFs in bit times. The nominal value is set to be 11,999. HCD should store the current value of this field before resetting HC. By setting the **HostControllerReset** field of *HcCommandStatus* as this will cause the HC to reset this field to its nominal value. HCD may choose to restore the stored value upon the completion of the Reset sequence.

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10.6.6.14 0x0438 OHCI Frame Remaining Register (Default Value: 0x0000_0000)

Offset: 0x0438				Register Name: HcFmRemaining
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31	R	R/W	0x0	**FrameRemaining Toggle** This bit is loaded from the **FrameIntervalToggle** field of *HcFmInterval* whenever **FrameRemaining** reaches 0. This bit is used by HCD for the synchronization between **FrameInterval** and **FrameRemaining**.
30:14	/	/	/	/
13:0	R	RW	0x0	**FramRemaining** This counter is decremented at each bit time. When it reaches zero, it is reset by loading the FrameInterval value specified in *HcFmInterval* at the next bit time boundary. When entering the USBOPERATIONAL state, HC re-loads the content with the FrameInterval of *HcFmInterval* and uses the updated value from the next SOF.

10.6.6.15 0x043C OHCI Frame Number Register (Default Value: 0x0000_0000)

Offset: 0x043C				Register Name: HcFmNumber
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:16	/	/	/	/
15:0	R	R/W	0x0	**FrameNumber** This is incremented when *HcFmRemaining* is re-loaded. It will be rolled over to 0x0 after 0x0ffff. When entering the USBOPERATIONAL state, this will be incremented automatically. The content will be written to HCCA after HC has incremented the **FrameNumber** at each frame boundary and sent a SOF but before HC reads the first ED in that Frame. After writing to HCCA, HC will set the **StartofFrame** in *HcInterruptStatus.*

10.6.6.16 0x0440 OHCI Periodic Start Register (Default Value: 0x0000_0000)

Offset: 0x0440				Register Name: HcPeriodicStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:14	/	/	/	/
13:0	R/W	R	0x0	**PeriodicStart** After a hardware reset, this field is cleared. This is then set by HCD

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Offset: 0x0440				Register Name: HcPeriodicStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				during the HC initialization. The value is calculated roughly as 10% off from *HcFmInterval*. A typical value will be 0x2A3F (or 0x3e67). When *HcFmRemaining* reaches the value specified, processing of the periodic lists will have priority over Control/Bulk processing. HC will therefore start processing the Interrupt list after completing the current Control or Bulk transaction that is in progress.

10.6.6.17 0x0444 OHCI LS Threshold Register (Default Value: 0x0000_0628)

Offset: 0x0444				Register Name: HcLSThreshold
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:12	/	/	/	/
11:0	R/W	R	0x0628	**LSThreshold** This field contains a value which is compared to the **FrameRemaining** field prior to initiating a Low Speed transaction. The transaction is started only if **FrameRemaining** this field. The value is calculated by HCD with the consideration of transmission and setup overhead.

10.6.6.18 0x0448 OHCI Root Hub DescriptorA Register (Default Value: 0x0200_1201)

Offset: 0x0448				Register Name: HcRhDescriptorA
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:24	R/W	R	0x2	**PowerOnToPowerGoodTime[POTPGT]** This byte specifies the duration HCD has to wait before accessing a powered-on port of the Root Hub. It is implementation-specific. The unit of time is 2 ms. The duration is calculated as POTPGT * 2ms.
23:13	/	/	/	/
12	R/W	R	0x1	**NoOverCurrentProtection** This bit describes how the overcurrent status for the Root Hub ports are reported. When this bit is cleared, the **OverCurrentProtectionMode** field specifies global or per-port reporting. **0** Over-current status is reported collectively for all downstream ports.

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Offset: 0x0448				Register Name: HcRhDescriptorA
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				1 No overcurrent protection supported.
11	R/W	R	0x0	**OverCurrentProtectionMode** This bit describes how the overcurrent status for the Root Hub ports are reported. At reset, these fields should reflect the same mode as **PowerSwitchingMode**. This field is valid only if the **NoOverCurrentProtection** field is cleared. 0 Over-current status is reported collectively for all downstream ports. 1 Over-current status is reported on per-port basis.
10	R	R	0x0	**Device Type** This bit specifies that the Root Hub is not a compound device. The Root Hub is not permitted to be a compound device. This field should always read/write 0.
9	R/W	R	0x1	**PowerSwitchingMode** This bit is used to specify how the power switching of the Root Hub ports is controlled. It is implementation-specific. This field is only valid if the **NoPowerSwitching** field is cleared. 0 All ports are powered at the same time. 1 Each port is powered individually. This mode allows port power to be controlled by either the global switch or per-port switching. If the **PortPowerControlMask** bit is set, the port responds only to port power commands (**Set/ClearPortPower**). If the port mask is cleared, then the port is controlled only by the global power switch (**Set/ClearGlobalPower**).
8	R/W	R	0x0	**NoPowerSwithcing** These bits are used to specify whether power switching is supported or ports are always powered. It is implementation-specific. When this bit is cleared, the **PowerSwitchingMode** specifies global or per-port switching. **0** Ports are power switched. **1** Ports are always powered on when the HC is powered on.
7:0	R	R	0x01	**NumberDownstreamPorts** These bits specify the number of downstream ports supported by the Root Hub. It is implementation-specific. The minimum number of ports is 1. The maximum number of ports supported.

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10.6.6.19 0x044C HcRhDescriptorB Register (Default Value: 0x0000_0000)

Offset: 0x044C				Register Name: HcRhDescriptorB Register
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:16	R/W	R	0x0	**PortPowerControlMask** Each bit indicates if a port is affected by a global power control command when **PowerSwitchingMode** is set. When set, the port's power state is only affected by per-port power control (**Set/ClearPortPower**). When cleared, the port is controlled by the global power switch (**Set/ClearGlobalPower**). If the device is configured to global switching mode (**PowerSwitchingMode** = 0), this field is not valid. Bit0 Reserved Bit1 Ganged-power mask on Port #1. Bit2 Ganged-power mask on Port #2. … Bit15 Ganged-power mask on Port #15.
15:0	R/W	R	0x0	**DeviceRemovable** Each bit is dedicated to a port of the Root Hub. When cleared, the attached device is removable. When set, the attached device is not removable. Bit0 Reserved Bit1 Device attached to Port #1. Bit2 Device attached to Port #2. … Bit15 Device attached to Port #15.

10.6.6.20 0x0450 HcRhStatus Register (Default Value: 0x0000_0000)

Offset: 0x0450				Register Name: HcRhStatus Register
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31	W	R	0x0	**(write)ClearRemoteWakeupEnable** Write a '1' clears **DeviceRemoteWakeupEnable.** Writing a '0' has no effect.
30:18	/	/	/	/
17	R/W	R	0x0	**OverCurrentIndicatorChang** This bit is set by hardware when a change has occurred to the **OverCurrentIndicator** field of this register. The HCD clears this bit by writing a '1'. Writing a '0' has no effect.
16	R/W	R	0x0	**(read)LocalPowerStartusChange**

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<table>
<tr><td colspan="4">Offset: 0x0450</td><td>Register Name: HcRhStatus Register</td></tr>
<tr><td rowspan="2">Bit</td><td colspan="2">Read/Write</td><td rowspan="2">Default/Hex</td><td rowspan="2">Description</td></tr>
<tr><td>HCD</td><td>HC</td></tr>
<tr><td></td><td></td><td></td><td></td><td>The Root Hub does not support the local power status features, thus, this bit is always read as ‘0’.
(write)SetGlobalPower
In global power mode (PowerSwitchingMode=0), This bit is written to ‘1’ to turn on power to all ports (clear PortPowerStatus). In per-port power mode, it sets PortPowerStatus only on ports whose PortPowerControlMask bit is not set. Writing a ‘0’ has no effect.</td></tr>
<tr><td>15</td><td>R/W</td><td>R</td><td>0x0</td><td>(read)DeviceRemoteWakeupEnable
This bit enables a ConnectStatusChange bit as a resume event, causing a USBSUSPEND to USBRESUME state transition and setting the ResumeDetected interrupt.
<table><tr><td>0</td><td>ConnectStatusChange is not a remote wakeup event.</td></tr><tr><td>1</td><td>ConnectStatusChange is a remote wakeup event.</td></tr></table>
(write)SetRemoteWakeupEnable
Writing a ‘1’ sets DeviceRemoveWakeupEnable. Writing a ‘0’ has no effect.</td></tr>
<tr><td>14:2</td><td>/</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>1</td><td>R</td><td>R/W</td><td>0x0</td><td>OverCurrentIndicator
This bit reports overcurrent conditions when the global reporting is implemented. When set, an overcurrent condition exists. When cleared, all power operations are normal.
If per-port overcurrent protection is implemented this bit is always ‘0’</td></tr>
<tr><td>0</td><td>R/W</td><td>R</td><td>0x0</td><td>(Read)LocalPowerStatus
When read, this bit returns the LocalPowerStatus of the Root Hub. The Root Hub does not support the local power status feature; thus, this bit is always read as ‘0’.
(Write)ClearGlobalPower
When write, this bit is operated as the ClearGlobalPower. In global power mode (PowerSwitchingMode=0), This bit is written to ‘1’ to turn off power to all ports (clear PortPowerStatus). In per-port power mode, it clears PortPowerStatus only on ports whose PortPowerControlMask bit is not set. Writing a ‘0’ has no effect.</td></tr>
</table>

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10.6.6.21 0x0454 HcRhPortStatus Register (Default Value: 0x0000_0100)

Offset: 0x0454				Register Name: HcRhPortStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
31:21	/	/	/	/
20	R/W	R/W	0x0	**PortResetStatusChange** This bit is set at the end of the 10-ms port reset signal. The HCD writes a '1' to clear this bit. Writing a '0' has no effect. 0 port reset is not complete 1 port reset is complete
19	R/W	R/W	0x0	**PortOverCurrentIndicatorChange** This bit is valid only if overcurrent conditions are reported on a per-port basis. This bit is set when Root Hub changes the **PortOverCurrentIndicator** bit. The HCD writes a '1' to clear this bit. Writing a '0' has no effect. 0 no change in **PortOverCurrentIndicator** 1 **PortOverCurrentIndicator** has changed
18	R/W	R/W	0x0	**PortSuspendStatusChange** This bit is set when the full resume sequence has been completed. This sequence includes the 20-s resume pulse, LS EOP, and 3-ms resychronization delay. The HCD writes a '1' to clear this bit. Writing a '0' has no effect. This bit is also cleared when **ResetStatusChange** is set. 0 resume is not completed 1 resume completed
17	R/W	R/W	0x0	**PortEnableStatusChange** This bit is set when hardware events cause the **PortEnableStatus** bit to be cleared. Changes from HCD writes do not set this bit. The HCD writes a '1' to clear this bit. Writing a '0' has no effect. 0 no change in **PortEnableStatus** 1 change in **PortEnableStatus**
16	R/W	R/W	0x0	**ConnectStatusChange** This bit is set whenever a connect or disconnect event occurs. The HCD writes a '1' to clear this bit. Writing a '0' has no effect. If **CurrentConnectStatus** is cleared when a **SetPortReset,SetPortEnable**, or **SetPortSuspend** write occurs, this bit is set to force the driver to re-evaluate the connection status since these writes should not occur if the port is disconnected. 0 no change in **PortEnableStatus** 1 change in **PortEnableStatus** **Note: If the DeviceRemovable[NDP] bit is set, this bit is set only**

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<table>
<tr><td colspan="3">Offset: 0x0454</td><td colspan="2">Register Name: HcRhPortStatus</td></tr>
<tr><td rowspan="2">Bit</td><td colspan="2">Read/Write</td><td rowspan="2">Default/Hex</td><td rowspan="2">Description</td></tr>
<tr><td>HCD</td><td>HC</td></tr>
<tr><td></td><td></td><td></td><td></td><td>after a Root Hub reset to inform the system that the device is attached.</td></tr>
<tr><td>15:10</td><td>/</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>9</td><td>R/W</td><td>R/W</td><td>0x0</td><td>(read)LowSpeedDeviceAttached
This bit indicates the speed of the device attached to this port. When set, a Low Speed device is attached to this port. When clear, a Full Speed device is attached to this port. This field is valid only when the CurrentConnectStatus is set.
<table><tr><td>0</td><td>full speed device attached</td></tr><tr><td>1</td><td>low speed device attached</td></tr></table>
(write)ClearPortPower
The HCD clears the PortPowerStatus bit by writing a ‘1’ to this bit. Writing a ‘0’ has no effect.</td></tr>
<tr><td>8</td><td>R/W</td><td>R/W</td><td>0x1</td><td>(read)PortPowerStatus
This bit reflects the port’s power status, regardless of the type of power switching implemented. This bit is cleared if an overcurrent condition is detected. HCD sets this bit by writing SetPortPower or SetGlobalPower. HCD clears this bit by writing ClearPortPower or ClearGlobalPower. Which power control switches are enabled is determined by PowerSwitchingMode and PortPortControlMask[NumberDownstreamPort]. In global switching mode(PowerSwitchingMode=0), only Set/ClearGlobalPower controls
this bit. In per-port power switching (PowerSwitchingMode=1), if the PortPowerControlMask[NDP] bit for the port is set, only Set/ClearPortPower commands are enabled. If the mask is not set, only Set/ClearGlobalPower commands are enabled. When port power is disabled, CurrentConnectStatus, PortEnableStatus, PortSuspendStatus, and PortResetStatus should be reset.
<table><tr><td>0</td><td>port power is off</td></tr><tr><td>1</td><td>port power is on</td></tr></table>
(write)SetPortPower
The HCD writes a ‘1’ to set the PortPowerStatus bit. Writing a ‘0’ has no effect.

Note: This bit is always reads ‘1b’ if power switching is not supported.</td></tr>
<tr><td>7:5</td><td>/</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>4</td><td>R/W</td><td>R/W</td><td>0x0</td><td>(read)PortResetStatus</td></tr>
</table>

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<table>
<tr><td colspan="3">Offset: 0x0454</td><td colspan="2">Register Name: HcRhPortStatus</td></tr>
<tr><td rowspan="2">Bit</td><td colspan="2">Read/Write</td><td rowspan="2">Default/Hex</td><td rowspan="2">Description</td></tr>
<tr><td>HCD</td><td>HC</td></tr>
<tr><td></td><td></td><td></td><td></td><td>When this bit is set by a write to SetPortReset, port reset signaling is asserted. When reset is completed, this bit is cleared when PortResetStatusChange is set. This bit cannot be set if CurrentConnectStatus is cleared.
<table><tr><td>0</td><td>port reset signal is not active</td></tr><tr><td>1</td><td>port reset signal is active</td></tr></table>
(write)SetPortReset
The HCD sets the port reset signaling by writing ‘1’ to this bit. Writing a ‘0’ has no effect. If CurrentConnectStatus is cleared, this write does not set PortResetStatus, but instead sets ConnectStatusChange. This informs the driver that it attempted to reset a disconnected port.</td></tr>
<tr><td>3</td><td>R/W</td><td>R/W</td><td>0x0</td><td>(read)PortOverCurrentIndicator
This bit is only valid when the Root Hub is configured in such a way that overcurrent conditions are reported on a per-port basis. If per-port overcurrent reporting is not supported, this bit is set to 0. If cleared, all power operations are normal for this port. If set, an overcurrent condition exists on this port. This bit always reflects the overcurrent input signal.
<table><tr><td>0</td><td>no overcurrent condition.</td></tr><tr><td>1</td><td>overcurrent condition detected.</td></tr></table>
(write)ClearSuspendStatus
The HCD writes a ‘1’ to initiate a resume. Writing a ‘0’ has no effect. A resume is initiated only if PortSuspendStatus is set.</td></tr>
<tr><td>2</td><td>R/W</td><td>R/W</td><td>0x0</td><td>(read)PortSuspendStatus
This bit indicates the port is suspended or in the resume sequence. It is set by a SetSuspendState write and cleared when PortSuspendStatusChange is set at the end of the resume interval. This bit cannot be set if CurrentConnectStatus is cleared. This bit is also cleared when PortResetStatusChange is set at the end of the port reset or when the HC is placed in the USBRESUME state. If an upstream resume is in progress, it should propagate to the HC.
<table><tr><td>0</td><td>port is not suspended</td></tr><tr><td>1</td><td>port is suspended</td></tr></table>
(write)SetPortSuspend
The HCD sets the PortSuspendStatus bit by writing a ‘1’ to this bit. Writing a ‘0’ has no effect. If CurrentConnectStatus is cleared, this</td></tr>
</table>

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Offset: 0x0454				Register Name: HcRhPortStatus
Bit	Read/Write		Default/Hex	Description
	HCD	HC		
				write does not set **PortSuspendStatus**; instead it sets **ConnectStatusChange**. This informs the driver that it attempted to suspend a disconnected port.
1	R/W	R/W	0x0	(read)**PortEnableStatus** This bit indicates whether the port is enabled or disabled. The Root Hub may clear this bit when an overcurrent condition, disconnect event, switched-off power, or operational bus error such as babble is detected. This change also causes **PortEnabledStatusChange** to be set. HCD sets this bit by writing **SetPortEnable** and clears it by writing **ClearPortEnable**. This bit cannot be set when **CurrentConnectStatus** is cleared. This bit is also set, if not already, at the completion of a port reset when **ResetStatusChange** is set or port suspend when **SuspendStatusChange** is set. 0 port is disabled 1 port is enabled (write)**SetPortEnable** The HCD sets **PortEnableStatus** by writing a '1'. Writing a '0' has no effect. If **CurrentConnectStatus** is cleared, this write does not set **PortEnableStatus**, but instead sets **ConnectStatusChange**. This informs the driver that it attempted to enable a disconnected Port.
0	R/W	R/W	0x0	(read)**CurrentConnectStatus** This bit reflects the current state of the downstream port. 0 No device connected 1 Device connected (write)**ClearPortEnable** The HCD writes a '1' to clear the PortEnableStatus bit. Writing '0' to this bit has no effect. The CurrentConnectStatus is not affected by any write. **Note: This bit is always read '1' when the attached device is nonremovalble (DviceRemoveable[NumberDownstreamPort]).**

10.6.6.22 0x0800 HCI Interface Register (Default Value: 0x1000_0000)

Offset: 0x0800			Register Name: USB_CTRL
Bit	Read/Write	Default/Hex	Description
31:29	/	/	Reserved

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Offset: 0x0800			Register Name: USB_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
28	R	1	DMA Transfer Status Enable 0: Disable 1: Enable
27:26	/	/	/
25	R/W	0	OHCI count select 1: Simulation mode. The counters will be much shorter then real time 0: Normal mode. The counters will count full time
24:19	/	/	/
18	R/W	0	1: Within 2 us of the resume-K to SE0 transition 0: Random time value of the resume-K to SE0 transition
17:13	/	/	/
12	R/W	0	PP2VBUS 1: ULPI wrapper interface will automatically set or clear DrvVbus register in ULPI PHY according to the port power status form the root hub 0: ULPI wrapper will ignore the difference between power status of root hub and ULPI PHY
11	R/W	0	AHB Master interface INCR16 enable 1: Use INCR16 when appropriate 0: Do not use INCR16, use other enabled INCRX or unspecified length burst INCR
10	R/W	0	AHB Master interface INCR8 enable 1: Use INCR8 when appropriate 0: Do not use INCR8, use other enabled INCRX or unspecified length burst INCR
9	R/W	0	AHB Master interface burst type INCR4 enable 1: Use INCR4 when appropriate 0: Do not use INCR4, use other enabled INCRX or unspecified length burst INCR
8	R/W	0	AHB Master interface INCRX align enable 1: Start INCRx burst only on burst x-align address 0: Start burst on any double word boundary Note: This bit must enable if any bit of bit[11:9] is enabled
7:1	/	/	/
0	R/W	0	ULPI bypass enable 1: Enable UTMI interface, disable ULPI interface 0: Enable ULPI interface, disable UTMI interface

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10.6.6.23 0x0808 HCI Control 3 Register (Default Value: 0x0001_0000)

Offset: 0x0808			Register Name: HCI_CTRL3
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	Reserved
16	R/W1C	1	Linestate Change Detect 0: Linestate change not dected 1: Linestate change dected Write '1' to clear.
15:4	/	/	Reserved
3	R/W	0	Remote Wakeup Enable 1: Enable 0: Disable
2	/	/	Reserved
1	R/W	0	Linestate Change Interrupt Enable 1: Enable 0: Disable
0	R/W	0	Linestate Change Detect Enable 1: Enable 0: Disable

10.6.6.24 0x0810 PHY Control Register (Default Value: 0x0000_0008)

Offset: 0x0810			Register Name: PHY_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0	bist_en_a
15:8	R/W	0	vc_addr
7	R/W	0	vc_di
6:4	/	/	/
3	R/W	0x1	SIDDQ 1: Write 1 to disable phy 0: Write 0 to enable phy
2:1	/	/	/
0	R/W	0x0	vc_clk

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10.6.6.25 0x0824 PHY Status Register (Default Value: 0x0000_0000)

Offset: 0x0824			Register Name: PHY_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R	0	Bist_error
16	R	0	bist_done
15:1	/	/	/
0	R	0	vc_do

10.6.6.26 0x0828 HCI SIE Port Disable Control Register (Default Value: 0x0000_0000)

Offset: 0x0828			Register Name: USB_SPDCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R/W	0	SE0 Status This bit is set when no-se0 is detected before SOF when bit[1:0] is 10b or 11b
15:5	/	/	/
4	R/W	0	resume_sel When set k-se0 transition 2 us, setting this bit to 1, which is cooperated with ss_utmi_backward_enb_i.
3:2	/	/	/
1:0	R/W	0	Port Disable Control 00: Port Disable when no-se0 detect before SOF 01: Port Disable when no-se0 detect before SOF 10: No Port Disable when no-se0 detect before SOF 11: Port Disable when no-se0 3 time detect before SOF during 8 frames

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10.7 GPIO

10.7.1 Overview

The general purpose input/output (GPIO) is one of the blocks controlling the chip multiplexing pins. The R528 supports 6 groups of GPIO pins. Each pin can be configured as input or output and these pins are used to generate input signals or output signals for special purposes.

The Port Controller has the following features:

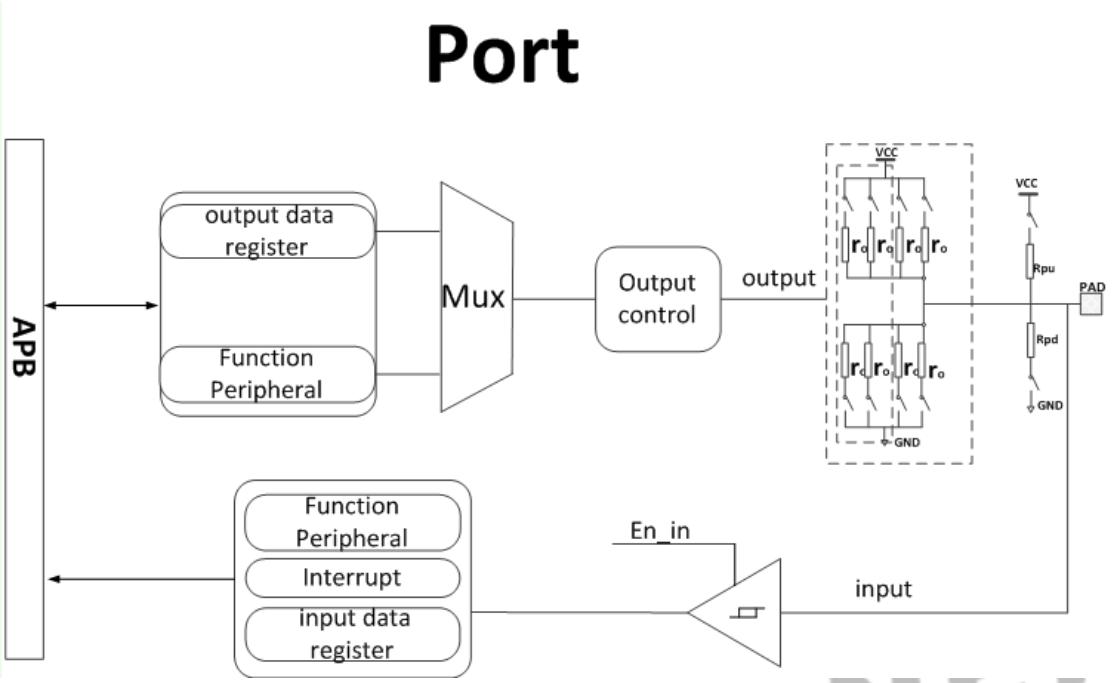
- 6 groups of ports (PB, PC, PD, PE, PF, PG)
- Software control for each signal pin
- Data input (capture)/output (drive)
- Each GPIO peripheral can produce an interrupt
- Pull-up/Pull-down/no-Pull register control
- Control the direction of every signal
- 4 drive strengths in each operating mode
- Up to 88 interrupts
- Configurable interrupt edges

10.7.2 Block Diagram

The following figure shows the block diagram of the GPIO.

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Figure 10-67 GPIO Block Diagram



The GPIO consists of the digital part (GPIO, external interface) and IO analog part (output buffer, dual pull down, pad). The digital part can select the output interface by the MUX switch; the analog part can configure pull up/down and buffer strength.

When executing GPIO read state, the GPIO reads the current level of the pin into the internal register bus. When not executing GPIO read state, the external pin and the internal register bus are off-status, which is high-impedance.

10.7.3 Functional Description

10.7.3.1 Multi-function Port

The R528 includes 88 multi-functional input/output port pins. There are 6 ports as listed below.

Table 10-20 Multi-function Port

Port Name	Number of Pins	Input Driver	Output Driver	Multiplex Pins	Power
PB	13	Schmitt	CMOS	LCD/DMIC/OWA/I2S/TWI/PWM/IR/SPI/ UART/PB-EINT	3.3 V
PC	8	Schmitt	CMOS	SPI/SMHC/UART/BOOT/TWI/TCON/LEDC/ PC-EINT	3.3 V/ 1.8 V

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Port Name	Number of Pins	Input Driver	Output Driver	Multiplex Pins	Power
PD	23	Schmitt	CMOS	LCD/LVDS/OWA/TWI/IR/DSI/SPI-DBI/ DMIC/UART/PWM/IR/PD-EINT	3.3 V/ 1.8 V
PE	18	Schmitt	CMOS	NCSI/TWI/UART/PWM/LCD/OWA/LEDC/IR /JTAG/EMAC/PE-EINT	3.3 V/ 2.8 V/ 1.8 V
PF	7	Schmitt	CMOS	SMHC/JTAG/UART/OWA/TWI/IR/I2S /PWM/PF-EINT	3.3 V/ 1.8 V
PG	19	Schmitt	CMOS	SMHC/UART/PWM/I2S/TWI/EMAC/OWA/ IR/TCON/LEDC/SPI/PG-EINT	3.3 V/ 1.8 V

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10.7.3.2 GPIO Multiplex Function

Table 10-21 to Table 10-26 show the multiplex function pins of the R528.

NOTE

For each GPIO, Function0 is input function; Function1 is output function; Function9 to Function13 are reserved.

Table 10-21 PB Multiplex Function

GPIO Port	Function 2	Function 3	Function 4	Function 5	Function 6	Function 7	Function 8	Function 14
PB0	PWM3	IR-TX	TWI2-SCK	SPI1-WP/DBI-TE	UART0-TX	UART2-TX	OWA-OUT	PB-EINT0
PB1	PWM4	I2S2-DOUT3	TWI2-SDA	I2S2-DIN3	UART0-RX	UART2-RX	IR-RX	PB-EINT1
PB2	LCD0-D0	I2S2-DOUT2	TWI0-SDA	I2S2-DIN2	LCD0-D18	UART4-TX		PB-EINT2
PB3	LCD0-D1	I2S2-DOUT1	TWI0-SCK	I2S2-DIN0	LCD0-D19	UART4-RX		PB-EINT3
PB4	LCD0-D8	I2S2-DOUT0	TWI1-SCK	I2S2-DIN1	LCD0-D20	UART5-TX		PB-EINT4
PB5	LCD0-D9	I2S2-BCLK	TWI1-SDA	PWM0	LCD0-D21	UART5-RX		PB-EINT5
PB6	LCD0-D16	I2S2-LRCK	TWI3-SCK	PWM1	LCD0-D22	UART3-TX	CPUBIST0	PB-EINT6
PB7	LCD0-D17	I2S2-MCLK	TWI3-SDA	IR-RX	LCD0-D23	UART3-RX	CPUBIST1	PB-EINT7
PB8	DMIC-DATA3	PWM5	TWI2-SCK	SPI1-HOLD/ DBI-DCX/ DBI-WRX	UART0-TX	UART1-TX		PB-EINT8
PB9	DMIC-DATA2	PWM6	TWI2-SDA	SPI1-MISO/ DBI-SDI/ DBI-TE/ DBI-DCX	UART0-RX	UART1-RX		PB-EINT9
PB10	DMIC-DATA1	PWM7	TWI0-SCK	SPI1-MOSI/ DBI-SDO	CLK-FANOUT0	UART1-RTS		PB-EINT10
PB11	DMIC-DATA0	PWM2	TWI0-SDA	SPI1-CLK/ DBI-SCLK	CLK-FANOUT1	UART1-CTS		PB-EINT11
PB12	DMIC-CLK	PWM0		SPI1-CS/ DBI-CSX	CLK-FANOUT2	IR-RX		PB-EINT12

Table 10-22 PC Multiplex Function

GPIO Port	Function 2	Function 3	Function 4	Function 5	Function 6	Function 7	Function 8	Function 14
PC0	UART2-TX	TWI2-SCK	LEDC-DO					PC-EINT0
PC1	UART2-RX	TWI2-SDA						PC-EINT1
PC2	SPI0-CLK	SDC2-CLK						PC-EINT2
PC3	SPI0-CS0	SDC2-CMD						PC-EINT3
PC4	SPI0-MOSI	SDC2-D2	BOOT-SEL0					PC-EINT4
PC5	SPI0-MISO	SDC2-D1	BOOT-SEL1					PC-EINT5
PC6	SPI0-WP	SDC2-D0	UART3-TX	TWI3-SCK	DBG-CLK			PC-EINT6
PC7	SPI0-HOLD	SDC2-D3	UART3-RX	TWI3-SDA	TCON-TRIG			PC-EINT7

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Table 10-23 PD Multiplex Function

GPIO Port	Function 2	Function 3	Function 4	Function 5	Function 6	Function 7	Function 8	Function 14
PD0	LCD0-D2	LVDS0-V0P	DSI-D0P	TWI0-SCK				PD-EINT0
PD1	LCD0-D3	LVDS0-V0N	DSI-D0N	UART2-TX				PD-EINT1
PD2	LCD0-D4	LVDS0-V1P	DSI-D1P	UART2-RX				PD-EINT2
PD3	LCD0-D5	LVDS0-V1N	DSI-D1N	UART2-RTS				PD-EINT3
PD4	LCD0-D6	LVDS0-V2P	DSI-CKP	UART2-CTS				PD-EINT4
PD5	LCD0-D7	LVDS0-V2N	DSI-CKN	UART5-TX				PD-EINT5
PD6	LCD0-D10	LVDS0-CKP	DSI-D2P	UART5-RX				PD-EINT6
PD7	LCD0-D11	LVDS0-CKN	DSI-D2N	UART4-TX				PD-EINT7
PD8	LCD0-D12	LVDS0-V3P	DSI-D3P	UART4-RX				PD-EINT8
PD9	LCD0-D13	LVDS0-V3N	DSI-D3N	PWM6				PD-EINT9
PD10	LCD0-D14	LVDS1-V0P	SPI1-CS/DBI-CSX	UART3-TX				PD-EINT10
PD11	LCD0-D15	LVDS1-V0N	SPI1-CLK/ DBI-SCLK	UART3-RX				PD-EINT11
PD12	LCD0-D18	LVDS1-V1P	SPI1-MOSI/ DBI-SDO	TWI0-SDA				PD-EINT12
PD13	LCD0-D19	LVDS1-V1N	SPI1-MISO/ DBI-SDI/DBI-TE/ DBI-DCX	UART3-RTS				PD-EINT13
PD14	LCD0-D20	LVDS1-V2P	SPI1-HOLD/ DBI-DCX/ DBI-WRX	UART3-CTS				PD-EINT14
PD15	LCD0-D21	LVDS1-V2N	SPI1-WP/DBI-TE	IR-RX				PD-EINT15
PD16	LCD0-D22	LVDS1-CKP	DMIC-DATA3	PWM0				PD-EINT16
PD17	LCD0-D23	LVDS1-CKN	DMIC-DATA2	PWM1				PD-EINT17
PD18	LCD0-CLK	LVDS1-V3P	DMIC-DATA1	PWM2				PD-EINT18
PD19	LCD0-DE	LVDS1-V3N	DMIC-DATA0	PWM3				PD-EINT19
PD20	LCD0-HSYNC	TWI2-SCK	DMIC-CLK	PWM4				PD-EINT20
PD21	LCD0-VSYNC	TWI2-SDA	UART1-TX	PWM5				PD-EINT21
PD22	OWA-OUT	IR-RX	UART1-RX	PWM7				PD-EINT22

Table 10-24 PE Multiplex Function

GPIO Port	Function 2	Function 3	Function 4	Function 5	Function 6	Function 7	Function 8	Function 14
PE0	NCSI0-HSYNC	UART2-RTS	TWI1-SCK	LCD0-HSYNC			RGMII-RXCTRL/ RMII-CRS-DV	PE-EINT0
PE1	NCSI0-VSYNC	UART2-CTS	TWI1-SDA	LCD0-VSYNC			RGMII-RXD0/ RMII-RXD0	PE-EINT1
PE2	NCSI0-PCLK	UART2-TX	TWI0-SCK	CLK-FANOUT0	UART0-TX		RGMII-RXD1/ RMII-RXD1	PE-EINT2
PE3	NCSI0-MCLK	UART2-RX	TWI0-SDA	CLK-FANOUT1	UART0-RX		RGMII-TXCK/ RMII-TXCK	PE-EINT3
PE4	NCSI0-D0	UART4-TX	TWI2-SCK	CLK-FANOUT2	D-JTAG-MS		RGMII-TXD0/ RMII-TXD0	PE-EINT4
PE5	NCSI0-D1	UART4-RX	TWI2-SDA	LEDC-DO	D-JTAG-DI		RGMII-TXD1/ RMII-TXD1	PE-EINT5

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GPIO Port	Function 2	Function 3	Function 4	Function 5	Function 6	Function 7	Function 8	Function 14
PE6	NCSI0-D2	UART5-TX	TWI3-SCK		D-JTAG-DO		RGMII-TXCTRL/ RMII-TXEN	PE-EINT6
PE7	NCSI0-D3	UART5-RX	TWI3-SDA	OWA-OUT	D-JTAG-CK		RGMII-CLKIN/ RMII-RXER	PE-EINT7
PE8	NCSI0-D4	UART1-RTS	PWM2	UART3-TX	JTAG-MS		MDC	PE-EINT8
PE9	NCSI0-D5	UART1-CTS	PWM3	UART3-RX	JTAG-DI		MDIO	PE-EINT9
PE10	NCSI0-D6	UART1-TX	PWM4	IR-RX	JTAG-DO		EPHY-25M	PE-EINT10
PE11	NCSI0-D7	UART1-RX	I2S0-DOUT3	I2S0-DIN3	JTAG-CK		RGMII-TXD2	PE-EINT11
PE12	TWI2-SCK	NCSI0-FIELD	I2S0-DOUT2	I2S0-DIN2			RGMII-TXD3	PE-EINT12
PE13	TWI2-SDA	PWM5	I2S0-DOUT0	I2S0-DIN1	DMIC-DATA3		RGMII-RXD2	PE-EINT13
PE14	TWI1-SCK	D-JTAG-MS	I2S0-DOUT1	I2S0-DIN0	DMIC-DATA2		RGMII-RXD3	PE-EINT14
PE15	TWI1-SDA	D-JTAG-DI	PWM6	I2S0-LRCK	DMIC-DATA1		RGMII-RXCK	PE-EINT15
PE16	TWI3-SCK	D-JTAG-DO	PWM7	I2S0-BCLK	DMIC-DATA0			PE-EINT16
PE17	TWI3-SDA	D-JTAG-CK	IR-TX	I2S0-MCLK	DMIC-CLK			PE-EINT17

Table 10-25 PF Multiplex Function

GPIO Port	Function 2	Function 3	Function 4	Function 5	Function 6	Function 7	Function 8	Function 14
PF0	SDC0-D1	JTAG-MS		I2S2-DOUT1	I2S2-DIN0			PF-EINT0
PF1	SDC0-D0	JTAG-DI		I2S2-DOUT0	I2S2-DIN1			PF-EINT1
PF2	SDC0-CLK	UART0-TX	TWI0-SCK					PF-EINT2
PF3	SDC0-CMD	JTAG-DO		I2S2-BCLK				PF-EINT3
PF4	SDC0-D3	UART0-RX	TWI0-SDA	PWM6	IR-TX			PF-EINT4
PF5	SDC0-D2	JTAG-CK		I2S2-LRCK				PF-EINT5
PF6		OWA-OUT	IR-RX	I2S2-MCLK	PWM5			PF-EINT6

Table 10-26 PG Multiplex Function

GPIO Port	Function 2	Function 3	Function 4	Function 5	Function 6	Function 7	Function 8	Function 14
PG0	SDC1-CLK	UART3-TX	RGMII-RXCTRL/ RMII-CRS-DV	PWM7				PG-EINT0
PG1	SDC1-CMD	UART3-RX	RGMII-RXD0/ RMII-RXD0	PWM6				PG-EINT1
PG2	SDC1-D0	UART3-RTS	RGMII-RXD1/ RMII-RXD1	UART4-TX				PG-EINT2
PG3	SDC1-D1	UART3-CTS	RGMII-TXCK/ RMII-TXCK	UART4-RX				PG-EINT3
PG4	SDC1-D2	UART5-TX	RGMII-TXD0/ RMII-TXD0	PWM5				PG-EINT4
PG5	SDC1-D3	UART5-RX	RGMII-TXD1/ RMII-TXD1	PWM4				PG-EINT5
PG6	UART1-TX	TWI2-SCK	RGMII-TXD2	PWM1				PG-EINT6
PG7	UART1-RX	TWI2-SDA	RGMII-TXD3					PG-EINT7
PG8	UART1-RTS	TWI1-SCK	RGMII-RXD2	UART3-TX				PG-EINT8
PG9	UART1-CTS	TWI1-SDA	RGMII-RXD3	UART3-RX				PG-EINT9
PG10	PWM3	TWI3-SCK	RGMII-RXCK	CLK-FANOUT0	IR-RX			PG-EINT10
PG11	I2S1-MCLK	TWI3-SDA	EPHY-25M	CLK-FANOUT1	TCON-TRIG			PG-EINT11

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GPIO Port	Function 2	Function 3	Function 4	Function 5	Function 6	Function 7	Function 8	Function 14
PG12	I2S1-LRCK	TWI0-SCK	RGMII-TXCTRL/ RMII-TXEN	CLK-FANOUT2	PWM0	UART1-TX		PG-EINT12
PG13	I2S1-BCLK	TWI0-SDA	RGMII-CLKIN/ RMII-RXER	PWM2	LEDC-DO	UART1-RX		PG-EINT13
PG14	I2S1-DIN0	TWI2-SCK	MDC	I2S1-DOUT1	SPI0-WP	UART1-RTS		PG-EINT14
PG15	I2S1-DOUT0	TWI2-SDA	MDIO	I2S1-DIN1	SPI0-HOLD	UART1-CTS		PG-EINT15
PG16	IR-RX	TCON-TRIG	PWM5	CLK-FANOUT2		LEDC-DO		PG-EINT16
PG17	UART2-TX	TWI3-SCK	PWM7	CLK-FANOUT0	IR-TX	UART0-TX		PG-EINT17
PG18	UART2-RX	TWI3-SDA	PWM6	CLK-FANOUT1	OWA-OUT	UART0-RX		PG-EINT18

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10.7.3.3 Port Function

The Port Controller supports 6 GPIOs, every GPIO can configure as Input, Output, Function Peripheral, IO disable or Interrupt function. The configuration instruction of every function is as follows.

Table 10-27 Port Function

	Function	Buffer Strength	Pull Up	Pull Down
Input	GPIO/Multiplexing Input	/	X	X
Output	GPIO/Multiplexing Output	Y	X	X
Disable	Pull Up	/	Y	N
	Pull Down	/	N	Y
Interrupt	Trigger	/	X	X

/: non-configure, configuration is invalid

Y: configure

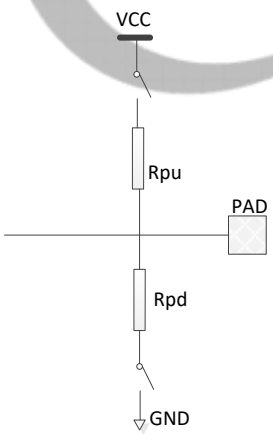
X: Select configuration according to the actual situation

N: Forbid to configure

10.7.3.4 Pull Up/Down and High-Impedance Logic

Each IO pin can configure the internal pull-up/down function or high-impedance.

Figure 10-68 Pull up/down Logic



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High-impedance, the output is float state, all buffer is off, the level is decided by external high/low level. When high-impedance, the software configures the switch on Rpu and Rpd as off, and the multiplexing function of IO is set as IO disable or input by software.

Pull-up, an uncertain signal is pulled high by resistance, the resistance has a current-limiting function. When pulling up, the switch on Rpu is conducted by software configuration, the IO is pulled up to VCC by Rpu.

Pull-down, an uncertain signal is pulled low by a resistance. When pulling down, the switch on Rpd is conducted by software configuration, the IO is pulled down to GND by Rpd.

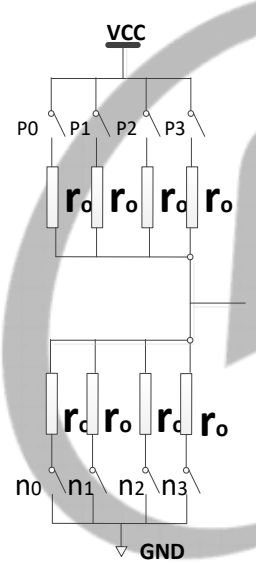
The pull-up/down of each IO is weak pull-up/down.

The setting of pull-down, pull-up, high-impedance is decided by the external circuit.

10.7.3.5 Buffer Strength

Each IO can be set as different buffer strength. The IO buffer diagram is as follows.

Figure 10-69 IO Buffer Strength Diagram



When output high level, the n0, n1, n2, n3 of NMOS is off, the p0, p1, p2, p3 of PMOS is on. When the buffer strength is set to 0 (buffer strength is weakest), only the p0 is on, the output impedance is maximum, the impedance value is r0. When the buffer strength is set to 1, only the p0 and p1 is on, the output impedance is equivalent to two r0 in parallel, the impedance value is r0/2. When the buffer strength is 2, only the p0, p1, and p2 is on, the output impedance is equivalent to three r0 in parallel, the impedance value is r0/3. When buffer strength is 3, the p0, p1, p2, and p3 is on, the output impedance is equivalent to four r0 in parallel, the impedance value is r0/4.

When output low level, the p0, p1, p2, p3 of PMOS is off, the n0, n1, n2, n3 of NMOS is on. When the buffer strength is set to 0 (buffer strength is weakest), only the n0 is on, the output impedance is maximum, the

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impedance value is r0. When the buffer strength is set to 1, only the n0 and n1 is on, the output impedance is equivalent to two r0 in parallel, the impedance value is r0/2. When the buffer strength is 2, only the n0, n1, and n2 is on, the output impedance is equivalent to three r0 in parallel, the impedance value is r0/3. When the buffer strength is 3, the n0, n1, n2, and n3 is on, the output impedance is equivalent to four r0 in parallel, the impedance value is r0/4.

When GPIO is set to input or interrupt function, between the output driver circuit and the port is unconnected, the driver configuration is invalid.

NOTE

The typical value of r0 is 180Ω.

10.7.3.6 Interrupt

Each group IO has an independent interrupt number. The IO within-group uses one interrupt number when one IO generates interrupt, the GPIO pins sent interrupt request to GIC. External Interrupt Status Register is used to query which IO generates interrupt.

The interrupt trigger of GPIO supports the following trigger types.

- Positive Edge: When a low level changes to a high level, the interrupt will generate. No matter how long a high level keeps, the interrupt generates only once.
- Negative Edge: When a high level changes to a low level, the interrupt will generate. No matter how long a low level keeps, the interrupt generates only once.
- High Level: Just keep a high level and the interrupt will always generate.
- Low Level: Just keep a low level and the interrupt will always generate.
- Double Edge: Positive and negative edge.

External Interrupt Configure Register is used to configure the trigger type.

The GPIO interrupt supports hardware debounce function by setting External Interrupt Debounce Register. Sample trigger signal using a lower sample clock, to reach the debounce effect because the dither frequency of the signal is higher than the sample frequency.

Set the sample clock source by PIO_INT_CLK_SELECT and the prescale factor by DEB_CLK_PRE_SCALE.

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10.7.4 Register List

Module Name	Base Address
GPIO	0x02000000

Register Name	Offset	Description
PB_CFG0	0x0030	PB Configure Register 0
PB_CFG1	0x0034	PB Configure Register 1
PB_DAT	0x0040	PB Data Register
PB_DRV0	0x0044	PB Multi_Driving Register 0
PB_DRV1	0x0048	PB Multi_Driving Register 1
PB_PULL0	0x0054	PB Pull Register 0
PC_CFG0	0x0060	PC Configure Register 0
PC_DAT	0x0070	PC Data Register
PC_DRV0	0x0074	PC Multi_Driving Register 0
PC_PULL0	0x0084	PC Pull Register 0
PD_CFG0	0x0090	PD Configure Register 0
PD_CFG1	0x0094	PD Configure Register 1
PD_CFG2	0x0098	PD Configure Register 2
PD_DAT	0x00A0	PD Data Register
PD_DRV0	0x00A4	PD Multi_Driving Register 0
PD_DRV1	0x00A8	PD Multi_Driving Register 1
PD_DRV2	0x00AC	PD Multi_Driving Register 2
PD_PULL0	0x00B4	PD Pull Register 0
PD_PULL1	0x00B8	PD Pull Register 1
PE_CFG0	0x00C0	PE Configure Register 0
PE_CFG1	0x00C4	PE Configure Register 1
PE_DAT	0x00D0	PE Data Register
PE_DRV0	0x00D4	PE Multi_Driving Register 0
PE_DRV1	0x00D8	PE Multi_Driving Register 1
PE_PULL0	0x00E4	PE Pull Register 0
PF_CFG0	0x00F0	PF Configure Register 0
PF_DAT	0x0100	PF Data Register
PF_DRV0	0x0104	PF Multi_Driving Register 0
PF_PULL0	0x0114	PF Pull Register 0
PG_CFG0	0x0120	PG Configure Register 0
PG_CFG1	0x0124	PG Configure Register 1
PG_DAT	0x0130	PG Data Register

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Register Name	Offset	Description
PG_DRV0	0x0134	PG Multi_Driving Register 0
PG_DRV1	0x0138	PG Multi_Driving Register 1
PG_DRV3	0x0140	PG Multi_Driving Register 3
PG_PULL0	0x0144	PG Pull Register 0
PB_EINT_CFG0	0x0220	PB External Interrupt Configure Register 0
PB_EINT_CTL	0x0230	PB External Interrupt Control Register
PB_EINT_STATUS	0x0234	PB External Interrupt Status Register
PB_EINT_DEB	0x0238	PB External Interrupt Debounce Register
PC_EINT_CFG0	0x0240	PC External Interrupt Configure Register 0
PC_EINT_CTL	0x0250	PC External Interrupt Control Register
PC_EINT_STATUS	0x0254	PC External Interrupt Status Register
PC_EINT_DEB	0x0258	PC External Interrupt Debounce Register
PD_EINT_CFG0	0x0260	PD External Interrupt Configure Register 0
PD_EINT_CFG1	0x0264	PD External Interrupt Configure Register 1
PD_EINT_CFG2	0x0268	PD External Interrupt Configure Register 2
PD_EINT_CTL	0x0270	PD External Interrupt Control Register
PD_EINT_STATUS	0x0274	PD External Interrupt Status Register
PD_EINT_DEB	0x0278	PD External Interrupt Debounce Register
PE_EINT_CFG0	0x0280	PE External Interrupt Configure Register 0
PE_EINT_CFG1	0x0284	PE External Interrupt Configure Register 1
PE_EINT_CTL	0x0290	PE External Interrupt Control Register
PE_EINT_STATUS	0x0294	PE External Interrupt Status Register
PE_EINT_DEB	0x0298	PE External Interrupt Debounce Register
PF_EINT_CFG0	0x02A0	PF External Interrupt Configure Register 0
PF_EINT_CTL	0x02B0	PF External Interrupt Control Register
PF_EINT_STATUS	0x02B4	PF External Interrupt Status Register
PF_EINT_DEB	0x02B8	PF External Interrupt Debounce Register
PG_EINT_CFG0	0x02C0	PG External Interrupt Configure Register 0
PG_EINT_CFG1	0x02C4	PG External Interrupt Configure Register 1
PG_EINT_CTL	0x02D0	PG External Interrupt Control Register
PG_EINT_STATUS	0x02D4	PG External Interrupt Status Register
PG_EINT_DEB	0x02D8	PG External Interrupt Debounce Register
PIO_POW_MOD_SEL	0x0340	PIO Group Withstand Voltage Mode Select Register
PIO_POW_MS_CTL	0x0344	PIO Group Withstand Voltage Mode Select Control Register
PIO_POW_VAL	0x0348	PIO Group Power Value Register

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Register Name	Offset	Description
PIO_POW_VOL_SEL_CTL	0x0350	PIO Group Power Voltage Select Control Register
PB_SECURE	0x0404	PB SECURE Register
PC_SECURE	0x0408	PC SECURE Register
PD_SECURE	0x040C	PD SECURE Register
PE_SECURE	0x0410	PE SECURE Register
PF_SECURE	0x0414	PF SECURE Register
PG_SECURE	0x0418	PG SECURE Register

10.7.5 Register Description

10.7.5.1 0x0030 PB Configure Register 0 (Default Value: 0xFFFF_FFFF)

Offset: 0x0030			Register Name: PB_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0xF	PB7_SELECT PB7 Select 0000:Input 0001:Output 0010:LCD0-D17 0011:I2S2-MCLK 0100:TWI3-SDA 0101:IR-RX 0110:LCD0-D23 0111:UART3-RX 1000:CPUBIST1 1001:Reserved 1110:PB-EINT7 1111:IO Disable
27:24	R/W	0xF	PB6_SELECT PB6 Select 0000:Input 0001:Output 0010:LCD0-D16 0011:I2S2-LRCK 0100:TWI3-SCK 0101:PWM1 0110:LCD0-D22 0111:UART3-TX 1000:CPUBIST0 1001:Reserved 1110:PB-EINT6 1111:IO Disable

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Offset: 0x0030			Register Name: PB_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	R/W	0xF	PB5_SELECT PB5 Select 0000:Input 0001:Output 0010:LCD0-D9 0011:I2S2-BCLK 0100:TWI1-SDA 0101:PWM0 0110:LCD0-D21 0111:UART5-RX 1000:Reserved 1001:Reserved 1110:PB-EINT5 1111:IO Disable
19:16	R/W	0xF	PB4_SELECT PB4 Select 0000:Input 0001:Output 0010:LCD0-D8 0011:I2S2-DOUT0 0100:TWI1-SCK 0101:I2S2-DIN1 0110:LCD0-D20 0111:UART5-TX 1000:Reserved 1001:Reserved 1110:PB-EINT4 1111:IO Disable
15:12	R/W	0xF	PB3_SELECT PB3 Select 0000:Input 0001:Output 0010:LCD0-D1 0011:I2S2-DOUT1 0100:TWI0-SCK 0101:I2S2-DIN0 0110:LCD0-D19 0111:UART4-RX 1000:Reserved 1001:Reserved 1110:PB-EINT3 1111:IO Disable
11:8	R/W	0xF	PB2_SELECT PB2 Select 0000:Input 0001:Output 0010:LCD0-D0 0011:I2S2-DOUT2 0100:TWI0-SDA 0101:I2S2-DIN2 0110:LCD0-D18 0111:UART4-TX 1000:Reserved 1001:Reserved 1110:PB-EINT2 1111:IO Disable

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Offset: 0x0030			Register Name: PB_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0xF	PB1_SELECT PB1 Select 0000:Input 0001:Output 0010:PWM4 0011:I2S2-DOUT3 0100:TWI2-SDA 0101:I2S2-DIN3 0110:UART0-RX 0111:UART2-RX 1000:IR-RX 1001:Reserved 1110:PB-EINT1 1111:IO Disable
3:0	R/W	0xF	PB0_SELECT PB0 Select 0000:Input 0001:Output 0010:PWM3 0011:IR-TX 0100:TWI2-SCK 0101:SPI1-WP/DBI-TE 0110:UART0-TX 0111:UART2-TX 1000:OWA-OUT 1001:Reserved 1110:PB-EINT0 1111:IO Disable

10.7.5.2 0x0034 PB Configure Register 1 (Default Value: 0x000F_FFFF)

Offset: 0x0034			Register Name: PB_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:20	/	/	/
19:16	R/W	0xF	PB12_SELECT PB12 Select 0000:Input 0001:Output 0010:DMIC-CLK 0011:PWM0 0100:Reserved 0101:SPI1-CS/DBI-CSX 0110:CLK-FANOUT2 0111:IR-RX 1000:Reserved 1001:Reserved 1110:PB-EINT12 1111:IO Disable

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Offset: 0x0034			Register Name: PB_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0xF	PB11_SELECT PB11 Select 0000:Input 0001:Output 0010:DMIC-DATA0 0011:PWM2 0100:TWI0-SDA 0101:SPI1-CLK/DBI-SCLK 0110:CLK-FANOUT1 0111:UART1-CTS 1000:Reserved 1001:Reserved 1110:PB-EINT11 1111:IO Disable
11:8	R/W	0xF	PB10_SELECT PB10 Select 0000:Input 0001:Output 0010:DMIC-DATA1 0011:PWM7 0100:TWI0-SCK 0101:SPI1-MOSI/DBI-SDO 0110:CLK-FANOUT0 0111:UART1-RTS 1000:Reserved 1001:Reserved 1110:PB-EINT10 1111:IO Disable
7:4	R/W	0xF	PB9_SELECT PB9 Select 0000:Input 0001:Output 0010:DMIC-DATA2 0011:PWM6 0100:TWI2-SDA 0101:SPI1-MISO/DBI-SDI/DBI-TE/DBI-DCX 0110:UART0-RX 0111:UART1-RX 1000:Reserved 1001:Reserved 1110:PB-EINT9 1111:IO Disable
3:0	R/W	0xF	PB8_SELECT PB8 Select 0000:Input 0001:Output 0010:DMIC-DATA3 0011:PWM5 0100:TWI2-SCK 0101:SPI1-HOLD/DBI-DCX/DBI-WRX 0110:UART0-TX 0111:UART1-TX 1000:Reserved 1001:Reserved 1110:PB-EINT8 1111:IO Disable

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10.7.5.3 0x0040 PB Data Register (Default Value: 0x0000_0000)

Offset: 0x0040			Register Name: PB_DAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:13	/	/	/
12:0	R/W	0x0	PB_DAT If the port is configured as the input function, the corresponding bit is the pin state. If the port is configured as the output function, the pin state is the same as the corresponding bit. The read bit value is the value set up by software. If the port is configured as a functional pin, the undefined value will be read.

10.7.5.4 0x0044 PB Multi_Driving Register 0 (Default Value: 0x1111_1111)

Offset: 0x0044			Register Name: PB_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x1	PB7_DRV PB7 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
27:26	/	/	/
25:24	R/W	0x1	PB6_DRV PB6 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
23:22	/	/	/
21:20	R/W	0x1	PB5_DRV PB5 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
19:18	/	/	/
17:16	R/W	0x1	PB4_DRV PB4 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
15:14	/	/	/

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Offset: 0x0044			Register Name: PB_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
13:12	R/W	0x1	PB3_DRV PB3 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/
9:8	R/W	0x1	PB2_DRV PB2 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PB1_DRV PB1 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/
1:0	R/W	0x1	PB0_DRV PB0 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

10.7.5.5 0x0048 PB Multi_Driving Register 1 (Default Value: 0x0001_1111)

Offset: 0x0048			Register Name: PB_DRV1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17:16	R/W	0x1	PB12_DRV PB12 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
15:14	/	/	/
13:12	R/W	0x1	PB11_DRV PB11 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/

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Offset: 0x0048			Register Name: PB_DRV1
Bit	**Read/Write**	**Default/Hex**	**Description**
9:8	R/W	0x1	PB10_DRV PB10 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PB9_DRV PB9 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/
1:0	R/W	0x1	PB8_DRV PB8 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

10.7.5.6 0x0054 PB Pull Register 0 (Default Value: 0x0000_0000)

Offset: 0x0054			Register Name: PB_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/
25:24	R/W	0x0	PB12_PULL PB12 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
23:22	R/W	0x0	PB11_PULL PB11 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
21:20	R/W	0x0	PB10_PULL PB10 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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Offset: 0x0054			Register Name: PB_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
19:18	R/W	0x0	PB9_PULL PB9 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
17:16	R/W	0x0	PB8_PULL PB8 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
15:14	R/W	0x0	PB7_PULL PB7 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
13:12	R/W	0x0	PB6_PULL PB6 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
11:10	R/W	0x0	PB5_PULL PB5 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
9:8	R/W	0x0	PB4_PULL PB4 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
7:6	R/W	0x0	PB3_PULL PB3 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
5:4	R/W	0x0	PB2_PULL PB2 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
3:2	R/W	0x0	PB1_PULL PB1 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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Offset: 0x0054			Register Name: PB_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
1:0	R/W	0x0	PB0_PULL PB0 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

10.7.5.7 0x0060 PC Configure Register 0 (Default Value: 0xFFFF_FFFF)

Offset: 0x0060			Register Name: PC_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0xF	PC7_SELECT PC7 Select 0000:Input 0001:Output 0010:SPI0-HOLD 0011:SDC2-D3 0100:UART3-RX 0101:TWI3-SDA 0110:TCON-TRIG 0111:Reserved 1000:Reserved 1001:Reserved 1110:PC-EINT7 1111:IO Disable
27:24	R/W	0xF	PC6_SELECT PC6 Select 0000:Input 0001:Output 0010:SPI0-WP 0011:SDC2-D0 0100:UART3-TX 0101:TWI3-SCK 0110:DBG-CLK 0111:Reserved 1000:Reserved 1001:Reserved 1110:PC-EINT6 1111:IO Disable
23:20	R/W	0xF	PC5_SELECT PC5 Select 0000:Input 0001:Output 0010:SPI0-MISO 0011:SDC2-D1 0100:BOOT-SEL1 0101:Reserved 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PC-EINT5 1111:IO Disable

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Offset: 0x0060			Register Name: PC_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
19:16	R/W	0xF	PC4_SELECT PC4 Select. 0000:Input 0001:Output 0010:SPI0-MOSI 0011:SDC2-D2 0100:BOOT-SEL0 0101:Reserved 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PC-EINT4 1111:IO Disable
15:12	R/W	0xF	PC3_SELECT PC3 Select 0000:Input 0001:Output 0010:SPI0-CS0 0011:SDC2-CMD 0100:Reserved 0101:Reserved 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PC-EINT3 1111:IO Disable
11:8	R/W	0xF	PC2_SELECT PC2 Select 0000:Input 0001:Output 0010:SPI0-CLK 0011:SDC2-CLK 0100:Reserved 0101:Reserved 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PC-EINT2 1111:IO Disable
7:4	R/W	0xF	PC1_SELECT PC1 Select. 0000:Input 0001:Output 0010:UART2-RX 0011:TWI2-SDA 0100:Reserved 0101:Reserved 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PC-EINT1 1111:IO Disable

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Offset: 0x0060			Register Name: PC_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0xF	PC0_SELECT PC0 Select 0000:Input 0001:Output 0010:UART2-TX 0011:TWI2-SCK 0100:LEDC-DO 0101:Reserved 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PC-EINT0 1111:IO Disable

10.7.5.8 0x0070 PC Data Register (Default Value: 0x0000_0000)

Offset: 0x0070			Register Name: PC_DAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x0	PC_DAT If the port is configured as the input function, the corresponding bit is the pin state. If the port is configured as the output function, the pin state is the same as the corresponding bit. The read bit value is the value set up by software. If the port is configured as a functional pin, the undefined value will be read.

10.7.5.9 0x0074 PC Multi_Driving Register 0 (Default Value: 0x1111_1111)

Offset: 0x0074			Register Name: PC_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x1	PC7_DRV PC7 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
27:26	/	/	/

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Offset: 0x0074			Register Name: PC_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
25:24	R/W	0x1	PC6_DRV PC6 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
23:22	/	/	/
21:20	R/W	0x1	PC5_DRV PC5 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
19:18	/	/	/
17:16	R/W	0x1	PC4_DRV PC4 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
15:14	/	/	/
13:12	R/W	0x1	PC3_DRV PC3 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/
9:8	R/W	0x1	PC2_DRV PC2 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PC1_DRV PC1 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/
1:0	R/W	0x1	PC0_DRV PC0 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

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10.7.5.10 0x0084 PC Pull Register 0 (Default Value: 0x0000_0540)

Offset: 0x0084			Register Name: PC_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:14	R/W	0x0	PC7_PULL PC7 Pull_up/down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
13:12	R/W	0x0	PC6_PULL PC6 Pull_up/down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
11:10	R/W	0x1	PC5_PULL PC5 Pull_up/down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
9:8	R/W	0x1	PC4_PULL PC4 Pull_up/down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
7:6	R/W	0x1	PC3_PULL PC3 Pull_up/down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
5:4	R/W	0x0	PC2_PULL PC2 Pull_up/down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
3:2	R/W	0x0	PC1_PULL PC1 Pull_up/down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
1:0	R/W	0x0	PC0_PULL PC0 Pull_up/down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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10.7.5.11 0x0090 PD Configure Register 0 (Default Value: 0xFFFF_FFFF)

Offset: 0x0090			Register Name: PD_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0xF	PD7_SELECT PD7 Select 0000:Input 0001:Output 0010:LCD0-D11 0011:LVDS0-CKN 0100:DSI-D2N 0101:UART4-TX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT7 1111:IO Disable
27:24	R/W	0xF	PD6_SELECT PD6 Select 0000:Input 0001:Output 0010:LCD0-D10 0011:LVDS0-CKP 0100:DSI-D2P 0101:UART5-RX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT6 1111:IO Disable
23:20	R/W	0xF	PD5_SELECT PD5 Select 0000:Input 0001:Output 0010:LCD0-D7 0011:LVDS0-V2N 0100:DSI-CKN 0101:UART5-TX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT5 1111:IO Disable
19:16	R/W	0xF	PD4_SELECT PD4 Select 0000:Input 0001:Output 0010:LCD0-D6 0011:LVDS0-V2P 0100:DSI-CKP 0101:UART2-CTS 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT4 1111:IO Disable

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Offset: 0x0090			Register Name: PD_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0xF	PD3_SELECT PD3 Select 0000:Input 0001:Output 0010:LCD0-D5 0011:LVDS0-V1N 0100:DSI-D1N 0101:UART2-RTS 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT3 1111:IO Disable
11:8	R/W	0xF	PD2_SELECT PD2 Select 0000:Input 0001:Output 0010:LCD0-D4 0011:LVDS0-V1P 0100:DSI-D1P 0101:UART2-RX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT2 1111:IO Disable
7:4	R/W	0xF	PD1_SELECT PD1 Select 0000:Input 0001:Output 0010:LCD0-D3 0011:LVDS0-V0N 0100:DSI-D0N 0101:UART2-TX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT1 1111:IO Disable
3:0	R/W	0xF	PD0_SELECT PD0 Select 0000:Input 0001:Output 0010:LCD0-D2 0011:LVDS0-V0P 0100:DSI-D0P 0101:TWI0-SCK 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT0 1111:IO Disable

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10.7.5.12 0x0094 PD Configure Register 1 (Default Value: 0xFFFF_FFFF)

Offset: 0x0094			Register Name: PD_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0xF	PD15_SELECT PD15 Select 0000:Input 0001:Output 0010:LCD0-D21 0011:LVDS1-V2N 0100:SPI1-WP/DBI-TE 0101:IR-RX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT15 1111:IO Disable
27:24	R/W	0xF	PD14_SELECT PD14 Select 0000:Input 0001:Output 0010:LCD0-D20 0011:LVDS1-V2P 0100:SPI1-HOLD/DBI-DCX/DBI-WRX 0101:UART3-CTS 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT14 1111:IO Disable
23:20	R/W	0xF	PD13_SELECT PD13 Select 0000:Input 0001:Output 0010:LCD0-D19 0011:LVDS1-V1N 0100:SPI1-MISO/DBI-SDI/DBI-TE/DBI-DCX 0101:UART3-RTS 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT13 1111:IO Disable
19:16	R/W	0xF	PD12_SELECT PD12 Select 0000:Input 0001:Output 0010:LCD0-D18 0011:LVDS1-V1P 0100:SPI1-MOSI/DBI-SDO 0101:TWI0-SDA 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT12 1111:IO Disable

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Offset: 0x0094			Register Name: PD_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0xF	PD11_SELECT PD11 Select 0000:Input 0001:Output 0010:LCD0-D15 0011:LVDS1-V0N 0100:SPI1-CLK/DBI-SCLK 0101:UART3-RX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT11 1111:IO Disable
11:8	R/W	0xF	PD10_SELECT PD10 Select 0000:Input 0001:Output 0010:LCD0-D14 0011:LVDS1-V0P 0100:SPI1-CS/DBI-CSX 0101:UART3-TX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT10 1111:IO Disable
7:4	R/W	0xF	PD9_SELECT PD9 Select 0000:Input 0001:Output 0010:LCD0-D13 0011:LVDS0-V3N 0100:DSI-D3N 0101:PWM6 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT9 1111:IO Disable
3:0	R/W	0xF	PD8_SELECT PD8 Select 0000:Input 0001:Output 0010:LCD0-D12 0011:LVDS0-V3P 0100:DSI-D3P 0101:UART4-RX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT8 1111:IO Disable

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10.7.5.13 0x0098 PD Configure Register 2 (Default Value: 0x0FFF_FFFF)

Offset: 0x0098			Register Name: PD_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/
27:24	R/W	0xF	PD22_SELECT PD22 Select 0000:Input 0001:Output 0010:OWA-OUT 0011:IR-RX 0100:UART1-RX 0101:PWM7 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT22 1111:IO Disable
23:20	R/W	0xF	PD21_SELECT PD21 Select 0000:Input 0001:Output 0010:LCD0-VSYNC 0011:TWI2-SDA 0100:UART1-TX 0101:PWM5 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT21 1111:IO Disable
19:16	R/W	0xF	PD20_SELECT PD20 Select 0000:Input 0001:Output 0010:LCD0-HSYNC 0011:TWI2-SCK 0100:DMIC-CLK 0101:PWM4 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT20 1111:IO Disable
15:12	R/W	0xF	PD19_SELECT PD19 Select 0000:Input 0001:Output 0010:LCD0-DE 0011:LVDS1-V3N 0100:DMIC-DATA0 0101:PWM3 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT19 1111:IO Disable

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Offset: 0x0098			Register Name: PD_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
11:8	R/W	0xF	PD18_SELECT PD18 Select 0000:Input 0001:Output 0010:LCD0-CLK 0011:LVDS1-V3P 0100:DMIC-DATA1 0101:PWM2 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT18 1111:IO Disable
7:4	R/W	0xF	PD17_SELECT PD17 Select. 0000:Input 0001:Output 0010:LCD0-D23 0011:LVDS1-CKN 0100:DMIC-DATA2 0101:PWM1 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT17 1111:IO Disable
3:0	R/W	0xF	PD16_SELECT PD16 Select 0000:Input 0001:Output 0010:LCD0-D22 0011:LVDS1-CKP 0100:DMIC-DATA3 0101:PWM0 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PD-EINT16 1111:IO Disable

10.7.5.14 0x00A0 PD Data Register (Default Value: 0x0000_0000)

Offset: 0x00A0			Register Name: PD_DAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:23	/	/	/

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Offset: 0x00A0			Register Name: PD_DAT
Bit	**Read/Write**	**Default/Hex**	**Description**
22:0	R/W	0x0	PD_DAT PD Data If the port is configured as the input function, the corresponding bit is the pin state. If the port is configured as the output function, the pin state is the same as the corresponding bit. The read bit value is the value set up by software. If the port is configured as a functional pin, the undefined value will be read.

10.7.5.15 0x00A4 PD Multi_Driving Register 0 (Default Value: 0x1111_1111)

Offset: 0x00A4			Register Name: PD_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x1	PD7_DRV PD7 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
27:26	/	/	/
25:24	R/W	0x1	PD6_DRV PD6 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
23:22	/	/	/
21:20	R/W	0x1	PD5_DRV PD5 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
19:18	/	/	/
17:16	R/W	0x1	PD4_DRV PD4 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
15:14	/	/	/

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Offset: 0x00A4			Register Name: PD_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
13:12	R/W	0x1	PD3_DRV PD3 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/
9:8	R/W	0x1	PD2_DRV PD2 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PD1_DRV PD1 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/
1:0	R/W	0x1	PD0_DRV PD0 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3

10.7.5.16 0x00A8 PD Multi_Driving Register 1 (Default Value: 0x1111_1111)

Offset: 0x00A8			Register Name: PD_DRV1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x1	PD15_DRV PD15 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
27:26	/	/	/
25:24	R/W	0x1	PD14_DRV PD14 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
23:22	/	/	/

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Offset: 0x00A8			Register Name: PD_DRV1
Bit	**Read/Write**	**Default/Hex**	**Description**
21:20	R/W	0x1	PD13_DRV PD13 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
19:18	/	/	/
17:16	R/W	0x1	PD12_DRV PD12 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
15:14	/	/	/
13:12	R/W	0x1	PD11_DRV PD11 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/
9:8	R/W	0x1	PD10_DRV PD10 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PD9_DRV PD9 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/
1:0	R/W	0x1	PD8_DRV PD8 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3

10.7.5.17 0x00AC PD Multi_Driving Register 2 (Default Value: 0x0111_1111)

Offset: 0x00AC			Register Name: PD_DRV2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/

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Offset: 0x00AC			Register Name: PD_DRV2
Bit	**Read/Write**	**Default/Hex**	**Description**
25:24	R/W	0x1	PD22_DRV PD22 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
23:22	/	/	/
21:20	R/W	0x1	PD21_DRV PD21 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
19:18	/	/	/
17:16	R/W	0x1	PD20_DRV PD20 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
15:14	/	/	/
13:12	R/W	0x1	PD19_DRV PD19 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/
9:8	R/W	0x1	PD18_DRV PD18 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PD17_DRV PD17 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/
1:0	R/W	0x1	PD16_DRV PD16 Multi_Driving Select. 00: Level 0 01: Level 1 10: Level 2 11: Level 3

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10.7.5.18 0x00B4 PD Pull Register 0 (Default Value: 0x0000_0000)

Offset: 0x00B4			Register Name: PD_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	R/W	0x0	PD15_PULL PD15 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
29:28	R/W	0x0	PD14_PULL PD14 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
27:26	R/W	0x0	PD13_PULL PD13 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
25:24	R/W	0x0	PD12_PULL PD12 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
23:22	R/W	0x0	PD11_PULL PD11 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
21:20	R/W	0x0	PD10_PULL PD10 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
19:18	R/W	0x0	PD9_PULL PD9 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
17:16	R/W	0x0	PD8_PULL PD8 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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Offset: 0x00B4			Register Name: PD_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
15:14	R/W	0x0	PD7_PULL PD7 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
13:12	R/W	0x0	PD6_PULL PD6 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
11:10	R/W	0x0	PD5_PULL PD5 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
9:8	R/W	0x0	PD4_PULL PD4 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
7:6	R/W	0x0	PD3_PULL PD3 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
5:4	R/W	0x0	PD2_PULL PD2 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
3:2	R/W	0x0	PD1_PULL PD1 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
1:0	R/W	0x0	PD0_PULL PD0 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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10.7.5.19 0x00B8 PD Pull Register 1 (Default Value: 0x0000_0000)

Offset: 0x00B8			Register Name: PD_PULL1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	/	/	/
13:12	R/W	0x0	PD22_PULL PD22 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
11:10	R/W	0x0	PD21_PULL PD21 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
9:8	R/W	0x0	PD20_PULL PD20 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
7:6	R/W	0x0	PD19_PULL PD19 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
5:4	R/W	0x0	PD18_PULL PD18 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
3:2	R/W	0x0	PD17_PULL PD17 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
1:0	R/W	0x0	PD16_PULL PD16 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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10.7.5.20 0x00C0 PE Configure Register 0 (Default Value: 0xFFFF_FFFF)

Offset: 0x00C0			Register Name: PE_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0xF	PE7_SELECT PE7 Select 0000:Input 0001:Output 0010:NCSI0-D3 0011:UART5-RX 0100:TWI3-SDA 0101:OWA-OUT 0110:D-JTAG-CK 0111:Reserved 1000:RGMII-CLKIN/RMII-RXER 1001:Reserved 1110:PE-EINT7 1111:IO Disable
27:24	R/W	0xF	PE6_SELECT PE6 Select 0000:Input 0001:Output 0010:NCSI0-D2 0011:UART5-TX 0100:TWI3-SCK 0101: Reserved 0110:D-JTAG-DO 0111:Reserved 1000:RMII-TXCTRL/RMII-TXEN 1001:Reserved 1110:PE-EINT6 1111:IO Disable
23:20	R/W	0xF	PE5_SELECT PE5 Select 0000:Input 0001:Output 0010:NCSI0-D1 0011:UART4-RX 0100:TWI2-SDA 0101:LEDC-DO 0110:D-JTAG-DI 0111:Reserved 1000:RGMII-TXD1/RMII-TXD1 1001:Reserved 1110:PE-EINT5 1111:IO Disable
19:16	R/W	0xF	PE4_SELECT PE4 Select 0000:Input 0001:Output 0010:NCSI0-D0 0011:UART4-TX 0100:TWI2-SCK 0101:CLK-FANOUT2 0110:D-JTAG-MS 0111:Reserved 1000:RGMII-TXD0/RMII-TXD0 1001:Reserved 1110:PE-EINT4 1111:IO Disable

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Offset: 0x00C0			Register Name: PE_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0xF	PE3_SELECT PE3 Select 0000:Input 0001:Output 0010:NCSI0-MCLK 0011:UART2-RX 0100:TWI0-SDA 0101:CLK-FANOUT1 0110:UART0-RX 0111:Reserved 1000:RGMII-TXCK/RMII-TXCK 1001:Reserved 1110:PE-EINT3 1111:IO Disable
11:8	R/W	0xF	PE2_SELECT PE2 Select 0000:Input 0001:Output 0010:NCSI0-PCLK 0011:UART2-TX 0100:TWI0-SCK 0101:CLK-FANOUT0 0110:UART0-TX 0111:Reserved 1000:RGMII-RXD1/RMII-RXD1 1001:Reserved 1110:PE-EINT2 1111:IO Disable
7:4	R/W	0xF	PE1_SELECT PE1 Select 0000:Input 0001:Output 0010:NCSI0-VSYNC 0011:UART2-CTS 0100:TWI1-SDA 0101:LCD0-VSYNC 0110:Reserved 0111:Reserved 1000:RGMII-RXD0/RMII-RXD0 1001:Reserved 1110:PE-EINT1 1111:IO Disable
3:0	R/W	0xF	PE0_SELECT PE0 Select 0000:Input 0001:Output 0010:NCSI0-HSYNC 0011:UART2-RTS 0100:TWI1-SCK 0101:LCD0-HSYNC 0110:Reserved 0111:Reserved 1000:RGMII-RXCTRL/RMII-CRS-DV 1001:Reserved 1110:PE-EINT0 1111:IO Disable

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10.7.5.21 0x00C4 PE Configure Register 1 (Default Value: 0xFFFF_FFFF)

Offset: 0x00C4			Register Name: PE_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0xF	PE15_SELECT PE15 Select 0000:Input 0001:Output 0010:TWI1-SDA 0011:D-JTAG-DI 0100:PWM6 0101:I2S0-LRCK 0110:DMIC-DATA1 0111:Reserved 1000:RGMII-RXCK 1001:Reserved 1110:PE-EINT15 1111:IO Disable
27:24	R/W	0xF	PE14_SELECT PE14 Select 0000:Input 0001:Output 0010:TWI1-SCK 0011:D-JTAG-MS 0100:I2S0-DOUT1 0101:I2S0-DIN0 0110:DMIC-DATA2 0111:Reserved 1000:RGMII-RXD3 1001:Reserved 1110:PE-EINT14 1111:IO Disable
23:20	R/W	0xF	PE13_SELECT PE13 Select 0000:Input 0001:Output 0010:TWI2-SDA 0011:PWM5 0100:I2S0-DOUT0 0101:I2S0-DIN1 0110: DMIC-DATA3 0111:Reserved 1000:RGMII-RXD2 1001:Reserved 1110:PE-EINT13 1111:IO Disable
19:16	R/W	0xF	PE12_SELECT PE12 Select 0000:Input 0001:Output 0010:TWI2-SCK 0011:NCSI0-FIELD 0100:I2S0-DOUT2 0101:I2S0-DIN2 0110:Reserved 0111:Reserved 1000:RGMII-TXD3 1001:Reserved 1110:PE-EINT12 1111:IO Disable

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Offset: 0x00C4			Register Name: PE_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0xF	PE11_SELECT PE11 Select 0000:Input 0001:Output 0010:NCSI0-D7 0011:UART1-RX 0100:I2S0-DOUT3 0101:I2S0-DIN3 0110:JTAG-CK 0111:Reserved 1000:RGMII-TXD2 1001:Reserved 1110:PE-EINT11 1111:IO Disable
11:8	R/W	0xF	PE10_SELECT PE10 Select 0000:Input 0001:Output 0010:NCSI0-D6 0011:UART1-TX 0100:PWM4 0101:IR-RX 0110:JTAG-DO 0111:Reserved 1000:EPHY-25M 1001:Reserved 1110:PE-EINT10 1111:IO Disable
7:4	R/W	0xF	PE9_SELECT PE9 Select 0000:Input 0001:Output 0010:NCSI0-D5 0011:UART1-CTS 0100:PWM3 0101:UART3-RX 0110:JTAG-DI 0111:Reserved 1000:MDIO 1001:Reserved 1110:PE-EINT9 1111:IO Disable
3:0	R/W	0xF	PE8_SELECT PE8 Select 0000:Input 0001:Output 0010:NCSI0-D4 0011:UART1-RTS 0100:PWM2 0101:UART3-TX 0110:JTAG-MS 0111:Reserved 1000:MDC 1001:Reserved 1110:PE_EINT8 1111:IO Disable

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10.7.5.22 0x00C8 PE Configure Register 2 (Default Value: 0x0000_00FF)

Offset: 0x00C8			Register Name: PE_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:4	R/W	0xF	PE17_SELECT PE17 Select 0000:Input 0001:Output 0010:TWI3-SDA 0011:D-JTAG-CK 0100:IR-TX 0101:I2S0-MCLK 0110:DMIC-CLK 0111:Reserved 1000:Reserved 1001:Reserved 1110:PE-EINT17 1111:IO Disable
3:0	R/W	0xF	PE16_SELECT PE16 Select 0000:Input 0001:Output 0010:TWI3-SCK 0011:D-JTAG-DO 0100:PWM7 0101:I2S0-BCLK 0110:DMIC-DATA0 0111:Reserved 1000:Reserved 1001:Reserved 1110:PE-EINT16 1111:IO Disable

10.7.5.23 0x00D0 PE Data Register (Default Value: 0x0000_0000)

Offset: 0x00D0			Register Name: PE_DAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17:0	R/W	0x0	PE_DAT PE Data If the port is configured as input, the corresponding bit is the pin state. If the port is configured as output, the pin state is the same as the corresponding bit. The read bit value is the value setup by software. If the port is configured as functional pin, the undefined value will be read.

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10.7.5.24 0x00D4 PE Multi_Driving Register 0 (Default Value: 0x1111_1111)

Offset: 0x00D4			Register Name: PE_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x1	PE7_DRV PE7 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
27:26	/	/	/
25:24	R/W	0x1	PE6_DRV PE6 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
23:22	/	/	/
21:20	R/W	0x1	PE5_DRV PE5 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
19:18	/	/	/
17:16	R/W	0x1	PE4_DRV PE4 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
15:14	/	/	/
13:12	R/W	0x1	PE3_DRV PE3 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/
9:8	R/W	0x1	PE2_DRV PE2 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/

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Offset: 0x00D4			Register Name: PE_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
5:4	R/W	0x1	PE1_DRV PE1 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/
1:0	R/W	0x1	PE0_DRV PE0 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

10.7.5.25 0x00D8 PE Multi_Driving Register 1 (Default Value: 0x1111_1111)

Offset: 0x00D8			Register Name: PE_DRV1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/
29:28	R/W	0x1	PE15_DRV PE15 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
27:26	/	/	/
25:24	R/W	0x1	PE14_DRV PE14 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
23:22	/	/	/
21:20	R/W	0x1	PE13_DRV PE13 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
19:18	/	/	/
17:16	R/W	0x1	PE12_DRV PE12 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

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Offset: 0x00D8			Register Name: PE_DRV1
Bit	**Read/Write**	**Default/Hex**	**Description**
15:14	/	/	/
13:12	R/W	0x1	PE11_DRV PE11 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/
9:8	R/W	0x1	PE10_DRV PE10 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PE9_DRV PE9 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/
1:0	R/W	0x1	PE8_DRV PE8 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

10.7.5.26 0x00DC PE Multi_Driving Register 2 (Default Value: 0x0000_0011)

Offset: 0x00DC			Register Name: PE_DRV2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:6	/	/	/
5:4	R/W	0x1	PE17_DRV PE17 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/

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Offset: 0x00DC			Register Name: PE_DRV2
Bit	**Read/Write**	**Default/Hex**	**Description**
1:0	R/W	0x1	PE16_DRV PE16 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

10.7.5.27 0x00E4 PE Pull Register 0 (Default Value: 0x0000_0000)

Offset: 0x00E4			Register Name: PE_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	R/W	0x0	PE15_PULL PE15 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
29:28	R/W	0x0	PE14_PULL PE14 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
27:26	R/W	0x0	PE13_PULL PE13 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
25:24	R/W	0x0	PE12_PULL PE12 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
23:22	R/W	0x0	PE11_PULL PE11 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
21:20	R/W	0x0	PE10_PULL PE10 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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Offset: 0x00E4			Register Name: PE_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
19:18	R/W	0x0	PE9_PULL PE9 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
17:16	R/W	0x0	PE8_PULL PE8 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
15:14	R/W	0x0	PE7_PULL PE7 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
13:12	R/W	0x0	PE6_PULL PE6 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
11:10	R/W	0x0	PE5_PULL PE5 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
9:8	R/W	0x0	PE4_PULL PE4 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
7:6	R/W	0x0	PE3_PULL PE3 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
5:4	R/W	0x0	PE2_PULL PE2 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
3:2	R/W	0x0	PE1_PULL PE1 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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Offset: 0x00E4			Register Name: PE_PULL0
Bit	Read/Write	Default/Hex	Description
1:0	R/W	0x0	PE0_PULL PE0 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

10.7.5.28 0x00E8 PE Pull Register 1 (Default Value: 0x0000_0000)

Offset: 0x00E8			Register Name: PE_PULL1
Bit	Read/Write	Default/Hex	Description
31:4	/	/	/
3:2	R/W	0x0	PE17_PULL PE17 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
1:0	R/W	0x0	PE16_PULL PE16 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

10.7.5.29 0x00F0 PF Configure Register 0 (Default Value: 0x0FFF_FFFF)

Offset: 0x00F0			Register Name: PF_CFG0
Bit	Read/Write	Default/Hex	Description
31:28	/	/	/
27:24	R/W	0xF	PF6_SELECT PF6 Select 0000:Input 0001:Output 0010:Reserved 0011:OWA-OUT 0100:IR-RX 0101:I2S2-MCLK 0110:PWM5 0111:Reserved 1000:Reserved 1001:Reserved 1110:PF-EINT6 1111:IO Disable

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Offset: 0x00F0			Register Name: PF_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	R/W	0xF	PF5_SELECT PF5 Select 0000:Input 0001:Output 0010:SDC0-D2 0011:JTAG-CK 0100:Reserved 0101:I2S2-LRCK 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PF-EINT5 1111:IO Disable
19:16	R/W	0xF	PF4_SELECT PF4 Select 0000:Input 0001:Output 0010:SDC0-D3 0011:UART0-RX 0100:TWI0-SDA 0101:PWM6 0110:IR-TX 0111:Reserved 1000:Reserved 1001:Reserved 1110:PF-EINT4 1111:IO Disable
15:12	R/W	0xF	PF3_SELECT PF3 Select 0000:Input 0001:Output 0010:SDC0-CMD 0011:JTAG-DO 0100:Reserved 0101:I2S2-BCLK 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PF-EINT3 1111:IO Disable
11:8	R/W	0xF	PF2_SELECT PF2 Select 0000:Input 0001:Output 0010:SDC0-CLK 0011:UART0-TX 0100:TWI0-SCK 0101: Reserved 0110: Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PF-EINT2 1111:IO Disable

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Offset: 0x00F0			Register Name: PF_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0xF	PF1_SELECT PF1 Select 0000:Input 0001:Output 0010:SDC0-D0 0011:JTAG-DI 0100:Reserved 0101:I2S2-DOUT0 0110:I2S2-DIN1 0111:Reserved 1000:Reserved 1001:Reserved 1110:PF-EINT1 1111:IO Disable
3:0	R/W	0xF	PF0_SELECT PF0 Select 0000:Input 0001:Output 0010:SDC0-D1 0011:JTAG-MS 0100:Reserved 0101:I2S2-DOUT1 0110:I2S2-DIN0 0111:Reserved 1000:Reserved 1001:Reserved 1110:PF-EINT0 1111:IO Disable

10.7.5.30 0x0100 PF Data Register (Default Value: 0x0000_0000)

Offset: 0x0100			Register Name: PF_DAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6:0	R/W	0	PF_DAT PF Data If the port is configured as input, the corresponding bit is the pin state. If the port is configured as output, the pin state is the same as the corresponding bit. The read bit value is the value setup by software. If the port is configured as functional pin, the undefined value will be read.

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10.7.5.31 0x0104 PF Multi_Driving Register 0 (Default Value: 0x0111_1111)

Offset: 0x0104			Register Name: PF_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:26	/	/	/
25:24	R/W	0x1	PF6_DRV PF6 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
23:22	/	/	/
21:20	R/W	0x1	PF5_DRV PF5 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
19:18	/	/	/
17:16	R/W	0x1	PF4_DRV PF4 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
15:14	/	/	/
13:12	R/W	0x1	PF3_DRV PF3 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/
9:8	R/W	0x1	PF2_DRV PF2 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PF1_DRV PF1 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/

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Offset: 0x0104			Register Name: PF_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
1:0	R/W	0x1	PF0_DRV PF0 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

10.7.5.32 0x0114 PF Pull Register 0 (Default Value: 0x0000_0000)

Offset: 0x0114			Register Name: PF_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	/	/	/
13:12	R/W	0x0	PF6_PULL PF6 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
11:10	R/W	0x0	PF5_PULL PF5 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
9:8	R/W	0x0	PF4_PULL PF4 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
7:6	R/W	0x0	PF3_PULL PF3 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
5:4	R/W	0x0	PF2_PULL PF2 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
3:2	R/W	0x0	PF1_PULL PF1 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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Offset: 0x0114			Register Name: PF_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
1:0	R/W	0x0	PF0_PULL PF0 Pull_up or down Select 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

10.7.5.33 0x0120 PG Configure Register 0 (Default Value: 0xFFFF_FFFF)

Offset: 0x0120			Register Name: PG_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0xF	PG7_SELECT PG7 Select 0000:Input 0001:Output 0010:UART1-RX 0011:TWI2-SDA 0100:RGMII-TXD3 0101: Reserved 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT7 1111:IO Disable
27:24	R/W	0xF	PG6_SELECT PG6 Select 0000:Input 0001:Output 0010:UART1-TX 0011:TWI2-SCK 0100:RGMII-TXD2 0101:PWM1 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT6 1111:IO Disable
23:20	R/W	0xF	PG5_SELECT PG5 Select 0000:Input 0001:Output 0010:SDC1-D3 0011:UART5-RX 0100:RGMII-TXD1/RMII-TXD1 0101:PWM4 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT5 1111:IO Disable

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Offset: 0x0120			Register Name: PG_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
19:16	R/W	0xF	PG4_SELECT PG4 Select 0000:Input 0001:Output 0010:SDC1-D2 0011:UART5-TX 0100:RGMII-TXD0/RMII-TXD0 0101:PWM5 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT4 1111:IO Disable
15:12	R/W	0xF	PG3_SELECT PG3 Select 0000:Input 0001:Output 0010:SDC1-D1 0011:UART3-CTS 0100:RGMII-TXCK/RMII-TXCK 0101:UART4-RX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT3 1111:IO Disable
11:8	R/W	0xF	PG2_SELECT PG2 Select 0000:Input 0001:Output 0010:SDC1-D0 0011:UART3-RTS 0100:RGMII-RXD1/RMII-RXD1 0101:UART4-TX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT2 1111:IO Disable
7:4	R/W	0xF	PG1_SELECT PG1 Select 0000:Input 0001:Output 0010:SDC1-CMD 0011:UART3-RX 0100:RGMII-RXD0/RMII-RXD0 0101:PWM6 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT1 1111:IO Disable

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Offset: 0x0120			Register Name: PG_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0xF	PG0_SELECT PG0 Select 0000:Input 0001:Output 0010:SDC1-CLK 0011:UART3-TX 0100:RGMII-RXCTRL/RMII-CRS-DV 0101:PWM7 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT0 1111:IO Disable

10.7.5.34 0x0124 PG Configure Register 1 (Default Value: 0xFFFF_FFFF)

Offset: 0x0124			Register Name: PG_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0xF	PG15_SELECT PG15 Select 0000:Input 0001:Output 0010:I2S1-DOUT0 0011:TWI2-SDA 0100:MDIO 0101:I2S1-DIN1 0110:SPI0-HOLD 0111:UART1-CTS 1000:Reserved 1001:Reserved 1110:PG-EINT15 1111:IO Disable
27:24	R/W	0xF	PG14_SELECT PG14 Select 0000:Input 0001:Output 0010:I2S1-DIN0 0011:TWI2-SCK 0100:MDC 0101:I2S1-DOUT1 0110:SPI0-WP 0111:UART1-RTS 1000:Reserved 1001:Reserved 1110:PG-EINT14 1111:IO Disable

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Offset: 0x0124			Register Name: PG_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	R/W	0xF	PG13_SELECT PG13 Select. 0000:Input 0001:Output 0010:I2S1-BCLK 0011:TWI0-SDA 0100:RGMII-CLKIN/RMII-RXER 0101:PWM2 0110:LEDC-DO 0111:UART1-RX 1000:Reserved 1001:Reserved 1110:PG-EINT13 1111:IO Disable
19:16	R/W	0xF	PG12_SELECT PG12 Select 0000:Input 0001:Output 0010:I2S1-LRCK 0011:TWI0-SCK 0100:RGMII-TXCTRL/RMII-TXEN 0101:CLK-FANOUT2 0110:PWM0 0111:UART1-TX 1000:Reserved 1001:Reserved 1110:PG-EINT12 1111:IO Disable
15:12	R/W	0xF	PG11_SELECT PG11 Select 0000:Input 0001:Output 0010:I2S1-MCLK 0011:TWI3-SDA 0100:EPHY-25M 0101:CLK-FANOUT1 0110:TCON-TRIG 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT11 1111:IO Disable
11:8	R/W	0xF	PG10_SELECT PG10 Select 0000:Input 0001:Output 0010:PWM3 0011:TWI3-SCK 0100:RGMII-RXCK 0101:CLK-FANOUT0 0110:IR-RX 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT10 1111:IO Disable

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Offset: 0x0124			Register Name: PG_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0xF	PG9_SELECT PG9 Select. 0000:Input 0001:Output 0010:UART1-CTS 0011:TWI1-SDA 0100:RGMII-RXD3 0101:UART3-RX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT9 1111:IO Disable
3:0	R/W	0xF	PG8_SELECT PG8 Select 0000:Input 0001:Output 0010:UART1-RTS 0011:TWI1-SCK 0100:RGMII-RXD2 0101:UART3-TX 0110:Reserved 0111:Reserved 1000:Reserved 1001:Reserved 1110:PG-EINT8 1111:IO Disable

10.7.5.35 0x0128 PG Configure Register 2 (Default Value: 0x0000_0FFF)

Offset: 0x0128			Register Name: PG_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:8	R/W	0xF	PG18_SELECT PG18 Select 0000:Input 0001:Output 0010:UART2-RX 0011:TWI3-SDA 0100:PWM6 0101:CLK-FANOUT1 0110:OWA-OUT 0111:UART0-RX 1000:Reserved 1001:Reserved 1110:PG-EINT18 1111:IO Disable

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Offset: 0x0128			Register Name: PG_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0xF	PG17_SELECT PG17 Select 0000:Input 0001:Output 0010:UART2-TX 0011:TWI3-SCK 0100:PWM7 0101:CLK-FANOUT0 0110:IR-TX 0111:UART0-TX 1000:Reserved 1001:Reserved 1110:PG-EINT17 1111:IO Disable
3:0	R/W	0xF	PG16_SELECT PG16 Select 0000:Input 0001:Output 0010:IR-RX 0011:TCON-TRIG 0100:PWM5 0101:CLK-FANOUT2 0110: Reserved 0111:LEDC-DO 1000:Reserved 1001:Reserved 1110:PG-EINT16 1111:IO Disable

10.7.5.36 0x0130 PG Data Register (Default Value: 0x0000_0000)

Offset: 0x0130			Register Name: PG_DAT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	/	/	/
18:0	R/W	0x0	PG_DAT If the port is configured as the input function, the corresponding bit is the pin state. If the port is configured as the output function, the pin state is the same as the corresponding bit. The read bit value is the value set up by software. If the port is configured as a functional pin, the undefined value will be read.

10.7.5.37 0x0134 PG Multi_Driving Register 0 (Default Value: 0x1111_1111)

Offset: 0x0134			Register Name: PG_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/

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Offset: 0x0134			Register Name: PG_DRV0
Bit	**Read/Write**	**Default/Hex**	**Description**
29:28	R/W	0x1	PG7_DRV PG7 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
27:26	/	/	/
25:24	R/W	0x1	PG6_DRV PG6 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
23:22	/	/	/
21:20	R/W	0x1	PG5_DRV PG5 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
19:18	/	/	/
17:16	R/W	0x1	PG4_DRV PG4 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
15:14	/	/	/
13:12	R/W	0x1	PG3_DRV PG3 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/
9:8	R/W	0x1	PG2_DRV PG2 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PG1_DRV PG1 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/

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Offset: 0x0134			Register Name: PG_DRV0
Bit	Read/Write	Default/Hex	Description
1:0	R/W	0x1	PG0_DRV PG0 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

10.7.5.38 0x0138 PG Multi_Driving Register 1 (Default Value: 0x1111_1111)

Offset: 0x0138			Register Name: PG_DRV1
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29:28	R/W	0x1	PG15_DRV PG15 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
27:26	/	/	/
25:24	R/W	0x1	PG14_DRV PG14 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
23:22	/	/	/
21:20	R/W	0x1	PG13_DRV PG13 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
19:18	/	/	/
17:16	R/W	0x1	PG12_DRV PG12 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
15:14	/	/	/
13:12	R/W	0x1	PG11_DRV PG11 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
11:10	/	/	/

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Offset: 0x0138			Register Name: PG_DRV1
Bit	**Read/Write**	**Default/Hex**	**Description**
9:8	R/W	0x1	PG10_DRV PG10 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PG9_DRV PG9 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/
1:0	R/W	0x1	PG8_DRV PG8 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

10.7.5.39 0x013C PG Multi_Driving Register 2 (Default Value: 0x0000_0111)

Offset: 0x013C			Register Name: PG_DRV2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:10	/	/	/
9:8	R/W	0x1	PG18_DRV PG18 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
7:6	/	/	/
5:4	R/W	0x1	PG17_DRV PG17 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3
3:2	/	/	/
1:0	R/W	0x1	PG16_DRV PG16 Multi_Driving Select 00: Level 0 01: Level 1 10: Level 2 11: Level 3

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10.7.5.40 0x0144 PG Pull Register 0 (Default Value: 0x0000_0000)

Offset: 0x0144			Register Name: PG_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	R/W	0x0	PG15_PULL PG15 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
29:28	R/W	0x0	PG14_PULL PG14 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
27:26	R/W	0x0	PG13_PULL PG13 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
25:24	R/W	0x0	PG12_PULL PG12 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
23:22	R/W	0x0	PG11_PULL PG11 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
21:20	R/W	0x0	PG10_PULL PG10 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
19:18	R/W	0x0	PG9_PULL PG9 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
17:16	R/W	0x0	PG8_PULL PG8 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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Offset: 0x0144			Register Name: PG_PULL0
Bit	**Read/Write**	**Default/Hex**	**Description**
15:14	R/W	0x0	PG7_PULL PG7 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
13:12	R/W	0x0	PG6_PULL PG6 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
11:10	R/W	0x0	PG5_PULL PG5 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
9:8	R/W	0x0	PG4_PULL PG4 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
7:6	R/W	0x0	PG3_PULL PG3 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
5:4	R/W	0x0	PG2_PULL PG2 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
3:2	R/W	0x0	PG1_PULL PG1 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
1:0	R/W	0x0	PG0_PULL PG0 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

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10.7.5.41 0x0148 PG Pull Register 1 (Default Value: 0x0000_0000)

Offset: 0x0148			Register Name: PG_PULL1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:6	/	/	/
5:4	R/W	0x0	PG18_PULL PG18 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
3:2	R/W	0x0	PG17_PULL PG17 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved
1:0	R/W	0x0	PG16_PULL PG16 Pull_up or down Select. 00: Pull_up/down disable 01: Pull_up 10: Pull_down 11: Reserved

10.7.5.42 0x0220 PB External Interrupt Configure Register 0 (Default Value: 0x0000_0000)

Offset: 0x0220			Register Name:PB_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	EINT7_CFG External INT7 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
27:24	R/W	0x0	EINT6_CFG External INT6 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0220			Register Name:PB_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	R/W	0x0	EINT5_CFG External INT5 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
19:16	R/W	0x0	EINT4_CFG External INT4 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
15:12	R/W	0x0	EINT3_CFG External INT3 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
11:8	R/W	0x0	EINT2_CFG External INT2 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0220			Register Name:PB_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0x0	EINT1_CFG External INT1 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
3:0	R/W	0x0	EINT0_CFG External INT0 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.43 0x0224 PB External Interrupt Configure Register 1 (Default Value: 0x0000_0000)

Offset: 0x0224			Register Name:PB_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:20	/	/	/
19:16	R/W	0x0	EINT12_CFG External INT12 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0224			Register Name:PB_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
15:12	R/W	0x0	EINT11_CFG External INT11 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
11:8	R/W	0x0	EINT10_CFG External INT10 Mode. 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
7:4	R/W	0x0	EINT9_CFG External INT9 Mode. 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
3:0	R/W	0x0	EINT8_CFG External INT8 Mode. 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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10.7.5.44 0x0230 PB External Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0230			Register Name: PB_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:13	/	/	/
12	R/W	0x0	EINT12_CTL External INT12 Enable 0: Disable 1: Enable
11	R/W	0x0	EINT11_CTL External INT11 Enable 0: Disable 1: Enable
10	R/W	0x0	EINT10_CTL External INT10 Enable 0: Disable 1: Enable
9	R/W	0x0	EINT9_CTL External INT9 Enable 0: Disable 1: Enable
8	R/W	0x0	EINT8_CTL External INT8 Enable 0: Disable 1: Enable
7	R/W	0x0	EINT7_CTL External INT7 Enable 0: Disable 1: Enable
6	R/W	0x0	EINT6_CTL External INT6 Enable 0: Disable 1: Enable
5	R/W	0x0	EINT5_CTL External INT5 Enable 0: Disable 1: Enable

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Offset: 0x0230			Register Name: PB_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W	0x0	EINT4_CTL External INT4 Enable 0: Disable 1: Enable
3	R/W	0x0	EINT3_CTL External INT3 Enable 0: Disable 1: Enable
2	R/W	0x0	EINT2_CTL External INT2 Enable 0: Disable 1: Enable
1	R/W	0x0	EINT1_CTL External INT1 Enable 0: Disable 1: Enable
0	R/W	0x0	EINT0_CTL External INT0 Enable 0: Disable 1: Enable

10.7.5.45 0x0234 PB External Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0234			Register Name: PB_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:13	/	/	/
12	R/W	0x0	EINT12_STATUS External INT12 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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Offset: 0x0234			Register Name: PB_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
11	R/W	0x0	EINT11_STATUS External INT11 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
10	R/W	0x0	EINT10_STATUS External INT10 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
9	R/W	0x0	EINT9_STATUS External INT9 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
8	R/W	0x0	EINT8_STATUS External INT8 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
7	R/W1C	0x0	EINT7_STATUS External INT7 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
6	R/W1C	0x0	EINT6_STATUS External INT6 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
5	R/W1C	0x0	EINT5_STATUS External INT5 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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Offset: 0x0234			Register Name: PB_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W1C	0x0	EINT4_STATUS External INT4 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
3	R/W1C	0x0	EINT3_STATUS External INT3 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
2	R/W1C	0x0	EINT2_STATUS External INT2 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
1	R/W	0x0	EINT1_STATUS External INT1 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
0	R/W	0x0	EINT0_STATUS External INT0 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

10.7.5.46 0x0238 PB External Interrupt Debounce Register (Default Value: 0x0000_0000)

Offset: 0x0238			Register Name: PB_EINT_DEB
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6:4	R/W	0x0	DEB_CLK_PRE_SCALE Debounce Clock Pre_scale n The selected clock source is prescaled by 2^n.
3:1	/	/	/

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Offset: 0x0238			Register Name: PB_EINT_DEB
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	PIO_INT_CLK_SELECT PIO Interrupt Clock Select 0: LOSC 32KHz 1: HOSC 24MHz

10.7.5.47 0x0240 PC External Interrupt Configure Register 0 (Default Value: 0x0000_0000)

Offset: 0x0240			Register Name:PC_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	EINT7_CFG External INT7 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
27:24	R/W	0x0	EINT6_CFG External INT6 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
23:20	R/W	0x0	EINT5_CFG External INT5 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0240			Register Name:PC_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
19:16	R/W	0x0	EINT4_CFG External INT4 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
15:12	R/W	0x0	EINT3_CFG External INT3 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
11:8	R/W	0x0	EINT2_CFG External INT2 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
7:4	R/W	0x0	EINT1_CFG External INT1 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0240			Register Name:PC_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	EINT0_CFG External INT0 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.48 0x0250 PC External Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0250			Register Name: PC_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	EINT7_CTL External INT7 Enable 0: Disable 1: Enable
6	R/W	0x0	EINT6_CTL External INT6 Enable 0: Disable 1: Enable
5	R/W	0x0	EINT5_CTL External INT5 Enable 0: Disable 1: Enable
4	R/W	0x0	EINT4_CTL External INT4 Enable 0: Disable 1: Enable
3	R/W	0x0	EINT3_CTL External INT3 Enable 0: Disable 1: Enable

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Offset: 0x0250			Register Name: PC_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	EINT2_CTL External INT2 Enable 0: Disable 1: Enable
1	R/W	0x0	EINT1_CTL External INT1 Enable 0: Disable 1: Enable
0	R/W	0x0	EINT0_CTL External INT0 Enable 0: Disable 1: Enable

10.7.5.49 0x0254 PC External Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0254			Register Name: PC_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W1C	0x0	EINT7_STATUS External INT7 Pending Bit 0: No IRQ pending 1: IRQ pending Write ‘1’ to clear
6	R/W1C	0x0	EINT6_STATUS External INT6 Pending Bit 0: No IRQ pending 1: IRQ pending Write ‘1’ to clear
5	R/W1C	0x0	EINT5_STATUS External INT5 Pending Bit 0: No IRQ pending 1: IRQ pending Write ‘1’ to clear

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Offset: 0x0254			Register Name: PC_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W1C	0x0	EINT4_STATUS External INT4 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
3	R/W1C	0x0	EINT3_STATUS External INT3 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
2	R/W1C	0x0	EINT2_STATUS External INT2 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
1	R/W	0x0	EINT1_STATUS External INT1 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
0	R/W	0x0	EINT0_STATUS External INT0 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

10.7.5.50 0x0258 PC External Interrupt Debounce Register (Default Value: 0x0000_0000)

Offset: 0x0258			Register Name: PC_EINT_DEB
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6:4	R/W	0x0	DEB_CLK_PRE_SCALE Debounce Clock Pre_scale n The selected clock source is prescaled by 2^n.
3:1	/	/	/

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Offset: 0x0258			Register Name: PC_EINT_DEB
Bit	Read/Write	Default/Hex	Description
0	R/W	0x0	PIO_INT_CLK_SELECT PIO Interrupt Clock Select 0: LOSC 32KHz 1: HOSC 24MHz

10.7.5.51 0x0260 PD External Interrupt Configure Register 0 (Default Value: 0x0000_0000)

Offset: 0x0260			Register Name:PD_EINT_CFG0
Bit	Read/Write	Default/Hex	Description
31:28	R/W	0x0	EINT7_CFG External INT7 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
27:24	R/W	0x0	EINT6_CFG External INT6 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
23:20	R/W	0x0	EINT5_CFG External INT5 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0260			Register Name:PD_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
19:16	R/W	0x0	EINT4_CFG External INT4 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
15:12	R/W	0x0	EINT3_CFG External INT3 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
11:8	R/W	0x0	EINT2_CFG External INT2 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
7:4	R/W	0x0	EINT1_CFG External INT1 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0260			Register Name:PD_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	EINT0_CFG External INT0 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.52 0x0264 PD External Interrupt Configure Register 1 (Default Value: 0x0000_0000)

Offset: 0x0264			Register Name:PD_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	EINT15_CFG External INT15 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
27:24	R/W	0x0	EINT14_CFG External INT14 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0264			Register Name:PD_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	R/W	0x0	EINT13_CFG External INT13 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
19:16	R/W	0x0	EINT12_CFG External INT12 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
15:12	R/W	0x0	EINT11_CFG External INT11 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
11:8	R/W	0x0	EINT10_CFG External INT10 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0264			Register Name:PD_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0x0	EINT9_CFG External INT9 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
3:0	R/W	0x0	EINT8_CFG External INT8 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.53 0x0268 PD External Interrupt Configure Register 2 (Default Value: 0x0000_0000)

Offset: 0x0268			Register Name:PD_EINT_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/
27:24	R/W	0x0	EINT22_CFG External INT22 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0268			Register Name:PD_EINT_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	R/W	0x0	EINT21_CFG External INT21 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
19:16	R/W	0x0	EINT20_CFG External INT20 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
15:12	R/W	0x0	EINT19_CFG External INT19 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
11:8	R/W	0x0	EINT18_CFG External INT18 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0268			Register Name:PD_EINT_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0x0	EINT17_CFG External INT17 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
3:0	R/W	0x0	EINT16_CFG External INT16 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.54 0x0270 PD External Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0270			Register Name: PD_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:23	/	/	/
22	R/W	0x0	EINT22_CTL External INT22 Enable 0: Disable 1: Enable
21	R/W	0x0	EINT21_CTL External INT21 Enable 0: Disable 1: Enable
20	R/W	0x0	EINT20_CTL External INT20 Enable 0: Disable 1: Enable

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Offset: 0x0270			Register Name: PD_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
19	R/W	0x0	EINT19_CTL External INT19 Enable 0: Disable 1: Enable
18	R/W	0x0	EINT18_CTL External INT18 Enable 0: Disable 1: Enable
17	R/W	0x0	EINT17_CTL External INT17 Enable 0: Disable 1: Enable
16	R/W	0x0	EINT16_CTL External INT16 Enable 0: Disable 1: Enable
15	R/W	0x0	EINT15_CTL External INT15 Enable 0: Disable 1: Enable
14	R/W	0x0	EINT14_CTL External INT14 Enable 0: Disable 1: Enable
13	R/W	0x0	EINT13_CTL External INT13 Enable 0: Disable 1: Enable
12	R/W	0x0	EINT12_CTL External INT12 Enable 0: Disable 1: Enable
11	R/W	0x0	EINT11_CTL External INT11 Enable 0: Disable 1: Enable

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Offset: 0x0270			Register Name: PD_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
10	R/W	0x0	EINT10_CTL External INT10 Enable 0: Disable 1: Enable
9	R/W	0x0	EINT9_CTL External INT9 Enable 0: Disable 1: Enable
8	R/W	0x0	EINT8_CTL External INT8 Enable 0: Disable 1: Enable
7	R/W	0x0	EINT7_CTL External INT7 Enable 0: Disable 1: Enable
6	R/W	0x0	EINT6_CTL External INT6 Enable 0: Disable 1: Enable
5	R/W	0x0	EINT5_CTL External INT5 Enable 0: Disable 1: Enable
4	R/W	0x0	EINT4_CTL External INT4 Enable 0: Disable 1: Enable
3	R/W	0x0	EINT3_CTL External INT3 Enable 0: Disable 1: Enable
2	R/W	0x0	EINT2_CTL External INT2 Enable 0: Disable 1: Enable

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Offset: 0x0270			Register Name: PD_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	EINT1_CTL External INT1 Enable 0: Disable 1: Enable
0	R/W	0x0	EINT0_CTL External INT0 Enable 0: Disable 1: Enable

10.7.5.55 0x0274 PD External Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0274			Register Name: PD_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:23	/	/	/
22	R/W1C	0x0	EINT22_STATUS External INT22 Pending Bit 0: No IRQ pending 1: IRQ pending Write ‘1’ to clear
21	R/W1C	0x0	EINT21_STATUS External INT21 Pending Bit 0: No IRQ pending 1: IRQ pending Write ‘1’ to clear
20	R/W1C	0x0	EINT20_STATUS External INT20 Pending Bit 0: No IRQ pending 1: IRQ pending Write ‘1’ to clear
19	R/W1C	0x0	EINT19_STATUS External INT19 Pending Bit 0: No IRQ pending 1: IRQ pending Write ‘1’ to clear

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Offset: 0x0274			Register Name: PD_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
18	R/W1C	0x0	EINT18_STATUS External INT18 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
17	R/W1C	0x0	EINT17_STATUS External INT17 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
16	R/W1C	0x0	EINT16_STATUS External INT16 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
15	R/W1C	0x0	EINT15_STATUS External INT15 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
14	R/W1C	0x0	EINT14_STATUS External INT14 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
13	R/W1C	0x0	EINT13_STATUS External INT13 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
12	R/W1C	0x0	EINT12_STATUS External INT12 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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Offset: 0x0274			Register Name: PD_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
11	R/W1C	0x0	EINT11_STATUS External INT11 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
10	R/W1C	0x0	EINT10_STATUS External INT10 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
9	R/W1C	0x0	EINT9_STATUS External INT9 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
8	R/W1C	0x0	EINT8_STATUS External INT8 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
7	R/W1C	0x0	EINT7_STATUS External INT7 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
6	R/W1C	0x0	EINT6_STATUS External INT6 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
5	R/W1C	0x0	EINT5_STATUS External INT5 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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Offset: 0x0274			Register Name: PD_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W1C	0x0	EINT4_STATUS External INT4 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
3	R/W1C	0x0	EINT3_STATUS External INT3 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
2	R/W1C	0x0	EINT2_STATUS External INT2 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
1	R/W1C	0x0	EINT1_STATUS External INT1 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
0	R/W1C	0x0	EINT0_STATUS External INT0 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

10.7.5.56 0x0278 PD External Interrupt Debounce Register (Default Value: 0x0000_0000)

Offset: 0x0278			Register Name: PD_EINT_DEB
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6:4	R/W	0x0	DEB_CLK_PRE_SCALE Debounce Clock Pre_scale n The selected clock source is prescaled by 2^n.
3:1	/	/	/

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Offset: 0x0278			Register Name: PD_EINT_DEB
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	PIO_INT_CLK_SELECT PIO Interrupt Clock Select 0: LOSC 32KHz 1: HOSC 24MHz

10.7.5.57 0x0280 PE External Interrupt Configure Register 0 (Default Value: 0x0000_0000)

Offset: 0x0280			Register Name:PE_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	EINT7_CFG External INT7 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
27:24	R/W	0x0	EINT6_CFG External INT6 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
23:20	R/W	0x0	EINT5_CFG External INT5 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0280			Register Name:PE_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
19:16	R/W	0x0	EINT4_CFG External INT4 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
15:12	R/W	0x0	EINT3_CFG External INT3 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
11:8	R/W	0x0	EINT2_CFG External INT2 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
7:4	R/W	0x0	EINT1_CFG External INT1 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0280			Register Name:PE_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	EINT0_CFG External INT0 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.58 0x0284 PE External Interrupt Configure Register 1 (Default Value: 0x0000_0000)

Offset: 0x0284			Register Name: PE_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	EINT15_CFG External INT15 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
27:24	R/W	0x0	EINT14_CFG External INT14 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0284			Register Name: PE_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	R/W	0x0	EINT13_CFG External INT13 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
19:16	R/W	0x0	EINT12_CFG External INT12 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
15:12	R/W	0x0	EINT11_CFG External INT11 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
11:8	R/W	0x0	EINT10_CFG External INT10 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0284			Register Name: PE_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0x0	EINT9_CFG External INT9 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
3:0	R/W	0x0	EINT8_CFG External INT8 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.59 0x0288 PE External Interrupt Configure Register 2 (Default Value: 0x0000_0000)

Offset: 0x0288			Register Name: PE_EINT_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:4	R/W	0x0	EINT17_CFG External INT17 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x0288			Register Name: PE_EINT_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	EINT16_CFG External INT16 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.60 0x0290 PE External Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0290			Register Name: PE_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/W	0x0	EINT17_CTL External INT17 Enable 0: Disable 1: Enable
16	R/W	0x0	EINT16_CTL External INT16 Enable 0: Disable 1: Enable
15	R/W	0x0	EINT15_CTL External INT15 Enable 0: Disable 1: Enable
14	R/W	0x0	EINT14_CTL External INT14 Enable 0: Disable 1: Enable
13	R/W	0x0	EINT13_CTL External INT13 Enable 0: Disable 1: Enable

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Offset: 0x0290			Register Name: PE_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
12	R/W	0x0	EINT12_CTL External INT12 Enable 0: Disable 1: Enable
11	R/W	0x0	EINT11_CTL External INT11 Enable 0: Disable 1: Enable
10	R/W	0x0	EINT10_CTL External INT10 Enable 0: Disable 1: Enable
9	R/W	0x0	EINT9_CTL External INT9 Enable 0: Disable 1: Enable
8	R/W	0x0	EINT8_CTL External INT8 Enable 0: Disable 1: Enable
7	R/W	0x0	EINT7_CTL External INT7 Enable 0: Disable 1: Enable
6	R/W	0x0	EINT6_CTL External INT6 Enable 0: Disable 1: Enable
5	R/W	0x0	EINT5_CTL External INT5 Enable 0: Disable 1: Enable
4	R/W	0x0	EINT4_CTL External INT4 Enable 0: Disable 1: Enable

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Offset: 0x0290			Register Name: PE_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W	0x0	EINT3_CTL External INT3 Enable 0: Disable 1: Enable
2	R/W	0x0	EINT2_CTL External INT2 Enable 0: Disable 1: Enable
1	R/W	0x0	EINT1_CTL External INT1 Enable 0: Disable 1: Enable
0	R/W	0x0	EINT0_CTL External INT0 Enable 0: Disable 1: Enable

10.7.5.61 0x0294 PE External Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0294			Register Name: PE_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/W	0x0	EINT17_STATUS External INT17 Pending Bit 0: No IRQ pending 1: IRQ pending Write ‘1’ to clear
16	R/W	0x0	EINT16_STATUS External INT16 Pending Bit 0: No IRQ pending 1: IRQ pending Write ‘1’ to clear

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Offset: 0x0294			Register Name: PE_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
15	R/W	0x0	EINT15_STATUS External INT15 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
14	R/W	0x0	EINT14_STATUS External INT14 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
13	R/W1C	0x0	EINT13_STATUS External INT13 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
12	R/W1C	0x0	EINT12_STATUS External INT12 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
11	R/W1C	0x0	EINT11_STATUS External INT11 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
10	R/W1C	0x0	EINT10_STATUS External INT10 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
9	R/W1C	0x0	EINT9_STATUS External INT9 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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Offset: 0x0294			Register Name: PE_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
8	R/W1C	0x0	EINT8_STATUS External INT8 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
7	R/W1C	0x0	EINT7_STATUS External INT7 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
6	R/W1C	0x0	EINT6_STATUS External INT6 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
5	R/W1C	0x0	EINT5_STATUS External INT5 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
4	R/W1C	0x0	EINT4_STATUS External INT4 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
3	R/W1C	0x0	EINT3_STATUS External INT3 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
2	R/W1C	0x0	EINT2_STATUS External INT2 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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Offset: 0x0294			Register Name: PE_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W1C	0x0	EINT1_STATUS External INT1 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
0	R/W1C	0x0	EINT0_STATUS External INT0 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

10.7.5.62 0x0298 PE External Interrupt Debounce Register (Default Value: 0x0000_0000)

Offset: 0x0298			Register Name: PE_EINT_DEB
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6:4	R/W	0x0	DEB_CLK_PRE_SCALE Debounce Clock Pre_scale n The selected clock source is prescaled by 2^n.
3:1	/	/	/
0	R/W	0x0	PIO_INT_CLK_SELECT PIO Interrupt Clock Select 0: LOSC 32KHz 1: HOSC 24MHz

10.7.5.63 0x02A0 PF External Interrupt Configure Register 0 (Default Value: 0x0000_0000)

Offset: 0x02A0			Register Name: PF_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/

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Offset: 0x02A0			Register Name: PF_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
27:24	R/W	0x0	EINT6_CFG External INT6 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
23:20	R/W	0x0	EINT5_CFG External INT5 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
19:16	R/W	0x0	EINT4_CFG External INT4 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
15:12	R/W	0x0	EINT3_CFG External INT3 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x02A0			Register Name: PF_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
11:8	R/W	0x0	EINT2_CFG External INT2 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
7:4	R/W	0x0	EINT1_CFG External INT1 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
3:0	R/W	0x0	EINT0_CFG External INT0 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.64 0x02B0 PF External Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x02B0			Register Name: PF_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6	R/W	0x0	EINT6_CTL External INT6 Enable 0: Disable 1: Enable

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Offset: 0x02B0			Register Name: PF_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R/W	0x0	EINT5_CTL External INT5 Enable 0: Disable 1: Enable
4	R/W	0x0	EINT4_CTL External INT4 Enable 0: Disable 1: Enable
3	R/W	0x0	EINT3_CTL External INT3 Enable 0: Disable 1: Enable
2	R/W	0x0	EINT2_CTL External INT2 Enable 0: Disable 1: Enable
1	R/W	0x0	EINT1_CTL External INT1 Enable 0: Disable 1: Enable
0	R/W	0x0	EINT0_CTL External INT0 Enable 0: Disable 1: Enable

10.7.5.65 0x02B4 PF External Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x02B4			Register Name: PF_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6	R/W1C	0x0	EINT6_STATUS External INT6 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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Offset: 0x02B4			Register Name: PF_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R/W1C	0x0	EINT5_STATUS External INT5 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
4	R/W1C	0x0	EINT4_STATUS External INT4 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
3	R/W1C	0x0	EINT3_STATUS External INT3 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
2	R/W1C	0x0	EINT2_STATUS External INT2 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
1	R/W1C	0x0	EINT1_STATUS External INT1 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
0	R/W1C	0x0	EINT0_STATUS External INT0 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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10.7.5.66 0x02B8 PF External Interrupt Debounce Register (Default Value: 0x0000_0000)

Offset: 0x02B8			Register Name: PF_EINT_DEB
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6:4	R/W	0x0	DEB_CLK_PRE_SCALE Debounce Clock Pre_scale n The selected clock source is prescaled by 2^n.
3:1	/	/	/
0	R/W	0x0	PIO_INT_CLK_SELECT PIO Interrupt Clock Select 0: LOSC 32KHz 1: HOSC 24MHz

10.7.5.67 0x02C0 PG External Interrupt Configure Register 0 (Default Value: 0x0000_0000)

Offset: 0x02C0			Register Name:PG_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	EINT7_CFG External INT7 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
27:24	R/W	0x0	EINT6_CFG External INT6 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x02C0			Register Name:PG_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	R/W	0x0	EINT5_CFG External INT5 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
19:16	R/W	0x0	EINT4_CFG External INT4 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
15:12	R/W	0x0	EINT3_CFG External INT3 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
11:8	R/W	0x0	EINT2_CFG External INT2 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x02C0			Register Name:PG_EINT_CFG0
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W	0x0	EINT1_CFG External INT1 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
3:0	R/W	0x0	EINT0_CFG External INT0 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.68 0x02C4 PG External Interrupt Configure Register 1 (Default Value: 0x0000_0000)

Offset: 0x02C4			Register Name: PG_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x0	EINT15_CFG External INT15 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x02C4			Register Name: PG_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
27:24	R/W	0x0	EINT14_CFG External INT14 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
23:20	R/W	0x0	EINT13_CFG External INT13 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
19:16	R/W	0x0	EINT12_CFG External INT12 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
15:12	R/W	0x0	EINT11_CFG External INT11 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

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Offset: 0x02C4			Register Name: PG_EINT_CFG1
Bit	**Read/Write**	**Default/Hex**	**Description**
11:8	R/W	0x0	EINT10_CFG External INT10 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
7:4	R/W	0x0	EINT9_CFG External INT9 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
3:0	R/W	0x0	EINT8_CFG External INT8 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.69 0x02C8 PG External Interrupt Configure Register 2 (Default Value: 0x0000_0000)

Offset: 0x02C8			Register Name: PG_EINT_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/

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Offset: 0x02C8			Register Name: PG_EINT_CFG2
Bit	**Read/Write**	**Default/Hex**	**Description**
11:8	R/W	0x0	EINT18_CFG External INT18 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
7:4	R/W	0x0	EINT17_CFG External INT17 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved
3:0	R/W	0x0	EINT16_CFG External INT16 Mode 0x0: Positive Edge 0x1: Negative Edge 0x2: High Level 0x3: Low Level 0x4: Double Edge (Positive/Negative) Others: Reserved

10.7.5.70 0x02D0 PG External Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x02D0			Register Name: PG_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	/	/	/
18	R/W	0x0	EINT18_CTL External INT18 Enable 0: Disable 1: Enable

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Offset: 0x02D0			Register Name: PG_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
17	R/W	0x0	EINT17_CTL External INT17 Enable 0: Disable 1: Enable
16	R/W	0x0	EINT16_CTL External INT16 Enable 0: Disable 1: Enable
15	R/W	0x0	EINT15_CTL External INT15 Enable 0: Disable 1: Enable
14	R/W	0x0	EINT14_CTL External INT14 Enable 0: Disable 1: Enable
13	R/W	0x0	EINT13_CTL External INT13 Enable 0: Disable 1: Enable
12	R/W	0x0	EINT12_CTL External INT12 Enable 0: Disable 1: Enable
11	R/W	0x0	EINT11_CTL External INT11 Enable 0: Disable 1: Enable
10	R/W	0x0	EINT10_CTL External INT10 Enable 0: Disable 1: Enable
9	R/W	0x0	EINT9_CTL External INT9 Enable 0: Disable 1: Enable

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Offset: 0x02D0			Register Name: PG_EINT_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
8	R/W	0x0	EINT8_CTL External INT8 Enable 0: Disable 1: Enable
7	R/W	0x0	EINT7_CTL External INT7 Enable 0: Disable 1: Enable
6	R/W	0x0	EINT6_CTL External INT6 Enable 0: Disable 1: Enable
5	R/W	0x0	EINT5_CTL External INT5 Enable 0: Disable 1: Enable
4	R/W	0x0	EINT4_CTL External INT4 Enable 0: Disable 1: Enable
3	R/W	0x0	EINT3_CTL External INT3 Enable 0: Disable 1: Enable
2	R/W	0x0	EINT2_CTL External INT2 Enable 0: Disable 1: Enable
1	R/W	0x0	EINT1_CTL External INT1 Enable 0: Disable 1: Enable
0	R/W	0x0	EINT0_CTL External INT0 Enable 0: Disable 1: Enable

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10.7.5.71 0x02D4 PG External Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x02D4			Register Name: PG_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	/	/	/
18	R/W	0x0	EINT18_STATUS External INT18 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
17	R/W	0x0	EINT17_STATUS External INT17 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
16	R/W	0x0	EINT16_STATUS External INT16 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
15	R/W1C	0x0	EINT15_STATUS External INT15 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
14	R/W1C	0x0	EINT14_STATUS External INT14 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
13	R/W1C	0x0	EINT13_STATUS External INT13 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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Offset: 0x02D4			Register Name: PG_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
12	R/W1C	0x0	EINT12_STATUS External INT12 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
11	R/W1C	0x0	EINT11_STATUS External INT11 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
10	R/W1C	0x0	EINT10_STATUS External INT10 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
9	R/W1C	0x0	EINT9_STATUS External INT9 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
8	R/W1C	0x0	EINT8_STATUS External INT8 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
7	R/W1C	0x0	EINT7_STATUS External INT7 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
6	R/W1C	0x0	EINT6_STATUS External INT6 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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Offset: 0x02D4			Register Name: PG_EINT_STATUS
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R/W1C	0x0	EINT5_STATUS External INT5 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
4	R/W1C	0x0	EINT4_STATUS External INT4 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
3	R/W1C	0x0	EINT3_STATUS External INT3 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
2	R/W1C	0x0	EINT2_STATUS External INT2 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
1	R/W1C	0x0	EINT1_STATUS External INT1 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear
0	R/W1C	0x0	EINT0_STATUS External INT0 Pending Bit 0: No IRQ pending 1: IRQ pending Write '1' to clear

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10.7.5.72 0x02D8 PG External Interrupt Debounce Register (Default Value: 0x0000_0000)

Offset: 0x02D8			Register Name: PG_EINT_DEB
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	/	/	/
6:4	R/W	0x0	DEB_CLK_PRE_SCALE Debounce Clock Pre_scale n The selected clock source is prescaled by 2^n.
3:1	/	/	/
0	R/W	0x0	PIO_INT_CLK_SELECT PIO Interrupt Clock Select 0: LOSC 32KHz 1: HOSC 24MHz

10.7.5.73 0x0340 PIO Group Withstand Voltage Mode Select Register (Default Value: 0x0000_0000)

When the power domain of GPIO is larger than 1.8 V, the withstand voltage is set to 3.3 V mode, the corresponding value in the 0x0340 register is set to 0.

When the power domain of GPIO is 1.8 V, the withstand voltage is set to 1.8 V mode, the corresponding value in the 0x0340 register is set to 1.

Offset: 0x0340			Register Name: PIO_POW_MOD_SEL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:13	/	/	/
12	R/W	0x0	VCCIO_PWR_MOD_SEL VCC_IO POWER MODE Select 0: 3.3 V 1: 1.8 V
11:7	/	/	/
6	R/W	0x0	PG_PWR_MOD_SEL PG_POWER MODE Select 0: 3.3 V 1: 1.8 V If PG_Port Power Source selects VCC_IO, this bit is invalid.

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Offset: 0x0340			Register Name: PIO_POW_MOD_SEL
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R/W	0x0	PF_PWR_MOD_SEL PF_POWER MODE Select 0: 3.3 V 1: 1.8 V If PF_Port Power Source selects VCC_IO, this bit is invalid.
4	R/W	0x0	PE_PWR_MOD_SEL PE_POWER MODE Select 0: 3.3 V 1: 1.8 V If PE_Port Power Source selects VCC_IO, this bit is invalid.
3	R/W	0x0	PD_PWR_MOD_SEL PD_POWER MODE Select 0: 3.3 V 1: 1.8 V If PD_Port Power Source selects VCC_IO, this bit is invalid.
2	R/W	0x0	PC_PWR_MOD_SEL PC_POWER MODE Select 0: 3.3 V 1: 1.8 V If PC_Port Power Source selects VCC_IO, this bit is invalid.
1:0	/	/	/

10.7.5.74 0x0344 PIO Group Withstand Voltage Mode Select Control Register (Default Value: 0x0000_0000)

For 1.8 V and 3.3 V power, the withstand function is enabled by default, the corresponding bit in the 0x0344 register is set to 0.

For 2.5 V power, the withstand function is disabled, the corresponding bit in the 0x0344 register is set to 1, and the corresponding withstand voltage in the 0x0340 register needs to be set to 3.3 V.

Offset: 0x0344			Register Name: PIO_POW_MS_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:13	/	/	/
12	R/W	0x0	VCCIO_WS_VOL_MOD_SEL VCC_IO Withstand Voltage Mode Select Control 0: Enable 1: Disable

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Offset: 0x0344			Register Name: PIO_POW_MS_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
11:7	/	/	/
6	R/W	0x0	VCC_PG_WS_VOL_MOD_SEL VCC_PG Withstand Voltage Mode Select Control 0: Enable 1: Disable
5	R/W	0x0	VCC_PF_WS_VOL_MOD_SEL VCC_PF Withstand Voltage Mode Select Control 0: Enable 1: Disable
4	R/W	0x0	VCC_PE_WS_VOL_MOD_SEL VCC_PE Withstand Voltage Mode Select Control 0: Enable 1: Disable
3	R/W	0x0	VCC_PD_WS_VOL_MOD_SEL VCC_PD Withstand Voltage Mode Select Control 0: Enable 1: Disable
2	R/W	0x0	VCC_PC_WS_VOL_MOD_SEL VCC_PC Withstand Voltage Mode Select Control 0: Enable 1: Disable
1:0	/	/	/

10.7.5.75 0x0348 PIO Group Power Value Register (Default Value: 0x0000_0000)

When the reading value of the 0x0348 register is 0, it indicates that the IO power voltage is greater than 2.5 V.
When the reading value of the 0x0348 register is 1, it indicates that the IO power voltage is less than 2.0 V.

Offset: 0x0348			Register Name: PIO_POW_VAL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:17	/	/	/
16	R	0x0	VCCIO_PWR_VAL VCC_IO Power Value
15:7	/	/	/

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Offset: 0x0348			Register Name: PIO_POW_VAL
Bit	**Read/Write**	**Default/Hex**	**Description**
6	R	0x0	PG_PWR_VAL PG_Port Power Value If PG_Port power source selects VCC_IO, this bit is invalid.
5	R	0x0	PF_PWR_VAL PF_Port Power Value If PF_Port power source selects VCC_IO, this bit is invalid.
4	R	0x0	PE_PWR_VAL PE_Port Power Value If PE_Port power source selects VCC_IO, this bit is invalid.
3	R	0x0	PD_PWR_VAL PD_Port Power Value If PD_Port power source selects VCC_IO, this bit is invalid.
2	R	0x0	PC_PWR_VAL PC_Port Power Value If PC_Port power source selects VCC_IO, this bit is invalid.
1:0	/	/	/

10.7.5.76 0x0350 PIO Group Power Voltage Select Control Register (Default Value: 0x0000_0001)

Offset: 0x0350			Register Name: PIO_POW_VOL_SEL_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x1	VCC-PF Power Voltage Select Control 0: 1.8 V 1: 3.3 V

10.7.5.77 0x0404 PB Secure Register (Default Value: 0x0000_0000)

Offset: 0x0404			Register Name: PB_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:13	R/W	0x0	Reserved

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Offset: 0x0404			Register Name: PB_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
12	R/W	0x0	PORT12_SEC_SEL Port12 secure select 0: Not secure 1: Secure
11	R/W	0x0	PORT11_SEC_SEL Port11 secure select 0: Not secure 1: Secure
10	R/W	0x0	PORT10_SEC_SEL Port10 secure select 0: Not secure 1: Secure
9	R/W	0x0	PORT9_SEC_SEL Port9 secure select 0: Not secure 1: Secure
8	R/W	0x0	PORT8_SEC_SEL Port8 secure select 0: Not secure 1: Secure
7	R/W	0x0	PORT7_SEC_SEL Port7 secure select 0: Not secure 1: Secure
6	R/W	0x0	PORT6_SEC_SEL Port6 secure select 0: Not secure 1: Secure
5	R/W	0x0	PORT5_SEC_SEL Port5 secure select 0: Not secure 1: Secure
4	R/W	0x0	PORT4_SEC_SEL Port4 secure select 0: Not secure 1: Secure

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Offset: 0x0404			Register Name: PB_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W	0x0	PORT3_SEC_SEL Port3 secure select 0: Not secure 1: Secure
2	R/W	0x0	PORT2_SEC_SEL Port2 secure select 0: Not secure 1: Secure
1	R/W	0x0	PORT1_SEC_SEL Port1 secure select 0: Not secure 1: Secure
0	R/W	0x0	PORT0_SEC_SEL Port0 secure select 0: Not secure 1: Secure

10.7.5.78 0x0408 PC Secure Register (Default Value: 0x0000_0000)

Offset: 0x0408			Register Name: PC_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	PORT7_SEC_SEL Port7 secure select 0: Not secure 1: Secure
6	R/W	0x0	PORT6_SEC_SEL Port6 secure select 0: Not secure 1: Secure
5	R/W	0x0	PORT5_SEC_SEL Port5 secure select 0: Not secure 1: Secure

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Offset: 0x0408			Register Name: PC_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W	0x0	PORT4_SEC_SEL Port4 secure select 0: Not secure 1: Secure
3	R/W	0x0	PORT3_SEC_SEL Port3 secure select 0: Not secure 1: Secure
2	R/W	0x0	PORT2_SEC_SEL Port2 secure select 0: Not secure 1: Secure
1	R/W	0x0	PORT1_SEC_SEL Port1 secure select 0: Not secure 1: Secure
0	R/W	0x0	PORT0_SEC_SEL Port0 secure select 0: Not secure 1: Secure

10.7.5.79 0x040C PD Secure Register (Default Value: 0x0000_0000)

Offset: 0x040C			Register Name: PD_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:23	R/W	0x0	Reserved
22	R/W	0x0	PORT22_SEC_SEL Port22 secure select 0: Not secure 1: Secure
21	R/W	0x0	PORT21_SEC_SEL Port21 secure select 0: Not secure 1: Secure

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Offset: 0x040C			Register Name: PD_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
20	R/W	0x0	PORT20_SEC_SEL Port20 secure select 0: Not secure 1: Secure
19	R/W	0x0	PORT19_SEC_SEL Port19 secure select 0: Not secure 1: Secure
18	R/W	0x0	PORT18_SEC_SEL Port18 secure select 0: Not secure 1: Secure
17	R/W	0x0	PORT17_SEC_SEL Port17 secure select 0: Not secure 1: Secure
16	R/W	0x0	PORT16_SEC_SEL Port16 secure select 0: Not secure 1: Secure
15	R/W	0x0	PORT15_SEC_SEL Port15 secure select 0: Not secure 1: Secure
14	R/W	0x0	PORT14_SEC_SEL Port14 secure select 0: Not secure 1: Secure
13	R/W	0x0	PORT13_SEC_SEL Port13 secure select 0: Not secure 1: Secure
12	R/W	0x0	PORT12_SEC_SEL Port12 secure select 0: Not secure 1: Secure

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Offset: 0x040C			Register Name: PD_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
11	R/W	0x0	PORT11_SEC_SEL Port11 secure select 0: Not secure 1: Secure
10	R/W	0x0	PORT10_SEC_SEL Port10 secure select 0: Not secure 1: Secure
9	R/W	0x0	PORT9_SEC_SEL Port9 secure select 0: Not secure 1: Secure
8	R/W	0x0	PORT8_SEC_SEL Port8 secure select 0: Not secure 1: Secure
7	R/W	0x0	PORT7_SEC_SEL Port7 secure select 0: Not secure 1: Secure
6	R/W	0x0	PORT6_SEC_SEL Port6 secure select. 0: Not secure 1: Secure
5	R/W	0x0	PORT5_SEC_SEL Port5 secure select 0: Not secure 1: Secure
4	R/W	0x0	PORT4_SEC_SEL Port4 secure select 0: Not secure 1: Secure
3	R/W	0x0	PORT3_SEC_SEL Port3 secure select 0: Not secure 1: Secure

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Offset: 0x040C			Register Name: PD_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	PORT2_SEC_SEL Port2 secure select 0: Not secure 1: Secure
1	R/W	0x0	PORT1_SEC_SEL Port1 secure select 0: Not secure 1: Secure
0	R/W	0x0	PORT0_SEC_SEL Port0 secure select 0: Not secure 1: Secure

10.7.5.80 0x0410 PE Secure Register (Default Value: 0x0000_0000)

Offset: 0x0410			Register Name: PE_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	R/W	0x0	Reserved
17	R/W	0x0	PORT17_SEC_SEL Port17 secure select 0: Not secure 1: Secure
16	R/W	0x0	PORT16_SEC_SEL Port16 secure select 0: Not secure 1: Secure
15	R/W	0x0	PORT15_SEC_SEL Port15 secure select 0: Not secure 1: Secure
14	R/W	0x0	PORT14_SEC_SEL Port14 secure select 0: Not secure 1: Secure

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Offset: 0x0410			Register Name: PE_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
13	R/W	0x0	PORT13_SEC_SEL Port13 secure select 0: Not secure 1: Secure
12	R/W	0x0	PORT12_SEC_SEL Port12 secure select 0: Not secure 1: Secure
11	R/W	0x0	PORT11_SEC_SEL Port11 secure select 0: Not secure 1: Secure
10	R/W	0x0	PORT10_SEC_SEL Port10 secure select 0: Not secure 1: Secure
9	R/W	0x0	PORT9_SEC_SEL Port9 secure select 0: Not secure 1: Secure
8	R/W	0x0	PORT8_SEC_SEL Port8 secure select 0: Not secure 1: Secure
7	R/W	0x0	PORT7_SEC_SEL Port7 secure select 0: Not secure 1: Secure
6	R/W	0x0	PORT6_SEC_SEL Port6 secure select. 0: Not secure 1: Secure
5	R/W	0x0	PORT5_SEC_SEL Port5 secure select 0: Not secure 1: Secure

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Offset: 0x0410			Register Name: PE_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W	0x0	PORT4_SEC_SEL Port4 secure select 0: Not secure 1: Secure
3	R/W	0x0	PORT3_SEC_SEL Port3 secure select 0: Not secure 1: Secure
2	R/W	0x0	PORT2_SEC_SEL Port2 secure select 0: Not secure 1: Secure
1	R/W	0x0	PORT1_SEC_SEL Port1 secure select 0: Not secure 1: Secure
0	R/W	0x0	PORT0_SEC_SEL Port0 secure select 0: Not secure 1: Secure

10.7.5.81 0x0414 PF Secure Register (Default Value: 0x0000_0000)

Offset: 0x0414			Register Name: PF_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:7	R/W	0x0	Reserved
6	R/W	0x0	PORT6_SEC_SEL Port6 secure select 0: Not secure 1: Secure
5	R/W	0x0	PORT5_SEC_SEL Port5 secure select 0: Not secure 1: Secure

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Offset: 0x0414			Register Name: PF_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W	0x0	PORT4_SEC_SEL Port4 secure select 0: Not secure 1: Secure
3	R/W	0x0	PORT3_SEC_SEL Port3 secure select 0: Not secure 1: Secure
2	R/W	0x0	PORT2_SEC_SEL Port2 secure select 0: Not secure 1: Secure
1	R/W	0x0	PORT1_SEC_SEL Port1 secure select 0: Not secure 1: Secure
0	R/W	0x0	PORT0_SEC_SEL Port0 secure select 0: Not secure 1: Secure

10.7.5.82 0x0418 PG Secure Register (Default Value: 0x0000_0000)

Offset: 0x0418			Register Name: PG_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	R/W	0x0	Reserved
18	R/W	0x0	PORT18_SEC_SEL Port18 secure select 0: Not secure 1: Secure
17	R/W	0x0	PORT17_SEC_SEL Port17 secure select 0: Not secure 1: Secure

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Offset: 0x0418			Register Name: PG_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
16	R/W	0x0	PORT16_SEC_SEL Port16 secure select 0: Not secure 1: Secure
15	R/W	0x0	PORT15_SEC_SEL Port15 secure select 0: Not secure 1: Secure
14	R/W	0x0	PORT14_SEC_SEL Port14 secure select 0: Not secure 1: Secure
13	R/W	0x0	PORT13_SEC_SEL Port13 secure select 0: Not secure 1: Secure
12	R/W	0x0	PORT12_SEC_SEL Port12 secure select 0: Not secure 1: Secure
11	R/W	0x0	PORT11_SEC_SEL Port11 secure select 0: Not secure 1: Secure
10	R/W	0x0	PORT10_SEC_SEL Port10 secure select 0: Not secure 1: Secure
9	R/W	0x0	PORT9_SEC_SEL Port9 secure select 0: Not secure 1: Secure
8	R/W	0x0	PORT8_SEC_SEL Port8 secure select 0: Not secure 1: Secure

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Offset: 0x0418			Register Name: PG_SECURE
Bit	**Read/Write**	**Default/Hex**	**Description**
7	R/W	0x0	PORT7_SEC_SEL Port7 secure select 0: Not secure 1: Secure
6	R/W	0x0	PORT6_SEC_SEL Port6 secure select. 0: Not secure 1: Secure
5	R/W	0x0	PORT5_SEC_SEL Port5 secure select 0: Not secure 1: Secure
4	R/W	0x0	PORT4_SEC_SEL Port4 secure select 0: Not secure 1: Secure
3	R/W	0x0	PORT3_SEC_SEL Port3 secure select 0: Not secure 1: Secure
2	R/W	0x0	PORT2_SEC_SEL Port2 secure select 0: Not secure 1: Secure
1	R/W	0x0	PORT1_SEC_SEL Port1 secure select 0: Not secure 1: Secure
0	R/W	0x0	PORT0_SEC_SEL Port0 secure select 0: Not secure 1: Secure

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10.8 GPADC

10.8.1 Overview

The General Purpose ADC (GPADC) can convert the external signal into a certain proportion of digital value, to realize the measurement of analog signal, which can be applied to power detection and key detection. This ADC is a type of successive approximation register (SAR) A/D converter.

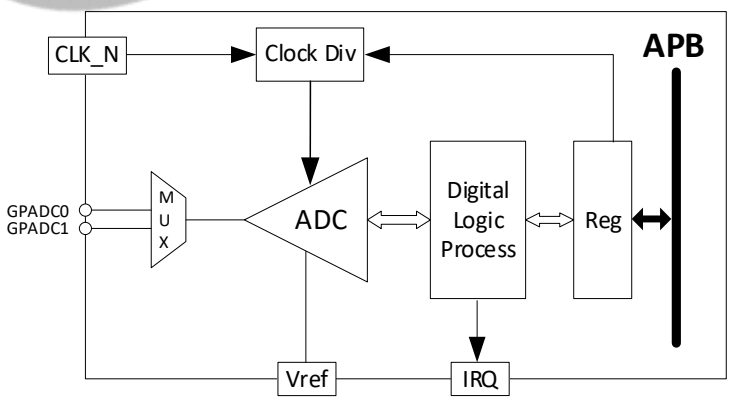
The GPADC has the following features:

- 2-ch SAR ADC
- 12-bit sampling resolution and 8-bit precision
- 64 FIFO depth of data register
- Power reference voltage: AVCC, and analog input voltage range: 0 to AVCC
- Maximum sampling frequency: 1 MHz
- Supports data compare and interrupt
- Supports three operation modes
  - Single conversion mode
  - Continuous conversion mode
  - Burst conversion mode

10.8.2 Block Diagram

Figure 10-70 shows the block diagram of the GPADC.

Figure 10-70 GPADC Block Diagram



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10.8.3 Functional Description

10.8.3.1 External Signals

The following table describes the external signals of the GPADC.

Table 10-28 GPADC External Signals

Signal	Description	Type
GPADC0	ADC Input Channel0	AI
GPADC1	ADC Input Channel1	AI

10.8.3.2 Clock Sources

The GPADC has one clock source. The following table describes the clock source for GPADC. Users can see section 3.3 "CCU" for clock setting, configuration, and gating information.

Table 10-29 GPADC Clock Sources

Clock Sources	Description
HOSC	24 MHz

10.8.3.3 GPADC Work Mode

- **Single conversion mode**

The GPADC completes one conversion in a specified channel, the converted data is updated at the data register of the corresponding channel.

- **Continuous conversion mode**

The GPADC has continuous conversion in a specified channel until the software stops, the converted data is updated at the data register of the corresponding channel.

- **Burst conversion mode**

The GPADC samples and converts in a specified channel, and sequentially stores the results in FIFO.

10.8.3.4 Clock and Timing Requirements

CLK_IN = 24 MHz

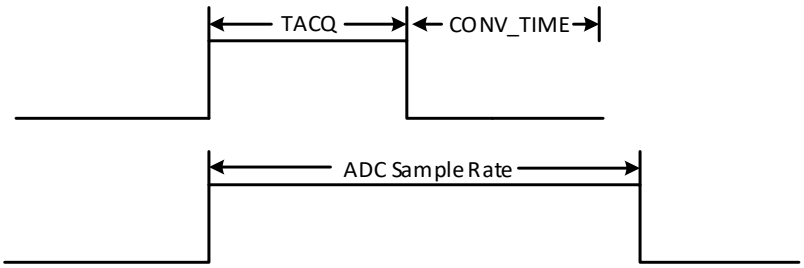
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CONV_TIME(Conversion Time) = 1/(24MHz/14Cycles) =0.583 (us)

TACQ > 10RC (R is output impedance of ADC sample circuit, C = 6.4 pF)

ADC Sample Frequency > TACQ+CONV_TIME

Figure 10-71 GPADC Clock and Timing Requirement



10.8.3.5 GPADC Calculate Formula

GPADC calculate formula: GPADC_DATA = Vin/V_{REF}*4095

Where:

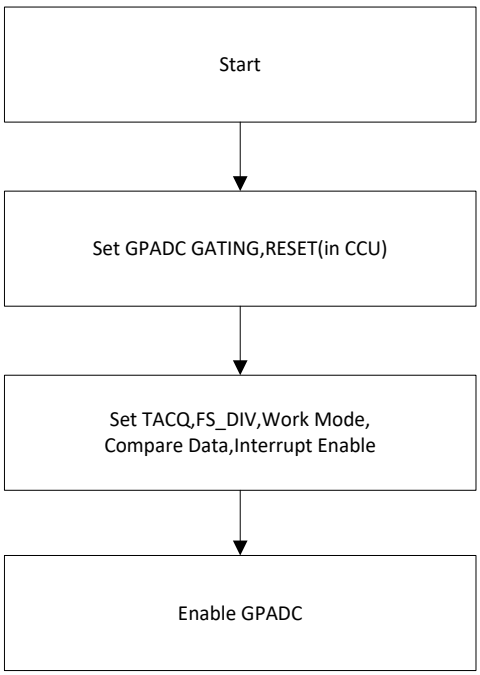
V_{REF} = 1.8 V

10.8.4 Programming Guidelines

The GPADC initial process is as follows.

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Figure 10-72 GPADC Initial Process



(1).Query Mode

Step 1 Write 0x1 to the bit[16] of **GPADC_BGR_REG** to dessert reset.

Step 2 Write 0x1 to the bit[0] of **GPADC_BGR_REG** to enable the GPADC clock.

Step 3 Write 0x2F to the bit[15:0] of **GP_SR_CON** to set *the acquiring time of ADC.*

Step 4 Write 0x1DF to the bit[31:16] of **GP_SR_CON** to set the *ADC sample frequency divider*.

Step 5 Write 0x2 to the bit[19:18] of **GP_CTRL** to set the *continuous conversion mode*.

Step 6 Write 0x1 to the bit[0] of **GP_CS_EN** to enable the *analog input channel*.

Step 7 Write 0x1 to the bit[16] of **GP_CTRL** to enable the ADC function.

Step 8 Read the bit[0] of **GP_DATA_INTS**, if the bit is 1, then data conversion is complete.

Step 9 Read the bit[11:0] of **GP_CH0_DATA**, and calculate voltage value based on GPADC formula.

(2).Interrupt Mode

Step 1 Write 0x1 to the bit[16] of **GPADC_BGR_REG** to dessert reset.

Step 2 Write 0x1 to the bit[0] of **GPADC_BGR_REG** to enable the GPADC clock.

Step 3 Write 0x2F to the bit[15:0] of **GP_SR_CON** to set *the acquiring time of ADC.*

Step 4 Write 0x1DF to the bit[31:16] of **GP_SR_CON** to set the *ADC sample frequency divider*.

Step 5 Write 0x2 to the bit[19:18] of **GP_CTRL** to *set* the *continuous conversion mode*.

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Step 6 Write 0x1 to the bit[0] of **GP_CS_EN** to enable the *analog input channel*.

Step 7 Write 0x1 to the bit[0] of **GP_DATA_INTC** to enable the GPADC data interrupt.

Step 8 Set the GIC module based on the IRQ 89.

Step 9 Put interrupt handler address into interrupt vector table based on the IRQ 148.

Step 10 Write 0x1 to the bit16 of **GP_CTRL** to enable the ADC function.

Step 11 Read the bit[11:0] of **GP_CH0_DATA** from the interrupt handler, calculate voltage value based on GPADC formula.

10.8.5 Register List

Module Name	Base Address
GPADC	0x02009000

Register Name	Offset	Description
GP_SR_CON	0x0000	GPADC Sample Rate Configure Register
GP_CTRL	0x0004	GPADC Control Register
GP_CS_EN	0x0008	GPADC Compare and Select Enable Register
GP_FIFO_INTC	0x000C	GPADC FIFO Interrupt Control Register
GP_FIFO_INTS	0x0010	GPADC FIFO Interrupt Status Register
GP_FIFO_DATA	0x0014	GPADC FIFO Data Register
GP_CDATA	0x0018	GPADC Calibration Data Register
GP_DATAL_INTC	0x0020	GPADC Data Low Interrupt Configure Register
GP_DATAH_INTC	0x0024	GPADC Data High Interrupt Configure Register
GP_DATA_INTC	0x0028	GPADC Data Interrupt Configure Register
GP_DATAL_INTS	0x0030	GPADC Data Low Interrupt Status Register
GP_DATAH_INTS	0x0034	GPADC Data High Interrupt Status Register
GP_DATA_INTS	0x0038	GPADC Data Interrupt Status Register
GP_CH0_CMP_DATA	0x0040	GPADC CH0 Compare Data Register
GP_CH1_CMP_DATA	0x0044	GPADC CH1 Compare Data Register
GP_CH0_DATA	0x0080	GPADC CH0 Data Register
GP_CH1_DATA	0x0084	GPADC CH1 Data Register

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10.8.6 Register Description

10.8.6.1 0x0000 GPADC Sample Rate Configure Register (Default Value: 0x01DF_002F)

Offset: 0x0000			Register Name: GP_SR_CON
Bit	**Read/Write**	**Default/Hex**	**Description**
31: 16	R/W	0x1DF	FS_DIV ADC sample frequency divider CLK_IN/(n+1) Default value: 50K
15:0	R/W	0x2F	TACQ ADC acquire time (n+1)/CLK_IN Default value: 2 us

10.8.6.2 0x0004 GPADC Control Register (Default Value: 0x0080_0000)

Offset: 0x0004			Register Name: GP_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	R/ W	0x0	ADC_FIRST_DLY ADC First Convert Delay Setting ADC conversion of each channel is delayed by N samples.
23	R/ W	0x1	ADC_AUTOCALI_EN ADC Auto Calibration
22	/	/	/
21:20	R/W	0x0	ADC_OP_BIAS ADC OP Bias Adjust the bandwidth of the ADC amplifier
19:18	R/W	0x0	GPADC Work Mode 00: Single conversion mode 01: Reserved 10: Continuous conversion mode 11: Burst conversion mode
17	R/W	0x0	ADC_CALI_EN ADC Calibration 1: Start Calibration, it is cleared to 0 after calibration

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Offset: 0x0004			Register Name: GP_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
16	R/W	0x0	ADC_EN ADC Function Enable Before the bit is enabled, configure ADC parameters including the work mode and channel number, etc. 0: Disable 1: Enable **Note: When selecting a single conversion mode, the bit can be cleared automatically after the switch is completed.**
15:0	/	/	/

10.8.6.3 0x0008 GPADC Compare and Select Enable Register (Default Value: 0x0000_0000)

Offset: 0x0008			Register Name: GP_CS_EN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/W	0x0	ADC_CH1_CMP_EN Channel 1 Compare Enable 0: Disable 1: Enable
16	R/W	0x0	ADC_CH0_CMP_EN Channel 0 Compare Enable 0: Disable 1: Enable
15:2	/	/	/
1	R/W	0x0	ADC_CH1_SELECT Analog Input Channel 1 Select 0: Disable 1: Enable
0	R/W	0x0	ADC_CH0_SELECT Analog Input Channel 0 Select 0: Disable 1: Enable

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10.8.6.4 0x000C GPADC FIFO Interrupt Control Register (Default Value: 0x0000_1F00)

Offset: 0x000C			Register Name: GP_FIFO_INTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:19	/	/	/
18	R/W	0x0	FIFO_DATA_DRQ_EN ADC FIFO Date DRQ Enable 0: Disable 1: Enable
17	R/W	0x0	FIFO_OVERRUN_IRQ_EN ADC FIFO Overrun IRQ Enable 0: Disable 1: Enable
16	R/W	0x0	FIFO_DATA_IRQ_EN ADC FIFO Data Available IRQ Enable 0: Disable 1: Enable
15:14	/	/	/
13:8	R/W	0x1F	FIFO_TRIG_LEVEL Interrupt trigger level for ADC Trigger Level = TXTL + 1
7:5	/	/	/
4	R/WAC	0x0	FIFO_FLUSH ADC FIFO Flush Write ‘1’ to flush TX FIFO, clear automatically to ‘0’.
3:0	/	/	/

10.8.6.5 0x0010 GPADC FIFO Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: GP_FIFO_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/

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Offset: 0x0010			Register Name: GP_FIFO_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
17	R/W1C	0x0	FIFO_OVERRUN_PENDING ADC FIFO Overrun IRQ Pending 0: No Pending IRQ 1: FIFO Overrun Pending IRQ Write '1' to clear this interrupt or automatically clear if the interrupt condition fails.
16	R/W1C	0x0	FIFO_DATA_PENDING ADC FIFO Data Available Pending Bit 0: NO Pending IRQ 1: FIFO Available Pending IRQ Write '1' to clear this interrupt or automatically clear if the interrupt condition fails.
15:14	/	/	/
13:8	R	0x0	RXA_CNT ADC FIFO available sample word counter
7:0	/	/	/

10.8.6.6 0x0014 GPADC FIFO Data Register (Default Value: 0x0000_0000)

Offset: 0x0014			Register Name: GP_FIFO_DATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:0	R	0x0	GP_FIFO_DATA GPADC Data in FIFO

10.8.6.7 0x0018 GPADC Calibration Data Register (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: GP_CDATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:0	R/W	0x0	GP_CDATA GPADC Calibration Data

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10.8.6.8 0x0020 GPADC Low Interrupt Configure Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: GP_DATAL_INTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R/W	0x0	CH1_LOW_IRQ_EN Channel 1 Voltage Low Available Interrupt Enable 0: Disable 1: Enable
0	R/W	0x0	CH0_LOW_IRQ_EN Channel 0 Voltage Low Available Interrupt Enable 0: Disable 1: Enable

10.8.6.9 0x0024 GPADC High Interrupt Configure Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: GP_DATAH_INTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R/W	0x0	CH1_HIG_IRQ_EN Channel 1 Voltage High Available Interrupt Enable 0: Disable 1: Enable
0	R/W	0x0	CH0_HIG_IRQ_EN Channel 0 Voltage High Available Interrupt Enable 0: Disable 1: Enable

10.8.6.10 0x0028 GPADC DATA Interrupt Configure Register (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: GP_DATA_INTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R/W	0x0	CH1_DATA_IRQ_EN 0: Disable 1: Enable

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Offset: 0x0028			Register Name: GP_DATA_INTC
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	CH0_DATA_IRQ_EN 0: Disable 1: Enable

10.8.6.11 0x0030 GPADC Low Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0030			Register Name: GP_DATAL_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R/W1C	0x0	CH1_LOW_PENGDING Channel 1 Voltage Low Available Interrupt Status 0: NO Pending IRQ 1: Channel 1 Voltage Low Available Pending IRQ Write '1' to clear this interrupt or automatically clear if the interrupt condition fails.
0	R/W1C	0x0	CH0_LOW_PENGDING Channel 0 Voltage Low Available Interrupt Status 0: NO Pending IRQ 1: Channel 0 Voltage Low Available Pending IRQ Write '1' to clear this interrupt or automatically clear if the interrupt condition fails.

10.8.6.12 0x0034 GPADC High Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0034			Register Name: GP_DATAH_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R/W1C	0x0	CH1_HIG_PENGDING 0: No Pending IRQ 1: Channel 1 Voltage High Available Pending IRQ Write '1' to clear this interrupt or automatically clear if the interrupt condition fails.

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Offset: 0x0034			Register Name: GP_DATAH_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W1C	0x0	CH0_HIG_PENGDING 0: No Pending IRQ 1: Channel 0 Voltage High Available Pending IRQ Write '1' to clear this interrupt or automatically clear if the interrupt condition fails.

10.8.6.13 0x0038 GPADC Data Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0038			Register Name: GP_DATA_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1	R/W1C	0x0	CH1_DATA_PENGDING Channel 1 Data Available Interrupt Status 0: No Pending IRQ 1: Channel 1 Data Available Pending IRQ Write '1' to clear this interrupt or automatically clear if the interrupt condition fails.
0	R/W1C	0x0	CH0_DATA_PENGDING Channel 0 Data Available Interrupt Status 0: No Pending IRQ 1: Channel 0 Data Available Pending IRQ Write '1' to clear this interrupt or automatically clear if the interrupt condition fails.

10.8.6.14 0x0040 GPADC CH0 Compare Data Register (Default Value: 0x0BFF_0400)

Offset: 0x0040			Register Name: GP_CH0_CMP_DATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/
27:16	R/W	0xBFF	CH0_CMP_HIG_DATA Channel 0 Voltage High Value
15:12	/	/	/
11:0	R/W	0x400	CH0_CMP_LOW_DATA Channel 0 Voltage Low Value

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10.8.6.15 0x0044 GPADC CH1 Compare Data Register (Default Value: 0x0BFF_0400)

Offset: 0x0044			Register Name: GP_CH1_CMP_DATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	/	/	/
27:16	R/W	0xBFF	CH1_CMP_HIG_DATA Channel 1 Voltage High Value
15:12	/	/	/
11:0	R/W	0x400	CH1_CMP_LOW_DATA Channel 1 Voltage Low Value

10.8.6.16 0x0080 GPADC CH0 Data Register (Default Value: 0x0000_0000)

Offset: 0x0080			Register Name: GP_CH0_DATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:0	R	0x000	GP_CH0_DATA Channel 0 Data

10.8.6.17 0x0084 GPADC CH1 Data Register (Default Value: 0x0000_0000)

Offset: 0x0084			Register Name: GP_CH1_DATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:0	R	0x000	GP_CH1_DATA Channel 1 Data

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10.9 TPADC

10.9.1 Overview

The Touch Panel ADC (TPADC) is a 4-wire resistive touch screen controller, including a 12-bit SAR type A/D converter.

The TPADC has the following features:

- 12 bit SAR type A/D converter
- Configurable sample frequency up to 1 MHz
- One 32x12 FIFO for storing A/D conversion result
- Supports DMA slave interface
- Supports 4-wire resistive touch panel input detection
  - Supports pen down detection with programmable sensitivity
  - Supports single touch coordinate measurement
  - Supports dual touch detection
  - Supports touch pressure measurement with programmable threshold
  - Supports median and averaging filter for noise reduction
  - Supports X and Y coordinate exchange function
- Supports Aux ADC with up to 4 channels

10.9.2 Functional Description

10.9.2.1 External Signals

The following table describes the external signals of the TPADC.

Table 10-30 TPADC External Signals

Signal	Description	Type
TP-X1	Touch Panel X1 Input	AI
TP-X2	Touch Panel X2 Input	AI
TP-Y1	Touch Panel Y1 Input	AI
TP-Y2	Touch Panel Y2 Input	AI

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10.9.2.2 Single-ended Mode and Differential Mode

The controller is a typical type of successive approximation ADC (SAR ADC) which contains a sample/hold, analog-to-digital conversion, serial data output functions.

The analog inputs (X+, X-, Y+, Y-) enter the ADC through the control register, the ADC can work in single-ended or differential mode. Selecting Aux ADC should work in single-ended mode; for a touch screen application, it works in a differential mode, which can effectively eliminate the impact on conversion accuracy caused by the parasitic resistance of the driver switch and external interference.

Figure 10-73 shows TPADC Single-Ended Mode for the measurement of Aux, using the 1.8V reference source as the ADC reference voltage.

Figure 10-73 TPADC Single-Ended Mode for AUX ADC

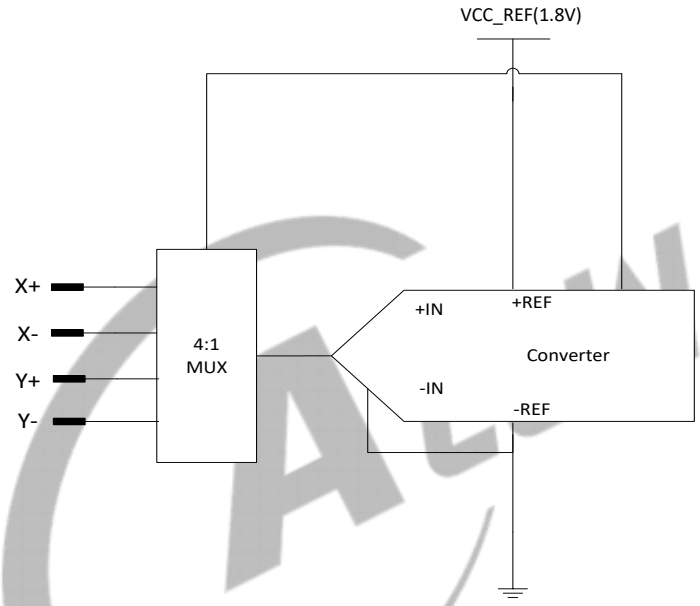
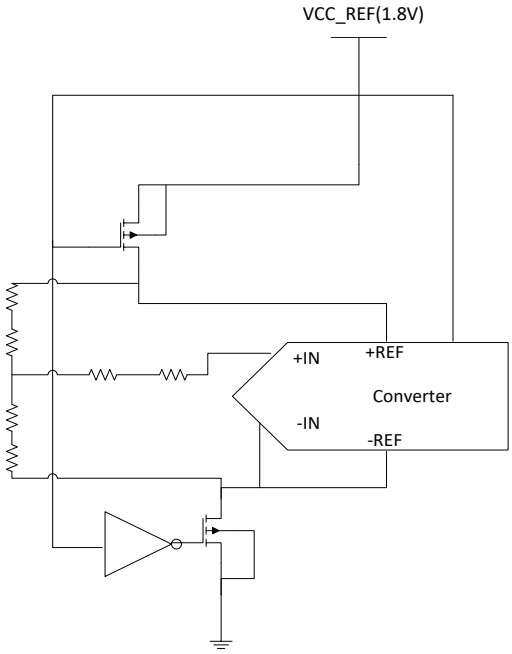


Figure 10-74 shows TPADC differential mode for the measurement of X/Y/Z coordinate of Touch Panel. The advantage of differential mode: +REF and –REF can directly input to the Y+ and Y-(or X+ and X-), which can eliminate the measurement error of X+/X-(or Y+/Y-) because of the switch on resistance. The disadvantage is that: both the sample or conversion process, the driver will need to be enabled. Compared with single-ended mode, the power consumption increases.

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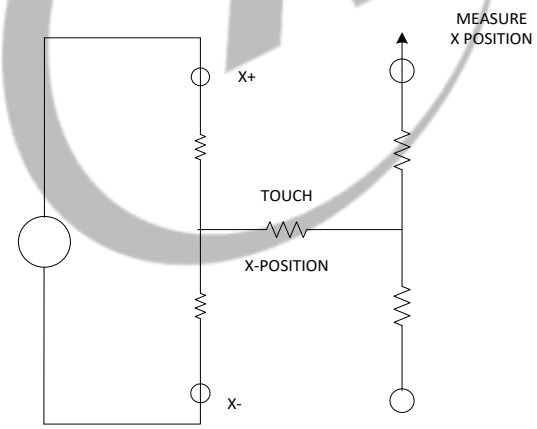
Figure 10-74 TPADC Differential Mode for Touch Panel



10.9.2.3 Single Touch Measurement

The following figure shows the operation principle of the single touch X-Coordinate measurement.

Figure 10-75 Single Touch X-Coordinate Measurement for Touch Panel



For an X coordinate measurement, the X+ pin is internally switched to VCC_REF and X- to GND. The X plate becomes a potential divider, and the voltage at the point of contact is proportional to its X co-ordinate. This voltage is measured on the Y+, which carries no current (hence there is no voltage drop in RY+ or RY-). Due to the ratio metric measurement method, the supply voltage does not affect measurement accuracy. The voltage

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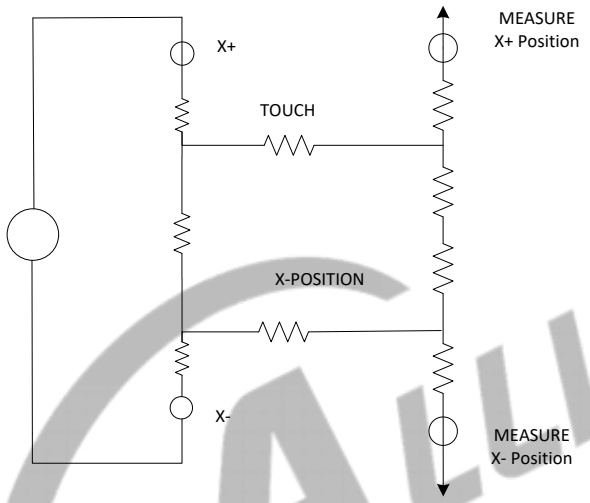
references VREF+ and VREF- are taken from after the matrix switches, so that any voltage drop in these switches has no effect on the ADC measurement.

Y coordinate measurements are similar to X coordinate measurements, with the X and Y plates interchanged.

10.9.2.4 Dual Touch Measurement

In single touch mode, it only needs to test X+ and Y+ signals. But in dual touch mode, it needs to test X+, X-, Y+, and Y- signals. The following figure shows the operation principle of dual touch detection for touch panel.

Figure 10-76 Dual Touch Detection for Touch Panel



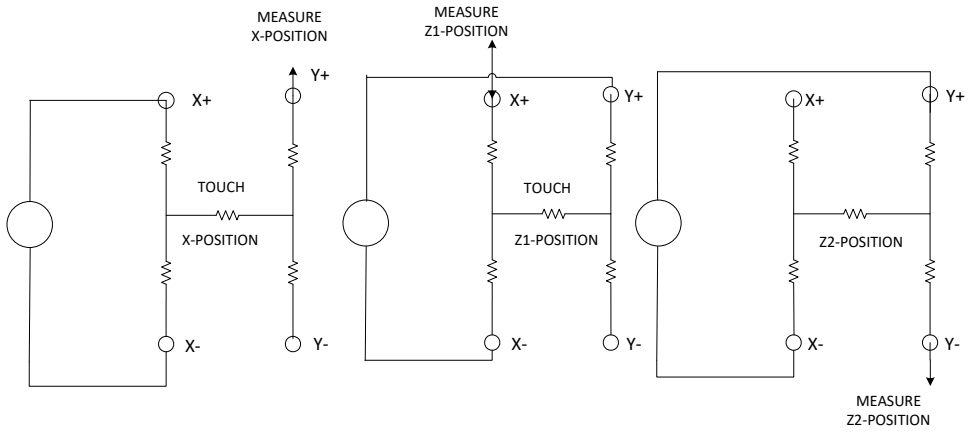
For X coordinates measurement, the X+ pin is internally switched to 3 V and X- to GND. The controller needs to test Y+ and Y-, Y coordinates measurement is similar. And record △X=|X+ - X-|, △Y= | Y+ - Y-|. In practice, we can set a threshold. If △X or △Y greater than the threshold, we consider it as a dual touch, otherwise as a single touch.

10.9.2.5 Touch Pressure Measurement

The pressure applied to the touch screen by a pen or finger to filter unavailable can also be measured by the controller using some simple calculations. The contact resistance between the X and Y plates is measured, which provides a good indication of the size of the depressed area and the applied pressure. The area of the touch spot t is proportional to the size of the object touching it. And the value of this resistance (R_{touch}) can be calculated using two different methods.

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Figure 10-77 Touch Pressure Measurement for Touch Panel



(1) First Method

The first method requires the user to know the total resistance of the X plate tablet (R_{XPLATE}). Three touch screen conversions are required: measurement of the X position, $X_{POSITION}$(Y+ input); measurement of the X+ input with the excitation voltage applied to Y+ and X− (Z1 measurement); and measurement of the Y− input with the excitation voltage applied to Y+ and X− (Z2 measurement). These three measurements are illustrated in following Figure. The controller have two special ADC channel settings to configure the X and Y switches for the Z1 and Z2 measurements and store the results in the Z1 and Z2 result registers. The touch resistance (R_{TOUCH}) can then be calculated using the following equation.

$$R_{TOUCH} = (R_{XPLATE}) \times (X_{POSITION}/4096) \times [(Z2/Z1) - 1]$$

(2) Second Method

The second method requires the user to know the resistance of the X-plate and Y-plate tablets. Three touch screen conversions are required: a measurement of the X position ($X_{POSITION}$), the Y position ($Y_{POSITION}$), and the Z1 position. The following equation also calculates the touch resistance (R_{TOUCH}).

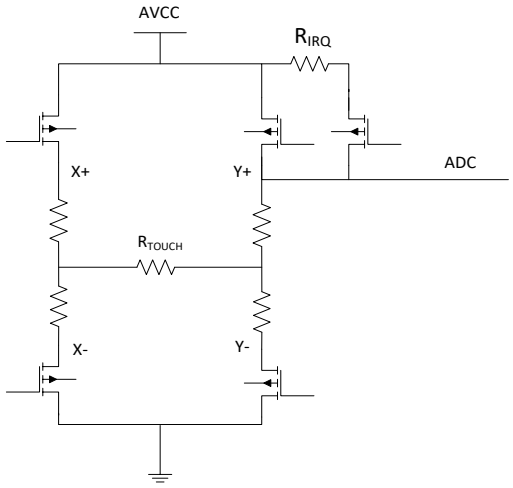
$$R_{TOUCH} = R_{XPLATE} \times (X_{POSITION}/4096) \times [(4096/Z1) - 1] - R_{YPLATE} \times [1 - (Y_{POSITION}/4096)]$$

10.9.2.6 Pen Down Detection

Pen down detection is used as an interrupt to the host. RIRQ is an internal pull-up resistor with a programmable value from 6 kΩ to 96 kΩ (default 48 kΩ).

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Figure 10-78 Pen Down Detection for Touch Panel



The pen down IRQ output is pulled high by an internal pull-up. In the pen down detection, the Y– driver is enabled and connected to GND, and the pen down IRQ output is connected to the X+ input. When the panel is touched, the X+ input is pulled to ground through the touch screen, and the pen down IRQ output goes low because of the current path through the panel to GND, initiating an interrupt to the processor.

During the measurement cycle for X-, Y-, and Z-position, the X+ input is disconnected from the pen down IRQ pull-down transistor to eliminate any pull-up resistor leakage current from flowing through the touch screen, thus causing no errors.

10.9.2.7 Median and Averaging Filter

Touch screens are composed of two resistive layers, normally placed over an LCD screen. Because these layers are in close proximity to the LCD screen, noise can be coupled from the screen onto these resistive layers, causing errors in the touch screen positional measurements.

The controller contain a filtering block to process the data and discard the spurious noise before sending the information to the host. The purpose of this block is not only the suppression of noise; the on-chip filtering also greatly reduces the host processing loading.

The processing function consists of two filters that are applied to the converted results: the median filter and the averaging filter. The median filter suppresses the isolated out-of-range noise and sets the number of measurements to be taken. These measurements are arranged in a temporary array, where the first value is the smallest measurement and the last value is the largest measurement. Then the averaging filter size determines the number of values to average. There are four choices which is configured by TP_CTRL3 register (bit 1 and bit 0) to filtrate the ADC sampling data.

Figure 10-79 Median and Averaging Filter Size

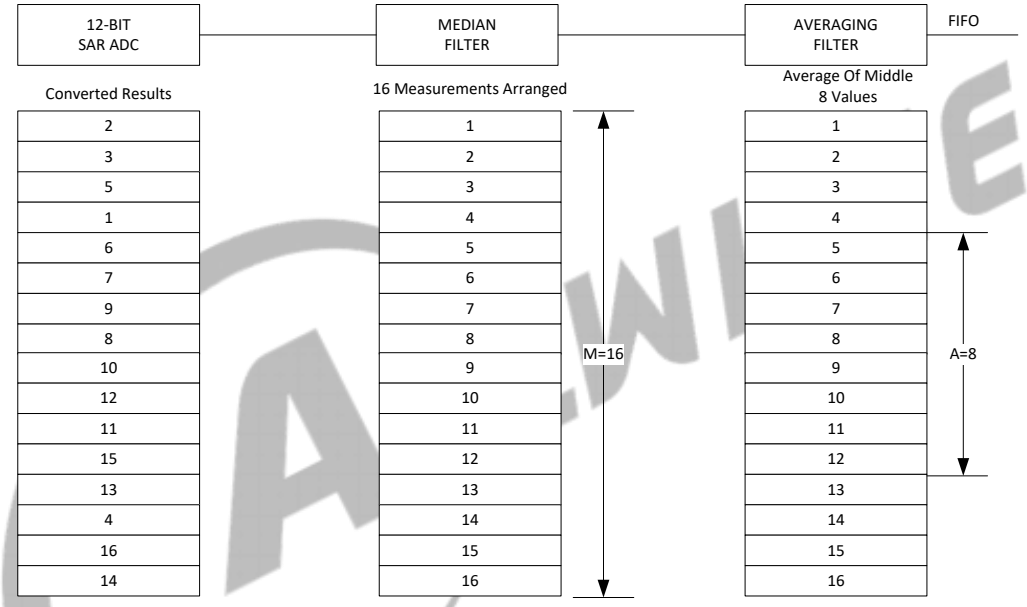
Bit1	Bit0	Averaging Filter Size	Median Filter Size
0	0	2	4

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Bit1	Bit0	Averaging Filter Size	Median Filter Size
0	1	3	5
1	0	4	8
1	1	8	16

Example: In this example, the bit[1:0] of TP_CTRL_REG3 is configured as 2'b11. So the median filter has a window size of 16. This means that 16 measurements are taken and arranged in descending order in a temporary array. The averaging window size in this example is 8. The output is the average of the middle eight values of the 16 measurements taken with the median filter.

Figure 10-80 Median and Averaging Filter Example



10.9.3 Register List

Module Name	Base Address
TPADC	0x02009C00

Register Name	Offset	Description
TP_CTRL_REG0	0x0000	TP Control Register 0
TP_CTRL_REG1	0x0004	TP Control Register 1
TP_CTRL_REG2	0x0008	TP Control Register 2
TP_CTRL_REG3	0x000C	TP Control Register 3
TP_INT_FIFO_CTRL_REG	0x0010	TP Interrupt FIFO Control Register
TP_INT_FIFO_STAT_REG	0x0014	TP Interrupt FIFO Status Register

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Register Name	Offset	Description
TP_CALI_DATA_REG	0x001C	TP Calibration Data Register
TP_DATA_REG	0x0024	TP Data Register

10.9.4 Register Description

10.9.4.1 0x0000 TP Control Register 0 (Default Value:0x0F80_0000)

Offset: 0x0000			Register Name: TP_CTRL0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	R/W	0xF	ADC_FIRST_DLY ADC First Convert Delay Time (T_FCDT) Setting Based on ADC first convert delay mode select (Bit 23) T_FCDT = ADC_FIRST_DLY * ADC_FIRST_DLY_MODE
23	R/W	0x1	ADC_FIRST_DLY_MODE ADC First Convert Delay Mode Select 0: CLK_IN/16 1: CLK_IN/16*256
22	/	/	/
21:20	R/W	0x0	ADC_CLK_DIVIDER ADC Clock Divider (CLK_IN) 00: CLK/2 01: CLK/3 10: CLK/6 11: CLK/1
19:16	R/W	0x0	FS_DIV ADC Sample Frequency Divider 0000: CLK_IN/$2^{(20-0)}$ 0001: CLK_IN/$2^{(20-1)}$ 0010: CLK_IN/$2^{(20-2)}$ .... 1111: CLK_IN/$2^{(20-15)}$
15:0	R/W	0x0	TACQ Touch panel ADC acquire time CLK_IN/(16*(N+1))

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10.9.4.2 0x0004 TP Control Register 1 (Default Value:0x0000_0101)

Offset: 0x0004			Register Name: TP_CTRL_REG1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:20	/	/	/
19:12	R/W	0x0	STYLUS_UP_DEBOUNCE Stylus Up De-bounce Time Setting 0x00: 0 …. 0xFF: 2N*(CLK_IN/16*256)
11:10	/	/	/
9	R/W	0x0	STYLUS_UP_DEBOUCE_EN Stylus Up Debounce Function Select 0: Disable 1: Enable
8	R/W	0x1	CHOPPER_EN T-sensor Chopping Enable 0: Disable 1: Enable This field is not used when there is no T-sensor in TPADC
7	R/W	0x0	TOUCH_PAN_CALI_EN Touch Panel Calibration 1: Start calibration, it is cleared to 0 after calibration
6	R/W	0x0	TP_DUAL_EN Touch Panel Double Point Enable 0: Disable 1: Enable
5	R/W	0x0	TP_EN. TP Function Enable 0: Disable 1: Enable
4	R/W	0x0	TP_MODE_SELECT. Touch Panel Mode and Auxiliary ADC Mode Select 0: TP 1: Auxiliary ADC

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Offset: 0x0004			Register Name: TP_CTRL_REG1
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W	0x0	ADC_CHAN3_SELECT Analog Input Channel 3 Select 0: Disable 1: Enable
2	R/W	0x0	ADC_CHAN2_SELECT Analog Input Channel 2 Select 0: Disable 1: Enable
1	R/W	0x0	ADC_CHAN1_SELECT Analog Input Channel 1 Select 0: Disable 1: Enable
0	R/W	0x1	ADC_CHAN0_SELECT Analog Input Channel 0 Select 0: Disable 1: Enable

CHAN0–3 can be selected at the same time. If N channel is selected, each channel has 1/N full speed of the ADC. If only one channel is selected, it has the full conversion rate. CHAN0–3 correspond to TP_YN, TP_YP, TP_XN, TP_XP.

10.9.4.3 0x0008 TP Control Register 2 (Default Value:0x8000_0FFF)

Offset: 0x0008			Register Name: TP_CTRL_REG2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:28	R/W	0x8	TP_SENSITIVE_ADJUST Internal Pull-up Resistor Control 0000: least sensitive …… 1111: most sensitive This field is used to adjust sensitivity of pen down detection.

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Offset: 0x0008			Register Name: TP_CTRL_REG2
Bit	**Read/Write**	**Default/Hex**	**Description**
27:26	R/W	0x0	TP_FIFO_MODE_SELECT TP FIFO Access Data Mode Select 00: FIFO store X1,Y1 data for single touch no pressure mode 01: FIFO store X1,Y1, △X, △Y data for dual touch no pressure mode 10: FIFO store X1,Y1, X2,Y2 data for dual touch no pressure mode 11: FIFO store X1,Y1, X2,Y2,Z1,Z2 data for dual touch and pressure mode The ADC output data in single touch mode can store in FIFO with TP_FIFO_MODE_SELECT configured as 01,10,11. But the data △X, △Y is theoretically equal to X1,Y1, and X2,Y2 is equal to 0. When PRE_MEA_EN is set and TP_FIFO_MODE_SELECT is not configured as 2'b11, X and Y data will not be stored unless x1*(z2-z1)/z1 < PRE_MEA_THRE_CNT. Z data will always be zero when TP_FIFO_MODE_SELECT is configured as 2'b11 but PRE_MEA_EN is not set.
25	/	/	/
24	R/W	0x0	PRE_MEA_EN TP Pressure Measurement Enable Control 0: Disable 1: Enable
23:0	R/W	0xFFF	PRE_MEA_THRE_CNT TP Pressure Measurement Threshold Control 0x000000:least sensitive 0xFFFFFF: most sensitive This field is used to adjust sensitivity of touch.

10.9.4.4 0x000C TP Control Register 3 (Default Value:0x0000_0001)

Offset: 0x000C			Register Name: TP_CTRL_REG3
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/

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Offset: 0x000C			Register Name: TP_CTRL_REG3
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	FILTER_EN Filter Enable 0: Disable 1: Enable
1:0	R/W	0x1	FILTER_TYPE Filter Type 00: 4/2 01: 5/3 10: 8/4 11: 16/8

10.9.4.5 0x0010 TP Interrupt& FIFO Control Register (Default Value:0x0000_0F00)

Offset: 0x0010			Register Name: TP_INT_FIFO_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/W	0x0	TP_OVERRUN_IRQ_EN TP FIFO Overrun IRQ Enable 0: Disable 1: Enable
16	R/W	0x0	TP_DATA_IRQ_EN TP FIFO Data Available IRQ Enable 0: Disable 1: Enable
15:14	/	/	/
13	R/W	0x0	TP_DATA_XY_CHANGE TP FIFO X,Y Data Interchange Function Select 0: Disable 1: Enable
12:8	R/W	0xF	TP_FIFO_TRIG_LEVEL TP FIFO Data Available Trigger Level Interrupt and DMA request trigger level for TP or Auxiliary ADC Trigger Level = TXTL + 1

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Offset: 0x0010			Register Name: TP_INT_FIFO_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
7	R/W	0x0	TP_DATA_DRQ_EN TP FIFO Data Available DRQ Enable 0: Disable 1: Enable
6:5	/	/	/
4	R/WAC	0x0	TP_FIFO_FLUSH TP FIFO Flush Write '1' to flush TX FIFO, self clear to '0'
3:2	/	/	/
1	R/W	0x0	TP_UP_IRQ_EN Touch Panel Last Touch (Stylus Up) IRQ Enable 0: Disable 1: Enable
0	R/W	0x0	TP_DOWN_IRQ_EN Touch Panel First Touch (Stylus Down) IRQ Enable 0: Disable 1: Enable

10.9.4.6 0x0014 TP Interrupt& FIFO Status Register (Default Value:0x0000_0000)

Offset: 0x0014			Register Name: TP_INT_FIFO_STAT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/W1C	0x0	FIFO_OVERRUN_PENDING TP FIFO Overrun IRQ pending 0: No Pending IRQ 1: FIFO Overrun Pending IRQ Write '1' to clear this interrupt or automatically clear if interrupt condition fails.
16	R/W1C	0x0	FIFO_DATA_PENDING TP FIFO Data Available Pending Bit 0: NO Pending IRQ 1: FIFO Available Pending IRQ Write '1' to clear this interrupt or automatically clear if FIFO flushed.

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Offset: 0x0014			Register Name: TP_INT_FIFO_STAT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
15:14	/	/	/
13:8	R	0x0	RXA_CNT TP FIFO Available Sample Word Counter
7:3	/	/	/
2	R	0x0	TP_IDLE_FLG Touch Panel Idle Flag 0: idle 1: not idle
1	R/W1C	0x0	TP_UP_PENDING Touch Panel Last Touch (Stylus Up) IRQ Pending bit 0: No IRQ 1: IRQ Writing 1 to the bit clears it and its corresponding interrupt if the interrupt is enabled.
0	R/W1C	0x0	TP_DOWN_PENDING Touch Panel First Touch (Stylus Down) IRQ Pending bit 0: No IRQ 1: IRQ Writing 1 to the bit clears it and its corresponding interrupt if the interrupt is enabled.

10.9.4.7 0x001C TP Calibration Data Register (Default Value:0x0000_0800)

Offset: 0x001C			Register Name: TP_CALI_DATA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:0	R/W	0x800	TP_CDAT TP Common Data It is used to adjust the tolerance of the internal ADC.

10.9.4.8 0x0024 TP Data Register (Default Value:0x0000_0000)

In touch panel mode, the data stored in this register bases on TP_FIFO_MODE_SELECT. In Auxiliary ADC mode, the data stored in this register bases on ADC_CHAN_SELECT. If four channels are enabled, FIFO will access the input data in successive turn (ADC_CHAN0 -> ADC_CHAN1 -> ADC_CHAN2 -> ADC_CHAN3). If only two or three

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channels are selected, such as ADC_CHAN0 and ADC_CHAN3, firstly ADC_CHAN0 input data is accessed, then ADC_CHAN3 input data.

Offset: 0x0024			Register Name: TP_DATA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:12	/	/	/
11:0	R	0x0	TP_DATA Touch Panel X ,Y data or Auxiliary analogy input data converted by the internal ADC.

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10.10 LRADC

10.10.1 Overview

The low rate analog-to-digital converter (LRADC) can convert the external signal into a certain proportion of digital value, to realize the measurement of analog signal, which can be applied to power detection and key detection.

The LRADC has the following features:

- 6-bit sampling resolution and 5-bit precision
- Sample rate up to 2 kHz
- Supports hold Key and general Key
- Supports normal, continuous and single working mode
- Power supply voltage: AVCC, and power reference voltage: 0.75*AVCC, analog input and detected voltage range: 0 to 1.266 V
- Supports interrupt

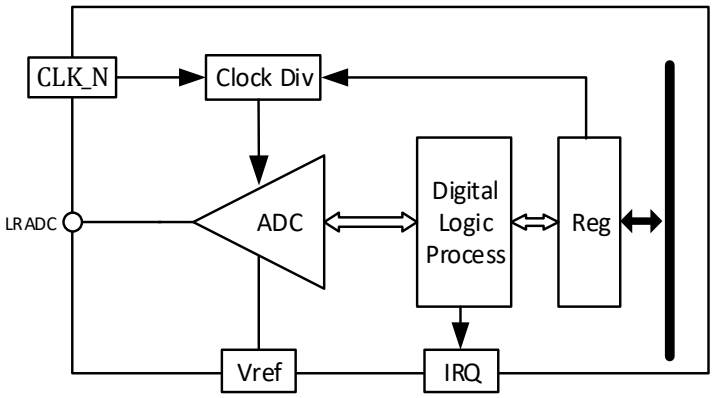
NOTE

The LRADC has a 6-bit resolution, 1-bit offset error, and 1-bit precision error. After the LRADC calibrates 1-bit offset error, the LRADC has 5-bit precision.

10.10.2 Block Diagram

Figure 10-81 shows the block diagram of the LRADC.

Figure 10-81 LRADC Block Diagram



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10.10.3 Functional Description

10.10.3.1 External Signals

The following table describes the external signals of the LRADC. The LRADC pin is the analog input signal.

Table 10-31 LRADC External Signals

Signal	Description	Type
LRADC	Analog Input Channel0	AI

10.10.3.2 Clock Sources

The LRADC has one clock source. The following table describes the clock source for LRADC.

Table 10-32 LRADC Clock Sources

Clock Sources	Description
LOSC	32.768 kHz LOSC

10.10.3.3 LRADC Working Mode

- **Normal Mode**

  The LRADC gathers 8 samples, the average value of these 8 samples is updated in the data register, and the data interrupt sign is enabled. It is sampled repeatedly according to this mode until the LRADC is disabled.

- **Continuous Mode**

  The LRADC gathers 8 samples every other 8*(N+1) sample cycle. The average value of every 8 samples is updated in the data register, and the data interrupt sign is enabled. (N is defined in the bit[19:16] of LRADC_CTRL).

- **Single Mode**

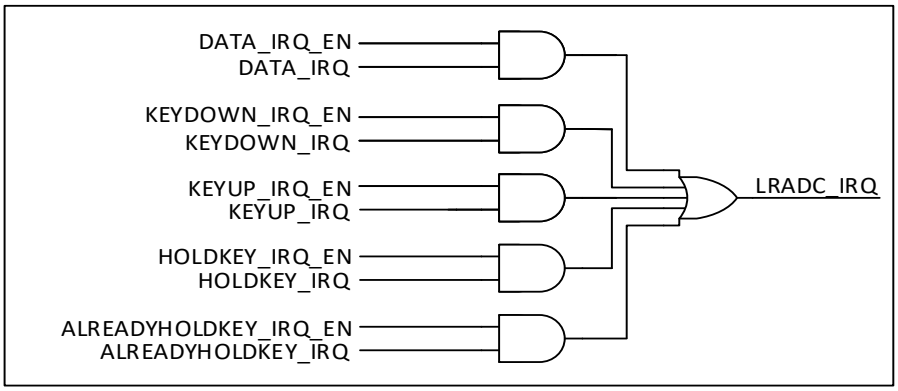
  The LRADC gathers 8 samples, and the average value of these 8 samples is updated in the data register, and the data interrupt sign is enabled at the same time, then the LRADC stops sample.

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10.10.3.4 Interrupt

Each LRADC channel has five interrupt sources and five interrupt enable controls.

Figure 10-82 LRADC Interrupt



When the input voltage is between LEVEL A (1.35 V) and LEVEL B (control by the bit[5:4] of **LRADC_CTRL**), the IRQ1 can be generated. When the input voltage is lower than LEVEL B, the IRQ2 can be generated.

If the controller receives IRQ1 and does not receive IRQ2 at the same time, then the controller will generate Hold Key Pending, otherwise Data IRQ Pending.

The Hold KEY usually is used for the self-locking key. When the self-locking key holds a locking status, the controller receives the IRQ2, then the controller will generate Already Hold Pending.

10.10.3.5 Calculation Formula

Calculation formula: LRADC_DATA = $Vin/V_{REF}*63$, V_{REF}=1.35 V

10.10.4 Programming Guidelines

10.10.4.1 Normal Detecting

Perform the following steps for normal detecting mode:

Step 1 Configure **LRADC_BGR_REG**[LRADC_GATING] to 0 to disable the clock of LRADC.

Step 2 Configure **LRADC_BGR_REG**[LRADC_RST] to 1 to deassert the reset of LRADC.

Step 3 Configure **LRADC_BGR_REG**[LRADC_GATING] to 1 to enable the clock of LRADC.

Step 4 Configure **LRADC_CTRL**[LRADC_SAMPLE_RATE] to set the appropriate sampling frequency.

Step 5 Configure **LRADC_CTRL**[LEVELB_VOL] to set the appropriate voltage threshold.

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Step 6 Configure **LRADC_CTRL**[FIRST_CONVER_DLY] and **LRADC_CTRL**[LEVELA_B_CNT] to set the appropriate debounce value.

Step 7 Configure **LRADC_CTRL**[LRADC_HOLD_KEY_EN] to 1.

Step 8 Configure **LRADC_CTRL**[KEY_MODE_SELECT] to 0 to set the normal mode.

Step 9 Configure **LRADC_INTC** to enable the corresponding interrupt.

Step 10 Configure **LRADC_CTRL**[LRADC_HOLD_KEY_EN] to 1.

Step 11 Read the corresponding key voltage value from **LRADC_DATA** when the CPU receives the LRADC interrupt.

10.10.4.2 Single Detecting

Perform the following steps for the single detecting mode:

Step 1 Configure **LRADC_BGR_REG**[LRADC_GATING] to 0 to disable the clock of LRADC.

Step 2 Configure **LRADC_BGR_REG**[LRADC_RST] to 1 to deassert the reset of LRADC.

Step 3 Configure **LRADC_BGR_REG**[LRADC_GATING] to 1 to enable the clock of LRADC.

Step 4 Configure **LRADC_CTRL**[LRADC_SAMPLE_RATE] to set the appropriate sampling frequency.

Step 5 Configure **LRADC_CTRL**[LEVELB_VOL] to set the appropriate voltage threshold.

Step 6 Configure **LRADC_CTRL**[FIRST_CONVER_DLY] and **LRADC_CTRL**[LEVELA_B_CNT] to set the appropriate debounce value.

Step 7 Configure **LRADC_CTRL**[LRADC_HOLD_KEY_EN] to 1.

Step 8 Configure **LRADC_CTRL**[KEY_MODE_SELECT] to 1 to set the single mode.

Step 9 Configure **LRADC_INTC** to enable the corresponding interrupt.

Step 10 Configure **LRADC_CTRL**[LRADC_HOLD_KEY_EN] to 1.

Step 11 Read the corresponding key voltage value from **LRADC_DATA** when the CPU receives the LRADC interrupt.

10.10.4.3 Continuous Detecting

Perform the following steps for continuous detecting mode:

Step 1 Configure **LRADC_BGR_REG**[LRADC_GATING] to 0 to disable the clock of LRADC.

Step 2 Configure **LRADC_BGR_REG**[LRADC_RST] to 1 to deassert the reset of LRADC.

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Step 3 Configure **LRADC_BGR_REG**[LRADC_GATING] to 1 to enable the clock of LRADC.

Step 4 Configure **LRADC_CTRL**[LRADC_SAMPLE_RATE] to set the appropriate sampling frequency.

Step 5 Configure **LRADC_CTRL**[LEVELB_VOL] to set the appropriate voltage threshold.

Step 6 Configure **LRADC_CTRL**[FIRST_CONVER_DLY] and **LRADC_CTRL**[LEVELA_B_CNT] to set the appropriate debounce value.

Step 7 Configure **LRADC_CTRL**[LRADC_HOLD_KEY_EN] to 1.

Step 8 Configure **LRADC_CTRL**[KEY_MODE_SELECT] to 2 to set the continuous mode, and configure **LRADC_CTRL**[CONTINUE_TIME_SELECT] to set a sampling interval.

Step 9 Configure **LRADC_INTC** to enable the corresponding interrupt.

Step 10 Configure **LRADC_CTRL**[LRADC_HOLD_KEY_EN] to 1.

Step 11 Read the corresponding key voltage value from **LRADC_DATA** when the CPU receives the LRADC interrupt.

10.10.5 Register List

Module Name	Base Address
LRADC	0x02009800

Register Name	Offset	Description
LRADC_CTRL	0x0000	LRADC Control Register
LRADC_INTC	0x0004	LRADC Interrupt Control Register
LRADC_INTS	0x0008	LRADC Interrupt Status Register
LRADC_DATA	0x000C	LRADC Data Register

10.10.6 Register Description

10.10.6.1 0x0000 LRADC Control Register (Default Value: 0x0100_0168)

Offset: 0x0000			Register Name: LRADC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	R/W	0x1	FIRST_CONVERT_DLY ADC First Convert Delay Setting ADC conversion is delayed by n samples.

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Offset: 0x0000			Register Name: LRADC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
23:20	/	/	/
19:16	R/W	0x0	CONTINUE_TIME_SELECT Continuous Mode Time Select One of 8*(N+1) sample as a valuable sample data.
15:14	/	/	/
13:12	R/W	0x0	KEY_MODE_SELECT Key Mode Select 00: Normal Mode 01: Single Mode 10: Continuous Mode
11:8	R/W	0x1	LEVELA_B_CNT Level A to Level B time threshold select Judge the ADC convert value from level A to level B in n+1 samples.
7	R/W	0x0	LRADC_HOLD_KEY_EN LRADC Hold KEY Enable 0: Disable 1: Enable
6	R/W	0x1	LRADC_CHANNEL_EN LRADC Channel Enable 0: Disable 1: Enable
5:4	R/W	0x2	LEVELB_VOL Level B Corresponding Data Value Setting (the real voltage value) 00: Reserved 01: 0x39 (1.221 V) 10: 0x36 (1.157 V) 11: 0x33 (1.093 V)
3:2	R/W	0x2	LRADC_SAMPLE_RATE LRADC Sample Rate 00: 2 kHz 01: 1 kHz 10: 500 Hz 11: 250 Hz
1	/	/	/

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Offset: 0x0000			Register Name: LRADC_CTRL
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	LRADC_EN LRADC Enable 0: Disable 1: Enable

10.10.6.2 0x0004 LRADC Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: LRADC_INTC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:5	/	/	/
4	R/W	0x0	ADC0_KEYUP_IRQ_EN ADC0 Key Up IRQ Enable 0: Disable 1: Enable
3	R/W	0x0	ADC0_ALRDY_HOLD_IRQ_EN ADC0 Already Hold Key IRQ Enable 0: Disable 1: Enable
2	R/W	0x0	ADC0_HOLD_IRQ_EN ADC0 Hold Key IRQ Enable 0: Disable 1: Enable
1	R/W	0x0	ADC0_KEYDOWN_EN ADC0 Key Down Enable 0: Disable 1: Enable
0	R/W	0x0	ADC0_DATA_IRQ_EN ADC0 Data IRQ Enable 0: Disable 1: Enable

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10.10.6.3 0x0008 LRADC Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x0008			Register Name: LRADC_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
31:5	/	/	/
4	R/W1C	0x0	ADC0_KEYUP_PENDING ADC0 Key up Pending Bit When the general key is pulled up, and the corresponding interrupt is enabled, the status bit is set. 0: No IRQ 1: IRQ Pending Writing 1 to the bit will clear it and its corresponding interrupt if the interrupt is enabled.
3	R/W1C	0x0	ADC0_ALRDY_HOLD_PENDING ADC0 Already Hold Pending Bit When the hold key is pulled down and the general key is pulled down, and the corresponding interrupt is enabled. 0: No IRQ 1: IRQ Pending Writing 1 to the bit will clear it and its corresponding interrupt if the interrupt is enabled.
2	R/W1C	0x0	ADC0_HOLDKEY_PENDING ADC0 Hold Key Pending Bit When the hold key is pulled down, and the corresponding interrupt is enabled, the status bit is set and the interrupt line is set. 0: NO IRQ 1: IRQ Pending Writing 1 to the bit will clear it and its corresponding interrupt if the interrupt is enabled.
1	R/W1C	0x0	ADC0_KEYDOWN_PENDING ADC0 Key Down IRQ Pending Bit When the general key is pulled down, and the corresponding interrupt is enabled, the status bit is set and the interrupt line is set. 0: No IRQ 1: IRQ Pending Writing 1 to the bit will clear it and its corresponding interrupt if the interrupt is enabled.

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Offset: 0x0008			Register Name: LRADC_INTS
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W1C	0x0	ADC0_DATA_PENDING ADC0 Data IRQ Pending Bit 0: No IRQ 1: IRQ Pending Writing 1 to the bit will clear it and its corresponding interrupt if the interrupt is enabled.

10.10.6.4 0x000C LRADC Data Register (Default Value: 0x0000_003F)

Offset: 0x000C			Register Name: LRADC_DATA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:6	/	/	/
5:0	R	0x3F	LRADC_DATA LRADC Data

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10.11 PWM

10.11.1 Overview

The Pulse Width Modulation (PWM) module can output the configurable PWM waveforms and measure the external input waveforms.

The PWM has the following features:

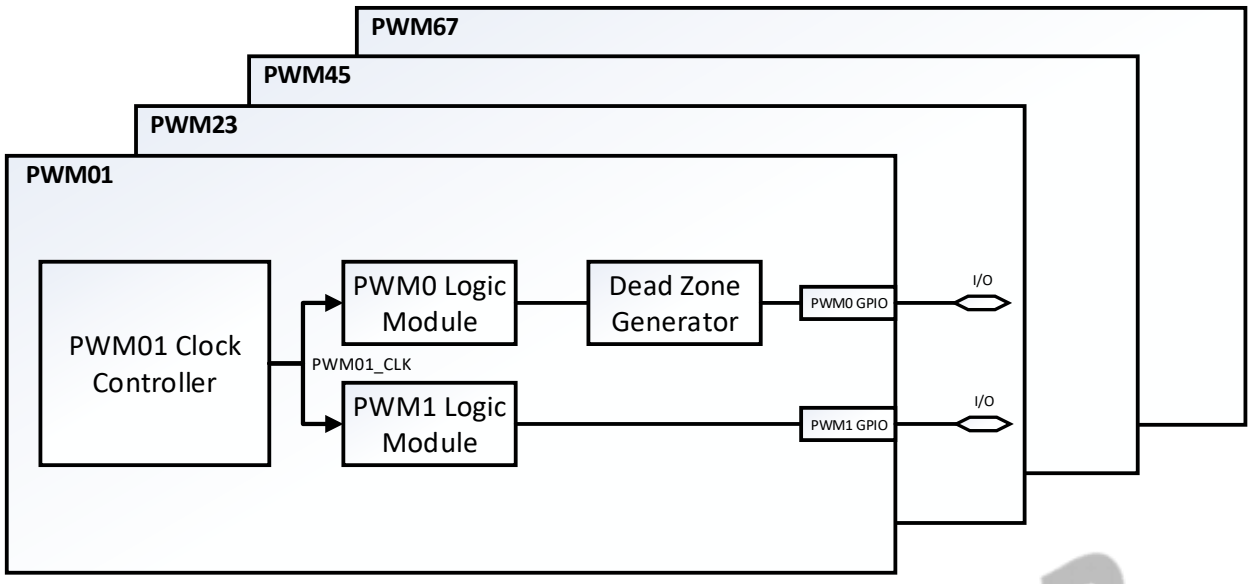
- Supports 8 independent PWM channels (PWM0 to PWM7)
  - Supports PWM continuous mode output
  - Supports PWM pulse mode output, and the pulse number is configurable
  - Output frequency range: 0 to 24 MHz or 100 MHz
  - Various duty-cycle: 0% to 100%
  - Minimum resolution: 1/65536
- Supports 4 complementary pairs output
  - PWM01 pair (PWM0 + PWM1), PWM23 pair (PWM2 + PWM3), PWM45 pair (PWM4 + PWM5), PWM67 pair (PWM6 + PWM7)
  - Supports dead-zone generator, and the dead-zone time is configurable
- Supports 4 group of PWM channel output for controlling stepping motors
  - Supports any plural channels to form a group, and output the same duty-cycle pulse
  - In group mode, the relative phase of the output waveform for each channel is configurable
- Supports 8 channels capture input
  - Supports rising edge detection and falling edge detection for input waveform pulse
  - Supports pulse-width measurement for input waveform pulse

10.11.2 Block Diagram

The PWM includes multi PWM channels. Each channel can generate different PWM waveform by the independent counter and duty-ratio configuration register. Each PWM pair shares one group of clock and dead-zone generator to generate PWM waveform.

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Figure 10-83 PWM Block Diagram



Each PWM pair consists of 1 clock module, 2 timer logic module, and 1 programmable dead-zone generator.

10.11.3 Functional Description

10.11.3.1 External Signals

The following table describes the external signals of the PWM.

Table 10-33 PWM External Signals

Signal	Description	Type
PWM0	Pulse Width Module Channel0	I/O
PWM1	Pulse Width Module Channel1	I/O
PWM2	Pulse Width Module Channel2	I/O
PWM3	Pulse Width Module Channel3	I/O
PWM4	Pulse Width Module Channel4	I/O
PWM5	Pulse Width Module Channel5	I/O
PWM6	Pulse Width Module Channel6	I/O
PWM7	Pulse Width Module Channel7	I/O

10.11.3.2 Typical Application

- Suitable for display device, such as LCD

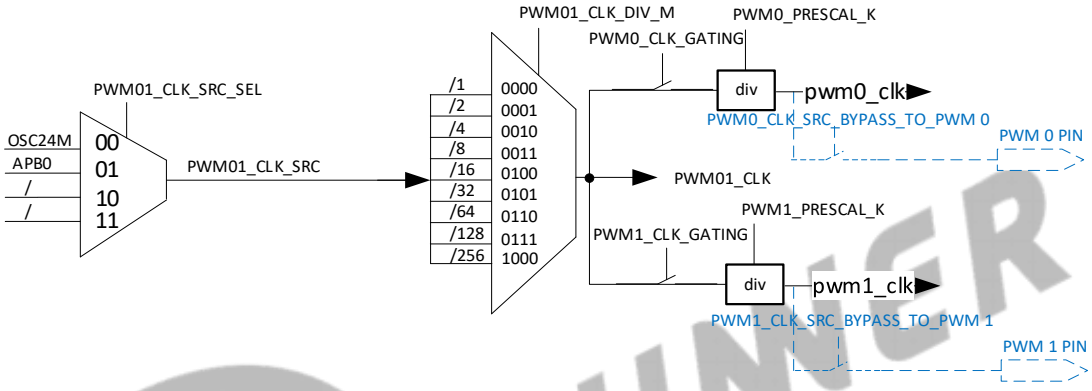
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- Suitable for electric motor control

10.11.3.3 Clock Controller

Using PWM01 as an example. The other PWM pairs are the same as PWM01.

Figure 10-84 PWM01 Clock Controller Diagram



The clock controller of each PWM pair includes clock source select (PWM01_CLK_SRC), 1~256 scaler (PWM01_CLK_DIV_M). Each PWM channel has the secondary frequency division (PWM_PRESCAL_K), clock source bypass (PWMx_CLK_BYPASS) and clock switch (PWMx_CLK_GATING).

The clock sources have HOSC and APB0. The HOSC comes from the external high-frequency oscillator; the APB0 is APB0 bus clock.

The bypass function of the clock source is that the clock source directly accesses PWM output, the PWM output waveform is the waveform of the clock controller output. The BYPASS gridlines in the above figure indicate the bypass function of the clock source, see Figure 10-85 for the details about implement. At last, the output clock of the clock controller is sent to the PWM logic module.

10.11.3.4 PWM Output

Taking PWM01 as an example, Figure 10-85 indicates the PWM01 output logic diagram. The logic diagrams of other PWM pairs are the same as PWM01.

The timer logic module of PWM consists of one 16-bit up-counter (**PCNTR**) and three 16-bit parameters (PWM_ENTIRE_CYCLE, PWM_ACT_CYCLE, PWM_COUNTER_START). The PWM_ENTIRE_CYCLE is used to

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control the PWM cycle, the PWM_ACT_CYCLE is used to control the duty-cycle, the PWM_COUNTER_START is used to control the output phase (multi-channel synchronization work requirements).

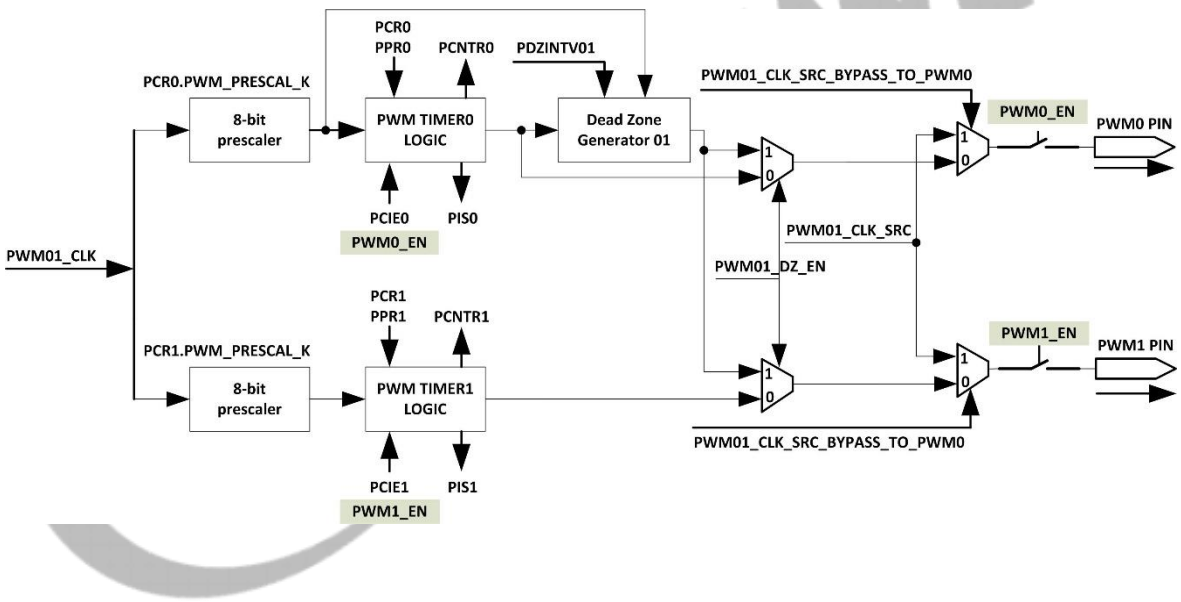
The PWM_ENTIRE_CYCLE and the PWM_ACT_CYCLE support the cache load, after PWM output is enabled, the register values of the PWM_ENTIRE_CYCLE and the PWM_ACT_CYCLE can be changed anytime, the changed value caches into the cache register. When the PCNTR counter outputs a period of PWM waveform, the value of the cache register can be updated for the PCNTR control. The purpose of the cache load is to avoid the unstable PWM output waveform with the burred feature when updating the values of the PWM_ENTIRE_CYCLE and PWM_ACT_CYCLE.

The PWM supports cycle and pulse waveform output.

Cycle mode: The PWM outputs the setting PWM waveform continually, that is, the output waveform is a continuous PWM square wave.

Pulse mode: After setting the PWM_PUL_NUM parameter, the PWM outputs (PWM_PULNUM+1) periods of PWM waveform, that is, the waveform with several pulses are output.

Figure 10-85 PWM01 Output Logic Module Diagram



10.11.3.5 Up-Counter and Comparator

The period, duty-cycle, and phase of PWM output waveform are decided by the **PCNTR**, PWM_ENTIRE_CYCLE, PWM_ACT_CYCLE, and PWM_COUNTER_START. The rules are as follows.

- PCNTR= (PCNTR==PWM_ENTIRE_CYCLE)?0 : PCNTR + 1
- PCNTR starts to count by PWM_COUNTER_START, the counter of a PWM period is (PWM_ENTIRE_CYCLE+1).
- PCNTR > (PWM_ENTIRE_CYCLE - PWM_ACT_CYCLE), output “active state”

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- PCNTR <= (PWM_ENTIRE_CYCLE - PWM_ACT_CYCLE), output "~ (active state)"

Active state of PWM0 channel is high level (PCR0. PWM_ACT_STA = 1)

When PCNTR0 > (PPR0. PWM_ENTIRE_CYCLE - PPR0.PWM_ACT_CYCLE), then PWM0 outputs 1 (high level).

When PCNTR0 <= (PPR0. PWM_ENTIRE_CYCLE - PPR0.PWM_ACT_CYCLE), then PWM0 outputs 0 (low level).

The formula of the output period and the duty-cycle for PWM are as follows.

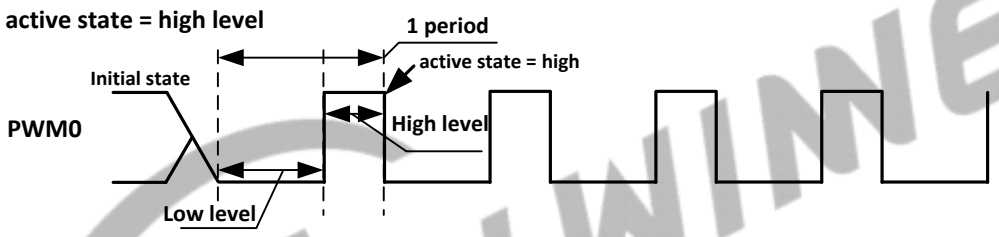
T_{period} = (PWM01_CLK / PWM0_PRESCALE_K)$^{-1}$ * (PPR0.PWM_ENTIRE_CYCLE + 1)

$T_{high\text{-}level}$ = (PWM01_CLK / PWM0_PRESCALE_K)$^{-1}$ * PPR0.PWM_ACT_CYCLE

$T_{low\text{-}level}$ = (PWM01_CLK / PWM0_PRESCALE_K)$^{-1}$ * (PPR0.PWM_ENTIRE_CYCLE + 1 - PPR0.PWM_ACT_CYCLE)

Duty-cycle = (high level time) / (1 period time) = $T_{high\text{-}level}$ / T_{period}

Figure 10-86 PWM0 High Level Active State



Active state of PWM0 channel is low level (PCR0. PWM_ACT_STA = 0)

When PCNTR0 > (PPR0.PWM_ENTIRE_CYCLE - PPR0.PWM_ACT_CYCLE), then PWM0 outputs 0.

When PCNTR0 <= (PPR0.PWM_ENTIRE_CYCLE - PPR0.PWM_ACT_CYCLE), then PWM0 outputs 1.

The formula of the output period and the duty-cycle for PWM are as follows.

T_{period} = (PWM01_CLK / PWM0_PRESCALE_K)$^{-1}$ * (PPR0.PWM_ENTIRE_CYCLE + 1)

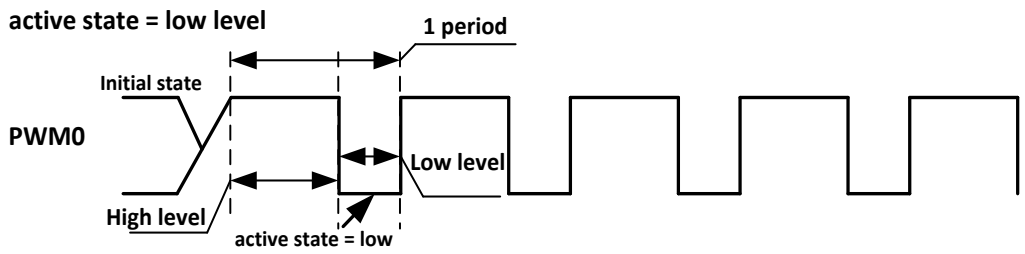
$T_{high\text{-}level}$ = (PWM01_CLK / PWM0_PRESCALE_K)$^{-1}$ * (PPR0.PWM_ENTIRE_CYCLE + 1 - PPR0.PWM_ACT_CYCLE)

$T_{low\text{-}level}$ = (PWM01_CLK / PWM0_PRESCALE_K)$^{-1}$ * PPR0.PWM_ACT_CYCLE

Duty-cycle = (low level time) / (1 period time) = $T_{low\text{-}level}$ / T_{period}

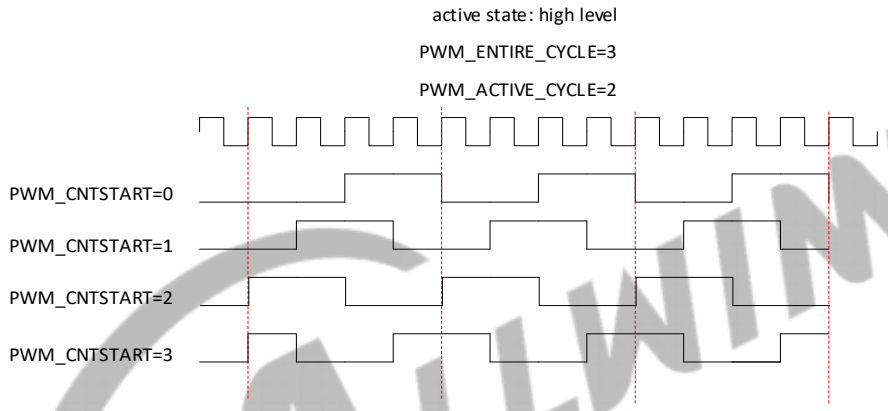
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Figure 10-87 PWM0 Low Level Active State



The counter of PCNTR starts from 0 by default, it can output the pulse control of the waveform by setting PWM_COUNTER_START. The figure is as follows.

Figure 10-88 Phase of PWM0 High Level Active State

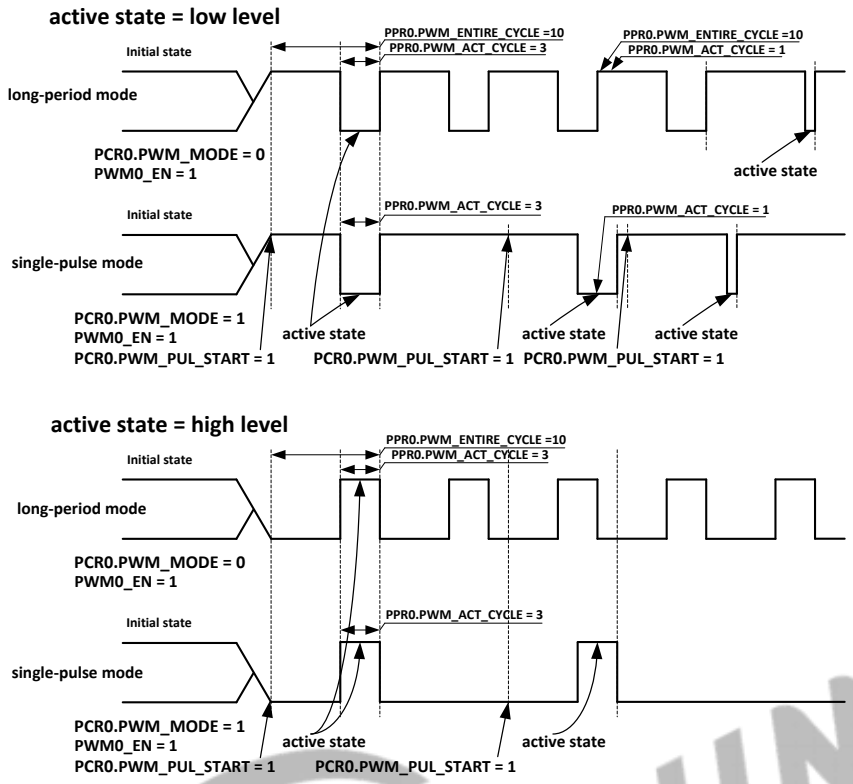


10.11.3.6 Pulse Mode and Cycle Mode

The PWM output supports pulse mode and cycle mode. PWM in pulse mode outputs one pulse waveform, but PWM in cycle mode outputs continuous waveform. Figure 10-89 shows the PWM output waveform in pulse mode and cycle mode.

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Figure 10-89 PWM0 Output Waveform in Pulse Mode and Cycle Mode



Each channel of the PWM module supports the PWM output of pulse mode and cycle mode, the active state of the PWM output waveform can be programmed to control.

When **PCR**0[PWM_MODE] is 0, the PWM0 outputs in cycle mode. When **PCR**0[PWM_MODE] is 1, the PWM0 outputs in pulse mode.

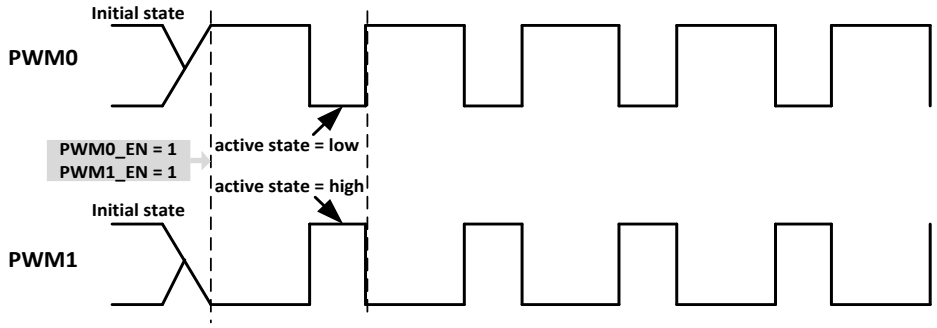
Specifically, in pulse mode, after the PWM0 channel enabled, **PCR**0[PWM_PUL_START] needs to be set to 1 when the PWM0 needs to output pulse waveform, after completed the output, **PCR**0[PWM_PUL_START] can be cleared to 0 by hardware. The next setting 1 can be operated after **PCR**0[PWM_PUL_START] is cleared.

10.11.3.7 Complementary Pair Output

Every PWM pair supports complementary pair output and PWM pair with dead-time. Figure 10-90 shows the complementary pair output of PWM01.

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Figure 10-90 PWM01 Complementary Pair Output



The complementary pair output needs to satisfy the following conditions:

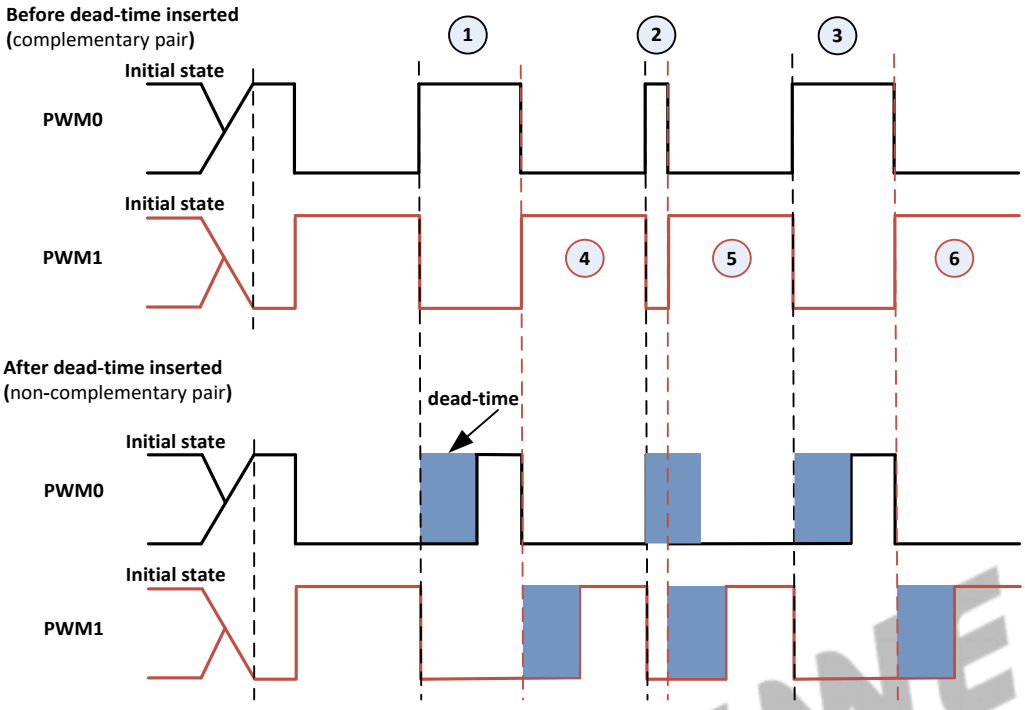
- PWM0 and PWM1 have the same clock divider, frequency, duty-cycle, and phase
- PWM0 and PWM1 have an opposite active state
- Enable the clock gating of PWM0 and PWM1 at the same time
- Enable the waveform output of PWM0 and PWM1 at the same time

10.11.3.8 Dead-time Generator

Every PWM pair has a programmable dead-time generator. When the dead-time function of the PWM pair enabled, the PWM01 output waveform is decided by PWM timer logic and DeadZone Generator. Figure 10-91 shows the output waveform.

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Figure 10-91 Dead-time Output Waveform



The PWM waveform before the insertion of dead-time indicates a complementary waveform pair of non-inserted dead-time in Dead Zone Generator 01.

The PWM waveform after the insertion of dead-time indicates a non-complementary PWM waveform pair inserted dead-time in a complementary waveform pair of Dead Zone Generator 01. The PWM waveform pair at last outputs to PWM0 pin and PWM1 pin.

For the complementary pair of Dead Zone Generator 01, the principle of inserting dead-time is that to insert dead-time as soon as the rising edge came. If the high level time for mark② in the above figure is less than dead-time, then dead-time will override the high level. The setting of dead-time needs to consider the period and the duty-cycle of the output waveform. The dead-time formula is defined as follows:

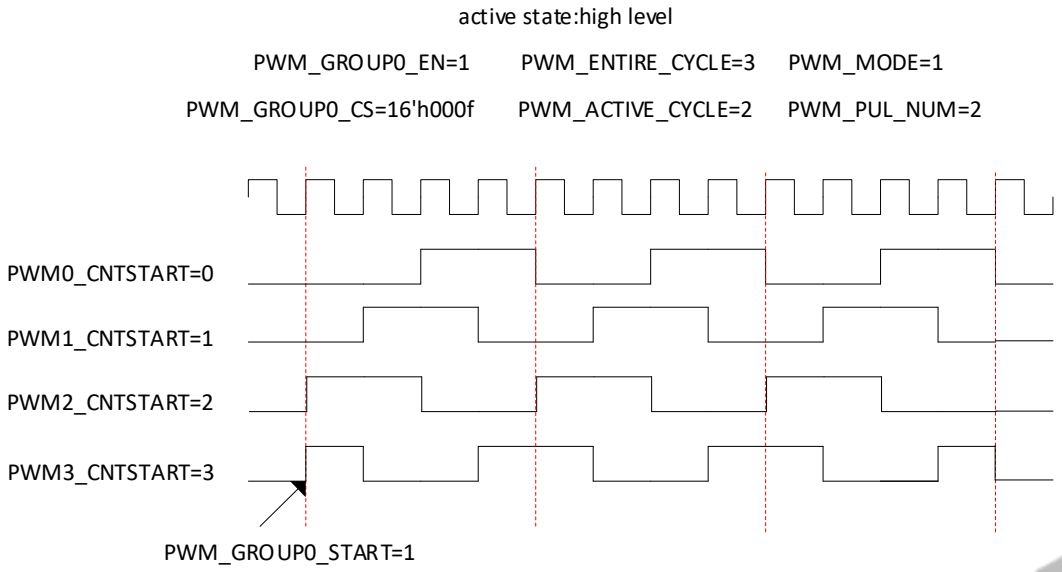
Dead-time = (PWM01_CLK / PWM0_PRESCALE_K)$^{-1}$ * PDZINTV01

10.11.3.9 PWM Group Mode

Taking PWM Group0 as an example. The same group of PWM channel is selected to work by PGR0.CS; the same PWM_ENTIRE_CYCLE, PWM_ACT_CYCLE are set by the same clock configuration; the different PWM_COUNTER_START can output PWM group signals with the same duty-cycle and the different phase.

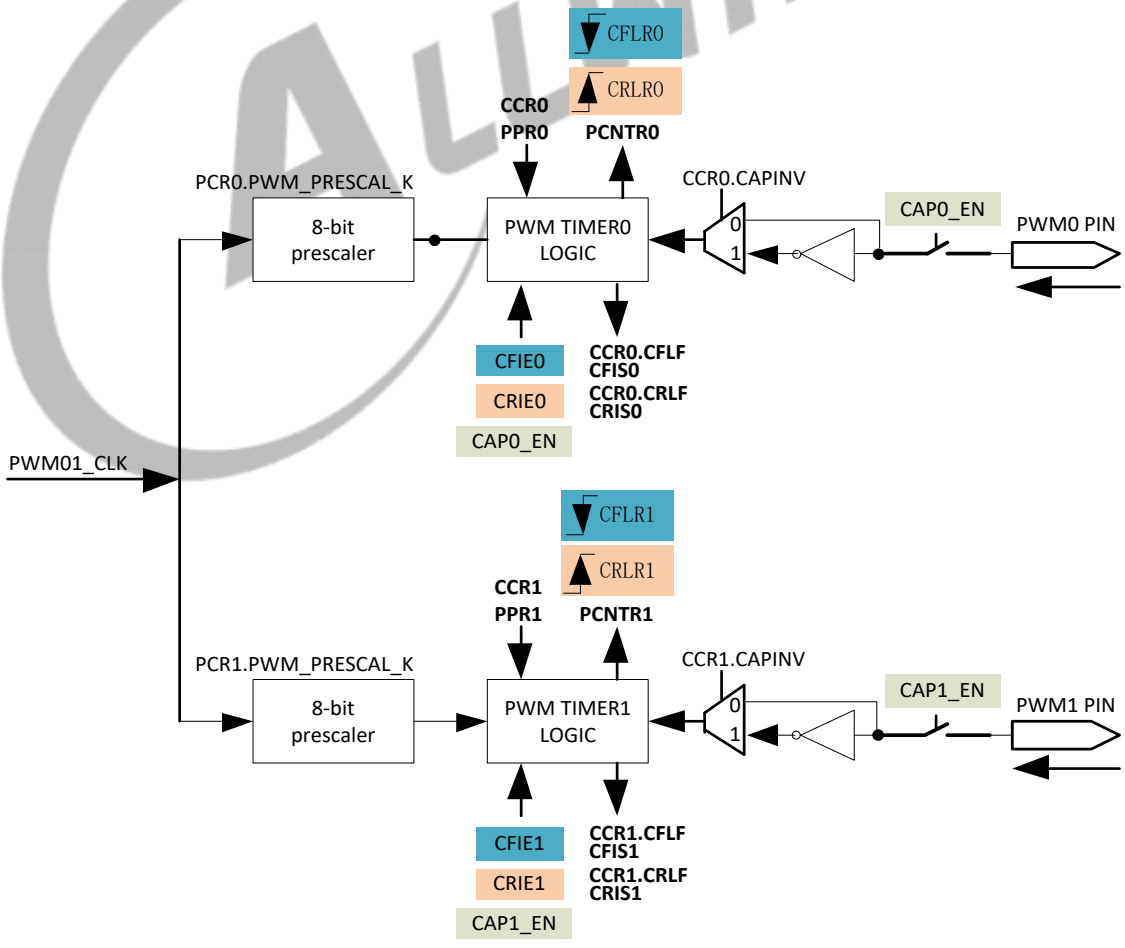
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Figure 10-92 Group 0~3 PWM Signal Output



10.11.3.10 Capture Input

Figure 10-93 PWM01 Capture Logic Module Diagram



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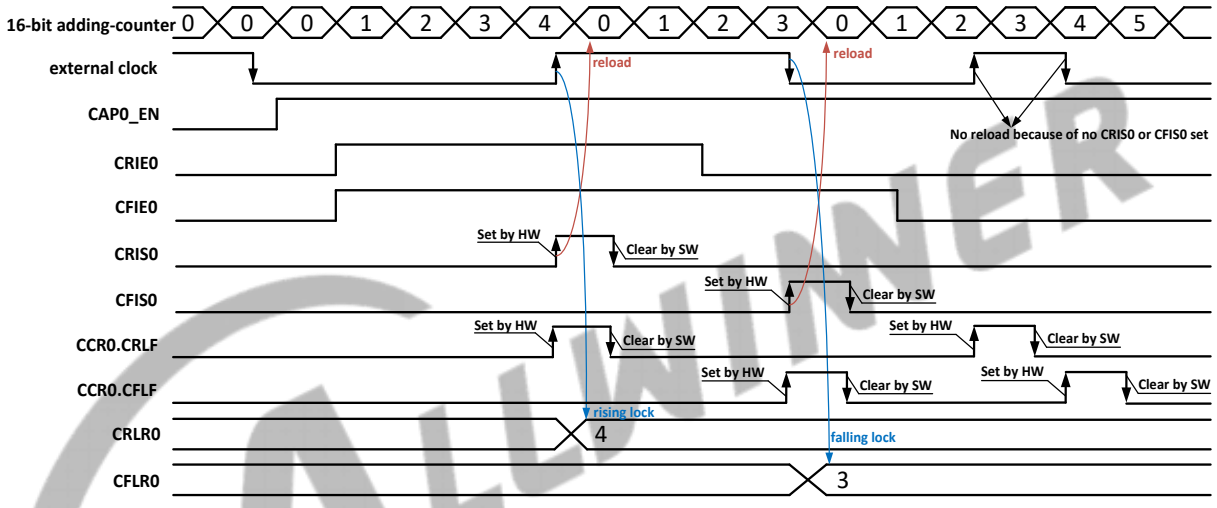
Besides the timer logic module of every PWM channel generates PWM output, it can be used to capture the rising edge and the falling edge of the external clock. Using the PWM0 channel as an example, the PWM0 channel has one **CFLR0** and one **CRLR0** for capturing up-counter value on the falling edge and rising edge, respectively. You can calculate the period of the external clock by **CFLR0** and **CRLR0**.

$T_{high\text{-}level}$ = (PWM01_CLK / PWM0_PRESCALE_K)$^{-1}$ * CRLR0

$T_{low\text{-}level}$ = (PWM01_CLK / PWM0_PRESCALE_K)$^{-1}$ * CFLR0

T_{period} = $T_{high\text{-}level}$ + $T_{low\text{-}level}$

Figure 10-94 PWM0 Channel Capture Timing



When the capture input function of the PWM0 channel is enabled, the PCNTR of the PWM0 channel starts to work.

When the timer logic module of PWM0 captures a rising edge, the current value of the up-counter is locked to **CRLR**0 and **CCR**0[CRLF] is set to 1. If CRIE0 is 1, then CRIS0 is set to 1, the PWM0 channel sends interrupt requests, and the up-counter is loaded to 0 and continues to count. If CRIE0 is 0, the timer logic module of PWM0 captures a rising edge, CRIS0 cannot be set to 1, the up-counter is not loaded to 0.

When the timer logic module of PWM0 captures one falling edge, the current value of PCNTR is locked to **CFLR**0 and **CCR**0[CFLF] is set to 1. If CFIE0 is 1, then CFIS0 is set to 1, the PWM0 channel sends interrupt requests, and the up-counter is loaded to 0 and continues to count. If CFIE0 is 0, the timer logic module of PWM0 captures a falling edge, CFIS0 cannot be set to 1, the up-counter is not loaded to 0.

10.11.3.11 Interrupt

The PWM supports an interrupt generation when configuring the PWM channel to PWM output or capturing input.

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For PWM output function, when the controller outputs one period of PWM waveform in cycle mode, the PIS of the corresponding PWM channel is set to 1; when the controller outputs (PWM_PULNUM+1) periods of PWM waveform in pulse mode, the PIS of the corresponding PWM channel is set to 1.

NOTE

The PIS bit is set to 1 automatically by hardware and cleared by software.

For capturing input function, when the timer logic module of the capture channel0 captures rising edge, and CRIE0 is 1, then CRIS0 is set to 1; when the timer logic module of the capture channel0 captures falling edge, and CFIE0 is 1, then CFIS0 is set to 1.

10.11.4 Programming Guidelines

The following working mode takes PWM01 as an example, other PWM pairs and PWM01 are consistent.

10.11.4.1 Configuring Clock

Step 1 PWM gating: When using PWM, write 1 to **PCGR**[PWMx_CLK_GATING].

Step 2 PWM clock source select: Set **PCCR01**[PWM01_CLK_SRC] to select HOSC or APB0 clock.

Step 3 PWM clock divider: Set **PCCR01**[PWM01_CLK_DIV_M] to select different frequency division coefficient (1/2/4/8/16/32/64/128/256).

Step 4 PWM clock bypass: Set **PCGR**[PWM_CLK_SRC_BYPASS_TO_PWM] to 1, output the PWM clock after the secondary frequency division to the corresponding PWM output pin.

Step 5 PWM internal clock configuration: Set **PCR**[PWM_PRESCAL_K] to select any frequency division coefficient from 1 to 256.

NOTE

For the channel of complementary output and group mode, firstly, set the same clock configurations (clock source selects APB0, clock division configures the same division factor); secondly, open clock gating at the same time; thirdly, configure PWM parameters; finally, enable PWM output at the same time to ensure each channel sync.

We suggest that the two channels of the same PWM pair cannot subject to two groups because of they have the same first level clock division and gating. If must allocate based on this way, the first level of clock division of the channel used by all groups needs to set to the same coefficient and open gating at the same time. And the total module needs to be reset when the group mode regroups.

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10.11.4.2 Configuring PWM

Step 1 PWM mode: Set **PCR**[PWM_MODE] to select cycle mode or pulse mode, if pulse mode, **PCR**[PWM_PUL_NUM] needs to be configured.

Step 2 PWM active level: Set **PCR**[PWM_ACT_STA] to select a low level or high level.

Step 3 PWM duty-cycle: Configure **PPR**[PWM_ENTIRE_CYCLE] and **PPR**[PWM_ACT_CYCLE] after clock gating is opened.

Step 4 PWM starting/stoping phase: Configure **PCNTR**[PWM_COUNTER_START] after the clock gating is enabled and before the PWM is enabled. You can verify whether the configuration was successful by reading back **PCNTR**[PWM_COUNTER_STATUS].

Step 5 Enable PWM: Configure PER to select the corresponding PWM enable bit; when selecting pulse mode, **PCR**[PWM_PUL_START] needs to be enabled.

10.11.4.3 Configuring Deadzone

Step 1 Set initial value: set [PDZINTV01].

Step 2 Enable Deadzone: set [PWM01_DZ_CN].

10.11.4.4 Configuring Capture Input

Step 1 Enable capture: Configure **CER** to enable the corresponding channel.

Step 2 Capture mode: Configure **CCR**[CRLF] and **CCR**[CFLF] to select rising edge capture or falling edge capture, configure **CCR**[CAPINV] to select whether the input signal does reverse processing.

10.11.5 Register List

Module Name	Base Address
PWM	0x02000C00

Register Name	Offset	Description
PIER	0x0000	PWM IRQ Enable Register
PISR	0x0004	PWM IRQ Status Register
CIER	0x0010	Capture IRQ Enable Register
CISR	0x0014	Capture IRQ Status Register

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Register Name	Offset	Description
PCCR01	0x0020	PWM01 Clock Configuration Register
PCCR23	0x0024	PWM23 Clock Configuration Register
PCCR45	0x0028	PWM45 Clock Configuration Register
PCCR67	0x002C	PWM67 Clock Configuration Register
PCGR	0x0040	PWM Clock Gating Register
PDZCR01	0x0060	PWM01 Dead Zone Control Register
PDZCR23	0x0064	PWM23 Dead Zone Control Register
PDZCR45	0x0068	PWM45 Dead Zone Control Register
PDZCR67	0x006C	PWM67 Dead Zone Control Register
PER	0x0080	PWM Enable Register
PGR0	0x0090	PWM Group0 Register
PGR1	0x0094	PWM Group1 Register
PGR2	0x0098	PWM Group2 Register
PGR3	0x009C	PWM Group3 Register
CER	0x00C0	Capture Enable Register
PCR	0x0100+0x0000+N*0x0020 (N= 0–7)	PWM Control Register
PPR	0x0100+0x0004+N*0x0020 (N= 0–7)	PWM Period Register
PCNTR	0x0100+0x0008+N*0x0020 (N= 0–7)	PWM Count Register
PPCNTR	0x0100+0x000C+N*0x0020 (N= 0–7)	PWM Pulse Count Register
CCR	0x0100+0x0010+N*0x0020 (N= 0–7)	Capture Control Register
CRLR	0x0100+0x0014+N*0x0020 (N= 0–7)	Capture Rise Lock Register
CFLR	0x0100+0x0018+N*0x0020 (N= 0–7)	Capture Fall Lock Register

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10.11.6 Register Description

10.11.6.1 0x0000 PWM IRQ Enable Register (Default Value: 0x0000_0000)

Offset:0x0000			Register Name: PIER
Bit	**Read/Write**	**Default/Hex**	**Description**
31:20	/	/	/
19	R/W	0x0	PGIE3 PWM Group 3 Interrupt Enable 0: Disable 1: Enable
18	R/W	0x0	PGIE2 PWM Group 2 Interrupt Enable 0: Disable 1: Enable
17	R/W	0x0	PGIE1 PWM Group 1 Interrupt Enable 0: Disable 1: Enable
16	R/W	0x0	PGIE0 PWM Group 0 Interrupt Enable 0: Disable 1: Enable
15:8	/	/	/
7	R/W	0x0	PCIE7 PWM Channel 7 Interrupt Enable 0: PWM Channel 7 Interrupt Disable 1: PWM Channel 7 Interrupt Enable
6	R/W	0x0	PCIE6 PWM Channel 6 Interrupt Enable 0: PWM Channel 6 Interrupt Disable 1: PWM Channel 6 Interrupt Enable
5	R/W	0x0	PCIE5 PWM Channel 5 Interrupt Enable 0: PWM Channel 5 Interrupt Disable 1: PWM Channel 5 Interrupt Enable

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Offset:0x0000			Register Name: PIER
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W	0x0	PCIE4 PWM Channel 4 Interrupt Enable 0: PWM Channel 4 Interrupt Disable 1: PWM Channel 4 Interrupt Enable
3	R/W	0x0	PCIE3 PWM Channel 3 Interrupt Enable 0: PWM Channel 3 Interrupt Disable 1: PWM Channel 3 Interrupt Enable
2	R/W	0x0	PCIE2 PWM Channel 2 Interrupt Enable 0: PWM Channel 2 Interrupt Disable 1: PWM Channel 2 Interrupt Enable
1	R/W	0x0	PCIE1 PWM Channel 1 Interrupt Enable 0: PWM Channel 1 Interrupt Disable 1: PWM Channel 1 Interrupt Enable
0	R/W	0x0	PCIE0 PWM Channel 0 Interrupt Enable 0: PWM Channel 0 Interrupt Disable 1: PWM Channel 0 Interrupt Enable

10.11.6.2 0x0004 PWM IRQ Status Register (Default Value: 0x0000_0000)

Offset:0x0004			Register Name: PISR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:20	/	/	/
19	R/W1C	0x0	PGIS3 PWM Group 3 Interrupt Status
18	R/W1C	0x0	PGIS2 PWM Group 2 Interrupt Status
17	R/W1C	0x0	PGIS1 PWM Group 1 Interrupt Status
16	R/W1C	0x0	PGIS0 PWM Group 0 Interrupt Status

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Offset:0x0004			Register Name: PISR
Bit	**Read/Write**	**Default/Hex**	**Description**
15:8	/	/	/
7	R/W1C	0x0	PIS7 PWM Channel 7 Interrupt Status When the PWM channel 7 counter reaches the Entire Cycle Value, this bit is set 1 by hardware. Writing 1 to clear this bit. Reads 0: PWM channel 7 interrupt is not pending. Reads 1: PWM channel 7 interrupt is pending. Writes 0: No effect. Writes 1: Clear PWM channel 7 interrupt status.
6	R/W1C	0x0	PIS6 PWM Channel 6 Interrupt Status When the PWM channel 6 counter reaches the Entire Cycle Value, this bit is set 1 by hardware. Writing 1 to clear this bit. Reads 0: PWM channel 6 interrupt is not pending. Reads 1: PWM channel 6 interrupt is pending. Writes 0: No effect. Writes 1: Clear PWM channel 6 interrupt status.
5	R/W1C	0x0	PIS5 PWM Channel 5 Interrupt Status When the PWM channel 5 counter reaches the Entire Cycle Value, this bit is set 1 by hardware. Writing 1 to clear this bit. Reads 0: PWM channel 5 interrupt is not pending. Reads 1: PWM channel 5 interrupt is pending. Writes 0: No effect. Writes 1: Clear PWM channel 5 interrupt status.
4	R/W1C	0x0	PIS4 PWM Channel 4 Interrupt Status When the PWM channel 4 counter reaches the Entire Cycle Value, this bit is set 1 by hardware. Writing 1 to clear this bit. Reads 0: PWM channel 4 interrupt is not pending. Reads 1: PWM channel 4 interrupt is pending. Writes 0: No effect. Writes 1: Clear PWM channel 4 interrupt status.

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Offset:0x0004			Register Name: PISR
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W1C	0x0	PIS3 PWM Channel 3 Interrupt Status When the PWM channel 3 counter reaches the Entire Cycle Value, this bit is set 1 by hardware. Writing 1 to clear this bit. Reads 0: PWM channel 3 interrupt is not pending. Reads 1: PWM channel 3 interrupt is pending. Writes 0: No effect. Writes 1: Clear PWM channel 3 interrupt status.
2	R/W1C	0x0	PIS2 PWM Channel 2 Interrupt Status When the PWM channel 2 counter reaches the Entire Cycle Value, this bit is set 1 by hardware. Writing 1 to clear this bit. Reads 0: PWM channel 2 interrupt is not pending. Reads 1: PWM channel 2 interrupt is pending. Writes 0: No effect. Writes 1: Clear PWM channel 2 interrupt status.
1	R/W1C	0x0	PIS1 PWM Channel 1 Interrupt Status When the PWM channel 1 counter reaches the Entire Cycle Value, this bit is set 1 by hardware. Writing 1 to clear this bit. Reads 0: PWM channel 1 interrupt is not pending. Reads 1: PWM channel 1 interrupt is pending. Writes 0: No effect. Writes 1: Clear PWM channel 1 interrupt status.
0	R/W1C	0x0	PIS0 PWM Channel 0 Interrupt Status When the PWM channel 0 counter reaches the Entire Cycle Value, this bit is set 1 by hardware. Writing 1 to clear this bit. Reads 0: PWM channel 0 interrupt is not pending. Reads 1: PWM channel 0 interrupt is pending. Writes 0: No effect. Writes 1: Clear PWM channel 0 interrupt status.

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10.11.6.3 0x0010 PWM Capture IRQ Enable Register (Default Value: 0x0000_0000)

Offset:0x0010			Register Name: CIER
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15	R/W	0x0	CFIE7 If the enable bit is set to 1, when the capture channel 7 captures falling edge, it generates a capture channel 7 pending. 0: Capture channel 7 fall lock interrupt disable 1: Capture channel 7 fall lock interrupt enable
14	R/W	0x0	CRIE7 If the enable bit is set to 1, when the capture channel 7 captures rising edge, it generates a capture channel 7 pending. 0: Capture channel 7 rise lock interrupt disable 1: Capture channel 7 rise lock interrupt enable
13	R/W	0x0	CFIE6 If the enable bit is set to 1, when the capture channel 6 captures falling edge, it generates a capture channel 6 pending. 0: Capture channel 6 fall lock interrupt disable 1: Capture channel 6 fall lock interrupt enable
12	R/W	0x0	CRIE6 If the enable bit is set to 1, when the capture channel 6 captures rising edge, it generates a capture channel 6 pending. 0: Capture channel 6 rise lock interrupt disable 1: Capture channel 6 rise lock interrupt enable
11	R/W	0x0	CFIE5 If the enable bit is set to 1, when the capture channel 5 captures falling edge, it generates a capture channel 5 pending. 0: Capture channel 5 fall lock interrupt disable 1: Capture channel 5 fall lock interrupt enable
10	R/W	0x0	CRIE5 If the enable bit is set to 1, when the capture channel 5 captures rising edge, it generates a capture channel 5 pending. 0: Capture channel 5 rise lock interrupt disable 1: Capture channel 5 rise lock interrupt enable

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Offset:0x0010			Register Name: CIER
Bit	**Read/Write**	**Default/Hex**	**Description**
9	R/W	0x0	CFIE4 If the enable bit is set to 1, when the capture channel 4 captures falling edge, it generates a capture channel 4 pending. 0: Capture channel 4 fall lock interrupt disable 1: Capture channel 4 fall lock interrupt enable
8	R/W	0x0	CRIE4 If the enable bit is set to 1, when the capture channel 4 captures rising edge, it generates a capture channel 4 pending. 0: Capture channel 4 rise lock interrupt disable 1: Capture channel 4 rise lock interrupt enable
7	R/W	0x0	CFIE3 If the enable bit is set to 1, when the capture channel 3 captures falling edge, it generates a capture channel 3 pending. 0: Capture channel 3 fall lock interrupt disable 1: Capture channel 3 fall lock interrupt enable
6	R/W	0x0	CRIE3 If the enable bit is set to 1, when the capture channel 3 captures rising edge, it generates a capture channel 3 pending. 0: Capture channel 3 rise lock interrupt disable 1: Capture channel 3 rise lock interrupt enable
5	R/W	0x0	CFIE2 If the enable bit is set to 1, when the capture channel 2 captures falling edge, it generates a capture channel 2 pending. 0: Capture channel 2 fall lock interrupt disable 1: Capture channel 2 fall lock interrupt enable
4	R/W	0x0	CRIE2 If the enable bit is set to 1, when the capture channel 2 captures rising edge, it generates a capture channel 2 pending. 0: Capture channel 2 rise lock interrupt disable 1: Capture channel 2 rise lock interrupt enable
3	R/W	0x0	CFIE1 If the enable bit is set to 1, when the capture channel 1 captures falling edge, it generates a capture channel 1 pending. 0: Capture channel 1 fall lock interrupt disable 1: Capture channel 1 fall lock interrupt enable

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Offset:0x0010			Register Name: CIER
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	CRIE1 If the enable bit is set to 1, when the capture channel 1 captures rising edge, it generates a capture channel 1 pending. 0: Capture channel 1 rise lock interrupt disable 1: Capture channel 1 rise lock interrupt enable
1	R/W	0x0	CFIE0 If the enable bit is set to 1, when the capture channel 0 captures falling edge, it generates a capture channel 0 pending. 0: Capture channel 0 fall lock interrupt disable 1: Capture channel 0 fall lock interrupt enable
0	R/W	0x0	CRIE0 If the enable bit is set to 1, when the capture channel 0 captures rising edge, it generates a capture channel 0 pending. 0: Capture channel 0 rise lock interrupt disable 1: Capture channel 0 rise lock interrupt enable

10.11.6.4 0x0014 PWM Capture IRQ Status Register (Default Value: 0x0000_0000)

Offset:0x0014			Register Name: CISR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
15	R/W1C	0x0	CFIS7 Status of the capture channel 7 falling lock interrupt When the capture channel 7 captures falling edge, if the fall lock interrupt (CFIE7) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 7 interrupt is not pending. Reads 1: The capture channel 7 interrupt is pending. Writes 0: No effect. Writes 1: Clear the status of the capture channel 7 interrupt.

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Offset:0x0014			Register Name: CISR
Bit	**Read/Write**	**Default/Hex**	**Description**
14	R/W1C	0x0	CRIS7 Status of the capture channel 7 rising lock interrupt When the capture channel 7 captures rising edge, if the rise lock interrupt (CRIE7) is enabled, this bit is set to 1 by hardware. Write 1 to clear this bit. Reads 0: The capture channel 7 interrupt is not pending. Reads 1: The capture channel 7 interrupt is pending. Writes 0: No effect. Writes 1: Clear the status of the capture channel 7 interrupt.
13	R/W1C	0x0	CFIS6 Status of the capture channel 6 falling lock interrupt When the capture channel 6 captures falling edge, if the fall lock interrupt (CFIE6) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 6 interrupt is not pending. Reads 1: The capture channel 6 interrupt is pending. Writes 0: No effect. Writes 1: Clear the status of the capture channel 6 interrupt.
12	R/W1C	0x0	CRIS6 Status of the capture channel 6 rising lock interrupt. When the capture channel 6 captures rising edge, if the rise lock interrupt (CRIE6) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 6 interrupt is not pending. Reads 1: The capture channel 6 interrupt is pending. Writes 0: No effect. Writes 1: Clear the status of the capture channel 6 interrupt.
11	R/W1C	0x0	CFIS5 Status of the capture channel 5 falling lock interrupt When the capturing channel 5 captures falling edge, if the fall lock interrupt (CFIE5) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 5 interrupt is not pending. Reads 1: The capture channel 5 interrupt is pending. Writes 0: No effect. Reads 1: Clear the status of the capture channel 5 interrupt.

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Offset:0x0014			Register Name: CISR
Bit	**Read/Write**	**Default/Hex**	**Description**
10	R/W1C	0x0	CRIS5 Status of the capture channel 5 rising lock interrupt When the capture channel 5 captures rising edge, if the rise lock interrupt (CRIE5) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 5 interrupt is not pending. Reads 1: The capture channel 5 interrupt is pending. Writes 0: No effect. Writes 1: Clear the status of the capture channel 5 interrupt.
9	R/W1C	0x0	CFIS4 Status of the capture channel 4 falling lock interrupt When the capture channel 4 captures falling edge, if the fall lock interrupt (CFIE4) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 4 interrupt is not pending. Reads 1: The capture channel 4 interrupt is pending. Writes 0: No effect. Writes 1: Clear the status of the capture channel 4 interrupt.
8	R/W1C	0x0	CRIS4 Status of the capture channel 4 rising lock interrupt. When the capture channel 4 captures rising edge, if the rise lock interrupt (CRIE4) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 4 interrupt is not pending. Reads 1: The capture channel 4 interrupt is pending. Writes 0: No effect. Writes 1: Clear the status of the capture channel 4 interrupt status.
7	R/W1C	0x0	CFIS3 Status of the capture channel 3 falling lock interrupt. When the capture channel 3 captures falling edge, if the fall lock interrupt (CFIE3) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 3 interrupt is not pending. Reads 1: The capture channel 3 interrupt is pending. Writes 0: no effect. Writes 1: Clear the status of the capture channel 3 interrupt.

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Offset:0x0014			Register Name: CISR
Bit	**Read/Write**	**Default/Hex**	**Description**
6	R/W1C	0x0	CRIS3 Status of the capture channel 3 rising lock interrupt When the capture channel 3 captures rising edge, if the rise lock interrupt (CRIE3) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 3 interrupt is not pending. Reads 1: The capture channel 3 interrupt is pending. Writes 0: no effect. Writes 1: Clear the status of the capture channel 3 interrupt.
5	R/W1C	0x0	CFIS2 Status of the capture channel 2 falling lock interrupt When the capture channel 2 captures falling edge, if the fall lock interrupt (CFIE2) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 2 interrupt is not pending. Reads 1: The capture channel 2 interrupt is pending. Writes 0: no effect. Writes 1: Clear the status of the capture channel 2 interrupt.
4	R/W1C	0x0	CRIS2 Status of the capture channel 2 rising lock interrupt. When the capture channel 2 captures rising edge, if the rise lock interrupt (CRIE2) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 2 interrupt is not pending. Reads 1: The capture channel 2 interrupt is pending. Writes 0: no effect. Writes 1: Clear the status of the capture channel 2 interrupt.
3	R/W1C	0x0	CFIS1 Status of the capture channel 1 falling lock interrupt When the capture channel 1 captures falling edge, if the fall lock interrupt (CFIE1) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 1 interrupt is not pending. Reads 1: The capture channel 1 interrupt is pending. Writes 0: no effect. Writes 1: Clear the status of the capture channel 1 interrupt.

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Offset:0x0014			Register Name: CISR
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W1C	0x0	CRIS1 Status of the capture channel 1 rising lock interrupt. When the capture channel 1 captures rising edge, if the rise lock interrupt (CRIE1) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 1 interrupt is not pending. Reads 1: The capture channel 1 interrupt is pending. Writes 0: no effect. Writes 1: Clear the status of the capture channel 1 interrupt.
1	R/W1C	0x0	CFIS0 Status of the capture channel 0 falling lock interrupt When the capture channel 0 captures falling edge, if the fall lock interrupt (CFIE0) is enabled, this bit is set to 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 0 interrupt is not pending. Reads 1: The capture channel 0 interrupt is pending. Writes 0: no effect. Writes 1: Clear the status of the capture channel 0 interrupt.
0	R/W1C	0x0	CRIS0 Status of the capture channel 0 rising lock interrupt When the capture channel 0 captures rising edge, if the rise lock interrupt (CRIE0) is enabled, this bit is set 1 by hardware. Writing 1 to clear this bit. Reads 0: The capture channel 0 interrupt is not pending. Reads 1: The capture channel 0 interrupt is pending. Writes 0: no effect. Writes 1: Clear the status of the capture channel 0 interrupt.

10.11.6.5 0x0020 PWM01 Clock Configuration Register (Default Value: 0x0000_0000)

Offset:0x0020			Register Name: PCCR01
Bit	**Read/Write**	**Default/Hex**	**Description**
31:9	/	/	/

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Offset:0x0020			Register Name: PCCR01
Bit	**Read/Write**	**Default/Hex**	**Description**
8:7	R/W	0x0	PWM01_CLK_SRC Select PWM01 Clock Source 00: HOSC 01: APB0 Others: Reserved
6:4	/	/	/
3:0	R/W	0x0	PWM01_CLK_DIV_M PWM01 Clock Divide M 0000: /1 0001: /2 0010: /4 0011: /8 0100: /16 0101: /32 0110: /64 0111: /128 1000: /256 Others: Reserved

10.11.6.6 0x0024 PWM23 Clock Configuration Register (Default Value: 0x0000_0000)

Offset:0x0024			Register Name: PCCR23
Bit	**Read/Write**	**Default/Hex**	**Description**
31:9	/	/	/
8:7	R/W	0x0	PWM23_CLK_SRC_SEL Select PWM23 Clock Source 00: HOSC 01: APB0 Others: Reserved
6:4	/	/	/

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Offset:0x0024			Register Name: PCCR23
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	PWM23_CLK_DIV_M PWM23 Clock Divide M 0000: /1 0001: /2 0010: /4 0011: /8 0100: /16 0101: /32 0110: /64 0111: /128 1000: /256 Others: Reserved

10.11.6.7 0x0028 PWM45 Clock Configuration Register (Default Value: 0x0000_0000)

Offset:0x0028			Register Name: PCCR45
Bit	**Read/Write**	**Default/Hex**	**Description**
31:9	/	/	/
8:7	R/W	0x0	PWM45_CLK_SRC_SEL Select PWM45 Clock Source 00: HOSC 01: APB0 Others: Reserved
6:4	/	/	/

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Offset:0x0028			Register Name: PCCR45
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	PWM45_CLK_DIV_M PWM45 Clock Divide M 0000: /1 0001: /2 0010: /4 0011: /8 0100: /16 0101: /32 0110: /64 0111: /128 1000: /256 Others: Reserved

10.11.6.8 0x002C PWM67 Clock Configuration Register (Default Value: 0x0000_0000)

Offset:0x002C			Register Name: PCCR67
Bit	**Read/Write**	**Default/Hex**	**Description**
31:9	/	/	/
8:7	R/W	0x0	PWM67_CLK_SRC_SEL Select PWM67 Clock Source 00: HOSC 01: APB0 Others: Reserved
6:4	/	/	/

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Offset:0x002C			Register Name: PCCR67
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	PWM67_CLK_DIV_M PWM67 Clock Divide M 0000: /1 0001: /2 0010: /4 0011: /8 0100: /16 0101: /32 0110: /64 0111: /128 1000: /256 Others: Reserved

10.11.6.9 0x0040 PWM Clock Gating Register (Default Value: 0x0000_0000)

Offset: 0x0040			Register Name: PCGR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:24	/	/	/
23	R/W	0x0	PWM7_CLK_BYPASS Bypass clock source (after pre-scale) to PWM7 output 0: not bypass 1: bypass
22	R/W	0x0	PWM6_CLK_BYPASS Bypass clock source (after pre-scale) to PWM6 output 0: not bypass 1: bypass
21	R/W	0x0	PWM5_CLK_BYPASS Bypass clock source (after pre-scale) to PWM5 output 0: not bypass 1: bypass
20	R/W	0x0	PWM4_CLK_BYPASS Bypass clock source (after pre-scale) to PWM4 output 0: not bypass 1: bypass

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Offset: 0x0040			Register Name: PCGR
Bit	**Read/Write**	**Default/Hex**	**Description**
19	R/W	0x0	PWM3_CLK_BYPASS Bypass clock source (after pre-scale) to PWM3 output 0: not bypass 1: bypass
18	R/W	0x0	PWM2_CLK_BYPASS Bypass clock source (after pre-scale) to PWM2 output 0: not bypass 1: bypass
17	R/W	0x0	PWM1_CLK_BYPASS Bypass clock source (after pre-scale) to PWM1 output 0: not bypass 1: bypass
16	R/W	0x0	PWM0_CLK_BYPASS Bypass clock source (after pre-scale) to PWM0 output 0: not bypass 1: bypass
15:8	/	/	/
7	R/W	0x0	PWM7_CLK_GATING Gating clock for PWM7 0: Mask 1: Pass
6	R/W	0x0	PWM6_CLK_GATING Gating clock for PWM6 0: Mask 1: Pass
5	R/W	0x0	PWM5_CLK_GATING Gating clock for PWM5 0: Mask 1: Pass
4	R/W	0x0	PWM4_CLK_GATING Gating clock for PWM4 0: Mask 1: Pass

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Offset: 0x0040			Register Name: PCGR
Bit	Read/Write	Default/Hex	Description
3	R/W	0x0	PWM3_CLK_GATING Gating clock for PWM3 0: Mask 1: Pass
2	R/W	0x0	PWM2_CLK_GATING Gating clock for PWM2 0: Mask 1: Pass
1	R/W	0x0	PWM1_CLK_GATING Gating clock for PWM1 0: Mask 1: Pass
0	R/W	0x0	PWM0_CLK_GATING Gating clock for PWM0 0: Mask 1: Pass

10.11.6.10 0x0060 PWM01 Dead Zone Control Register (Default Value: 0x0000_0000)

Offset:0x0060			Register Name: PDZCR01
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:8	R/W	0x0	PWM01_DZ_INTV PWM01 Dead Zone Interval Value
7:1	/	/	/
0	R/W	0x0	PWM01_DZ_EN PWM01 Dead Zone Enable 0: Dead Zone disable 1: Dead Zone enable

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10.11.6.11 0x0064 PWM23 Dead Zone Control Register (Default Value: 0x0000_0000)

Offset:0x0064			Register Name: PDZCR23
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:8	R/W	0x0	PWM23_DZ_INTV PWM23 Dead Zone Interval Value
7:1	/	/	/
0	R/W	0x0	PWM23_DZ_EN PWM23 Dead Zone Enable 0: Dead Zone disable 1: Dead Zone enable

10.11.6.12 0x0068 PWM45 Dead Zone Control Register (Default Value: 0x0000_0000)

Offset:0x0068			Register Name: PDZCR45
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:8	R/W	0x0	PWM45_DZ_INTV PWM45 Dead Zone Interval Value
7:1	/	/	/
0	R/W	0x0	PWM45_DZ_EN PWM45 Dead Zone Enable 0: Dead Zone disable 1: Dead Zone enable

10.11.6.13 0x006C PWM67 Dead Zone Control Register (Default Value: 0x0000_0000)

Offset:0x006C			Register Name: PDZCR67
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:8	R/W	0x0	PWM67_DZ_INTV PWM67 Dead Zone Interval Value
7:1	/	/	/

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Offset:0x006C			Register Name: PDZCR67
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	PWM67_DZ_EN PWM67 Dead Zone Enable 0: Dead Zone disable 1: Dead Zone enable

10.11.6.14 0x0080 PWM Enable Register (Default Value: 0x0000_0000)

Offset:0x0080			Register Name: PER
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	PWM7_EN When PWM is enabled, the 16-bit up-counter starts working and PWM channel7 is permitted to output PWM waveform. 0: PWM disable 1: PWM enable
6	R/W	0x0	PWM6_EN When PWM is enabled, the 16-bit up-counter starts working and PWM channel6 is permitted to output PWM waveform. 0: PWM disable 1: PWM enable
5	R/W	0x0	PWM5_EN When PWM is enabled, the 16-bit up-counter starts working and PWM channel5 is permitted to output PWM waveform. 0: PWM disable 1: PWM enable
4	R/W	0x0	PWM4_EN When PWM is enabled, the 16-bit up-counter starts working and PWM channel4 is permitted to output PWM waveform. 0: PWM disable 1: PWM enable
3	R/W	0x0	PWM3_EN When PWM is enabled, the 16-bit up-counter starts working and PWM channel3 is permitted to output PWM waveform. 0: PWM disable 1: PWM enable

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Offset:0x0080			Register Name: PER
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	PWM2_EN When PWM is enabled, the 16-bit up-counter starts working and PWM channel2 is permitted to output PWM waveform. 0: PWM disable 1: PWM enable
1	R/W	0x0	PWM1_EN When PWM is enabled, the 16-bit up-counter starts working and PWM channel1 is permitted to output PWM waveform. 0: PWM disable 1: PWM enable
0	R/W	0x0	PWM0_EN When PWM is enabled, the 16-bit up-counter starts working and PWM channel0 is permitted to output PWM waveform. 0: PWM disable 1: PWM enable

10.11.6.15 0x0090 PWM Group0 Register (Default Value: 0x0000_0000)

Offset: 0x0090			Register Name: PGR0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/WAC	0x0	PWMG0_START The PWM channels selected in **PWMG0_CS** start to output PWM waveform at the same time.
16	R/W	0x0	PWMG0_EN PWM Group0 Enable.
15:0	R/W	0x0	PWMG0_CS If bit[i] is set, the PWM i is selected as one channel of PWM Group0.

10.11.6.16 0x0094 PWM Group1 Register (Default Value: 0x0000_0000)

Offset: 0x0094			Register Name: PGR1
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/

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Offset: 0x0094			Register Name: PGR1
Bit	**Read/Write**	**Default/Hex**	**Description**
17	R/WAC	0x0	PWMG1_START The PWM channels selected in **PWMG1_CS** start to output PWM waveform at the same time.
16	R/W	0x0	PWMG1_EN PWM Group1 Enable.
15:0	R/W	0x0	PWMG1_CS If bit[i] is set, the PWM i is selected as one channel of PWM Group1.

10.11.6.17 0x0098 PWM Group2 Register (Default Value: 0x0000_0000)

Offset: 0x0098			Register Name: PGR2
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/WAC	0x0	PWMG2_START The PWM channels selected in **PWMG2_CS** start to output PWM waveform at the same time.
16	R/W	0x0	PWMG2_EN PWM Group2 Enable.
15:0	R/W	0x0	PWMG2_CS If bit[i] is set, the PWM i is selected as one channel of PWM Group2.

10.11.6.18 0x009C PWM Group3 Register (Default Value: 0x0000_0000)

Offset: 0x009C			Register Name: PGR3
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R/WAC	0x0	PWMG3_START The PWM channels selected in **PWMG3_CS** start to output PWM waveform at the same time.
16	R/W	0x0	PWMG3_EN PWM Group3 Enable.
15:0	R/W	0x0	PWMG3_CS If bit[i] is set, the PWM i is selected as one channel of PWM Group3.

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10.11.6.19 0x00C0 Capture Enable Register (Default Value: 0x0000_0000)

Offset: 0x00C0			Register Name: CER
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	CAP7_EN When enabling the capture function, the 16-bit up-counter starts working, and the capture channel7 is permitted to capture external falling edge or rising edge. 0: Capture disable 1: Capture enable
6	R/W	0x0	CAP6_EN When enabling the capture function, the 16-bit up-counter starts working, and the capture channel6 is permitted to capture external falling edge or rising edge. 0: Capture disable 1: Capture enable
5	R/W	0x0	CAP5_EN When enabling the capture function, the 16-bit up-counter starts working, and the capture channel5 is permitted to capture external falling edge or rising edge. 0: Capture disable 1: Capture enable
4	R/W	0x0	CAP4_EN When enabling the capture function, the 16-bit up-counter starts working, and the capture channel4 is permitted to capture external falling edge or rising edge. 0: Capture disable 1: Capture enable
3	R/W	0x0	CAP3_EN When enabling the capture function, the 16-bit up-counter starts working, and the capture channel3 is permitted to capture external falling edge or rising edge. 0: Capture disable 1: Capture enable

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Offset: 0x00C0			Register Name: CER
Bit	**Read/Write**	**Default/Hex**	**Description**
2	R/W	0x0	CAP2_EN When enabling the capture function, the 16-bit up-counter starts working, and the capture channel2 is permitted to capture external falling edge or rising edge. 0: Capture disable 1: Capture enable
1	R/W	0x0	CAP1_EN When enabling the capture function, the 16-bit up-counter starts working, and the capture channel1 is permitted to capture external falling edge or rising edge. 0: Capture disable 1: Capture enable
0	R/W	0x0	CAP0_EN When enabling the capture function, the 16-bit up-counter starts working, and the capture channel is permitted to capture external falling edge or rising edge. 0: Capture disable 1: Capture enable

10.11.6.20 0x0100 + N*0x20 PWM Control Register (Default Value: 0x0000_0000)

Offset:0x0100+0x0+N*0x20 (N=0~7)			Register Name: PCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0	PWM_PUL_NUM In pulse mode, the PWM outputs pulse for PWM_CYCLE_NUM+1 times and then stops.
15:12	/	/	/
11	R	0x0	PWM_PERIOD_RDY PWM Period Register Ready 0: PWM period register is ready to write 1: PWM period register is busy

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Offset:0x0100+0x0+N*0x20 (N=0~7)			Register Name: PCR
Bit	**Read/Write**	**Default/Hex**	**Description**
10	R/WAC	0x0	PWM_PUL_START PWM Pulse Output Start 0: No effect 1: Output pulse for PWM_CYCLE_NUM+1. After finishing configuration for the output pulse, set this bit once , then PWM would output waveform. After the waveform is finished, the bit will be cleared automatically.
9	R/W	0x0	PWM_MODE PWM Output Mode Select 0: Cycle mode 1: Pulse mode
8	R/W	0x0	PWM_ACT_STA PWM Active State 0: Low Level 1: High Level
7:0	R/W	0x0	PWM_PRESCAL_K PWM pre-scale K, actual pre-scale is (K+1). K = 0, actual pre-scale: 1 K = 1, actual pre-scale: 2 K = 2, actual pre-scale: 3 K = 3, actual pre-scale: 4 ... K = 255, actual pre-scale: 256

10.11.6.21 0x0104 + N*0x20 PWM Period Register (Default Value: 0x0000_0000)

Offset:0x0100+0x04+N*0x20 (N=0~7)			Register Name: PPR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0	PWM_ENTIRE_CYCLE Number of the entire cycles in the PWM clock. 0: 1 cycle 1: 2 cycles … N: N+1 cycles If the register needs to be modified dynamically, the PCLK should be faster than the PWM CLK.

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Offset:0x0100+0x04+N*0x20 (N=0~7)			Register Name: PPR
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R/W	0x0	PWM_ACT_CYCLE Number of the active cycles in the PWM clock. 0: 0 cycle 1: 1 cycle … N: N cycles

10.11.6.22 0x0108 + N*0x20 PWM Counter Register (Default Value: 0x0000_0000)

Offset:0x0100+0x08+N*0x20 (N=0~7)			Register Name: PCNTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	R/W	0x0	PWM_COUNTER_START PWM counter value is set for phase control.
15:0	R	0x0	PWM_COUNTER_STATUS On PWM output or capture input, reading this register could get the current value of the PWM 16-bit up-counter.

10.11.6.23 0x010C + N*0x20 PWM Pulse Counter Register (Default Value: 0x0000_0000)

Offset: 0x0100+0x0C+N*0x20 (N=0~7)			Register Name: PPCNTR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R	0x0	PWM_PUL_COUNTER_STATUS On PWM output, reading this register could get the current value of the PWM pulse counter.

10.11.6.24 0x0110 + N*0x20 PWM Capture Control Register (Default Value: 0x0000_0000)

Offset:0x0100+0x10+N*0x20 (N=0~7)			Register Name: CCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:5	/	/	/

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Offset:0x0100+0x10+N*0x20 (N=0~7)			Register Name: CCR
Bit	**Read/Write**	**Default/Hex**	**Description**
4	R/W1C	0x0	CRLF When the capture channel captures a rising edge, the current value of the 16-bit up-counter is latched to CRLR, and then this bit is set 1 by hardware. Write 1 to clear this bit.
3	R/W1C	0x0	CFLF When the capture channel captures a falling edge, the current value of the 16-bit up-counter is latched to CFLR, and then this bit is set 1 by hardware. Write 1 to clear this bit.
2	R/W	0x0	CRTE Rising edge capture trigger enable
1	R/W	0x0	CFTE Falling edge capture trigger enable
0	R/W	0x0	CAPINV Inverse the signal input from capture channel before 16-bit counter of capture channel. 0: not inverse 1: inverse

10.11.6.25 0x0114 + N*0x20 PWM Capture Rise Lock Register (Default Value: 0x0000_0000)

Offset:0x0100+0x14+N*0x20 (N=0~7)			Register Name: CRLR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:0	R	0x0	CRLR When the capture channel captures a rising edge, the current value of the 16-bit up-counter is latched to the register.

10.11.6.26 0x0118 + N*0x20 PWM Capture Fall Lock Register (Default Value: 0x0000_0000)

Offset:0x0100+0x18+N*0x20 (N=0~7)			Register Name: CFLR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/

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Offset:0x0100+0x18+N*0x20 (N=0~7)			Register Name: CFLR
Bit	**Read/Write**	**Default/Hex**	**Description**
15:0	R	0x0	CFLR When the capture channel captures a falling edge, the current value of the 16-bit up-counter is latched to the register.

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10.12 LEDC

10.12.1 Overview

The LEDC is used to control the external LED lamp.

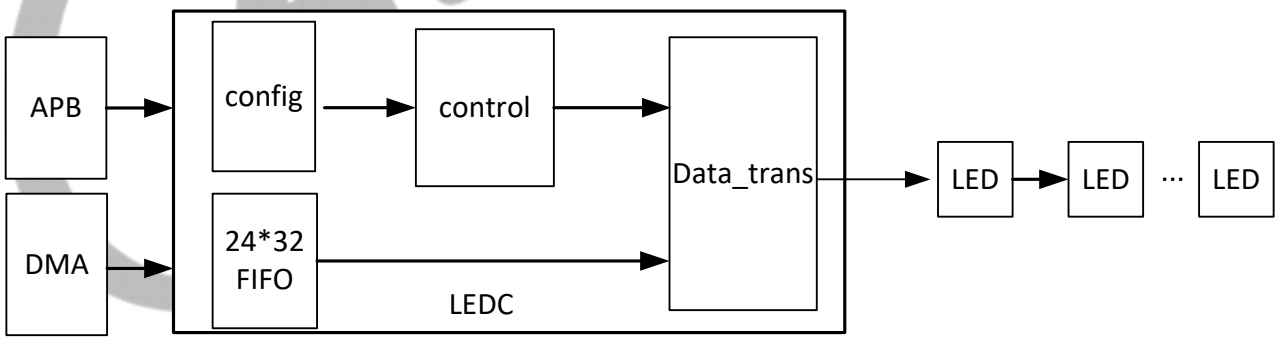
The LEDC has the following features:

- Configurable LED output high-/low-level width
- Configurable LED reset time
- LEDC data supports DMA configuration mode and CPU configuration mode
- Maximum 1024 LEDs serial connect
- LED data transfer rate up to 800 kbit/s
- Configurable RGB display mode
- The default level of non-data output is configurable

10.12.2 Block Diagram

The following figure shows a block diagram of the LEDC.

Figure 10-95 LEDC Block Diagram



LEDC contains the following sub-blocks:

Table 10-34 LEDC Sub-blocks

Sub-block	Description
config	register configuration
control	LEDC timing control and status control
FIFO	24-bit width x 32 depth
Data_trans	Convert input data to the 0 and 1 characters of LED

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10.12.3 Functional Description

10.12.3.1 External Signals

The following table describes the external signals of the LEDC.

Table 10-35 LEDC External Signals

Signal	Description	Type
LEDC-DO	Intelligent Control LED Signal Output	O

10.12.3.2 Clock Sources

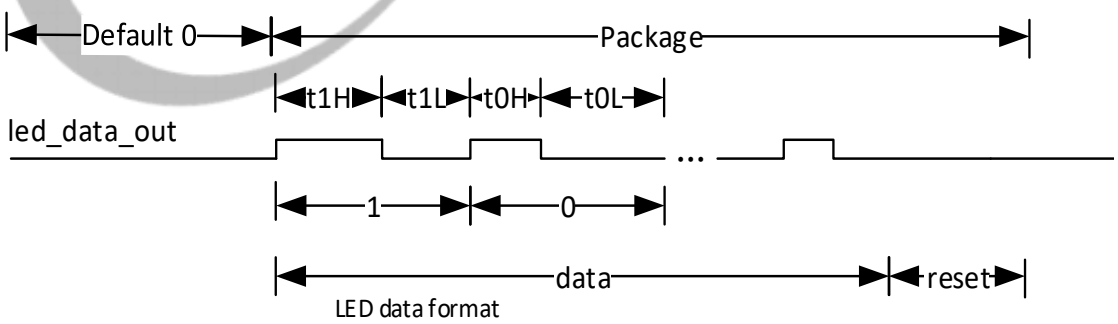
The following table describes the clock sources of the LEDC.

Table 10-36 LEDC Clock Sources

Clock Sources	Description
HOSC	24 MHz
PLL_PERI(1X)	Peripheral Clock. The default value is 600 MHz

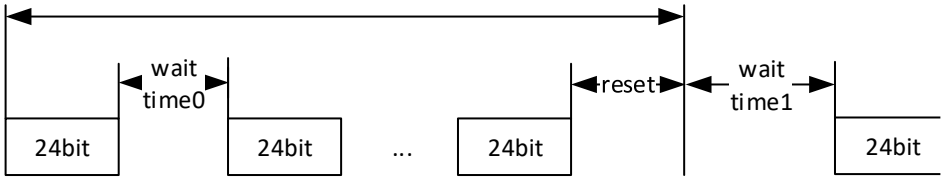
10.12.3.3 LEDC Timing

Figure 10-96 LEDC Package Output Timing Diagram



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Figure 10-97 LEDC 1-frame Output Timing Diagram



10.12.3.4 LEDC Input Data Structure

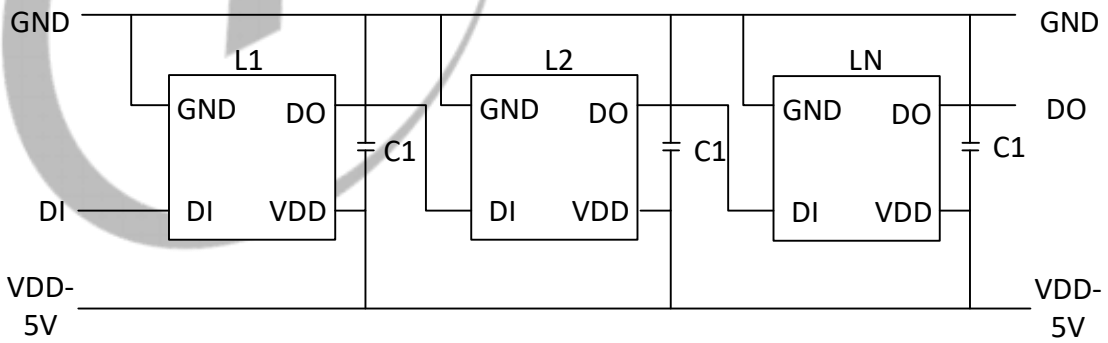
The RGB mode of LEDC data is configurable. By default, the data is sent in GRB order, and the higher bit is transmitted first.

Figure 10-98 LEDC Input Data Structure

G7	G6	G5	G4	G3	G2	G1	G0	R7	R6	R5	R4	R3	R2	R1	R0	B7	B6	B5	B4	B3	B2	B1	B0

10.12.3.5 LEDC Typical Circuit

Figure 10-99 LEDC Typical Circuit

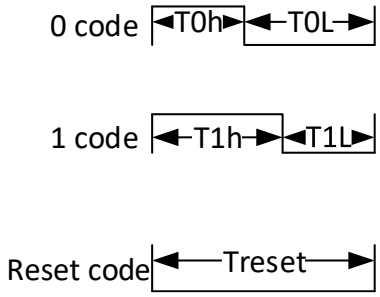


C1 is the bypass capacitor of LED light, and its value is usually 100 nF.

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10.12.3.6 LEDC Data Input Code

Figure 10-100 LEDC Data Input Code



10.12.3.7 LEDC Data Transfer Time

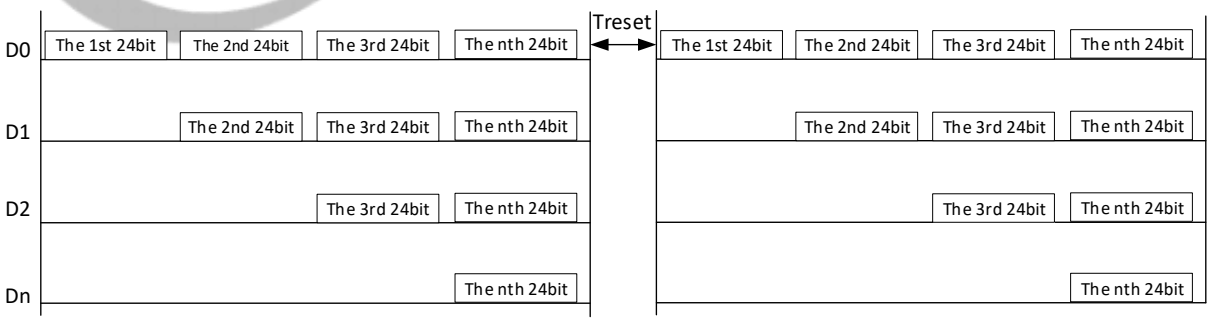
The time parameter of the typical LED specification shows as follows.

Table 10-37 Time Parameters of Typical LED Specification

T0H	0 code, high-level time	220 ns to 380 ns
T0L	0 code, low-level time	580 ns to 1.6 us
T1H	1 code, high-level time	580 ns to 1.6 us
T1L	1 code, low-level time	220 ns to 420 ns
RESET	Frame unit, low-level time	> 280 us

10.12.3.8 LEDC Data Transfer Mode

Figure 10-101 LEDC Data Transfer Mode



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10.12.3.9 LEDC Parameter

1. PAD rate > 800 kbit/s
2. LED number supported:

$T_{0\text{-}code}$: 800 ns to 1980 ns, $T_{1\text{-}code}$: 800 ns to 2020 ns

When the LED refresh rate is 30 frame/s, LED number supported is (1 s/30-280 us)/((800 ns to 2020 ns)*24) =1024 ↓to 681.

When the LED refresh rate is 60 frame/s, LED number supported is (1 s/60-280 us)/((800 ns to 2020 ns)*24) =853 ↓to 338.

10.12.3.10 LEDC Data Transfer

The LEDC supports DMA data transfer mode or CPU data transfer mode. The DMA data transfer mode is set by LEDC_DMA_EN

Data transfer in DMA mode

When the valid space of internal FIFO is greater than the setting FIFO free space threshold, the LEDC sends DMA_REQ to require DMA to transfer data from DRAM to LEDC. The maximum data transfer size in DMA mode is 16 words. (The internal FIFO level is 32.)

Data transfer in CPU mode

When the valid space of internal FIFO is greater than the setting FIFO free space threshold, the LEDC sends LEDC_CPUREQ_INT to require CPU to transfer data to LEDC. The transfer data size in CPU mode is controlled by software. The internal FIFO destination address is 0x06700014. The data width is 32-bit. (The lower 24-bit is valid.)

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10.12.3.11 LEDC Interrupt

Module Name	Description
FIFO_OVERFLOW_INT	FIFO overflow interrupt. The data written by external is more than the maximum storage space of LED FIFO, the LEDC will be in data loss state. At this time, software needs to deal with the abnormal situation. The processing mode is as follows. The software can query LED_FIFO_DATA_REG to determine which data has been stored in the internal FIFO of LEDC. The LEDC performs soft_reset operation to refresh all data.
WAITDATA_TIMEOUT_INT	Wait for data timeout interrupt When internal FIFO of LEDC cannot get data because of some abnormal situation, the timeout interrupt is set after led_wait_data_time, now the LEDC is in WAIT_DATA state, and the LEDC outputs a level state configured by LED_POLARITY; in the course of wait_data, if the new data arrives, the LEDC will continue to send data, at this time the software needs to notice whether the waiting time of the LEDC exceeds the operation time of reset. If the waiting time of the LEDC exceeds the operation time of reset (this is equivalent to reset operation sent by LEDC), the LED may enter in refresh state, the data has not been sent.
FIFO_CPUREQ_INT	FIFO request CPU data interrupt When FIFO data is less than a threshold, the interrupt will be reported to the CPU.
LEDC_TRANS_FINISH_INT	Data transfer complete interrupt The value indicates that the data configured as total_data_length has been transferred completely.

LEDC interrupt usage scenario:

CPU mode

The software can enable GLOBAL_INT_EN, FIFO_CPUREQ_INT_EN, WAITDATA_TIMEOUT_INT_EN, FIFO_OVERFLOW_INT_EN, LEDC_TRANS_FINISH_INT_EN, and cooperate with LEDC_FIFO_TRIG_LEVEL to use. When FIFO_CPUREQ_INT is set to 1, the software can configure data of LEDC_FIFO_TRIG_LEVEL to LEDC.

DMA mode

The software can enable GLOBAL_INT_EN, WAITDATA_TIMEOUT_INT_EN, FIFO_OVERFLOW_INT_EN, LEDC_TRANS_FINISH_INT_EN, and cooperate with LEDC_FIFO_TRIG_LEVEL to use. When DMA receives LEDC DMA_REQ, DMA can transfer data of LEDC_FIFO_TRIG_LEVEL to LEDC.

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10.12.4 Programming Guidelines

10.12.4.1 LEDC Normal Configuration Process

Step 1 Configure LEDC_CLK and bus pclk.

Step 2 Configure the written LEDC data.

Step 3 Configure LED_T01_TIMING_CTRL_REG, LEDC_DATA_FINISH_CNT_REG, LED_RESET_TIMING_CTRL_REG, LEDC_WAIT_TIME0_CTRL_REG, LEDC_DMA_CTRL_REG, LEDC_INTERRUPT_CTRL_REG. Configure 0-code, 1-code, reset time, LEDC waiting time, and the number of external connected LEDC and the threshold of DMA transfer data.

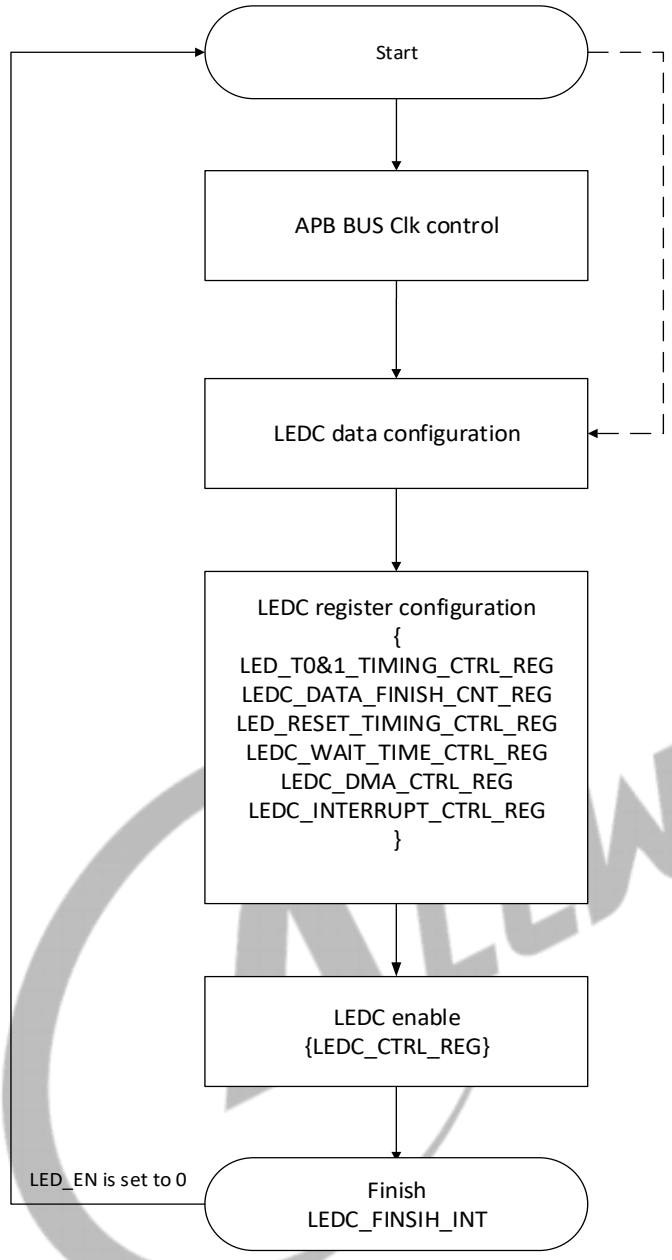
Step 4 Configure LEDC_CTRL_REG to enable LEDC_EN, the LEDC will start to output data.

Step 5 When the LEDC interrupt is pulled up, it indicates the configured data has transferred complete, at this time LED_EN will be set to 0, and the read/write point of LEDC FIFO is cleared to 0.

Step 6 Repeat step1, 2, 3, 4 to re-execute a new round of configuration, enable LEDC_EN, the LEDC will start new data transfer.

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Figure 10-102 LEDC Normal Configuration Process



10.12.4.2 LEDC Abnormal Scene Processing Flow

WAITDATA_TIMEOUT Abnormal Status

Step 1 When WAITDATA_TIMEOUT_INT appears, it indicates the internal FIFO data request of LEDC cannot obtain a response, at this time if the default output level is low, then the external LED may think there was a reset operation and cause LED data to be flushed incorrectly.

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Step 2 The LEDC needs to be performed soft_reset operation (LEDC_SOFT_RESET=1); after soft_reset, the LEDC_EN will be pulled-down automatically, all internal status register and control state machine will return to the idle state, the LEDC FIFO read & write point is cleared to 0, the LEDC interrupt is cleared.

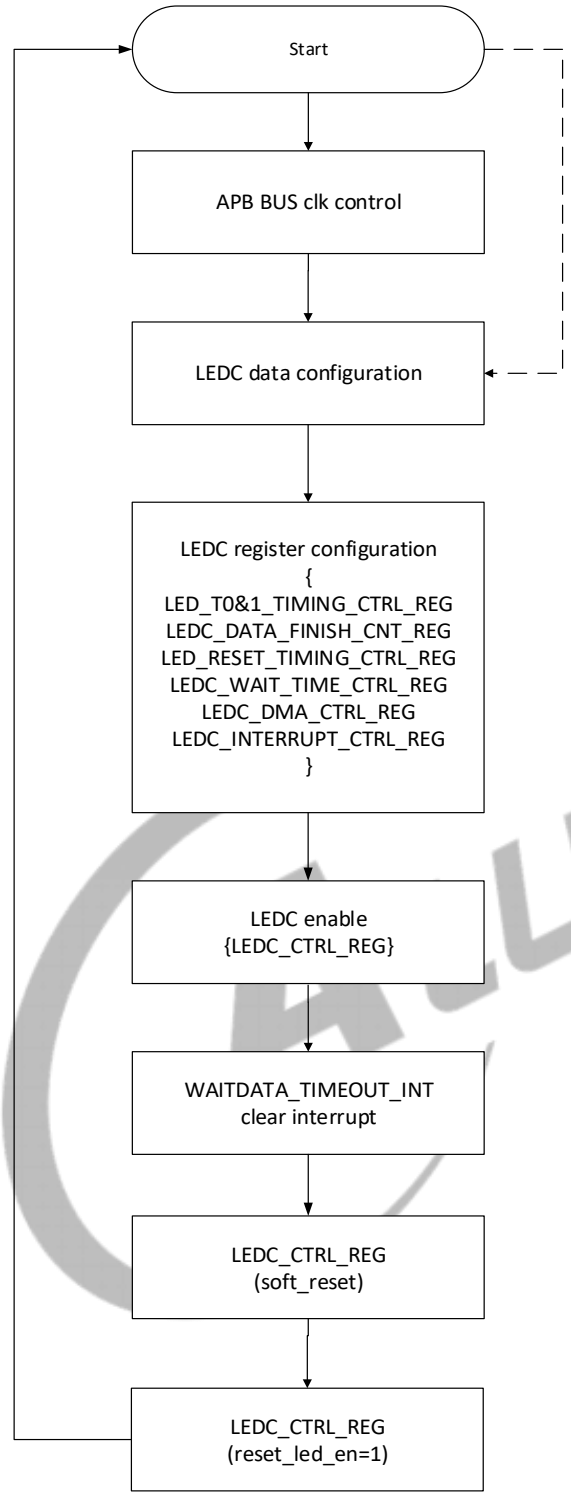
Step 3 Setting reset_led_en to 1 indicates LEDC can actively send a reset operation to ensure the external LED lamp in the right state.

Step 4 The software reads the status of reset_led_en, when the status value is 1, it indicates LEDC does not perform the transmission of LED reset operation; when the status value is 0, the LEDC completes the transmission of LED reset operation.

Step 5 When LEDC reset operation finishes, the LEDC data and register configuration need to be re-operated to start re-transmission data operation.

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Figure 10-103 LEDC Timeout Abnormal Processing Flow



FIFO Overflow Abnormal Status

Step 1 When FIFO_OVERFLOW_INT appears, it indicates the data configured by software exceeds the LEDC FIFO space, at this time the redundant data will be lost.

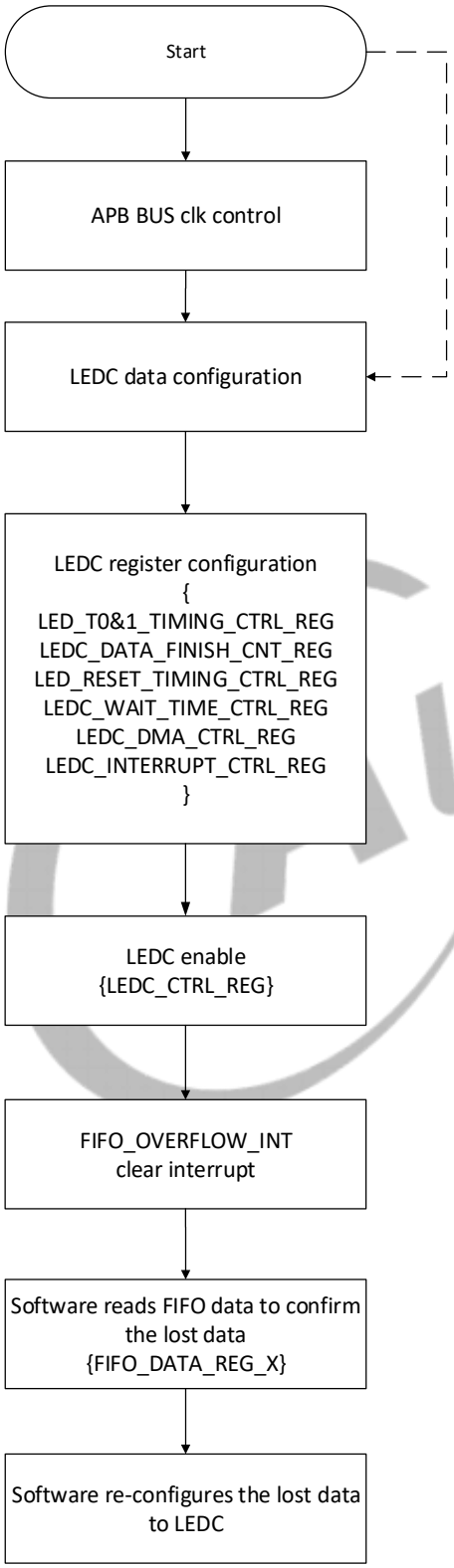
Step 2 The software needs to read data in **LEDC_FIFO_DATA_X** to confirm the lost data.

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Step 3 The software re-configures the lost data to the LEDC.

Step 4 If the software uses the soft_reset operation, the operation is the same with the timeout abnormal processing flow.

Figure 10-104 FIFO Overflow Abnormal Processing Flow



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10.12.5 Register List

Module Name	Base Address
LEDC	0x02008000

Register Name	Offset	Description
LEDC_CTRL_REG	0x0000	LEDC Control Register
LED_T01_TIMING_CTRL_REG	0x0004	LEDC T0 & T1 Timing Control Register
LEDC_DATA_FINISH_CNT_REG	0x0008	LEDC Data Finish Counter Register
LED_RESET_TIMING_CTRL_REG	0x000C	LEDC Reset Timing Control Register
LEDC_WAIT_TIME0_CTRL_REG	0x0010	LEDC Wait Time0 Control Register
LEDC_DATA_REG	0x0014	LEDC Data Register
LEDC_DMA_CTRL_REG	0x0018	LEDC DMA Control Register
LEDC_INT_CTRL_REG	0x001C	LEDC Interrupt Control Register
LEDC_INT_STS_REG	0x0020	LEDC Interrupt Status Register
LEDC_WAIT_TIME1_CTRL_REG	0x0028	LEDC Wait Time1 Control Register
LEDC_FIFO_DATA_REG	0x0030+0x04*N	LEDC FIFO Data Register

10.12.6 Register Description

10.12.6.1 0x0000 LEDC Control Register (Default Value: 0x0000_003C)

Offset: 0x0000			Register Name: LEDC_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x0	TOTAL_DATA_LENGTH Total length of transfer data (range: 0 to 8K, unit: 32-bit, only low 24-bit is valid) The field is recommended to be set to an integer multiple of (LED_NUM+1). If TOTAL_DATA_LENGTH is greater than (LED_NUM+1), but non-integer multiple, the last frame of data will transfer data less than (LED_NUM+1).
15:11	/	/	/
10	R/W	0x0	RESET_LED_EN Write operation:

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<table>
<tr><td colspan="3">Offset: 0x0000</td><td>Register Name: LEDC_CTRL_REG</td></tr>
<tr><td>Bit</td><td>Read/Write</td><td>Default/Hex</td><td>Description</td></tr>
<tr><td></td><td></td><td></td><td>The software writes 1 to the bit, the CPU triggers LEDC to transfer a reset to LED.
Only when LEDC is in IDLE status, the reset can be performed. After the reset finished, the control state machine returns to the IDLE status. To return LEDC to the IDLE status, it also needs to be used with SOFT_RESET.
When the software sets the bit, the software can read the bit to check if the reset is complete.
Read operation:
0: LEDC completes the transmission of the LED reset operation
1: LEDC does not complete the transmission of the LED reset operation</td></tr>
<tr><td>9</td><td>/</td><td>/</td><td>/</td></tr>
<tr><td>8:6</td><td>R/W</td><td>0x0</td><td>LED_RGB_MODE
000 GRB (bypass)
001 GBR
010 RGB
011 RBG
100 BGR
101 BRG
By default, the software configures data to LEDC according to GRB (MSB) mode, the LEDC internal combines data to output to the external LED.
Other modes configure as follows.
<table>
<tr><td>Software Input Mode</td><td>Configuration</td><td>LEDC Output Mode</td></tr>
<tr><td rowspan="6">GRB</td><td>000</td><td>GRB</td></tr>
<tr><td>001</td><td>GBR</td></tr>
<tr><td>010</td><td>RGB</td></tr>
<tr><td>011</td><td>RBG</td></tr>
<tr><td>100</td><td>BGR</td></tr>
<tr><td>101</td><td>BRG</td></tr>
<tr><td rowspan="4">GBR</td><td>000</td><td>GBR</td></tr>
<tr><td>001</td><td>GRB</td></tr>
<tr><td>010</td><td>BGR</td></tr>
<tr><td>011</td><td>BRG</td></tr>
</table></td></tr>
</table>

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<table>
<tr><td colspan="3">Offset: 0x0000</td><td colspan="3">Register Name: LEDC_CTRL_REG</td></tr>
<tr><td>Bit</td><td>Read/Write</td><td>Default/Hex</td><td colspan="3">Description</td></tr>
<tr><td></td><td></td><td></td><td></td><td>100</td><td>RGB</td></tr>
<tr><td></td><td></td><td></td><td></td><td>101</td><td>RBG</td></tr>
<tr><td></td><td></td><td></td><td rowspan="6">RGB</td><td>000</td><td>RGB</td></tr>
<tr><td></td><td></td><td></td><td></td><td>001</td><td>RBG</td></tr>
<tr><td></td><td></td><td></td><td></td><td>010</td><td>GRB</td></tr>
<tr><td></td><td></td><td></td><td></td><td>011</td><td>GBR</td></tr>
<tr><td></td><td></td><td></td><td></td><td>100</td><td>BRG</td></tr>
<tr><td></td><td></td><td></td><td></td><td>101</td><td>BGR</td></tr>
<tr><td></td><td></td><td></td><td rowspan="6">RBG</td><td>000</td><td>RBG</td></tr>
<tr><td></td><td></td><td></td><td></td><td>001</td><td>RGB</td></tr>
<tr><td></td><td></td><td></td><td></td><td>010</td><td>BRG</td></tr>
<tr><td></td><td></td><td></td><td></td><td>011</td><td>BGR</td></tr>
<tr><td></td><td></td><td></td><td></td><td>100</td><td>GRB</td></tr>
<tr><td></td><td></td><td></td><td></td><td>101</td><td>GBR</td></tr>
<tr><td></td><td></td><td></td><td rowspan="6">BGR</td><td>000</td><td>BGR</td></tr>
<tr><td></td><td></td><td></td><td></td><td>001</td><td>BRG</td></tr>
<tr><td></td><td></td><td></td><td></td><td>010</td><td>GBR</td></tr>
<tr><td></td><td></td><td></td><td></td><td>011</td><td>GRB</td></tr>
<tr><td></td><td></td><td></td><td></td><td>100</td><td>RBG</td></tr>
<tr><td></td><td></td><td></td><td></td><td>101</td><td>RGB</td></tr>
<tr><td></td><td></td><td></td><td rowspan="6">BRG</td><td>000</td><td>BRG</td></tr>
<tr><td></td><td></td><td></td><td></td><td>001</td><td>BGR</td></tr>
<tr><td></td><td></td><td></td><td></td><td>010</td><td>RBG</td></tr>
<tr><td></td><td></td><td></td><td></td><td>011</td><td>RGB</td></tr>
<tr><td></td><td></td><td></td><td></td><td>100</td><td>GBR</td></tr>
<tr><td></td><td></td><td></td><td></td><td>101</td><td>GRB</td></tr>
<tr><td>5</td><td>R/W</td><td>0x1</td><td colspan="3">LED_MSB_TOP
Adjust sequence of the combined GRB data
0: LSB
1: MSB</td></tr>
<tr><td>4</td><td>R/W</td><td>0x1</td><td colspan="3">LED_MSB_G
MSB control for Green data
0: LSB</td></tr>
</table>

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Offset: 0x0000			Register Name: LEDC_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
			1: MSB
3	R/W	0x1	LED_MSB_R MSB control for Red data 0: LSB 1: MSB
2	R/W	0x1	LED_MSB_B MSB control for Blue data 0: LSB 1: MSB
1	R/W1C	0x0	LEDC_SOFT_RESET LEDC soft reset Write 1 to clear it automatically. The ranges of LEDC soft reset include the following points: all internal status registers, the control state machine returns to in idle status, the LEDC FIFO read & write point is cleared to 0, the LEDC interrupt is cleared; and the affected registers are followed. 1.LEDC_CTRL_REG (LEDC_EN is cleared to 0); 2. PLL_T0&1_TIMING_CTRL_REG remains unchanged; 3. LEDC_DATA_FINISH_CNT_REG (LEDC_DATA_FINISH_CNT is cleared to 0); 4.LED_RESET_TIMING_CTRL_REG remains unchanged; 5. LEDC_WAIT_TIME_CTRL_REG remains unchanged; 6. LEDC_DMA_CTRL_REG remains unchanged; 7. LEDC_INTERRUPT_CTRL_REG remains unchanged; 8.LEDC_INT_STS _REG is cleared to 0; 9. LEDC_CLK_GATING_REG remains unchanged; 10.LEDC_FIFO_DATA_REG remains unchanged;
0	R/W	0x0	LEDC_EN LEDC Enable 0: Disable 1: Enable That the bit is enabled indicates LEDC can be started when LEDC data finished transmission or LEDC_EN is cleared to 0 by hardware in LEDC_SOFT_RESET situation.

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10.12.6.2 0x0004 LEDC T0 & T1 Timing Control Register (Default Value: 0x0286_01D3)

Offset: 0x0004			Register Name: LED_T01_TIMING_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:27	/	/	/
26:21	R/W	0x14	T1H_TIME LED T1H time Unit: cycle (24 MHz), T1H_TIME =42 ns*(N+1) The default value is 882 ns, the range is 80 ns–2560 ns. N: 1–3F. When is 0, T1H_TIME = 3F
20:16	R/W	0x6	T1L_TIME LED T1L time Unit: cycle (24 MHz), T1L_TIME =42 ns*(N+1) The default value is 294 ns, the range is 80 ns–1280 ns. N: 1–1F. When is 0, T1L_TIME = 1F
15:11	/	/	/
10:6	R/W	0x7	T0H_TIME LED T0h time Unit: cycle (24 MHz), T0H_TIME =42 ns*(N+1) The default value is 336 ns, the range is 80 ns–1280 ns. N: 1–1F. When is 0, T0H_TIME = 1F
5:0	R/W	0x13	T0L_TIME LED T0l time Unit: cycle (24 MHz), T0L_TIME =42 ns*(N+1) The default value is 840 ns, the range is 80 ns–2560 ns. N: 1–3F. When is 0, T0L_TIME = 3F

10.12.6.3 0x0008 LEDC Data Finish Counter Register (Default Value: 0x1D4C_0000)

Offset: 0x0008			Register Name: LEDC_DATA_FINISH_CNT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:30	/	/	/

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Offset: 0x0008			Register Name: LEDC_DATA_FINISH_CNT_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
29:16	R/W	0x1D4C	LED_WAIT_DATA_TIME The value is the time that internal FIFO in LEDC is waiting for data. When the time is exceeded, the LEDC will send the wait_data_timeout_int interrupt. (This is an abnormal situation, software needs to reset LEDC.) The value is about 300 us by default. The adjust range is 80 ns–655 us. led_wait_data_time=42ns*(N+1). N: 1–1FFF. When the field is 0, LEDC_WAIT_DATA_TIME=1FFF
15:13	/	/	/
12:0	R	0x0	LED_DATA_FINISH_CNT The value is the total LED data that have been sent. (Range: 0–8k)

10.12.6.4 0x000C LEDC Reset Timing Control Register (Default Value: 0x1D4C_0000)

Offset: 0x000C			Register Name: LED_RESET_TIMING_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:29	/	/	/
28:16	R/W	0x1D4C	TR_TIME Reset time control of LED lamp Unit: cycle (24 MHz), tr_time=42 ns*(N+1) The default value is 300 us. The adjust range is 80 ns–327 us. N: 1–1FFF
15:10	/	/	/
9:0	R/W	0x0	LED_NUM The value is the number of external LED lamp. Maximum up to 1024. The default value 0 indicates that 1 LED lamp is external connected. The range is from 0 to 1023.

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10.12.6.5 0x0010 LEDC Wait Time 0 Control Register (Default Value: 0x0000_00FF)

Offset: 0x0010			Register Name: LEDC_WAIT_TIME0_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:9	/	/	/
8	R/W	0x0	WAIT_TIM0_EN WAIT_TIME0 enable When it is 1, the controller automatically inserts waiting time between LED package data. 0: Disable 1: Enable
7:0	R/W	0xFF	TOTAL_WAIT_TIME0 Waiting time between 2 LED data. The LEDC output is low level. The adjust range is 80 ns–10 us. wait_time0=42 ns*(N+1) Unit: cycle(24 MHz) N: 1–FF

10.12.6.6 0x0014 LEDC Data Register (Default Value: 0x0000_0000)

Offset: 0x0014			Register Name: LEDC_DATA_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	W	0x0	LEDC DATA LED display data (the lower 24-bit is valid)

10.12.6.7 0x0018 LEDC DMA Control Register (Default Value: 0x0000_002F)

Offset: 0x0018			Register Name: LEDC_DMA_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:6	/	/	/
5	R/W	0x1	LEDC_DMA_EN LEDC DMA request enable 0: Disable request of DMA transfer data 1: Enable request of DMA transfer data

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Offset: 0x0018			Register Name: LEDC_DMA_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
4:0	R/W	0x0F	LEDC_FIFO_TRIG_LEVEL The remaining space of internal FIFO in LEDC The internal FIFO in LEDC is 24*32. When the remaining space of internal FIFO in LEDC is more than or equal to LEDFIFO_TRIG_LEVEL, the DMA or the CPU request will generate. The default value is 15. The adjusted value is from 1 to 31. The recommended configuration is 7 or 15. When the configuration value is 0, LEDFIFO_TRIG_LEVEL=F.

10.12.6.8 0x001C LEDC Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: LEDC_INTERRUPT_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:6	/	/	/
5	R/W	0x0	GLOBAL_INT_EN Global interrupt enable 0: Disable 1: Enable
4	R/W	0x0	FIFO_OVERFLOW_INT_EN FIFO overflow interrupt enable When the data written by the software is more than the internal FIFO level of LEDC, the LEDC is in the data loss state. 0: Disable 1: Enable
3	R/W	0x0	WAITDATA_TIMEOUT_INT_EN The internal FIFO in LEDC cannot get data because of some abnormal situation, after the time of led_wait_data_time, the interrupt will be enabled. 0: Disable 1: Enable
2	/	/	/
1	R/W	0x0	FIFO_CPUREQ_INT_EN FIFO request CPU data interrupt enable 0: Disable 1: Enable

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Offset: 0x001C			Register Name: LEDC_INTERRUPT_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	LED_TRANS_FINISH_INT_EN Data transmission complete interrupt enable 0: Disable 1: Enable

10.12.6.9 0x0020 LEDC Interrupt Status Register (Default Value: 0x0002_0000)

Offset: 0x0020			Register Name: LEDC_INT_STS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:18	/	/	/
17	R	0x1	FIFO_EMPTY FIFO empty status flag
16	R	0x0	FIFO_FULL FIFO full status flag
15:10	R	0x0	FIFO_WLW FIFO internal valid data depth It indicates the space FIFO has been occupied.
9:5	/	/	/
4	R/W1C	0x0	FIFO_OVERFLOW_INT FIFO overflow interrupt The data written by external is more than the maximum storage space of LED FIFO, the LEDC will be in the data loss state. At this time, the software needs to deal with the abnormal situation. The processing mode is as follows. (1) The software can query LED_FIFO_DATA_REG to determine which data has been stored in the internal FIFO of LEDC. (2) The LEDC performs soft_reset operation to refresh all data. 0: FIFO not overflow 1: FIFO overflow

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Offset: 0x0020			Register Name: LEDC_INT_STS_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R/W1C	0x0	WAITDATA_TIMEOUT_INT When internal FIFO of LEDC cannot get data because of some abnormal situation, after led_wait_data_time, the timeout interrupt is set, the LEDC is in WAIT_DATA state, the LEDC outputs a level state configured by LED_POLARITY; in the course of wait_data, if the new data arrives, the LEDC will continue to send data, at this time software needs to notice whether the waiting time of LEDC exceeds the operation time of reset. If the waiting time of LEDC exceeds the operation time of reset (this is equivalent to reset operation sent by LEDC), the LED may enter in refresh state, the data has not been sent. 0: LEDC not timeout 1: LEDC timeout
2	/	/	/
1	R/W1C	0x0	FIFO_CPUREQ_INT FIFO request CPU data interrupt When FIFO data is less than the threshold, the interrupt will be reported to the CPU. 0: FIFO does not request that CPU transfers data 1: FIFO requests that CPU transfers data
0	R/W1C	0x0	LED_TRANS_FINISH_INT Data transfer complete interrupt The value indicates that the data configured as total_data_length is transferred completely. 0: Data is not transferred completely 1: Data is transferred completely

10.12.6.10 0x0028 LEDC Wait Time 1 Control Register (Default Value: 0x01FF_FFFF)

Offset: 0x0028			Register Name: LEDC_WAIT_TIME1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	WAIT_TIM1_EN 0: Disable 1: Enable WAIT_TIME1 enable When the bit is 1, the controller automatically inserts the waiting time between the LED frame data.

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Offset: 0x0028			Register Name: LEDC_WAIT_TIME1_CTRL_REG
Bit	**Read/Write**	**Default/Hex**	**Description**
30:0	R/W	0x01FFFFFF	TOTAL_WAIT_TIME1 Waiting time between 2 frame data. The LEDC output is low level. The adjust range is 80 ns– 85 s. wait_time1=42 ns*(N+1) Unit: cycle (24 MHz) N: 0x80–0x7FFFFFFF If the value is 0, TOTAL_WAIT_TIME1=0x7FFFFFFF

10.12.6.11 0x0030+N*0x04 LEDC FIFO Data Register X (Default Value: 0x0000_0000)

Offset: 0x0030+N*0x04 (N=0–31)			Register Name: LEDC_FIFO_DATA_X
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	LEDC_FIFO_DATA_X Internal FIFO data of LEDC The lower 24-bit is valid.

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10.13 EMAC

10.13.1 Overview

The Ethernet Medium Access Controller (EMAC) enables a host to transmit and receive data over Ethernet in compliance with the IEEE 802.3-2002 standard. It supports 10/100/1000 Mbit/s external PHY with RMII/RGMII interface in full-duplex and half-duplex modes. The internal DMA is designed for packet-oriented data transfers based on a linked list of descriptors.

The EMAC has the following features:

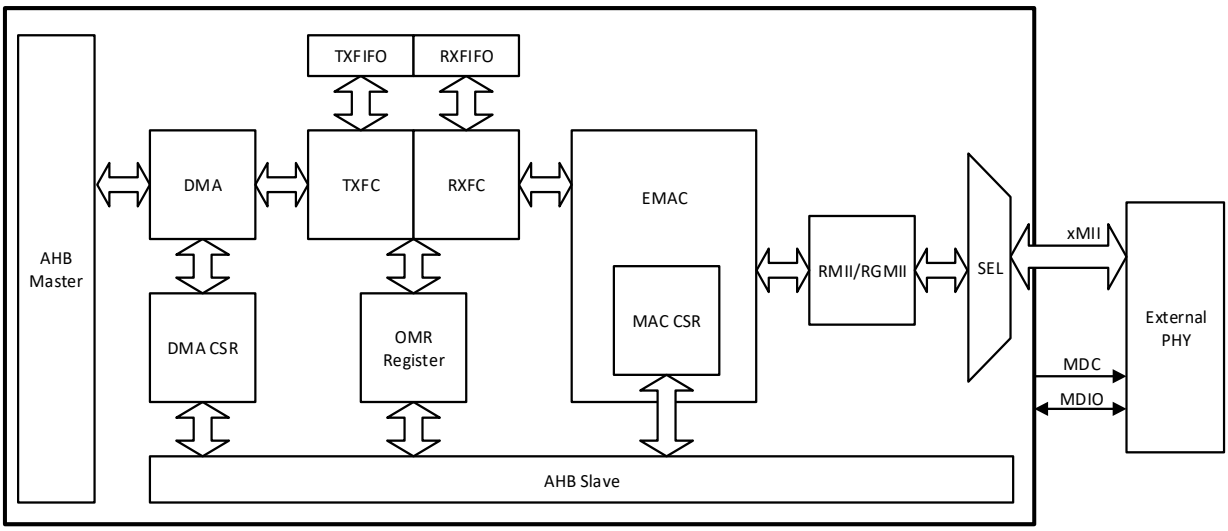
- One 10/100/1000 Mbit/s Ethernet port with reduced gigabit media independent interface (RGMII) and reduced media independent interface (RMII) interfaces, for connecting the external EPHY
- Compliant with IEEE 802.3-2002 standard
- Provides the management data input/output (MDIO) interface for PHY device configuration and management with configurable clock frequencies
- Supports both full-duplex and half-duplex operations
- Programmable frame length to support Standard or Jumbo Ethernet frames with sizes up to 16 KB
- Supports a variety of flexible address filtering modes
- Separate 32-bit status returned for transmission and reception packets
- Optimization for packet-oriented DMA transfers with frame delimiters
  - Supports linked-list descriptor list structure
  - Descriptor architecture, allowing large blocks of data transfer with minimum CPU intervention; each descriptor can transfer up to 4 KB of data
  - Comprehensive status reporting for normal operation and transfers with errors
- 4 KB TXFIFO for transmission packets and 16 KB RXFIFO for reception packets
- Programmable interrupt options for different operational conditions

10.13.2 Block Diagram

The following figure shows the block diagram of EMAC.

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Figure 10-105 EMAC Block Diagram



10.13.3 Functional Description

10.13.3.1 External Signals

The following table describes the pin mapping of EMAC.

Table 10-38 EMAC Pin Mapping

Pin Name	RGMII	RMII
RGMII-RXD3	RXD3	/
RGMII-RXD2	RXD2	/
RGMII-RXD1/RMII-RXD1	RXD1	RXD1
RGMII-RXD0/RMII-RXD0	RXD0	RXD0
RGMII-RXCK	RXCK	/
RGMII-RXCTRL/RMII-CRS-DV	RXCTRL	CRS-DV
RGMII-TXD3	TXD3	/
RGMII-TXD2	TXD2	/
RGMII-TXD1/RMII-TXD1	TXD1	TXD1
RGMII-TXD0/RMII-TXD0	TXD0	TXD0
RGMII-TXCK/RMII-TXCK	TXCK	TXCK
RGMII-TXCTRL/RMII-TXEN	TXCTRL	TXEN
RGMII-CLKIN/ RMII-RXER	CLKIN	RXER
MDC	MDC	MDC
MDIO	MDIO	MDIO

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Pin Name	RGMII	RMII
EPHY-25M	EPHY-25M	EPHY-25M

The following table describes the pin list of RGMII.

Table 10-39 EMAC RGMII Pin List

Pin Name	Description	Type
RGMII-TXD[3:0]	EMAC RGMII transmit data	O
RGMII-TXCTRL	EMAC RGMII transmit control	O
RGMII-TXCK	EMAC RGMII transmit clock	O
RGMII-RXD[3:0]	EMAC RGMII receive data	I
RGMII-RXCTRL	EMAC RGMII receive control	I
RGMII-RXCK	EMAC RGMII receive clock	I
RGMII-CKIN	EMAC RGMII 125M reference clock input	I
MDC	EMAC management data clock	O
MDIO	EMAC management data input output	I/O
EPHY-25M	25 MHz output for EMAC PHY	O

The following table describes the pin list of RMII.

Table 10-40 EMAC RMII Pin List

Pin Name	Description	Type
RMII-TXD[1:0]	EMAC RMII transmit data	O
RMII-TXEN	EMAC RMII transmit enable	O
RMII-TXCK	EMAC RMII transmit clock	I
RMII-RXD[1:0]	EMAC RMII receive data	I
RMII-CRS-DV	EMAC RMII receive data valid	I
RMII-RXER	EMAC RMII receive error	I
MDC	EMAC management data clock	O
MDIO	EMAC management data input output	I/O
EPHY-25M	25 MHz output for EMAC PHY	O

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10.13.3.2 Clock Characteristics

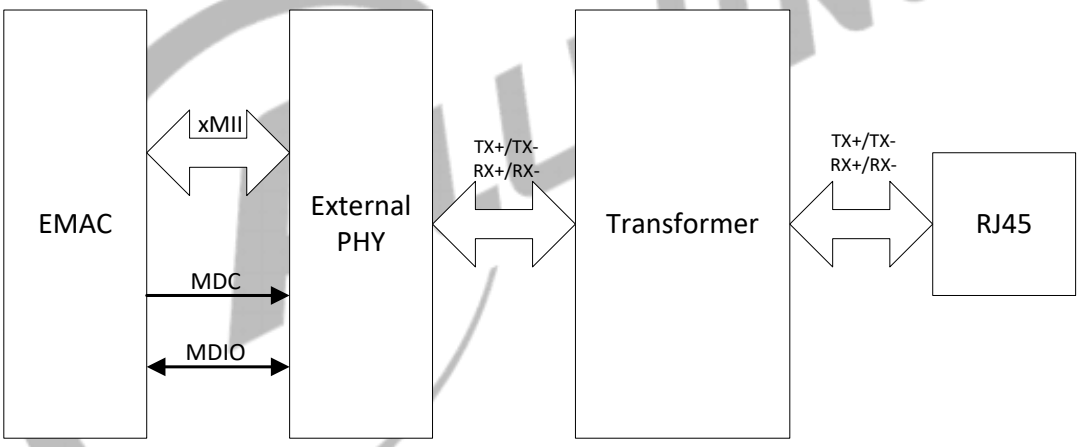
The following table describes the clock of EMAC.

Table 10-41 EMAC Clock Characteristics

Clock Name	Description	Type
RGMII0-TXCK/RMII0-TXCK	In RGMII mode, output 2.5 MHz/25 MHz/125 MHz. In RMII mode, input 5 MHz/50 MHz.	O/I
RGMII0-RXCK	In RGMII mode, input 2.5 MHz/25 MHz/125 MHz. In RMII mode, no input.	I
RGMII0-CLKIN	In RGMII mode, input 125M Reference Clock. In RMII mode, no clock.	I

10.13.3.3 Typical Application

Figure 10-106 EMAC Typical Application

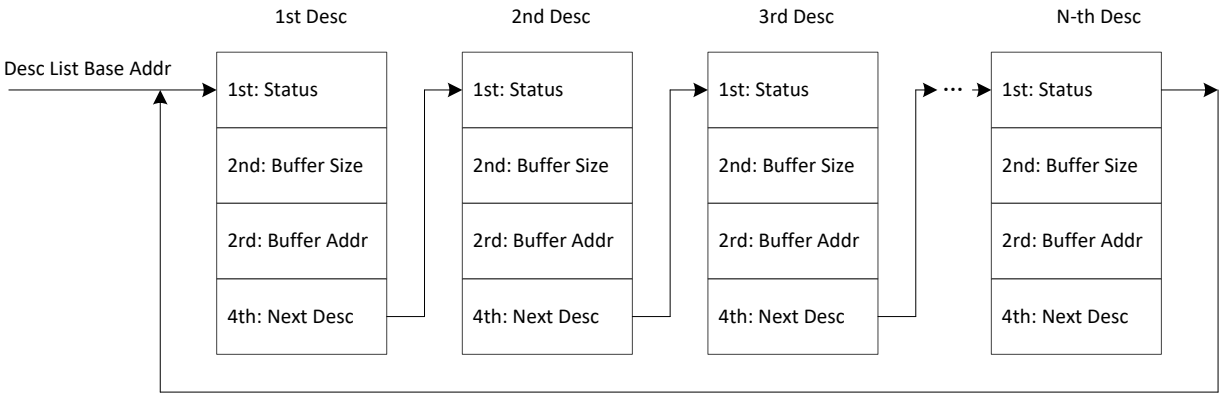


10.13.3.4 EMAC RX/TX Descriptor

The internal DMA of EMAC transfers data between host memory and internal RX/TX FIFO by a linked list of descriptors. Each descriptor consists of four words and contains some necessary information to transfer TX and RX frames. The following figure shows the descriptor list structure. The address of each descriptor must be 32-bit aligned.

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Figure 10-107 EMAC RX/TX Descriptor List



10.13.3.5 TX Descriptor

1st Word of TX Descriptor

Bits	Description
31	TX_DESC_CTL When set, the current descriptor can be used by DMA. This bit is cleared by DMA when the whole frame is transmitted or all data in the buffer of the current descriptor are transmitted.
30:17	Reserved
16	TX_HEADER_ERR When set, the checksum of the header for the transmitted frame is wrong.
15	Reserved
14	TX_LENGHT_ERR When set, the length of the transmitted frame is wrong.
13	Reserved
12	TX_PAYLOAD_ERR When set, the checksum of the payload for the transmitted frame is wrong.
11	Reserved
10	TX_CRS_ERR When set, the carrier is lost during transmission.
9	TX_COL_ERR_0 When set, the frame is aborted because of a collision after the contention period.
8	TX_COL_ERR_1 When set, the frame is aborted because of too many collisions.
7	Reserved

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Bits	Description
6:3	TX_COL_CNT The number of collisions before transmission.
2	TX_DEFER_ERR When set, the frame is aborted because of too much deferral.
1	TX_UNDERFLOW_ERR When set, the frame is aborted because of the TX FIFO underflow error.
0	TX_DEFER When set in Half-Duplex mode, the EMAC defers the frame transmission.

2nd Word of TX Descriptor

Bits	Description
31	TX_INT_CTL When it is set and the current frame has been transmitted, the TX_INT in Interrupt Status Register will be set.
30	LAST_DESC When it is set, the current descriptor is the last one of the current frame.
29	FIR_DESC When it is set, the current descriptor is the first one of the current frame.
28:27	CHECKSUM_CTL These bits control to insert checksum in the transmit frame.
26	CRC_CTL When it is set, the CRC field is not transmitted.
25:11	Reserved
10:0	BUF_SIZE The size of the buffer specified by the current descriptor.

3rd Word of TX Descriptor

Bits	Description
31:0	BUF_ADDR The address of the buffer specified by the current descriptor.

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4th Word of TX Descriptor

Bits	Description
31:0	NEXT_DESC_ADDR The address of the next descriptor. It must be 32-bit aligned.

10.13.3.6 RX Descriptor

1st Word of RX Descriptor

Bits	Description
31	RX_DESC_CTL When it is set, the current descriptor can be used by DMA. This bit is cleared by DMA when the complete frame is received or the buffer of the current descriptor is full.
30	RX_DAF_FAIL When it is set, the current frame does not pass the DA filter.
29:16	RX_FRM_LEN When LAST_DESC is not set and no error bit is set, this field is the length of received data for the current frame. When LAST_DESC is set, RX_OVERFLOW_ERR and RX_NO_ENOUGH_BUF_ERR are not set, this field is the length of the received frame.
15	Reserved
14	RX_NO_ENOUGH_BUF_ERR When it is set, the current frame is clipped because of no enough buffer.
13	RX_SAF_FAIL When it is set, the current fame does not pass the SA filter.
12	Reserved
11	RX_OVERFLOW_ERR When it is set, a buffer overflow error occurred and the current frame is wrong.
10	Reserved
9	FIR_DESC When it is set, the current descriptor is the first descriptor of the current frame.
8	LAST_DESC When it is set, the current descriptor is the last descriptor of the current frame.
7	RX_HEADER_ERR When it is set, the checksum of the frame header is wrong.

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Bits	Description
6	RX_COL_ERR When it is set, there is a late collision during the reception in half-duplex mode.
5	Reserved
4	RX_LENGTH_ERR When it is set, the length of the current frame is wrong.
3	RX_PHY_ERR When it is set, the receive error signal from PHY is asserted during the reception.
2	Reserved
1	RX_CRC_ERR When it is set, the CRC field of the received frame is wrong.
0	RX_PAYLOAD_ERR When it is set, the checksum or length of the payload for the received frame is wrong.

2nd Word of RX Descriptor

Bits	Description
31	RX_INT_CTL When it is set and a frame has been received, the RX_INT will not be set.
30:11	Reserved
10:0	BUF_SIZE The size of the buffer is specified by the current descriptor.

3rd Word of RX Descriptor

Bits	Description
31:0	BUF_ADDR The address of the buffer specified by the current descriptor.

4th Word of RX Descriptor

Bits	Description
31:0	NEXT_DESC_ADDR The address of the next descriptor. This field must be 32-bit aligned.

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10.13.4 Programming Guidelines

10.13.4.1 EMAC System Configuration

Perform the following steps:

Step 1 Write 0 to EMAC_BGR_REG[bit16] to assert the module reset.

Step 2 Write 1 to EMAC_BGR_REG[bit16] to deassert the module reset.

Step 3 Write 1 to EMAC_BGR_REG[bit0] to enable the bus clock of the module.

Step 4 Configure the pin interfaces of EMAC by setting GPIO module.

Step 5 Configure EMAC_EPHY_CLK_REG0 to set the transmission clock source of RGMII/RMII.

For RGMII RXCLK/CLK125M:

In RGMII mode, in addition to the configuration of the transmission clock source, it is generally necessary to adjust the timing by configuring the transmission clock delay, reception clock delay, transmission clock reverse, reception clock reverse.

- Write 0 to the bit[13] and write 1 to the bit[2] to select the RGMII interface.
- If selecting RXCLK as the clock source of RGMII, write 2 to the bit[1:0]; if selecting CLK125M as the clock source of RGMII, write 1 to the bit[1:0].
- Write 0 to the bit[3], write 0 to the bit[4], write 31 to the bit[9:5], and write 7 to the bit[12:10] to transmit the reception sequence adjustment.

For RMII TXCLK:

- Write 1 to the bit[13] and write 0 to the bit[2] to select the RMII interface.
- Write 0 to the bit[0] to select TXCLK as the clock source of RMII.

The configuration value of EMAC_EPHY_CLK_REG0 can refer to the following table.

Table 10-42 EMAC_EPHY_CLK_REG0 Configuration Value

EMAC_EPHY_CLK_REG0	PHY_SEL	RMII_EN	ETXDC	ERXDC	ERXIE	ETXIE	RMII/RGMII	ETCS
	Bit15	Bit13	Bit[12:10]	Bit[9:5]	Bit4	Bit3	Bit2	Bit[1:0]
RGMII	0	0	7	31	0	0	1	1/2
RMII	0	1	0	0	0	0	0	0

10.13.4.2 EMAC Initialization

Step 1 Write 1 to EMAC_BASIC_CTL1[bit0] to perform the software reset.

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Step 2 Write 1 to EMAC_BASIC_CTL1[bit1] to set the DMA priority of TX/RX.

Step 3 Configure EMAC_TX_CTL1 and EMAC_RX_CTL1 to set the configuration of DMA TX and DMA RX.

Step 4 Configure EMAC_INT_EN to set the corresponding interrupts and shield the needless interrupts.

Step 5 Configure EMAC_TX_DMA_LIST and EMAC_RX_DMA_LIST to set the first address of the TX descriptor and the RX descriptor, respectively.

Step 6 Configure EMAC_TX_CTL0 and EMAC_RX_CTL0 to set the TX and RX parameters. Configure EMAC_BASIC_CTL0 to set the speed, duplex mode, loopback configuration. (If enabled the auto-negotiation, the configuration is performed as a result of the negotiation)

Step 7 Configure EMAC_RX_FRM_FLT to set the RX frame filter.

Step 8 Configure EMAC_TX_FLOW_CTL and EMAC_RX_CTL0 to set the control mechanism of TX and RX.

Step 9 Clear all interrupt flags.

Step 10 Write 1 to EMAC_TX_CTL0[bit31] and write 1 to EMAC_RX_CTL0[bit31] to enable the TX and RX functions.

10.13.5 Register List

Module Name	Base Address
EMAC	0x04500000

Register Name	Offset	Description
EMAC_BASIC_CTL0	0x0000	EMAC Basic Control Register0
EMAC_BASIC_CTL1	0x0004	EMAC Basic Control Register1
EMAC_INT_STA	0x0008	EMAC Interrupt Status Register
EMAC_INT_EN	0x000C	EMAC Interrupt Enable Register
EMAC_TX_CTL0	0x0010	EMAC Transmit Control Register0
EMAC_TX_CTL1	0x0014	EMAC Transmit Control Register1
EMAC_TX_FLOW_CTL	0x001C	EMAC Transmit Flow Control Register
EMAC_TX_DMA_DESC_LIST	0x0020	EMAC Transmit Descriptor List Address Register
EMAC_RX_CTL0	0x0024	EMAC Receive Control Register0
EMAC_RX_CTL1	0x0028	EMAC Receive Control Register1
EMAC_RX_DMA_DESC_LIST	0x0034	EMAC Receive Descriptor List Address Register
EMAC_RX_FRM_FLT	0x0038	EMAC Receive Frame Filter Register
EMAC_RX_HASH0	0x0040	EMAC Hash Table Register0

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Register Name	Offset	Description
EMAC_RX_HASH1	0x0044	EMAC Hash Table Register1
EMAC_MII_CMD	0x0048	EMAC Management Interface Command Register
EMAC_MII_DATA	0x004C	EMAC Management Interface Data Register
EMAC_ADDR_HIGH0	0x0050	EMAC MAC Address High Register0
EMAC_ADDR_LOW0	0x0054	EMAC MAC Address Low Register0
EMAC_ADDR_HIGHN	0x0050+0x08*N (N=1–7)	EMAC MAC Address High Register N (N=1–7)
EMAC_ADDR_LOWN	0x0054+0x08*N (N=1–7)	EMAC MAC Address Low Register N (N=1–7)
EMAC_TX_DMA_STA	0x00B0	EMAC Transmit DMA Status Register
EMAC_TX_CUR_DESC	0x00B4	EMAC Current Transmit Descriptor Register
EMAC_TX_CUR_BUF	0x00B8	EMAC Current Transmit Buffer Address Register
EMAC_RX_DMA_STA	0x00C0	EMAC Receive DMA Status Register
EMAC_RX_CUR_DESC	0x00C4	EMAC Current Receive Descriptor Register
EMAC_RX_CUR_BUF	0x00C8	EMAC Current Receive Buffer Address Register
EMAC_RGMII_STA	0x00D0	EMAC RGMII Status Register

10.13.6 Register Description

10.13.6.1 0x0000 EMAC Basic Control Register0 (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: EMAC_BASIC_CTL0
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3:2	R/W	0x0	SPEED EMAC Working Speed 00: 1000 Mbit/s 01: Reserved 10: 10 Mbit/s 11: 100 Mbit/s
1	R/W	0x0	LOOPBACK EMAC Loopback Mode For Test 0: Disable 1: Enable

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Offset: 0x0000			Register Name: EMAC_BASIC_CTL0
Bit	Read/Write	Default/Hex	Description
0	R/W	0x0	DUPLEX EMAC Transfer Mode 0: Half-duplex 1: Full-duplex

10.13.6.2 0x0004 EMAC Basic Control Register1 (Default Value: 0x0800_0000)

Offset: 0x0004			Register Name: EMAC_BASIC_CTL1
Bit	Read/Write	Default/Hex	Description
31:30	/	/	/
29:24	R/W	0x8	BURST_LEN The burst length of RX and TX DMA transfer.
23:2	/	/	/
1	R/W	0x0	RX_TX_PRI RX TX DMA Priority 0: Same priority 1: RX priority is over TX
0	R/W	0x0	SOFT_RST Soft Reset all Registers and Logic 0: No valid 1: Reset All clock inputs must be valid before soft reset. This bit is cleared internally when the reset operation is completed fully. Before writing any register, this bit should read a 0.

10.13.6.3 0x0008 EMAC Interrupt Status Register (Default Value: 0x4000_0000)

Offset: 0x0008			Register Name: EMAC_INT_STA
Bit	Read/Write	Default/Hex	Description
31:17	R	0x2000	Reserved
16	R/W1C	0x0	RGMII_LINK_STA_P RMII Link Status Changed Interrupt Pending 0: No Pending 1: Pending Write '1' to clear it.

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Offset: 0x0008			Register Name: EMAC_INT_STA
Bit	**Read/Write**	**Default/Hex**	**Description**
15:14	/	/	/
13	R/W1C	0x0	RX_EARLY_P RX DMA Filled First Data Buffer of the Receive Frame Interrupt Pending 0: No Pending 1: Pending Write '1' to clear it.
12	R/W1C	0x0	RX_OVERFLOW_P RX FIFO Overflow Error Interrupt Pending 0: No Pending 1: Pending Write '1' to clear it.
11	R/W1C	0x0	RX_TIMEOUT_P RX Timeout Interrupt Pending 0: No Pending 1: Pending Write '1' to clear it. When this bit is asserted, the length of the received frame is greater than 2048 bytes (10240 when JUMBO_FRM_EN is set)
10	R/W1C	0x0	RX_DMA_STOPPED_P When this bit asserted, the RX DMA FSM is stopped.
9	R/W1C	0x0	RX_BUF_UA _P RX Buffer UA Interrupt Pending 0: No Pending 1: Pending Write '1' to clear it. When this bit is asserted, the RX DMA cannot acquire the next RX descriptor and RX DMA FSM is suspended. The ownership of the next RX descriptor should be changed to RX DMA. The RX DMA FSM will resume when the RX_DMA_START is written or the next receive frame is coming.
8	R/W1C	0x0	RX_P Frame RX Completed Interrupt Pending 0: No Pending 1: Pending Write '1' to clear it. When this bit is asserted, a frame reception is completed. The RX DMA FSM remains running.
7:6	/	/	/

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Offset: 0x0008			Register Name: EMAC_INT_STA
Bit	**Read/Write**	**Default/Hex**	**Description**
5	R/W1C	0x0	TX_EARLY_P Total interrupt pending which the frame is transmitted to FIFO 0: No Pending 1: Pending Write '1' to clear it.
4	R/W1C	0x0	TX_UNDERFLOW_P TX FIFO Underflow Interrupt Pending 0: No Pending 1: Pending Write '1' to clear it.
3	R/W1C	0x0	TX_TIMEOUT_P Transmitter Timeout Interrupt Pending 0: No Pending 1: Pending Write '1' to clear it.
2	R/W1C	0x0	TX_BUF_UA_P TX Buffer UA Interrupt Pending 0: No Pending 1: Pending When this asserted, the TX DMA can not acquire the next TX descriptor and the TX DMA FSM is suspended. The ownership of the next TX descriptor should be changed to TX DMA. The TX DMA FSM will resume when writing to TX_DMA_START bit.
1	R/W1C	0x0	TX_DMA_STOPPED_P Transmission DMA Stopped Interrupt Pending 0: No Pending 1: Pending Write '1' to clear it.
0	R/W1C	0x0	TX_P Frame Transmission Interrupt Pending 0: No Pending 1: Pending Write '1' to clear it.

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10.13.6.4 0x000C EMAC Interrupt Enable Register (Default Value: 0x0000_0000)

Offset: 0x000C			Register Name: EMAC_INT_EN
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	/	/	/
13	R/W	0x0	RX_EARLY_INT_EN Early Receive Interrupt 0: Disable 1: Enable
12	R/W	0x0	RX_OVERFLOW_INT_EN Receive Overflow Interrupt 0: Disable 1: Enable
11	R/W	0x0	RX_TIMEOUT_INT_EN Receive Timeout Interrupt 0: Disable 1: Enable
10	R/W	0x0	RX_DMA_STOPPED_INT_EN Receive DMA FSM Stopped Interrupt 0: Disable 1: Enable
9	R/W	0x0	RX_BUF_UA_INT_EN Receive Buffer Unavailable Interrupt 0: Disable 1: Enable
8	R/W	0x0	RX_INT_EN Receive Interrupt 0: Disable 1: Enable
7:6	/	/	/
5	R/W	0x0	TX_EARLY_INT_EN Early Transmit Interrupt 0: Disable 1: Enable
4	R/W	0x0	TX_UNDERFLOW_INT_EN Transmit Underflow Interrupt 0: Disable 1: Enable

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Offset: 0x000C			Register Name: EMAC_INT_EN
Bit	Read/Write	Default/Hex	Description
3	R/W	0x0	TX_TIMEOUT_INT_EN Transmit Timeout Interrupt 0: Disable 1: Enable
2	R/W	0x0	TX_BUF_UA_INT_EN Transmit Buffer Available Interrupt 0: Disable 1: Enable
1	R/W	0x0	TX_DMA_STOPPED_INT_EN Transmit DMA FSM Stopped Interrupt 0: Disable 1: Enable
0	R/W	0x0	TX_INT_EN Transmit Interrupt 0: Disable 1: Enable

10.13.6.5 0x0010 EMAC Transmit Control Register0 (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: EMAC_TX_CTL0
Bit	Read/Write	Default/Hex	Description
31	R/W	0x0	TX_EN Enable Transmitter 0: Disable 1: Enable When disabled, the transmission will continue until the current transmission finishes.
30	R/W	0x0	TX_FRM_LEN_CTL Frame Transmit Length Control 0: Up to 2,048 bytes (JUMBO_FRM_EN==0) Up to 10,240 bytes (JUMBO_FRM_EN==1) 1: Up to 16,384 bytes Any bytes after that is cut off.
29:0	/	/	/

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10.13.6.6 0x0014 EMAC Transmit Control Register1 (Default Value: 0x0000_0000)

Offset: 0x0014			Register Name: EMAC_TX_CTL1
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	TX_DMA_START Transmit DMA FSM Start 0: No valid 1: Start It is cleared internally and always read a 0.
30	R/W	0x0	TX_DMA_EN 0: Stop TX DMA after the completion of current frame transmission 1: Start and run TX DMA
29:11	/	/	/
10:8	R/W	0x0	TX_TH Threshold value of TX DMA FIFO When TX_MD is 0, the transmission starts when the frame size in TX DMA FIFO is greater than the threshold. In addition, the full frames with a length less than the threshold are transferred automatically. 000: 64 001: 128 010: 192 011: 256 Others: Reserved
7:2	/	/	/
1	R/W	0x0	TX_MD Transmission Mode 0: TX starts after the TX DMA FIFO bytes is greater than the TX_TH 1: TX starts after the TX DMA FIFO is located a full frame
0	R/WAC	0x0	FLUSH_TX_FIFO Flush the data in the TX FIFO 0: Enable 1: Disable

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10.13.6.7 0x001C EMAC Transmit Flow Control Register (Default Value: 0x0000_0000)

Offset: 0x001C			Register Name: EMAC_TX_FLOW_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	TX_FLOW_CTL_STA This bit indicates a pause frame transmission is in progress. When the configuration of flow control is ready, set this bit to transmit a pause frame in full-duplex mode or activate the backpressure function. After the transmission is completed, this bit will be cleared automatically. Before writing TX_FLOW_CTRL register, this bit must be read as 0.
30:22	/	/	/
21:20	R/W	0x0	TX_PAUSE_FRM_SLOT The threshold of the pause timer at which the input flow control signal is checked for automatic re-transmission of the pause frame. The threshold values should be always less than PAUSE_TIME.
19:4	R/W	0x0	PAUSE_TIME The pause time field in the transmitted control frame.
3:2	/	/	/
1	R/W	0x0	ZQP_FRM_EN 0: Disable 1: Enable When set, enable the functionality to generate the Zero-Quanta Pause control frame.
0	R/W	0x0	TX_FLOW_CTL_EN TX Flow Control Enable 0: Disable 1: Enable When set, enable flow control operation to transmit pause frames in full-duplex mode, or enable the back-pressure operation in half-duplex mode.

10.13.6.8 0x0020 EMAC Transmit DMA Descriptor List Address Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: EMAC_TX_DMA_LIST
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	TX_DESC_LIST The base address of the transmission descriptor list It must be 32-bit aligned.

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10.13.6.9 0x0024 EMAC Receive Control Register0 (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: EMAC_RX_CTL0
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	RX_EN Enable Receiver 0: Disable receiver after current reception 1: Enable
30	R/W	0x0	RX_FRM_LEN_CTL Frame Receive Length Control 0: Up to 2048 bytes (JUMBO_FRM_EN==0) Up to 10240 bytes (JUMBO_FRM_EN==1) 1: Up to 16384 bytes Any bytes after that is cut off.
29	R/W	0x0	JUMBO_FRM_EN Jumbo Frame Enable 0: Disable 1: Enable Jumbo frames of 9018 bytes without reporting a giant
28	R/W	0x0	STRIP_FCS When set, strip the Pad/FCS field on received frames only when the length of field value is less than or equal to 1500 bytes.
27	R/W	0x0	CHECK_CRC Check CRC Enable 0: Disable 1: Calculate CRC and check the IPv4 Header Checksum
26:18	/	/	/
17	R/W	0x0	RX_PAUSE_FRM_MD 0: Only detect multicast pause frame specified in the 802.3x standard. 1: In addition to detect multicast pause frame specified in the 802.3x standard, also detect unicast pause frame with the address specified in MAC Address 0 High Register and MAC address 0 Low Register.
16	R/W	0x0	RX_FLOW_CTL_EN When set, enable the functionality that decodes the received pause frame and disable its transmitter for a specified time by pause frame.
15:0	/	/	/

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10.13.6.10 0x0028 EMAC Receive Control Register1 (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: EMAC_RX_CTL1
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	RX_DMA_START When set, the RX DMA will work. It is cleared internally and always read a 0.
30	R/W	0x0	RX_DMA_EN Receive DMA Enable 0: Stop RX DMA after finishing the received current frame 1: Start and run RX DMA
29:25	/	/	/
24	R/W	0x0	RX_FIFO_FLOW_CTL Receive FIFO Flow Control Enable 0: Disable 1: Enable, base on RX_FLOW_CTL_TH_DEACT and RX_FLOW_CTL_TH_ACT
23:22	R/W	0x0	RX_FLOW_CTL_TH_DEACT Threshold for Deactivating Flow Control 00: Full minus 1 KB 01: Full minus 2 KB 10: Full minus 3 KB 11: Full minus 4 KB Valid in both half-duplex mode and full-duplex mode.
21:20	R/W	0x0	RX_FLOW_CTL_TH_ACT Threshold for Activating Flow Control 00: Full minus 1 KB 01: Full minus 2 KB 10: Full minus 3 KB 11: Full minus 4 KB Valid in both half-duplex mode and full-duplex mode.
19:6	/	/	/

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Offset: 0x0028			Register Name: EMAC_RX_CTL1
Bit	**Read/Write**	**Default/Hex**	**Description**
5:4	R/W	0x0	RX_TH Threshold for RX DMA FIFO Start 00: 64 01: 32 10: 96 11: 128 Only valid when RX_MD == 0, the full frames with a length less than the threshold are transferred automatically.
3	R/W	0x0	RX_ERR_FRM 0: RX DMA drops frames with error 1: RX DMA forwards frames with error
2	R/W	0x0	RX_RUNT_FRM When the bit is set to 1, it indicates forward undersized frames with no error and length less than 64 bytes.
1	R/W	0x0	RX_MD Receive Mode 0: RX starts to read after the RX DMA FIFO byte is greater than RX_TH 1: RX starts to read after the RX DMA FIFO is located a full frame
0	R/W	0x0	FLUSH_RX_FRM Flush Receive Frames 0: Enable when the receive descriptors/buffers are unavailable 1: Disable

10.13.6.11 0x0034 EMAC Receive DMA Descriptor List Address Register (Default Value: 0x0000_0000)

Offset: 0x0034			Register Name: EMAC_RX_DMA_LIST
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	RX_DESC_LIST The base address of the received descriptor list It must be 32-bit aligned.

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10.13.6.12 0x0038 EMAC Receive Frame Filter Register (Default Value: 0x0000_0000)

Offset: 0x0038			Register Name: EMAC_RX_FRM_FLT
Bit	**Read/Write**	**Default/Hex**	**Description**
31	R/W	0x0	DIS_ADDR_FILTER Disable Address Filter 0: Enable 1: Disable
30:18	/	/	/
17	R/W	0x0	DIS_BROADCAST Disable Receive Broadcast Frames 0: Receive 1: Drop
16	R/W	0x0	RX_ALL_MULTICAST Receive All Multicast Frames Filter 0: Filter according to HASH_MULTICAST 1: Receive all
15:14	/	/	/
13:12	R/W	0x0	CTL_FRM_FILTER Receive Control Frames Filter 00: Drop all control frames 01: Drop all control frames 10: Receive all control frames 11: Receive all control frames when passing the address filter
11:10	/	/	/
9	R/W	0x0	HASH_MULTICAST Filter Multicast Frames Set 0: By comparing the DA field in DA MAC address registers 1: According to the hash table
8	R/W	0x0	HASH_UNICAST Filter Unicast Frames Set 0: By comparing the DA field in DA MAC address registers 1: According to the hash table
7	/	/	/

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Offset: 0x0038			Register Name: EMAC_RX_FRM_FLT
Bit	Read/Write	Default/Hex	Description
6	R/W	0x0	SA_FILTER_EN Receive SA Filter Enable 0: Receive frames and update the result of SA filter 1: Update the result of the SA filter. In addition, if the SA field of the received frame does not match the values in SA MAC address registers, drop this frame.
5	R/W	0x0	SA_INV_FILTER Receive SA Invert Filter Set 0: Pass frames whose SA field matches SA MAC address registers 1: Pass frames whose SA field does not match SA MAC address registers
4	R/W	0x0	DA_INV_FILTER 0: Normal filtering of frames is performed 1: Filter both unicast and multicast frames by comparing DA field in inverse filtering mode
3:2	/	/	/
1	R/W	0x0	FLT_MD 0: If the HASH_MULTICAST or HASH_UNICAST is set, the frame is passed only when it matches the Hash filter 1: Receive the frame when it passes the address register filter or the hash filter (set by HASH_MULTICAST or HASH_UNICAST)
0	R/W	0x0	RX_ALL Receive All Frame 0: Receive the frames that pass the SA/DA address filter 1: Receive all frames and update the result of address filter (pass or fail) in the receive status word

10.13.6.13 0x0040 EMAC Receive Hash Table Register0 (Default Value: 0x0000_0000)

Offset: 0x0040			Register Name: EMAC_RX_HASH0
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	HASH_TAB0 The upper 32 bits of Hash table for the received frame filter.

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10.13.6.14 0x0044 EMAC Receive Hash Table Register1 (Default Value: 0x0000_0000)

Offset: 0x0044			Register Name: EMAC_RX_HASH1
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	HASH_TAB1 The lower 32 bits of Hash table for the received frame filter.

10.13.6.15 0x0048 EMAC MII Command Register (Default Value: 0x0000_0000)

Offset: 0x0048			Register Name: EMAC_MII_CMD
Bit	Read/Write	Default/Hex	Description
31:23	/	/	/
22:20	R/W	0x0	MDC_DIV_RATIO_M MDC Clock Divider Ratio The MDC Clock is divided from the AHB clock. 000: 16 001: 32 010: 64 011: 128 Others: Reserved
19:17	/	/	/
16:12	R/W	0x0	PHY_ADDR PHY Address
11:9	/	/	/
8:4	R/W	0x0	PHY_REG_ADDR PHY Register Address
3:2	/	/	/
1	R/W	0x0	MII_WR MII Write and Read 0: Read 1: Write
0	R/WAC	0x0	MII_BUSY MII Status 0: Writing 0 is no valid, and reading 0 indicates the read/write operation is finished 1: Writing 1 starts the read/write operation, and reading 1 indicates busy.

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10.13.6.16 0x004C EMAC MII Data Register (Default Value: 0x0000_0000)

Offset: 0x004C			Register Name: EMAC_MII_DATA
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0x0	MII_DATA Write to or read from the register in the selected PHY.

10.13.6.17 0x0050 EMAC MAC Address High Register0 (Default Value: 0x0000_FFFF)

Offset: 0x0050			Register Name: EMAC_ADDR_HIGH0
Bit	Read/Write	Default/Hex	Description
31:16	/	/	/
15:0	R/W	0xFFFF	MAC_ADDR_HIGH0 The upper 16 bits of the 1st MAC address.

10.13.6.18 0x0054 EMAC MAC Address Low Register0 (Default Value: 0xFFFF_FFFF)

Offset: 0x0054			Register Name: EMAC_ADDR_LOW0
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0xFFFFFFFF	MAC_ADDR_LOW0 The lower 32 bits of 1st MAC address.

10.13.6.19 0x0050+0x08*N EMAC MAC Address High Register N (Default Value: 0x0000_FFFF)

Offset: 0x0050+0x08*N (N=1~7)			Register Name: EMAC_ADDR_HIGHN
Bit	Read/Write	Default/Hex	Description
31	R/W	0x0	MAC_ADDR_CTL MAC Address Valid 0: Not valid 1: Valid
30	R/W	0x0	MAC_ADDR_TYPE MAC Address Type 0: Used to compare with the destination address of the received frame 1: Used to compare with the source address of the received frame

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Offset: 0x0050+0x08*N (N=1~7)			Register Name: EMAC_ADDR_HIGHN
Bit	Read/Write	Default/Hex	Description
29:24	R/W	0x0	MAC_ADDR_BYTE_CTL MAC Address Byte Control Mask The lower bit of mask controls the lower byte of the MAC address. When the bit of mask is 1, do not compare the corresponding byte.
23:16	/	/	/
15:0	R/W	0xFFFF	MAC_ADDR_HIGH The upper 16 bits of the MAC address.

10.13.6.20 0x0054+0x08*N EMAC MAC Address Low Register N (Default Value: 0x0000_0000)

Offset: 0x0054+0x08*N (N=1~7)			Register Name: EMAC_ADDR_LOWN
Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	MAC_ADDR_LOWN The lower 32 bits of MAC address N (N: 1–7).

10.13.6.21 0x00B0 EMAC Transmit DMA Status Register (Default Value: 0x0000_0000)

Offset: 0x00B0			Register Name: EMAC_TX_DMA_STA
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2:0	R	0x0	TX_DMA_STA The State of Transmit DMA FSM 000: STOP, when reset or disable TX DMA 001: RUN_FETCH_DESC, fetching TX DMA descriptor 010: RUN_WAIT_STA, waiting for the status of TX frame 011: RUN_TRANS_DATA, passing the frame from host memory to TX DMA FIFO 100: Reserved 101: Reserved 111: RUN_CLOSE_DESC, closing TX descriptor 110: SUSPEND, TX descriptor is unavailable or TX DMA FIFO underflow

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10.13.6.22 0x00B4 EMAC Transmit DMA Current Descriptor Register (Default Value: 0x0000_0000)

Offset: 0x00B4			Register Name: EMAC_TX_DMA_CUR_DESC
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	TX_DMA_CUR_DESC The address of current transmit descriptor.

10.13.6.23 0x00B8 EMAC Transmit DMA Current Buffer Address Register (Default Value: 0x0000_0000)

Offset: 0x00B8			Register Name: EMAC_TX_DMA_CUR_BUF
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	TX_DMA_CUR_BUF The address of current transmit DMA buffer.

10.13.6.24 0x00C0 EMAC Receive DMA Status Register (Default Value: 0x0000_0000)

Offset: 0x00C0			Register Name: EMAC_RX_DMA_STA
Bit	Read/Write	Default/Hex	Description
31:3	/	/	/
2:0	R	0x0	RX_DMA_STA The State of RX DMA FSM 000: STOP, when reset or disable RX DMA 001: RUN_FETCH_DESC, fetching RX DMA descriptor 010: Reserved 011: RUN_WAIT_FRM, waiting for the frame 100: SUSPEND, RX descriptor is unavailable 101: RUN_CLOSE_DESC, closing RX descriptor 110: Reserved 111: RUN_TRANS_DATA, passing the frame from host memory to RX DMA FIFO

10.13.6.25 0x00C4 EMAC Receive DMA Current Descriptor Register (Default Value: 0x0000_0000)

Offset: 0x00C4			Register Name: EMAC_RX_DMA_CUR_DESC
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	RX_DMA_CUR_DESC The address of current receive descriptor

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10.13.6.26 0x00C8 EMAC Receive DMA Current Buffer Address Register (Default Value: 0x0000_0000)

Offset: 0x00C8			Register Name: EMAC_RX_DMA_CUR_BUF
Bit	Read/Write	Default/Hex	Description
31:0	R	0x0	RX_DMA_CUR_BUF The address of current receive DMA buffer

10.13.6.27 0x00D0 EMAC RGMII Status Register (Default Value: 0x0000_0000)

Offset: 0x00D0			Register Name: EMAC_RGMII_STA
Bit	Read/Write	Default/Hex	Description
31:4	/	/	/
3	R	0x0	RGMII_LINK The link status of the RGMII interface 0: Down 1: Up
2:1	R	0x0	RGMII_LINK_SPD The link speed of the RGMII interface 00: 2.5 MHz 01: 25 MHz 10: 125 MHz 11: Reserved
0	R	0x0	RGMII_LINK_MD The link mode of the RGMII interface 0: Half-Duplex 1: Full-Duplex

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10.14 CIR Receiver

10.14.1 Overview

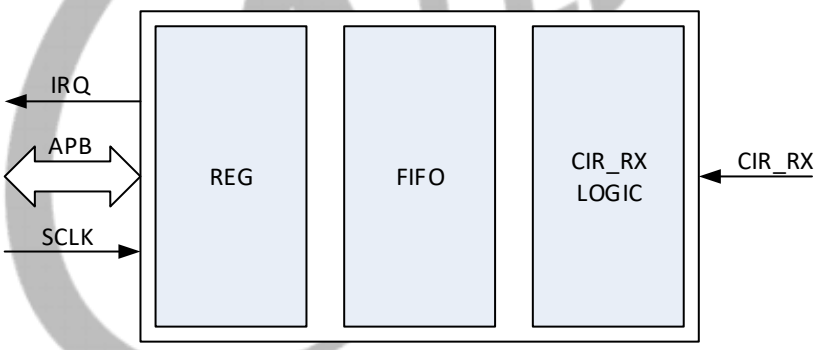
The Consumer Infrared (CIR) receiver captures pulse from the IR Receiver module and uses the Run-Length Code (RLC) to encode the pulse.

The CIR receiver has the following features:

- Supports CIR remote control receiver
- Supports NEC IR protocol
- 64x8 bits RX FIFO for data buffer
- Programmable RX FIFO thresholds
- Supports interrupt
- Sample clock up to 1 MHz

10.14.2 Block Diagram

Figure 10-108 CIR Receiver Block Diagram



The CIR receiver samples the input signal on the programmable frequency and records these samples into RX FIFO when one CIR signal is found on the air. The CIR receiver uses Run-Length Code (RLC) to encode pulse width. The encoded data is buffered in 64 levels and 8-bit width RX FIFO; the MSB bit is used to record the polarity of the receiving CIR signal, the rest 7 bits are used for the length of RLC. The maximum length of the RLC is 128. If the duration of one level (high or low level) is more than 128, another byte is used.

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10.14.3 Functional Description

10.14.3.1 External Signals

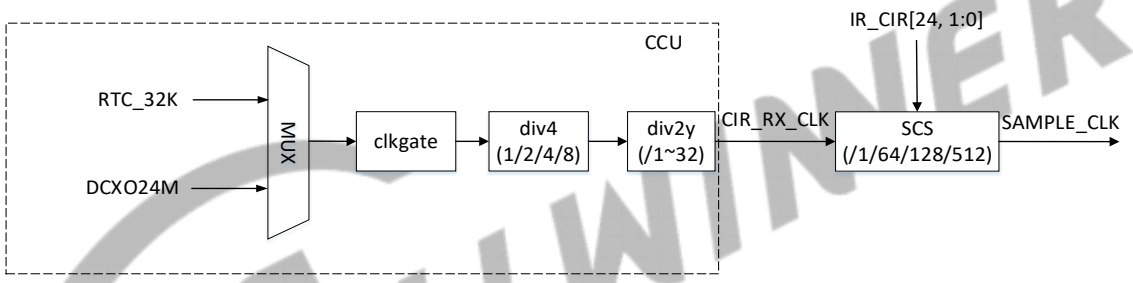
The following table describes the external signals of CIR Receiver.

Table 10-43 CIR Receiver External Signals

Signal	Description	Type
IR-RX	Consumer Infrared Receiver	I

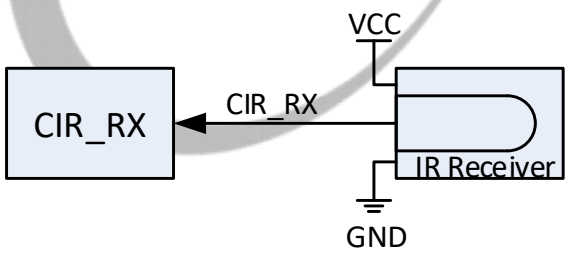
10.14.3.2 Clock Sources

Figure 10-109 CIR Receiver Clock



10.14.3.3 Typical Application

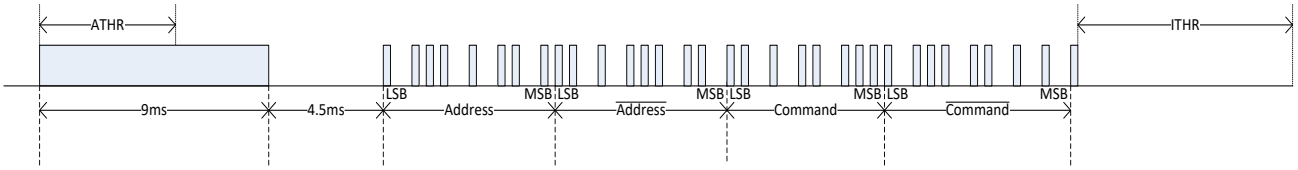
Figure 10-110 CIR Receiver Application Diagram



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10.14.3.4 NEC Protocol Format

Figure 10-111 NEC Protocol



The CIR receiver module is a timer with a capture function.

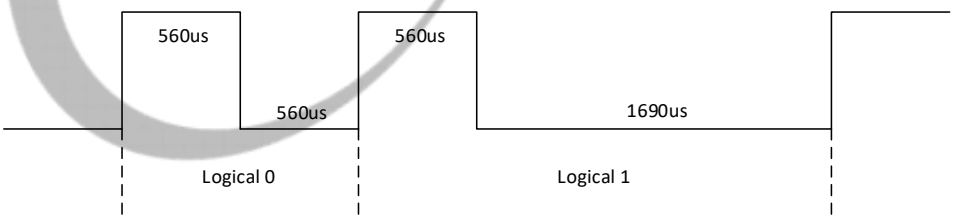
When CIR_RX signals satisfy the Active Threshold (ATHR), the CIR receiver can start to capture. In the process, the signal is ignored if the pulse width of the signal is less than NTHR. When CIR_RX signals satisfy ITHR (Idle Threshold), the capture process is stopped and the Receiver Packet End interrupt is generated, then the Receiver Packet End Flag is asserted.

In a capture process, every effective pulse is buffered to FIFO in bytes according to the form of the Run-Length Code. The MSB bit of a byte is the polarity of pulse, and the rest 7 bits is pulse width by taking Sample Clock as a basic unit. This is the code form of the RLC-Byte. When the level changes or the pulse width counter overflows, the RLC-Byte is buffered to FIFO. The CIR_RX module receives the infrared signals transmitted by the infrared remote control, the software decodes the signals.

10.14.3.5 Operating Mode

Sample Clock

Figure 10-112 Logical '0' and Logical '1' of NEC Protocol



For NEC protocol, a logical "1" takes 2.25 ms (560 us+1680 us) to transmit, while a logical "0" is only half of that, being 1.12 ms (560 us+560 us).

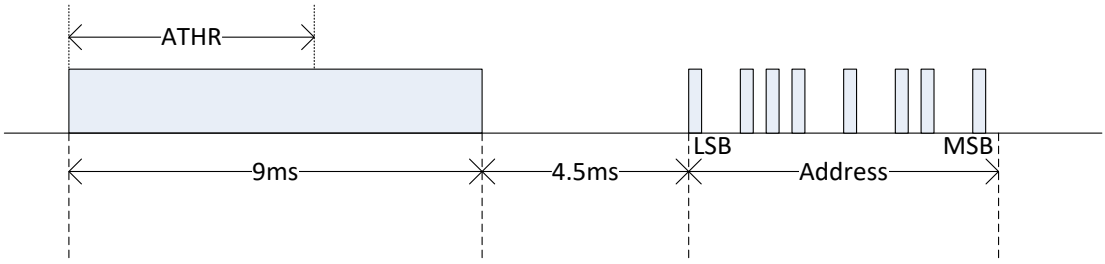
For example, if the sample clock is 31.25 kHz, a sample cycle is 32 us, then 18 sample cycles are 560 us. So the RLC of 560 us low level is 0x12 (b'00010010), the RLC of 560 us high level is 0x92 (b'10010010). Then a logical "1" takes code 0x12 (b'00010010) and code 0xb5 (b'10110101) to transmit, a logical "0" takes code 0x12 and code 0x92 to transmit.

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Active Threshold (ATHR)

When the CIR receiver is in Idle state, if the electrical level of the CIR_RX signal changes (positive jump or negative jump), and the duration reaches this threshold, then the CIR receiver takes the starting of the signal as a lead code, and the CIR receiver turns into an active state and starts to capture CIR_RX signals.

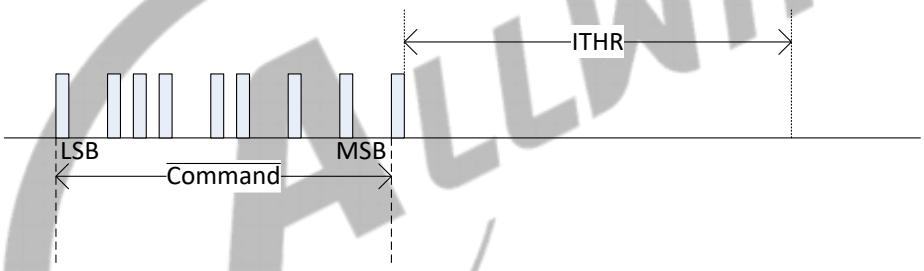
Figure 10-113 ATHR Definition



Idle Threshold (ITHR)

If the electrical level of CIR_RX signals has no change, and the duration reaches this threshold, then the CIR receiver enters into Idle state and ends this capture.

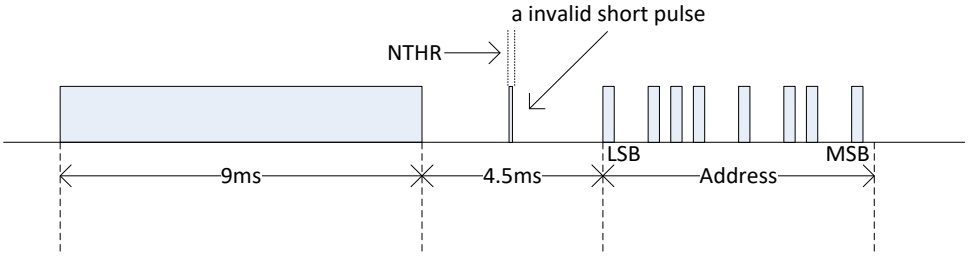
Figure 10-114 ITHR Definition



Noise Threshold (NTHR)

In the capture process, the pulse is ignored if the pulse width is less than the Noise Threshold.

Figure 10-115 NTHR Definition

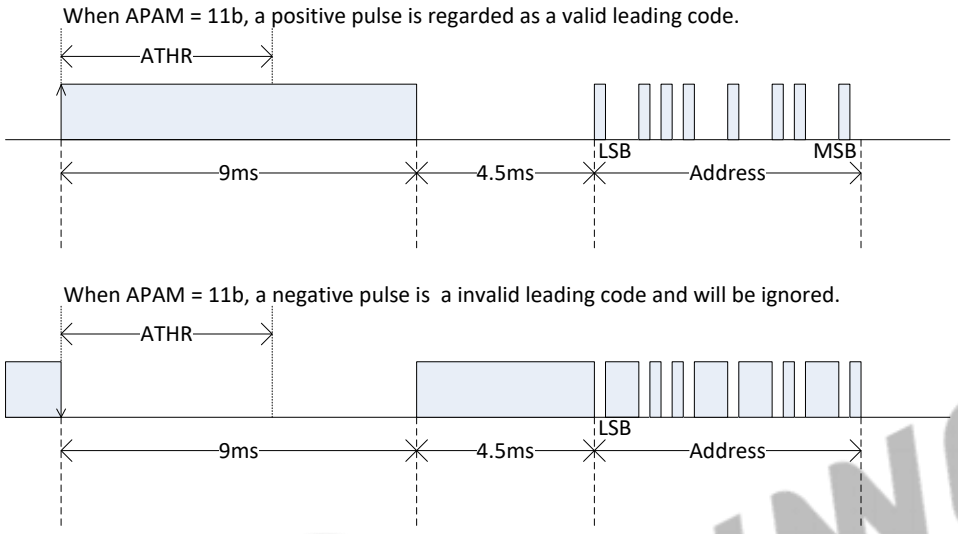


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Active Pulse Accept Mode (APAM)

The APAM is used to fit the type of lead code. If a pulse does not fit the type of lead code, it is not regarded as a lead code even if the pulse width reaches ATHR.

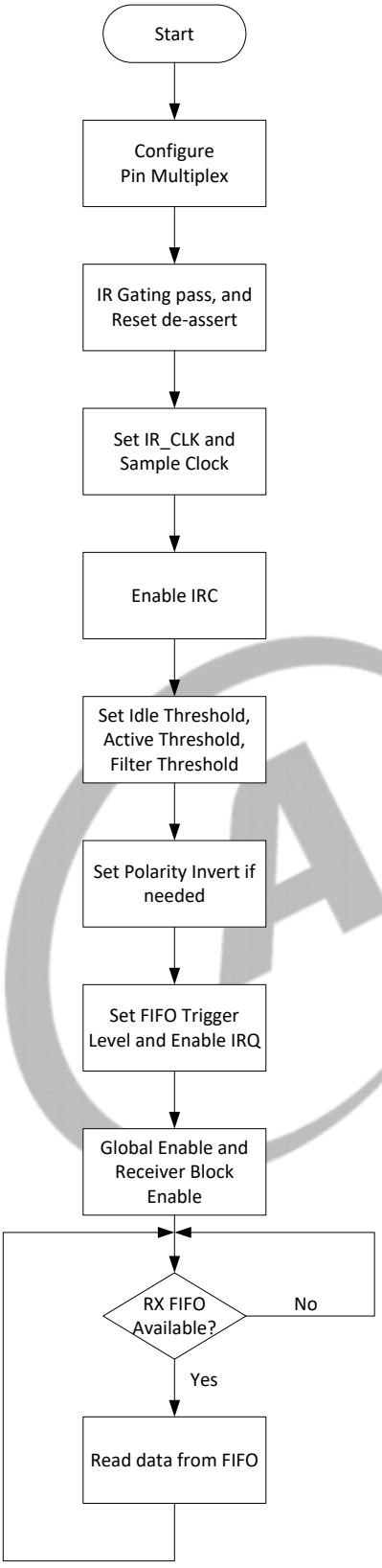
Figure 10-116 APAM Definition



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10.14.4 Programming Guidelines

Figure 10-117 CIR Receiver Process



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10.14.5 Register List

Module Name	Base Address
CIR_RX	0x07040000

Register Name	Offset	Description
CIR_CTL	0x0000	CIR Control Register
CIR_RXPCFG	0x0010	CIR Receiver Pulse Configure Register
CIR_RXFIFO	0x0020	CIR Receiver FIFO Register
CIR_RXINT	0x002C	CIR Receiver Interrupt Control Register
CIR_RXSTA	0x0030	CIR Receiver Status Register
CIR_RXCFG	0x0034	CIR Receiver Configure Register

10.14.6 Register Description

10.14.6.1 0x0000 CIR Receiver Control Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: CIR_CTL
Bit	Read/Write	Default/Hex	Description
31:8	/	/	/
7:6	R/W	0x0	APAM Active Pulse Accept Mode 00, 01: Both positive and negative pulses are valid as a leading code 10: Only negative pulse is valid as a leading code 11: Only positive pulse is valid as a leading code
5:4	R/W	0x0	CIR ENABLE 00~10: Reserved 11: CIR mode enable
3:2	/	/	/
1	R/W	0x0	RXEN Receiver Block Enable 0: Disable 1: Enable

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Offset: 0x0000			Register Name: CIR_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
0	R/W	0x0	GEN Global Enable A disable on this bit overrides any other block or channel enables and flushes all FIFOs. 0: Disable 1: Enable

10.14.6.2 0x0010 CIR Receiver Pulse Configure Register (Default Value: 0x0000_0004)

Offset: 0x0010			Register Name: CIR_RXPCFG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/
2	R/W	0x1	RPPI Receiver Pulse Polarity Invert 0: Do not invert receiver signal 1: Invert receiver signal
1:0	/	/	/

10.14.6.3 0x0020 CIR Receiver FIFO Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: CIR_RXFIFO
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R	0x0	RBF Receiver Byte FIFO

10.14.6.4 0x002C CIR Receiver Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x002C			Register Name: CIR_RXINT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:14	/	/	/

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Offset: 0x002C			Register Name: CIR_RXINT
Bit	**Read/Write**	**Default/Hex**	**Description**
13:8	R/W	0x0	RAL RX FIFO available received byte level for interrupt and DMA request TRIGGER_LEVEL = RAL + 1
5	R/W	0x0	DRQ_EN RX FIFO DMA Enable 0: Disable 1: Enable When it is set to '1', the Receiver FIFO DRQ is asserted if reaching RAL. The DRQ is de-asserted when the condition fails.
4	R/W	0x0	RAI_EN RX FIFO Available Interrupt Enable 0: Disable 1: Enable When it is set to '1', the Receiver FIFO IRQ is asserted if reaching RAL. The IRQ is de-asserted when the condition fails.
3:2	/	/	/
1	R/W	0x0	RPEI_EN Receiver Packet End Interrupt Enable 0: Disable 1: Enable
0	R/W	0x0	ROI_EN Receiver FIFO Overrun Interrupt Enable 0: Disable 1: Enable

10.14.6.5 0x0030 CIR Receiver Status Register (Default Value: 0x0000_0000)

Offset: 0x0030			Register Name: CIR_RXSTA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:15	/	/	/

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Offset: 0x0030			Register Name: CIR_RXSTA
Bit	**Read/Write**	**Default/Hex**	**Description**
14:8	R	0x0	RAC RX FIFO Available Counter 0: No available data in RX FIFO 1: 1-byte available data in RX FIFO 2: 2-bytes available data in RX FIFO … 64: 64-bytes available data in RX FIFO
7	R	0x0	STAT Status of CIR 0: Idle 1: Busy
6:5	/	/	/
4	R/W1C	0x0	RA RX FIFO Available 0: RX FIFO not available according to its level 1: RX FIFO available according to its level Writing 1 clears this bit.
3:2	/	/	/
1	R/W1C	0x0	RPE Receiver Packet End Flag 0: STO was not detected. In CIR mode, one CIR symbol is receiving or not detected. 1: STO field or packet abort symbol (7'b0000,000 and 8'b0000,0000 for MIR and FIR) is detected. In CIR mode, one CIR symbol is received. Writing 1 clears this bit.
0	R/W1C	0x0	ROI Receiver FIFO Overrun 0: Receiver FIFO not overrun 1: Receiver FIFO overrun Writing 1 clears this bit.

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10.14.6.6 0x0034 CIR Receiver Configure Register (Default Value: 0x0000_1828)

Offset: 0x0034			Register Name: CIR_RXCFG
Bit	**Read/Write**	**Default/Hex**	**Description**
31:25	/	/	/
24	R/W	0x0	SCS2 Bit2 of Sample Clock Select for CIR This bit is defined by SCS bits below.
23	R/W	0x0	ATHC Active Threshold Control for CIR 0: ATHR in a unit of (Sample Clock) 1: ATHR in a unit of (128*Sample Clocks)
22:16	R/W	0x0	ATHR Active Threshold for CIR These bits control the duration of CIR from the idle to the active state. The duration can be calculated by ((ATHR + 1)*(ATHC? Sample Clock: 128*Sample Clock)).
15:8	R/W	0x18	ITHR Idle Threshold for CIR The Receiver uses it to decide whether the CIR command is received. If there is no CIR signal on the air, the receiver is staying in IDLE status. One active pulse will bring the receiver from IDLE status to Receiving status. After the CIR receiver ends, the inputting signal will keep the specified level (high or low level) for a long time. The receiver can use this idle signal duration to decide that it has received the CIR command. The corresponding flag is asserted. If the corresponding interrupt is enabled, the interrupt line is asserted to the CPU. When the duration of the signal keeps one status (high or low level) for the specified duration ((ITHR + 1)*128 sample_clk), this means that the previous CIR command is finished.

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<table>
<tr><td colspan="3">Offset: 0x0034</td><td>Register Name: CIR_RXCFG</td></tr>
<tr><td>Bit</td><td>Read/Write</td><td>Default/Hex</td><td>Description</td></tr>
<tr><td>7:2</td><td>R/W</td><td>0xA</td><td>NTHR
Noise Threshold for CIR
When the duration of the signal pulse (high or low level) is less than NTHR, the pulse is taken as noise and should be discarded by hardware.
0: All samples are recorded into RX FIFO
1: If the signal is only one sample duration, it is taken as noise and discarded.
2: If the signal is less than (<=) two sample duration, it is taken as noise and discarded.
…
61: If the signal is less than (<=) sixty-one sample duration, it is taken as noise and discarded.</td></tr>
<tr><td>1:0</td><td>R/W</td><td>0x0</td><td>SCS
Sample Clock Select for CIR
<table>
<tr><td>SCS2</td><td>SCS[1]</td><td>SCS[0]</td><td>Sample Clock</td></tr>
<tr><td>0</td><td>0</td><td>0</td><td>CIR_CLK/64</td></tr>
<tr><td>0</td><td>0</td><td>1</td><td>CIR_CLK/128</td></tr>
<tr><td>0</td><td>1</td><td>0</td><td>CIR_CLK/256</td></tr>
<tr><td>0</td><td>1</td><td>1</td><td>CIR_CLK/512</td></tr>
<tr><td>1</td><td>0</td><td>0</td><td>CIR_CLK</td></tr>
<tr><td>1</td><td>0</td><td>1</td><td>Reserved</td></tr>
<tr><td>1</td><td>1</td><td>0</td><td>Reserved</td></tr>
<tr><td>1</td><td>1</td><td>1</td><td>Reserved</td></tr>
</table></td></tr>
</table>

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10.15 CIR Transmitter

10.15.1 Overview

The CIR transmitter (CIR_TX) can transfer arbitrary waves which can be modulated with configurable carrier waves such as 38 kHz.

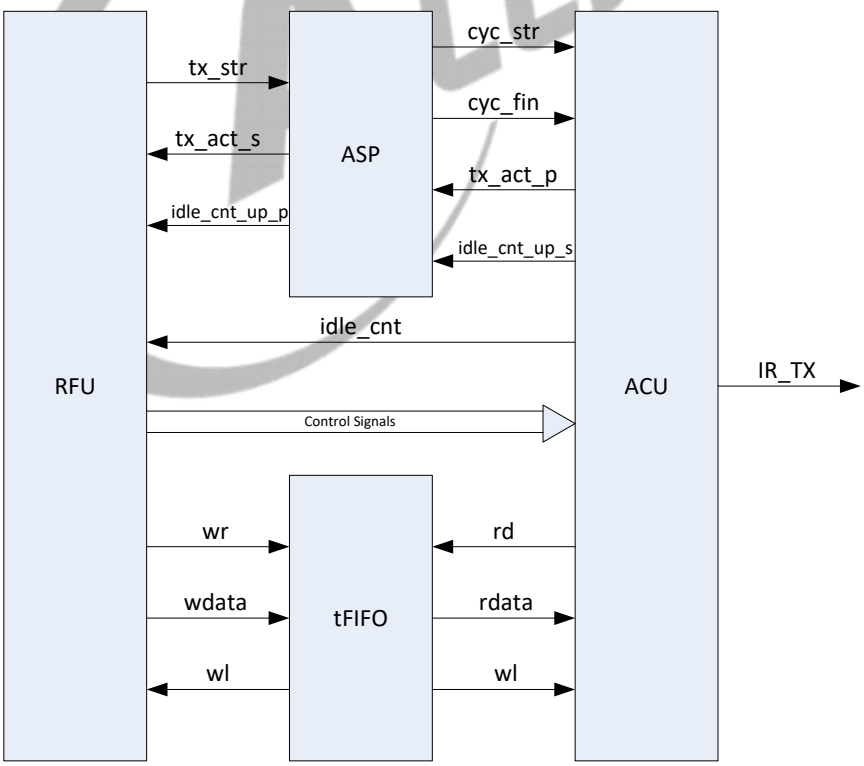
The CIR_TX has the following features:

- Supports CIR remote control transmitter
- 128 bytes FIFO for data buffer
- Configurable carrier frequency
- Supports Interrupt and DMA
- Supports handshake mode and waiting mode of DMA

10.15.2 Block Diagram

The following figure shows a block diagram of the CIR_TX.

Figure 10-118 CIR_TX Block Diagram



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10.15.3 Functional Description

10.15.3.1 External Signals

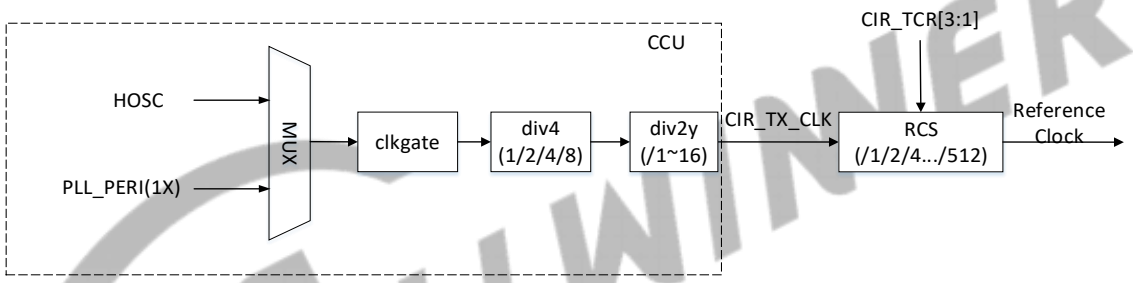
The following table describes the external signals of CIR_TX.

Table 10-44 CIR_TX External Signals

Signal	Description	Type
CIR-TX	Consumer infrared transmitter	O

10.15.3.2 Clock Sources

Figure 10-119 CIR_TX Clock Description



10.15.3.3 Function Implementation

The CIR_TX is used to generate a waveform of arbitrary length, arbitrary shape, and no high-speed requirement, and it can change the data into the high-/low-level sequence of a certain length. Every transmitting data is in bytes, the Bit[7] of a byte means whether the level of a transmitting wave is high or low, the Bit[6:0] is the length of this wave. If the current transmitting frequency-division is 1, 0x88 is a high level of 8 cycles, 0x08 is a low level of 8 cycles. If the current transmitting frequency-division is 4, 0x88 is a high level of 32 cycles, 0x08 is a low level of 32 cycles.

The CIR_TX has two transmission modes: non-cycle transmission, and cycle transmission.

The non-cycle transmission is to transmit all the data in TX_FIFO until the FIFO is empty.

The cycle transmission is to transmit all the data in TX_FIFO, after the transmission completion, wait for a certain time to recover the data in TX_FIFO and then send it until a stop signal is detected. The data recovery in FIFO is implemented by clearing the read pointer.

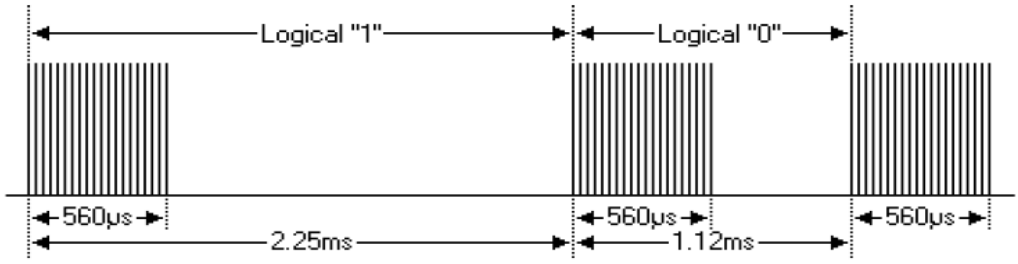
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10.15.3.4 Timing Diagram

The CIR remote control contains many protocols designed by different manufacturers. Here to NEC protocol as an example, the CIR-TX module uses a variable pulse-width modulation technique to encompass the various formats of infrared encoding for remote-control applications. A message is started by a 9 ms AGC burst, which is used to set the gain of the earlier CIR receivers. This AGC burst is then followed by a 4.5 ms space, which is then followed by the address and command.

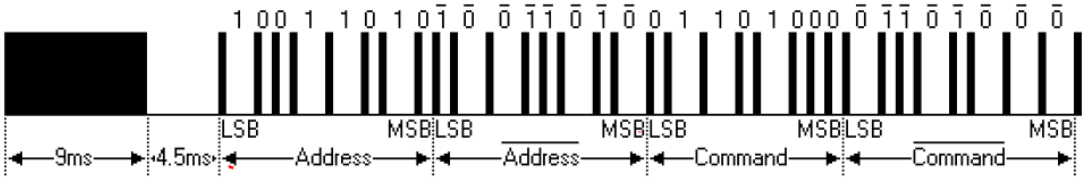
Bit definition: the logical “1” takes 2.25 ms to transmit, while a logical “0” is only 1.12 ms.

Figure 10-120 Definitions of Logical “1” and Logical “0”



Timing for a message:

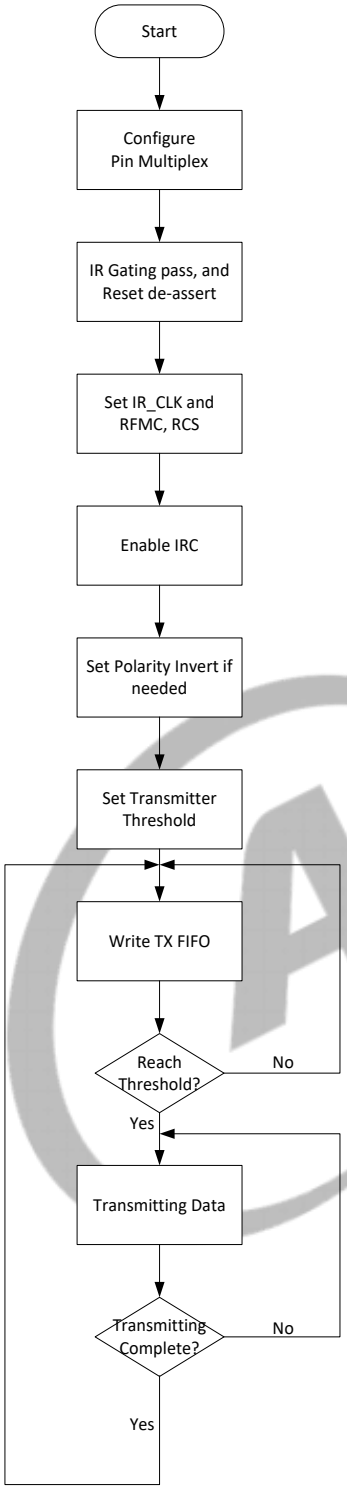
Figure 10-121 CIR Message Timing Diagram



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10.15.4 Programming Guidelines

Figure 10-122 CIR Transmitter Process



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10.15.5 Register List

Module Name	Base Address
CIR_TX	0x02003000

Register Name	Offset	Description
CIR_TGLR	0x0000	CIR Transmit Global Register
CIR_TMCR	0x0004	CIR Transmit Modulation Control Register
CIR_TCR	0x0008	CIR Transmit Control Register
CIR_IDC_H	0x000C	CIR Transmit Idle Duration Threshold High Bit Register
CIR_IDC_L	0x0010	CIR Transmit Idle Duration Threshold Low Bit Register
CIR_TICR_H	0x0014	CIR Transmit Idle Counter High Bit Register
CIR_TICR_L	0x0018	CIR Transmit Idle Counter Low Bit Register
CIR_TEL	0x0020	CIR TX FIFO Empty Level Register
CIR_TXINT	0x0024	CIR Transmit Interrupt Control Register
CIR_TAC	0x0028	CIR Transmit FIFO Available Counter Register
CIR_TXSTA	0x002C	CIR Transmit Status Register
CIR_TXT	0x0030	CIR Transmit Threshold Register
CIR_DMA	0x0034	CIR DMA Control Register
CIR_TXFIFO	0x0080	CIR Transmit FIFO Data Register

10.15.6 Register Description

10.15.6.1 0x0000 CIR Transmitter Global Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: CIR_TGLR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	IMS Internal Modulation Select 0: The transmitting signal is not modulated 1: The transmitting signal is modulated internally

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Offset: 0x0000			Register Name: CIR_TGLR
Bit	**Read/Write**	**Default/Hex**	**Description**
6:5	R/W	0x0	DRMC Duty ratio of modulated carrier is high level/low level. 00: Low level is equal to high level 01: Low level is the double of high level 10: Low level is the triple of high level 11: Reserved
4:3	/	/	/
2	R/W	0x0	TPPI Transmit Pulse Polarity Invert 0: Not invert transmit pulse 1: Invert transmit pulse
1	R/W	0x0	TR Transmit Reset When this bit is set, the transmitting is reset. The FIFO will be flushed, the TIC filed and the CSS field will be cleared during Transmit Reset. This field will automatically be cleared when the Transmit Reset is finished, and the CIR transmitter will state Idle.
0	R/W	0x0	TXEN Transmit Block Enable 0: Disable the CIR Transmitter 1: Enable the CIR Transmitter

10.15.6.2 0x0004 CIR Transmitter Modulation Control Register (Default Value: 0x0000_009E)

Offset: 0x0004			Register Name: CIR_TMCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x9E	RFMC Reference Frequency of modulated carrier. Reference Frequency of modulated carrier based on a division of a fixed functional clock (FCLK). The range of the modulated carrier is usually 30 kHz to 60 kHz. Most consumer electronics is 38 kHz. The default modulated carrier is 38 kHz when FCLK is 12 MHz. RFMC= FCLK/((N+1)*(DRMC+2)).

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10.15.6.3 0x0008 CIR Transmitter Control Register (Default Value: 0x0000_0000)

Offset: 0x0008			Register Name: CIR_TCR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7	R/W	0x0	CSS Cyclical Pulse Start/Stop Control 0: Stop when cleared to '0'. From start to stop, all data in FIFO must be transmitted. 1: Start. Start to transmit when it is set to '1'.
6:4	/	/	/
3:1	R/W	0x0	RCS Reference Clock Select for CIR Transmit The data in TX_FIFO is used to describe the pulse in Run-Length Code. The basic unit of pulse width is Reference Clock. 000: CIR Transmit reference clock is ir_clk 001: CIR Transmit reference clock is ir_clk/2 010: CIR Transmit reference clock is ir_clk/4 011: CIR Transmit reference clock is ir_clk/8 100: CIR Transmit reference clock is ir_clk/64 101: CIR Transmit reference clock is ir_clk/128 110: CIR Transmit reference clock is ir_clk/256 111: CIR Transmit reference clock is ir_clk/512
0	R/W	0x0	TTS Type of the transmission signal 0: The transmitting wave is a single non-cyclical pulse. 1: The transmitting wave is a cyclical short-pulse.

10.15.6.4 0x000C CIR Transmitter Idle Duration Counter High Bit Register (Default Value: 0x0000_0000)

Offset: 0x000C			Register Name: CIR_IDC_H
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/

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Offset: 0x000C			Register Name: CIR_IDC_H
Bit	**Read/Write**	**Default/Hex**	**Description**
3:0	R/W	0x0	IDC_H Idle Duration Counter Threshold (High 4 bits) Idle Duration = 128*IDC*Ts (IDC = 0~4095) It is used in cyclical transmission mode. When all the data in FIFO is transmitted, the signals can be transmitted after a specific time.

10.15.6.5 0x0010 CIR Transmitter Idle Duration Counter Low Bit Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: CIR_IDC_L
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
3:0	R/W	0x0	IDC_L Idle Duration Counter Threshold (Low 8 bits) Idle Duration = 128*IDC*Ts (IDC = 0~4095) It is used in cyclical transmission mode. When all the data in FIFO is transmitted, the signals can be transmitted after a specific time.

10.15.6.6 0x0014 CIR Transmitter Idle Counter High Bit Register (Default Value: 0x0000_0000)

Offset: 0x0014			Register Name: CIR_TICR_H
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R	0x0	TIC_H Transmit Idle Counter_H (High 8 bits) It is used to count the idle duration of CIR transmitter by software. Count in 128*Ts (Sample Duration, 1/Fs) when the transmitter is idle, and it should be reset when the transmitter is active. When this counter reaches the maximum value (0xFFFF), it will stop automatically, and should not be cleared to zero.

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10.15.6.7 0x0018 CIR Transmitter Idle Counter Low Bit Register (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: CIR_TICR_L
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R	0x0	TIC_L Transmit Idle Counter_L (Low 8 bits) It is used to count the idle duration of CIR transmitter by software. Count in 128*Ts (Sample Duration, 1/Fs) when the transmitter is idle, and it should be reset when the transmitter is active. When this counter reaches the maximum value (0xFFFF), it will stop automatically, and should not be cleared to zero.

10.15.6.8 0x0020 CIR Transmitter FIFO Empty Register (Default Value: 0x0000_0000)

Offset: 0x0020			Register Name: CIR_TEL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x0	TEL TX FIFO empty Level for DRQ and IRQ. TRIGGER_LEVEL = TEL + 1

10.15.6.9 0x0024 CIR Transmitter Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: CIR_TXINT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:3	/	/	/
2	R/W	0x0	DRQ_EN TX FIFO DMA Enable 0: Disable 1: Enable When it is set to '1', the TX FIFO DRQ is asserted if the number of the transmitting data in the FIFO is less than the RAL. The DRQ is de-asserted when the condition fails.

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Offset: 0x0024			Register Name: CIR_TXINT
Bit	**Read/Write**	**Default/Hex**	**Description**
1	R/W	0x0	TAI_EN TX FIFO Available Interrupt Enable 0: Disable 1: Enable
0	R/W	0x0	TPEI_EN Transmit Packet End Interrupt Enable for Cyclical Pulse 0: Disable 1: Enable TUI_EN Transmitter FIFO Underrun Interrupt Enable for Non-cyclical Pulse 0: Disable 1: Enable

10.15.6.10 0x0028 CIR Transmitter FIFO Available Counter Register (Default Value: 0x0000_0080)

Offset: 0x0028			Register Name: CIR_TAC
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R	0x80	TAC TX FIFO Available Space Counter 0x00: No available space in TX FIFO 0x01: 1 byte available space in TX FIFO 0x02: 2 bytes available space in TX FIFO … 0x80: 128 bytes available space in TX FIFO

10.15.6.11 0x002C CIR Transmitter Status Register (Default Value: 0x0000_0002)

Offset: 0x002C			Register Name: CIR_TXSTA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/

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Offset: 0x002C			Register Name: CIR_TXSTA
Bit	**Read/Write**	**Default/Hex**	**Description**
3	R	0x0	STCT Status of CIR Transmitter 0: Idle 1: Active This bit will automatically set when the controller begins to transmit the data in the FIFO. The “1” will last when the data in the FIFO. It will automatically be cleared to “0” when all data in the FIFO is transmitted. The bit is for debugging. The output Level of Idle state is determined by the level of the last data output.
2	R	0x0	DRQ DMA Request Flag When set to ‘1’, the TX FIFO DRQ is asserted if the number of the transmission data in the FIFO is less than the RAL. The DRQ is de-asserted when the condition fails. This bit is for debugging.
1	R/W	0x1	TAI TX FIFO Available Interrupt Flag 0: TX FIFO not available by its level 1: TX FIFO available by its level Writing 1 clears this bit.
0	R/W	0x0	TPE Transmitter Packet End Flag for Cyclical Pulse 0: Transmissions of address, control and data fields not completed 1: Transmissions of address, control and data fields completed TUR Transmitter FIFO Underrun Flag for Non-cyclical Pulse 0: No transmitter FIFO underrun 1: Transmitter FIFO underrun Writing 1 clears this bit.

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10.15.6.12 0x0030 CIR Transmitter Threshold Register (Default Value: 0x0000_0000)

Offset: 0x0030			Register Name: CIR_TXT
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0x0	NCTT Non-cyclical Pulse Transmit Threshold The controller will trigger transmitting the data in the FIFO when the data byte number has reached the Transmit Threshold set in this field.

10.15.6.13 0x0034 CIR Transmitter DMA Control Register (Default Value: 0x0000_00A5)

Offset: 0x0034			Register Name: CIR_DMA_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	R/W	0xA5	DMA Handshake Configuration 0xA5: DMA waiting cycle mode 0xEA: DMA handshake mode

10.15.6.14 0x0080 CIR Transmitter FIFO Data Register (Default Value: 0x0000_0000)

Offset: 0x0080			Register Name: CIR_TXFIFO
Bit	**Read/Write**	**Default/Hex**	**Description**
31:8	/	/	/
7:0	W	0x0	TBF Transmit Byte FIFO When the transmission is triggered, the data in the FIFO will be transmitted until the data number is transmitted completely.

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11 Security System

11.1 Crypto Engine

11.1.1 Overview

The Crypto Engine (CE) module is one encryption/decryption algorithm accelerator. It supports kinds of symmetric, asymmetric, Hash, and RNG algorithms.

The symmetric algorithm supports data encryption and decryption by following the data encryption standard (DES), 3DES, or advanced encryption standard (AES) algorithms. It can encrypt or decrypt a large amount of data effectively.

The Rivest-Shamir-Adleman (RSA) asymmetric algorithm is used for data encryption/decryption and digital signature verification. It is a public key encryption/decryption algorithm implemented through the modular exponentiation operation.

The Hash algorithm supports data integrity authentication and digital signature. The hash supports MD5, SHA1, SHA224, SHA256, SHA384, SHA512, HMAC-SHA1, and HMAC-SHA256 algorithms.

The RNG algorithm can generate true-random numbers and pseudo-random numbers.

The R528 has two separate CE controllers: one CE is for secure world, the other CE is for non-secure world. The software interface of the controller is simple, only setting interrupt control, task description address, and load tag. The algorithm control information is written in memory by task descriptor, then the CE automatically reads it when executing a request. It supports parallel execution of 4 channels and has an internal DMA controller to transfer data between CE and memory.

The CE has the following features:

- Symmetrical algorithm: AES, DES, 3DES
- Hash algorithm: MD5, SHA1, SHA224, SHA256, SHA384, SHA512, HMAC-SHA1, HMAC-SHA256
- Asymmetrical algorithm: RSA512/1024/2048-bit
- 160-bit hardware PRNG with 175-bit seed
- 256-bit hardware TRNG
- Electronic codebook (ECB), cipher block chaining (CBC), counter (CTR), cipher text stealing (CTS), 128-output feedback (OFB), 1-/8-/64-/128-cipher feedback (CFB) modes for AES algorithm
- ECB, CBC, CTR modes for DES/3DES algorithm
- 128-, 192-, 256-bit key size for AES algorithms
- 16-, 32-, 64-, 128-bit wide size for AES CTR mode

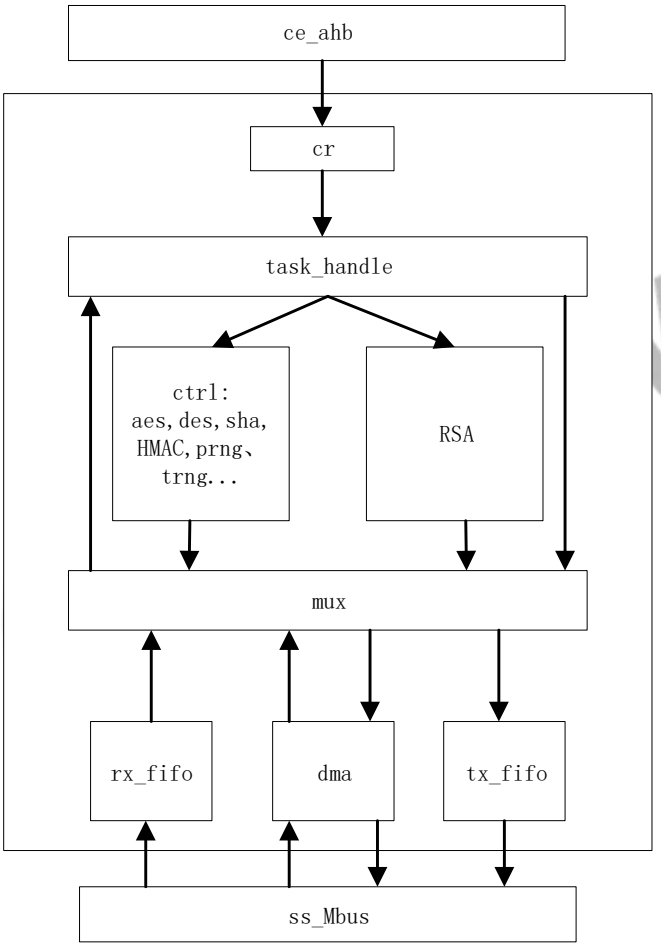
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- 16-, 32-, 64-bit wide size for DES/3DES CTR mode
- One or more blocks mode for MD5/SHA1/SHA224/SHA256/SHA384/SHA512
- Internal DMA controller for data transfer with memory
- Supports secure and non-secure interfaces respectively

11.1.2 Block Diagram

The following figure shows the block diagram of Crypto Engine.

Figure 11-1 CE Block Diagram



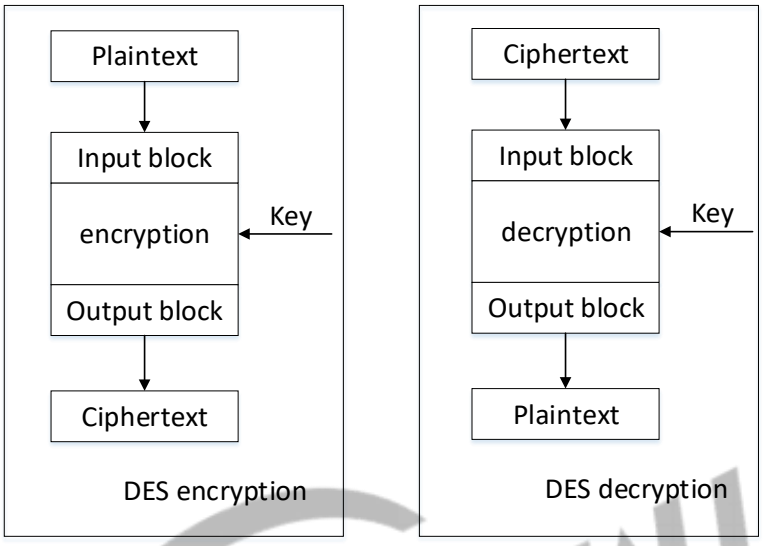
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11.1.3 Functional Description

11.1.3.1 DES Algorithm

Figure 11-2 shows the DES encryption and decryption operation.

Figure 11-2 DES Encryption and Decryption

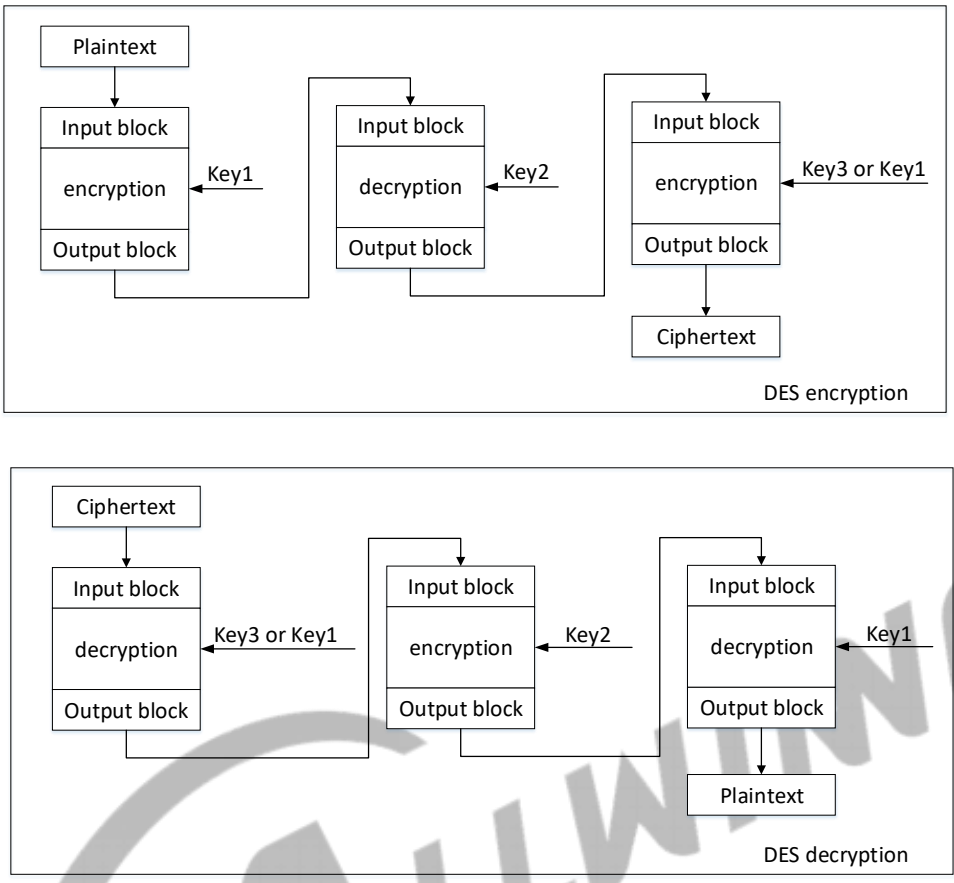


11.1.3.2 3DES Algorithm

The 3DES algorithm supports both 3-key and 2-key operations. A 2-key operation can be regarded as a simplified 3-key operation. To be specific, key 3 is represented by key 1 in a 2-key operation. Figure 11-3 shows the 3DES encryption and decryption operation of a 3-key operation and a 2-key operation.

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Figure 11-3 3DES Encryption and Decryption of a 3-key Operation and a 2-key Operation



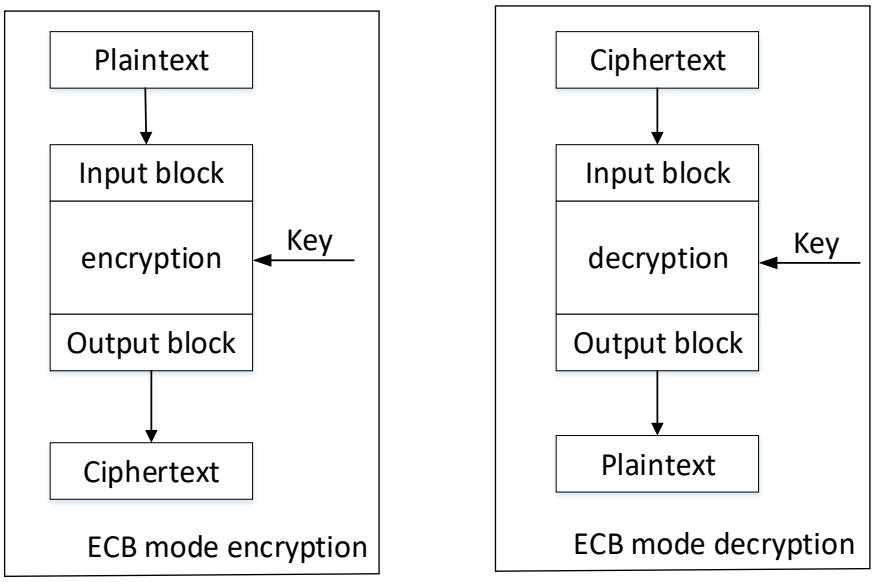
11.1.3.3 ECB Mode

The ECB mode is a confidentiality mode that features, for a given key, the assignment of a fixed ciphertext block to each plaintext block, analogous to the assignment of code words in a codebook.

In ECB mode, encryption and decryption algorithms are directly applied to the block data. The operation of each block is independent, so the plaintext encryption and ciphertext decryption can be performed concurrently.

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Figure 11-4 ECB Mode Encryption and Decryption

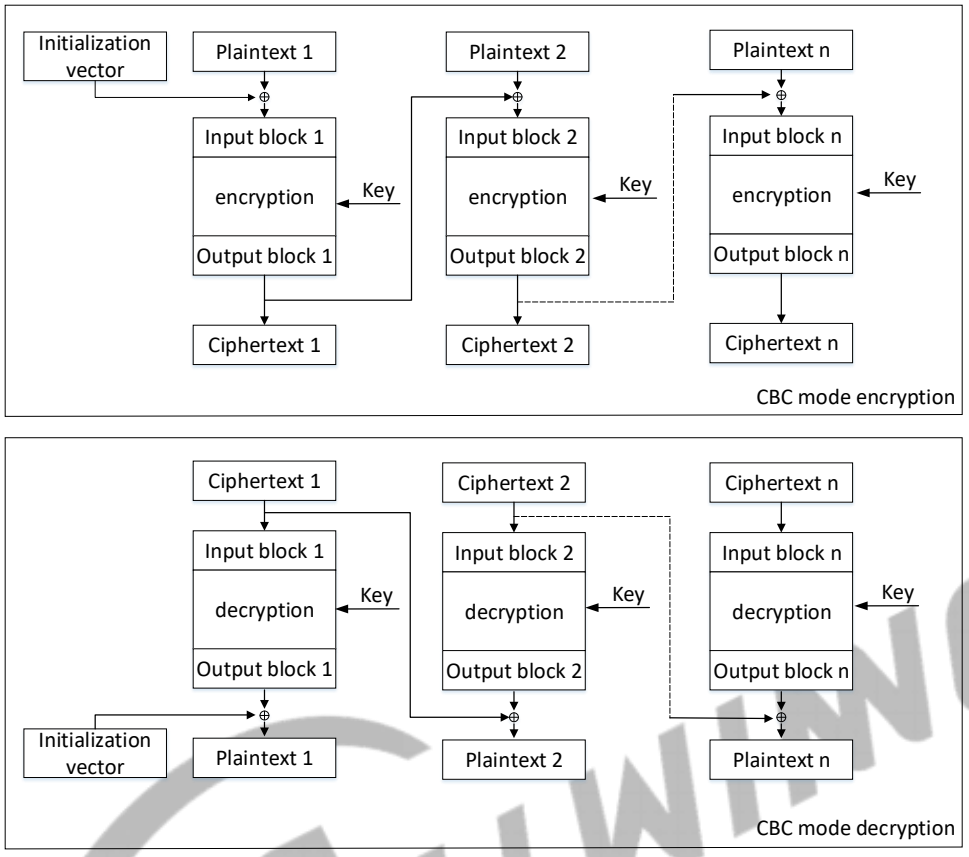


11.1.3.4 CBC Mode

The CBC mode is a confidentiality mode whose encryption process features the combining of the plaintext blocks with the previous ciphertext blocks. The CBC mode requires an initialization vector (IV) to combine with the first plaintext block. The encryption process of each plaintext block is related to the block processing result of the previous ciphertext blocks, so encryption operations cannot be concurrently performed in CBC mode. The decryption operation is independent of output plain text of the previous block, so decryption operations can be performed concurrently.

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Figure 11-5 CBC Mode Encryption and Decryption

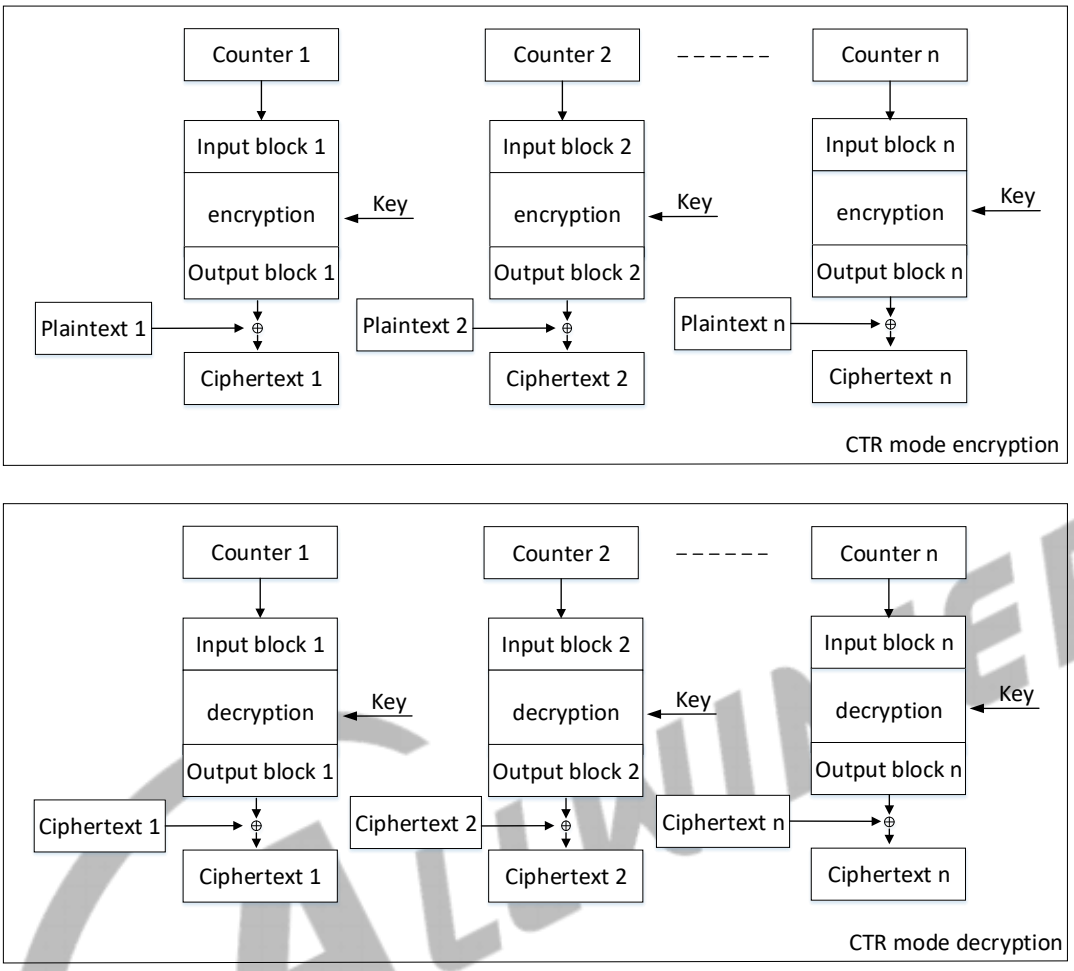


11.1.3.5 CTR Mode

The CTR mode is a confidentiality mode that features the application of the forward cipher to a set of input blocks, called counters, to produce a sequence of output blocks that are exclusive-ORed with the plaintext to produce the ciphertext, and vice versa. All of the counters must be distinct.

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Figure 11-6 CTR Mode Encryption and Decryption



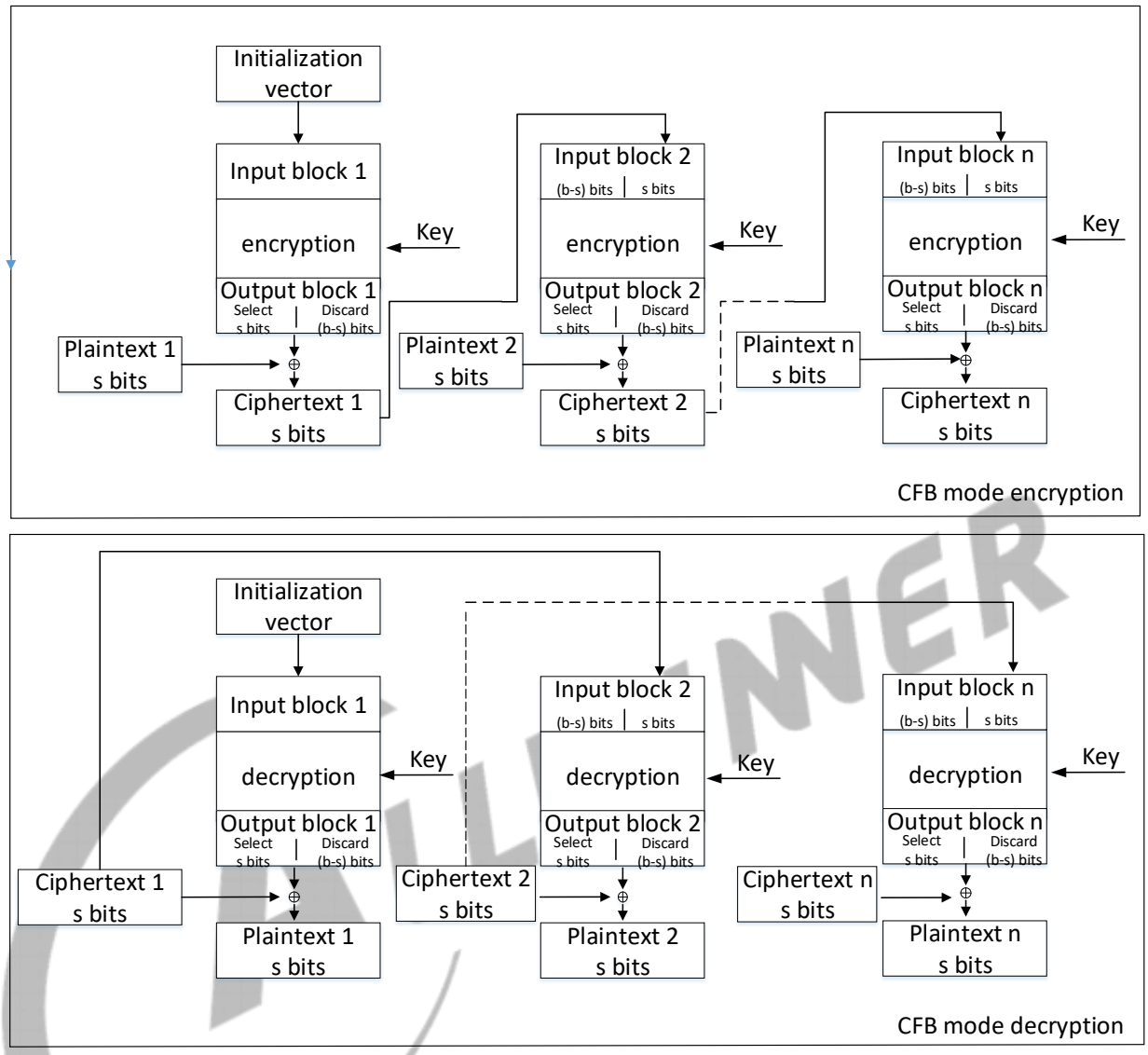
11.1.3.6 CFB Mode

The CFB mode is a confidentiality mode that features the feedback of successive ciphertext segments into the input blocks of the forward cipher to generate output blocks that are exclusive-ORed with the plaintext to produce the ciphertext, and vice versa. The CFB mode requires an IV as the initial input block, and the forward cipher operation is applied to the IV to produce the first output block. The first ciphertext segment is produced by exclusive-ORing the first plaintext segment with the *s* most significant bits of the first output block. The value of s is 1 bit, 8 bits, 64 bits, or 128 bits.

The following figure shows the s-bit CFB mode of the AES algorithms.

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Figure 11-7 CFB Mode Encryption and Decryption

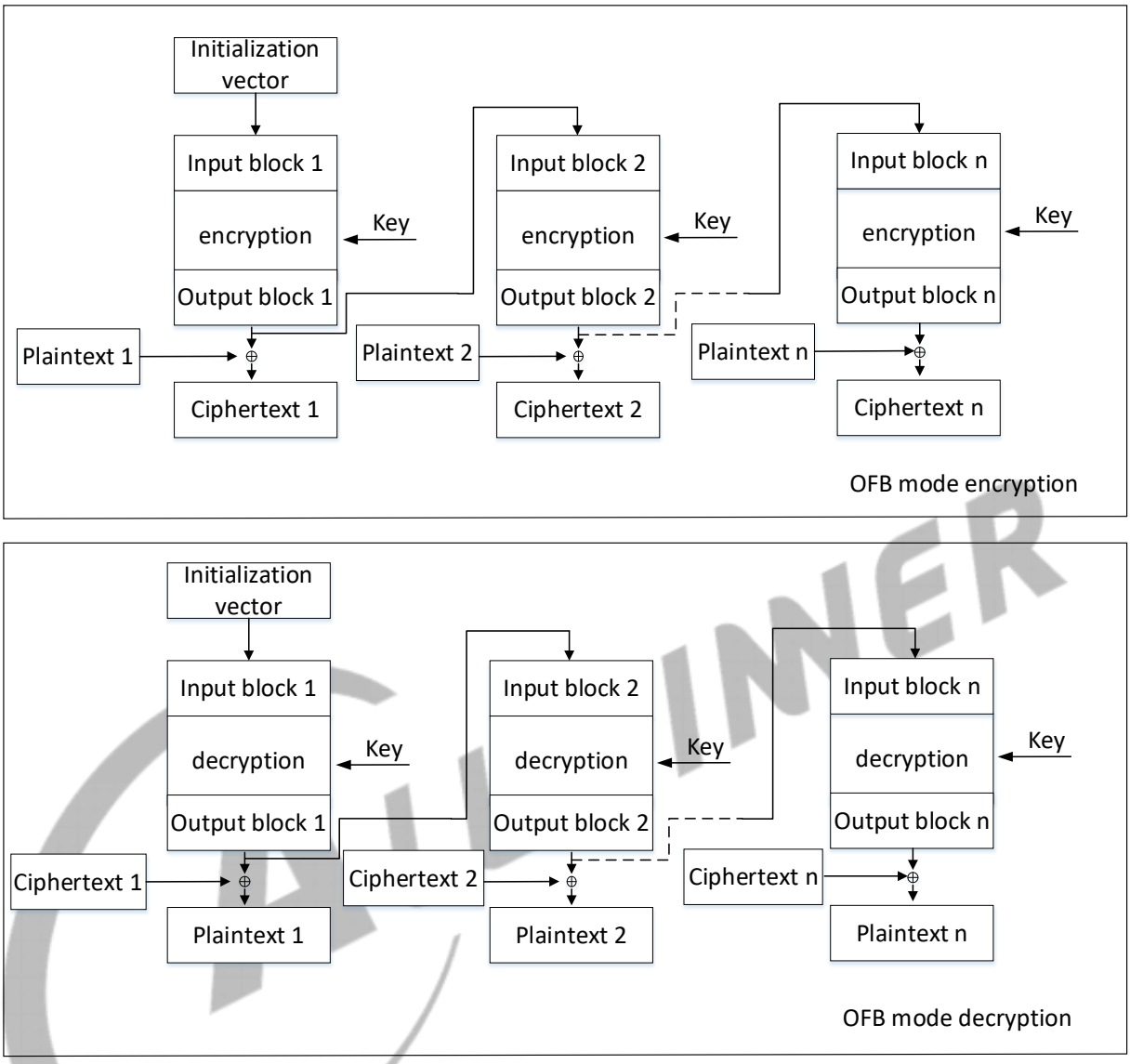


11.1.3.7 OFB Mode

The OFB mode is a confidentiality mode that features the iteration of the forward cipher on an IV to generate a sequence of output blocks that are exclusive-ORed with the plaintext to produce the ciphertext, and vice versa. If a same key is used, different IVs must be used to ensure operation security.

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Figure 11-8 OFB Mode Encryption and Decryption

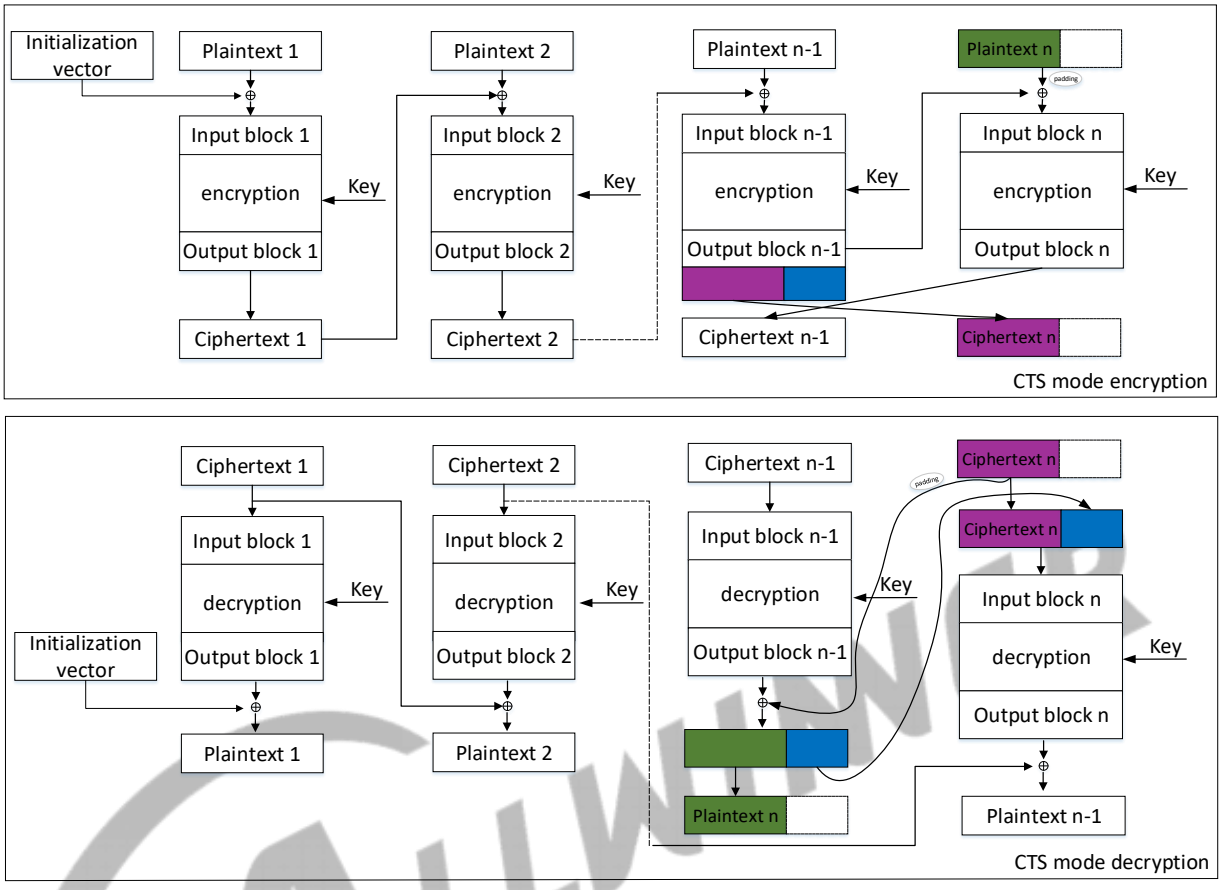


11.1.3.8 CTS Mode

The CTS mode is a confidentiality mode that accepts any plaintext input whose bit length is greater than or equal to the block size but not necessarily a multiple of the block size. Below are the diagrams for CTS encryption and decryption.

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Figure 11-9 CTS Mode Encryption and Decryption



11.1.3.9 HASH Algorithm

The hash algorithms support MD5, SHA1, SHA224, SHA256, SHA384, SHA512, HMAC-SHA1, and HMAC-SHA256. All algorithms are iterative, one-way hash functions that can process a message to produce a condensed representation called a *message digest*. When a message is received, the *message digest* can be used to verify whether the data has changed, that is, to verify its integrity.

The hash algorithm of R528 supports block-aligned total length of the input data (padded by software), that is, a multiple of 64 bytes. The message length after padding by software is used as the configured data length for the hash algorithm.

11.1.3.10 RSA Algorithm

The RSA is a public key encryption/decryption algorithm implemented through the modular exponentiation operation.

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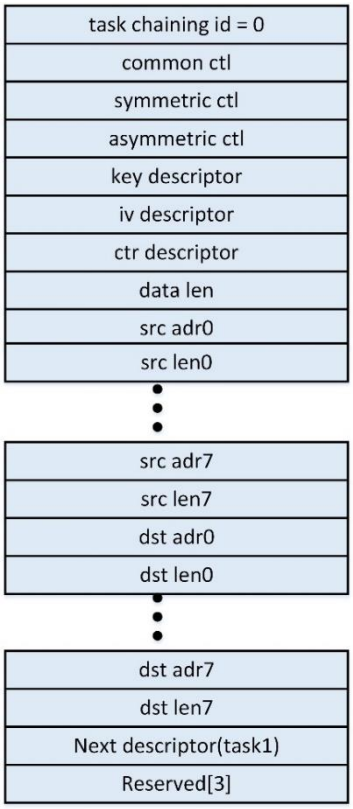
The ciphertext is obtained as follows: $C = M^E \bmod N$. The plaintext is obtained as follows: $M = C^D \bmod N$.

M indicates the plaintext, C indicates the ciphertext, (N, E) indicates the public key, and (N, D) indicates the private key.

11.1.3.11 Task Descriptor

The software makes request through task descriptor, including algorithm type, algorithm mode, key address, source/destination address and size, and so on. The structure of the task descriptor is as follows.

Figure 11-10 Structure of Task Descriptor Chaining



The bit definitions of the task descriptor are as follows.

Task ID

Bit	Read/Write	Default/Hex	Description
31:4	/	/	/

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Bit	Read/Write	Default/Hex	Description
3:0	R/W	0x0	CHN Task channel ID Indicates which channel the task is running on. It supports 0 to 3.

Common Control

Bit	Read/Write	Default/Hex	Description
31	R/W	0x0	Interrupt enable (IE) for the current task 0: disable interrupt 1: enable interrupt Represents whether an interrupt signal is generated when the task chain ends at the end of this task. When the last task in a task chain ends, the operation of the task chain will end normally; if a task fails in the middle, the task chain will be aborted abnormally. And it is determined whether to generate an interrupt signal according to the IE configuration of the current task when the current task ends or aborts. Therefore, if you want to use interrupts, it is recommended that not only the IE of the last task of each task chain is configured to 1 to generate the end interrupt of the task chain, but also the IEs of other tasks in this task chain are also configured to 1. The purpose is to generate an interrupt signal once an abnormal error occurs in these tasks and the interrupt is aborted.
30:17	/	/	/
16	R/W	0x0	IV mode IV mode for SHA1/SHA224/SHA256/SHA384/SHA512/MD5 or constants 0: use initial constants defined in FIPS-180 1: use input iv
15	R/W	0x0	Last HMAC plaintext 0: not the last HMAC plaintext package 1: the last HMAC plaintext package
14:9	/	/	/

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Bit	Read/Write	Default/Hex	Description
8	R/W	0x0	OP DIR Algorithm Operation Direction 0: Encryption 1: Decryption Configure according to the requirements of encryption or decryption.
7	/	/	/
6:0	R/W	0x0	Algorithm Type 0x0: AES 0x1: DES 0x2: Triple DES (3DES) 0x10: MD5 0x11: SHA-1 0x12: SHA-224 0x13: SHA-256 0x14: SHA-384 0x15: SHA-512 0x16: HMAC-SHA1 0x17: HMAC-SHA256 0x20: RSA 0x30: TRNG 0x31: PRNG Others: reserved

Symmetric Control

Bit	Read/Write	Default/Hex	Description
31:24	/	/	/
23:20	R/W	0x0	KEY_SELECT key select for AES 0000: Select input CE_KEYx (Normal Mode) 0001: Select {SSK} 0010: Select {HUK} 0011: Select {RSSK} 0100-0111: Reserved 1000-1111: Select internal Key n (n from 0 to 7)

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Bit	Read/Write	Default/Hex	Description
19:18	R/W	0x0	CFB_WIDTH AES-CFB width 00: CFB1 01: CFB8 10: CFB64 11: CFB128
17	R/W	0x0	PRNG_LD Load new 15 bits key into linear feedback shift register (LFSR) for PRNG. When the algorithm type is PRNG, it is necessary to post-process the random number output by PRNG through the linear shift operation to generate the operand. When the PRNG_LD is configured to 1, use iv_addr[14:0] as the input number for linear shift operation, and do XOR operation between the data and the random number output by PRNG to generate the post-processing result of further operation.
16	R/W	0x0	CTS_LPKG AES CTS last package flag When set to '1', it means this is the last package for AES-CTS mode (the size of the last package is larger than 128 bits).
15:12	/	/	/
11:8	R/W	0x0	ALGORITHM_MODE CE algorithm mode 0000: Electronic Code Book (ECB) mode 0001: Cipher Block Chaining (CBC) mode 0010: Counter (CTR) mode 0011: Cipher Text Stealing (CTS) mode 0100: Output Feedback (OFB) mode 0101: Cipher Feedback (CFB) mode Other: reserved
7:4	/	/	/
3:2	R/W	0x0	CTR WIDTH Counter width for CTR mode 00: 16-bit Counter 01: 32-bit Counter 10: 64-bit Counter 11: 128-bit Counter

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Bit	Read/Write	Default/Hex	Description
1:0	R/W	0x0	AES KEY SIZE 00: 128-bit 01: 192-bit 10: 256-bit 11: Reserved

Asymmetric Control

Bit	Read/Write	Default/Hex	Description
31	/	/	/
30:28	R/W	0x0	RSA Pubic Modulus Width 000: 512-bit 001: 1024-bit 010: 2048-bit Other: reserved
27:19	/	/	/
18:16	R/W	0x0	RSA MODE RSA algorithm mode. For modular computation: 000: modular exponent(RSA) 001: modular div 010: modular mul 011: modular inv others: reserved
15:0	/	/	/

Key Descriptor

Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	Key Address The address of KEY that needs to be stored.

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IV Descriptor

Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	IV Address The address of IV that needs to be stored.

Counter Descriptor

Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	CTR Data Output Address The address of CTR data output that needs to be stored.

Data Length

Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	Data Length Configure the data length of the corresponding segment. The data length size needs to be consistent with dst_data_length (destination data length 0 +... + destination data length 7). The data length field in the task descriptor has different meanings for different algorithms. For AES-CTS, the data length field indicates byte numbers of source data, for others indicate word numbers of source data. For PRNG, the data length should be 5 words aligned. For TRNG, it should be 8 words aligned.

Source Address 0~7

Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	Source Data Address The address of the source data that needs to be stored.

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Source Data Length 0~7

Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	Source Data Length The length of the source data. Unit: byte

Destination Address 0~7

Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	Destination Data Address The address of the destination data that needs to be stored.

Destination Data Length 0~7

Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	Destination Data Length The length of the destination data. Unit: byte

Next Descriptor Address

Bit	Read/Write	Default/Hex	Description
31:0	R/W	0x0	Next Task Address The address where the descriptor of the next task in a task-chain is saved. If there is the only task or the last task of a task-chain, the next task address must be 32'h0.

11.1.3.12 Storing Message

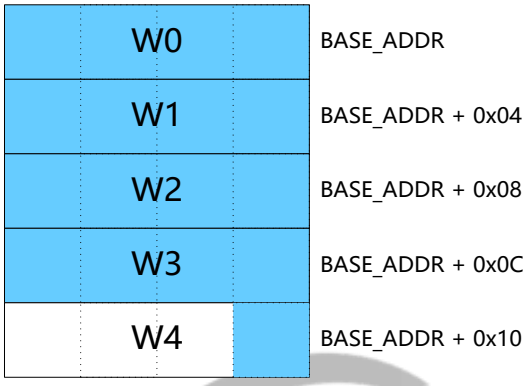
In the application, a message may not be stored contiguously in the memory, but divided into multiple segments. Or a piece of continuously stored messages can be artificially split into multiple pieces as needs.

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Then each segment corresponds to a set of the source address and source length in the descriptor. Multiple segments correspond to groups 0-7 source address/source length in sequence.

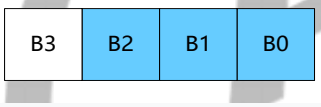
Each task supports up to 8 message segments, and the data volume of each message segment supports up to 4 GWord (AES-CTS is 1 GByte). The total amount of all segments in a task (that is a package) supports up to 4 GWord (AES-CTS is 1 GByte). If a message is divided into multiple packages, all others are required to be whole words; when the last package of AES-CTS is less than one word, 0 needs to be padded, and those less than one word are counted as one word. The following figure shows the address order structure.

Figure 11-11 Word Address of Message



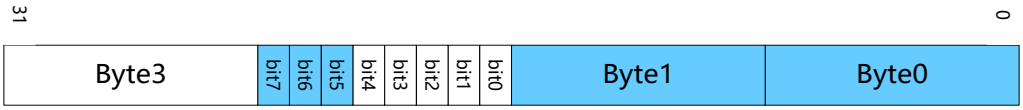
Byte order: low byte first, high byte last. When the data is less than one word, the low byte is filled first. The following figure shows the byte order structure (blue means it is filled by the message).

Figure 11-12 Byte Order



Bit order: high bit first, low bit last. When the data is less than one Byte, the high bit is filled first. The following figure shows the bit order structure.

Figure 11-13 Bit Order



11.1.3.13 Storing Key

The length of KEY must be an integer multiple of word, refer to section 10.1.3.15 “Algorithm Length Properties”.

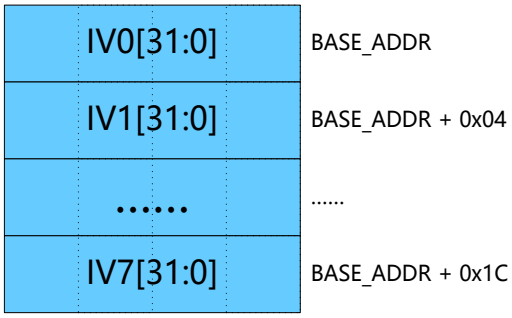
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11.1.3.14 Storing IV

For different algorithms, the length of IV is different. But they are integer multiples of word. To keep the byte order of IV and HASH digest output consistent, the byte order of IV is different from that of the message. For the multi-packet operation, the first address of the digest output result of the previous HASH can be directly configured to the first address of the next IV, and the software does not need to do any processing on the digest.

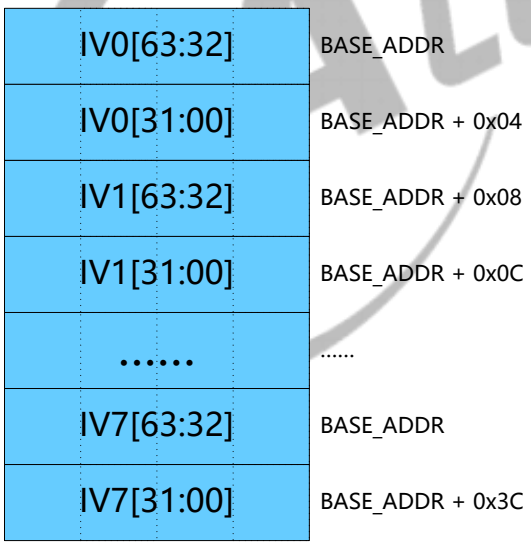
The following figure shows the storage method of 32-bit IV value.

Figure 11-14 The Storage Method of 32-bit IV



The following figure shows the storage method of 64-bit IV value.

Figure 11-15 The Storage Method of 64-bit IV



11.1.3.15 Algorithm Length Properties

The algorithm length has different requirements for different algorithms.

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Table 10-1 Symmetric Algorithm Configuration Properties

Algorithm	Length Setting				Alignment	Software Padding
	Source Size	Destination Size	KEY	IV		
AES (except CTS)	< 4 GWord	< 4 GWord	AES-128: 4 Word AES-192: 6 Word AES 256: 8 Word	4 Word	Word-aligned	need
AES-CTS	< 1 GByte	< 1 GByte	AES-128: 4 word AES-192: 6 word AES 256: 8 word	4 Word	Word-aligned	need
DES	< 4 GWord	< 4 GWord	2 Word	2 Word	Word-aligned	need
TDES	< 4 GWord	< 4 GWord	6 Word	2 Word	Word-aligned	need

Table 10-2 Hash Algorithm Configuration Properties

Algorithm	Length Setting				Alignment	Software Padding
	Source Size	Destination Size	KEY	IV		
MD5	< 4 GWord	4 Word	Fixed to 0	4 Word	Word-aligned	need
SHA-1	< 4 GWord	5 Word	Fixed to 0	5 Word	Word-aligned	need
SHA-224	< 4 GWord	8 Word	Fixed to 0	8 Word	Word-aligned	need
SHA-256	< 4 GWord	8 Word	Fixed to 0	8 Word	Word-aligned	need
SHA-384	< 4 GWord	16 Word	Fixed to 0	16 Word	Word-aligned	need
SHA-512	< 4 GWord	16 Word	Fixed to 0	16 Word	Word-aligned	need
HMAC-SHA1	< 4 GWord	5 Word	16 Word	5 Word	Word-aligned	need
HMAC-SHA256	< 4 GWord	8 Word	16 Word	8 Word	Word-aligned	need

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Table 10-3 RNG Configuration Properties

Algorithm	Length Setting				Alignment	Software Padding
	Source Size	Destination Size	KEY	IV		
TRNG	< 4 GWord	< 4 GWord	Fixed to 0	4 Word	Word-aligned	need
PRNG	< 4 GWord	< 4 GWord	6 Word	4 Word	Word-aligned	need

Table 10-4 Asymmetric Algorithm Configuration Properties

Algorithm	Length Setting				Alignment	Software Padding
	Source Size	Destination Size	KEY	IV		
RSA512	16 Word	16 Word	16 Word	Not use IV	Word-aligned	need
RSA1024	32 Word	32 Word	32 Word	Not use IV	Word-aligned	need
RSA2048	64 Word	64 Word	64 Word	Not use IV	Word-aligned	need

11.1.3.16 Security Operation

When the CPU issues request to the CE module, the CE module will save the secure mode of CPU. When executing this request, this state bit works as a access flag for the inner and system resources. For access to SID module through the AHB bus, only the secure mode can succeed, or else these keys will be read to 0 or cannot write. When issuing MBUS read and write requests, the CE will use send this secure mode bit to BUS, so secure requests can access secure and non-secure space, but non-secure requests only can access non-secure space.

11.1.3.17 Error Detection

The CE module includes error detection for task configuration, data computing error, and authentication invalid. When the algorithm type in task descriptor is read into the CE module, the CE will check whether this type is supported through checking algorithm type field in common control. If the type value is out of scope, the CE will issue interrupt signal and set error state. Each type has certain input and output data size. After getting a task descriptor, the input size and output size configuration will be checked to avoid size error. If the size configuration is wrong, the CE will issue interrupt signal and set error state.

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11.1.3.18 Clock Requirement

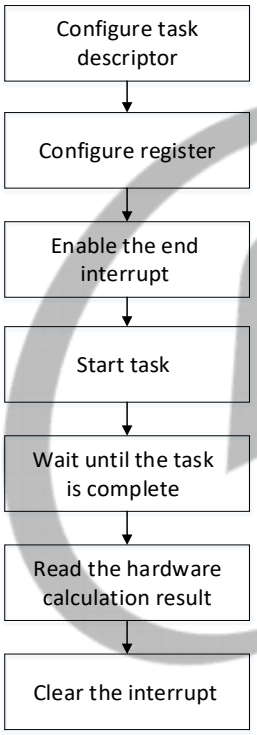
Clock Name	Description	Requirement
hclk	AHB bus clock	24 MHz – 200 MHz
mclk	MBUS clock	24 MHz – 400 MHz
ce_clk	CE work clock	24 MHz – 400 MHz

11.1.4 Programming Guidelines

11.1.4.1 Symmetrical/Asymmetrical/Hash/RNG Algorithm Operation Process

The following figure shows the process of an algorithm operation.

Figure 11-16 Task Request Process



Step 1 The software should configure a task descriptor in memory, including the related fields in the descriptor. The channel id corresponds to one channel in CE. According to algorithm type, the software should set the fields in common control, symmetric control, asymmetric control, then provide key/iv/ctr address and the data length of this task. The source and destination address and size are set based on the upper application. If there is another task concatenating after this task, then set its descriptor address at the next descriptor field. For more details for task descriptor, see section 10.1.4.2, section 10.1.4.3 and section 10.1.4.4.

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Step 2 The software should set registers. Configure the first address of the task descriptor structure to CE Task Descriptor Address Register. Configure the source/destination address to CE Current Source Address Register/CE Current Destination Address Register.

Step 3 Enable the end interrupt of the corresponding task channel by setting CE Interrupt Control Register.

Step 4 The software reads CE Task Load Register to ensure that the bit0 is 0. If the bit0 is not read out to be 0, wait until it is 0, then configure the bit0 to be 1 to start task.

Step 5 Wait for interrupt status by reading CE Interrupt Status Register.

Step 6 Read the result from the destination address.

Step 7 Clear the interrupt.

11.1.4.2 Configuring Task Descriptor of AES

- **Common control**: Configure Common Control[6:0] to 0x0 to select AES algorithm type.
- **Symmetric control**: According to the corresponding algorithm requirements, configure Symmetric Control to select the key size, CTR width, CTS last package flag, CFB width, and AES algorithm mode, and so on.
- **Asymmetric control**: The symmetric algorithm does not need to be configured for this field.
- **Key descriptor**: Because the storage of the key requires word alignment, ensure that this descriptor is the first address of the KEY (word address).
- **IV descriptor**: In the task that requires the IV value, configure the first address of the storage space where the IV is stored here. Because the storage of the IV requires word alignment, ensure that this descriptor is the first address of the IV (word address).
- **Data length**: Configure the data length of the corresponding segment. The data length size needs to be consistent with dst_data_length (destination data length 0 +... + destination data length 7). When the algorithm is CTS mode, the higher 30-bit of the data length is the word numbers of data volume; when the data_length[1:0] is 0, the data length is the higher 30-bit, otherwise it is increased by 1. For AES CTS, the data length indicates the byte numbers of the source data; for other algorithms, it indicates the word numbers.
- **Source address**: The first address of source data segments. Because the storage of the source data requires word alignment, ensure that this descriptor is the first address (word address).
- **Source data length**: The data volume of source data segments. The unit is word, and those less than one word are counted as one word. Note that only the last word of the entire message is allowed to be non-integer words, and the others must be integer words.
- **Destination address**: The first address of destination data segments. Because the storage of the destination data requires word alignment, ensure that this descriptor is the first address (word address).

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- **Destination data length**: The data volume of destination data segments. The unit is word, and those less than one word are counted as one word. Note that only the last word of the entire message is allowed to be non-integer words, and the others must be integer words.
- **Next descriptor**: The first address of the next task descriptor. Because the storage of the descriptor requires word alignment, ensure that this descriptor is the first address (word address).
- **Reserved**: Configure to 0x0.

11.1.4.3 Configuring Task Descriptor of HASH

- **Common control**
  - **Algorithm type**: Configure Common Control[6:0] to select SHA or HMAC algorithm type.
  - **Last HMAC plaintext**: If the algorithm type is HMAC, and the task is the last package of the message or if the message has only one package, then Common Control[15] needs to set to 1.
  - **IV mode**: The Common Control[16] (IV MODE) bit is only set to 1 in the following two scenarios, except that the bit must be configured to 0. (1). When the message is split into multiple packages, the Common Control[16] bit of other packages needs to be set to 1, except that the bit of the first package needs to be cleared to 0. (2). In special applications, if you need to customize the IV value to form the initial value of a certain HASH algorithm, you need to set the Common Control[16] bit of the first (or only one) package to 1, and the first address of the storage space where the customized IV value is stored in IV address.
- **Key descriptor**: Because the storage of the key requires word alignment, ensure that this descriptor is the first address of the KEY (word address).
- **IV descriptor**: In the task that requires the IV value, configure the first address of the storage space where the IV is stored here. Because the storage of the IV requires word alignment, ensure that this descriptor is the first address of the IV (word address).
- **Data length**: Configure the data length of the corresponding segment. The data length size needs to be consistent with dst_data_length (destination data length 0 +... + destination data length 7).
- **Source address**: The first address of source data segments. Because the storage of the source data requires word alignment, ensure that this descriptor is the first address (word address).
- **Source data length**: The data volume of source data segments. The unit is word, and those less than one word are counted as one word. Note that only the last word of the entire message is allowed to be non-integer words, and the others must be integer words.
- **Destination address**: The first address of destination data segments. Because the storage of the destination data requires word alignment, ensure that this descriptor is the first address (word address).

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- **Destination data length**: The data volume of destination data segments. The unit is word, and those less than one word are counted as one word. Note that only the last word of the entire message is allowed to be non-integer words, and the others must be integer words.
- **Next descriptor**: The first address of the next task descriptor. Because the storage of the descriptor requires word alignment, ensure that this descriptor is the first address (word address).
- **Reserved**: Configure to 0x0.

11.1.4.4 Configuring Task Descriptor of RSA

- **Common control**: Configure Common Control[6:0] to 0x20 to select RSA algorithm type.
- **Asymmetric control**: Configure Asymmetric Control[30:28] to select the RSA width.
- **Key descriptor**: Because the storage of the key requires word alignment, ensure that this descriptor is the first address of the KEY (word address).
- **Data length**: Configure the data length of the corresponding segment. The data length size needs to be consistent with dst_data_length (destination data length 0 +... + destination data length 7).
- **Source address**: The first address of source data segments. Because the storage of the source data requires word alignment, ensure that this descriptor is the first address (word address).
- **Source data length**: The data volume of source data segments. The unit is word, and those less than one word are counted as one word. Note that only the last word of the entire message is allowed to be non-integer words, and the others must be integer words.
- **Destination address**: The first address of destination data segments. Because the storage of the destination data requires word alignment, ensure that this descriptor is the first address (word address).
- **Destination data length**: The data volume of destination data segments. The unit is word, and those less than one word are counted as one word. Note that only the last word of the entire message is allowed to be non-integer words, and the others must be integer words.
- **Next descriptor**: The first address of the next task descriptor. Because the storage of the descriptor requires word alignment, ensure that this descriptor is the first address (word address).
- **Reserved**: Configure to 0x0.

11.1.5 Register List

Module Name	Base Address
CE_NS (Non-Security CE)	0x03040000

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Module Name	Base Address
CE_S (Security CE)	0x03040800

Register Name	Offset	Description
CE_TDA	0x0000	Task Descriptor Address
CE_CTL	0x0004	Control Register
CE_ICR	0x0008	Interrupt Control Register
CE_ISR	0x000C	Interrupt Status Register
CE_TLR	0x0010	Task Load Register
CE_TSR	0x0014	Task Status Register
CE_ESR	0x0018	Error Status Register
CE_CSA	0x0024	DMA Current Source Address
CE_CDA	0x0028	DMA Current Destination Address
CE_TPR	0x002C	Throughput Register

11.1.6 Register Description

11.1.6.1 0x0000 CE Task Descriptor Address Register (Default Value: 0x0000_0000)

Offset: 0x0000			Register Name: CE_TDA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/W	0x0	Task Descriptor Address Configure as the first address of the descriptor structure.

11.1.6.2 0x0004 CE Control Register (Default Value: 0x0000_0000)

Offset: 0x0004			Register Name: CE_CTL
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3	R/W	0x0	RSA CLK Gating Enable (only for CE_S) 0: RSA clock gating enable 1: RSA clock gating disable
2:0	/	/	/

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11.1.6.3 0x0008 CE Interrupt Control Register (Default Value: 0x0000_0000)

Offset: 0x0008			Register Name: CE_ICR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3:0	R/W	0x0	Task Channel3~0 Interrupt Enable 0: Disable 1: Enable

11.1.6.4 0x000C CE Interrupt Status Register (Default Value: 0x0000_0000)

Offset: 0x000C			Register Name: CE_ISR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:4	/	/	/
3:0	R/W1C	0x0	Task Channel3~0 End Pending 0: Not finished 1: Finished It indicates whether task is completed. Write the corresponding channel bit of the register to clear the end flag. When the last task in the task chain ends, the operation of the task chain will end normally. If the task fails in the middle, the task chain will be aborted. The CE_ISR register will be automatically updated when it ends normally or aborts abnormally. And it is determined whether to generate an interrupt signal according to the IE configuration (bit31) of Common Control when the current task ends or aborts. If using interrupt, after receiving the interrupt, read the corresponding channel bit of CE_ISR to judge whether it ends successfully or stops failure. If not using interrupt, the CE_ISR status register can be continuously queried for the channel bit until the successful end flag is set or the failure stop flag is set. Write the corresponding channel bit of the register to clear the end flag. If it fails to stop, you can read the error code on the channel corresponding to the **CE_ESR** register.

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11.1.6.5 0x0010 CE Task Load Register (Default Value: 0x0000_0000)

Offset: 0x0010			Register Name: CE_TLR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:1	/	/	/
0	R/W	0x0	Task Load When set, the CE can load the descriptor of task if the task FIFO is not full.

11.1.6.6 0x0014 CE Task Status Register (Default Value: 0x0000_0000)

Offset: 0x0014			Register Name: CE_TSR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:2	/	/	/
1:0	R	0x0	Running Channel Number 00: Task channel0 01: Task channel1 10: Task channel2 11: Task channel3

11.1.6.7 0x0018 CE Error Status Register (Default Value: 0x0000_0000)

Offset: 0x0018			Register Name: CE_ESR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:16	/	/	/
15:12	R/W1C	0x0	Task Channel3 Error Type xxx1: Algorithm not support xx1x: Data length error x1xx: keysram access error for AES 1xxx: Reserved
11:8	R/W1C	0x0	Task Channel2 Error Type xxx1: Algorithm not support xx1x: Data length error x1xx: keysram access error for AES 1xxx: Reserved

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Offset: 0x0018			Register Name: CE_ESR
Bit	**Read/Write**	**Default/Hex**	**Description**
7:4	R/W1C	0x0	Task Channel1 Error Type xxx1: Algorithm not support xx1x: Data length error x1xx: keysram access error for AES 1xxx: Reserved
3:0	R/W1C	0x0	Task Channel0 Error Type xxx1: Algorithm not support xx1x: Data length error x1xx: keysram access error for AES 1xxx: Reserved

11.1.6.8 0x0024 CE Current Source Address Register (Default Value: 0x0000_0000)

Offset: 0x0024			Register Name: CE_CSA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	CUR_SRC_ADDR Current source address

11.1.6.9 0x0028 CE Current Destination Address Register (Default Value: 0x0000_0000)

Offset: 0x0028			Register Name: CE_CDA
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R	0x0	CUR_DST_ADDR Current destination address

11.1.6.10 0x002C CE Throughput Register (Default Value: 0x0000_0000)

Offset: 0x002C			Register Name: CE_TPR
Bit	**Read/Write**	**Default/Hex**	**Description**
31:0	R/WC	0x0	TP_NUM It indicates the throughput writing to this register at last time. Writing to this register will clear it to 0.

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11.2 Security ID

The Security ID (SID) is used to program and read keys which include chip ID, thermal sensor, HASH code, and security key, and so on.

The SID module has the following features:

- 2 Kbit electrical fuse (eFuse)
- The module register is non-secure forever, the eFuse has secure zone and non-secure zone
- Backup eFuse information by using SID_SRAM
- A fuse only can program one time
- Burning the key to the SID
- Reading the key use status in the SID
- Loading the key to the CE

CAUTION

Before performing the burning operation, ensure that the power supply of the eFuse power pin is stable. After the burning operation is completed, cancel the power supply of the eFuse power pin.

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Appendix: Glossary

The following table contains acronyms and abbreviations used in this document.

Term	Meaning
A	
ADC	Analog-to-Digital Converter
AE	Automatic Exposure
AEC	Audio Echo Cancellation
AES	Advanced Encryption Standard
AF	Automatic Focus
AGC	Automatic Gain Control
AHB	AMBA High-Speed Bus
ALC	Automatic Level Control
ANR	Active Noise Reduction
APB	Advanced Peripheral Bus
ARM	Advanced RISC Machine
AVS	Audio Video Synchronization
AWB	Automatic White Balance
B	
BROM	Boot ROM
C	
CIR	Consumer Infrared
CMOS	Complementary Metal-Oxide Semiconductor
CP15	Coprocessor 15
CPU	Central Processing Unit
CRC	Cyclic Redundancy Check
CSI	Camera Serial Interface
D	
DDR	Double Data Rate
DES	Data Encryption Standard
DLL	Delay-Locked Loop
DMA	Direct Memory Access
DRC	Dynamic Range Compression
DVFS	Dynamic Voltage and Frequency Scaling
E	
ECC	Error Correction Code
eFuse	Electrical Fuse, A one-time programmable memory
EHCI	Enhanced Host Controller Interface
eMMC	Embedded Multi-Media Card
ESD	Electrostatic Discharge
F	
FBGA	Fine Pitch Ball Grid Array
FEL	Fireware Exchange Launch

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Term	Meaning
FIFO	First In First Out
G	
GIC	Generic Interrupt Controller
GPIO	General Purpose Input Output
I	
I2C	Inter Integrated Circuit
I2S	Inter IC Sound
ISP	Image Signal Processor
J	
JEDEC	Joint Electron Device Engineering Council
JPEG	Joint Photographic Experts Group
JTAG	Joint Test Action Group
L	
LCD	Liquid-Crystal Display
LFBGA	Low Profile Fine Pitch Ball Grid Array
LRADC	Low Rate Analog to Digital Converter
LSB	Least Significant Bit
LVDS	Low Voltage Differential Signaling
M	
MAC	Media Access Control
MIC	Microphone
MIPI	Mobile Industry Processor Interface
MLC	Multi-Level Cell
MMC	Multimedia Card
MPEG	Motion Pictures Expert Group
MSB	Most Significant Bit
N	
N/A	Not Application
NMI	Non Maskable Interrupt
NTSC	National Television Standards Committee
NVM	Non Volatile Storage Medium
O	
OHCI	Open Host Controller Interface
OTP	One Time Programmable
OWA	One Wire Audio
P	
PAL	Phase Alternating Line
PCM	Pulse Code Modulation
PHY	Physical Layer Controller
PID	Packet Identifier
PLL	Phase-Locked Loop
POR	Power-On Reset
PRCM	Power Reset Clock Management

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Term	Meaning
PWM	Pulse Width Modulation
R	
R	Read only/non-Write
RGB	Read Green Blue
RGMII	Reduced Gigabit Media Independent Interface
RMII	Reduced Media Independent Interface
ROM	Read Only Memory
RSA	Rivest-Shamir-Adleman
RTC	Real Time Clock
S	
SAR	Successive Approximation Register
SD	Secure Digital
SDIO	Secure Digital Input Output
SDK	Software Development Kit
SDRAM	Synchronous Dynamic Random Access Memory
SDXC	Secure Digital Extended Capacity
SLC	Single-Level Cell
SoC	System on Chip
SPI	Serial Peripheral Interface
SRAM	Static Random Access Memory
T	
TDES	Triple Data Encryption Standard
TWI	Two Wire Interface
U	
UART	Universal Asynchronous Receiver Transmitter
UDF	Undefined
USB DRD	Universal Serial Bus Dual Role Device
UTMI	USB2.0 Transceiver Macrocell Interface

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